A8499

## High Voltage Step－Down Regulator

## Features and Benefits

－ 8 to 50 V input range
－Integrated DMOS switch
－Adjustable fixed off－time
－Highly efficient
－Adjustable 1.2 to 24 V output

## Description

The A8499 is a step down regulator that will handle a wide input operating voltage range．
The A8499 is supplied in a low－profile 8－lead SOIC with exposed pad（package LJ）．
Applications include：
－Printer power supplies
－Consumer equipment power supplies

## Package：8－Lead SOIC with exposed thermal pad（suffix LJ）



Approximate Scale 1：1

Functional Block Diagram


## Absolute Maximum Ratings

Supply Voltage, $\mathrm{V}_{\text {IN }}$ $\qquad$50 V

VBIAS Input Voltage, $\mathrm{V}_{\text {BIAS }}$.................................................... $\mathbf{0 . 3}$ to 7 V
Switch Voltage, $\mathrm{V}_{\mathrm{LX}}$. $\qquad$ - 1 V

ENB Input Voltage, $\mathrm{V}_{\mathrm{ENB}}$.................................................... $\mathbf{0 . 3}$ to $\mathbf{7}$ V
Junction Temperature, $\mathrm{T}_{\mathrm{J}(\max )}$. $\qquad$ $150^{\circ} \mathrm{C}$
Storage Temperature, $\mathrm{T}_{\mathrm{S}} \ldots . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . . ~-55^{\circ} \mathrm{C}$ to $\mathbf{1 5 0}^{\circ} \mathrm{C}$
Operating Ambient Temperature, $\mathrm{T}_{\mathrm{A}}$ $\qquad$

## Package Thermal Characteristics*

| Package | $\mathbf{R}_{\text {日JA }}$ <br> $\left({ }^{\circ} \mathrm{C} / \mathrm{W}\right)$ | PCB |
| :---: | :---: | :---: |
| LJ | 35 | 4-layer |

* Additional information is available on the Allegro Web site


## Ordering Information

Use the following complete part numbers when ordering:

| Part Number | Packing $^{\mathbf{b}}$ | Description |
| :---: | :---: | :---: |
| A8499SLJTR-T | 13 in. reel, 3000 pieces/reel | LJ package, SOIC surface mount with |
| A8499SLJ-T | 98 pieces/tube |  |

## A8499

## High Voltage Step-Down Regulator

ELECTRICAL CHARACTERISTICS ${ }^{1,2}$ at $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}, \mathrm{V}_{\text {IN }}=8$ to 50 V (unless noted otherwise)

| Characteristics | Symbol | Test Conditions | Min. | Typ. | Max. | Units |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| VIN Quiescent Current | $\mathrm{I}_{\mathrm{VIN}(\mathrm{Q})}$ | $\begin{aligned} & V_{\text {ENB }}=L O W, I_{\text {OUT }}=0 \mathrm{~mA}, \mathrm{~V}_{\mathrm{IN}}=42 \mathrm{~V} \\ & \mathrm{~V}_{\mathrm{BIAS}}=\mathrm{V}_{\text {OUT }}\left(\text { see note }{ }^{3}\right) \end{aligned}$ | - | 0.90 | 1.35 | mA |
|  |  | $\begin{aligned} & \mathrm{V}_{\mathrm{ENB}}=\mathrm{LOW}, \mathrm{I}_{\mathrm{OUT}}=0 \mathrm{~mA}, \mathrm{~V}_{\mathrm{IN}}=42 \mathrm{~V} \\ & \mathrm{~V}_{\mathrm{BIAS}}<3 \mathrm{~V} \end{aligned}$ | - | 4.4 | 6.35 | mA |
|  |  | $\mathrm{V}_{\mathrm{ENB}}=\mathrm{HIGH}$ | - | - | 100 | $\mu \mathrm{A}$ |
| VBIAS Input Current | $\mathrm{I}_{\text {BIAS }}$ | $\mathrm{V}_{\text {BIAS }}=\mathrm{V}_{\text {OUT }}$ | - | 3.5 | 5 | mA |
| Buck Switch On Resistance | $\mathrm{R}_{\mathrm{DS} \text { (on) }}$ | $\mathrm{T}_{\mathrm{A}}=25^{\circ} \mathrm{C}, \mathrm{I}_{\text {OUT }}=2 \mathrm{~A}$ | - | 700 | 800 | $\mathrm{m} \Omega$ |
|  |  | $\mathrm{T}_{\mathrm{A}}=125^{\circ} \mathrm{C}, \mathrm{I}_{\text {OUT }}=2 \mathrm{~A}$ | - | - | 1.6 | $\Omega$ |
| Fixed Off-Time Proportion |  | Based on calculated value | -15 | - | 15 | \% |
| Feedback Voltage | $\mathrm{V}_{\mathrm{FB}}$ |  | 1.176 | 1.200 | 1.224 | V |
| Output Voltage Regulation |  | $\mathrm{I}_{\text {Out }}=0 \mathrm{~mA}$ to 2 A | -3 | - | 3 | \% |
| Feedback Input Bias Current | $\mathrm{I}_{\text {FB }}$ |  | -400 | -100 | 100 | nA |
| Soft Start Time | $\mathrm{t}_{\text {ss }}$ |  | 5 | 10 | 15 | ms |
| Buck Switch Current Limit | $\mathrm{I}_{\mathrm{CL}}$ | $\mathrm{V}_{\mathrm{FB}}>0.5 \mathrm{~V}$ | 2.2 | - | 3 | A |
|  |  | $\mathrm{V}_{\mathrm{FB}}<0.5 \mathrm{~V}$ | 0.5 | - | 1.2 | A |
| ENB Open Circuit Voltage | $\mathrm{V}_{\text {OC }}$ | Output disabled | 2.0 | - | 7 | V |
| ENB Input Voltage Threshold | $\mathrm{V}_{\mathrm{ENB}(0)}$ | LOW level input (Logic 0), output enabled | - | - | 1.0 | V |
| ENB Input Current | $\mathrm{I}_{\mathrm{ENB}(0)}$ | $\mathrm{V}_{\mathrm{ENB}}=0 \mathrm{~V}$ | -10 | - | -1 | $\mu \mathrm{A}$ |
| VIN Undervoltage Threshold | $\mathrm{V}_{\text {UVLO }}$ | $\mathrm{V}_{\text {IN }}$ rising | - | 6.9 | 7.1 | V |
| VIN Undervoltage Hysteresis | $\mathrm{V}_{\text {UVLOHYS }}$ | $\mathrm{V}_{\text {IN }}$ falling | 0.7 | - | 1.1 | V |
| Thermal Shutdown Temperature | $\mathrm{T}_{\text {JTSD }}$ | Temperature increasing | - | 165 | - | ${ }^{\circ} \mathrm{C}$ |
| Thermal Shutdown Hysteresis | $\Delta \mathrm{T}_{J}$ | Recovery $=\mathrm{T}_{\text {JTSD }}-\Delta \mathrm{T}_{J}$ | - | 15 | - | ${ }^{\circ} \mathrm{C}$ |

1. Negative current is defined as coming out of (sourcing) the specified device pin.
2. Specifications over the junction temperature range of $0^{\circ} \mathrm{C}$ to $125^{\circ} \mathrm{C}$ are assured by design and characterization.
3. VBIAS is connected to VOUT node when $\mathrm{V}_{\text {OUT }}$ target level is between 3.3 and 5 V .

## A8499

# High Voltage Step-Down Regulator 

## Functional Description

The A8499 is a fixed off-time, current-mode-controlled buck switching regulator. The regulator requires an external clamping diode, inductor, and filter capacitor, and operates in both continuous and discontinuous modes. An internal blanking circuit is used to filter out transients resulting from the reverse recovery of the external clamp diode. Typical blanking time is 200 ns .

The value of a resistor between the TSET pin and ground determines the fixed off-time (see graph in the $\mathrm{t}_{\text {off }}$ section).
$\mathbf{V}_{\text {OUT }}$. The output voltage is adjustable from 1.2 to 24 V , based on the combination of the value of the external resistor divider and the internal $1.2 \mathrm{~V} \pm 3 \%$ reference. The voltage can be calculated with the following formula:

$$
\begin{equation*}
V_{\mathrm{OUT}}=V_{\mathrm{FB}} \times(1+\mathrm{R} 1 / \mathrm{R} 2) \tag{1}
\end{equation*}
$$

Light Load Regulation. To maintain voltage regulation during light load conditions, the switching regulator enters a cycle-skipping mode. As the output current decreases, there remains some energy that is stored during the power switch minimum on-time. In order to prevent the output voltage from rising, the regulator skips cycles once it reaches the minimum on-time, effectively making the off-time larger.

Soft Start. An internal ramp generator and counter allow the output to slowly ramp up. This limits the maximum demand on the external power supply by controlling the inrush current required to charge the external capacitor and any dc load at startup. Internally, the ramp is set to 10 ms nominal rise time. During soft start, current limit is 2.2 A minimum.
The following conditions are required to trigger a soft start:

- $\mathrm{V}_{\mathrm{IN}}>6 \mathrm{~V}$
- ENB pin input falling edge
- Reset of a TSD (thermal shut down) event
$\mathbf{V}_{\text {BIAS. }}$. To improve overall system efficiency, the regulator output, $\mathrm{V}_{\text {OUT }}$, is connected to the VBIAS input to supply the operating bias current during normal operating conditions. During start up the circuitry is run off of the VIN supply. VBIAS should be connected to VOUT when the $\mathrm{V}_{\text {OUT }}$ target level is between 3.3 and 5 V . If the output voltage is less than 3.3 V , then the A8499 can operate with an internal supply and pay a penalty in efficiency, as the bias current will come from the high voltage supply, VIN. VBIAS can also be supplied with an external voltage source. No power-up sequencing is required for normal opperation.

ON/OFF Control. The ENB pin is externally pulled to ground
to enable the device and begin the soft start sequence. When the ENB is open circuited, the switcher is disabled and the output decays to 0 V .

Protection. The buck switch will be disabled under one or more of the following fault conditions:

- $\mathrm{V}_{\mathrm{IN}}<6 \mathrm{~V}$
- ENB pin = open circuit
- TSD fault

When the device comes out of a TSD fault, it will go into a soft start to limit inrush current.
$\mathbf{t}_{\mathbf{O F F}}$. The value of a resistor between the TSET pin and ground determines the fixed off-time. The formula to calculate $\mathrm{t}_{\mathrm{OFF}}(\mu \mathrm{s})$ is:

$$
\begin{equation*}
t_{\mathrm{OFF}}=\frac{R_{\mathrm{TSET}}}{1.2 \times 10^{10}} \tag{2}
\end{equation*}
$$

where $\mathrm{R}_{\text {TSET }}(\mathrm{k} \Omega)$ is the value of the resistor. Results are shown in the following graph:

$\mathbf{t}_{\mathbf{O N}}$. From the volt-second balance of the inductor, the turn-on time, $\mathrm{t}_{\mathrm{ON}}$, can be calculated approximately by the equation:

$$
\begin{equation*}
t_{\mathrm{ON}}=\frac{\left(V_{\mathrm{OUT}}+V_{\mathrm{f}}+I_{\mathrm{OUT}} \times R_{\mathrm{L}}\right) \times t_{\mathrm{OFF}}}{V_{\mathrm{IN}}-I_{\mathrm{OUT}} \times R_{\mathrm{DS}(\mathrm{on})}-I_{\mathrm{OUT}} \times R_{\mathrm{L}}-V_{\mathrm{OUT}}} \tag{3}
\end{equation*}
$$

where
$V_{\mathrm{f}}$ is the voltage drop across the external Schottky diode,
$R_{\mathrm{L}}$ is the winding resistance of the inductor, and
$R_{\mathrm{DS}(\mathrm{on})}$ is the on-resistance of the switching MOSFET.

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## High Voltage Step-Down Regulator

The switching frequency is calculated as follows:

$$
\begin{equation*}
f_{\mathrm{SW}}=\frac{1}{t_{\mathrm{ON}}+t_{\mathrm{OFF}}} \tag{4}
\end{equation*}
$$

Shorted Load. If the voltage on the FB pin falls below 0.5 V , the regulator will invoke a 0.8 A typical overcurrent limit to handle shorted load condition at the regulator output. For low output voltages at power up and in the case of a shorted output, the offtime is extended to prevent loss of control of the current limit due
to the minimum on-time of the switcher.
The extension of the off-time is based on the value of the TSET multiplier and the FB voltage, as shown in the following table:

| $\mathrm{V}_{\mathrm{FB}}(\mathrm{V})$ | TSET Multiplier |
| :---: | :---: |
| $<0.25$ | $8 \times \mathrm{t}_{\text {OFF }}$ |
| $<0.50$ | $4 \times \mathrm{t}_{\text {OFF }}$ |
| $<0.75$ | $2 \times \mathrm{t}_{\text {OFF }}$ |
| $>0.75$ | $\mathrm{t}_{\text {OFF }}$ |

## Component Selection

L1. The inductor must be rated to handle the total load current. The value should be chosen to keep the ripple current to a reasonable value. The ripple current, $\mathrm{I}_{\text {RIPPLE }}$, can be calculated by:

$$
\begin{gather*}
I_{\mathrm{RIPPLE}}=V_{\mathrm{L}(\mathrm{OFF})} \times \mathrm{t}_{\mathrm{OFF}} / L  \tag{5}\\
\mathrm{~V}_{\mathrm{L}(\mathrm{OFF})}=\mathrm{V}_{\mathrm{OUT}}+\mathrm{V}_{f}+I_{\mathrm{L}(\mathrm{AVG})} \times R_{\mathrm{L}} \tag{6}
\end{gather*}
$$

Example:
Given $\mathrm{V}_{\text {OUT }}=5 \mathrm{~V}, \mathrm{~V}_{\mathrm{f}}=0.55 \mathrm{~V}, \mathrm{~V}_{\text {IN }}=42 \mathrm{~V}, \mathrm{I}_{\text {LOAD }}=0.5 \mathrm{~A}$, power inductor with $\mathrm{L}=180 \mu \mathrm{H}$ and $\mathrm{R}_{\mathrm{L}}=0.5 \Omega \mathrm{Rdc}$ at $55^{\circ} \mathrm{C}$, $\mathrm{t}_{\mathrm{OFF}}=$ $7 \mu \mathrm{~s}$, and $\mathrm{R}_{\mathrm{DS}(\text { on })}=1 \Omega$.

Substituting into equation 6:

$$
\mathrm{V}_{\mathrm{L}(\mathrm{OFF})}=5 \mathrm{~V}+0.55 \mathrm{~V}+0.5 \mathrm{~A} \times 0.5 \Omega=5.8 \mathrm{~V}
$$

Substituting into equation 5 :

$$
\mathrm{I}_{\text {RIPPLE }}=5.8 \mathrm{~V} \times 7 \mu \mathrm{~s} / 180 \mu \mathrm{H}=225 \mathrm{~mA}
$$

The switching frequency, $\mathrm{f}_{\mathrm{SW}}$, can then be estimated by:

$$
\begin{gather*}
f_{\mathrm{SW}}=1 /\left(\mathrm{t}_{\mathrm{ON}}+t_{\mathrm{OFF}}\right)  \tag{7}\\
t_{\mathrm{ON}}=I_{\mathrm{RIPPLE}} \times L / V_{\mathrm{L}(\mathrm{ON})}  \tag{8}\\
\mathrm{V}_{\mathrm{L}(\mathrm{ON})}=\mathrm{V}_{\mathrm{IN}}-I_{\mathrm{L}(\mathrm{AVG})} \times \mathrm{R}_{\mathrm{DS}((\mathrm{n})}-I_{\mathrm{L}(\mathrm{AVG})} \times R_{\mathrm{L}}-V_{\mathrm{OUT}} \tag{9}
\end{gather*}
$$

Substituting into equation 9:

$$
\mathrm{V}_{\mathrm{L}(\mathrm{ON})}=42 \mathrm{~V}-0.5 \mathrm{~A} \times 1 \Omega-0.5 \mathrm{~A} \times 0.5 \Omega-5 \mathrm{~V}=36 \mathrm{~V}
$$

Substituting into equation 8 :

$$
\mathrm{t}_{\mathrm{ON}}=225 \mathrm{~mA} \times 180 \mu \mathrm{H} / 36 \mathrm{~V}=1.12 \mu \mathrm{~s}
$$

Substituting into equation 7 :

$$
f_{\mathrm{SW}}=1 /(7 \mu \mathrm{~s}+1.12 \mu \mathrm{~s})=123 \mathrm{kHz}
$$

Higher inductor values can be chosen to lower the ripple current. This may be an option if it is required to increase the total maximum current available above that drawn from the switching regulator. The maximum total current available, $I_{\text {LOAD(MAX) }}$, is:

$$
\begin{equation*}
I_{\mathrm{LOAD}(\mathrm{MAX})}=I_{\mathrm{CL}(\mathrm{MIN})} \times \mathrm{t}_{\mathrm{OFF}} / L \tag{5}
\end{equation*}
$$

where $\mathrm{I}_{\mathrm{CL}(\mathrm{MIN})}$ is 2.2 A , from the Electrical Chracteristics table.
D1. The Schottky catch diode should be rated to handle 1.2 times the maximum load current. The voltage rating should be higher than the maximum input voltage expected during all operating conditions. The duty cycle for high input voltages can be very close to $100 \%$.

COUT. The main consideration in selecting an output capacitor is voltage ripple on the output. For electrolytic output capacitors, a low-ESR type is recommended.

The peak-to-peak output voltage ripple is simply $\mathrm{I}_{\text {RIPPLE }} \times \mathrm{ESR}$. Note that increasing the inductor value can decrease the ripple current. The ESR should be in the range from 50 to $500 \mathrm{~m} \Omega$.

RTSET Selection. Correct selection of RTSET values will ensure that minimum on time of the switcher is not violated and prevent the switcher from cycle skipping. For a given $\mathrm{V}_{\text {IN }}$ to $\mathrm{V}_{\text {OUT }}$ ratio, the RTSET value must be greater than or equal to the value defined by the curve in the chart RTSET Value versus $\mathrm{V}_{\text {IN }} / \mathrm{V}_{\text {OUT }}$, on the next page.
Note. The curve represents the minimum RTSET value. When calculating $\mathrm{R}_{\text {TSET }}$, be sure to use $\mathrm{V}_{\text {IN }}(\max ) / \mathrm{V}_{\text {OUT }}$ (min). Resistor tolerance should also be considered, so that under no operating conditions the resistance on the TSET pin is allowed to go below the minimum value.

## A8499

## High Voltage Step-Down Regulator



Typical Application Circuit


12 V step down to 5.0 V at 1.8 A

Pin-out Diagram


Terminal List Table

| Pin Name | Pin Description | Pin Number |
| :---: | :--- | :---: |
| BOOT | Gate drive boost node | 1 |
| ENB | On/off control logic input | 2 |
| TSET | Off-time setting | 3 |
| GND | Ground | 4 |
| NC | No connect | N/A |
| NC | No connect | N/A |
| FB | Feedback for adjustable regulator | 5 |
| VBIAS | Bias supply input | 6 |
| LX | Buck switching node | 7 |
| VIN | Supply input | 8 |
| Pad | Exposed pad for thermal dissipation | Pad |

Package LJ 8-Pin SOIC


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