19-2331: Rev 1: 9/03

3V/5V, 10-Bit, Serial Voltage-Output Dual DACs with Internal Reference

General Description

The MAX5232/MAX5233 low-power, dual 10-bit voltageoutput digital-to-analog converters (DACs) feature an internal 10ppm/°C precision bandgap voltage reference and precision output amplifiers. The MAX5233 operates on a single 5V supply with an internal 2.465V reference and features a 4.092V full-scale output range. The MAX5232 operates on a single 3V supply with an internal 1.234V reference and features a 2.046V full-scale output range. The MAX5233 consumes only 470µA while the MAX5232 consumes only 420µA of supply current. Both devices feature low-power (2µA) software- and hardware-enabled shutdown modes.

The MAX5232/MAX5233 feature a 13.5MHz SPI™-QSPITM-, and MICROWIRETM-compatible 3-wire serial interface. An additional data output (DOUT) allows for daisy-chaining and read back. Each DAC has a doublebuffered digital input. The MAX5232/MAX5233 feature two software-selectable shutdown output impedances: $1k\Omega$ or $200k\Omega$. A power-up reset feature sets DAC outputs at ground or at the midscale DAC code.

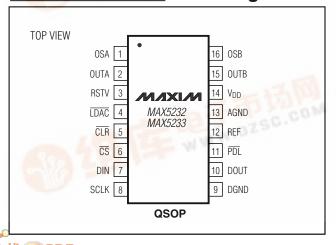
The MAX5232/MAX5233 are specified over the extended temperature range (-40°C to +85°C) and are available in 16-pin QSOP packages.

Applications

Industrial Process Controls Automatic Test Equipment Digital Offset and Gain Adjustment Motion Control

μP-Controlled Systems

Pin Configuration



Features

- ◆ Internal 10ppm/°C Precision Bandgap Reference 2.465V (MAX5233) 1.234V (MAX5232)
- ♦ 30ppm/°C (max) Full-Scale Output Range 4.092V (MAX5233) 2.046V (MAX5232)
- **♦ Single-Supply Operation** 5V (MAX5233) 3V (MAX5232)
- ♦ Low Supply Current 470µA (MAX5233) 420µA (MAX5232)
- ♦ 13.5MHz SPI/QSPI/MICROWIRE-Compatible, 3-Wire Serial Interface
- ♦ Pin-Programmable Power-Up Reset State to Zero or Midscale Output Voltage
- ♦ Programmable Shutdown Modes with 1kΩ or 200kΩ Internal Output Loads
- ♦ Recalls Output State Prior to Shutdown or Reset
- ♦ Buffered Output Drives 5kΩ | 100pF Loads
- ♦ Space-Saving 16-Pin QSOP Package

Ordering Information

PART	TEMP RANGE	NGE PIN- PACKAGE	
MAX5232EEE	-40°C to +85°C	16 QSOP	±0.5
MAX5233EEE	-40°C to +85°C	16 QSOP	±0.5

Functional Diagram appears at end of data sheet.

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ABSOLUTE MAXIMUM RATINGS

V _{DD} to AGND, DGND0.3V to +6V	Maximum Current into Any Pin50mA
AGND to DGND0.3V to +0.3V	Continuous Power Dissipation ($T_A = +70^{\circ}C$)
Digital Inputs to DGND0.3V to +6V	16-Pin QSOP (derate 8.3mW/°C above +70°C)667mW
Digital Output (DOUT) to DGND0.3V to V _{DD} + 0.3V	Operating Temperature Range40°C to +85°C
OUT_ to AGND0.3V to V _{DD} + 0.3V	Storage Temperature Range65°C to +150°C
OS_ to AGND4V to V _{DD} + 0.3V	Lead Temperature (soldering, 10s)+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

ELECTRICAL CHARACTERISTICS—MAX5233

 $(V_{DD} = +4.5V \text{ to } +5.5V, OS_ = AGND = DGND = 0, R_L = 5k\Omega, C_L = 100pF, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted.}$ Typical values are at $T_A = +25^{\circ}C.)$

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
STATIC PERFORMANCE			•			
Resolution	Ν		10			Bits
Integral Nonlinearity (Note 1)	INL				±0.5	LSB
Differential Nonlinearity	DNL				±1	LSB
Offset Error (Note 2)	Vos				±3	mV
Offset-Temperature Coefficient (Note 3)	TCV _{OS}			8		μV/°C
Full-Scale Voltage	VFS	Code = 3FF hex, T _A = +25°C	4.067	4.092	4.117	V
Full-Scale Temperature Coefficient (Notes 3 and 6)	TCVFS			10	30	ppm/°C
Power-Supply Rejection	PSR	$4.5V \le V_{DD} \le 5.5V$		175	500	μV
DC Crosstalk (Note 4)					100	μV
REFERENCE			•			
Output-Voltage	V _{REF}			2.465		V
Output Voltage Temperature Coefficient (Note 3)	TCV _{REF}			10		ppm/°C
Reference External Load Regulation	Vout/Iout	0 ≤ I _{OUT} ≤ 100μA (sourcing)		0.1	2	μV/μΑ
Reference Short-Circuit Current				4		mA
DIGITAL INPUTS			•			
Input High Voltage	VIH		0.7 x V _{DD}			V
Input Low Voltage	VIL				0.3 x V _{DD}	V
Input Hysteresis	V _{HYS}			200		mV
Input Leakage Current	I _{IN}	Digital inputs = 0 or V _{DD}			±1	μΑ
Input Capacitance	CIN			8		рF
DIGITAL OUTPUTS		•	•			
Output High Voltage	V _{OH}	I _{SOURCE} = 2mA	4.25			V
Output Low Voltage	Vol	I _{SINK} = 2mA			0.2	V

ELECTRICAL CHARACTERISTICS—MAX5233 (continued)

 $(V_{DD} = +4.5V \text{ to } +5.5V, OS_ = AGND = DGND = 0, R_L = 5k\Omega, C_L = 100pF, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted.}$ Typical values are at $T_A = +25^{\circ}C.)$

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
DYNAMIC PERFORMANCE	l					
Voltage-Output Slew Rate	SR			0.6		V/µs
Voltage-Output Settling Time		To ±0.5LSB, V _{STEP} = ±4V (V _{DD} - 0.25V) ≥ V _{OUT} ≥ 0.25V		10		μs
Output-Voltage Swing (Note 5)				0 to V _{DD}		V
OS_ Input Resistance	Ros		83	121		kΩ
Time Required for Output to Settle After Turning on V _{DD} (Note 6)				95	400	μs
Time Required for Output to Settle After Exiting Full Power-Down (Note 6)				95	400	μs
Time Required for Output to Settle After Exiting DAC Power-Down (Note 6)				12	160	μs
Digital Feedthrough		CS = V _{DD} , f _{SCLK} = 100kHz, V _{SCLK} = 5V _{P-P}		5		nV-s
Major-Carry Glitch Energy				90		nV-s
POWER SUPPLIES						
Power-Supply Voltage	V_{DD}		4.5		5.5	V
Power-Supply Current (Note 7)	I _{DD}			470	525	μΑ
Dower Cupply Current in Dower Down		Full power-down mode		1.4	5	
Power-Supply Current in Power-Down and Shutdown Modes (Note 7)		One DAC shutdown mode		350	390	μΑ
		Both DACs shutdown mode		235	260	

ELECTRICAL CHARACTERISTICS—MAX5232

 $(V_{DD} = +2.7V \text{ to } +3.6V, OS_ = AGND = DGND = 0, R_L = 5k\Omega, C_L = 100pF, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted.}$ Typical values are at $T_A = +25^{\circ}C.)$

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Resolution	N		10			Bits
Integral Nonlinearity (Note 1)	INL				±0.5	LSB
Differential Nonlinearity	DNL				±1	LSB
Offset Error (Note 2)	Vos				±3	mV
Offset-Temperature Coefficient (Note 3)	TCV _{OS}			8		μV/°C
Full-Scale Voltage	VFS	Code = 3FF hex, T _A = +25°C	2.0335	2.0460	2.0585	V
Full-Scale Temperature Coefficient (Notes 3 and 6)	TCV _{FS}			10	30	ppm/°C
Power-Supply Rejection	PSR	$2.7V \le V_{DD} \le 3.6V$		175	500	μV
DC Crosstalk (Note 4)					100	μV

ELECTRICAL CHARACTERISTICS—MAX5232 (continued)

 $(V_{DD} = +2.7V \text{ to } +3.6V, OS_ = AGND = DGND = 0, R_L = 5k\Omega, C_L = 100pF, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted.}$ Typical values are at $T_A = +25^{\circ}C.)$

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
REFERENCE						
Output Voltage	V _{REF}			1.234		V
Output-Voltage Temperature Coefficient (Note 3)	TCV _{REF}			10		ppm/°C
Reference External Load Regulation	V _{OUT} /I _{OUT}	0 ≤ I _{OUT} ≤ 100µA (sourcing)		0.1	2	μV/μΑ
Reference Short-Circuit Current				4		mA
DIGITAL INPUTS						
Input High Voltage	V _{IH}		0.7 x V _{DD}			V
Input Low Voltage	VIL				$0.3 \times V_{DD}$	V
Input Hysteresis	V _H YS			200		mV
Input Leakage Current	I _{IN}	Digital inputs = 0 or V _{DD}			±1	μΑ
Input Capacitance	C _{IN}			8		рF
DIGITAL OUTPUTS						
Output High Voltage	VoH	ISOURCE = 2mA	2.3			V
Output Low Voltage	VoL	I _{SINK} = 2mA			0.25	V
DYNAMIC PERFORMANCE						
Voltage-Output Slew Rate	SR			0.6		V/µs
Voltage-Output Settling Time		To ±0.5 LSB, $V_{STEP} = \pm 2V$ ($V_{DD} - 0.25V$) $\geq V_{OUT} \geq 0.25V$		10		μs
Output-Voltage Swing (Note 5)				0 to V _{DD}		V
OS_ Input Resistance	Ros		83	121		kΩ
Time Required for Output to Settle After Turning on VDD (Note 6)				95	400	μs
Time Required for Output to Settle After Exiting Full Power-Down (Note 6)				95	400	μs
Time Required for Output to Settle After Exiting DAC Power-Down (Note 6)				12	160	μs
Digital Feedthrough		CS = VDD, fSCLK = 100kHz, VSCLK = 3VP-P		5		nV-s
Major-Carry Glitch Energy				90		nV-s

ELECTRICAL CHARACTERISTICS—MAX5232 (continued)

 $(V_{DD} = +2.7V \text{ to } +3.6V, OS_ = AGND = DGND = 0, R_L = 5k\Omega, C_L = 100pF, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted. Typical values are at } T_A = +25^{\circ}C.)$

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
POWER SUPPLIES						
Power-Supply Voltage	V_{DD}		2.7		3.6	V
Power-Supply Current (Note 7)	I _{DD}			420	475	μΑ
		Full power-down mode		0.9	5	
Power-Supply Current in Power-Down and Shutdown Modes (Note 7)		One DAC shutdown mode		320	360	μΑ
and ondidown wodes (Note 1)		Both DACs shutdown mode		220	245	

Note 1: Accuracy is guaranteed as shown in the following table:

V _{DD}	ACCURACY GUARANTEED					
(V)	FROM CODE	TO CODE				
3	6	1023				
5	3	1023				

- Note 2: Offset is measured at the code closest to 12mV.
- **Note 3:** Temperature coefficient is determined by the box method in which the maximum ΔV_{OUT} over the temperature range is divided by ΔT .
- Note 4: DC crosstalk is measured as follows: set DAC A to midscale, and DAC B to zero, and measure DAC A output; then change DAC B to full scale, and measure ΔV_{OUT} for DAC A. Repeat the same measurement with DAC A and DAC B interchanged. DC crosstalk is the maximum ΔV_{OUT} measured.
- **Note 5:** Accuracy is better than 1LSB for $V_{OUT} = 12 \text{mV}$ to V_{DD} 180 mV.
- Note 6: Guaranteed by design, not production tested.
- **Note 7:** $R_{LOAD} = \infty$ and digital inputs are at either V_{DD} or DGND.

TIMING CHARACTERISTICS—MAX5233

 $(V_{DD} = +4.5V \text{ to } +5.5V, \text{ AGND} = \text{DGND} = 0, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted. Typical values are at } T_A = +25^{\circ}\text{C.})$ (Figures 1 and 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
SCLK Clock Period	tcp		74			ns	
SCLK Pulse Width High	tсн		30			ns	
SCLK Pulse Width Low	tcL		30			ns	
CS Fall to SCLK Rise Setup Time	tcss		30			ns	
SCLK Rise to CS Rise Hold Time	tcsh		0			ns	
DIN Setup Time	t _{DS}		30			ns	
DIN Hold Time	tDH		0			ns	
SCLK Rise to DOUT Valid		C _{LOAD} = 200pF		45	100		
Propagation Delay Time	t _{DO1}	C _{LOAD} = 100pF		30		ns	
SCLK Fall to DOUT Valid		C _{LOAD} = 200pF		45	100		
Propagation Delay Time	t _{DO2}	C _{LOAD} = 100pF		30		ns	
SCLK Rise to CS Fall Delay	tcso		10			ns	
CS Rise to SCLK Rise Hold Time	tcs1		30			ns	
CS Pulse Width High	tcsw		75			ns	
LDAC Pulse Width Low	t _{LDL}		30			ns	
CS Rise to LDAC Rise Hold Time	tcsld	(Note 8)	40			ns	

TIMING CHARACTERISTICS—MAX5232

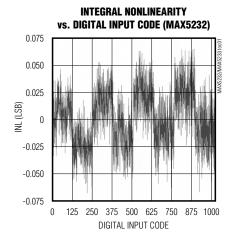
 $(V_{DD} = +2.7V \text{ to } +3.6V, \text{ AGND} = \text{DGND} = 0, T_A = T_{MIN} \text{ to } T_{MAX}, \text{ unless otherwise noted. Typical values are at } T_A = +25^{\circ}\text{C.})$ (Figures 1 and 2)

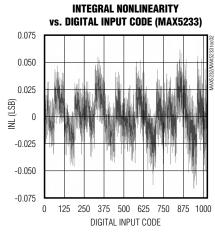
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS	
SCLK Clock Period	tcp		74			ns	
SCLK Pulse Width High	tсн		30			ns	
SCLK Pulse Width Low	tCL		30			ns	
CS Fall to SCLK Rise Setup Time	tcss		30			ns	
SCLK Rise to CS Rise Hold Time	tcsh		0			ns	
DIN Setup Time	t _{DS}		30			ns	
DIN Hold Time	tDH		0			ns	
SCLK Rise to DOUT Valid	4	C _{LOAD} = 200pF		60	200		
Propagation Delay Time	t _{DO1}	C _{LOAD} = 100pF		45		ns	
SCLK Fall to DOUT Valid	+= 0 =	C _{LOAD} = 200pF		60	200	no	
Propagation Delay Time	t _{DO2}	C _{LOAD} = 100pF		45		ns	
SCLK Rise to CS Fall Delay	tcso		10			ns	
CS Rise to SCLK Rise Hold Time	tCS1		30			ns	
CS Pulse Width High	tcsw		75			ns	
LDAC Pulse Width Low	tLDL		30			ns	
CS Rise to LDAC Rise Hold Time	tcsld	(Note 8)	75			ns	

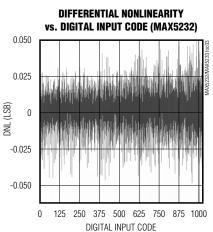
Note 8: This timing requirement applies only to $\overline{\text{CS}}$ rising edges, which execute commands modifying the DAC input register contents.

Typical Operating Characteristics

 $(V_{DD} = +3V \text{ (MAX5230)}, V_{DD} = +5V \text{ (MAX5231)}, R_L = 5k\Omega, C_L = 100pF, OS_ = AGND, both DACs enabled with full-scale output code, T_A = +25°C, unless otherwise noted.)$

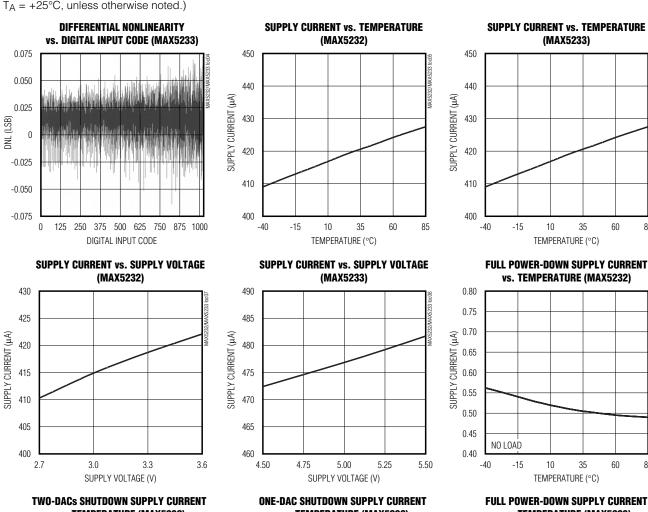


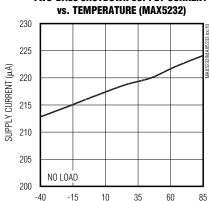




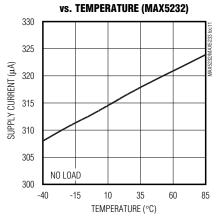
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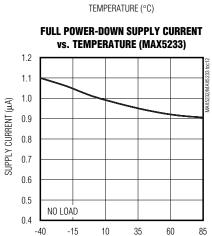
 $(V_{DD} = +3V (MAX5232), V_{DD} = +5V (MAX5233), R_{L} = 5k\Omega, C_{L} = 100pF, OS_{L} = AGND, both DACs enabled with full-scale output code,$ $T_A = +25$ °C, unless otherwise noted.)





TEMPERATURE (°C)





TEMPERATURE (°C)

10

35

60

85

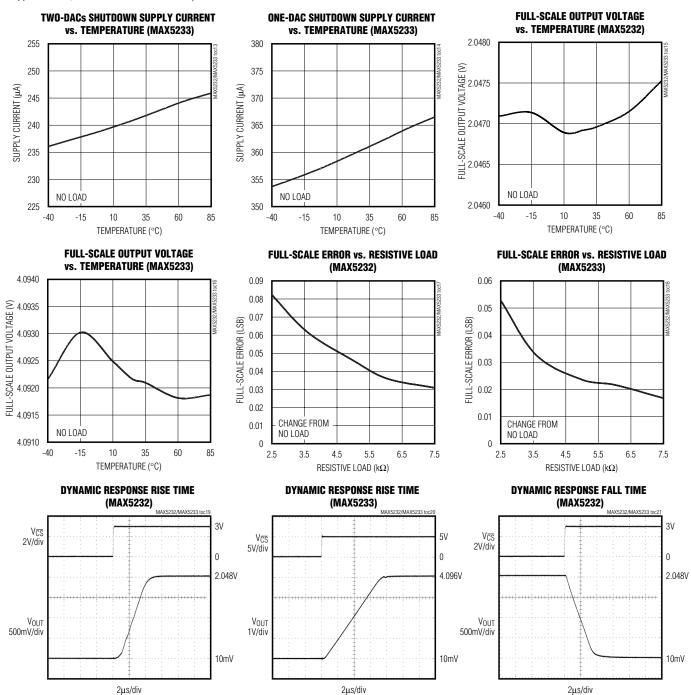
10

35

60

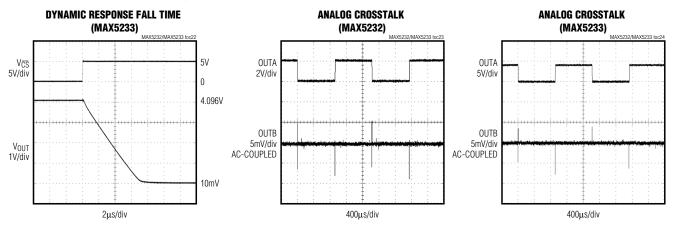
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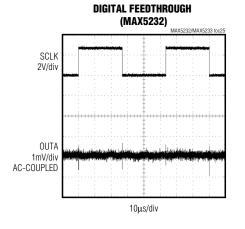
 $(V_{DD} = +3V \text{ (MAX5232)}, V_{DD} = +5V \text{ (MAX5233)}, R_L = 5k\Omega, C_L = 100pF, OS_ = AGND, both DACs enabled with full-scale output code, T_A = +25°C, unless otherwise noted.)$

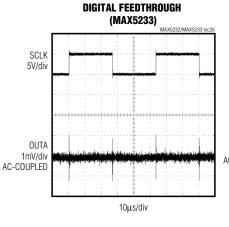


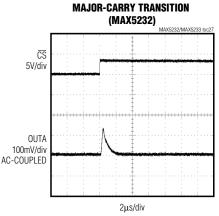
Typical Operating Characteristics (continued)

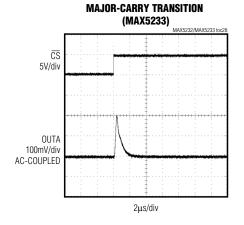
 $(V_{DD} = +3V \text{ (MAX5232)}, V_{DD} = +5V \text{ (MAX5233)}, R_L = 5k\Omega, C_L = 100pF, OS_ = AGND, both DACs enabled with full-scale output code, T_A = +25°C, unless otherwise noted.)$

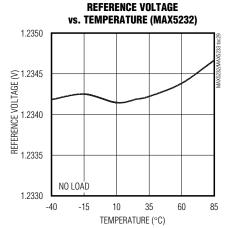


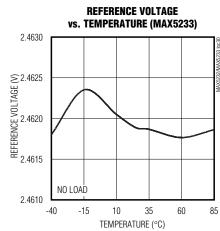












Pin Description

PIN	NAME	FUNCTION
1	OSA	DAC A Offset Adjust
2	OUTA	DAC A Output
3	RSTV	Reset Value Input 1: Connect to V _{DD} to select midscale as the reset value. 0: Connect to DGND to select zero as the reset value.
4	LDAC	Load DACs A and B
5	CLR	Clear Input. Both DAC outputs go to zero or midscale. Clears both DAC internal registers (input register and DAC register) to its predetermined (RSTV) state.
6	CS	Chip-Select Input
7	DIN	Serial Data Input. Data is clocked in on the rising edge of SCLK.
8	SCLK	Serial Clock Input
9	DGND	Digital Ground
10	DOUT	Serial Data Output
11	PDL	Power-Down Lockout. Disables shutdown of both DACs when low.
12	REF	Reference Output. Reference provides a 2.465V (MAX5233) or 1.234V (MAX5232) nominal output.
13	AGND	Analog Ground
14	V _{DD}	Positive Power Supply. Bypass V _{DD} with a 0.1µF capacitor in parallel with a 4.7µF capacitor to AGND, and bypass V _{DD} with a 0.1µF capacitor to DGND.
15	OUTB	DAC B Output
16	OSB	DAC B Offset Adjust

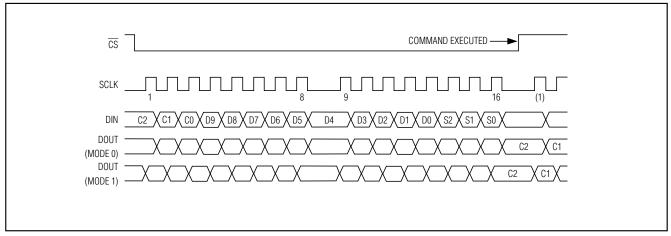


Figure 1. Serial Interface Timing

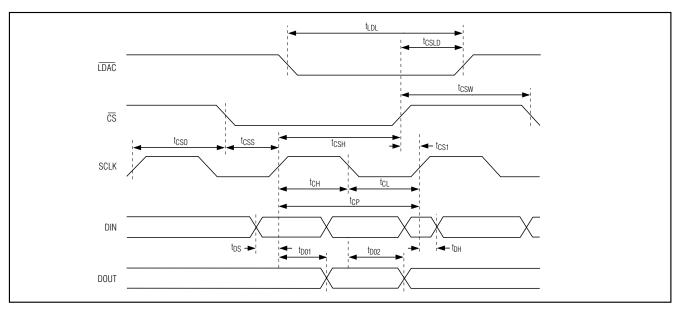


Figure 2. Detailed Serial Interface Timing

Detailed Description

The MAX5232/MAX5233 10-bit, voltage-output DACs are easily configured with a 3-wire SPI-, QSPI-, MICROWIRE-compatible serial interface. The devices include a 16-bit data-in/data-out shift register and have an input consisting of an input register and a DAC register. In addition, these devices employ precision trimmed internal resistors to produce a gain of 1.6384V/V, maximizing the output voltage swing, and a programmable-shutdown output impedance of 1k Ω or 200k Ω The full-scale output voltage is 4.092V for the MAX5233 and 2.046V for the MAX5232. These devices produce a weighted output voltage proportional to the digital input code with an inverted Rail-to-Rail ladder network (Figure 3).

Internal Reference

The MAX5230/MAX5231 use an on-board precision bandgap reference to generate an output voltage of 1.234V (MAX5232) or 2.465V (MAX5233). With a low temperature coefficient of only 10ppm/°C, REF can source up to 100µA and is stable for capacitive loads less than 200pF.

Output Amplifiers

The output amplifiers have internal resistors that provide for a gain of 1.6384V/V when OS_ is connected to AGND. The output amplifiers have a typical slew rate of

Rail-to-Rail is a registered trademark of Nippon Motorola, Ltd.

0.6V/µs and settle to 1/2LSB within 10µs with a load of $5k\Omega$ in parallel with 100pF. Use the serial interface to set the shutdown output impedance of the amplifiers to $1k\Omega$ or $200k\Omega$.

OS_ can be used to produce an offset voltage at the output. For instance, to achieve a 1V offset, apply -1V to OS_ to produce an output range from 1V to (1V + VFS/VREF). Note that the DAC's output range is still limited by the maximum output voltage specification.

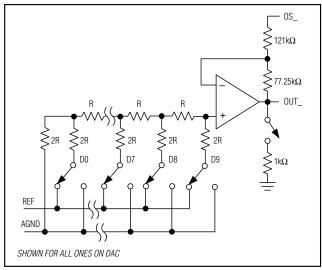


Figure 3. Simplified DAC Circuit Diagram

Table 1. Serial Data Format

MSB <> LSB					
3 Control Bits	MSB 10 Data Bits LSB	Sub-Bit			
C2C0	D9D0	S2, S1, S0			

Serial Interface

The 3-wire serial interface (SPI, QSPI, MICROWIRE compatible) used in the MAX5232/MAX5233 allows for complete control of DAC operations (Figures 4 and 5). Figures 1 and 2 show the timing for the serial interface. The serial word consists of 3 control bits followed by 10 data bits (MSB first) and 1 sub-bit as described in Tables 1, 2, and 3. When the three control bits are all zeros or all 1, D9–D6 are used as additional control bits, allowing for greater DAC functionality.

The digital inputs allow any of the following: loading the input register(s) without updating the DAC register(s), updating the DAC register(s) from the input register(s), or updating the input and DAC register(s) simultane-

ously. The control bits and D9-D6 allow the DACs to operate independently.

Send the 16-bit data as one 16-bit word (QSPI) or two 8-bit packets (SPI, MICROWIRE), with \overline{CS} low during this period. The control bits and D9-D6 determine which registers update and the state of the registers when exiting shutdown. The 3-bit control and D9-D6 determine the following:

- Registers to be updated
- Selection of the power-down and shutdown modes

The general timing diagram of Figure 1 illustrates data acquisition. Driving \overline{CS} low enables the device to receive data. Otherwise the interface control circuitry is disabled. With \overline{CS} low, data at DIN is clocked into the register on the rising edge of SCLK. As \overline{CS} goes high, data is latched into the input and/or DAC registers, depending on the control bits and D9–D6. The maximum clock frequency guaranteed for proper operation is 13.5MHz. Figure 2 depicts a more detailed timing diagram of the serial interface.

Table 2. Serial-Interface Programming Commands

16-BIT SERIAL WORD					FUNCTION	
C2	C1	C0	D9D0	S2-S0	FUNCTION	
0	0	1	10-bit DAC data	000	Load input register A; DAC registers are unchanged.	
0	1	0	10-bit DAC data	000	Load input register A; all DAC registers are updated.	
0	1	1	10-bit DAC data	000	Load all DAC registers from the shift register (start up both DACs with new data, and load the input registers).	
1	0	0	xxxxxxxxx	000	Update both DAC registers from their respective input registers (start up both DACs with data previously stored in the input registers).	
1	0	1	10-bit DAC data	000	Load input register B; DAC registers are unchanged.	
1	1	0	10-bit DAC data	000	Load input register B; all DAC registers are updated.	
1	1	1	P1A P1B X X X X X X X X	000	Shut down both DACs, respectively, according to bits P1A and P1B (see Table 3). Internal bias and reference remain active.	
0	0	0	0 0 1 X X X X X X X	000	Update DAC register A from input register A (start up DAC A with data previously stored in input register A).	
0	0	0	0 1 1 P1A P1B X X X X X	000	Full Power-Down. Power down the main bias generator and shut down both DACs, respectively, according to bits P1A and P1B (see Table 3).	
0	0	0	1 0 1 X X X X X X X	000	Update DAC register B from input register B (start up DAC B with data previously stored in input register B).	
0	0	0	1 1 0 P1A X X X X X X	000	Shut down DAC A according to bit P1A (see Table 3).	
0	0	0	1 1 1 P1B X X X X X X	000	Shut down DAC B according to bit P1B (see Table 3).	
0	0	0	1000XXXXXX	000	Mode 0. DOUT clocked out on SCLK falling edge (default).	
0	0	0	1001XXXXXX	000	Mode 1. DOUT clocked out on SCLK rising edge.	

X = Don't care.

^{*} S0 must be zero for proper operation.

Power-Down and Shutdown Modes

As described in Tables 2 and 3, several serial interface commands put one or both of the DACs into shutdown mode. Shutdown modes are completely independent for each DAC. In shutdown, the amplifier output becomes high impedance, and OUT_ terminates to OS_ through the 200k Ω (typ) gain resistors. Optionally (see Tables 2 and 3), OUT_ can have an additional termination of 1k Ω to AGND.

Full power-down mode shuts down the main bias generator, reference, and both DACs. The shutdown impedance of the DAC outputs can still be controlled independently, as described in Tables 2 and 3.

A serial interface command exits shutdown mode and updates a DAC register. Each DAC can exit shutdown at the same time or independently (see Tables 2 and 3). For example, if both DACs are shut down, updating the DAC A register causes DAC A to power up, while DAC B remains shutdown. In full power-down mode, powering up either DAC also powers up the main bias generator and reference. To change from full power-down to both DACs shutdown requires the waking of at least one DAC between states.

When powering up the MAX5232/MAX5233 (powering V_{DD}), allow 400 μ s (max) for the output to stabilize. When exiting full power-down mode, also allow 400 μ s (max) for the output to stabilize. When exiting DAC shutdown mode, allow 160 μ s (max) for the output to stabilize.

Reset Value (RSTV) and Clear (CLR) Inputs

Driving $\overline{\text{CLR}}$ low asynchronously forces both DAC outputs and all the internal registers (input registers and DAC registers) for both DACs to either zero or midscale, depending on the level at RSTV. RSTV = DGND sets the zero value, and RSTV = VDD sets the midscale value.

The internal power-on reset circuit sets the DAC outputs and internal registers to either zero or midscale when power is first applied to the device, depending on the level at RSTV as described in the preceding paragraph. The DAC outputs are enabled after power is first applied. In order to obtain the midscale value on power-up (RSTV = V_{DD}), the voltage on RSTV must rise simultaneously with the V_{DD} supply.

Table 3. P1 Shutdown Modes

P1 (A/B)	SHUTDOWN MODE		
0	Shut down with internal $1k\Omega$ load to GND		
1	Shut down with internal 200k Ω load to GND		

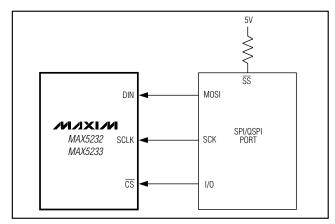


Figure 4. SPI/QSPI Interface Connections

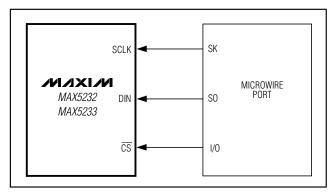


Figure 5. Connections for MICROWIRE

Load DAC Input (LDAC)

Asserting LDAC asynchronously loads the DAC registers from their corresponding input registers (DACs that are shut down remain shut down). The LDAC input is totally asynchronous and does not require any activity on CS, SCLK, or DIN in order to take effect. If LDAC is asserted coincident with a rising edge of CS, which executes a serial command modifying the value of either DAC input register, then LDAC must remain asserted for at least 30ns following the CS rising edge. This requirement applies only for serial commands that modify the value of the DAC input registers.

Power-Down Lockout Input (PDL)

Driving PDL low disables shutdown of either DAC. When PDL is low, serial commands to shut down either DAC are ignored. When either DAC is in shutdown mode, a high-to-low transition on PDL brings the DACs and the reference out of shutdown with DAC outputs set to the state prior to shutdown.

Applications Information

Definitions

Integral Nonlinearity (INL)

Integral nonlinearity (Figure 6a) is the deviation of the values on an actual transfer function from a straight line. This straight line can be either a best-straight-line fit (closest approximation to the actual transfer curve) or a line drawn between the endpoints of the transfer function, once offset and gain errors have been nullified. For a DAC, the deviations are measured at every single step.

Differential Nonlinearity (DNL)

Differential nonlinearity (Figure 6b) is the difference between an actual step height and the ideal value of 1LSB. If the magnitude of the DNL is less than 1LSB, the DAC guarantees no missing codes and is monotonic.

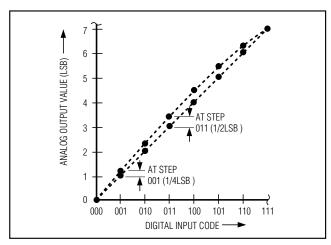


Figure 6a. Integral Nonlinearity

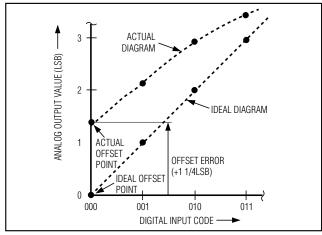


Figure 6c. Offset Error

Offset Error

The offset error (Figure 6c) is the difference between the ideal and the actual offset point. For a DAC, the offset point is the step value when the digital input is zero. This error affects all codes by the same amount and can usually be compensated for by trimming.

Gain Error

Gain error (Figure 6d) is the difference between the ideal and the actual full-scale output voltage on the transfer curve, after nullifying the offset error. This error alters the slope of the transfer function and corresponds to the same percentage error in each step.

Settling Time

The settling time is the amount of time required from the start of a transition, until the DAC output settles to its new output value within the converter's specified accuracy.

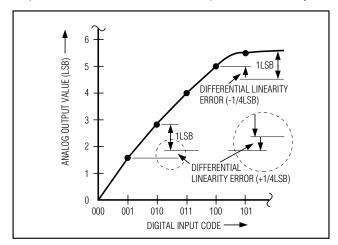


Figure 6b. Differential Nonlinearity

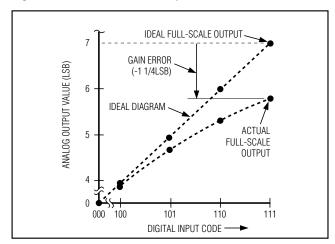


Figure 6d. Gain Error

Table 4. Unipolar Code Table

DAC CONT	ENTS	ANALOG OUTPUT (V)		
MSB	LSB	MAX5232	MAX5233	
1111 1111 11	(000)	2.046	4.092	
1000 0000 01	(000)	1.025	2.050	
1000 0000 00	(000)	1.023	2.046	
0111 1111 11	(000)	1.021	2.042	
0000 0000 01	(000)	0.002	0.004	
0000 0000 00	(000)	0	0	

Digital Feedthrough

Digital feedthrough is noise generated on the DAC's output when any digital input transitions. Proper board layout and grounding significantly reduce this noise, but there is always some feedthrough caused by the DAC itself.

Unipolar Output

Figure 7 shows the MAX5232/MAX5233 configured for unipolar, rail-to-rail operation. The MAX5233 produces a 0 to 4.092V output, while the MAX5232 produces 0 to 2.046V output. Table 4 lists the unipolar output codes.

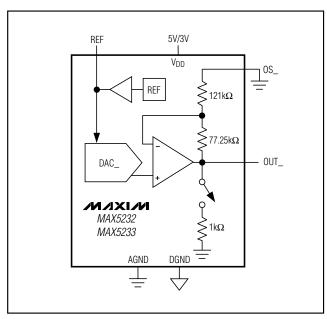


Figure 7. Unipolar Output Circuit (Rail-to-Rail)

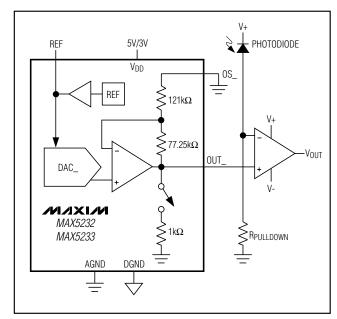


Figure 8. Digital Calibration

Digital Calibration and Threshold Selection

Figure 8 shows the MAX5232/MAX5233 in a digital calibration application. With a bright light value applied to the photodiode (on), the DAC is digitally ramped until it trips the comparator. The microprocessor (μP) stores this high calibration value. Repeat the process with a dim light (off) to obtain the dark current calibration. The μP then programs the DAC to set an output voltage at the midpoint of the two calibrated values. Applications include tachometers, motion sensing, automatic readers, and liquid clarity analysis.

Sharing a Common DIN Line

Several MAX5232/MAX5233s may share one common DIN signal line (Figure 9). In this configuration, the data bus is common to all devices; data is not shifted through a daisy-chain. The SCLK and DIN lines are shared by all devices, but each IC needs its own dedicated \overline{CS} line.

Daisy-Chaining Devices

Any number of MAX5232/MAX5233s can be daisy-chained by connecting the serial data output (DOUT) of one device to the digital input (DIN) of the following device in the chain (Figure 10).

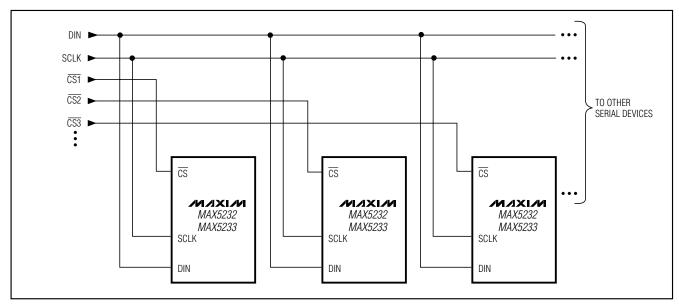


Figure 9. Multiple MAX5230/MAX5231s Sharing a Common DIN Line

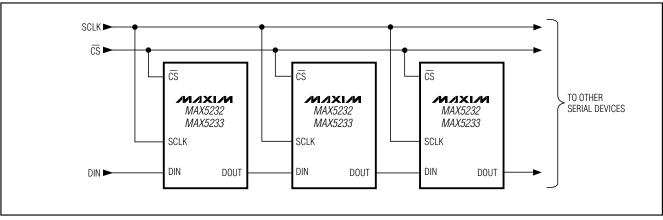


Figure 10. Daisy-Chaining MAX5230/MAX5231 Devices

Power-Supply and Bypassing Considerations

On power-up, the input and DAC registers are cleared to either zero (RSTV = DGND) or midscale (RSTV = V_{DD}). Bypass V_{DD} with a 4.7 μ F capacitor in parallel with a 0.1 μ F capacitor to AGND, and bypass V_{DD} with a 0.1 μ F capacitor to DGND. Minimize lead lengths to reduce lead inductance.

Grounding and Layout Considerations

Digital and AC transient signals on AGND or DGND can create noise at the output. Connect AGND and DGND to the highest quality ground available. Use proper

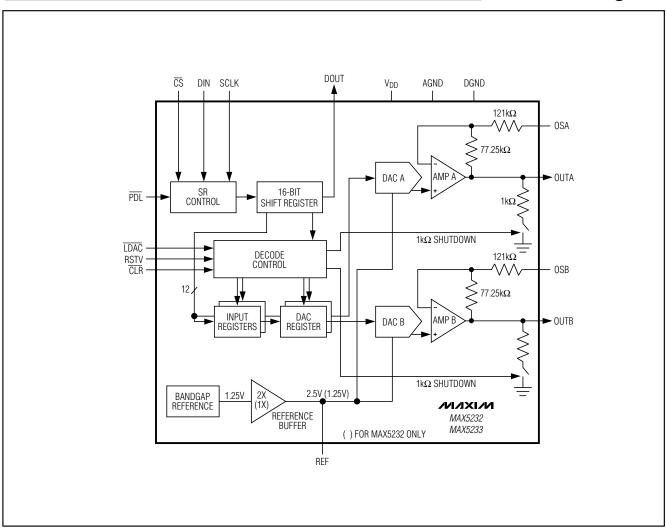
grounding techniques, such as a multilayer board with a low-inductance ground plane or star connect all ground return paths back to the MAX5232/MAX5233 AGND. Carefully lay out the traces between channels to reduce AC cross-coupling and crosstalk. Wire-wrapped boards and sockets are not recommended. If noise becomes an issue, shielding may be required.

_Chip Information

TRANSISTOR COUNT: 4745

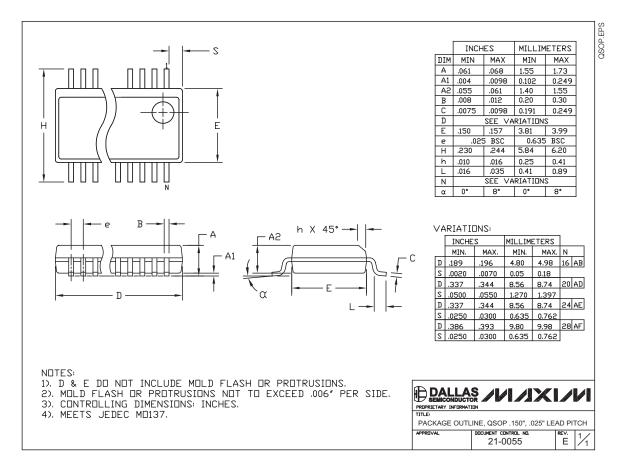
PROCESS: BICMOS

Functional Diagram



Package Information

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information go to www.maxim-ic.com/packages.)



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