32K x 9 Bit Synchronous Dual I/O or Separate I/O Fast Static RAM with Parity Checker

The MCM62110 is a 294,912 bit synchronous static random access memory organized as 32,768 words of 9 bits, fabricated using Motorola's high–performance silicon–gate CMOS technology. The device integrates a 32K x 9 SRAM core with advanced peripheral circuitry consisting of address registers, two sets of input data registers, two sets of output latches, active high and active low chip enables, and a parity checker. The RAM checks odd parity during RAM read cycles. The data parity error (DPE) output is an open drain type output which indicates the result of this check. This device has increased output drive capability supported by multiple power pins. In addition, the output levels can be either 3.3 V or 5 V TTL compatible by choice of the appropriate output bus power supply.

The device has both asynchronous and synchronous inputs. Asynchronous inputs include the processor output enable (\overline{POE}), system output enable (\overline{SOE}), and the clock (K).

The address (A0 – A14) and chip enable ($\overline{E1}$ and E2) inputs are synchronous and are registered on the falling edge of K. Write enable (\overline{W}), processor input enable (\overline{PIE}) and system input enable (\overline{SIE}) are registered on the rising edge of K. Writes to the RAM are self–timed.

All data inputs/outputs, PDQ0 – PDQ7, SDQ0 – SDQ7, PDQP, and SDQP have input data registers triggered by the rising edge of the clock. These pins also have three—state output latches which are transparent during the high level of the clock and latched during the low level of the clock.

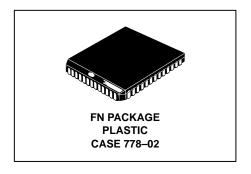
This device has a special feature which allows data to be passed through the RAM between the system and processor ports in either direction. This streaming is accomplished by latching in data from one port and asynchronously output enabling the other port. It is also possible to write to the RAM while streaming.

Additional power supply pins have been utilized for maximum performance. The output buffer power (V $_{CCQ}$) and ground pins (V $_{SSQ}$) are electrically isolated from V $_{SS}$ and V $_{CC}$, and supply power and ground only to the output buffers. This allows connecting the output buffers to 3.3 V instead of 5.0 V if desired. If 3.3 V output levels are chosen, the output buffer impedance in the "high" state is approximately equal to the impedance in the "low" state thereby allowing simplified transmission line terminations.

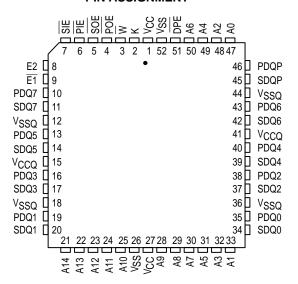
The MCM62110 is available in a 52–pin plastic leaded chip carrier (PLCC). This device is ideally suited for pipelined systems and systems with multiple data buses and multiprocessing systems, where a local processor has a bus isolated from a common system bus.

- Single 5 V ± 10% Power Supply
- Choice of 5 V or 3.3 V \pm 10% Power Supplies for Output Level Compatibility
- Fast Access and Cycle Times: 15/17/20 ns Max
- Self–Timed Write Cycles
- · Clock Controlled Output Latches
- · Address, Chip Enable, and Data Input Registers
- Common Data Inputs and Data Outputs
- Dual I/O for Separate Processor and Memory Buses
- Separate Output Enable Controlled Three-State Outputs
- Odd Parity Checker During Reads
- Open Drain Output on Data Parity Error (DPE) Allowing Wire-ORing of Outputs
- High Output Drive Capability: 85 pF/Output at Rated Access Time
- High Board Density 52 Lead PLCC Package
- Active High and Low Chip Enables for Easy Memory Depth Expansion
- Can be used as Separate I/O x9

MCM62110



PIN ASSIGNMENT



		ŀ	1	r	4	Г	N/	A	IV	ᄩ	S
											Address Inputs

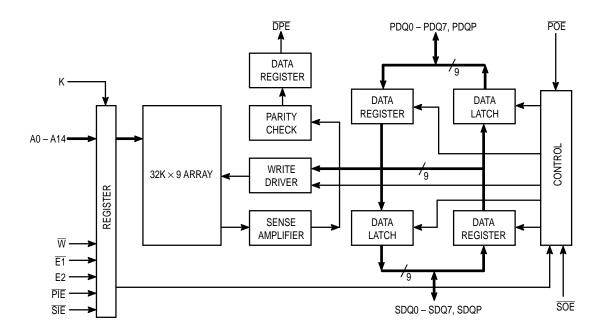
A0 – A14 Address Inputs
KClock Input
W Write Enable
E1 Active Low Chip Enable
E2 Active High Chip Enable
PIE Processor Input Enable
SIE System Input Enable
POE Processor Output Enable
SOE System Output Enable
DPE Data Parity Error
PDQ0 – PDQ7 Processor Data I/O
PDQP Processor Data Parity
SDQ0 – SDQ7 System Data I/O
SDQP System Data Parity
V _{CC} + 5 V Power Supply
VCCQ Output Buffer Power Supply
VSSQ Output Buffer Ground
V _{SS} Ground
155 Ologija

All power supply and ground pins must be connected for proper operation of the device. $V_{CC} \ge V_{CCQ}$ at all times including power up.

REV 3 5/95



BLOCK DIAGRAM



FUNCTIONAL TRUTH TABLE (See Notes 1 and 2)

w	PIE	SIE	POE	SOE	Mode	Memory Subsystem Cycle	PDQ0 – PDQ7, PDQP Output	SDQ0 – SDQ7, SDQP Output	DPE	Notes
1	1	1	0	1	Read	Processor Read	Data Out	High–Z	Parity Out	3, 4
1	1	1	1	0	Read	Copy Back	High–Z	Data Out	Parity Out	3, 4
1	1	1	0	0	Read	Dual Bus Read	Data Out	Data Out	Parity Out	3, 4
1	Х	Х	1	1	Read	NOP	High–Z	High–Z	1	
Х	0	0	Х	Х	N/A	NOP	High–Z	High–Z	1	2, 5
0	0	1	1	1	Write	Processor Write Hit	Data In	High–Z	1	2, 6
0	1	0	1	1	Write	Allocate	High–Z	Data In	1	2
0	0	1	1	0	Write	Write Through	Data In	Stream Data	1	2, 7
0	1	0	0	1	Write	Allocate With Stream	Stream Data	Data In	1	2, 7
1	0	1	1	0	N/A	Cache Inhibit Write	Data In	Stream Data	1	2, 7
1	1	0	0	1	N/A	Cache Inhibit Read	Stream Data	Data In	1	2, 7
0	1	1	Х	Х	N/A	NOP	High–Z	High–Z	1	5
Х	0	1	0	0	N/A	Invalid	Data In	Stream	1	2, 8
Х	0	1	0	1	N/A	Invalid	Data In	High–Z	1	2, 8
Х	1	0	0	0	N/A	Invalid	Stream	Data In	1	2, 8
Х	1	0	1	0	N/A	Invalid	High–Z	Data In	1	2, 8

NOTES:

- A '0' represents an input voltage ≤ V_{IL} and a '1' represents an input voltage ≥ V_{IH}. All inputs must satisfy the specified setup and hold times for the falling or rising edge of K. Some entries in this truth table represent latched values. This table assumes that the chip is selected (i.e., E1 = 0 and E2 = 1) and V_{CC} current is equal to I_{CCA}. If this is not true, the chip will be in standby mode, the V_{CC} current will equal I_{SB1} or I_{SB2} DPE will default to 1 and all RAM outputs will be in High–Z. Other possible combinations of control inputs not covered by this note or the table above are not supported and the RAM's behavior is not specified.
- 2. If either $\overline{\text{IE}}$ signal is sampled low on the rising edge of clock, the corresponding $\overline{\text{OE}}$ is a don't care, and the corresponding outputs are High–Z.
- 3. A read cycle is defined as a cycle where data is driven on the internal data bus by the RAM.
- 4. DPE is registered on the rising edge of K at the beginning of the following clock cycle
- 5. No RAM cycle is performed.
- A write cycle is defined as a cycle where data is driven onto the internal data bus through one of the data I/O ports (PDQ0 PDQ7 and PDQP or SDQ0 SDQ7 and SPDQ), and written into the RAM.
- Data is driven on the internal data bus by one I/O port through its data input register and latched into the data output latch of the other I/O port.
- 8. Data contention will occur.

PARITY CHECKER

Parity Scheme	DPE
$\overline{E1} = V_{IH}$ and/or $E2 = V_{IL}$	1
$RAMP = \overline{RAM0 \oplus RAM1 \oplus \ldots \oplus RAM7}$	1
$RAMP \neq \overline{RAM0 \oplus RAM1 \oplus \ldots \oplus RAM7}$	0

NOTE: RAMP, RAMO, RAM1 . . . , refer to the data that is present on the RAMs internal bus, not necessarily data that resides in the RAM array. DPE is always delayed one clock, and is registered on the rising edge of K at the beginning of the following clock cycle (see AC CHARACTERISTICS).

ABSOLUTE MAXIMUM RATINGS (Voltages Referenced to V_{SS} = V_{SSQ} = 0 V)

Rating	Symbol	Value	Unit
Power Supply	Vcc	- 0.5 to + 7.0	٧
Voltage Relative to VSS/VSSQ for Any Pin Except VCC and VCCQ	V _{in} , V _{out}	- 0.5 to V _{CC} + 0.5	V
Output Current (per I/O)	l _{out}	± 20	mA
Power Dissipation	PD	1.2	W
Temperature Under Bias	T _{bias}	- 10 to + 85	°C
Operating Temperature	TA	0 to +70	°C
Storage Temperature	T _{stg}	- 55 to + 125	°C

NOTE: Permanent device damage may occur if ABSOLUTE MAXIMUM RATINGS are exceeded. Functional operation should be restricted to RECOMMENDED OPER-ATING CONDITIONS. Exposure to higher than recommended voltages for extended periods of time could affect device reliability.

This device contains circuitry to protect the inputs against damage due to high static voltages or electric fields; however, it is advised that normal precautions be taken to avoid application of any voltage higher than maximum rated voltages to this high–impedance circuit.

This CMOS memory circuit has been designed to meet the dc and ac specifications shown in the tables, after thermal equilibrium has been established.

This device contains circuitry that will ensure the output devices are in High–Z at power up.

DC OPERATING CONDITIONS AND CHARACTERISTICS

(VCC = 5.0 V \pm 10%, VCCQ = 5.0 V or 3.3 V \pm 10%, TA = 0 to + 70°C, Unless Otherwise Noted)

RECOMMENDED OPERATING CONDITIONS (Voltages referenced to $V_{SS} = V_{SSQ} = 0 \text{ V}$)

Parameter	Symbol	Min	Max	Unit
Supply Voltage (Operating Voltage Range)	Vcc	4.5	5.5	V
Output Buffer Supply Voltage (5.0 V TTL Compatible) (3.3 V 50 Ω Compatible)	Vccq	4.5 3.0	5.5 3.6	٧
Input High Voltage	VIH	2.2	V _{CC} + 0.3	V
Input Low Voltage	V _{IL}	- 0.5*	0.8	V

^{*} V_{IL} (min) = -3.0 V ac (pulse width ≤ 20 ns)

DC CHARACTERISTICS

Parameter	Symbol	Min	Max	Unit
Input Leakage Current (All Inputs, V _{in} = 0 to V _{CC})	l _{lkg(l)}	_	± 1.0	μΑ
Output Leakage Current (POE, SOE = VIH)	I _{lkg(O)}	_	± 1.0	μΑ
AC Supply Current (All Inputs = V _{IL} or V _{IH} ,V _{IL} = 0.0 V and V _{IH} \geq 3.0 V, I _{Out} = 0 mA, Cycle Time \geq t _{KHKH} min) MCM62110–15: t _{KHKH} = 15 ns MCM62110–17: t _{KHKH} = 17 ns MCM62110–20: t _{KHKH} = 20 ns	:	_ _ _	190 190 190	mA
TTL Standby Current ($V_{CC} = Max, \overline{E1} = V_{IH}$ or $E2 = V_{IL}$)	I _{SB1}	_	40	mA
CMOS Standby Current (V_{CC} = Max, f = 0 MHz, $\overline{E1}$ = V_{IH} or E2 = V_{IL} , $V_{in} \le V_{SS}$ + 0.2 V or $\ge V_{CC}$ - 0.2 V)	I _{SB2}	_	30	mA
Output Low Voltage (I _{OL} = + 8.0 mA, DPE: I _{OL} = + 23.0 mA)	VOL	_	0.4	V
Output High Voltage (I _{OH} = - 4.0 mA)	VOH	2.4	_	V

$\textbf{CAPACITANCE} \text{ (f = 1.0 MHz, dV = 3.0 V, T}_{A} = 25^{\circ}\text{C, Periodically Sampled Rather Than 100\% Tested)}$

Parameter	Symbol	Тур	Max	Unit
Input Capacitance (All Pins Except I/Os)	C _{in}	2	3	pF
Input/Output Capacitance (PDQ0 - PDQ7, SDQ0 - SDQ7, PDQP, SDQP)	C _{out}	6	7	pF
Data Parity Error Output Capacitance (DPE)	C _{out(DPE)}	6	7	pF

AC SPEC LOADS

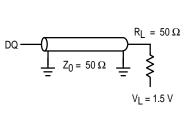


Figure 1A

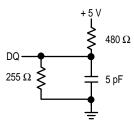


Figure 1B

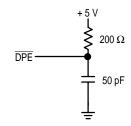


Figure 1C

MCM62110 MOTOROLA FAST SRAM

AC OPERATING CONDITIONS AND CHARACTERISTICS

 $(V_{CC} = 5.0 \text{ V} \pm 10\%, V_{CCQ} = 5.0 \text{ V} \text{ or } 3.3 \text{ V} \pm 10\%, T_A = 0 \text{ to } + 70^{\circ}\text{C}, \text{Unless Otherwise Noted})$

Input Timing Measurement Reference Level 1.5 V	Output Measurement Timing Level 1.5 V
Input Pulse Levels	Output Load See Figure 1A Unless Otherwise Noted
Input Rise/Fall Time	

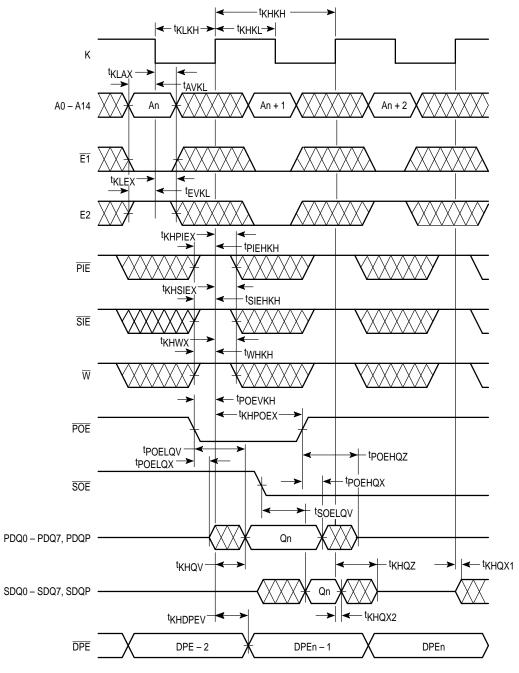
READ CYCLE (See Note 1)

		MCM62	110–15	MCM62	110–17	MCM62	2110–20		
Parameter	Symbol	Min	Max	Min	Max	Min	Max	Unit	Notes
Read Cycle Time Clock High to Clock High	^t KHKH	15	_	17	_	20	_	ns	1, 2
Clock Low Pulse Width	^t KLKH	5	_	5	_	5	_	ns	
Clock High Pulse Width	^t KHKL	7	_	7	_	7	_	ns	
Clock High to DPE Valid	^t KHDPEV	_	7	_	8	_	10	ns	5
Clock High to Output Valid	^t KHQV	_	7	_	7.5	_	10	ns	4, 3
Clock (K) High to Output Low Z After Write	tKHQX1	8	_	8	_	8	_	ns	
Output Hold from Clock High	^t KHQX2	5	_	5	_	5	_	ns	4, 6
Clock High to Q High–Z (E1 or E2 = False)	^t KHQZ	_	8	_	9	_	10	ns	6
Setup TImes: $\begin{matrix} A \\ \overline{\mathbb{W}} \\ \hline E1, E2 \\ \hline PIE \\ \overline{\mathbb{S}IE} \\ \hline POE \\ \overline{\mathbb{S}OE} \end{matrix}$	tavkl twhkh tevkl tpiehkh tsiehkh tpoevkh tsoevkh	2.5	_	2.5	_	2.5	_	ns	7 7
Hold Times: $\begin{array}{c} A \\ \overline{\mathbb{W}} \\ \hline E1, E2 \\ \overline{\text{PIE}} \\ \overline{\text{SIE}} \\ \overline{\text{POE}} \\ \overline{\text{SOE}} \end{array}$	tKLAX tKHWX tKLEX tKHPIEX tKHSIEX tKHPOEX tKHSOEX	2	_	2	_	2	_	ns	7 7
Output Enable High to Q High–Z	^t POEHQZ ^t SOEHQZ	0	8	0	9	0	9	ns	6
Output Hold from Output Enable High	^t POEHQX ^t SOEHQX	5	_	5	_	5	_	ns	6
Output Enable Low to Q Active	^t POELQX ^t SOELQX	0	_	0	_	0	_	ns	6
Output Enable Low to Output Valid	^t POELQV ^t SOELQV	_	5	_	6	_	8	ns	

NOTES:

- 1. A read is defined by \overline{W} high for the setup and hold times.
- 2. All read cycle timing is referenced from K, $\overline{\text{SOE}}$, or $\overline{\text{POE}}$.
- 3. Access time is controlled by tKLQV if the clock low pulse width is less than (tKLQV-tKHQV); otherwise it is controlled by KHQV.
- 4. K must be at a high level for outputs to transition.
- 5. DPE is valid exactly one clock cycle after the output data is valid.
- 6. Transition is measured ± 500 mV from steady–state voltage with output load of Figure 1B. This parameter is sampled and not 100% tested. At any given voltage and temperature, tkhQz is less than tkhQx, tpoehQz is less than tpoehQx for a given device, and tsoehQz is less than tsoehQx for a given device.
- 7. These read cycle timings are used to guarantee proper parity operation only.

READ CYCLE (See Notes)



NOTES

1. $\overline{\text{DPE}}$ is valid exactly one clock cycle after the output data is valid.

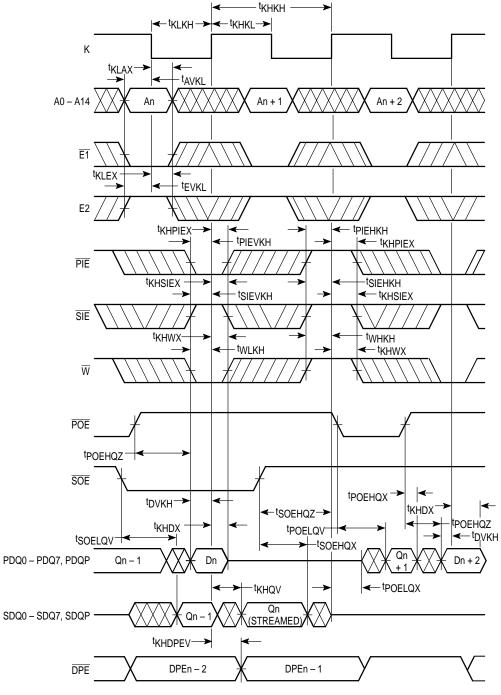
WRITE CYCLE (See Note 1)

		MCM62110-15 MCM62110-17 MC		MCM62	MCM62110-20				
Parameter	Symbol	Min	Max	Min	Max	Min	Max	Unit	Notes
Write Cycle Times	tKHKH	15	_	17	_	20	_	ns	1, 2
Clock Low Pulse Width	^t KLKH	5	_	5	_	5	_	ns	
Clock High Pulse Width	^t KHKL	7	_	7	_	7	_	ns	
Clock High to Output High–Z (\overline{W} = V _{IL} and \overline{SIE} = \overline{PIE} = V _{IH})	^t KHQZ	_	8	_	9	_	10	ns	3, 4
Setup Times: A W E1, E2 PIE SIE SDQ0 – SDQ7, SDQP, PDQ0 – PDQ7, PDQP	tavkl twlkh tevkl tpievkh tsievkh tdvkh	2.5	_	2.5	_	2.5	_	ns	
Hold Times: $\begin{array}{c} A\\ \overline{\mathbb{W}}\\ \hline \overline{\text{E1}}, \text{E2}\\ \hline \overline{\text{PIE}}\\ \overline{\text{SIE}}\\ \\ \text{SDQ0}-\text{SDQ7}, \text{SDQP}, \text{PDQ0}-\text{PDQ7}, \text{PDQP} \end{array}$	tKLAX tKHWX tKLEX tKHPIEX tKHSIEX tKHDX	2	_	2	_	2	_	ns	
Write with Streaming (PIE = SOE = V _{IL} or SIE = POE = V _{IL}) Clock High to Output Valid	^t KHQV	_	7	_	7.5	_	8	ns	5
Output Enable High to Q High–Z	^t POEHQZ ^t SOEHQZ	0	8	0	9	0	9	ns	6
Output Hold from Output Enable High	^t POEHQX ^t SOEHQX	5		5		5		ns	
Output Enable Low to Q Active	^t POELQX ^t SOELQX	0	_	0		0		ns	6
Output Enable Low to Output Valid	^t POELQV ^t SOELQV	_	5	_	6	_	8	ns	

NOTES:

- 1. A write is performed with $\overline{W} = V_{IL}$, $\overline{E1} = V_{IL}$, $E2 = V_{IH}$ for the specified setup and hold times and either $\overline{PIE} = V_{IL}$ or $\overline{SIE} = V_{IL}$ or $\overline{SIE} = V_{IL}$ and $\overline{SIE$
- 2. All write cycle timings are referenced from K.
- 3. K must be at a high level for the outputs to transition.
- 4. Transition is measured \pm 500 mV from steady–state voltage with output load of Figure 1B. This parameter is sampled and not 100% tested. At any given voltage and temperature, t_{KHOZ} is less than t_{KHOX} for a given device.
- 5. A write with streaming is defined as a write cycle which writes data from one data bus to the array and outputs the same data onto the other data bus.
- 6. Transition is measured ± 500 mV from steady–state voltage with output load of Figure 1B. This parameter is sampled and not 100% tested. At any given voltage and temperature, tkhQZ is less than tkhQX, tpoehQZ is less than tpoehQX for a given device, and tsoehQZ is less than tsoehQX for a given device.

WRITE THROUGH — READ — WRITE (See Note)



NOTE: $\overline{\mbox{DPE}}$ is valid exactly one clock cycle after the output data is written.

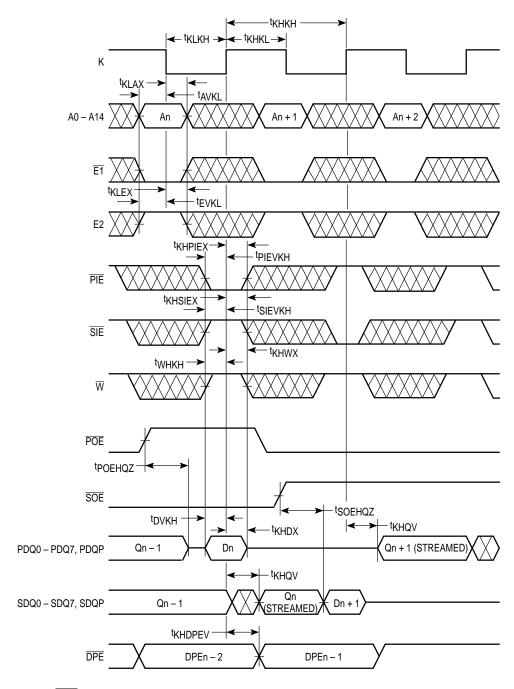
STREAM CYCLE (See Note 1)

		MCM62	110–15	МСМ62	110–17	MCM62110-20			
Parameter	Symbol	Min	Max	Min	Max	Min	Max	Unit	Notes
Stream Cycle Time	^t KHKH	15	_	17	_	20	_	ns	1, 2
Clock Low Pulse Width	^t KLKH	5	_	5	_	5	_	ns	
Clock High Pulse Width	^t KHKL	7	_	7	_	7	_	ns	
Stream Access Time	^t KHQV	_	7	_	7.5	_	8	ns	
Setup Times: A W E1, E2 PIE SIE SDQ0 – SDQ7, SDQP, PDQ0 – PDQ7, PDQP	tavkl twhkh tevkl tpievkh tsievkh tdvkh	2.5	_	2.5	_	2.5	_	ns	
Hold Times: $\begin{array}{c} A\\ \overline{\mathbb{W}}\\ \hline E1, E2\\ \hline PIE\\ \overline{SIE}\\ SDQ0-SDQ7, SDQP, PDQ0-PDQ7, PDQP \end{array}$	[†] KLAX [†] KHWX [†] KLEX [†] KHPIEX [†] KHSIEX [†] KHDX	2	_	2	_	2	_	ns	
Output Enable High to Q High–Z	^t POEHQZ ^t SOEHQZ	0	8	0	9	0	9	ns	3
Output Enable Low to Q Active	^t POELQX ^t SOELQX	0	_	0	_	0	_	ns	3
Output Enable Low to Output Valid	^t POELQV ^t SOELQV	_	5	_	6	_	8	ns	

NOTES:

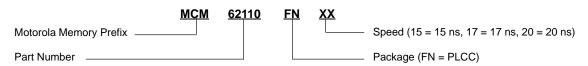
- 1. A stream cycle is defined as a cycle where data is passed from one data bus to the other data bus.
- 2. All stream cycle timing is referenced from K.
- 3. Transition is measured ±500 mV from steady–state voltage with output load of Figure 1B. This parameter is sampled and not 100% tested. At any given voltage and temperature, tpoehqz is less than tpoehqz is less than tpoehqz is less than tkhqz for a given device.

STREAM CYCLE (See Note)



NOTE: $\overline{\text{DPE}}$ is valid exactly one clock cycle after the output data is valid.

ORDERING INFORMATION (Order by Full Part Number)



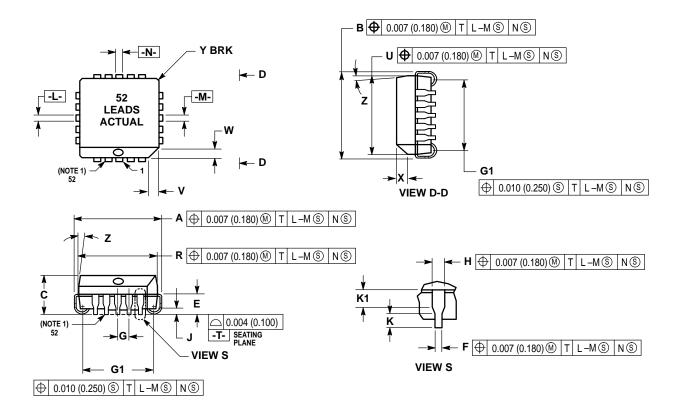
Full Part Numbers — MCM62110FN15

MCM62110FN17

MCM62110FN20

PACKAGE DIMENSIONS

FN PACKAGE 52-LEAD PLCC **CASE 778-02**



- 1. DUE TO SPACE LIMITATION, CASE 778-02 SHALL BE REPRESENTED BY A GENERAL (SMALLER) CASE
 OUTLINE DRAWING RATHER THAN SHOWING ALL 52
- DATUMS -L-, -M-, AND -N- DETERMINED WHERE TOP OF LEAD SHOULDER EXITS PLASTIC BODY AT MOLD
- PARTING LINE.
 DIM G1, TRUE POSITION TO BE MEASURED AT DATUM -T-, SEATING PLANE.
 DIM R AND U DO NOT INCLUDE MOLD FLASH.
- ALLOWABLE MOLD FLASH IS 0.010 (0.250) PER SIDE. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M,
- CONTROLLING DIMENSION: INCH.
- CONTROLLING DIMENSION: INCH.
 THE PACKAGE TOP MAY BE SMALLER THAN THE
 PACKAGE BOTTOM BY UP TO 0.012 (0.300). DIMENSIONS
 R AND U ARE DETERMINED AT THE OUTERMOST
 EXTREMES OF THE PLASTIC BODY EXCLUSIVE OF MOLD
 FLASH, TIE BAR BURRS, GATE BURRS AND INTERLEAD FLASH, BUT INCLUDING ANY MISMATCH BETWEEN THE TOP AND BOTTOM OF THE PLASTIC BODY.
- DIMENSION H DOES NOT INCLUDE DAMBAR PROTRUSION OR INTRUSION. THE DAMBAR PROTRUSION(S) SHALL NOT CAUSE THE H DIMENSION TO BE GREATER THAN 0.037 (0.940). THE DAMBAR INTRUSION(S) SHALL NOT CAUSE THE H DIMENSION TO BE SMALLER THAN 0.025 (0.635).

	INCHES		MILLIMETERS	
DIM	MIN	MAX	MIN	MAX
Α	0.785	0.795	19.94	20.19
В	0.785	0.795	19.94	20.19
С	0.165	0.180	4.20	4.57
E	0.090	0.110	2.29	2.79
F	0.013	0.019	0.33	0.48
G	0.050 BSC		1.27 BSC	
Н	0.026	0.032	0.66	0.81
J	0.020	_	0.51	_
K	0.025	_	0.64	_
R	0.750	0.756	19.05	19.20
U	0.750	0.756	19.05	19.20
٧	0.042	0.048	1.07	1.21
W	0.042	0.048	1.07	1.21
Х	0.042	0.056	1.07	1.42
Υ	-	0.020	_	0.50
Z	2°	10°	2°	10°
G1	0.710	0.730	18.04	18.54
K1	0.040	_	1.02	_

Motorola reserves the right to make changes without further notice to any products herein. Motorola makes no warranty, representation or guarantee regarding the suitability of its products for any particular purpose, nor does Motorola assume any liability arising out of the application or use of any product or circuit, and specifically disclaims any and all liability, including without limitation consequential or incidental damages. "Typical" parameters can and do vary in different applications. All operating parameters, including "Typicals" must be validated for each customer application by customer's technical experts. Motorola does not convey any license under its patent rights nor the rights of others. Motorola products are not designed, intended, or authorized for use as components in systems intended for surgical implant into the body, or other applications intended to support or sustain life, or for any other application in which the failure of the Motorola product could create a situation where personal injury or death may occur. Should Buyer purchase or use Motorola products for any such unintended or unauthorized application, Buyer shall indemnify and hold Motorola and its officers, employees, subsidiaries, affiliates, and distributors harmless against all claims, costs, damages, and expenses, and reasonable attorney fees arising out of, directly or indirectly, any claim of personal injury or death associated with such unintended or unauthorized use, even if such claim alleges that Motorola was negligent regarding the design or manufacture of the part. Motorola and are registered trademarks of Motorola, Inc. Motorola, Inc. is an Equal Opportunity/Affirmative Action Employer.

Literature Distribution Centers:

USA/EUROPE: Motorola Literature Distribution; P.O. Box 20912; Phoenix, Arizona 85036.

JAPAN: Nippon Motorola Ltd.; 4–32–1, Nishi–Gotanda, Shinagawa–ku, Tokyo 141, Japan.

ASIA PACIFIC: Motorola Semiconductors H.K. Ltd.; Silicon Harbour Center, No. 2 Dai King Street, Tai Po Industrial Estate, Tai Po, N.T., Hong Kong.





Copyright © Each Manufacturing Company.

All Datasheets cannot be modified without permission.

This datasheet has been download from:

www.AllDataSheet.com

100% Free DataSheet Search Site.

Free Download.

No Register.

Fast Search System.

www.AllDataSheet.com