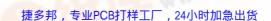
查询PBD3545/1供应商

ERICSSON 🔰



January 1993

PBD 3545/1 Universal Sink Driver

Description

PBD 3545/1 is a bipolar universal high-current highly-protected low side driver with transparent input and 2 A continuous-current sink capability. A high-level input activates the output.

The driver is equipped with extensive electrical protection, such as overcurrent protection and thermal protection, which makes the device viritually indestructible. Furthermore it can detect open circuit and short circuit to ground.

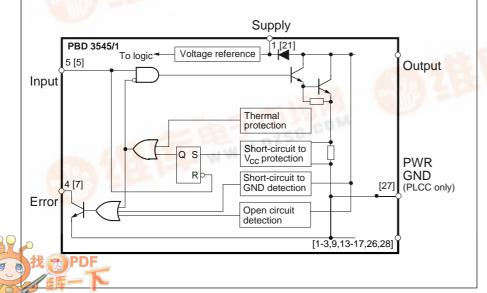
A special feature is the Error indicating output function pin which signals to the host system if the protection or the load check functions is activated.

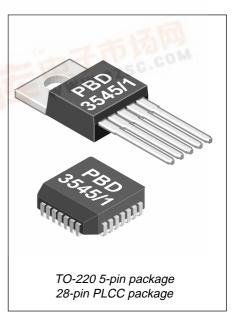
Typical loads are solenoids, relays or resistive loads.

The PBD 3545/1 and PBD 3548/1 are complementary drivers and have similar data.

Key Features

- 2 A continuous-output current
- Short circuit to V_{CC} protection
- Error signal to host system
- Open circuit detection
- Short circuit to ground detection
- Thermal protection
- Built-in protection diodes
- LS-TTL, CMOS, and supply voltage compatible input
- ESD protected
- 5-pin TO-220 package, or 28-lead power PLCC with lead-frame for heatsinking through PC board copper.





Wigure 1: Block Diagram. Pin number in brackets refer to PLCC package.

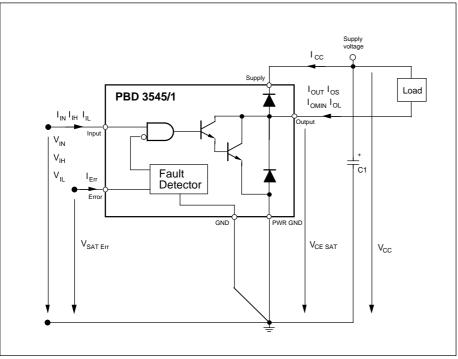
ERICSSON 💋

Maximum Ratings

Parameter	Pin no.	Symbol	Min	Мах	Unit
Voltage					
Supply voltage	1 [21]	V _{cc}	0	45	V
Logic input voltage	5 [5]	V _{IN}	-0.3	V _{cc}	V
Current					
Logic input current	5 [5]	I _{IN}	-10		mA
Continuous DC Operation output current	2 [24]	I _{OUT}		2.0	Α
Error output current	4 [7]	I		10	mA
Temperature					
Operating junction temperature (internally limited)		T		+140	°C
Storage temperature		T _s	-55	+150	°C
Power Dissipation (Package Data)					
Power dissipation at $T_{Case} = 85^{\circ}C$, TO-220 package		P _D		11	W
Power dissipation at $T_{Case} = 85^{\circ}C$, PLCC package		P		5	W
ESD					
ESD tolerance (Note 2)			2000		V

Recommended Operating Conditions

Parameter	Symbol	Min	Тур	Max	Unit
Supply voltage	V _{cc}	4.75		40	V
Output current	I _{OUT}			2.0	A
Operating ambient temperature	T _A	-40		+85	°C
Error output current	l _{Err}		5	8	mA



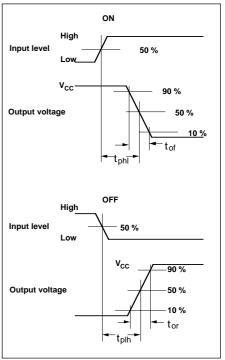


Figure 3. Timing diagram, input vs. output. $V_{cc} = 24V$.

Figure 2. Definition of symbols.

ERICSSON 🗾

PBD 3545/1

Electrical Characteristics

At 5 V \leq V_{cc} \leq 40 V, -40°C \leq T_J \leq +100°C. Typical values are given at V_{cc} = 24 V, T_J = 25°C.

Parameter	Symbol	Ref. fig.	Conditions	Min	Тур	Max	Unit
General							
Supply currrent	I _{cc}	2,7	$0 \le V_{IN} \le 0.8$	1.5	4	7	mA
Thermal shutdown	T _{JS}			+120	+130	+140	°C
Thermal shutdown release	T _{JSR}			+110	+120	+130	°C
Logic input							
High level input voltage	V _{IH}	2		2.0		V _{cc}	V
Low level input voltage	VIL	2		-0.3		0.8	V
High level input current	I _{IH}	2,9	$2.0 \le V_{IN} \le V_{CC}$		9	20	μA
Low level input current	I _{IH}	2,9	$0 \le V_{IN} \le 0.8$	-400			μΑ
Outputs							
Error output saturation voltage	V _{Err SAT}	2,10	I _{Err} = 5 mA		0.2	1	V
Output saturation voltage V _c		2,11	$I_{OUT} = 2$ A		1.4	1.8	V
Output current shutdown		2,5,14		2.0	3.2	4.5	Α
Output current		2,5	$2.0 \le V_{\rm IN} \le V_{\rm CC}$	0.5	2	8	mA
(not detected as open circuit)	onne						
Output leakage current	I _{ol}	2,12	0 V≤ V _{IN} ≤0.8 V. Output = 0 V	-8	-6	-2	μΑ
Clamping diode forward voltage	~~~	8	$I_F = 2.0 \text{ A}$		1.5	1.8	V
Timing							
Propagation time		3	I _{OUT} = 2 A				
Output high to low (50%), t _{phl}					1.5	3.0	μs
Output low to high (50%), t _{plh}					0.5	1.0	μs
Rise time (10 to 90%),	t _{or}	3			0.2	0.5	μs
Fall time (90 to 10%), t _{of}		3			0.2	0.5	μs

Thermal Charateristics

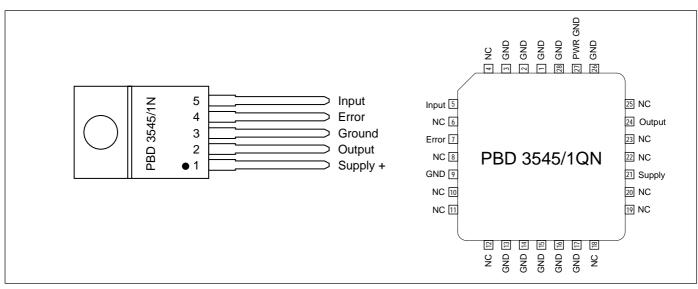
Parameter	Symbol	Ref. fig.	Conditions	lin	Тур	Max	Unit
Thermal resistance	Rth	21	TO-220 package, junction to case		5		°C/W
	Rth J-A	21	TO-220 package, junction to ambient		60		°C/W
	Rth _{J-BW}	20	PLCC package, junction to batwing, note	e 4		10	°C/W
	Rth _{J-A}	20,22	PLCC package, note 3.		35		°C/W

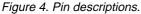
Notes: 1. Currents are defined positive if flowing into, and negative if flowing out of a terminal. Voltages are defined between terminal and ground.

2. ESD testing according to Human Body Model ($C_{zap} = 100 \text{ pF}$, $R_{zap} = 1500 \Omega$) 3. All ground pins soldered onto a 20 cm² PCB copper area with free air convection, $T_A = +25^{\circ}C$.

4. Batwing = Ground pins.

ERICSSON 📁





Pin Description

TO-220	PLCC	Symbol	Description
1	[21]	Supply	Supply voltage. Nominally 5 V to 40 V.
2	[24]	Output	Output pin. Current flows from supply through the load into the pin. Nominal current is 8 mA to 2 A.
3	[1-3,9,	GND	Ground supply. Note: for PLCC these pins are used thermally for heat sinking. Make sure that all pins
	13-17,	26,28]	are soldered onto a suitably large copper ground for efficient heat sinking. Power ground pin.
	[27]	PWR	In the PLCC package, the emitter of the output transistor including the protection
		GND	diode are bonded to a separate pin.
4	[7]	Error	Error indicating pin. Sinks current to ground if the protection and/or detection circuitry is activated. Note: the current must be externally limited to 8 mA.
5	[5]	Input	TTL compatible input. A LOW input signal turns the output transistor off and a HIGH input turns it on. If the input is left open it will be detected as low level.
NC	[4,6,8, 18-20,	10-12 22,23,25]	No connection. Pins are not bonded to the chip and may therefore be soldered to any PC board trace for efficient heat sinking.

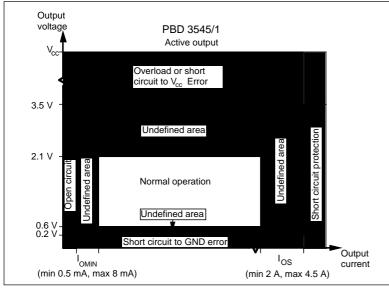


Figure 5. Error state vs. output voltage and output current, active output ($2.0 \le V_{IN} \le V_{CC}$), 5 V < V_{CC} < 40 V, - 40°C <T_J < +100°C.

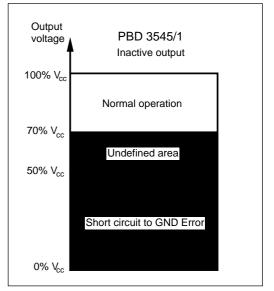


Figure 6. Error state vs. output voltage, inactive output (0 V \leq V_{IN} \leq 0.8 V), 5 V \leq V_{CC} \leq 40 V, - 40°C < T_J < +100°C.

ERICSSON 📕

Typical Performance Characeristics

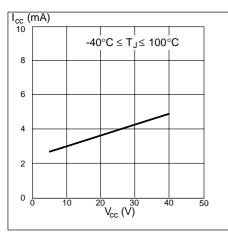


Figure 7. Current consumption vs. supply voltage at $0 V \le V_{in} \le 0.8 V$. (Inactive output)

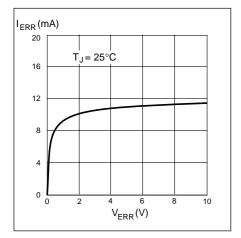


Figure 10. Error output saturation voltage vs. error current. $V_{cc} = 24 V$.

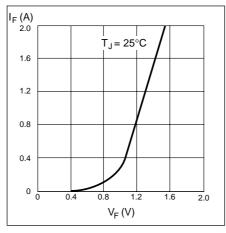


Figure 8. Diode forward voltage drop vs. forward current.

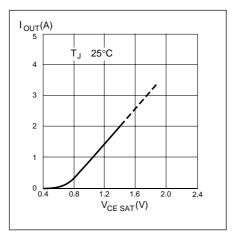


Figure 11. Output saturation voltage vs. output current. 5 V < V_{cc} < 40 V.

Figure 9. Input current vs. input voltage. 5 $V \le V_{cc} \le 40 V$.

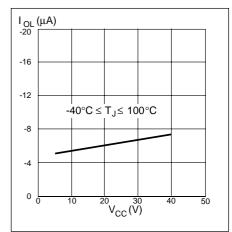


Figure 12. Output leakage current vs. supply voltage. $0 V \le V_{IN} \le 0.8 V$. Output = 0 V.

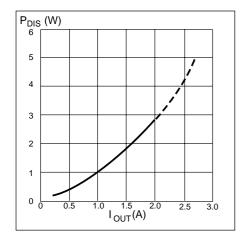


Figure 13. Power dissipation vs. output current.

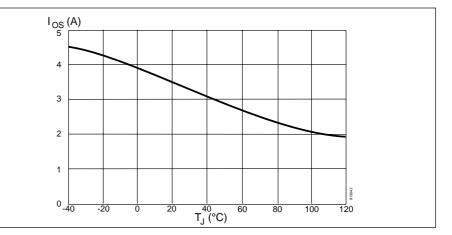


Figure 14. Typical output current shut-down vs. chip temperature. 5 $V \le V_{cc} \le 40 V$.

PBD 3545/1

Functional Description

The circuit PBD 3545/1 is a low side driver capable of driving resistive or inductive loads not exceeding 2 A.

The driver has an error indicating function which generates an Error output signal when a fault condition has occurred.

The circuits PBD 3545/1 and PBD 3548/1 are complementary drivers with equivalent functions and similar data. PDB 3545/1 is a sink driver and PBD 3548/1 is a source driver.

Input stage

The output stage is switched on and off according to the status of the input. HIGH level activates the output. If the input is left open, the circuit will accept it as a LOW level.

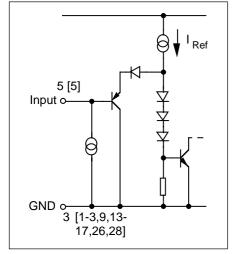


Figure 15. Input stage.

Output stage

The output stage contains a power transistor and two clamping diodes. The diodes are used for terminating line transients from inductive loads. If the driver is inactive and the output is shorted to GND the driver will leak maximum

8 μA. See figure 12.

Protection circutry

The circuit contains two protection circuits:

- Overload and Short circuit protection
- Thermal protection .

The overload and short circuit protection will be activated at I_{out} = 3.5 A typically at T_{1} = +25°C, see figure 14.

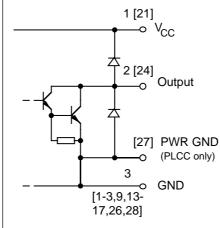


Figure 16. Output stage.

0 LOW

Fault condition Input Output Error How to resume normal operation LOW=ERROR HIGH=Normal LOW Normal 0 1 OFF 1 HIGH 1 HIGH 0 ON 1 HIGH Vout Short to GND Remove fault condition. 0 LOW OFF 0 LOW 1 0 LOW 1 HIGH ON Remove fault condition. 0 V_{out} Short to V_{cc} 0 LOW 1 OFF 1 HIGH 1 HIGH OFF LOW 1 0 Turn off and on after fault condition is removed. LOW HIGH Open load 0 1 OFF 1 1 HIGH 0 ON 0 LOW Attach proper load to output or turn off the driver. Over temperature LOW OFF HIGH 0 1 1

The output will be turned off immediately and latched to a high-impedance state after an overload or short circuit

A logic-level change at the input will reset the internal error latch. If the fault still is present at turn-on, the circuit will once again turn the output off.

Due to a slight delay in the circuit, a high current transient will occur when the output is shorted to V_... This current transient may reach 8 A during 5 µs. Consequently, switching at high frequencies with a shorted output may destroy the circuit. If a short circuit condition is detected, stop switching the input and remove fault condition.

Thermal protection

has been detected.

The output of PDB 3545/1 is equipped with a thermal shut-down function, which limits the junction temperature to typically +130°C. The output will be turned off until the junction temperature has decreased to approximately 120°C.

Error functions

Temperature is reduced to approx 120°C, or turn off the driver.

The Error indicating signal occurs on a separate pin. The complete error table is shown in figure 17.

The following conditions generate an error signal:

When the driver is activated and at least one of the following conditions has occurred:

Figure 17. Error table.

1

HIGH

1 OFF

T =130 °C

ERICSSON 📕

- thermal overload
- short circuit to GND
- short circuit to V_{cc}
- open circuit

An output current less than 8 mA might be detected as "open circuit". Output currents larger than 8 mA and less than 2 A will definitely not generate an error. The normal operational area is shown in figure 5.

Also when the driver is inactivated an Error indication can occur. That is if the output is shorted to GND. In figure 6 short circuit to GND Error state versus output voltage is shown.

When the Error-detection function is activated, the Error output is capable of sinking 8 mA, supporting direct connection of an LED. The current has to be externally limited by a series resistor.

Signal diagrams

The signal diagram in figure 18 shows the input signal and the resulting output signals for each error mode. For details, se error table, figure 17.

 V_{IN} = Input voltage. Active = HIGH.

V_{OUT} = Output voltage.

 I_{OUT} = Output current from driver.

 V_{ERR} = Error output voltage. Error = LOW.

Applications Information

Important application areas are:

- Programmable logic control systems.
- Security systems.
- Relay control.
- Hydraulic valves.
- Intelligent interfaces between microprocessors and loads.
- Vehicle control systems.
- · Robot techniques.
- Dashboard information systems.
- Print head drivers.
- High-current stepper motor drivers with security aspects.

Transient protection

1. Keep $\rm V_{cc}$ and GND leads as short as possible.

2. Connect a filter capacitor close to the circuit. Recommended filter capacitor between V_{cc} and GND is 6.8 μF , of tantalum type. A ceramic capacitor in

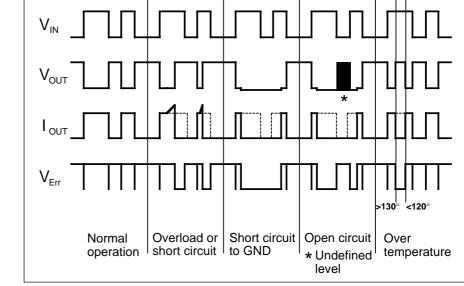


Figure 18. Signal diagram.

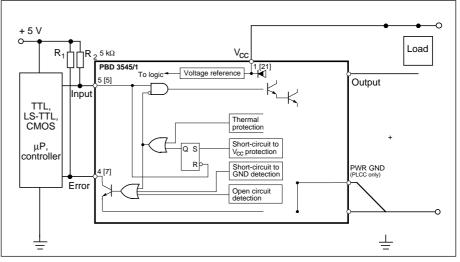


Figure 19. Typical application. Pin numbers refer to TO 220 package.

parallel will improve high frequency decoupling. Typical values range from 0.002 μF to 0.1 μF . In an application having a highly stable supply and short power leads to the driver a low leakage electrolytic type can be used, which is less expensive.

3. Connect Input and Error via pull-up resistors to the appropriate logic supply level or V_{cc} to obtain highest noise immunity. Se figure 19. The resistor R₁ limits the current into the Error indicating pin. This current must not exceed 8 mA. R₂ is a pull-up resistor which improves noise immunity at the Input. Pull-up current should not exceed the sinking capacity of the controlling device output.

4. If several supply voltages are to be used, prefere a supply having separate ground leads. In this case the logic ground and the power ground should be connected together at only one point, the ground pin of the driver.

Switch mode applications

The internal diodes are normally sufficient for clamping of transients caused by inductive load turn off. External diodes may be necessary in PWM/switch mode applications, and when the terminals are externally accessible and thereby exposed to an electrically noisy environment. Recommended diodes are BYV27/100, BYV98/100, UF4001 or similar types with a $t_r < 100$ ns and $I_F \ge 1$ A.

PBD 3545/1

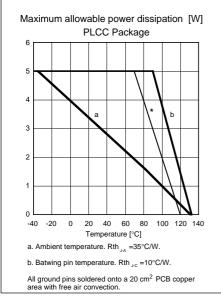


Figure 20. Maximum allowable power dissipation. PLCC package.

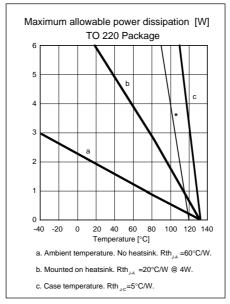
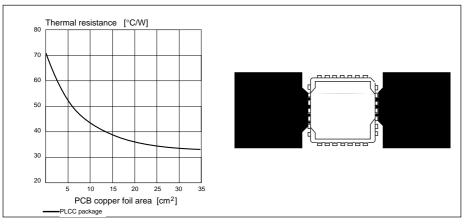


Figure 21. Maximum allowable power dissipation. TO 220 package.





Information given in this data sheet is believed to be accurate and reliable. However no responsibility is assumed for the consequences of its use nor for any infringement of patents or other rights of third parties which may result from its use. No license is granted by implication or otherwise under any patent or patent rights of Ericsson Components. These products are sold only according to Ericsson Components' general conditions of sale, unless otherwise confirmed in writing.

Specifications subject to change without notice.

1522-PBD 3545/1 Uen Rev.B © Ericsson Components 1993



Ericsson Components AB S-164 81 Kista-Stockholm, Sweden Telephone: (08) 757 50 00

Ordering Information

Package TO-220 PLCC Temp. range -40 to +85°C -40 to +85°C

Part No. PBD 3545/1N PBD 3545/1QN

ERICSSON 🔰

Error indication signal

When the circuit is switched on/off, a short pulse (t_{Err} <10 μ S for resistive loads) is generated at the Error output. This is a correct detection of an incorrect level during the rise and fall times of the output voltage. Consequently the Error output should not be detected when switching on and off. An alternative is to low-pass filter at the Error output at around 100 kHz.

Heat sinking

PBD 3545/1N is packaged in a 5-pin TO 220 power package. The circuit GND is connected to the heat sink tab. External heatsinking is achieved by mounting the package to a heat sink.

The circuit is also avaible in a 28 pin power PLCC package. In the PLCC package the circuit ground is connected to the lead frame batwing. External heatsinking is achieved by soldering the ground leads onto a copper ground plane. Note: The power ground pin (PWR GND) should also be connected to the ground plane.

Maximum continuous output current is heavily dependant on the heatsinking applied and ambient temperature. Consult figures 13, 20, 21 and 22 to determine the maximum output current under varying conditions.