

## **General Description**

The MAX3540 complete single-conversion television tuner is designed for use in analog/digital terrestrial applications and digital set-top boxes. This television tuner draws only 760mW of power from a +3.3V supply voltage.

The MAX3540 is designed to convert NTSC or ATSC signals in the 54MHz to 860MHz band to a 44MHz intermediate frequency (IF).

The MAX3540 includes a variable-gain low-noise amplifier (LNA), multiband tracking filters, a harmonic-rejection mixer, a low-noise IF amplifier, an IF power detector, and a variable-gain IF amplifier. The MAX3540 also includes fully monolithic VCOs and tank circuits as well as a complete frequency synthesizer. This highly integrated design allows for low-power tuner-on-board applications without the cost and power-dissipation issues of dual-conversion tuner solutions.

The MAX3540 is specified for operation in the 0°C to +85°C temperature range and is available in a leadless 48-pin flip-chip (fcLGA) package.

### **Applications**

Televisions Analog/Digital Terrestrial Receivers Digital Set-Top Boxes Cable Modems VOIP Gateways

M/XI/M

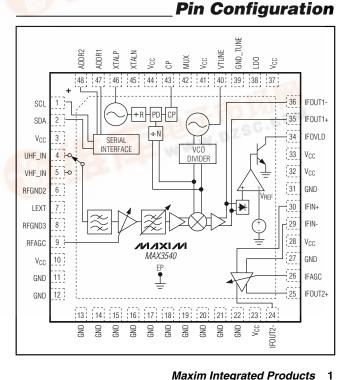
#### Features

- Low Power Consumption: 760mW (typ) from a +3.3V Supply Voltage
- Integrated Tracking Filters
- ATSC A/74 Compliant
- ♦ 40dB Adjacent Channel Protection Ratio (ACPR)
- ♦ 4.4dB (typ) Low Noise Figure
- Small, 7mm x 7mm, fcLGA Leadless Package
- ♦ 256-QAM-Compatible Phase-Noise Performance
- IF Overload Detector Controls RF Variable-Gain
  Amplifier
- ◆ 2-Wire I<sup>2</sup>C-Compatible Serial Control Interface

### Ordering Information

PART	TEMP RANGE	PIN- PACKAGE	PKG CODE
MAX3540ULM#G42	0°C to +85°C	48 fcLGA-EP*	L4877A-E
*EP = Exposed padd	le.	N.C.	

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or pricing, delivery, and ordering information, please contact Maxim Direct at 1-888-629-4642

## **ABSOLUTE MAXIMUM RATINGS**

V <sub>CC</sub> to GND0.3V, -	+3.6V
RFIN, IFIN_, IFOUT1_, IFOUT2_, IFAGC, RFAGC,	
VTUNE, LDO, MUX, CP, XTAL to GND0.3V to (VCC +	0.3V)
SDA, SCL, ADDR2, ADDR1 to GND0.3V to -	+3.6V
IFOUT Short-Circuit DurationInde	efinite
RF Input Power+10	JdBm

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

**CAUTION!** ESD SENSITIVE DEVICE

## DC ELECTRICAL CHARACTERISTICS

(MAX3540 Evaluation Kit,  $V_{CC} = +3.1V$  to +3.5V, no RF signals at RF inputs, default register settings,  $V_{RFAGC} = V_{IFAGC} = +3V$  (minimum attenuation),  $T_A = 0^{\circ}C$  to +85°C, unless otherwise noted. Typical values are at  $V_{CC} = +3.3V$ ,  $T_A = +25^{\circ}C$ , unless otherwise noted.)

PARAMETER	CONDITIONS	MIN	ТҮР	MAX	UNITS
SUPPLY VOLTAGE AND CURRE	NT				
Supply Voltage		+3.1		+3.5	V
Supply Current	Receive mode		240	275	mA
Supply Current	Shutdown mode		5		MA
RF and IF AGC Input Bias Current	At +0.5V and +3V	-50		+50	μA
RF and IF AGC Control Voltage	Minimum attenuation	+3			V
(Note 1)	Maximum attenuation			+0.5	V
Digital Input Logic-Level Low				0.3 x V <sub>CC</sub>	V
Digital Input Logic-Level High		0.7 x V <sub>CC</sub>			V
SERIAL INTERFACE		L.			
Input Logic-Level Low				0.3 x V <sub>CC</sub>	V
Input Logic-Level High		0.7 x V <sub>CC</sub>			V
Input Hysteresis			0.05 x V <sub>CC</sub>		V
SDA, SCL Input Current		-10		+10	μΑ
Output Logic-Level Low	3mA sink current			0.4	V
Output Logic-Level High		V <sub>CC</sub> - 0.5			V

## AC ELECTRICAL CHARACTERISTICS

(MAX3540 Evaluation Kit,  $V_{CC} = +3.1V$  to +3.5V,  $75\Omega$  system impedance, default register settings,  $V_{RFAGC} = V_{IFAGC} = +3V$  (minimum attenuation),  $T_A = 0^{\circ}C$  to  $+85^{\circ}C$ , unless otherwise noted. Typical values are at  $V_{CC} = +3.3V$ ,  $T_A = +25^{\circ}C$ , unless otherwise noted.)

PARAMETER	CO	NDITIONS	MIN	ТҮР	MAX	UNITS	
RF INPUT TO IFOUT1_OUTPUT							
	VHF_IN, LPF enabled, INI	PT = 00	54		100		
Operating Frequency Range	VHF_IN, LPF disabled, IN	PT = 01	100		300	MHz	
(See Table 7)	UHF_IN, INPT = 10	UHF_IN, INPT = 10			860		
	Analog channel PIX carrie	er		45.75			
Output Frequency	Digital channel center frequency			44		MHz	
	Source impedance =	Maximum gain, $V_{RFAGC} = 3V$ , 54MHz to 860MHz		34			
Voltage Gain	75Ω, load impedance = $200$ Ω	Maximum gain, V <sub>RFAGC</sub> = 3V, broadcast channels	28.0	34	45.5	dB	
		Minimum gain, $V_{RFAGC} = 0.5V$		-11			
	Gain specification met	VHF_IN	54		300		
Operating Frequency Range	across these frequency bands	UHF_IN	300		860	MHz	
Input Return Loss	Worst case, selected cha	nnel		8		dB	
Noise Figure	Maximum gain, V <sub>RFVGC</sub> =	3V (Note 1)		4.4		dB	
Input IP2	Maximum gain, V <sub>RFVGC</sub> =	: 3V		15		dBm	
(In-Band and Out-of-Band Tones)	At 12.5dB of gain			29		UDITI	
Input IP3	Maximum gain, V <sub>RFVGC</sub> =	: 3V		-13		-ID	
(In-Band and Out-of-Band Tones)	At 12.5dB of gain		5	11		dBm	
	Maximum gain, V <sub>RFVGC</sub> =	: 3V		-24.5			
Input P <sub>1dB</sub>	At 12.5dB of gain, CW tor 69 in UHF band	he at f <sub>C</sub> - 36MHz, tested at Ch		-3		dBm	
Beats Within Output	0dBmV PIX carrier level (1	Note 1)		-60		dBc	
	VHF_IN from 150MHz to 9	960MHz		-60			
Beats, Converted to Output	VHF_IN from 960MHz to 1	400MHz		-40		dBc	
	UHF_IN from 600MHz to <sup>-</sup>	1400MHz		-40			
Gain Flatness	54MHz to 60MHz				1.5	dBp-p	
Isolation	5MHz to 50MHz, RF input channel	to IF output, relative to desired		60		dBc	
Port-to-Port Isolation	Isolation between RF inpu	It ports at 215MHz		30		dB	
	Measured at 91.5MHz	54MHz to 860MHz		70			
Image Rejection	above desired channel's center frequency	Broadcast channels, $T_A = +25^{\circ}C$	66			dBc	
	5MHz to 65MHz			-40			
Spurious Leakage at RF Input	65MHz to 878MHz			-40		dBmV	
	10kHz offset		-85				
Phase Noise (Single-Sideband)	100kHz offset, 1.5kHz loo	p bandwidth		-105		dBc/Hz	
	1MHz offset, 1.5kHz loop	bandwidth		-125			
Output Return Loss	Balanced 50 $\Omega$ load			9		dB	



## AC ELECTRICAL CHARACTERISTICS (continued)

(MAX3540 Evaluation Kit,  $V_{CC} = +3.1V$  to +3.5V,  $75\Omega$  system impedance, default register settings,  $V_{RFAGC} = V_{IFAGC} = +3V$  (minimum attenuation),  $T_A = 0^{\circ}C$  to  $+85^{\circ}C$ , unless otherwise noted. Typical values are at  $V_{CC} = +3.3V$ ,  $T_A = +25^{\circ}C$ , unless otherwise noted.)

PARAMETER	CONDITIONS		MIN	ТҮР	MAX	UNITS
IF VARIABLE-GAIN AMPLIFIER						
Input Impedance	Balanced			2000		Ω
Output Impedance	Balanced (Note 1)				300	Ω
Deephand Vallage Cain	Source load = $300\Omega$ ,	Maximum gain setting, VIFAGC = 3V	54	56	65	٩D
Passband Voltage Gain	output load = $300\Omega$	Minimum gain setting, VIFAGC = 0.5V			21	dB
Passband Gain Flatness	40MHz to 48MHz (Note	1)			1.2	dB
Output Voltage	VIFAGC = 3V (Note 1)				2	Vp-p
AGC Gain Slope	$V_{IFAGC} = 3V \text{ to } 0.5V  (Note: Note: No$	ote 1)			30	dB/V
Equivalent Input Voltage Noise Density	At 44MHz, maximum ga	ain, VIFAGC = 3V (Note 1)			7.3	nV/√Hz
Noise Figure Change vs. Attenuation				< 0.35		dB/dB
IM3	V <sub>OUT</sub> = 1.5V <sub>P-P</sub> , 40dB <	< gain < 60dB (Note 1)	-54			dBc
IF OVERLOAD DETECTOR (see t	the IF Overload Detector	r section)				
Output Overload Attack Point				0.7		V <sub>P-P</sub>
Attack-Point Accuracy				±1		dB
Detector Output Voltage Range		Negative polarity, overload reduces V <sub>DET</sub> (open collector, 0.3mA sink)			3.0	V
Detector Gain				70		V/V
FREQUENCY SYNTHESIZER						
REFERENCE OSCILLATOR						
Frequency				4		MHz
DIVIDERS						
RF N-Divider Ratio			256		32,767	
RF R-Divider Ratio			8		127	
LO PHASE DETECTOR AND CHA	ARGE PUMP					
Comparison Frequency			31.50		250.00	kHz
	CP = 00			0.5		
Charge Rump Current	CP = 01			1		~^^
Charge-Pump Current	CP = 10			1.5		mA
	CP = 11			2		
Charge-Pump Three-State Current				±5		nA
Charge-Pump Current Matching				5		%
LOCAL OSCILLATOR (OSCILLA	TOR WITH NARROW BA	ND LOOP)				
VCO Tuning Range	Tank frequency		2160		4400	MHz
VCO Tuning Gain	Tank oscillator gain				500	MHz/V
2-WIRE SERIAL INTERFACE			·			
Clock Frequency					400	kHz
Note 1: Guaranteed by design and						

Note 1: Guaranteed by design and characterization.



## \_Pin Description

PIN	NAME	FUNCTION
1	SCL	2-Wire Serial-Clock Interface. Requires a pullup resistor to V <sub>CC</sub> .
2	SDA	2-Wire Serial-Data Interface. Requires a pullup resistor to V <sub>CC</sub> .
3, 10, 23, 28, 32, 33, 37, 41, 44	V <sub>CC</sub>	Power-Supply Connections. Bypass each supply pin to ground with a 1000pF capacitor.
4	UHF_IN	UHF RF Input. Matched to 75 $\Omega$ over the operating band. Requires a DC-blocking capacitor.
5	VHF_IN	VHF RF Input. Matched to 75 $\Omega$ over the operating band. Requires a DC-blocking capacitor.
6	RFGND2	RF Ground. Bypass to the PCB's ground plane with a 1000pF capacitor. <b>Do not connect RFGND2</b> and RFGND3 together.
7	LEXT	RF VGA Supply Voltage. Connect through a 270nH pullup inductor to V <sub>CC</sub> .
8	RFGND3	RF Ground. Bypass to the PCB's ground plane with a 1000pF capacitor. <b>Do not connect RFGND2</b> and RFGND3 together.
9	RFAGC	RF AGC Gain-Control Voltage. Accepts a DC voltage from 0.5V (minimum gain) to 3V (maximum gain).
11–22, 27, 31	GND	Ground. Connect to the PCB's ground plane.
24	IFOUT2-	Inverting IF-VGA Output. Connect to the input of an anti-aliasing filter. Requires a DC-blocking capacitor.
25	IFOUT2+	Noninverting IF-VGA Output. Connect to the input of an anti-aliasing filter. Requires a DC-blocking capacitor.
26	IFAGC	IF AGC Gain-Control Voltage. Accepts a DC voltage from 0.5V (minimum gain) to 3V (maximum gain).
29	IFIN-	Inverting IF-VGA Input. Connect to the output of an IF-SAW filter.
30	IFIN+	Noninverting IF-VGA Input. Connect to the output of an IF-SAW filter.
34	IFOVLD	IF Power Detector Open-Collector Output. Requires a $10k\Omega$ pullup resistor to V <sub>CC</sub> .
35	IFOUT1+	Noninverting IF-LNA Output. Requires a DC-blocking capacitor.
36	IFOUT1-	Inverting IF-LNA Output. Requires a DC-blocking capacitor.
38	LDO	VCO LDO Bypass. Bypass to ground with a 0.47µF capacitor.
39	GND_TUNE	VTUNE Ground Connection. Connect to the PCB ground plane. All loop filter component GND must be connected to this pin (see the <i>Typical Application Circuit</i> ).
40	VTUNE	VCO Tuning Input. Connect to the PLL loop filter output.
42	MUX	Test Output. Leave this pin unconnected during normal operation.
43	CP	Charge-Pump Output. Connect to the PLL loop filter input.
45	XTALN	Crystal Oscillator Feedback. See the Typical Application Circuit.
46	XTALP	Crystal Input. Requires a DC-blocking capacitor.
47	ADDR1	2-Wire Serial-Interface Address Line 1. This pin along with ADDR2 sets the device address for the I <sup>2</sup> C-compatible serial interface.
48	ADDR2	2-Wire Serial-Interface Address Line 2. This pin along with ADDR1 sets the device address for the I <sup>2</sup> C-compatible serial interface.
EP	EP	Exposed Paddle. Solder evenly to the PCB ground plane for proper operation.

## **Detailed Description**

#### **Register Descriptions**

The MAX3540 includes 11 programmable registers and two read-only registers. The 11 programmable registers include two N-divider registers, an R-divider register, a VCO register, an RSSI/charge-pump/filter-select register, a control register, a shutdown register, and trackingfilter control registers. These 11 programmable registers are also readable. The read-only registers include a status register and a ROM table data register.

Recommended default bit settings are provided for user convenience only and are not guaranteed. The user must write all registers after power-up and no earlier than 100µs after power-up.

			MSB							LSB
REGISTER NAME	READ/ WRITE	REGISTER ADDRESS				DATA BY	TE			
	White	ADDRESS	D7	D6	D5	D4	D3	D2	D1	D0
N-DIV High	Both	0x00	0	N14	N13	N12	N11	N10	N9	N8
N-DIV Low	Both	0x01	N7	N6	N5	N4	N3	N2	N1	N0
R-DIV	Both	0x02	0	R6	R5	R4	R3	R2	R1	R0
VCO	Both	0x03	VCO4	VCO3	VCO2	VCO1	VCO0	LD	VDIV1	VDIV0
IFOVLD, Charge Pump, and Filter Select	Both	0x04	0	IFOVLD2	IFOVLD1	IFOVLD0	CP1	CP0	TF1	TF0
Control	Both	0x05	0	0	0	0	SHDN_RF	SHDN_IFAGC	INPT1	INPT0
Shutdown	Both	0x06	SHDN_MIX1	SHDN_MIX0	SHDN_IF	SHDN_PD	SHDN_SYN	0	0	0
Tracking Filter Series Cap	Both	0x07	TFS7	TFS6	TFS5	TFS4	TFS3	TFS2	TFS1	TFS0
Tracking Filter Parallel Cap	Both	0x08	FLD	0	TFP5	TFP4	TFP3	TFP2	TFP1	TFP0
Tracking Filter ROM Address	Both	0x09	0	0	0	0	TFA3	TFA2	TFA1	TFA0
Reserved	Both	0x0A	Х	Х	Х	Х	Х	Х	Х	Х
ROM Table Data Readback	Read	0x0B	TFR7	TFR6	TFR5	TFR4	TFR3	TFR2	TFR1	TFR0
Status	Read	0x0C	POR	LD2	LD1	LD0	Х	Х	Х	Х

### **Table 1. Register Configuration**

### Table 2. N-DIV High Register (Address: 0000b)

BIT NAME	BIT LOCATION (0 = LSB)	RECOMMENDED DEFAULT	FUNCTION
RESERVED	7	0	Must be set to 0.
N[14:8]	6–0		Sets the most significant bits of the PLL integer divider (N). Default integer divider value is N = 4688. N can range from 256 to 32,767.



BIT NAME	BIT LOCATION (0 = LSB)	RECOMMENDED DEFAULT	FUNCTION
N[7:0]	7–0	0101 0000	Sets the least significant bits of the PLL integer divider (N). Default integer divider value is N = 4688. N can range from 256 to 32,767.

## Table 3. N-DIV Low Register (Address: 0001<sub>b</sub>)

## Table 4. R-DIV Register (Address: 0010b)

BIT NAME	BIT LOCATION (0 = LSB)	RECOMMENDED DEFAULT	FUNCTION
RESERVED	7	0	Must be set to 0.
R[6:0]	6–0	100 0000	Sets the PLL reference divider (R). Default reference divider value is $R = 64$ . R can range from 16 to 127.

## Table 5. VCO Register (Address: 0011<sub>b</sub>)

BIT NAME	BIT LOCATION (0 = LSB)	RECOMMENDED DEFAULT	FUNCTION
VCO[4:3]	7, 6	01	VCO select. Selects one of three possible VCOs. 00 = VCOs shut down 01 = selects VCO1 10 = selects VCO2 11 = selects VCO3
VCO[2:0]	5, 4, 3	101	VCO sub-band select. Selects one of eight possible VCO sub-bands. 000 = selects SB0 001 = selects SB1 010 = selects SB2 011 = selects SB3 100 = selects SB4 101 = selects SB5 110 = selects SB6 111 = selects SB7
LD	2	1	Lock-detect enable. 0 = disabled 1 = enabled
VDIV[1:0]	1, 0	01	VCO divider ratio select. 00 = sets VCO divider to 4 01 = sets VCO divider to 8 10 = sets VCO divider to 16 11 = sets VCO divider to 32

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Table 6. RSSI, Charge Pump, and Filter Select Register (Address: 0100b)					
BIT NAME BIT LOCATION (0 = LSB) RECOMMENDE DEFAULT		RECOMMENDED DEFAULT	FUNCTION		
RESERVED	7	0	Must be set to 0.		
IFOVLD[2:0]	6, 5, 4	000	Write content of ROM register OD[2:0] to this location.		
CP[1:0]	3, 2	00	Selects the typical charge-pump current. 00 = 0.5mA 01 = 1mA 10 = 1.5mA 11 = 2mA		
TF[1:0]	1, 0	00	Selects the tracking filter band of operation. 00 = VHF low 01 = VHF high 10 = UHF 11 = factory use only		

Table 7. Control Register (Address: 0101<sub>b</sub>)

BIT NAME	BIT LOCATION (0 = LSB)	RECOMMENDED DEFAULT	FUNCTION
RESERVED	7–4	0000	Must be set to 0000.
SHDN_RF	3	0	RF shutdown. 0 = RF circuitry enabled 1 = RF circuitry disabled
SHDN_IFV GA	2	1	IF VGA shutdown. 0 = IF VGA enabled 1 = IF VGA disabled
INPT[1:0]	1, 0	00	Selects the RF input. 00 = selects VHF_IN with LPF 01 = selects VHF_IN, no LPF 10 = selects UHF_IN 11 = factory use only

BIT NAME	BIT LOCATION (0 = LSB)	RECOMMENDED DEFAULT	FUNCTION
SHDN_MIX	7, 6	0	Mixer shutdown. 00 = mixer enabled 01, 10 = factory use only 11 = mixer disabled
SHDN_IF	5	0	IF shutdown. 0 = IF section enabled 1 = IF section disabled
SHDN_PD	4	0	IF OVLD shutdown. 0 = power detector enabled 1 = power detector disabled
SHDN_SYN	3	0	Frequency synthesizer shutdown. 0 = synthesizer enabled 1 = synthesizer disabled
RESERVED	2, 1, 0	000	Must be set to 000.

## Table 8. Shutdown Register (Address: 0110b)

## Table 9. Tracking-Filter Series Cap Register (Address: 0111<sub>b</sub>)

BIT NAME	BIT LOCATION (0 = LSB)	RECOMMENDED DEFAULT	FUNCTION	
TFS[7:0]	7–0	0000000*	Programs series capacitor values in the tracking filter.	

## Table 10. Tracking-Filter Parallel Cap Register (Address: 1000b)

BIT NAME	BIT LOCATION (0 = LSB)	RECOMMENDED DEFAULT	FUNCTION
FLD	7	0	Filter load bit. A 0 to 1 transition of this bit forces the loading of the ROM table data readback register.
Reserved	6	0	Must be set to 0.
TFP[5:0]	5–0	000000*	Programs parallel capacitor values in the tracking filter.

## Table 11. Tracking-Filter ROM Address Register (Address: 1001<sub>b</sub>)

BIT NAME	BIT LOCATION (0 = LSB)	RECOMMENDED DEFAULT	FUNCTION	
Reserved	7–4	0000	Must be set to 0000.	
TFA[3:0]	3–0	0000*	Address bits of the ROM register to be read.	

\*See the RF Tracking Filter section.

## Table 12. Reserved Register (Address: 1010b)

BIT NAME	BIT LOCATION (0 = LSB)	RECOMMENDED DEFAULT	FUNCTION
Reserved	7–0	N/A	Reserved. Do not program these bits during normal operation.

BIT NAME	BIT LOCATION (0 = LSB)	RECOMMENDED DEFAULT	FUNCTION
TFR[7:0]	7–0	0000000*	Tracking-filter data bits read from the device's ROM table.

### Table 13. ROM Table Data Readback Register (Address: 1011<sub>b</sub>)

See the RF Tracking Filter section.

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BIT NAME	BIT LOCATION (0 = LSB)	RECOMMENDED DEFAULT	FUNCTION
POR	7	0	Power-on reset. 0 = status register has been read 1 = power reset since last status register read
LD[2:0]	6, 5, 4	000	VCO tuning voltage indicators. 000 = PLL not in lock, tune to the next lowest sub-band 001–110 = PLL in lock 111 = PLL not in lock, tune to the next higher sub-band
Reserved	3–0	0000	Reserved.

#### **2-Wire Serial Interface**

The MAX3540 uses a 2-wire I<sup>2</sup>C-compatible serial interface consisting of a serial-data line (SDA) and a serialclock line (SCL). SDA and SCL facilitate bidirectional communication between the MAX3540 and the master at clock frequencies up to 400kHz. The master initiates a data transfer on the bus and generates the SCL signal to permit data transfer. The MAX3540 behaves as a slave device that transfers and receives data to and from the master. Pull SDA and SCL high with external pullup resistors (1k $\Omega$  or greater) for proper bus operation.

One bit is transferred during each SCL clock cycle. A minimum of nine clock cycles is required to transfer a byte in or out of the MAX3540 (8 data bits and an ACK/NACK). The data on SDA must remain stable during the high period of the SCL clock pulse. Changes in SDA while SCL is high and stable are considered control signals (see the *START and STOP Conditions* section). Both SDA and SCL remain high when the bus is not busy.

#### START and STOP Conditions

The master initiates a transmission with a START condition (S), which is a high-to-low transition on SDA while SCL is high. The master terminates a transmission with a STOP condition (P), which is a low-to-high transition on SDA while SCL is high.

**Acknowledge and Not-Acknowledge Conditions** Data transfers are framed with an acknowledge bit (ACK) or a not-acknowledge bit (NACK). Both the master and the MAX3540 (slave) generate acknowledge bits. To generate an acknowledge, the receiving device

### Table 15. MAX3540 Address Configurations

ADDR2	ADDR1	WRITE ADDRESS	READ ADDRESS
0	0	0xC0	0xC1
0	1	0xC2	0xC3
1	0	0xC4	0xC5
1	1	0xC6	0xC7

must pull SDA low before the rising edge of the acknowledge-related clock pulse (ninth pulse) and keep it low during the high period of the clock pulse.

To generate a not-acknowledge condition, the receiver allows SDA to be pulled high before the rising edge of the acknowledge-related clock pulse, and leaves SDA high during the high period of the clock pulse. Monitoring the acknowledge bits allows for detection of unsuccessful data transfers. An unsuccessful data transfer happens if a receiving device is busy or if a system fault has occurred. In the event of an unsuccessful data transfer, the bus master must reattempt communication at a later time.

#### Slave Address

The MAX3540 has a 7-bit slave address that must be sent to the device following a START condition to initiate communication. The slave address is determined by the state of the ADDR2 and ADDR1 pins and is equal to 11000[ADDR2][ADDR1]. The 8th bit (R/W) following the 7-bit address determines whether a read or write operation will occur. Table 15 shows the possible address configurations.



The MAX3540 continuously awaits a START condition followed by its slave address. When the device recognizes its slave address, it acknowledges by pulling the SDA line low for one clock period. It is ready to accept or send data depending on the R/W bit (Figure 1).

#### Write Cycle

When addressed with a write command, the MAX3540 allows the master to write to a single register or to multiple successive registers.

A write cycle begins with the bus master issuing a START condition followed by the 7 slave address bits and a write bit (R/W = 0). The MAX3540 issues an ACK if the slave address byte is successfully received. The bus master must then send to the slave the address of the first register it wishes to write to. If the slave acknowledges the address, the master can then write one byte to the register at the specified address. Data is written beginning with the most significant bit. The MAX3540 again issues an ACK if the data is successfully written to the register. The master can continue to write data to the successive internal registers with the MAX3540 acknowledging each successful transfer, or it can terminate transmission by issuing a STOP condition. The write cycle does not terminate until the master issues a STOP condition.

Figure 2 illustrates an example in which registers 0 through 2 are written with 0x0E, 0xD8, and 0xE1, respectively.

#### Read Cycle

A read cycle begins with the bus master issuing a START condition followed by the seven slave address bits and a write bit  $(R/\overline{W} = 0)$ . The MAX3540 issues an ACK if the slave address byte is successfully received. The master then sends the 8-bit address of the first register that it wishes to read. The MAX3540 then issues another ACK. Next, the master must issue a START condition followed by the 7 slave address bits and a read bit (R/W = 1). The MAX3540 issues an ACK if it successfully recognizes its address and begins sending data from the specified register address starting with the most significant bit (MSB). Data is clocked out of the MAX3540 on the rising edge of SCL. On the 9th rising edge of SCL, the master can issue an ACK and continue reading successive registers or it can issue a NACK followed by a STOP condition to terminate transmission. The read cycle does not terminate until the master issues a STOP condition. Figure 3 illustrates an example in which registers 0 and 1 are read back.

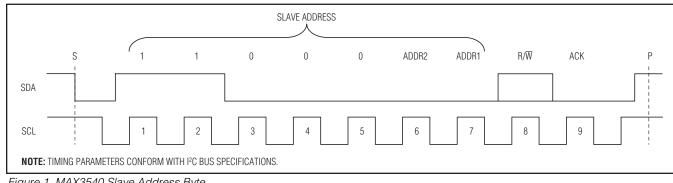


Figure 1. MAX3540 Slave Address Byte

START	WRITE DEVICE ADDRESS	R/W	ACK	WRITE REGISTER ADDRESS	ACK	WRITE DATA TO REGISTER 0x00	ACK	WRITE DATA TO REGISTER 0x01	ACK	WRITE DATA TO REGISTER 0x02	ACK	STOP
	11000[ADDR2][ADDR1]	0	_	0x00	—	0x0E	_	0xD8	_	0xE1		

Figure 2. Example: Write registers 0 through 2 with 0x0E, 0xD8, and 0xE1, respectively.

START	WRITE DEVICE ADDRESS	R/W	ACK	WRITE 1st REGISTER ADDRESS	ACK	ACK START	WRITE DEVICE ADDRESS	R/W	ACK	READ DATA REG 0	ACK	READ DATA REG 1	NACK	STOP
	110000[ADDR2][ADDR1]	0	_	0x00			110000[ADDR2][ADDR1]	1	_	D7-D0	_	D7-D0		

Figure 3. Example: Read data from registers 0 through 1.



### **Applications Information**

#### **RF** Inputs

The MAX3540 features separate UHF and VHF inputs that are matched to  $75\Omega$ . Both inputs require a DC-blocking capacitor. The input registers select the active inputs. In addition, the input registers enable or disable the low-pass filter, which can be used when the VHF input is selected. For 54MHz to 100MHz, select the VHF\_IN with the LPF filter enabled (INPT = 00). For 100MHz to 300MHz, select VHF\_IN with LPF disabled (INPT = 01). For 300MHz to 860MHz, select UHF\_IN (INPT = 10).

#### **RF Gain Control**

The gain of the RF low-noise amplifier can be adjusted over a typical 45dB range by the RFAGC pin. The RFAGC input accepts a DC voltage from 0.5V to 3V, with 3V providing maximum gain. This pin can be controlled with the IF power-detector output to form a closed RF gain-control loop. See the *Closed-Loop RF Gain Control* section for more information.

#### **RF Tracking Filter**

The MAX3540 includes a programmable tracking filter for each band of operation to optimize rejection of out-ofband interference while minimizing insertion loss for the desired received signal. VHF low, VHF high, or UHF tracking filter is selected by the TF register. The center frequency of each tracking filter is selected by a switchedcapacitor array, which is programmed by the TFS[7:0] bits in the Tracking-Filter Series Cap register and the TFP[5:0] bits in the Tracking-Filter Parallel Cap register.

To accommodate part-to-part variations each part is factory-calibrated by Maxim. During calibration the y-intercept and slope for the series and parallel tracking capacitor arrays is calculated and written into an internal ROM table. The user must read the ROM table upon power-up and store the data in local memory (8 bytes total) to calculate the optimal TFS[7:0] and TFP[5:0] settings for each channel. Table 16 shows the address and bits for each ROM table entry. See the *Interpolating Tracking Filter Coefficients* section for more information on how to calculate the required values.

#### Reading the ROM Table

Each ROM table entry must be read using a two-step process. First, the address of the ROM bits to be read must be programmed into the TFA[3:0] bits in the Tracking Filter ROM Address register (Table 11).

Once the address has been programmed, the data stored in that address is transferred to the TFR[7:0] bits in the ROM Table Data Readback register (Table 13). The ROM data at the specified address can then be read from the TFR[7:0] bits and stored in the micro-processor's local memory.

		MSB									
DESCRIPTION	ADDRESS	DATA BYTE									
		D7	D6	D5	D4	D3	D2	D1	D0		
IFOVLD	0x0	OD2	OD1	OD0	Х	Х	Х	Х	Х		
VHF Low Series/ Parallel Y-Intercept	0x1	LS0[5]	LS0[4]	LS0[3]	LS0[2]	LS0[1]	LS0[0]	LS1[3]	LS1[2]		
VHF High Series/ Parallel Y-Intercept	0x2	LS1[1]	LS1[0]	LP0[5]	LP0[4]	LP0[3]	LP0[2]	LP0[1]	LP0[0]		
UHF Series/ Parallel Y-Intercept	0x3	LP1[3]	LP1[2]	LP1[1]	LP1[0]	HS0[3]	HS0[2]	HS0[1]	HS0[0]		
VHF Low Series Slope	0x4	HS1[3]	HS1[2]	HS1[1]	HS1[0]	HP0[3]	HP0[2]	HP0[1]	HP0[0]		
VHF High Parallel Slope	0x5	HP1[3]	HP1[2]	HP1[1]	HP1[0]	US0[7]	US0[6]	US0[5]	US0[4]		
VHF Low Parallel Slope	0x6	US0[3]	US0[2]	US0[1]	US0[0]	US1[5]	US1[4]	US1[3]	US1[2]		
VHF High Parallel Slope	0x7	US1[1]	US1[0]	UP0[7]	UP0[6]	UP0[5]	UP0[4]	UP0[3]	UP0[2]		
UHF Parallel Slope	0x8	UP0[1]	UP0[0]	UP1[5]	UP1[4]	UP1[3]	UP1[2]	UP1[1]	UP1[0]		

#### Table 16. ROM Table



#### Interpolating Tracking Filter Coefficients

The TFS[7:0] and TFP[5:0] bits must be reprogrammed for each channel frequency to optimize performance. The optimal settings for each channel can be calculated from the ROM table data using the equations below. VHF LO filter:

$$TFS = 10 \left[ (2.4 + \frac{LS0}{64} \times 0.6) + (-8.5 + \frac{LS1}{16} \times 2) \times f_{RF} \times 10^{-3} \right]$$
$$TFP = INT \left[ 10^{\left[ (1.6 + \frac{LP0}{64} \times 0.4) + (-6 + \frac{LP1}{16} \times 2) \times f_{RF} \times 10^{-3} \right]} \right]$$

VHF High filter:

$$TFS = INT \left[ 10^{\left[ (2.8 + \frac{HS0}{16} \times 0.8) + (-4.2 + \frac{HS1}{16} \times 0.8) \times f_{RF} \times 10^{-3} \right]} \right] - 20$$
$$TFP = INT \left[ 10^{\left[ (1.6 + \frac{HP0}{16} \times 0.8) + (-1.5 + \frac{HP1}{16} \times 0.6) \times f_{RF} \times 10^{-3} \right]} \right] - 10$$

UHF filter:

$$TFS = INT \left[ 10^{\left[ (3 + \frac{US0}{256}) + (-2.6 + \frac{US1}{64} \times 0.8) \times f_{RF} \times 10^{-3} \right]} \right] - 20$$
$$TFP = INT \left[ 10^{\left[ (1.6 + \frac{UP0}{256} \times 0.8) + (-1.4 + \frac{UP1}{64} \times 0.8) \times f_{RF} \times 10^{-3} \right]} \right] - 10$$

Where:

f<sub>RF</sub> = operating frequency in MHz

- TFS = decimal value of the optimal TFS[7:0] setting (Table 9) for the given operating frequencyTFP = decimal value of the optimal TFP[5:0] setting (Table 10) for the given operating frequency
- LS0, LS1, LP0, LP1, HS0, HS1, HP0, HP1, US0, US1, UP0, and UP1 = the decimal values of the ROM table coefficients (Table 16).

#### IF Overload Detector

The MAX3541 includes a broadband IF overload detector, which provides an indication of the total power present at the RF input. The overload-detector output voltage is compared to a reference voltage and the difference is amplified. This error signal drives an opencollector transistor whose collector is connected to the IFOVLD pin, causing the IFOVLD pin to sink current.

The nominal full-scale current sunk by the IFOVLD pin is 300 $\mu A.$  The IFOVLD pin requires a 10k $\Omega$  pullup resistor to VCC.

The IF overload detector is calibrated at the factory to attack at 0.6V<sub>P-P</sub> at IFOUT1. Upon power-up, the baseband processor must read OD[2:0] from the ROM table and store it in the IFVOLD register.

#### **Closed-Loop RF Gain Control**

Closed-loop RF gain control can be implemented by connecting the IFOVLD output to the RFAGC input. Using a  $10k\Omega$  pullup resistor on the IFOVLD pin, as shown in the *Typical Application Circuit*, results in a nominal 0.5V to 3V control voltage range.

#### VCO and VCO Divider Selection

The MAX3540 frequency synthesizer includes three VCOs and eight VCO sub-bands to guarantee a 2160MHz to 4400MHz VCO frequency range. The frequency synthesizer also features an additional VCO frequency divider, which must be programmed to either 4, 8, 16, or 32 through the VDIV[1:0] bits in the VCO register based on the channel being received. Table 5 describes how the VDIV[1:0] bits should be programmed for each band of operation.

To ensure PLL, lock the proper VCO and VCO sub-band for the channel being received, which must be chosen by iteratively selecting a VCO and VCO sub-band then reading the LD[2:0] bits to determine if the PLL is locked. Any reading from 001 to 110 indicates the PLL is locked. If LD[2:0] reads 000, the PLL is unlocked and the selected VCO is at the bottom of its tuning range; a lower VCO subband must be selected. If LD[2:0] reads 111, the PLL is unlocked and the selected VCO is at the top of its tuning range; a higher VCO sub-band must be selected. The VCO and VCO sub-band settings should be progressively increased or decreased until the LD[2:0] reading falls in the 001 to 110 range.

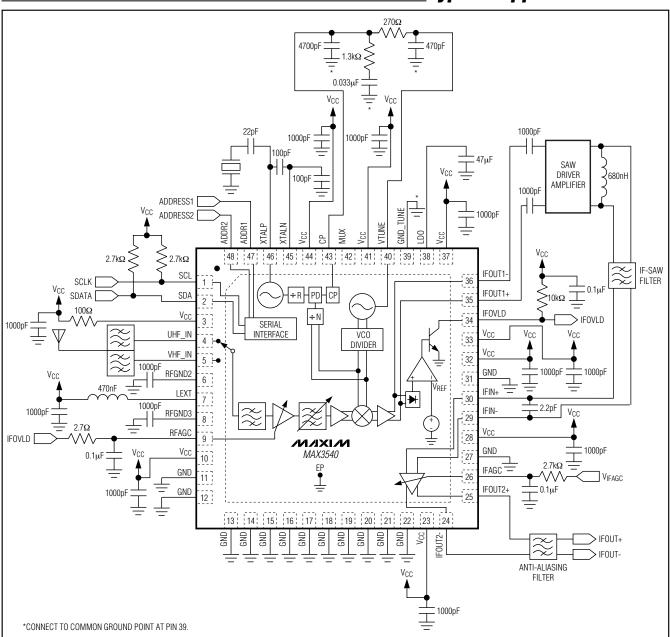
Due to overlap between VCO sub-band frequencies, it is possible that multiple VCO settings can be used to tune to the same channel frequency. System performance at a given channel should be similar between the various possible VCO settings, so it is sufficient to select the first VCO and VCO sub-band that provides lock.

#### **Layout Considerations**

The MAX3540 EV kit can serve as a guide for PCB layout. Keep RF signal lines as short as possible to minimize losses and radiation. Use controlled impedance on all high-frequency traces. The exposed paddle must be soldered evenly to the board's ground plane for proper operation. Use abundant vias beneath the exposed paddle for maximum heat dissipation. Use abundant ground vias between RF traces to minimize undesired coupling.

**MAX3540** 

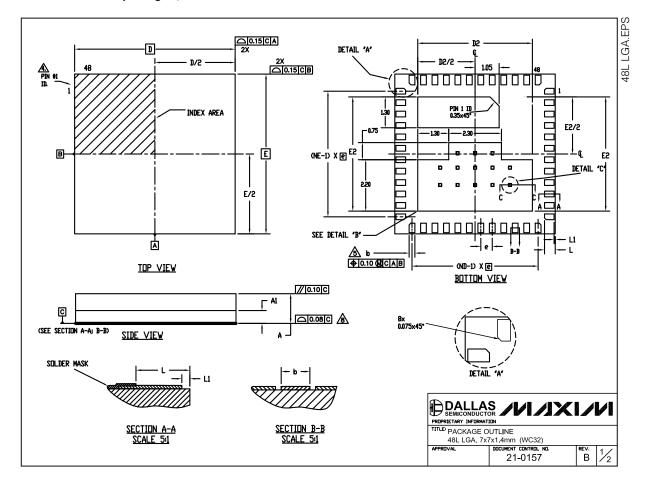
To minimize coupling between different sections of the IC, the ideal power-supply layout is a star configuration, which has a large decoupling capacitor at the central  $V_{CC}$  node. The  $V_{CC}$  traces branch out from this node, with each trace going to separate  $V_{CC}$  pins of the MAX3540. Each V<sub>CC</sub> pin must have a bypass capacitor with a low impedance to ground at the frequency of interest. Do not share ground vias among multiple connections to the PCB ground plane.



### **Typical Application Circuit**

## **Package Information**

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information go to **www.maxim-ic.com/packages**.)

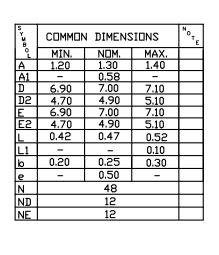


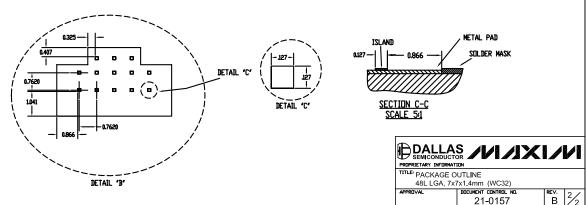
## **Package Information (continued)**

(The package drawing(s) in this data sheet may not reflect the most current specifications. For the latest package outline information go to <u>www.maxim-ic.com/packages</u>.)

NOTES:

- 1. DIMENSIONING & TOLERANCING CONFORM TO ASME Y14.5M-1994.
- 2. ALL DIMENSIONS ARE IN MILLIMETERS. ANGLES ARE IN DEGREES.
- 3. N IS THE TOTAL NUMBER OF TERMINALS.
- A THE TERMINAL #1 IDENTIFIER AND TERMINAL NUMBERING CONVENTION SHALL CONFORM TO JESD 95-1 SPP-012. DETAILS OF TERMINAL #1 IDENTIFIER ARE OPTIONAL, BUT MUST BE LOCATED WITHIN THE ZONE INDICATED. THE TERMINAL #1 DENTIFIER MAY BE EITHER A MOLD OR MARKED FEATURE.
- A DIMENSION & APPLIES TO METALLIZED TERMINAL AND IS MEASURED BETWEEN 0.25 mm AND 0.30 mm FROM TERMINAL TIP.
- A ND AND NE REFER TO THE NUMBER OF TERMINALS ON EACH D AND E SIDE RESPECTIVELY.
- 7. DEPOPULATION IS POSSIBLE IN A SYMMETRICAL FASHION.
- COPLANARITY APPLIES TO THE EXPOSED HEAT SINK SLUG AS WELL AS THE TERMINALS.
- 9. WARPAGE SHALL NOT EXCEED 0.10 mm.





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