

### General Description

The MAX4100/MAX4101 op amps combine ultra-highspeed performance with low-power operation. The MAX4100 is compensated for unity-gain stability, while the MAX4101 is compensated for stability in applications with a closed-loop gain (A<sub>VCL</sub>) of 2V/V or greater.

The MAX4100/MAX4101 require only 5mA of supply current while delivering a 500MHz unity-gain bandwidth (MAX4100) or a 200MHz -3dB bandwidth (MAX4101) with a 250V/ $\mu$ s slew rate.

These high-speed op amps have a wide output voltage swing of  $\pm 3.5V$  and a high current-drive capability of 80mA.

#### \_Applications

Video Cable Driver

Ultrasound

Gamma Cameras

Portable Instruments

Active Filters

ADC Buffers

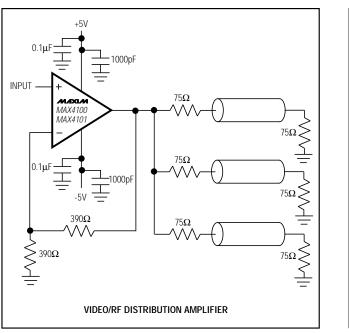
#### \_\_Features

- 500MHz Unity-Gain Bandwidth (MAX4100)
  200MHz -3dB Bandwidth (Avcl = 2V/V, MAX4101)
- 65MHz 0.1dB Gain Flatness (MAX4100)
- ♦ 250V/µs Slew Rate
- ♦ 0.06%/0.04° Differential Gain/Phase
- + High Output Drive: 80mA
- + Low Power: 5mA Supply Current
- Fast Settling Time: 18ns to 0.1% 35ns to 0.01%

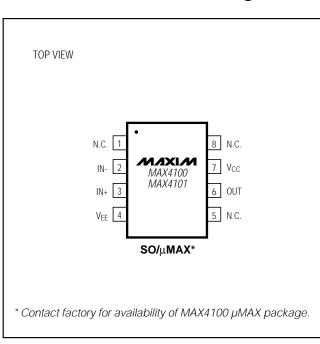
#### \_Ordering Information

PART	TEMP. RANGE	PIN-PACKAGE
MAX4100ESA	-40°C to +85°C	8 SO
MAX4100EUA	-40°C to +85°C	8 µMAX*
MAX4101ESA	-40°C to +85°C	8 SO

\* Contact factory for availability of µMAX package.



Typical Application Circuit



## 

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## Pin Configuration

## **ABSOLUTE MAXIMUM RATINGS**

Power-Supply Voltage (V <sub>CC</sub> , V <sub>EE</sub> )	±6V
Voltage on Any Pin to Ground or Any Other Pin	
Short-Circuit Duration (VOUT to GND)	Indefinite
Continuous Power Dissipation ( $T_A = +70^{\circ}C$ )	
SO (derate 5.88mW/°C above +70°C)	471mW
µMAX (derate 4.10mW/°C above +70°C)	330mW

Operating Temperature Ranges	
MAX4100E_A/MAX4101E_A	40°C to +85°C
Storage Temperature Range	65°C to +160°C
Lead Temperature (soldering, 10sec)	+300°C

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

#### **ELECTRICAL CHARACTERISTICS**

(V<sub>CC</sub> = 5V, V<sub>EE</sub> = -5V, T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted. Typical values are at T<sub>A</sub> = +25°C.)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
DC SPECIFICATIONS			ł				
Input Offset Voltage	Vos	Vout = 0V			1	8	mV
Input Offset Voltage Drift	TCVOS	Vout = 0V			15		µV/°C
Input Bias Current	Ι <sub>Β</sub>	Vout = 0V, VIN = -Vos			3	9	μA
Input Offset Current	los	Vout = 0V, VIN = -Vos			0.05	0.5	μA
Common-Mode Input Resistance	RINCM	Either input			5		MΩ
Common-Mode Input Capacitance	CINCM	Either input			1		pF
Input Valtage Naise		6 100111	MAX4100		8		
Input Voltage Noise	en	f = 100kHz	MAX4101		6		nV/√Hz
Integrated Voltage Noise			MAX4100		100		μV <sub>RMS</sub>
Integrated Voltage Noise		f = 1MHz to 100MHz	MAX4101		75		
Input Current Noice		f = 100kHz	MAX4100	MAX4100 0.8			
Input Current Noise	in		MAX4101		0.8		— pA/√Hz
Integrated Current Naice		f = 1MHz to 100MHz	MAX4100		10	0	
Integrated Current Noise			MAX4101		10		nA <sub>RMS</sub>
Common-Mode Input Voltage	Vcm			-2.5		2.5	V
Common-Mode Rejection	CMR	$V_{CM} = \pm 2.5 V$		75	90		dB
Power-Supply Rejection	PSR	$V_{S} = \pm 4.5 V \text{ to } \pm 5.5 V$		55	60		dB
			RL = ∞	53	58		- dB
Open-Loop Voltage Gain	A <sub>OL</sub>	$V_{OUT} = \pm 2.0V$ , $V_{CM} = 0V$	$R_L = 100\Omega$	51	56		
Quiescent Supply Current	I <sub>SY</sub>	$V_{IN} = 0V$			5	6	mA
Output Voltage Swing	N	RL = ∞		±3.5	±3.8		V
Output Voltage Swing	Vout	$R_L = 100\Omega$		±3.1	±3.5		l v
Output Current		$R_L = 30\Omega$ , $T_A = 0^{\circ}C$ to $+85^{\circ}C$		65	80		mA
Short-Circuit Output Current	I <sub>SC</sub>	Short to ground or either supply voltage			90		mA

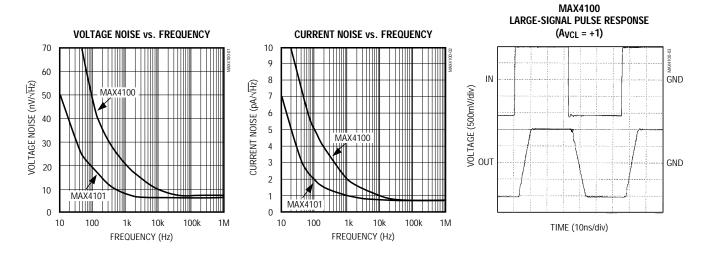
#### **ELECTRICAL CHARACTERISTICS (continued)**

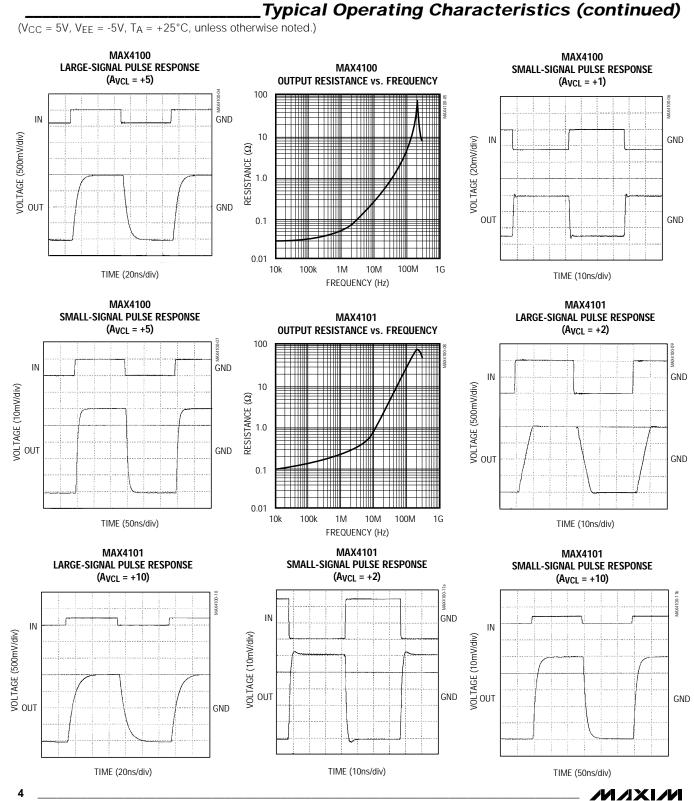
 $(V_{CC} = 5V, V_{EE} = -5V, T_A = T_{MIN}$  to  $T_{MAX}$ , unless otherwise noted. Typical values are at  $T_A = +25^{\circ}C$ .)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS		
AC SPECIFICATIONS								1	
-3dB Bandwidth	BW	Volit < 0.1Vrms		MAX4100		500		MHz	
-SUD Dahuwiulii	DVV			MAX4101		200			
0.1dB Bandwidth		MAX4100, A <sub>VCL</sub> = +1 MAX4100, A <sub>VCL</sub> = +2				65			
					50		- MHz		
Slew Rate	SR	$-2V \le V_{OUT} \le 2V$		250			V/µs		
Sottling Time	+		1000	to 0.1%		18			
Settling Time	ts	$-1V \le V_{OUT} \le 1V$ , $R_L = 100\Omega$		to 0.01%		35		– ns	
Rise/Fall Times	to to	10% to 90%, -2V $\leq$ V <sub>OUT</sub> $\leq$ 2V, R <sub>L</sub> =		100Ω		13		nc	
RISE/Fall TIMES	t <sub>R</sub> , t <sub>F</sub>	10% to 90%, -50mV $\leq$ V <sub>OUT</sub> $\leq$ 50mV, R <sub>L</sub> = 100 $\Omega$			1.5		ns		
Differential Gain	DG	f = 3.58MHz	MAX4100,	$A_{VCL} = +1$		0.06		0/	
Direrential Gain	DG	1 = 3.30IVITZ	MAX4101,	$A_{VCL} = +2$		0.07		- %	
Differential Phase	DP	f = 3.58MHz	MAX4100,	$A_{VCL} = +1$		0.04		dogroop	
	DP	MAX4101, Avcl = +2		$A_{VCL} = +2$		0.04		degrees	
Input Capacitance	CIN					2		pF	
Output Resistance	Dour	f = 10MHz	MAX4100,	$A_{VCL} = +1$		0.8		Ω	
	Rout		MAX4101,	$A_{VCL} = +2$		0.3			
Spurious-Free Dynamic Range	SFDR			$A_{VCL} = +1$		-70		dBc	
				$A_{VCL} = +2$		-65		ubc.	
Third-Order Intercept		$f_C = 10MHz, A_{VCL} = -$	$_{C} = 10MHz, A_{VCL} = +2$			36		dBm	

(V\_{CC} = 5V, V\_{EE} = -5V, T\_A = +25 ^{\circ}C, unless otherwise noted.)

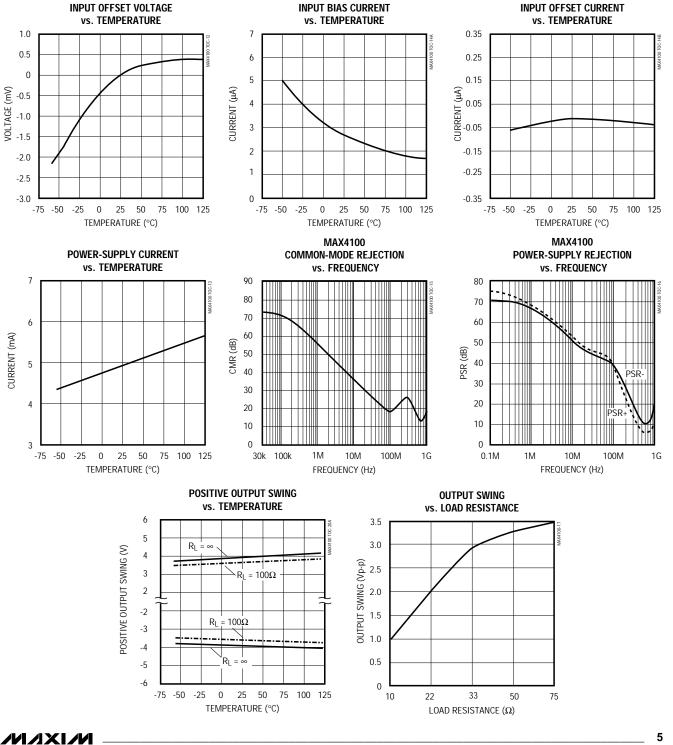
## **Typical Operating Characteristics**

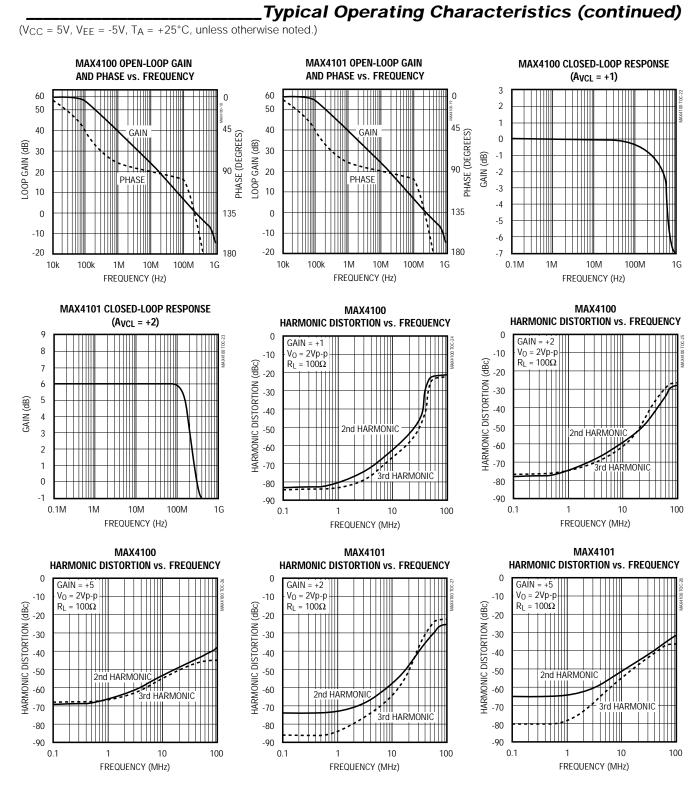




#### **Typical Operating Characteristics (continued)**

 $(V_{CC} = 5V, V_{EE} = -5V, T_A = +25^{\circ}C, unless otherwise noted.)$ 

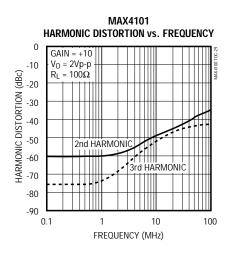




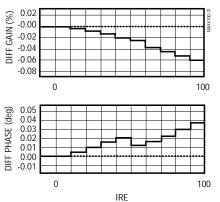
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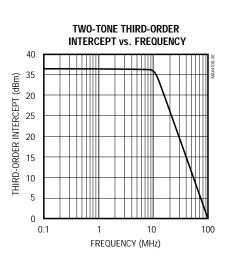
#### **Typical Operating Characteristics (continued)**

 $(V_{CC} = 5V, V_{EE} = -5V, T_A = +25^{\circ}C, unless otherwise noted.)$ 

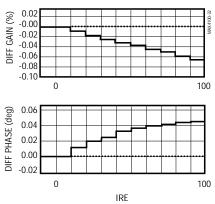


MAX4100 DIFFERENTIAL GAIN AND PHASE





MAX4101 DIFFERENTIAL GAIN AND PHASE



## \_Pin Description

PIN	NAME	FUNCTION	
1, 5, 8	N.C.	No Connection, not internally connected	
2	IN-	Inverting Input	
3	IN+	Noninverting Input	
4	VEE	Negative Power Supply, connected to -5V	
6	OUT	Amplifier Output	
7	V <sub>CC</sub>	Positive Power Supply, connected to +5V	

## \_Detailed Description

The MAX4100/MAX4101 are low-power, high-bandwidth operational amplifiers optimized for driving back-terminated cables in composite video, RGB, and RF systems. The MAX4100 is unity-gain stable, and the MAX4101 is optimized for closed-loop gains greater than or equal to 2V/V (A<sub>VCL</sub>  $\geq$  2V/V). While consuming only 5mA (6mA max) supply current, both devices can drive 50 $\Omega$  back-terminated cables to ±3.1V minimum.

The MAX4100 features a bandwidth in excess of 500MHz and a 0.1dB gain flatness of 65MHz. It offers differential gain and phase errors of 0.06%/0.04°, respectively. The MAX4101 features a -3dB bandwidth of 200MHz, a 0.1dB bandwidth of 50MHz, and 0.07%/0.04° differential gain and phase.

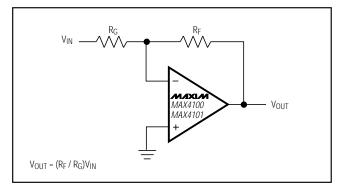
Available in small 8-pin SO and µMAX packages, these ICs are ideally suited for use in portable systems (in RGB, broadcast, or consumer video applications) that benefit from low power consumption.

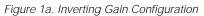
#### \_Applications Information

#### Layout and Power-Supply Bypassing

The MAX4100/MAX4101 have an RF bandwidth and, consequently, require careful board layout. Depending on the size of the PC board used and the frequency of operation, it may be desirable to use constant-impedance microstrip or stripline techniques.

To realize the full AC performance of this high-speed amplifier, pay careful attention to power-supply bypassing and board layout. The PC board should have at least two layers: a signal and power layer on one side, and a large, low-impedance ground plane on the other side. The ground plane should be as free of voids as possible. With multilayer boards, locate the ground plane on a layer that incorporates no signal or power traces.





Regardless of whether a constant-impedance board is used, it is best to observe the following guidelines when designing the board. Wire-wrap boards are much too inductive, and breadboards are much too capacitive; neither should be used. IC sockets increase parasitic capacitance and inductance, and should not be used. In general, surface-mount components give better high-frequency performance than through-hole components. They have shorter leads and lower parasitic reactances. Keep lines as short and as straight as possible. Do not make 90° turns; round all corners.

High-frequency bypassing techniques must be observed to maintain the amplifier accuracy. The bypass capacitors should include a 1000pF ceramic capacitor between each supply pin and the ground plane, located as close to the package as possible. Next, place a 0.01µF to 0.1µF ceramic capacitor in parallel with each 1000pF capacitor, and as close to each as possible. Then place a 10µF to 15µF low-ESR tantalum at the point of entry (to the PC board) of the power-supply pins. The power-supply trace should lead directly from the tantalum capacitor to the V<sub>CC</sub> and V<sub>EE</sub> pins. To minimize parasitic inductance, keep PC traces short and use surface-mount components.

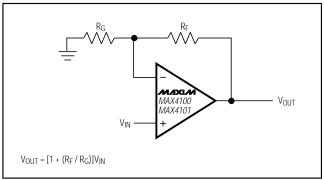


Figure 1b. Noninverting Gain Configuration

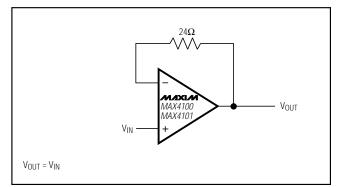


Figure 1c. MAX4100 Unity-Gain Buffer Configuration



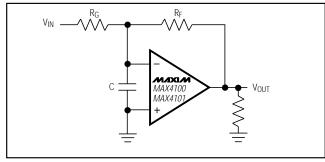


Figure 2. Effect of Feedback Resistor Values and Parasitic Capacitance on Bandwidth

#### Setting Gain

The MAX4100/MAX4101 are voltage-feedback op amps that can be configured as an inverting or noninverting gain block, as shown in Figures 1a and 1b. The gain is determined by the ratio of two resistors and does not affect amplifier frequency compensation.

In the unity-gain configuration (as shown in Figure 1c), maximum bandwidth and stability is achieved with the MAX4100 when a small feedback resistor is included. This resistor suppresses the negative effects of parasitic inductance and capacitance. A value of 24 $\Omega$  provides the best combination of wide bandwidth, low peaking, and fast settling time. In addition, this resistor reduces the errors from input bias currents.

#### **Choosing Resistor Values**

The values of feedback and input resistors used in the inverting or noninverting gain configurations are not critical (as is the case with current feedback amplifiers). However, take care when selecting because the ohmic values need to be kept small and noninductive for practical reasons.

The input capacitance of the MAX4100/MAX4101 is approximately 2pF. In either the inverting or noninverting configuration, the bandwidth limit caused by the package capacitance and resistor time constant is f3dB = 1 / (2 $\Pi$  RC), where R is the parallel combination of the input and feedback resistors (RF and RG in Figure 2) and C is the package and board capacitance at the inverting input. Table 1 shows the bandwidth limit for several values of RF and RG, assuming 4pF total capacitance (2pF for the MAX4100/MAX4101 and 2pF of PC board parasitics).

# Table 1. Resistor and Bandwidth Valuesfor Various Gain Configurations

GAIN (V/V)	Rg (Ω)	Rϝ (Ω)	BANDWIDTH LIMIT* (MHz)
+1	∞	24	1659
+2	200	200	398
+5	50	200	995
+10	30	270	1474
-1	200	200	398
-2	75	150	796
-5	50	250	955
-10	50	500	875

\* Assuming an infinite bandwidth amplifier.

#### **Resistor Types**

Surface-mount resistors are the best choice for highfrequency circuits. They are of similar material to the metal film resistors, but are deposited using a thick-film process in a flat, linear manner so that inductance is minimized. Their small size and lack of leads also minimize parasitic inductance and capacitance, thereby yielding more predictable performance.

#### DC and Noise Errors

There are several major error sources to be considered in any operational amplifier. These apply equally to the MAX4100/MAX4101. Offset-error terms are given by the equation below. Voltage and current noise errors are root-square summed, so are computed separately. Using the circuit in Figure 3, the total output offset voltage is determined by:

- a) The input offset voltage (V<sub>OS</sub>) times the closed-loop gain (1 + R<sub>F</sub> / R<sub>G</sub>)
- b) The positive input bias current ( $I_{B+}$ ) times the source resistor ( $R_S$ ) minus the negative input bias current ( $I_{B-}$ ) times the parallel combination of  $R_G$  and  $R_F$ . Ios (offset current) is the difference between the two bias currents. If  $R_G || R_F = R_S$ , this part of the expression becomes Ios x Rs.

The equation for total DC error is:

$$V_{OUT} = \left(I_{OS}R_{S} + V_{OS}\right)\left(1 + \frac{R_{F}}{R_{G}}\right)$$

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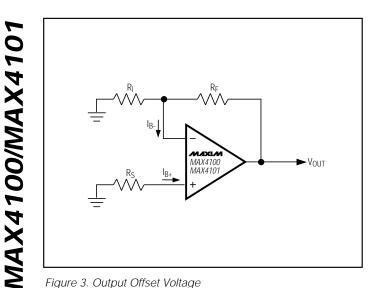


Figure 3. Output Offset Voltage

c) Total output-referred noise voltage is shown by the equation below  $(e_n(OUT))$ :

$$e_{n(OUT)} = \left(1 + \frac{R_F}{R_G}\right) \sqrt{\left(2i_n R_S\right)^2 + \left(e_N\right)^2}$$

The MAX4100/MAX4101, with two high-impedance inputs, have low 8nVVHz voltage noise and only 0.8pAVHz current noise.

An example of DC error calculations, using the MAX4100/MAX4101 typical data and the typical operating circuit with  $R_F = R_G = 200\Omega$  ( $R_S = 100\Omega$ ), gives:

$$V_{OUT} = (I_{OS}R_{S} + V_{OS}) \left(1 + \frac{R_{F}}{R_{G}}\right)$$
$$V_{OUT} = \left(3 \times 10^{-6} \times 10^{2} + 1 \times 10^{-3}\right) (1+1)$$
$$V_{OUT} = 2.6 \text{mV}$$

Calculating total output-referred noise in a similar manner yields:

$$\begin{split} e_{n(OUT)} &= (1+1) \sqrt{\left(2 \times 0.8 \times 10^{-12} \times 100\right)^2 + \left(8 \times 10^{-9}\right)^2} \\ e_{n(OUT)} &= 8nV / \sqrt{Hz} \end{split}$$

With a 200MHz system bandwidth, this calculates to  $133\mu V_{RMS}$  (approximately  $679\mu V_{p-p}$ ).

In both DC and noise calculations, errors are dominated by offset voltage and noise voltage (rather than by input bias current or noise current).

Metal-film resistors with leads are manufactured using a thin-film process, where resistive material is deposited in a spiral layer around a ceramic rod. Although the materials used are noninductive, the spiral winding presents a small inductance (about 5nH) that may have an adverse effect on high-frequency circuits.

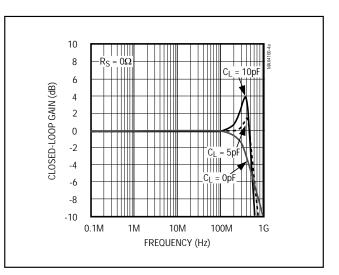


Figure 4a. MAX4100 Bandwidth vs. Capacitive Load

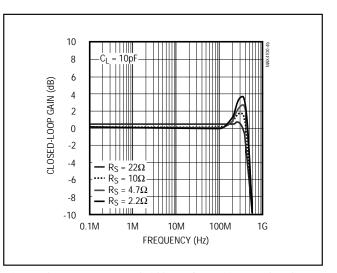


Figure 4b. MAX4100 Bandwidth vs. Capacitive Load and Isolation Resistor



Carbon composition resistors with leads are manufactured by pouring the resistor material into a mold. This process yields a relatively low-inductance resistor that is very useful in high-frequency applications, although they tend to cost more and have more thermal noise than other types. The ability of carbon composition resistors to self-heal after a large current overload makes them useful in high-power RF applications.

For general-purpose use, surface-mount metal-film resistors seem to have the best overall performance for low cost, low inductance, and low noise.

#### Driving Capacitive Loads

When driving  $50\Omega$  or  $75\Omega$  back-terminated transmission lines, capacitive loading is not an issue; therefore an isolation resistor is not required. For other applications where the ability to drive capacitive loads is required, the MAX4100/MAX4101 can typically drive 5pF and 20pF, respectively. Figure 4a illustrates how a capacitive load influences the amplifier's peaking without an isolation resistor (Rs). Figure 4b shows how an isolation resistor decreases the amplifier's peaking.

The MAX4100/MAX4101 can drive capacitive loads up to 5pF. By using a small isolation resistor between the amplifier output and the load, large capacitance values may be driven without oscillation (Figure 5a). In most cases, less than 50 $\Omega$  is sufficient. Use Figure 5b to determine the value needed in your application. Determine the worst-case maximum capacitive load you may encounter and select the appropriate resistor from the graph.

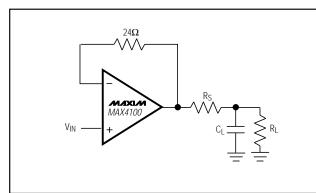


Figure 5a. Using an Isolation Resistor for High Capacitive Loads (MAX4100)

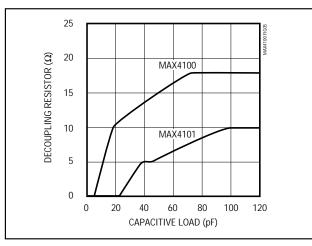
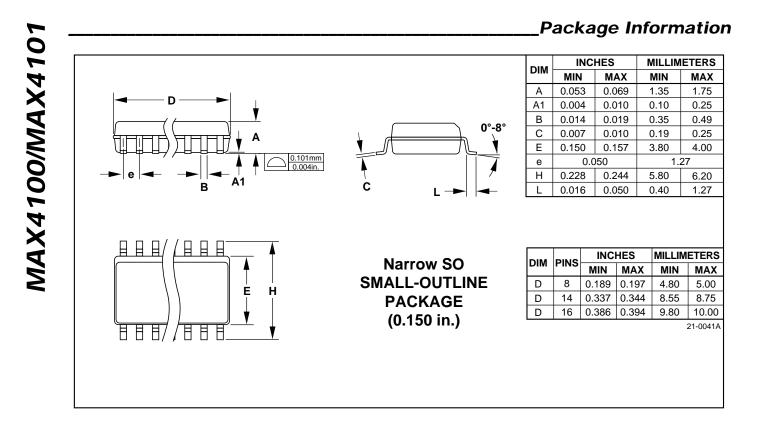


Figure 5b. Isolation vs. Capacitive Load



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