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Complete SO-8, 12-Bit, 400ksps ADC with Shutdown

DESCRIPTION

The LTC[®]1400 is a complete 400ksps, 12-bit A/D converter which draws only 75mW from a 5V or \pm 5V supplies. This easy-to-use device comes complete with a 200ns sample-and-hold and a precision reference. Unipolar and bipolar conversion modes add to the flexibility of the ADC. The LTC1400 has two power saving modes: Nap and Sleep. In Nap mode, it consumes only 6mW of power and can wake up and convert immediately. In the Sleep mode, it consumes 30µW of power typically. Upon power-up from Sleep mode, a reference ready (REFRDY) signal is available in the serial data word to indicate that the reference has settled and the chip is ready to convert.

The LTC1400 converts 0V to 4.096V unipolar inputs from a single 5V supply and $\pm 2.048V$ bipolar inputs from $\pm 5V$ supplies. Maximum DC specs include $\pm 1LSB$ INL, $\pm 1LSB$ DNL and $45ppm/^{\circ}C$ drift over temperature. Guaranteed AC performance includes 70dB S/(N + D) and -76dB THD at an input frequency of 100kHz, over temperature.

The 3-wire serial port allows compact and efficient data transfer to a wide range of microprocessors, microcontrollers and DSPs.

T, LTC and LT are registered trademarks of Linear Technology Corporation. MICROWIRE is a trademark of National Semiconductor Corp.

FEATURES

- Complete 12-Bit ADC in SO-8
- Single Supply 5V or ±5V Operation

查询LTC1400供应商

- Sample Rate: 400ksps
- Power Dissipation: 75mW (Typ)
- 72dB S/(N + D) and 80dB THD at Nyquist
- No Missing Codes over Temperature
- Nap Mode with Instant Wake-Up: 6mW
- Sleep Mode: 30µW
- High Impedance Analog Input
- Input Range (1mV/LSB): 0V to 4.096 or ± 2.048V
- Internal Reference Can Be Overdriven Externally
- 3-Wire Interface to DSPs and Processors (SPI and MICROWIRE[™] Compatible)

APPLICATIONS

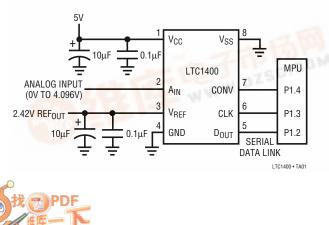
- High Speed Data Acquisition
- Digital Signal Processing
- Multiplexed Data Acquisition Systems
- Audio and Telecom Processing
- Digital Radio
- Spectrum Analysis

'sc.con

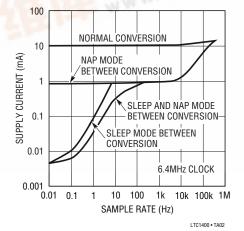
- Low Power and Battery-Operated Systems
- Handheld or Portable Instruments

TYPICAL APPLICATION

Single 5V Supply, 400kHz, 12-Bit Sampling A/D Converter



Power Consumption vs Sample Rate



ABSOLUTE MAXIMUM RATINGS

(Notes 1, 2)
Supply Voltage (V _{CC})
Negative Supply Voltage (V _{SS}) –6V to GND
Total Supply Voltage (V _{CC} to V _{SS})
Bipolar Operation Only 12V
Analog Input Voltage (Note 3)
Unipolar Operation $-0.3V$ to (V _{CC} + 0.3V)
Bipolar Operation $(V_{SS} - 0.3V)$ to $(V_{CC} + 0.3V)$
Digital Input Voltage (Note 4)
Unipolar Operation–0.3V to 12V
Bipolar Operation (V _{SS} – 0.3V) to 12V
Digital Output Voltage
Unipolar Operation $-0.3V$ to (V _{CC} + 0.3V)
Bipolar Operation $(V_{SS} - 0.3V)$ to $(V_{CC} + 0.3V)$
Power Dissipation
Operation Temperature Range
LTC1400C
LTC1400I –40°C to 85°C
Storage Temperature Range –65°C to 150°C
Lead Temperature (Soldering, 10 sec)

PACKAGE/ORDER INFORMATIONORDER PART
NUMBERVcc 18VssVcc 18VssAIN 27CONVVREF 36CLKGND 45Dout

 S8 PACKAGE

 8-LEAD PLASTIC SO

 TJMAX = 150°C, θJA = 130°C/W

 1400

 1400I

Consult factory for PDIP packages and Military grade parts.

POWER REQUIREMENTS (Note 5)

SYMBOL	PARAMETER	CONDITIONS		MIN	TYP	MAX	UNITS
V _{CC} Positive Supply Voltage (Note	Positive Supply Voltage (Note 6)	Unipolar		4.75		5.25	V
		Bipolar		4.75		5.25	V
V _{SS}	Negative Supply Voltage (Note 6)	Bipolar Only		-2.45		-5.25	V
Icc	Positive Supply Current	f _{SAMPLE} = 400ksps	•		15	30	mA
		Nap Mode	•		1.0	3.0	mA
		Sleep Mode	•		5.0	20.0	μA
I _{SS}	Negative Supply Current	f _{SAMPLE} = 400ksps, V _{SS} = -5V	•		0.3	0.6	mA
		Nap Mode	•		0.2	0.5	mA
		Sleep Mode	•		1	5	μA
P _D	Power Dissipation	f _{SAMPLE} = 400ksps	•		75	160	mW
		Nap Mode	•		6	20	mW
		Sleep Mode	•		30	125	μW

ANALOG INPUT (Note 5)

SYMBOL	PARAMETER	CONDITIONS		MIN	ТҮР	MAX	UNITS
V _{IN}	Analog Input Range (Note 7)	$4.75V \le V_{CC} \le 5.25V$ (Unipolar) $4.75V \le V_{CC} \le 5.25V$, $-5.25V \le V_{SS} \le -2.45V$ (Bipolar)	•		0 to 4.096 ±2.048		V V
I _{IN}	Analog Input Leakage Current	During Conversions (Hold Mode)	•			±1	μA
C _{IN}	Analog Input Capacitance	Between Conversions (Sample Mode) During Conversions (Hold Mode)			45 5		pF pF

CONVERTER CHARACTERISTICS With internal reference (Notes 5, 8)

PARAMETER	CONDITIONS	CONDITIONS				UNITS
Resolution (No Missing Codes)		•	12			Bits
Integral Linearity Error	(Note 9)	•			±1	LSB
Differential Linearity Error		•			±1	LSB
Offset Error	(Note 10)	•			±6 ±8	LSB LSB
Full-Scale Error					±15	LSB
Full-Scale Tempco	I _{OUT(REF)} = 0	•		±10	±45	ppm/°C

DYNAMIC ACCURACY $V_{CC} = 5V, V_{SS} = -5V, f_{SAMPLE} = 400 \text{kHz}$

SYMBOL	PARAMETER	CONDITIONS		MIN	ТҮР	MAX	UNITS
S/(N + D)	Signal-to-Noise Plus Distortion Ratio	100kHz Input Signal Commercial Industrial	•	70 69	72		dB dB
		200kHz Input Signal			72		dB
THD	Total Harmonic Distortion Up to 5th Harmonic	100kHz Input Signal 200kHz Input Signal	•		-82 -80	-76	dB dB
	Peak Harmonic or Spurious Noise	100kHz Input Signal 200kHz Input Signal	•		-84 -82	-76	dB dB
IMD	Intermodulation Distortion	f _{IN1} = 99.51kHz, f _{IN2} = 102.44kHz f _{IN1} = 199.12kHz, f _{IN2} = 202.05kHz			-82 -70		dB dB
	Full Power Bandwidth				4		MHz
	Full Linear Bandwidth $(S/(N + D) \ge 68dB)$				900		kHz

INTERNAL REFERENCE CHARACTERISTICS (Note 5)

PARAMETER	CONDITIONS		MIN	ТҮР	MAX	UNITS
V _{REF} Output Voltage	$I_{OUT} = 0$		2.400	2.420	2.440	V
V _{REF} Output Tempco	$I_{OUT} = 0$	•		±10	±45	ppm/°C
V _{REF} Line Regulation	$\begin{array}{c} 4.75V \leq V_{CC} \leq 5.25V \\ -5.25V \leq V_{SS} \leq 0V \end{array}$			0.01 0.01		LSB/V LSB/V
V _{REF} Load Regulation	$0 \le I_{OUT} \le 1$ mA			2		LSB/mA
V _{REF} Wake-Up Time from Sleep Mode (Note 7)	C _{VREF} = 10µF			4		ms

DIGITAL INPUTS AND OUTPUTS (Note 5)

SYMBOL	PARAMETER	CONDITIONS		MIN	ТҮР	MAX	UNITS
V _{IH}	High Level Input Voltage	V _{CC} = 5.25V	•	2.0			V
V _{IL}	Low Level Input Voltage	V _{CC} = 4.75V	•			0.8	V
I _{IN}	Digital Input Current	$V_{IN} = 0V$ to V_{CC}	•			±10	μA
C _{IN}	Digital Input Capacitance				5		pF
V _{OH}	High Level Output Voltage	$V_{CC} = 4.75V, I_0 = -10\mu A$ $V_{CC} = 4.75V, I_0 = -200\mu A$	•	4.0	4.7		V V
V _{OL}	Low Level Output Voltage	$V_{CC} = 4.75V, I_0 = 160\mu A$ $V_{CC} = 4.75V, I_0 = 1.6m A$	•		0.05 0.10	0.4	V V

DIGITAL INPUTS AND OUTPUTS (Note 5)

SYMBOL	PARAMETER	CONDITIONS		MIN	ТҮР	MAX	UNITS
I _{OZ}	Hi-Z Output Leakage D _{OUT}	$V_{OUT} = 0V$ to V_{CC}	•			±10	μA
C _{OZ}	Hi-Z Output Capacitance D _{OUT} (Note 7)				15		pF
ISOURCE	Output Source Current	V _{OUT} = 0			-10		mA
I _{SINK}	Output Sink Current	V _{OUT} = V _{CC}			10		mA

TIMING CHARACTERISTICS (Note 5)

SYMBOL	PARAMETER	CONDITIONS		MIN	ТҮР	MAX	UNITS
f _{SAMPLE(MAX)}	Maximum Sampling Frequency	(Note 6)	•	400			kHz
t _{CONV}	Conversion Time	f _{CLK} = 6.4MHz	•			2.1	μs
t _{ACQ}	Acquisition Time (Unipolar Mode) (Bipolar Mode V _{SS} = -5V)	(Note 7)	•		230 200	300 270	ns ns
f _{CLK}	CLK Frequency		•	0.1		6.4	MHz
t _{CLK}	CLK Pulse Width	(Note 7)	•	50			ns
t _{WK(NAP)}	Time to Wake Up from Nap Mode	(Note 7)			350		ns
t ₁	CLK Pulse Width to Return to Active Mode		•	50			ns
t ₂	CONV↑ to CLK↑ Setup Time		•	80			ns
t ₃	CONV [↑] After Leading CLK [↑]		•	0			ns
t ₄	CONV Pulse Width	(Note 11)	•	50			ns
t ₅	Time from CLK↑to Sample Mode	(Note 7)			80		ns
t ₆	Aperture Delay of Sample-and-Hold	Jitter < 50ps (Note 7)	•		45	65	ns
t ₇			•		265 235	385 355	ns ns
t ₈	Delay Time, CLK↑ to D _{OUT} Valid	C _{LOAD} = 20pF	•		40	80	ns
tg	Delay Time, CLK↑to D _{OUT} Hi-Z	C _{LOAD} = 20pF	•		40	80	ns
t ₁₀	Time from Previous Data Remains Valid After CLK↑	C _{LOAD} = 20pF	•	14	25		ns

The \bullet denotes specifications which apply over the full operating temperature range; all other limits and typicals T_A = 25°C.

Note 1: Absolute Maximum Ratings are those values beyond which the life of a device may be impaired.

Note 2: All voltage values are with respect to GND.

Note 3: When these pin voltages are taken below V_{SS} (ground for unipolar mode) or above V_{CC} , they will be clamped by internal diodes. This product can handle input currents greater than 40mA below V_{SS} (ground for unipolar mode) or above V_{CC} without latch-up.

Note 4: When these pin voltages are taken below V_{SS} (ground for unipolar mode), they will be clamped by internal diodes. This product can handle input currents greater than 40mA below V_{SS} (ground for unipolar mode) without latch-up. These pins are not clamped to V_{CC}.

Note 5: V_{CC} = 5V, f_{SAMPLE} = 400kHz, t_r = t_f = 5ns unless otherwise specified.

Note 6: Recommended operating conditions.

Note 7: Guaranteed by design, not subject to test.

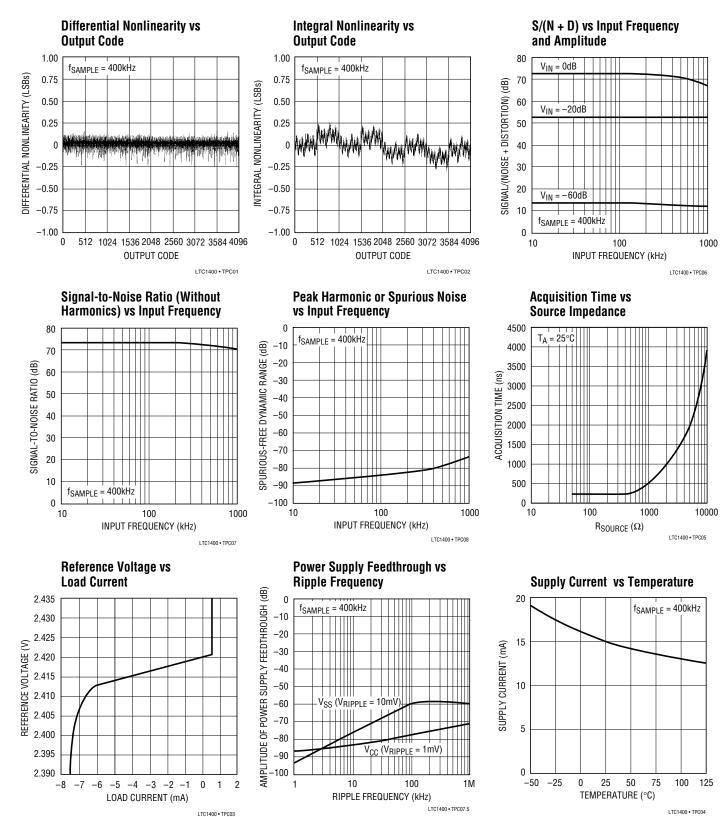
Note 8: Linearity, offset and full-scale specifications apply for unipolar and bipolar modes.

Note 9: Integral nonlinearity is defined as the deviation of a code from a straight line passing through the actual endpoints of the transfer curve. The deviation is measured from the center of the quantization band.

Note 10: Bipolar offset is the offset voltage measured from -0.5LSB when the output code flickers between 0000 0000 0000 and 1111 1111 1111.

Note 11: The rising edge of CONV starts a conversion. If CONV returns low at a bit decision point during the conversion, it can create small errors. For best performance ensure that CONV returns low either within 120ns after conversion starts (i.e., before the first bit decision) or after the 14 clock cycle. (Figure 13 Timing Diagram).

TYPICAL PERFORMANCE CHARACTERISTICS



. . .

PIN FUNCTIONS

 V_{CC} (Pin 1): Positive Supply, 5V. Bypass to GND (10µF tantalum in parallel with 0.1µF ceramic).

A_{IN} (Pin 2): Analog Input. 0V to 4.096V (Unipolar), ±2.048V (Bipolar).

 V_{REF} (Pin 3): 2.42V Reference Output. Bypass to GND (10 μ F tantalum in parallel with 0.1 μ F ceramic).

GND (Pin 4): Ground. GND should be tied directly to an analog ground plane.

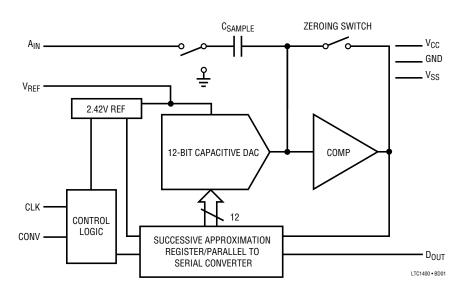
D_{OUT} (**Pin 5**): The A/D conversion result is shifted out from this pin.

CLK (Pin 6): Clock. This clock synchronizes the serial data transfer. A minimum CLK pulse of 50ns will cause the ADC to wake up from Nap or Sleep mode.

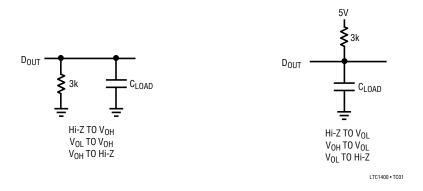
CONV (Pin 7): Conversion Start Signal. This active high signal starts a conversion on its rising edge. Keeping CLK low and pulsing CONV two/four times will put the ADC into Nap/Sleep mode.

 V_{SS} (Pin 8): Negative Supply. -5V for bipolar operation. Bypass to GND with 0.1µF ceramic. V_{SS} should be tied to GND for unipolar operation.

FUNCTIONAL BLOCK DIAGRAM



TEST CIRCUITS



Conversion Details

The LTC1400 uses a successive approximation algorithm and an internal sample-and-hold circuit to convert an analog signal to a 12-bit serial output based on a precision internal reference. The control logic provides easy interface to microprocessors and DSPs through 3-wire connections.

A rising edge on the CONV input starts a conversion. At the start of a conversion the successive approximation register (SAR) is reset. Once a conversion cycle has begun it cannot be restarted.

During conversion, the internal 12-bit capacitive DAC output is sequenced by the SAR from the most significant bit (MSB) to the least significant bit (LSB). Referring to Figure 1, the AIN input connects to the sample-and-hold capacitor during the acquired phase and the comparator offset is nulled by the feedback switch. In this acquire phase, it typically takes 200ns for the sample-and-hold capacitor to acquire the analog signal. During the convert phase, the comparator feedback switch opens, putting the comparator into the compare mode. The input switches connect C_{SAMPLF} to ground, injecting the analog input charge onto the summing junction. This input charge is successively compared with the binary-weighted charges supplied by the capacitive DAC. Bit decisions are made by the high speed comparator. At the end of a conversion, the DAC output balances the AIN input charge. The SAR contents (a 12-bit data word) which represent the input voltage, are output through the serial pin D_{OUT} .

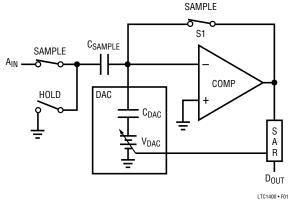


Figure 1. A_{IN} Input

Dynamic Performance

The LTC1400 has excellent high speed sampling capability. FFT (Fast Fourier Transform) test techniques are used to test the ADC's frequency response, distortion and noise at the rated throughput. By applying a low distortion sine wave and analyzing the digital output using an FFT algorithm, the ADC's spectral content can be examined for frequencies outside the fundamental. Figure 2a shows a typical LTC1400 FFT plot.

Signal-to-Noise Ratio

The signal-to-noise plus distortion ratio [S/(N + D)] is the ratio between the RMS amplitude of the fundamental input frequency to the RMS amplitude of all other frequency components at the A/D output. The output is band limited to frequencies from DC to half the sampling frequency. Figure 2a shows a typical spectral content with a 400kHz sampling rate and a 100kHz input. The dynamic performance is excellent for input frequencies up to the Nyquist limit of 200kHz as shown in Figure 2b.

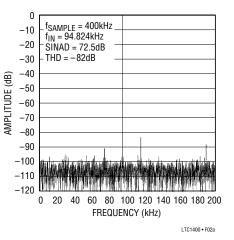


Figure 2a. LTC1400 Nonaveraged, 4096 Point FFT Plot with 100kHz Input Frequency in Bipolar Mode

Effective Number of Bits

The effective number of bits (ENOBs) is a measurement of the effective resolution of an ADC and is directly related to the S/(N + D) by the equation:

$$N = \frac{S/(N+D) - 1.76}{6.02}$$

APPLICATIONS INFORMATION

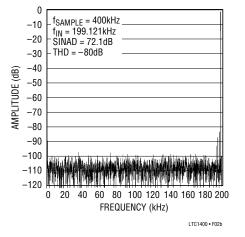


Figure 2b. LTC1400 Nonaveraged, 4096 Point FFT Plot with 200kHz Input Frequency in Bipolar Mode

where N is the effective number of bits of resolution and S/(N + D) is expressed in dB. At the maximum sampling rate of 400kHz, the LTC1400 maintains very good ENOBs up to the Nyquist input frequency of 200kHz (refer to Figure 3).

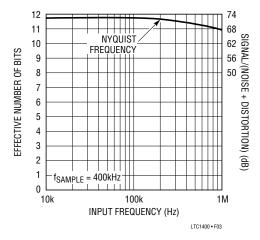


Figure 3. Effective Bits and Signal-to-Noise + Distortion vs Input Frequency in Bipolar Mode

Total Harmonic Distortion

Total harmonic distortion (THD) is the ratio of the RMS sum of all harmonics of the input signal to the fundamental itself. The out-of-band harmonics alias into the frequency band between DC and half of the sampling frequency. THD is expressed as:

$$THD = 20 \log \frac{\sqrt{V2^2 + V3^2 + V4^2 + \dots Vn^2}}{V1}$$

where V1 is the RMS amplitude of the fundamental frequency and V2 through Vn are the amplitudes of the second through nth harmonics. THD vs input frequency is shown in Figure 4. The LTC1400 has good distortion performance up to the Nyquist frequency and beyond.

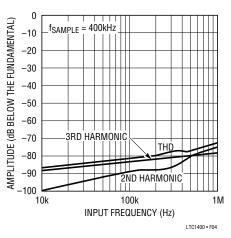


Figure 4. Distortion vs Input Frequency in Bipolar Mode

Intermodulation Distortion

If the ADC input signal consists of more than one spectral component, the ADC transfer function nonlinearity can produce intermodulation distortion (IMD) in addition to THD. IMD is the change in one sinusoidal input caused by the presence of another sinusoidal input at a different frequency.

If two pure sine waves of frequencies fa and fb are applied to the ADC input, nonlinearities in the ADC transfer function can create distortion products at sum and difference frequencies of mfa \pm nfb, where m and n = 0, 1, 2, 3, etc. For example, the 2nd order IMD terms include (fa + fb) and (fa - fb) while the 3rd order IMD terms includes (2fa + fb), (2fa - fb), (fa + 2fb) and (fa - 2fb). If the two input sine waves are equal in magnitude, the value (in decibels) of the 2nd order IMD products can be expressed by the following formula.

 $IMD(fa \pm fb) = 20log \frac{Amplitude at (fa \pm fb)}{Amplitude at fa}$

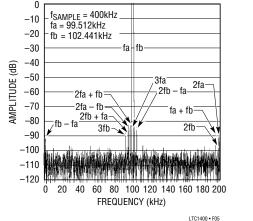


Figure 5. Intermodulation Distortion Plot in Bipolar Mode

Figure 5 shows the IMD performance at a 100kHz input.

Peak Harmonic or Spurious Noise

The peak harmonic or spurious noise is the largest spectral component excluding the input signal and DC. This value is expressed in decibels relative to the RMS value of a full-scale input signal.

Full Power and Full Linear Bandwidth

The full power bandwidth is the input frequency at which the amplitude of the reconstructed fundamental is reduced by 3dB for a full-scale input signal.

The full linear bandwidth is the input frequency at which the S/(N + D) has dropped to 68dB (11 effective bits). The LTC1400 has been designed to optimize input bandwidth, allowing the ADC to undersample input signals with frequencies above the converter's Nyquist Frequency. The noise floor stays very low at high frequencies; S/(N + D) becomes dominated by distortion at frequencies far beyond Nyquist.

Driving the Analog Input

The analog input of the LTC1400 is easy to drive. It draws only one small current spike while charging the sampleand-hold capacitor at the end of a conversion. During conversion, the analog input draws only a small leakage current. The only requirement is that the amplifier driving the analog input must settle after the small current spike before the next conversion starts. Any op amp that settles in 200ns to small load current transient will allow maximum speed operation. If a slower op amp is used, more settling time can be provided by increasing the time between conversions. Suitable devices capable of driving the ADC's $A_{\rm IN}$ input include the LT[®]1360 and the LT1363 op amps.

LTC1400 comes with a built-in unipolar/bipolar detection circuit. If V_{SS} potential is forced below GND, the internal circuitry will automatically switch to bipolar mode.

The following list is a summary of the op amps that are suitable for driving the LTC1400, more detailed information is available in the Linear Technology databooks and the LinearView[™] CD-ROM.

LT 1215/LT1216: Dual and quad 23MHz, 50V/ μ s single supply op amps. Single 5V to \pm 15V supplies, 6.6mA specifications, 90ns settling to 0.5LSB.

LT1223: 100MHz video current feedback amplifier. \pm 5V to \pm 15V supplies, 6mA supply current. Low distortion up to and above 400kHz. Low noise. Good for AC applications.

LT1227: 140MHz video current feedback amplifier. \pm 5V to \pm 15V supplies, 10mA supply current. Lowest distortion at frequencies above 400kHz. Low noise. Best for AC applications.

LT1229/LT1230: Dual and quad 100MHz current feedback amplifiers. $\pm 2V$ to $\pm 15V$ supplies, 6mA supply current each amplifier. Low noise. Good AC specs.

LT1360: 37MHz voltage feedback amplifier. \pm 5V to \pm 15V supplies. 3.8mA supply current. Good AC and DC specs. 70ns settling to 0.5LSB.

LT1363: 50MHz, 450V/ μs op amps. $\pm 5V$ to $\pm 15V$ supplies. 6.3mA supply current. Good AC and DC specs. 60ns settling to 0.5LSB.

LT1364/LT1365: Dual and quad 50MHz, 450V/ μ s op amps. \pm 5V to \pm 15V supplies, 6.3mA supply current per amplifier. 60ns settling to 0.5LSB.

Internal Reference

The LTC1400 has an on-chip, temperature compensated, curvature corrected, bandgap reference, which is factory

APPLICATIONS INFORMATION

trimmed to 2.42V. It is internally connected to the DAC and is available at Pin 3 to provide up to 1mA of current to an external load. For minimum code transition noise, the reference output should be decoupled with a capacitor to filter wideband noise from the reference (10uF tantalum in parallel with a 0.1μ F ceramic). The V_{BFF} pin can be driven with a DAC or other means to provide input span adjustment in bipolar mode. The V_{REF} pin must be driven to at least 2.45V to prevent conflict with the internal reference. The reference should not be driven to more than 5V. Figure 6 shows an LT 1306 op amp driving the reference pin. Figure 7 shows a typical reference, the LT1019A-5 connected to the LTC1360. This will provide an improved drift (equal to the maximum 5ppm/°C of the LT1019A-5) and a $\pm 4.231V$ full scale. If V_{BFF} is forced lower than 2.42V, the REFRDY bit in the serial data output will be forced to low.

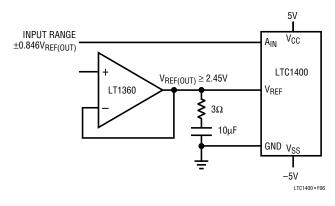


Figure 6. Driving the V_{REF} with the LT1360 Op Amp

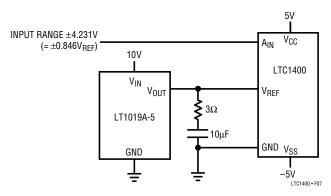


Figure 7. Supplying a 5V Reference Voltage to the LTC1400 with the LT1019A-5

UNIPOLAR / BIPOLAR OPERATION AND ADJUSTMENT

Figure 8 shows the ideal input/output characteristics for the LTC1400. The code transitions occur midway between successive integer LSB values (i.e., 0.5LSB, 1.5LSB, 2.5LSB, ... FS – 1.5LSB). The output code is natural binary with 1LSB = 4.096/4096 = 1mV. Figure 9 shows the input/output transfer characteristics for the bipolar mode in two's complement format.

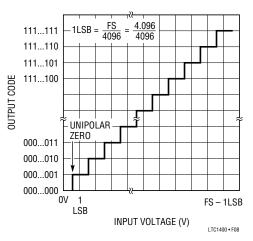


Figure 8. LTC1400 Unipolar Transfer Characteristics

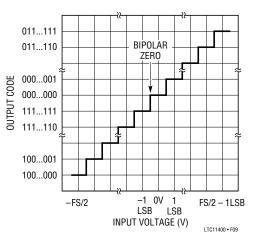


Figure 9. LTC1400 Bipolar Transfer Characteristics

Unipolar Offset and Full-Scale Error Adjustments

In applications where absolute accuracy is important, offset and full-scale errors can be adjusted to zero. Figure 10a shows the extra components required for full-scale

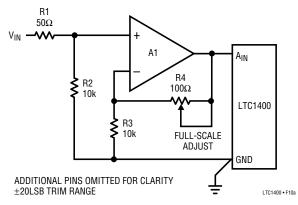


Figure 10a. LTC1400 Full-Scale Adjust Circuit

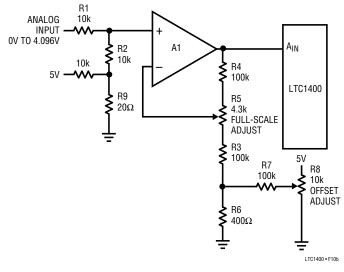


Figure 10b. LTC1400 Offset and Full-Scale Adjust Circuit

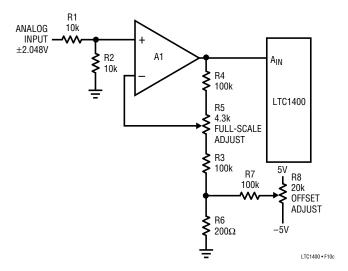


Figure 10c. LTC1400 Bipolar Offset and Full-Scale Adjust Circuit

error adjustment. Figure 10b shows offset and full-scale adjustment. Offset error must be adjusted before full-scale error. Zero offset is achieved by applying 0.5mV (i.e., 0.5LSB) at the input and adjusting the offset trim until the LTC1400 output code flickers between 0000 0000 0000 and 0000 0001. For zero full-scale error, apply an analog input of 4.0945V (FS – 1.5LSB or last code transition) at the input and adjust R5 until the LTC1400 output code flickers between 1111 1111 1111 1111

Bipolar Offset and Full-Scale Error Adjustments

Bipolar offset and full-scale errors are adjusted in a similar fashion to the unipolar case. Bipolar offset error adjustment is achieved by applying an input voltage of -0.5mV (-0.5LSB) to the input in Figure 10c and adjusting the op amp until the ADC output code flickers between 0000 0000 0000 and 1111 1111 1111. For full-scale adjustment, an input voltage of 2.0465V (FS – 1.5LSBs) is applied to the input and R5 is adjusted until the output code flickers between 0111 1111 1110 and 0111 1111 1111.

BOARD LAYOUT AND BYPASSING

To obtain the best performance from the LTC1400, a printed circuit board is required. Layout for the printed circuit board should ensure that digital and analog signal lines are separated as much as possible. In particular, care should be taken not to run any digital track alongside an analog signal track or underneath the ADC. The analog input should be screened by GND.

High quality tantalum and ceramic bypass capacitors should be used at the V_{CC} and V_{REF} pins as shown in the Typical Application on the first page of this data sheet. For the bipolar mode, a 0.1μ F ceramic provides adequate bypassing for the V_{SS} pin. For optimum performance, a 10μ F surface mount AVX capacitor with a 0.1μ F ceramic is recommended for the V_{CC} and V_{REF} pins. The capacitors must be located as close to the pins as possible. The traces connecting the pins and the bypass capacitors must be kept short and should be made as wide as possible. In unipolar mode operation, V_{SS} should be isolated from any noise source before shorting to the GND pin.

Input signal leads to A_{IN} and signal return leads from GND (Pin 4) should be kept as short as possible to minimize noise coupling. In applications where this is not possible, a shielded cable between source and ADC is recommended. Also, since any potential difference in grounds between the signal source and ADC appears as an error voltage in series with the input signal, attention should be paid to reducing the ground circuit impedance as much as possible.

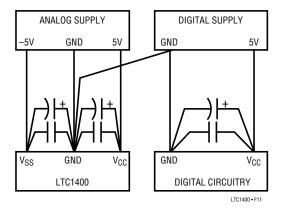


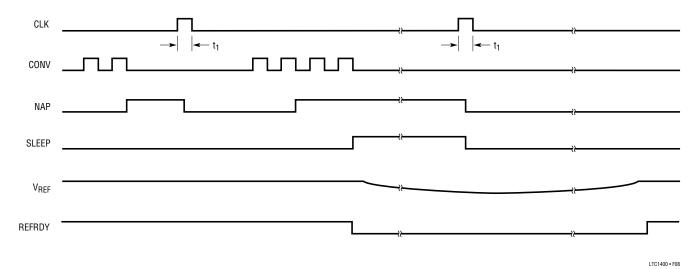
Figure 11. Power Supply Connection

Figure 11 shows the recommended system ground connections. All analog circuitry grounds should be terminated at the LTC1400 GND pin. The ground return from the LTC1400 Pin 4 to the power supply should be low impedance for noise free operation. Digital circuitry grounds must be connected to the digital supply common.

In applications where the ADC data outputs and control signals are connected to a continuously active microprocessor bus, it is possible to get errors in the conversion results. These errors are due to feedthrough from the microprocessor to the successive approximation comparator. The problem can be eliminated by forcing the microprocessor into a Wait state during conversion or by using three-state buffers to isolate the ADC data bus.

Power-Down Mode

Upon power-up, the LTC1400 is initialized to the active state and is ready for conversion. However, the chip can be easily placed into the Nap or Sleep mode by exercising the right combination of CLK and CONV signal. In the Nap mode all power is off except the internal reference, which is still active and provides 2.42V output voltage to the other circuitry. In this mode, the ADC draws only 6mW of power instead of 75mW (for minimum power, the logic inputs must be within 500mV of the supply rails). The wake-up time from the Nap mode to the active mode is



NOTE: NAP AND SLEEP ARE INTERNAL SIGNALS. REFRDY APPEARS AS A BIT IN THE DOUT WORD.

Figure 12. Nap Mode and Sleep Mode Waveforms

350ns. In the Sleep mode, power consumption is reduced to a minimum by cutting off the supply to all internal circuitry including the reference. Figure 12 shows the ways to power down the LTC1400. The chip can enter the Nap mode by keeping the CLK signal low and pulsing the CONV signal twice. For Sleep mode operation, CONV signal should be activated four times while CLK is kept low.

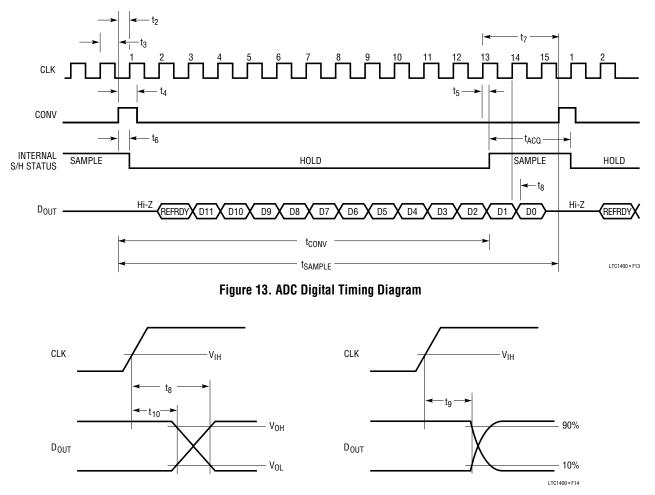
The LTC1400 can be returned to active mode easily. The rising edge of CLK will wake-up the LTC1400. During the transition from Sleep mode to active mode, the V_{REF} voltage ramp-up time is a function of the loading conditions. With a 10µF bypass capacitor, the wake-up time from Sleep mode is typically 4ms. A REFRDY signal will be activated once the reference has settled and is ready for an A/D conversion. This REFRDY bit is output to the D_{OUT} pin before the rest of the A/D converted code.

DIGITAL INTERFACE

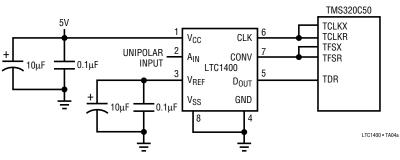
The digital interface requires only three digital lines. CLK and CONV are both inputs, and the D_{OUT} output provides the conversion result in serial form.

Figure 13 shows the digital timing diagram of the LTC1400 during the A/D conversion. The CONV rising edge starts the conversion. Once initiated, it can not be restarted until the conversion is completed. If the time from CONV signal to CLK rising edge is less than t_2 , the digital output will be delayed by one clock cycle.

The digital output data is updated on the rising edge of the CLK line. D_{OUT} data should be captured by the receiving system on the rising CLK edge. Data remains valid for a minimum time of t_{10} after the rising CLK edge to allow capture to occur.

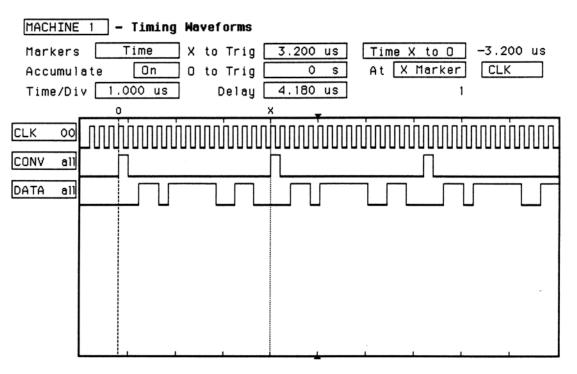






Hardware Interface to TMS320C50's TDM Serial Port (Frame Sync is Generated from TFSX)

Logic Analyzer Waveforms Show 3.2µs Throughput Rate (Input Voltage = 3.046V, Output Code = 1011 1110 0110 = 3046₁₀)



Data from LTC1400 Loaded into TMS320C50's TRCV Register

Х	RDY	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	D0	Х	Х	
---	-----	-----	-----	----	----	----	----	----	----	----	----	----	----	---	---	--

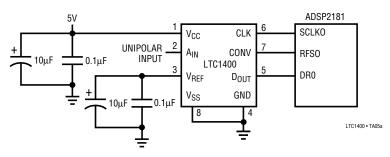
Data Stored in TMS320C50's Memory (in Right Justified Format)

TMS320C50 Code for Circuit

THIS PROGRAM DEMONSTRATES LTC1400 INTERFACE TO TMS320C50 FRAME SYNC PULSE IS GENERATED FROM TFSX

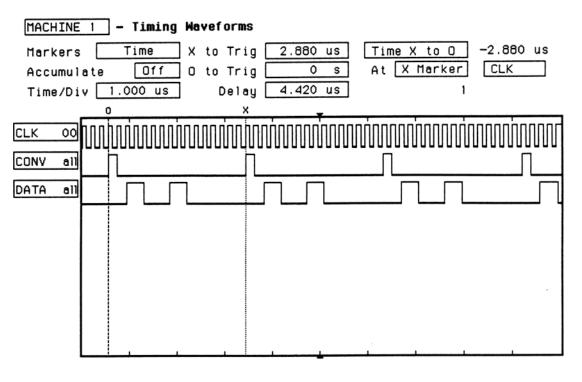
*Initializa				UENERATED FROM IFSA
.mmre				; Defines global symbolic names
; Initiali	ized data n	nemory	to zero	
	.ds	OFOOI	h	; Initialize data to zero
DATAO	.word	0		; Begin sample data location
DATA1	.word	0		;.
DATA2	.word	0		; Location of data
DATA3	.word	0		· · ·
DATA4	.word	0		; .
DATA5	.word	0		; End sample data location
; Set up	o the ISR v			
	.ps	080A		; Serial ports interrupts
rint :	В	RECE		; 0A;
xint :	В		ISMIT	; 0C;
trnt :	В	TREC		; 0E;
txnt :	В	TTRA	NX	; 10;
	the reset	vector		
.ps _. 0A				
.entry				
START:				
*TMS320	050 Initia	lization	*	
SETC	INTM		; Tempoi	rarily disable all interrupts
LDP	#0			a page pointer to zero
0PL	#0834h,	PMST	; Set up t	the PMST status and control register
LACC	#0			-
SAMN	/I CWSR		; Set soft	tware wait state to 0
SAMN	/I PDWSR		;	
Configu	re Serial P	ort		
	#0038h,		· Sot TDI	M Serial Port
	<i>"</i> 000011,	1010		0 Stand Alone mode
				Not loop back
			; FO=0 1	
				Burst Mode
				CLKX is generated internally
				FSX as output pin
				al port into reset
				RRST=0)
	#00F8h,	TSPC	· Tako Qa	erial Port out of reset
	<i>"</i> 001 011,	1010		RRST=1)
	#0FFFFh,	IFR		I the pending interrupts
0 DI 1/				

Start Ser	ial Communicatio	n
SACL	TDXR	; Generate frame sync pulse
	#040h, IMR	; Turn on TRNT receiver interrupt
	INTM	; Enable interrupt
CLRC	SXM	; For Unipolar input, set for right shift
	* 4 0 7	; with no sign extension
MAR LAR		; Load the auxiliary register pointer with seven
LAN	AR7, #0F00h	; Load the auxiliary register seven with #0F00h ; as the begin address for data storage
WAIT:	NOP	; Wait for a receive interrupt
	NOP	
	NOP	
SACL	TDXR	; !! regenerate the frame sync pulse
В	WAIT	,
;	 end of main pro 	ıgram ;
Receiver	Interrupt Service	Routine
TREC:		
LAMM	TRCV	; Load the data received from LTC1400
SFR		; Shift right two times
SFR		· · · AND and with #1FFFh
AND	#1FFFh, 0	; ANDed with #1FFFh
		; For converting the data to right ; justified format
		·
SACL	*+, 0	, Write to data memory pointed by AR7 and
	, -	; increase the memory address by one
LACC		;
		; Compare to end sample address #0F05h
BCND	END_TRCV, GEQ	; If the end sample address has exceeded jump
		to END_TRCV
SDI K	#040h, IMR	, ; Else Re-enable the TRNT receive interrupt
RETE		; Return to main program and enable interrupt
	ainad tha Data fr	om LTC1400, Program Jump to END_TRCV*
END_TRC		JIII LTG1400, Plografii Juliip to END_TRGV
		; Enable INT2 for program to halt
CLRC		, Enable harz for program to hart
SUCCESS		
В	SUCCESS	
Fill the U	nused Interrupt w	<i>i</i> th RETE, to avoid program get "lost"
TTRANX:		
RETE		
RECEIVE:		
RETE		
TRANSMI	T:	
RETE		
INT2: B halt		· Halte the running CDU
DIIdil		; Halts the running CPU



LTC1400 Interface to ADSP2181's SPORTO (Frame Sync is Generated from RFS0)

Logic Analyzer Waveforms Show 2.88µs Throughput Rate (Input Voltage = 2.240V, Output Code = 1000 1100 0000 = 224010)



Data from LTC1400 (Normal Mode)

Х	RDY	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	DO	Х	Х
														LTC14	00 • TA05

Data Stored in ADSP2181's Memory (Normal Mode, SLEN = D)

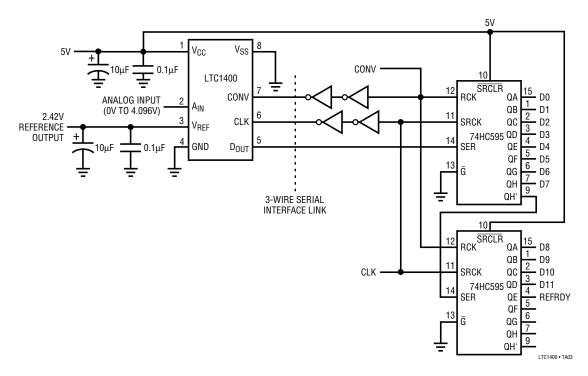
0	0	0	RDY	D11	D10	D9	D8	D7	D6	D5	D4	D3	D2	D1	DO
														LTC14	00 • TA05d

ADSP2181 Code for Circuit

THIS PROGRAM DEMONSTRATES LTC1400 INTERFACE TO ADSP-2181 FRAME SYNC PULSE IS GENERATED FROM RFS0

	MONSTRATES LTC1400 INTERFACE TO ADSP-2181 YNC PULSE IS GENERATED FROM RFS0	/*to configure CLKDIV	CLKDIV and RFSDIV, setup interrupts*/ reg*/		
/*Section 1: Initializati .module/ram/abs = 0 a jump start; nop; nop; nop; rti; ax0 = rx0;		ax0= 2; dm(0x3FF5) =ax0; /*to Configure RFSDIV ax0 = 15; dm(0x3FF4) =ax0; /*to setup interrupt*/ ifc= 0x0066; icntl= 0; imask= 0x0020;	/*set the serial clock divide modulus reg SCLKDIV*/ /*the input clock frequency = 16.67MHz*/ /*CLKOUT frequency = 2x = 33MHz*/ /*SCLK= 1/2*CLKOUT*1/(SCLKDIV+1)*/ /*for SCLKDIV = 2, SCLK = 33/6 = 5.5MHz*/		
/*Section 2: Configure SPORTO*/ start: /*to configure SPORTO control reg*/ /*SPORTO address = 0X3FF6*/ /*RFS is used for frame sync generation*/			/*bit 4 = IRQEB int = 0*/ /*bit 5 = SPORTO receive int = 1*/ /*bit 6 = SPORTO transmit int = 0*/ /*bit 7 = IRQ2B int = 0*/ /*enable SPORTO receive interrupt*/		
ax0 = 0x6B0D; dm (0x3FF6) =ax0;	/*RFS0 is internal, TFS is not use*/ /*bit 0-3 = Slen*/ /*F = 15 = 1111*/ /*E = 14 = 1110*/ /*D = 13 = 1101*/ /*bit 4,5 data type right justified zero filled MSB*/ /*bit 6 INVRFS = 0*/ /*bit 7 INVTFS = 0*/ /*bit 8 IRFS=1 receive internal frame sync*/ /*bit 8 IRFS=1 receive internal frame sync*/ /*bit 12 TFSW=1 receive is Normal mode*/ /*bit 13 RTFS=1 receive is framed mode*/ /*bit 14 ISCLK internal = 1*/ /*bit 15 multichannel mode = 0*/ /*normal mode, bit12=0*/ /*if alternate mode bit12=1, ax0=0x7F0E*/	/*to configure system of ax0 = dm(0x3FFF); ay0 = 0xFFF0; ar = ax0 AND ay0; ay0 = 0x1000; ar = ar OR ay0; dm(0x3FFF) = ar; /*frame sync pulse reg cntr = 5000; do waitloop until ce; nop; nop; nop; nop; nop; nop;	System Control Register and Start Communication*/ control reg*/ /*read the system control reg*/ /*set wait state to zero*/ /*bit12 = 1, enable SPORTO*/ enerated automatically*/		
		nop; waitloop: nop; rts;			

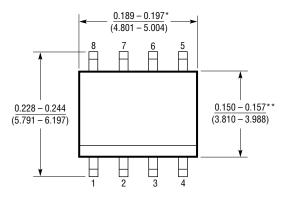
.endmod;

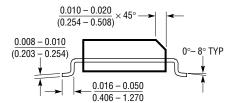


Quick Look Circuit for Converting Data to Parallel Format

PACKAGE DESCRIPTION Dimensions in inches (millimeters) unless otherwise noted.

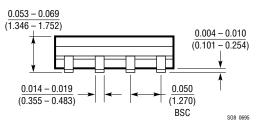
S8 Package 8-Lead Plastic Small Outline (Narrow 0.150) (LTC DWG # 05-08-1610)

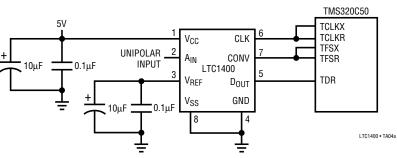




*DIMENSION DOES NOT INCLUDE MOLD FLASH. MOLD FLASH SHALL NOT EXCEED 0.006" (0.152mm) PER SIDE **DIMENSION DOES NOT INCLUDE INTERLEAD FLASH. INTERLEAD

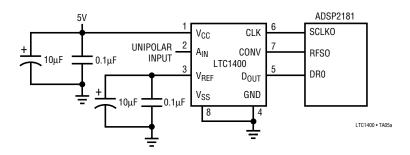
FLASH SHALL NOT EXCEED 0.010" (0.254mm) PER SIDE





LTC1400 Interface to TMS320C50

LTC1400 Interface to ADSP2181



RELATED PARTS

12-Bit Parallel Output ADCs

PART NUMBER	SAMPLE RATE	POWER DISSIPATION	DESCRIPTION
LTC1272	250ksps	75mW	Single 5V, 7572 Upgrade
LTC1273/LTC1275/LTC1276	300ksps	75mW	With Clock and Reference
LTC1274/LTC1277	100ksps	10mW	Low Power ADCs with 1µA Shutdown
LTC1278/LTC1279	500/600ksps	75mW	70dB at Nyquist, Low Power, Single 5V
LTC1282	140ksps	12mW	$3V \text{ or } \pm 3V \text{ ADC}$ with Clock and Reference
LTC1410	1.25Msps	150mW	71dB at Nyquist, Differential Input

12-Bit Serial Output ADCs

PART NUMBER	V _{CC}	SAMPLE RATE	POWER DISSIPATION	DESCRIPTION
LTC1285/LTC1288	3V	7.5/6.6ksps	0.48mW	3V, One or Two Input, Micropower, SO-8
LTC1286/LTC1298	5V	12.5/11.1ksps	1.25mV	One or Two Input, Micropower, SO-8
LTC1290	5/±5V	50ksps	30mW	8 Input, Full-Duplex Serial I/O
LTC1296	5/±5V	46.5ksps	30mW	8 Input, Half-Duplex Serial I/O, Power Shutdown Output