



National Semiconductor

## CLC449

# 1.1GHz Ultra-Wideband Monolithic Op Amp

### General Description

The CLC449 is an ultra-high-speed monolithic op amp, with a typical -3dB bandwidth of 1.1GHz at a gain of +2. This wideband op amp supports rise and fall times less than 1ns, settling time of 6ns (to 0.2%) and slew rate of 2500V/ $\mu$ s. The CLC449 achieves 2nd harmonic distortion of -68dBc at 5MHz at a low supply current of only 12mA. These performance advantages have been achieved through improvements in National's proven current feedback topology combined with a high-speed complementary bipolar process.

The DC to 1.2GHz bandwidth of the CLC449 is suitable for many IF and RF applications as a versatile op amp building block for replacement of AC coupled discrete designs. Operational amplifier functions such as active filters, gain blocks, differentiation, addition, subtraction and other signal conditioning functions take full advantage of the CLC449's unity-gain stable closed-loop performance.

The CLC449 performance provides greater headroom for lower frequency applications such as component video, high-resolution workstation graphics, and LCD displays. The amplifier's 0.1dB gain flatness to beyond 200MHz, plus 0.8ns 2V rise and fall times are ideal for improved time domain performance. In addition, the 0.03%/0.02° differential gain/phase performance allows system flexibility for handling standard NTSC and PAL signals.

In applications using high-speed flash A/D and D/A converters, the CLC449 provides the necessary wide bandwidth (1.1GHz), settling (6ns to 0.2%) and low distortion into 50 $\Omega$  loads to improve SFDR.

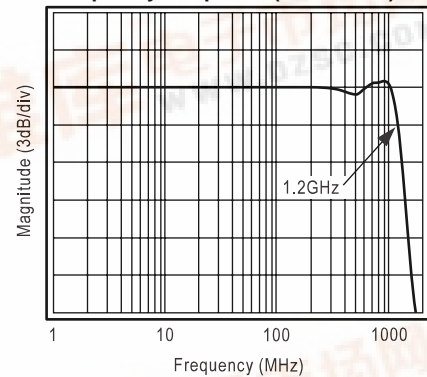
### Features

- 1.1GHz small-signal bandwidth ( $A_v = +2$ )
- 2500V/ $\mu$ s slew rate
- 0.03%, 0.02°  $D_G$ ,  $D_\Phi$
- 6ns settling time to 0.2%
- 3rd order intercept, 30dBm @ 70MHz
- Dual  $\pm 5V$  or single 10V supply
- High output current: 90mA
- 2.5dB noise figure

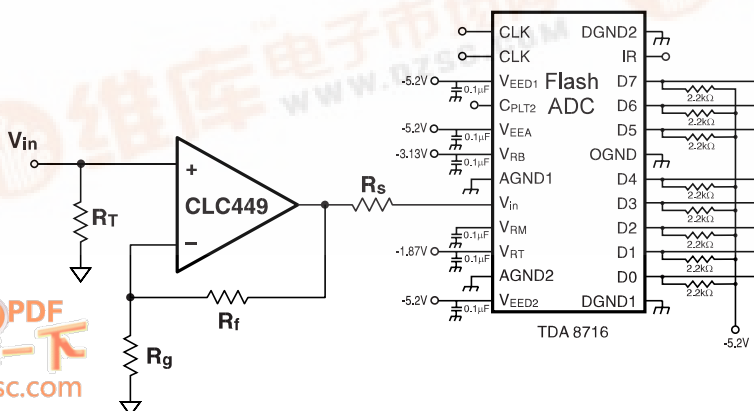
### Applications

- High performance RGB video
- RF/IF amplifier
- Instrumentation
- Medical electronics
- Active filters
- High-speed A/D driver
- High-speed D/A buffer

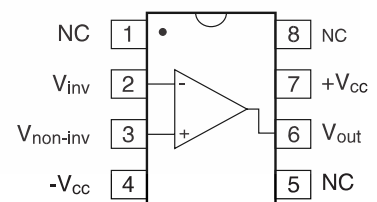
Frequency Response ( $A_v = +2V/V$ )



### Typical Application 120MSPS High-Speed Flash ADC Driver



### Pinout DIP & SOIC



# CLC449 Electrical Characteristics (A<sub>v</sub> = +2, R<sub>f</sub> = 250Ω, V<sub>cc</sub> = ±5V, R<sub>L</sub> = 100Ω; unless specified)

| PARAMETERS                           |                               | CONDITONS | TYP  | MIN/MAX RATINGS |            |              | UNITS  | NOTES |
|--------------------------------------|-------------------------------|-----------|------|-----------------|------------|--------------|--------|-------|
|                                      |                               | CLC449    | +25° | +25°            | 0° to +70° | -40° to +85° |        |       |
| <b>FREQUENCY DOMAIN RESPONSE</b>     |                               |           |      |                 |            |              |        |       |
| -3dB bandwidth                       |                               |           |      |                 |            |              |        |       |
| small signal                         | <0.2V <sub>pp</sub>           | 1100      |      |                 |            |              | MHz    |       |
| large signal                         | <2V <sub>pp</sub>             | 500       | 380  | 380             | 360        |              | MHz    |       |
| ±0.1 dB bandwidth                    | <2V <sub>pp</sub>             | 200       |      |                 |            |              | MHz    |       |
| gain flatness                        |                               |           |      |                 |            |              |        |       |
| peaking                              | DC to 200MHz                  | 0         |      |                 |            |              | dB     |       |
| rolloff                              | DC to 200MHz                  | 0.1       | 0.5  | 0.5             | 0.5        |              | dB     |       |
| linear phase deviation               | <200MHz                       | 0.8       |      |                 |            |              | deg    |       |
| differential gain                    | 4.43MHz, R <sub>L</sub> =150Ω | 0.03      | 0.05 | 0.05            | 0.05       |              | %      |       |
| differential phase                   | 4.43MHz, R <sub>L</sub> =150Ω | 0.02      | 0.02 | 0.05            | 0.05       |              | deg    |       |
| <b>TIME DOMAIN RESPONSE</b>          |                               |           |      |                 |            |              |        |       |
| rise and fall time                   | 2V step                       | 0.8       | 1.1  | 1.1             | 1.1        |              | ns     |       |
| settling time to 0.2%                | 2V step                       | 6         |      |                 |            |              | ns     |       |
| settling time to 0.1%                | 2V step                       | 11        |      |                 |            |              | ns     |       |
| overshoot                            | 2V step                       | 10        | 18   | 18              | 18         |              | %      |       |
| slew rate                            | 4V step                       | 2500      | 2000 | 2000            | 2000       |              | V/μs   |       |
| <b>DISTORTION AND NOISE RESPONSE</b> |                               |           |      |                 |            |              |        |       |
| 2nd harmonic distortion              | 2V <sub>pp</sub> , 5MHz       | -63       | 59   | 59              | 59         |              | dBc    |       |
|                                      | 2V <sub>pp</sub> , 20MHz      | -52       | -48  | -48             | -48        |              | dBc    |       |
|                                      | 2V <sub>pp</sub> , 50MHz      | -44       | 40   | 40              | 40         |              | dBc    |       |
| 3rd harmonic distortion              | 2V <sub>pp</sub> , 5MHz       | -84       | 77   | 75              | 75         |              | dBc    |       |
|                                      | 2V <sub>pp</sub> , 20MHz      | -73       | -66  | -64             | -64        |              | dBc    |       |
|                                      | 2V <sub>pp</sub> , 50MHz      | -62       | 55   | 53              | 53         |              | dBc    |       |
| 3rd order intercept                  | 70MHz                         | 30        |      |                 |            |              | dBm    |       |
| 1dB gain compression @ 50MHz         |                               | 16        |      |                 |            |              | dBm    |       |
| equivalent input noise               |                               |           |      |                 |            |              |        |       |
| non-inverting voltage                | 1MHz                          | 2.2       | 2.9  |                 |            |              | nV/√Hz |       |
| inverting current                    | 1MHz                          | 15        | 20.0 |                 |            |              | pA/√Hz |       |
| non-inverting current                | 1MHz                          | 3         | 5.0  |                 |            |              | pA/√Hz |       |
| <b>STATIC DC PERFORMANCE</b>         |                               |           |      |                 |            |              |        |       |
| input offset voltage                 |                               | 3         | 7    | 9               | 9          |              | mV     | A     |
| average drift                        |                               | 25        |      |                 |            |              | μV/°C  |       |
| input bias current                   | non-inverting                 | 6         | 30   | 45              | 60         |              | μA     | A     |
| average drift                        |                               | 50        |      |                 |            |              | nA/°C  |       |
| input bias current                   | inverting                     | 2         | 20   | 25              | 40         |              | μA     | A     |
| average drift                        |                               | 25        |      |                 |            |              | nA/°C  |       |
| power supply rejection ratio         | DC                            | 48        | 43   | 41              | 41         |              | dB     | A     |
| common-mode rejection ratio          | DC                            | 47        | 44   | 45              | 46         |              | dB     |       |
| supply current                       | R <sub>L</sub> = ∞            | 12        | 13.5 | 14              | 14         |              | mA     | A     |
| <b>MISCELLANEOUS PERFORMANCE</b>     |                               |           |      |                 |            |              |        |       |
| input resistance                     | non-inverting                 | 400       | 200  | 200             | 150        |              | kΩ     |       |
| input capacitance                    | non-inverting                 | 1.3       |      |                 |            |              | pF     |       |
| output resistance                    | closed loop                   | 0.1       | 0.15 | 0.15            | 0.25       |              | Ω      |       |
| output voltage range                 | R <sub>L</sub> = ∞            | 3.3       | 3.1  | 3.1             | 3.1        |              | V      |       |
|                                      | R <sub>L</sub> = 100Ω         | 2.9       | 2.8  | 2.8             | 2.8        |              | V      |       |
| input voltage range                  | common-mode                   | 2.4       | 2.2  | 2.1             | 1.9        |              | V      |       |
| output current                       |                               | 80        | 60   | 50              | 40         |              | mA     |       |

Min/max ratings are based on product characterization and simulation. Individual parameters are tested as noted. Outgoing quality levels are determined from tested parameters.

## Absolute Maximum Ratings

|   |                  |
|---|------------------|
| V <sub>oc</sub>                                       | ±6V              |
| I <sub>out</sub> is short circuit protected to ground |                  |
| common-mode input voltage                             | ±V <sub>CC</sub> |
| maximum junction temperature                          | +150°C           |
| operating temperature range                           |                  |
| AJ  | -40°C to +85°C   |
| storage temperature range                             | -65°C to +150°C  |
| lead temperature (soldering 10 sec)                   | +300°C           |
| ESD (human body model)                                | 500V             |

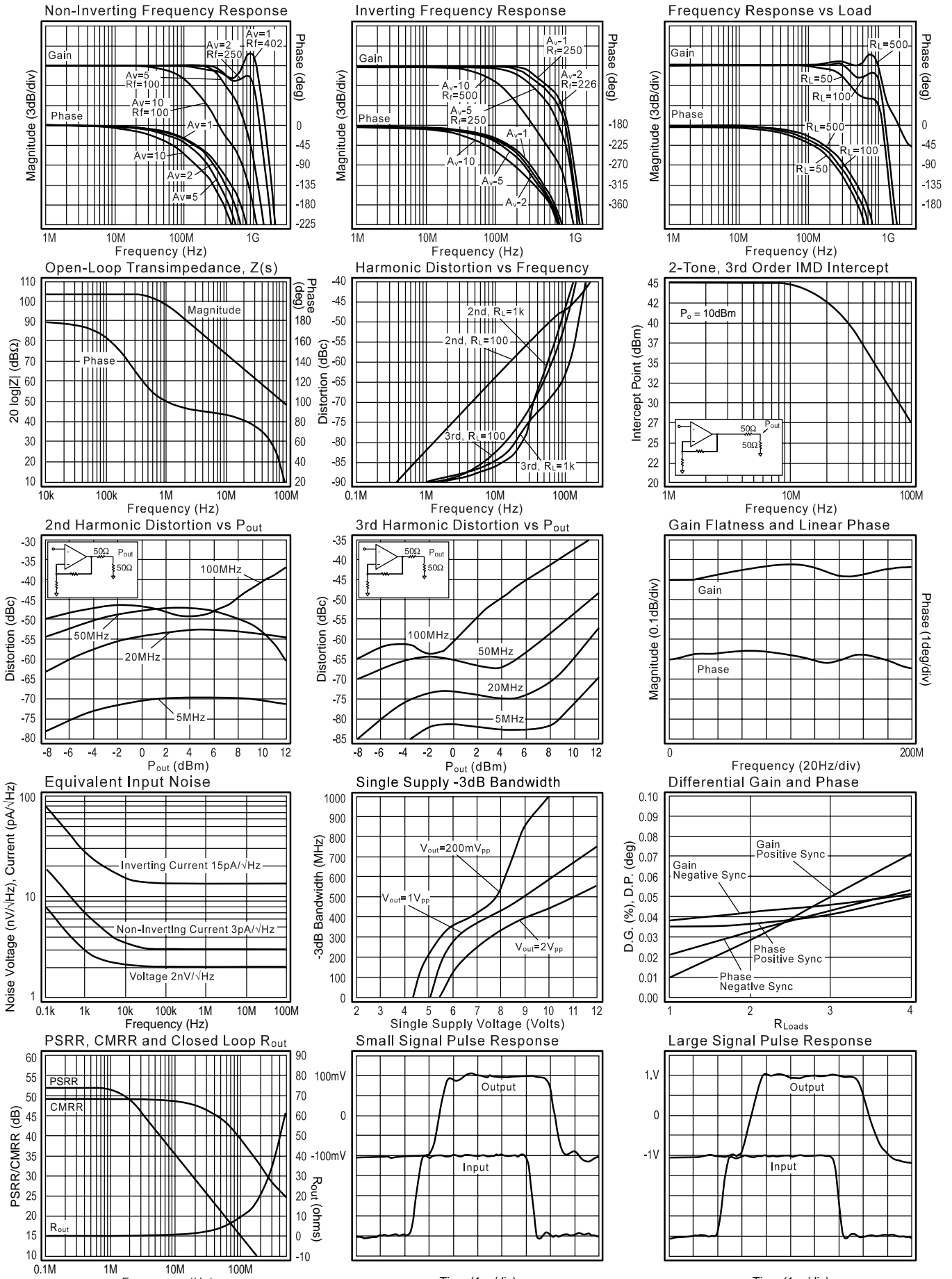
## Notes

A) J-level: spec is 100% tested at +25°C.

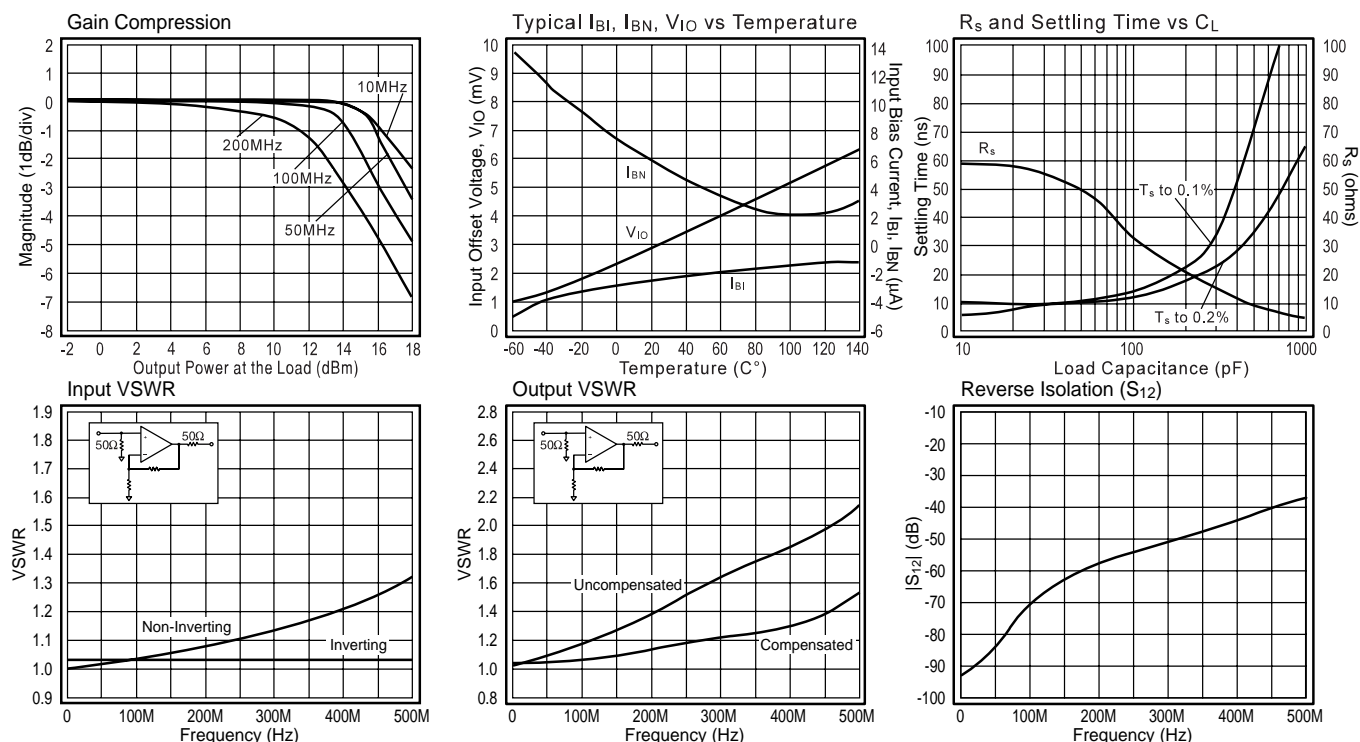
## Package Thermal Resistance

| Package             | θ <sub>JC</sub> | θ <sub>JA</sub> |
|---------------------|-----------------|-----------------|
| Plastic (AJP)       | 90°C/W          | 105°C/W         |
| Surface Mount (AJE) | 110°C/W         | 130°C/W         |

# CLC449 Typical Performance Characteristics ( $T_A = 25^\circ\text{C}$ , $V_{CC} = \pm 5\text{V}$ , $R_f = 250\Omega$ , $A_v = +2$ , $R_L = 100\Omega$ )



## CLC449 Typical Performance Characteristics ( $T_A = 25^\circ\text{C}$ , $V_{CC} = \pm 5\text{V}$ , $R_f = 250\Omega$ , $A_v = +2$ , $R_L = 100\Omega$ )



## CLC449 OPERATION

### CLC449 Extended Application Information

The following design and application topics will supply you with:

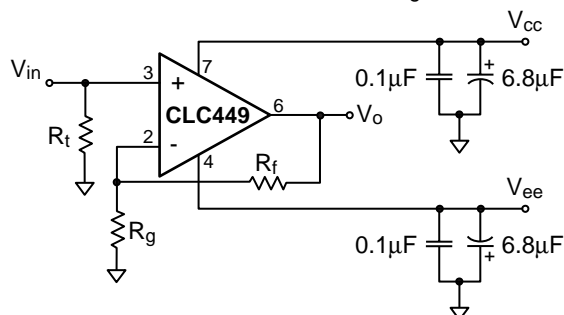
- A comprehensive set of design parameters and design parameter adjustment techniques.
- A set of formulas that support design parameter change prediction.
- A series of common applications that the CLC449 supports.
- A set of easy to use design guidelines for the CLC449.

Additional design applications are possible with the CLC449. If you have application questions, call 1-800-272-9959 in the U.S. to contact a technical staff member.

### DC Gain (Non-Inverting)

The non-inverting DC voltage gain for the configuration shown in Figure 1 is:

$$A_v = 1 + \frac{R_f}{R_g}$$



The normalized gain plots in the **Typical Performance Characteristics** section show different feedback resistors,  $R_f$ , for different gains. These values of  $R_f$  are recommended for obtaining the highest bandwidth with minimal peaking. The resistor  $R_f$  in Figure 1 provides DC bias for the non-inverting input.

For  $A_v \leq 5$ , calculate the recommended  $R_f$  as follows:  $R_f \cong 340 - A_v \cdot R_i$ , where  $R_i = 45\Omega$ . For  $A_v > 5$ , the minimum recommended feedback resistor is  $R_f = 100\Omega$ .

Select  $R_g$  to set the DC gain:  $R_g = \frac{R_f}{A_v - 1}$

Accuracy of DC gain is usually limited by the tolerance of the external resistors  $R_f$  and  $R_g$ .

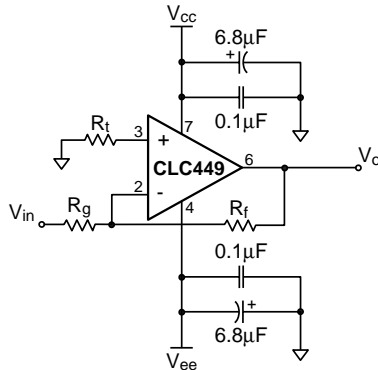
### DC Gain (Unity Gain Buffer)

Unity gain buffers are easily designed with a current-feedback amplifier as long as the recommended feedback resistor  $R_f = 402\Omega$  is used and  $R_g = \infty$ , i.e. open. Parasitic capacitance at the inverting node may require a slight increase of the feedback resistor  $R_f$  to maintain a flat frequency response.

### DC Gain (Inverting)

The inverting DC voltage gain for the configuration shown in Figure 2 is:

$$A_v = -\frac{R_f}{R_g}$$



**Figure 2: Inverting Gain**

The normalized gain plots in the **Typical Performance Characteristics** section show different feedback resistors,  $R_f$ , for different gains. These values of  $R_f$  are recommended for obtaining the highest bandwidth with minimal peaking. The resistor  $R_i$  in Figure 2 provides DC bias for the non-inverting input.

For  $|A_v| \leq 4$ , calculate the recommended  $R_f$  as follows:  $R_f \cong 295 - |A_v| \cdot R_i$ , where  $R_i = 45\Omega$ . For  $|A_v| > 4$ , the minimum recommended feedback resistor is  $R_f = 100\Omega$ .

Select  $R_g$  to set the DC gain:

$$R_g = \frac{R_f}{|A_v|}$$

At large gains,  $R_g$  becomes small and will load the previous stage. This situation is resolved by driving  $R_g$  with a low impedance buffer like the CLC111, or increasing  $R_f$  and  $R_g$  (see the **Bandwidth (Small Signal)** sub-section for the tradeoffs).

Accurate DC gain is usually limited by the tolerance of the external resistors  $R_f$  and  $R_g$ .

### Bandwidth (Small Signal)

The CLC449 current-feedback amplifier bandwidth is a function of the feedback resistor ( $R_f$ ), not of the DC voltage gain ( $A_v$ ). The bandwidth is approximately proportional to  $1/R_f$ . As a rule, if  $R_f$  doubles, the bandwidth is cut in half. Other AC specifications will also be degraded. **Decreasing  $R_f$  from the recommended value increases peaking and for very small values of  $R_f$  oscillation will occur.**

With an inverting amplifier design, peaking is sometimes observed. This is often the result of layout parasitics caused by inadequate ground planes or long traces. If this is observed, placing a 50 to 200 $\Omega$  resistor between the non-inverting pin and ground will usually reduce the peaking.

### Bandwidth (Minimum Slew Rate)

Slew rate influences the bandwidth for large signal sinusoids. To determine an approximate value of slew rate, necessary to support large sinusoids use the following equation:

$$SR \cong 5 \cdot f \cdot V_{peak}$$

$V_{peak}$  is the peak output sinusoidal voltage,  $f$  is the frequency of the sinusoid.

The slew rate of the CLC449 in inverting gains is always

higher than in non-inverting gains.

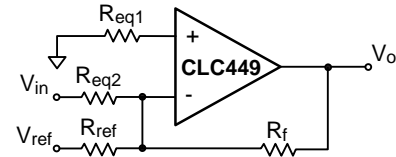
### DC Design (Level Shifting)

Figure 3 shows a DC level shifting circuit for inverting gain configurations.  $V_{ref}$  produces a DC output level shift of

$$-V_{ref} \cdot \frac{R_f}{R_{ref}}$$

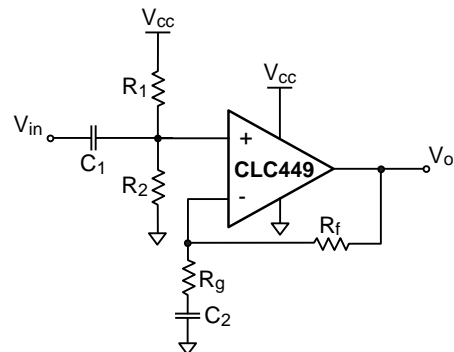
which is independent of the DC output produced by  $V_{in}$ .

**Figure 3: Level Shifting Circuit**



### DC Design (Single Supply)

Figure 4 is a typical single-supply circuit. Resistors  $R_1$  and  $R_2$  form a voltage divider that sets the non-inverting input DC voltage. This circuit has a DC gain of 1. The coupling capacitor  $C_1$  isolates the DC bias point from the previous stage. Both capacitors make a high pass response; the high frequency gain is determined by  $R_f$  and  $R_g$ .



**Figure 4: Single Supply Circuit**

The complete gain equation for the circuit in Figure 4 is:

$$\frac{V_o}{V_{in}} = \frac{s\tau_1}{1+s\tau_1} \cdot \frac{1+s\tau_2 \cdot \left(1 + \frac{R_f}{R_g}\right)}{1+s\tau_2}$$

where  $s = j\omega$ ,  $\tau_1 = (R_1 || R_2) \cdot C_1$ , and  $\tau_2 = R_g C_2$ .

### DC Design (DC Offsets)

The DC offset model shown in Figure 5 is used to calculate the output offset voltage. The equation for output offset voltage is:

$$V_o = - \left( V_{os} + I_{BN} \cdot R_{eq1} \right) \cdot \left( 1 + \frac{R_f}{R_{eq2}} \right) + (I_{BI} \cdot R_f)$$

The current offset terms,  $I_{BN}$  and  $I_{BI}$ , **do not track each other**. The specifications are stated in terms of magnitude only. Therefore, the terms  $V_{os}$ ,  $I_{BN}$ , and  $I_{BI}$  may have either positive or negative polarity. Matching the equivalent resistance seen at both input pins does not reduce the output offset voltage.



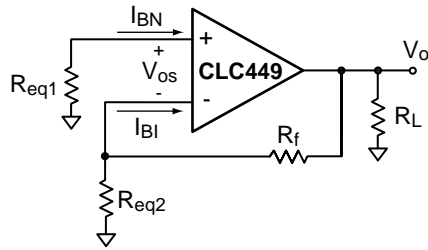


Figure 5: DC Offset Model

### DC Design (Output Loading)

$R_L$ ,  $R_f$ , and  $R_g$  load the op amp output. The equivalent closed-loop load impedance seen by the output in Figure 5 is:

- $R_{L\_eq} = R_L \parallel (R_f + R_{eq2})$ , non-inverting gain
- $R_{L\_eq} = R_L \parallel R_f$ , inverting gain

$R_{L\_eq}$  needs to be kept large enough so that the minimum available output current can produce the required output voltage swing.

### Capacitive Loads

Capacitive loads, such as found in A/D converters, require a series resistor ( $R_s$ ) in the output to improve settling performance. The  **$R_s$  and Settling Time vs.  $C_L$**  plot in the **Typical Performance Characteristics** section provides the information for selecting this resistor.

Also, use a series resistor to reduce the effects of reactive loads on amplifier loop dynamics. For instance, driving coaxial cables without an output series resistor may cause peaking or oscillation.

### Transmission Line Matching

One method for matching the characteristic impedance of a transmission line is to place the appropriate resistor at the input or output of the amplifier. Figure 6 shows the typical circuit configurations for matching transmission lines.

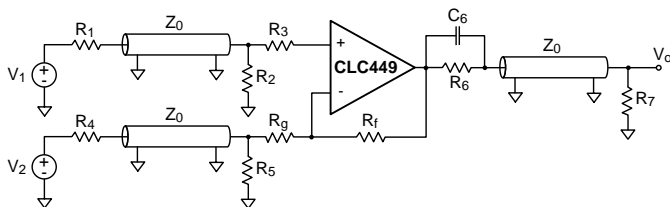


Figure 6: Transmission Line Matching

In non-inverting gain applications,  $R_g$  is connected directly to ground. The resistors  $R_1$ ,  $R_2$ ,  $R_6$ , and  $R_7$  are equal to the characteristic impedance,  $Z_0$ , of the transmission line or cable.

In inverting gain applications,  $R_3$  is connected directly to ground. The resistors  $R_4$ ,  $R_6$ , and  $R_7$  are equal to  $Z_0$ . The parallel combination of  $R_5$  and  $R_g$  is also equal to  $Z_0$ .

The input and output matching resistors attenuate the signal by a factor of 2, therefore additional gain is needed.

Matching the output transmission line over greater frequency ranges is accomplished by placing  $C_6$  in parallel with  $R_6$ , reducing the output impedance to compensate for the internal increase of the op-amp's output impedance with frequency.

### Thermal Design

To calculate the power dissipation for the CLC449, follow these steps:

- Calculate the no-load op amp power:  
 $P_{amp} = I_{cc} \cdot (V_{cc} - V_{ee})$
- Calculate the output stage's RMS power:  
 $P_o = (V_{cc} - V_{load}) \cdot I_{load}$   
where  $V_{load}$  and  $I_{load}$  are the RMS voltage and current across the external load.
- Calculate the total op amp RMS power:  
 $P_t = P_{amp} + P_o$

To calculate the maximum allowable ambient temperature, solve the following equation:  $T_{amb} = 175 - P_t \cdot \theta_{JA}$ , where  $\theta_{JA}$  is the thermal resistance from junction to ambient in  $^{\circ}\text{C}/\text{W}$  and  $T_{amb}$  is in  $^{\circ}\text{C}$ . Thermal resistance for the various packages are found in the **Package Thermal Resistance** section.

### Dynamic Range (Input /Output Protection)

Input ESD diodes are present on all connected pins for protection from static voltage damage. For a signal that may exceed the supply voltages, we recommend using diode clamps at the amplifier's input to limit the signals to less than the supply voltages.

### Dynamic Range (Input /Output Levels)

The **Electrical Characteristics** section contains the Common-Mode Input Range and Output Voltage Range; these voltage ranges scale with the supplies. Output Current is also specified in the **Electrical Characteristics** section.

Unity gain applications are limited by the Common-Mode Input Range. At greater non-inverting gains, the Output Voltage Range becomes the limiting factor. Inverting gain applications are limited by the Output Voltage Range.

For transimpedance or inverting gain applications, the current ( $I_{inv}$ ) injected at the inverting input pin of the op amp needs to be:

$$|I_{inv}| \leq \frac{V_{max}}{R_f}$$

where  $V_{max}$  is the Output Voltage Range.

The voltage ranges discussed above are achieved as long as the equivalent output load is large enough so that the output current can produce the required output voltage swing. See the **DC Design (Output Loading)** sub-section for details.

### Dynamic Range (Intermods)

For RF applications, the CLC449 specifies a third order intercept of 30dBm at 70MHz and  $P_o = 10\text{dBm}$ .

A **2-Tone, 3rd Order IMD Intercept** plot is found in the **Typical Performance Characteristics** section. The output power level is taken at the load. Third-order harmonic distortion is calculated with the formula:

$$HD3^{rd} = 2 \cdot (IP3_o - P_o)$$

where:

- $IP3_o$  = third-order output intercept, dBm at the load.
- $P_o$  = output power level, dBm at the load.
- $HD3^{rd}$  = third-order distortion from the fundamental, -dBc.
- dBm is the power in mW, at the load, expressed in dB.

Realized third-order output distortion is highly dependent upon the external circuit. Some of the common external circuit choices that improve 3<sup>rd</sup> order distortion are:

- short and equal return paths from the load to the supplies.
- de-coupling capacitors of the correct value.
- higher load resistance.
- a lower ratio of the output swing to the power supply voltage.

### Dynamic Range (Noise)

In RF applications, noise is frequently specified as Noise Figure (NF). Figure 7 plots NF for the CLC449 at a gain of 10, with a feedback resistor  $R_f$  of 100 $\Omega$ , and with no input matching resistor. The minimum Noise Figure (2.5dB) for these conditions occurs when the source resistance equals 700 $\Omega$ .

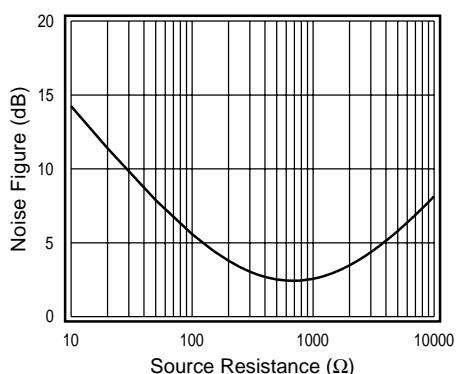


Figure 7. Noise Figure Plot

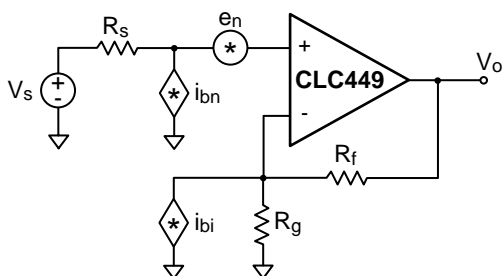


Figure 8: CLC449 Noise Model

The CLC449 noise model in Figure 8 is used to develop the equation below.

The equation for Noise Figure (NF) is:

$$NF = 10 \log \left( \frac{e_{ni}^2 + (i_{bn} R_s)^2 + 4kTR_s + (i_{bi} \cdot R_f \parallel R_g)^2 + 4kT \cdot R_f \parallel R_g}{4kTR_s} \right)$$

where:

- $R_s$  is the source resistance at the non-inverting input.
- There is no matching resistor from the input to ground.
- $e_{ni}$ ,  $i_{bn}$ ,  $i_{bi}$  are the voltage and current noise density terms (see in the **Distortion and Noise Response** sub-section of the **Electrical Characteristics** section).
- $4kT = 16 \times 10^{-21} J$ ,  $T = 290^\circ K$ .
- $R_f$  is the feedback resistor and  $R_g$  is the gain setting resistor.

### Printed Circuit Board Layout and Measurement

High Frequency op amp performance is strongly dependent on proper layout, proper resistive termination and adequate power supply decoupling. The most important layout points to follow are:

- Use a ground plane.
- Bypass power supply pins with monolithic capacitors of about 0.1 $\mu F$  value and place the capacitors less than 0.1" (3mm) from the pin.
- Bypass power supply pins with 6.8 $\mu F$  tantalum capacitors for large signal current swings or improved power supply noise rejection.
- Minimize trace and lead lengths for components between the inverting and output pins.
- Remove ground plane underneath the amplifier package and within 0.1" (3mm) of all input/output pads.
- If parts must be socketed, always use flush-mount socket pins instead of high profile sockets.

Evaluation boards are available for proto-typing and measurements. Additional layout information is available in the evaluation board literature.

## CLC449 APPLICATIONS

### Low Noise Composite Amp With Input Matching

The composite circuit shown in Figure 9 eliminates the need for a matching resistor to ground at the input. By connecting two amplifiers in series, the first non-inverting and the second inverting, an overall inverting gain is realized. The feedback resistor ( $R_f$ ) connected from the output of the second amplifier to the non-inverting input of the first amplifier closes the loop, and generates a set input resistance ( $R_{in}$ ) that can be matched to  $R_s$ . This resistor generates less noise than a matching resistor to ground at the input.

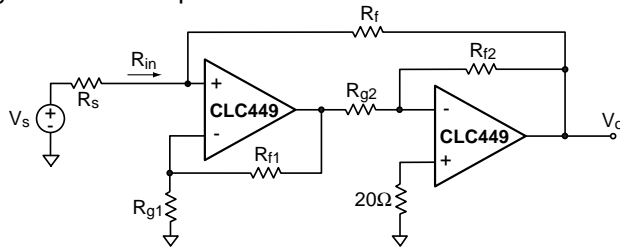


Figure 9: Composite Amplifier

Input resistance and DC voltage gain of the amplifier are:

$$R_{in} = \frac{R_f}{1+G}, \text{ where } G = \left(1 + \frac{R_{f1}}{R_{g1}}\right) \cdot \left(\frac{R_{f2}}{R_{g2}}\right)$$

$$\frac{V_o}{V_s} = -G \cdot \left(\frac{R_{in}}{R_{in} + R_s}\right)$$

Match the source resistance by setting:  $R_{in} = R_s$

Noise voltage produced by  $R_f$ , referred to the source  $V_s$ , is:

$$e^2_{R_f} = 4kTR_s \cdot \left(\frac{R_s}{R_{in} \cdot (1+G)}\right)$$

The noise of a simple input matching resistor connected to ground can be calculated by setting  $G$  to 0 in this equation. Thus, this circuit reduces the thermal noise produced by the matching resistor by a factor of  $(1+G)$ .

### Rectifier Circuit

Wide bandwidth rectifier circuits have many applications. Figure 10 shows a 200MHz wideband full-wave rectifier circuit using a CLC449 and CLC522 amplifier. Schottky or PIN diodes are used for D1 and D2. They produce an active half-wave rectifier whose signals are taken at the feedback diode connection. The CLC522 takes the difference of the two half-wave rectified signal, producing a full-wave rectifier. The CLC522 is used at a gain of 5 to

achieve high differential bandwidth. For best high frequency performance, maintain low parasitic capacitance from the diodes D1 and D2 to ground, and from the input of the CLC522, to ground.

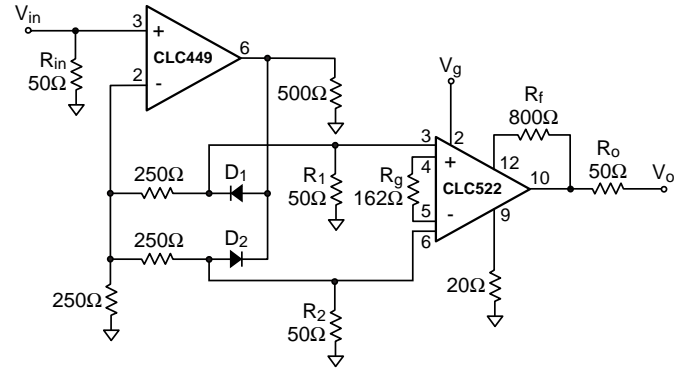


Figure 10: Full-Wave Rectifier

### Flash A/D Application

The Typical Application circuit on the front page shows the CLC449 driving a flash A/D. Flash A/D's require fast settling, low distortion, low noise and wide bandwidth to achieve high Effective Number of Bits and Spurious Free Dynamic Range (SFDR).

This circuit connects a CLC449 to a TDA8716, 8-bit, 120MHz Flash Converter. The input capacitance for this converter is typically 13pF plus layout capacitance. From the  $R_s$  and Settling Time vs.  $C_L$  plot in the **Typical Performance Characteristics** section, select a series resistor ( $R_s$ ) of 55Ω. Place  $R_s$  in series with the output of the CLC449 to achieve settling to 0.1% in approximately 11ns.

Keep the amplifier noise seen at the A/D input at least 3dB lower than the A/D's noise, to avoid degrading A/D noise performance.

## Ordering Information

| Model     | Temperature Range | Description       |
|-----------|-------------------|-------------------|
| CLC449AJP | -40°C to +85°C    | 8-pin PDIP        |
| CLC449AJE | -40°C to +85°C    | 8-pin SOIC        |
| CLC449AMC | -55°C to +125°C   | dice, MIL-STD-883 |

Contact factory for other packages and DESC SMD number.

## Reliability Information

|                  |    |
|------------------|----|
| Transistor count | 26 |
|------------------|----|



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