

Preliminary Information

Low Voltage 1:10 Differential LVDS Clock Fanout Buffer

The Motorola MC100ES7111 is a LVDS differential clock fanout buffer. Designed for most demanding clock distribution systems, the MC100ES7111 supports various applications that require the distribution of precisely aligned differential clock signals. Using SiGe technology and a fully differential architecture, the device offers very low skew outputs and superior digital signal characteristics. Target applications for this clock driver are high performance clock distribution in computing, networking and telecommunication systems.

Features:

- 1:10 differential clock fanout buffer
- 50 ps maximum device skew¹
- SiGe technology
- Supports DC to 1000 MHz operation¹ of clock or data signals
- LVDS compatible differential clock outputs
- PECL and HSTL/LVDS compatible differential clock inputs
- 3.3V power supply
- Supports industrial temperature range
- Standard 32 lead LQFP package

Functional Description

The MC100ES7111 is designed for low skew clock distribution systems and supports clock frequencies up to 1000 MHz¹. The device accepts two clock sources. The CLK0 input accepts LVDS or HSTL compatible signals and CLK1 accepts PECL compatible signals. The selected input signal is distributed to 10 identical, differential LVDS compatible outputs.

The output enable control is synchronized internally preventing output runt pulse generation. Outputs are only disabled or enabled when the outputs are already in logic low state (true outputs logic low, inverted outputs logic high). The internal synchronizer eliminates the setup and hold time requirements for the external clock enable signal. The device is packaged in a 7x7 mm² 32-lead LQFP package.

MC100ES7111

**LOW-VOLTAGE
1:10 DIFFERENTIAL
LVDS CLOCK
FANOUT DRIVER**



FA SUFFIX
32-LEAD LQFP PACKAGE
CASE 873A

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1. AC specifications are design targets and subject to change

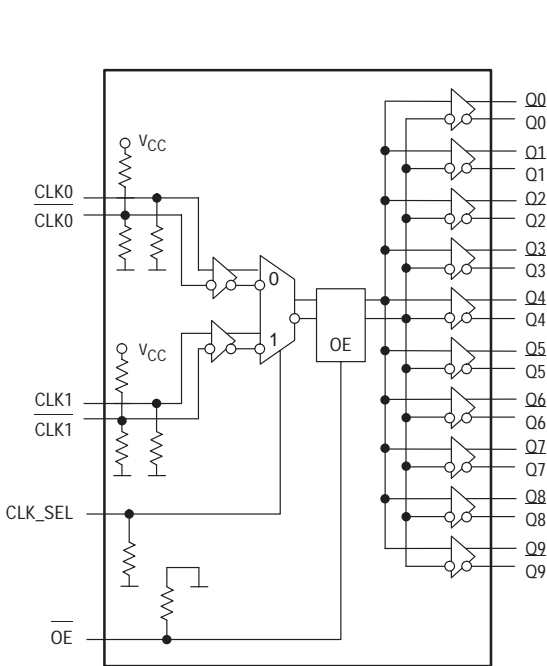


Figure 1. MC100ES7111 Logic Diagram

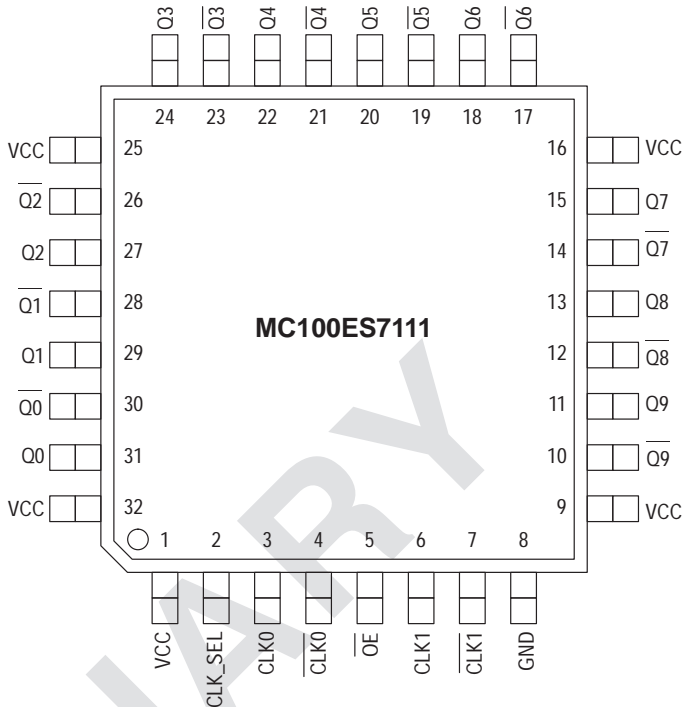


Figure 2. 32-Lead Package Pinout (Top View)

Table 1. PIN CONFIGURATION

| Pin | I/O | Type | Function |
|----------------|--------|-----------|--|
| CLK0, CLK0 | Input | HSTL/LVDS | Differential HSTL or LVDS reference clock signal input |
| CLK1, CLK1 | Input | PECL | Differential PECL reference clock signal input |
| CLK_SEL | Input | LVC MOS | Reference clock input select |
| OE | Input | LVC MOS | Output enable/disable. OE is synchronous to the input reference clock which eliminates possible output runt pulses when the OE state is changed. |
| Q[0-9], Q[0-9] | Output | LVDS | Differential clock outputs |
| GND | Supply | | Negative power supply |
| VCC | Supply | | Positive power supply of the device (3.3V) |

Table 2. FUNCTION TABLE

| Control | Default | 0 | 1 |
|---------|---------|---|--|
| CLK_SEL | 0 | CLK0, CLK0 (HSTL/LVDS) is the active differential clock input | CLK1, CLK1 (PECL) is the active differential clock input |
| OE | 0 | Q[0-9], Q[0-9] are active. Deassertion of OE can be asynchronous to the reference clock without generation of output runt pulses. | Q[0-9] = L, Q[0-9] =H (outputs disabled). Assertion of OE can be asynchronous to the reference clock without generation of output runt pulses. |

Table 3. Absolute Maximum Ratings^a

| Symbol | Characteristics | Min | Max | Unit | Condition |
|-------------------|------------------------------|----------------------|-----------------------|------|-----------|
| V _{CC} | Supply Voltage | -0.3 | 3.9 | V | |
| V _{IN} | DC Input Voltage | -0.3 | V _{CC} + 0.3 | V | |
| V _{OUT} | DC Output Voltage | -0.3 | V _{CC} + 0.3 | V | |
| I _{IN} | DC Input Current | | ±20 | mA | |
| I _{OUT} | DC Output Current | | ±50 | mA | |
| T _S | Storage temperature | -65 | 125 | °C | |
| T _{Func} | Functional temperature range | T _A = -40 | T _J = +110 | °C | |

a. Absolute maximum continuous ratings are those maximum values beyond which damage to the device may occur. Exposure to these conditions or conditions beyond those indicated may adversely affect device reliability. Functional operation at absolute-maximum-rated conditions is not implied.

Table 4. General Specifications

| Symbol | Characteristics | Min | Typ | Max | Unit | Condition |
|-----------------|--|------|------|------|------|--------------------------------|
| MM | ESD Protection (Machine model) | 200 | | | V | |
| HBM | ESD Protection (Human body model) | 2000 | | | V | |
| CDM | ESD Protection (Charged device model) | TBD | | | V | |
| LU | Latch-up immunity | 200 | | | mA | |
| C _{IN} | Input Capacitance | | 4.0 | | pF | Inputs |
| θ _{JA} | Thermal resistance junction to ambient JESD 51-3, single layer test board | | 83.1 | 86.0 | °C/W | Natural convection |
| | | | 73.3 | 75.4 | °C/W | 100 ft/min |
| | | | 68.9 | 70.9 | °C/W | 200 ft/min |
| | | | 63.8 | 65.3 | °C/W | 400 ft/min |
| | | | 57.4 | 59.6 | °C/W | 800 ft/min |
| | JESD 51-6, 2S2P multilayer test board | | 59.0 | 60.6 | °C/W | Natural convection |
| | | | 54.4 | 55.7 | °C/W | 100 ft/min |
| | | | 52.5 | 53.8 | °C/W | 200 ft/min |
| | | | 50.4 | 51.5 | °C/W | 400 ft/min |
| | | | 47.8 | 48.8 | °C/W | 800 ft/min |
| θ _{JC} | Thermal resistance junction to case | | 23.0 | 26.3 | °C/W | MIL-SPEC 883E Method 1012.1 |
| T _J | Operating junction temperature ^a (continuous operation) MTBF = 9.1 years | | | 110 | °C | |

a. Operating junction temperature impacts device life time. Maximum continuous operating junction temperature should be selected according to the application life time requirements (See application note AN1545 and the application section in this datasheet for more information). The device AC and DC parameters are specified up to 110°C junction temperature allowing the MC100ES7111 to be used in applications requiring industrial temperature range. It is recommended that users of the MC100ES7111 employ thermal modeling analysis to assist in applying the junction temperature specifications to their particular application.

Table 5. DC Characteristics ($V_{CC} = 3.3V \pm 5\%$, $T_J = 0^\circ\text{C}$ to $+110^\circ\text{C}$)^a

| Symbol | Characteristics | Min | Typ | Max | Unit | Condition |
|--|---|----------------|------------|----------------|------|-------------------------------|
| Clock input pair CLK0, CLK0 (HSTL/LVDS differential signals) | | | | | | |
| V_{DIF} | Differential input voltage ^b | 0.2 | | | V | |
| $V_{X, IN}$ | Differential cross point voltage ^c | 0.25 | 0.68 - 0.9 | $V_{CC}-1.3$ | V | |
| V_{IH} | Input high voltage | $V_X+0.1$ | | | V | |
| V_{IL} | Input low voltage | | | $V_X-0.1$ | V | |
| I_{IN} | Input Current | | | ± 150 | mA | $V_{IN} = V_X \pm 0.1V$ |
| Clock input pair CLK1, CLK1 (PECL differential signals) | | | | | | |
| V_{PP} | Differential input voltage ^d | 0.15 | | 1.0 | V | Differential operation |
| V_{CMR} | Differential cross point voltage ^e | 1.0 | | $V_{CC}-0.6$ | V | Differential operation |
| V_{IH} | Input voltage high | $V_{CC}-1.165$ | | $V_{CC}-0.880$ | V | |
| V_{IL} | Input voltage low | $V_{CC}-1.810$ | | $V_{CC}-1.475$ | V | |
| I_{IN} | Input Current ^a | | | ± 150 | mA | $V_{IN} = V_{IH}$ or V_{IL} |
| LVCMOS control inputs OE, CLK_SEL | | | | | | |
| V_{IL} | Input voltage low | | | 0.8 | V | |
| V_{IH} | Input voltage high | 2.0 | | | V | |
| I_{IN} | Input Current | | | ± 150 | mA | $V_{IN} = V_{IH}$ or V_{IL} |
| LVDS clock outputs (Q[0-9], Q[0-9]) | | | | | | |
| V_{PP} | Output Differential Voltage (peak-to-peak) | 250 | | | mV | LVDS |
| V_{OS} | Output Offset Voltage | 1125 | | 1275 | mV | LVDS |
| Supply current | | | | | | |
| I_{CC} | Maximum Quiescent Supply Current without output termination current | | TBD | TBD | mA | V_{CC} pin (core) |

a. DC characteristics are design targets and pending characterization.

b. V_{DIF} (DC) is the minimum differential HSTL/LVDS input voltage swing required for device functionality.

c. V_X (DC) is the crosspoint of the differential HSTL/LVDS input signal. Functional operation is obtained when the crosspoint is within the V_X (DC) range and the input swing lies within the V_{PP} (DC) specification.

d. V_{PP} (DC) is the minimum differential input voltage swing required to maintain device functionality.

e. V_{CMR} (DC) is the crosspoint of the differential input signal. Functional operation is obtained when the crosspoint is within the V_{CMR} (DC) range and the input swing lies within the V_{PP} (DC) specification.

Table 6. AC Characteristics ($V_{CC} = 3.3V \pm 5\%$, $T_J = 0^\circ C$ to $+110^\circ C$) ^a

| Symbol | Characteristics | Min | Typ | Max | Unit | Condition |
|--|--|------------------------|------|------------------------|------|--------------------|
| Clock input pair CLK0, CLK0 (HSTL/LVDS differential signals) | | | | | | |
| V_{DIF} | Differential input voltage ^c (peak-to-peak) | 0.4 | | | V | |
| V_X, IN | Differential cross point voltage ^d | 0.68 | | 1.275 | V | |
| f_{CLK} | Input Frequency | | 1000 | TBD | MHz | |
| t_{PD} | Propagation Delay CLK0 to Q[0-9] | | | TBD | ps | |
| Clock input pair CLK1, CLK1 (PECL differential signals) | | | | | | |
| V_{PP} | Differential input voltage ^e (peak-to-peak) | 0.2 | | 1.0 | V | |
| V_{CMR} | Differential input crosspoint voltage ^f | 1 | | $V_{CC}-0.6$ | V | |
| f_{CLK} | Input Frequency | | 1000 | | MHz | Differential |
| t_{PD} | Propagation Delay CLK1 to Q[0-9] | | | TBD | ps | Differential |
| LVDS clock outputs (Q[0-9], Q[0-9]) | | | | | | |
| $t_{sk(O)}$ | Output-to-output skew | | | 50 | ps | Differential |
| $t_{sk(PP)}$ | Output-to-output skew (part-to-part) | | | TBD | ps | Differential |
| $t_{JIT(CC)}$ | Output cycle-to-cycle jitter | | | TBD | | |
| DC_O | Output duty cycle | TBD | 50 | TBD | % | $DC_{fref} = 50\%$ |
| t_r, t_f | Output Rise/Fall Time | 0.05 | | TBD | ns | 20% to 80% |
| t_{PDL}^g | Output disable time | $2.5 \cdot T + t_{PD}$ | | $3.5 \cdot T + t_{PD}$ | ns | $T = CLK$ period |
| t_{PLD}^h | Output enable time | $3 \cdot T + t_{PD}$ | | $4 \cdot T + t_{PD}$ | ns | $T = CLK$ period |

a. AC characteristics are design targets and pending characterization.

b. AC characteristics apply for parallel output termination of 50Ω to V_{TT} .

c. V_{DIF} (DC) is the minimum differential HSTL/LVDS input voltage swing required for device functionality.

d. V_X (DC) is the crosspoint of the differential HSTL/LVDS input signal. Functional operation is obtained when the crosspoint is within the V_X (DC) range and the input swing lies within the V_{DIF} (DC) specification.

e. V_{PP} (AC) is the minimum differential PECL input voltage swing required to maintain AC characteristics including t_{pd} and device-to-device skew.

f. V_{CMR} (AC) is the crosspoint of the differential HSTL input signal. Normal AC operation is obtained when the crosspoint is within the V_{CMR} (AC) range and the input swing lies within the V_{PP} (AC) specification. Violation of V_{CMR} (AC) or V_{PP} (AC) impacts the device propagation delay, device and part-to-part skew.

g. Propagation delay \overline{OE} deassertion to differential output disabled (differential low: true output low, complementary output high).

h. Propagation delay OE assertion to output enabled (active).

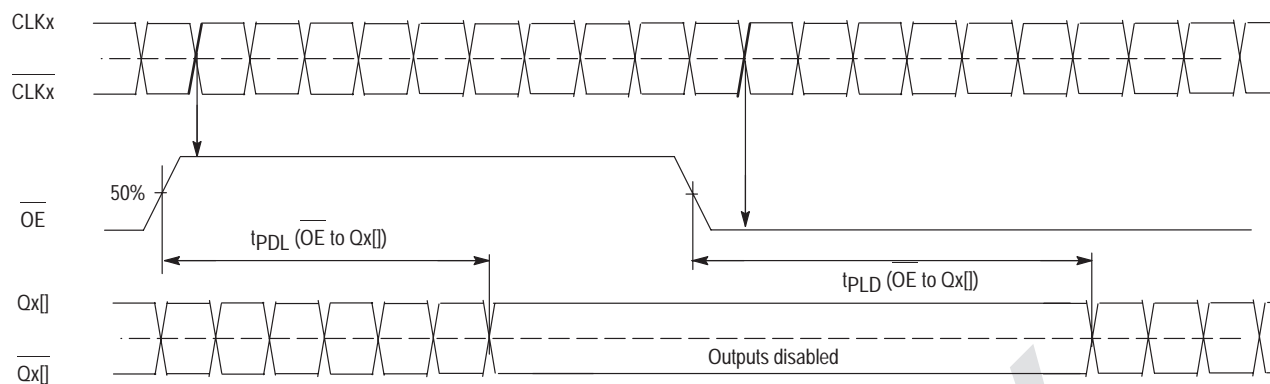


Figure 3. MC100ES7111 AC test reference

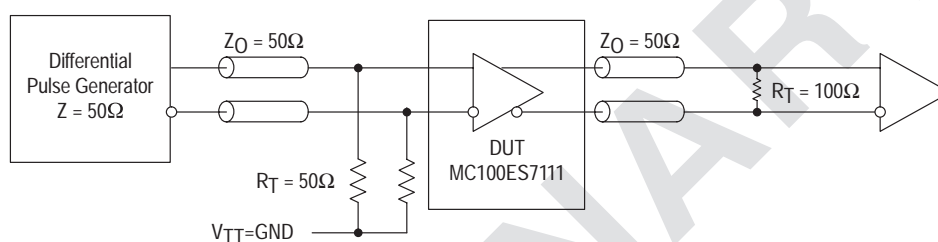


Figure 4. MC100ES7111 AC test reference

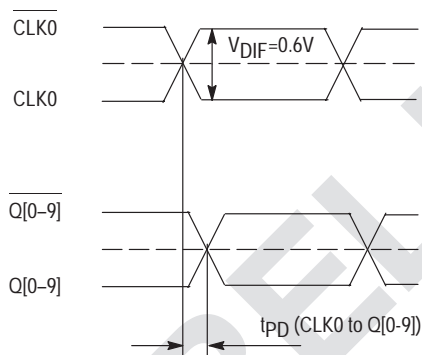


Figure 5. MC100ES7111 AC reference measurement waveform (HSTL input)

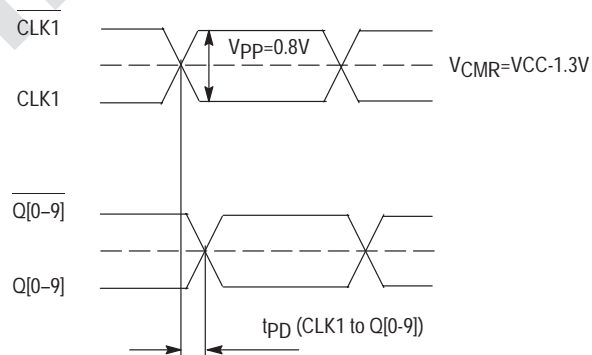


Figure 6. MC100ES7111 AC reference measurement waveform (PECL input)

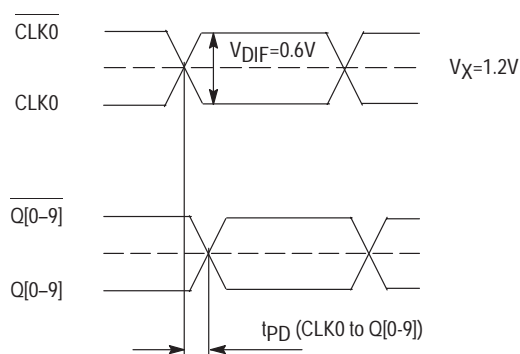


Figure 7. MC100ES7111 AC reference measurement waveform (LVDS input)

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