Lattice®
Semiconductor Corporation

New 5V Tolerant Inputs on 22LV10D

GAL22LV10
Low Voltage E²CMOS PLD
Generic Array Logic™

FEATURES

- **HIGH PERFORMANCE E²CMOS® TECHNOLOGY**
  - 4 ns Maximum Propagation Delay
  - Fmax = 250 MHz
  - 3 ns Maximum from Clock Input to Data Output
  - UltraMOS® Advanced CMOS Technology

- **3.3V LOW VOLTAGE 22V10 ARCHITECTURE**
  - JEDEC-Compatible 3.3V Interface Standard
  - 5V Compatible Inputs
  - I/O Interfaces with Standard 5V TTL Devices (GAL22LV10C)

- **ACTIVE PULL-UPS ON ALL PINS (GAL22LV10D)**

- **E² CELL TECHNOLOGY**
  - Reconfigurable Logic
  - Reprogrammable Cells
  - 100% Tested/100% Yields
  - High Speed Electrical Erasure (<100ms)
  - 20 Year Data Retention

- **TEN OUTPUT LOGIC MACROCELLS**
  - Maximum Flexibility for Complex Logic Designs
  - Programmable Output Polarity

- **PRELOAD AND POWER-ON RESET OF ALL REGISTERS**
  - 100% Functional Testability

- **APPLICATIONS INCLUDE:**
  - Glue Logic for 3.3V Systems
  - DMA Control
  - State Machine Control
  - High Speed Graphics Processing
  - Standard Logic Speed Upgrade

- **ELECTRONIC SIGNATURE FOR IDENTIFICATION**

DESCRIPTION

The GAL22LV10D, at 4 ns maximum propagation delay time, provides the highest speed performance available in the PLD market. The GAL22LV10C can interface with both 3.3V and 5V signal levels. The GAL22LV10 is manufactured using Lattice Semiconductor's advanced 3.3V E²CMOS process, which combines CMOS with Electrically Erasable (E²) floating gate technology. High speed erase times (<100ms) allow the devices to be reprogrammed quickly and efficiently.

The generic architecture provides maximum design flexibility by allowing the Output Logic Macrocell (OLMC) to be configured by the user.

Unique test circuitry and reprogrammable cells allow complete AC, DC, and functional testing during manufacture. As a result, Lattice Semiconductor delivers 100% field programmability and functionality of all GAL products. In addition, 100 erase/write cycles and data retention in excess of 20 years are specified.
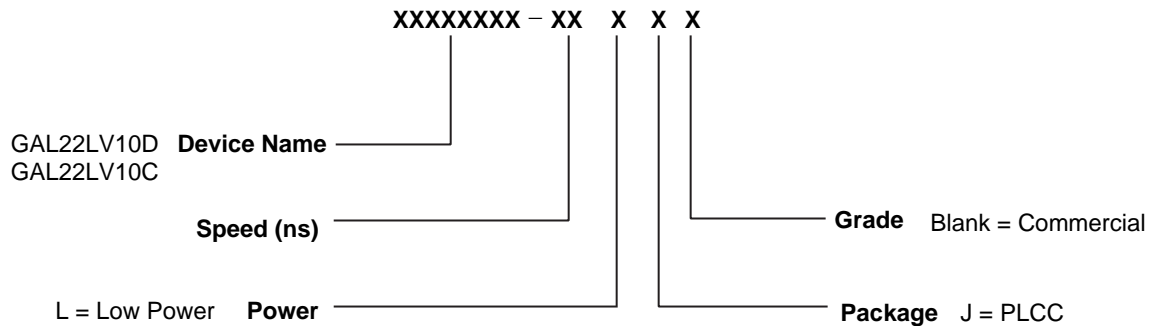
FUNCTIONAL BLOCK DIAGRAM
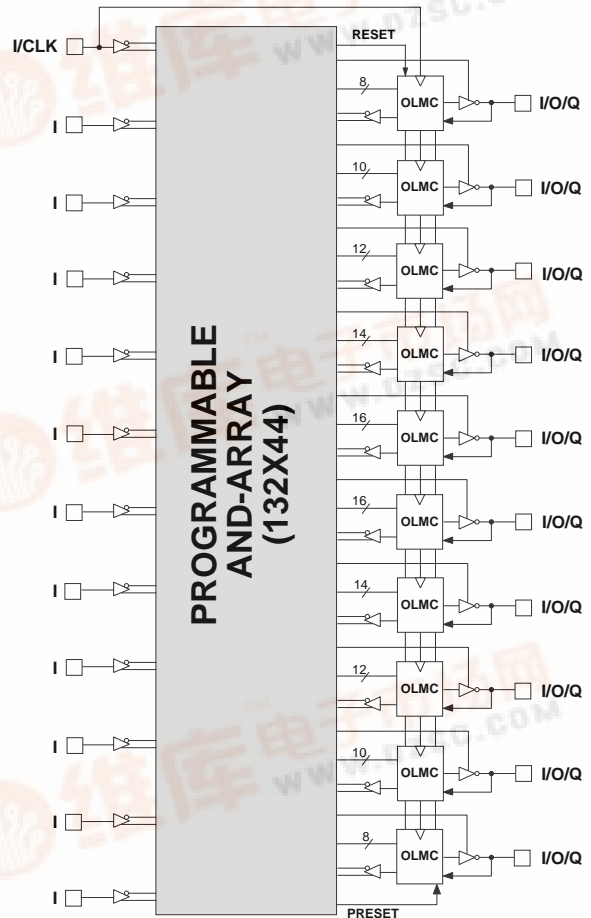
PIN CONFIGURATION

PLCC
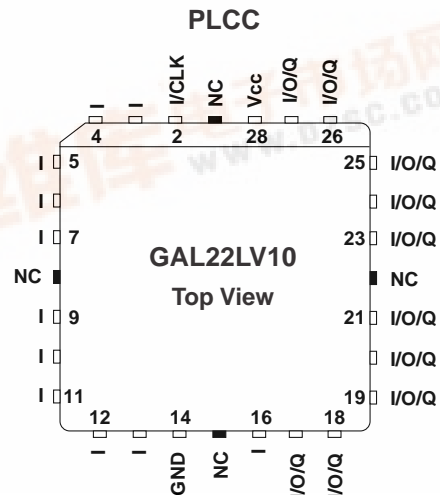
GAL22LV10
Top View

GAL22LV10 ORDERING INFORMATION

Commercial Grade Specifications

Tpd (ns)	Tsu (ns)	Tco (ns)	Icc (mA)	Ordering #	Package
4	3	3	130	GAL22LV10D-4LJ	28-Lead PLCC
5	3.5	3.5	130	GAL22LV10D-5LJ	28-Lead PLCC
7.5	6.5	5	75	GAL22LV10C-7LJ	28-Lead PLCC
10	7.5	6.5	75	GAL22LV10C-10LJ	28-Lead PLCC
15	10	10	75	GAL22LV10C-15LJ	28-Lead PLCC

PART NUMBER DESCRIPTION

XXXXXXXX − XX X X X

GAL22LV10D **Device Name**
GAL22LV10C

Speed (ns)

Grade Blank = Commercial

L = Low Power **Power**

Package J = PLCC

OUTPUT LOGIC MACROCELL (OLMC)

The GAL22LV10 has a variable number of product terms per OLMC. Of the ten available OLMCs, two OLMCs have access to eight product terms (pins 17 and 27), two have ten product terms (pins 18 and 26), two have twelve product terms (pins 19 and 25), two have fourteen product terms (pins 20 and 24), and two OLMCs have sixteen product terms (pins 21 and 23). In addition to the product terms available for logic, each OLMC has an additional product-term dedicated to output enable control.

The output polarity of each OLMC can be individually programmed to be true or inverting, in either combinatorial or registered mode. This allows each output to be individually configured as either active high or active low.

The GAL22LV10 has a product term for Asynchronous Reset (AR) and a product term for Synchronous Preset (SP). These two product terms are common to all registered OLMCs. The Asynchronous Reset sets all registers to zero any time this dedicated product term is asserted. The Synchronous Preset sets all registers to a logic one on the rising edge of the next clock pulse after this product term is asserted.

NOTE: The AR and SP product terms will force the Q output of the flip-flop into the same state regardless of the polarity of the output. Therefore, a reset operation, which sets the register output to a zero, may result in either a high or low at the output pin, depending on the pin polarity chosen.

GAL22LV10 OUTPUT LOGIC MACROCELL (OLMC)
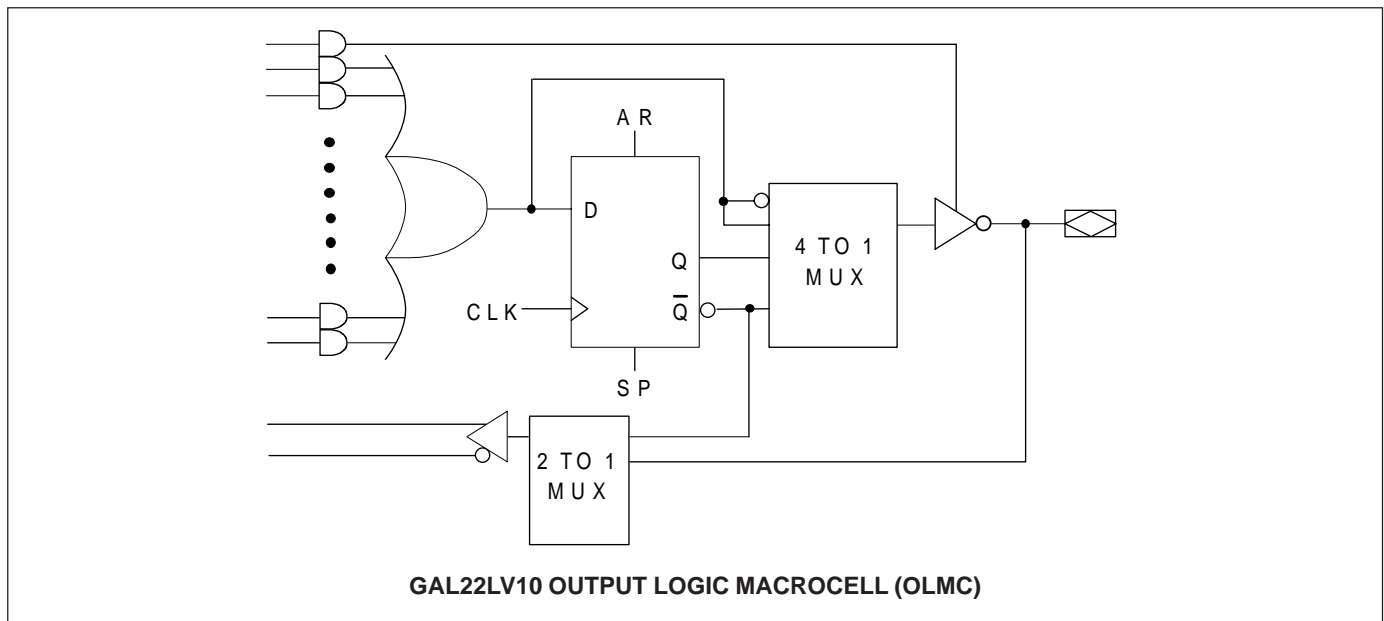
OUTPUT LOGIC MACROCELL CONFIGURATIONS

Each of the Macrocells of the GAL22LV10 has two primary functional modes: registered, and combinatorial I/O. The modes and the output polarity are set by two bits (SO and S1), which are normally controlled by the logic compiler. Each of these two primary modes, and the bit settings required to enable them, are described below and on the following page.
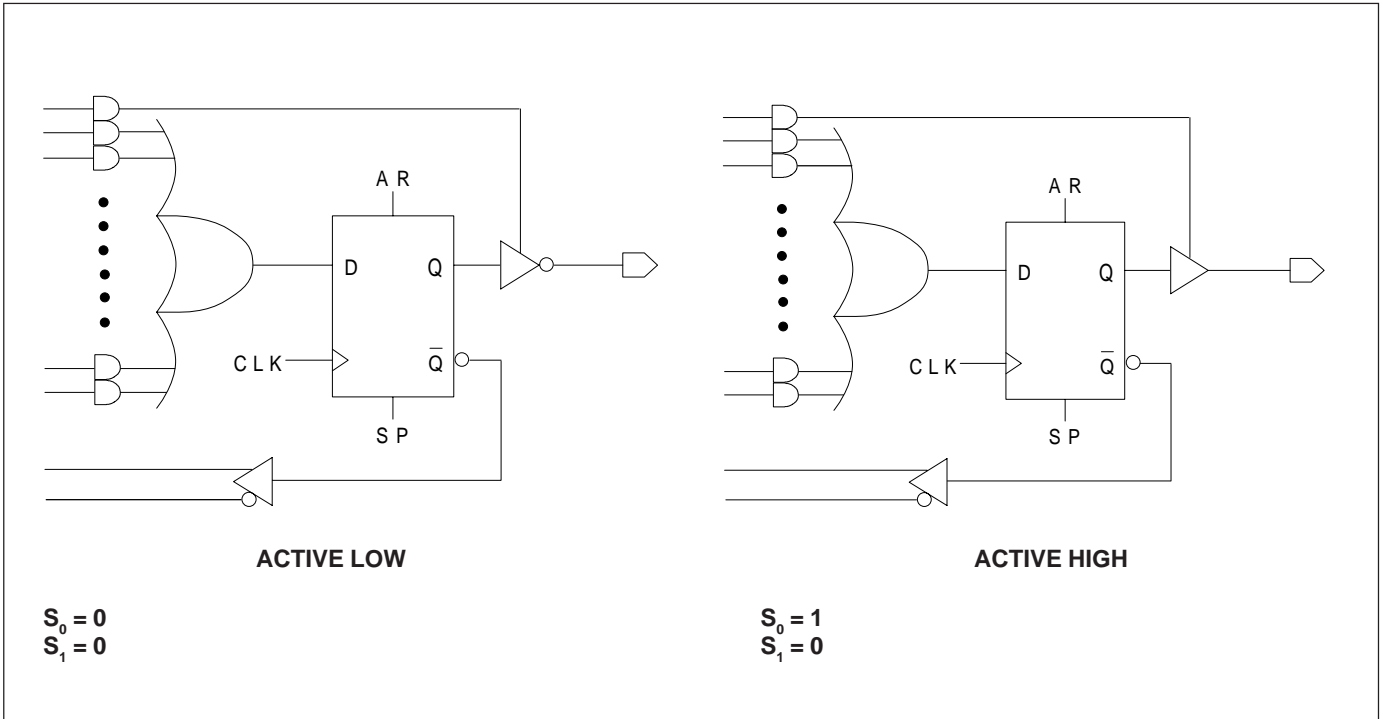
REGISTERED
In registered mode the output pin associated with an individual OLMC is driven by the Q output of that OLMC's D-type flip-flop. Logic polarity of the output signal at the pin may be selected by specifying that the output buffer drive either true (active high) or inverted (active low). Output tri-state control is available as an individual product-term for each OLMC, and can therefore be defined by a logic equation. The D flip-flop's /Q output is fed back into the AND array, with both the true and complement of the feedback available as inputs to the AND array.

NOTE: In registered mode, the feedback is from the /Q output of the register, and not from the pin; therefore, a pin defined as registered is an output only, and cannot be used for dynamic I/O, as can the combinatorial pins.
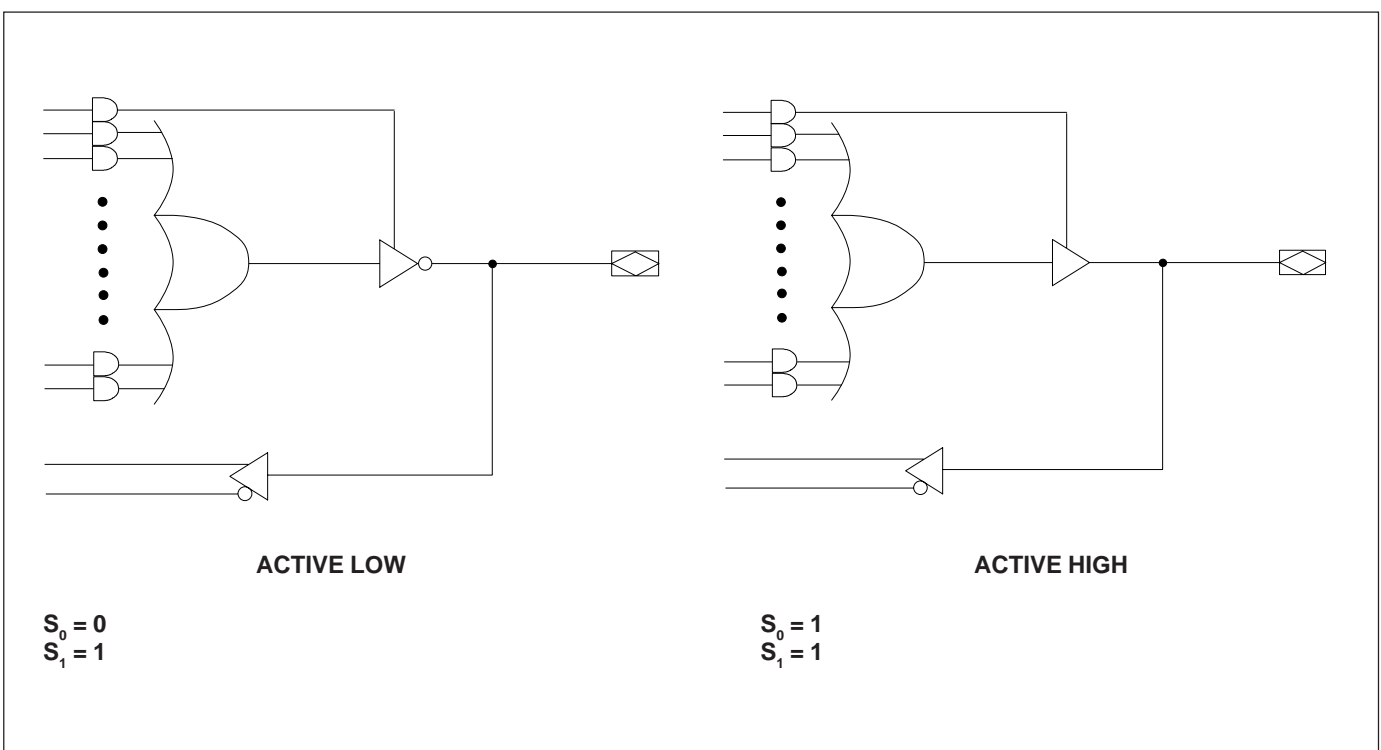
COMBINATORIAL I/O
In combinatorial mode the pin associated with an individual OLMC is driven by the output of the sum term gate. Logic polarity of the output signal at the pin may be selected by specifying that the output buffer drive either true (active high) or inverted (active low). Output tri-state control is available as an individual product-term for each output, and may be individually set by the compiler as either "on" (dedicated output), "off" (dedicated input), or "product-term driven" (dynamic I/O). Feedback into the AND array is from the pin side of the output enable buffer. Both polarities (true and inverted) of the pin are fed back into the AND array.
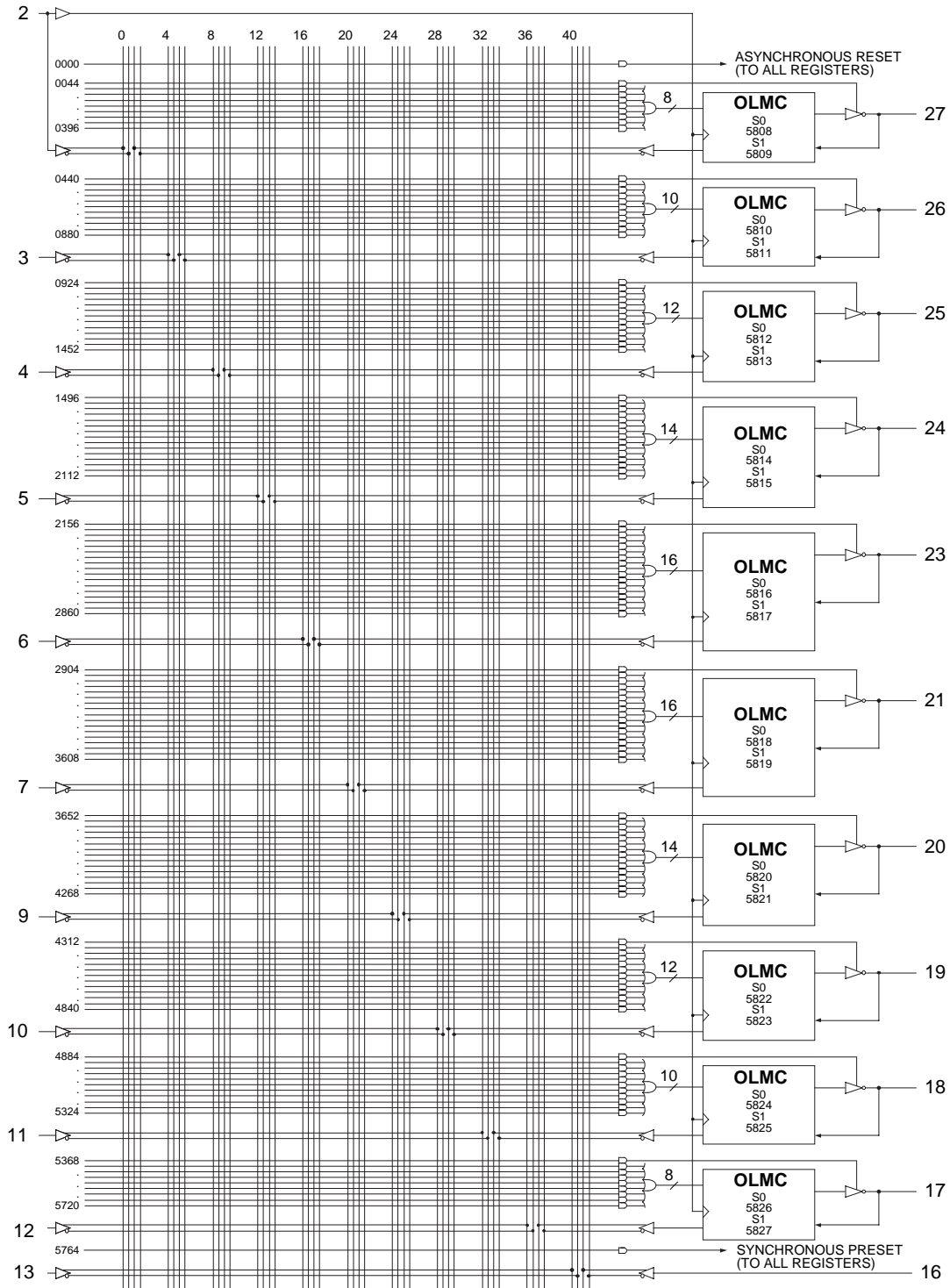
REGISTERED MODE

ACTIVE LOW

$S_0 = 0$
$S_1 = 0$

ACTIVE HIGH

$S_0 = 1$
$S_1 = 0$

COMBINATORIAL MODE

ACTIVE LOW

$S_0 = 0$
$S_1 = 1$

ACTIVE HIGH

$S_0 = 1$
$S_1 = 1$

GAL22LV10 LOGIC DIAGRAM / JEDEC FUSE MAP

PLCC Package Pinout

| 0 | 4 | 8 | 12 | 16 | 20 | 24 | 28 | 32 | 36 | 40 |

2

0000 — ASYNCHRONOUS RESET (TO ALL REGISTERS)

0044
:
0396

8 — OLMC S0 5808 S1 5809 — 27

0440
:
0880

10 — OLMC S0 5810 S1 5811 — 26

3

0924
:
1452

12 — OLMC S0 5812 S1 5813 — 25

4

1496
:
2112

14 — OLMC S0 5814 S1 5815 — 24

5

2156
:
2860

16 — OLMC S0 5816 S1 5817 — 23

6

2904
:
3608

16 — OLMC S0 5818 S1 5819 — 21

7

3652
:
4268

14 — OLMC S0 5820 S1 5821 — 20

9

4312
:
4840

12 — OLMC S0 5822 S1 5823 — 19

10

4884
:
5324

10 — OLMC S0 5824 S1 5825 — 18

11

5368
:
5720

8 — OLMC S0 5826 S1 5827 — 17

12

5764 — SYNCHRONOUS PRESET (TO ALL REGISTERS)

13 — 16

5828, 5829 ...	Electronic Signature	... 5890, 5891					
Byte 7	Byte 6	Byte 5	Byte 4	Byte 3	Byte 2	Byte 1	Byte 0

M
S
B

L
S
B

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ABSOLUTE MAXIMUM RATINGS[1]

Supply voltage V_{CC} .... -0.5 to +4.6V
Input voltage applied .... -0.5 to +5.6V
I/O voltage applied .... -0.5 to +4.6V
Off-state output voltage applied................. -0.5 to +4.6V
Storage Temperature.................................. -65 to 150°C
Ambient Temperature with
  Power Applied .... -55 to 125°C

1. Stresses above those listed under the "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress only ratings and functional operation of the device at these or at any other conditions above those indicated in the operational sections of this specification is not implied (while programming, follow the programming specifications).

RECOMMENDED OPERATING COND.

Commercial Devices:
Ambient Temperature (T_A) .... 0 to 75°C
Supply voltage (V_{CC})
  with Respect to Ground .... +3.0 to +3.6V

DC ELECTRICAL CHARACTERISTICS

Over Recommended Operating Conditions (Unless Otherwise Specified)

SYMBOL	PARAMETER	CONDITION	MIN.	TYP.[3]	MAX.	UNITS
V_{IL}	Input Low Voltage		Vss - 0.3	—	0.8	V
V_{IH}	Input High Voltage		2.0	—	5.25	V
	I/O High Voltage		2.0	—	Vcc+0.5	V
I_{IL}[1]	Input or I/O Low Leakage Current	$0V \leq V_{IN} \leq V_{IL}$ (MAX.)	—	—	-100	µA
I_{IH}	Input or I/O High Leakage Current	$(V_{CC}-0.2)V \leq V_{IN} \leq V_{CC}$	—	—	10	µA
	Input High Leakage Current	$V_{CC} \leq V_{IN} \leq 5.25V$	—	—	10	µA
	I/O High Leakage Current	$V_{CC} \leq V_{IN} \leq 4.6V$	—	—	20	mA
V_{OL}	Output Low Voltage	I_{OL} = MAX. Vin = V_{IL} or V_{IH}	—	—	0.4	V
		I_{OL} = 500µA Vin = V_{IL} or V_{IH}	—	—	0.2	V
V_{OH}	Output High Voltage	I_{OH} = MAX. Vin = V_{IL} or V_{IH}	2.4	—	—	V
		I_{OH} = -100µA Vin = V_{IL} or V_{IH}	Vcc-0.2V	—	—	V
I_{OL}	Low Level Output Current		—	—	8	mA
I_{OH}	High Level Output Current		—	—	–8	mA
I_{OS}[2]	Output Short Circuit Current	V_{CC} = 3.3V V_{OUT} = 0.5V T_A = 25°C	-15	—	-80	mA

COMMERCIAL

I_{CC}	Operating Power Supply Current	V_{IL} = 0V V_{IH} = 3.0V Unused Inputs at V_{IL} f_{toggle} = 1MHz Outputs Open	—	90	130	mA

1) The leakage current is due to the internal pull-up resistor on all pins. See **Input Buffer** section for more information.
2) One output at a time for a maximum duration of one second. Vout = 0.5V was selected to avoid test problems caused by tester ground degradation. Characterized but not 100% tested.
3) Typical values are at Vcc = 3.3V and T_A = 25 °C

AC SWITCHING CHARACTERISTICS

Over Recommended Operating Conditions

PARAMETER	TEST COND[1].	DESCRIPTION	COM -4		COM -5		UNITS
			MIN.	MAX.	MIN.	MAX.	
t_{pd}[2]	A	Input or I/O to Combinational Output	1	4	1	5	ns
t_{co}[2]	A	Clock to Output Delay	1	3	1	3.5	ns
t_{cf}[3]	—	Clock to Feedback Delay	—	2.5	—	3	ns
t_{su}	—	Setup Time, Input or Feedback before Clock↑	3	—	3.5	—	ns
t_h	—	Hold Time, Input or Feedback after Clock↑	0	—	0	—	ns
f_{max}[4]	A	Maximum Clock Frequency with External Feedback, 1/(tsu + tco)	167	—	143	—	MHz
	A	Maximum Clock Frequency with Internal Feedback, 1/(tsu + tcf)	182	—	154	—	MHz
	A	Maximum Clock Frequency with No Feedback	250	—	200	—	MHz
t_{wh}[4]	—	Clock Pulse Duration, High	2	—	2.5	—	ns
t_{wl}[4]	—	Clock Pulse Duration, Low	2	—	2.5	—	ns
t_{en}	B	Input or I/O to Output Enabled	1	5	1	6	ns
t_{dis}	C	Input or I/O to Output Disabled	1	5	1	6	ns
t_{ar}	A	Input or I/O to Asynchronous Reset of Register	1	4.5	1	5.5	ns
t_{arw}	—	Asynchronous Reset Pulse Duration	4.5	—	5.5	—	ns
t_{arr}	—	Asynchronous Reset to Clock↑ Recovery Time	3.5	—	4	—	ns
t_{spr}	—	Synchronous Preset to Clock↑ Recovery Time	3.5	—	4	—	ns

1) Refer to **Switching Test Conditions** section.
2) Minimum values for t_{pd} and t_{co} are not 100% tested but established by characterization.
3) Calculated from f_{max} with internal feedback. Refer to **fmax Descriptions** section.
4) Refer to **fmax Descriptions** section. Characterized but not 100% tested.

CAPACITANCE (T_A = 25°C, f = 1.0 MHz)

SYMBOL	PARAMETER	TYPICAL	UNITS	TEST CONDITIONS
C_I	Input Capacitance	5	pF	V_{CC} = 3.3V, V_I = 0V
$C_{I/O}$	I/O Capacitance	5	pF	V_{CC} = 3.3V, $V_{I/O}$ = 0V

ABSOLUTE MAXIMUM RATINGS[1]

Supply voltage V_{CC} .... -0.5 to +5.6V

Input voltage applied .... -0.5 to +5.6V

Off-state output voltage applied................. -0.5 to +5.6V

Storage Temperature...................................-65 to 150°C

Ambient Temperature with

  Power Applied ....-55 to 125°C

1. Stresses above those listed under the "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress only ratings and functional operation of the device at these or at any other conditions above those indicated in the operational sections of this specification is not implied (while programming, follow the programming specifications).

RECOMMENDED OPERATING COND.

Commercial Devices:

Ambient Temperature (T_A) .... 0 to +75°C
Supply voltage (V_{CC})
  with Respect to Ground .... +3.0 to +3.6V

DC ELECTRICAL CHARACTERISTICS

Over Recommended Operating Conditions (Unless Otherwise Specified)

SYMBOL	PARAMETER	CONDITION	MIN.	TYP.[2]	MAX.	UNITS
V_{IL}	Input Low Voltage		Vss – 0.5	—	0.8	V
V_{IH}	Input High Voltage		2.0	—	5.25	V
I_{IL}	Input or I/O Low Leakage Current	$0V \leq V_{IN} \leq V_{IL}$ (MAX.)	—	—	-10	µA
I_{IH}	Input or I/O High Leakage Current	$(V_{CC} - 0.2)V \leq V_{IN} \leq V_{CC}$	—	—	10	µA
		$V_{CC} \leq V_{IN} \leq 5.25V$	—	—	30	mA
V_{OL}	Output Low Voltage	I_{OL} = MAX. Vin = V_{IL} or V_{IH}	—	—	0.4	V
		I_{OL} = 0.5 mA Vin = V_{IL} or V_{IH}	—	—	0.2	V
V_{OH}	Output High Voltage	I_{OH} = MAX. Vin = V_{IL} or V_{IH}	2.4	—	—	V
		I_{OH} = -0.5 mA Vin = V_{IL} or V_{IH}	Vcc-0.45	—	—	V
		I_{OH} = -100 µA Vin = V_{IL} or V_{IH}	Vcc-0.2	—	—	V
I_{OL}	Low Level Output Current		—	—	8	mA
I_{OH}	High Level Output Current		—	—	-4	mA
I_{OS}[1]	Output Short Circuit Current	V_{CC} = 3.3V V_{OUT} = 0.5V T_A = 25°C	-15	—	-60	mA

COMMERCIAL

I_{CC}	Operating Power Supply Current	V_{IL} = 0.0V V_{IH} = 3.0V f_{toggle} = 1MHz Outputs Open	—	45	75	mA

1) One output at a time for a maximum duration of one second. Vout = 0.5V was selected to avoid test problems by tester ground degradation. Characterized but not 100% tested.
2) Typical values are at Vcc = 3.3V and T_A = 25 °C

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AC SWITCHING CHARACTERISTICS

Over Recommended Operating Conditions

PARAM	TEST COND.[1]	DESCRIPTION	COM -7 MIN.	-7 MAX.	COM -10 MIN.	-10 MAX.	COM -15 MIN.	-15 MAX.	UNITS
t_{pd}[2]	A	Input or I/O to Combinatorial Output	2	7.5	2	10	2	15	ns
t_{co}[2]	A	Clock to Output Delay	1	5	1	6.5	1	10	ns
t_{cf}[3]	—	Clock to Feedback Delay	—	3	—	5	—	5	ns
t_{su}	—	Setup Time, Input or Fdbk before Clk↑	6.5	—	7.5	—	10	—	ns
t_h	—	Hold Time, Input or Fdbk after Clk↑	0	—	0	—	0	—	ns
f_{max}[4]	A	Maximum Clock Frequency with External Feedback, 1/(tsu + tco)	87	—	71	—	50	—	MHz
	A	Maximum Clock Frequency with Internal Feedback, 1/(tsu + tcf)	105	—	80	—	66	—	MHz
	A	Maximum Clock Frequency with No Feedback	125	—	111	—	83	—	MHz
t_{wh}	—	Clock Pulse Duration, High	3.5	—	4	—	6	—	ns
t_{wl}	—	Clock Pulse Duration, Low	3.5	—	4	—	6	—	ns
t_{en}	B	Input or I/O to Output Enabled	2	10	2	12	2	15	ns
t_{dis}	C	Input or I/O to Output Disabled	2	10	2	12	2	15	ns
t_{ar}	A	Input or I/O to Asynch. Reset of Reg.	2	11	2	13	2	20	ns
t_{arw}	—	Asynch. Reset Pulse Duration	7	—	8	—	12	—	ns
t_{arr}	—	Asynch. Reset to Clk↑ Recovery Time	7	—	8	—	10	—	ns
t_{spr}	—	Synch. Preset to Clk↑ Recovery Time	8	—	10	—	10	—	ns

1) Refer to **Switching Test Conditions** section.
2) Minimum values for **t**pd and **t**co are not 100% tested but established by characterization.
3) Calculated from **f**max with internal feedback. Refer to **fmax Description** section.
4) Refer to **fmax Description** section.

CAPACITANCE (T_A = 25°C, f = 1.0 MHz)

SYMBOL	PARAMETER	TYPICAL	UNITS	TEST CONDITIONS
C_I	Input Capacitance	8	pF	V_{CC} = 3.3V, V_I = 0V
$C_{I/O}$	I/O Capacitance	8	pF	V_{CC} = 3.3V, $V_{I/O}$ = 0V

SWITCHING WAVEFORMS

INPUT or
I/O FEEDBACK

VALID INPUT

t_{pd}

COMBINATORIAL
OUTPUT
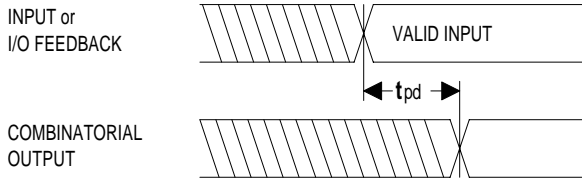
Combinatorial Output

INPUT or
I/O FEEDBACK

VALID INPUT

t_{su} t_h

CLK

t_{co}

REGISTERED
OUTPUT

$1/f_{max}$
(external fdbk)

Registered Output

INPUT or
I/O FEEDBACK

t_{dis} t_{en}
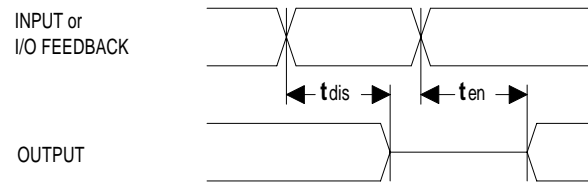
OUTPUT

Input or I/O to Output Enable/Disable
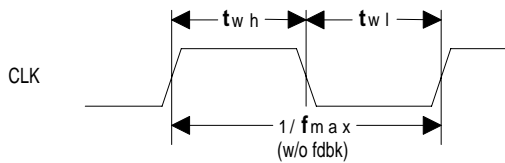
CLK

$1/f_{max}$ (internal fdbk)

t_{cf} t_{su}

REGISTERED
FEEDBACK

f_{max} with Feedback

t_{wh} t_{wl}

CLK

$1/f_{max}$
(w/o fdbk)

Clock Width

INPUT or
I/O FEEDBACK
DRIVING SP

t_{su} t_h t_{spr}

CLK

t_{co}

REGISTERED
OUTPUT

Synchronous Preset

INPUT or
I/O FEEDBACK
DRIVING AR

t_{arw}

CLK

t_{arr}

REGISTERED
OUTPUT

t_{ar}
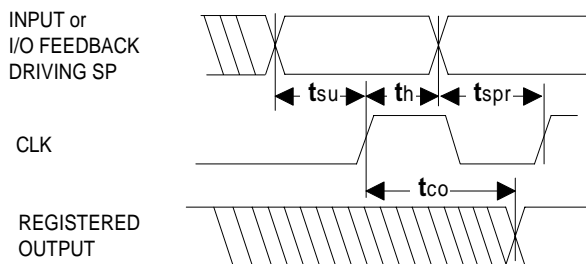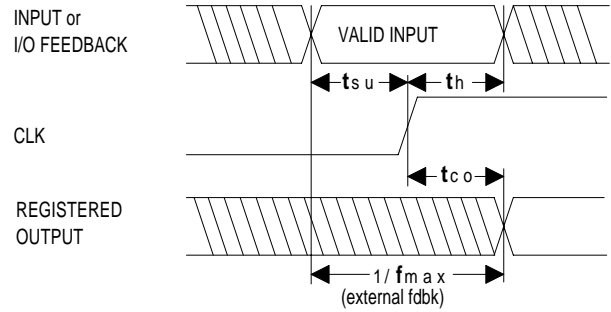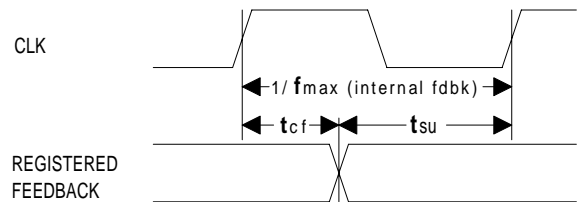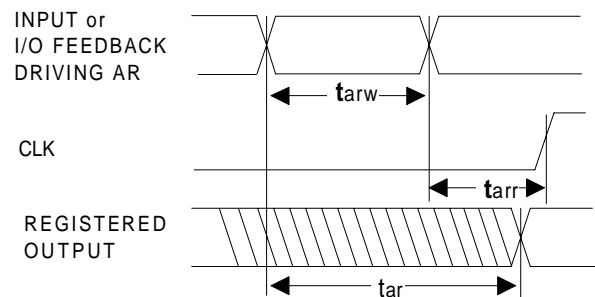
Asynchronous Reset

fmax DESCRIPTIONS
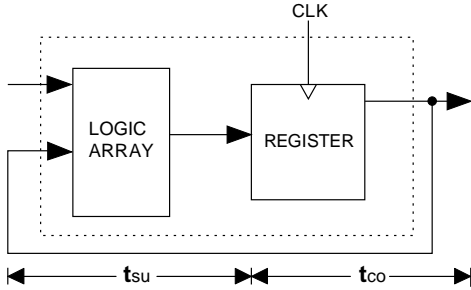
fmax with External Feedback 1/($t_{su}+t_{co}$)

Note: fmax with external feedback is calculated from measured t_{su} and t_{co}.
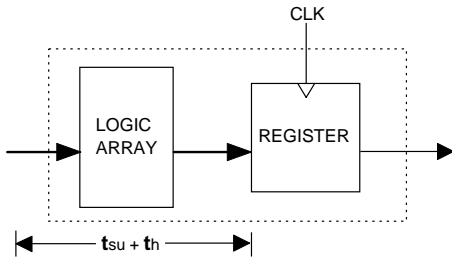
fmax with No Feedback

Note: fmax with no feedback may be less than 1/($t_{wh} + t_{wl}$). This is to allow for a clock duty cycle of other than 50%.
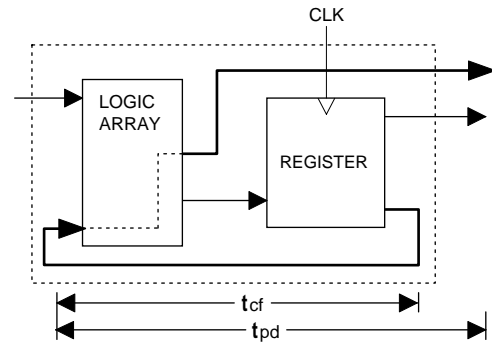
fmax with Internal Feedback 1/($t_{su}+t_{cf}$)

Note: t_{cf} is a calculated value, derived by subtracting t_{su} from the period of fmax w/internal feedback ($t_{cf} = 1/f_{max} - t_{su}$). The value of t_{cf} is used primarily when calculating the delay from clocking a register to a combinatorial output (through registered feedback), as shown above. For example, the timing from clock to a combinatorial output is equal to $t_{cf} + t_{pd}$.

GAL22LV10D: SWITCHING TEST CONDITIONS

Input Pulse Levels	GND to 3.0V
Input Rise and Fall Times	1.5ns 10% – 90%
Input Timing Reference Levels	1.5V
Output Timing Reference Levels	1.5V
Output Load	See Figure

Output Load Conditions (see figure)

Test Condition		R_1	C_L
A		50Ω	35pF
B	High Z to Active High at 1.9V	50Ω	35pF
	High Z to Active Low at 1.0V	50Ω	35pF
C	Active High to High Z at 1.9V	50Ω	35pF
	Active Low to High Z at 1.0V	50Ω	35pF

+1.45V

TEST POINT

R_1

FROM OUTPUT (O/Q)
UNDER TEST

$Z_0 = 50Ω, C_L = 35pF*$

*C_L includes test fixture and probe capacitance.
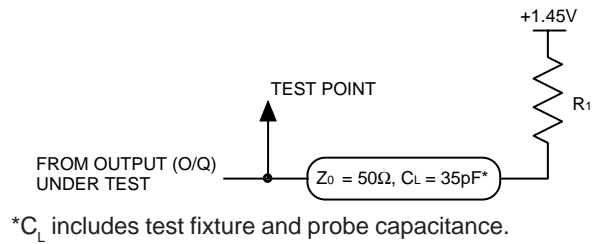
GAL22LV10C: SWITCHING TEST CONDITIONS

Input Pulse Levels	GND to 3.0V
Input Rise and Fall Times	2.0ns 10% – 90%
Input Timing Reference Levels	1.5V
Output Timing Reference Levels	1.5V
Output Load	See Figure

3-state levels are measured 0.5V from steady-state active level.

Output Load Conditions (see figure)

Test Condition		R_1	R_2	C_L
A		316Ω	348Ω	35pF
B	Active High	316Ω	348Ω	35pF
	Active Low	316Ω	348Ω	35pF
C	Active High	316Ω	348Ω	5pF
	Active Low	316Ω	348Ω	5pF

+3.3V

R_1

FROM OUTPUT (O/Q)
UNDER TEST

TEST POINT

R_2

C_L*

*C_L INCLUDES TEST FIXTURE AND PROBE CAPACITANCE
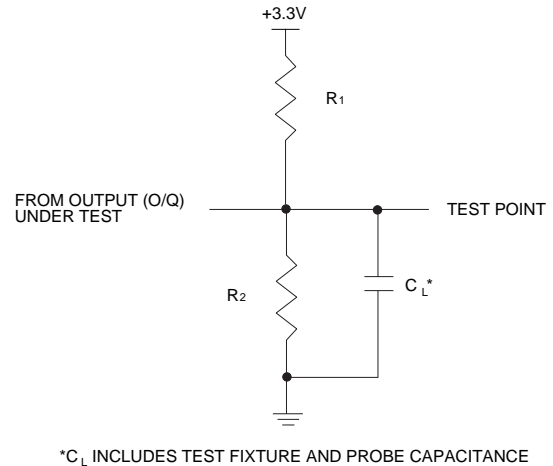
ELECTRONIC SIGNATURE

An electronic signature (ES) is provided in every GAL22LV10 device. It contains 64 bits of reprogrammable memory that can contain user-defined data. Some uses include user ID codes, revision numbers, or inventory control. The signature data is always available to the user independent of the state of the security cell.

The electronic signature is an additional feature not present in other manufacturers' 22V10 devices. To use the extra feature of the user-programmable electronic signature it is necessary to choose a Lattice Semiconductor 22V10 device type when compiling a set of logic equations. In addition, many device programmers have two separate selections for the device, typically a GAL22LV10 and a GAL22V10-UES (UES = User Electronic Signature) or GAL22V10-ES. This allows users to maintain compatibility with existing 22V10 designs, while still having the option to use the GAL device's extra feature.

The JEDEC map for the GAL22LV10 contains the 64 extra fuses for the electronic signature, for a total of 5892 fuses. However, the GAL22LV10 device can still be programmed with a standard 22V10 JEDEC map (5828 fuses) with any qualified device programmer.

SECURITY CELL

A security cell is provided in every GAL22LV10 device to prevent unauthorized copying of the array patterns. Once programmed, this cell prevents further read access to the functional bits in the device. This cell can only be erased by re-programming the device, so the original configuration can never be examined once this cell is programmed. The Electronic Signature is always available to the user, regardless of the state of this control cell.

LATCH-UP PROTECTION

GAL22LV10 devices are designed with an on-board charge pump to negatively bias the substrate. The negative bias is of sufficient magnitude to prevent input undershoots from causing the circuitry to latch.

DEVICE PROGRAMMING

GAL devices are programmed using a Lattice Semiconductor-approved Logic Programmer, available from a number of manufacturers (see the the GAL Development Tools section). Complete programming of the device takes only a few seconds. Erasing of the device is transparent to the user, and is done automatically as part of the programming cycle.

OUTPUT REGISTER PRELOAD

When testing state machine designs, all possible states and state transitions must be verified in the design, not just those required in the normal machine operations. This is because certain events may occur during system operation that throw the logic into an illegal state (power-up, line voltage glitches, brown-outs, etc.). To test a design for proper treatment of these conditions, a way must be provided to break the feedback paths, and force any desired (i.e., illegal) state into the registers. Then the machine can be sequenced and the outputs tested for correct next state conditions.

The GAL22LV10 device includes circuitry that allows each registered output to be synchronously set either high or low. Thus, any present state condition can be forced for test sequencing. If necessary, approved GAL programmers capable of executing test vectors perform output register preload automatically.

INPUT BUFFERS

GAL22LV10 devices are designed with TTL level compatible input buffers. These buffers have a characteristically high impedance, and present a much lighter load to the driving logic than bipolar TTL devices.

The input and I/O pins on the GAL22LV10D also have built-in active pull-ups. As a result, floating inputs will float to a TTL high (logic 1). However, Lattice Semiconductor recommends that all unused inputs and tri-stated I/O pins be connected to an adjacent active input, Vcc, or ground. Doing so will tend to improve noise immunity and reduce Icc for the device. (See equivalent input and I/O schematics on the following page.)

Typical Input Pull-up Characteristic
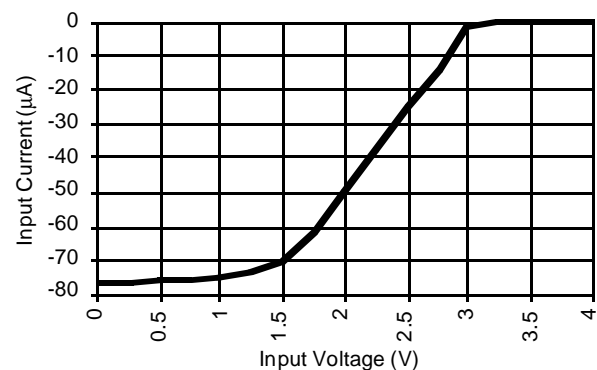
POWER-UP RESET
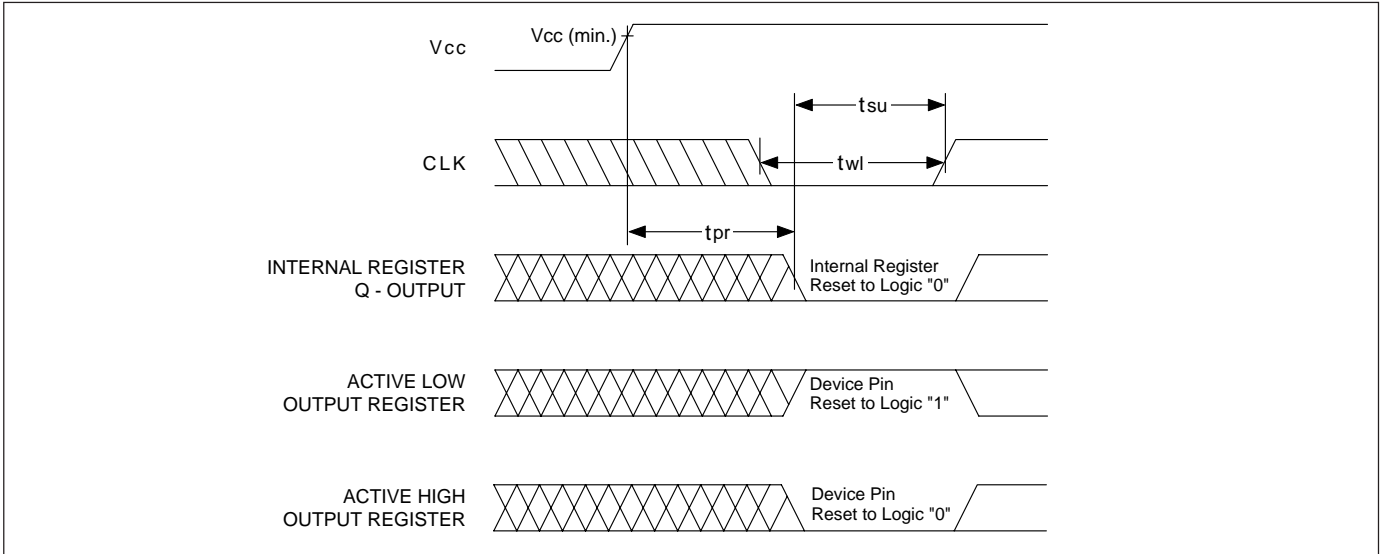
Circuitry within the GAL22V10 provides a reset signal to all registers during power-up. All internal registers will have their Q outputs set low after a specified time (tpr, 1μs MAX). As a result, the state on the registered output pins (if they are enabled) will be either high or low on power-up, depending on the programmed polarity of the output pins. This feature can greatly simplify state machine design by providing a known state on power-up. The timing diagram for power-up is shown below. Because of the asynchronous nature of system power-up, some conditions must be met to provide a valid power-up reset of the GAL22V10. First, the Vcc rise must be monotonic. Second, the clock input must be at static TTL level as shown in the diagram during power up. The registers will reset within a maximum of tpr time. As in normal system operation, avoid clocking the device until all input and feedback path setup times have been met. The clock must also meet the minimum pulse width requirements.

INPUT/OUTPUT EQUIVALENT SCHEMATICS

Typ. Vref = Vcc

Typical Input

Typ. Vref = Vcc
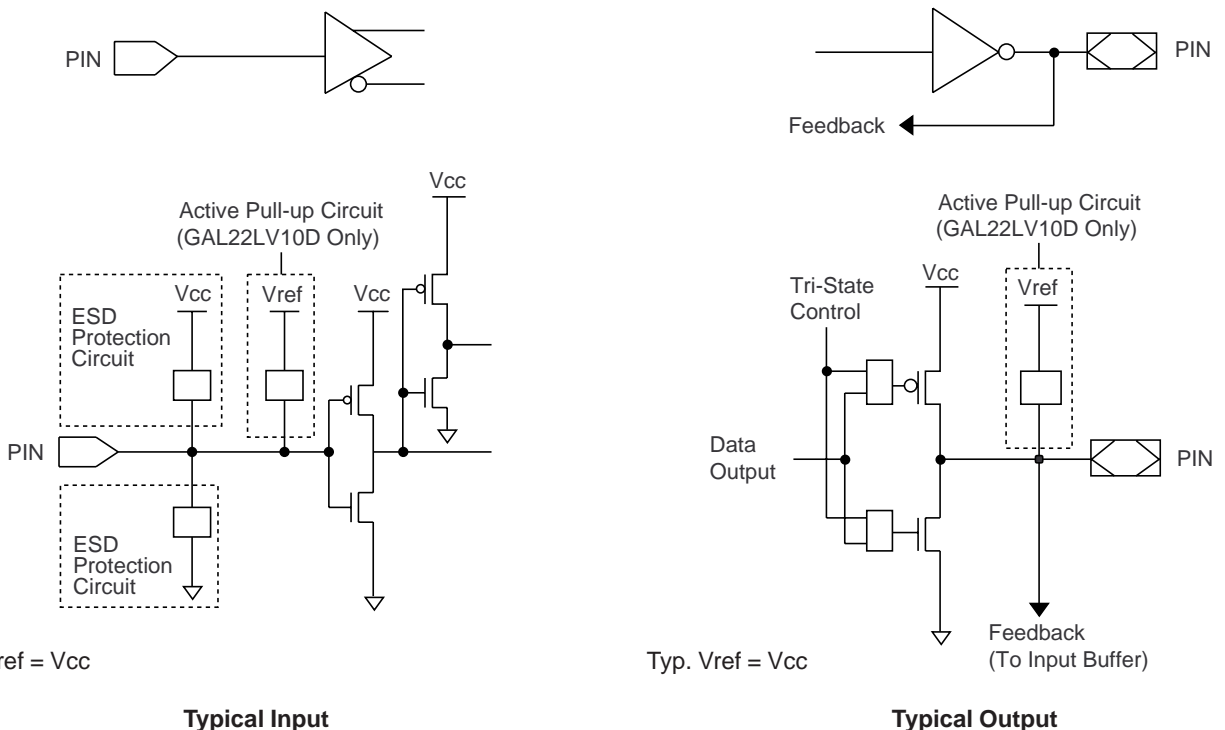
Typical Output

GAL22LV10D: TYPICAL AC AND DC CHARACTERISTIC DIAGRAMS
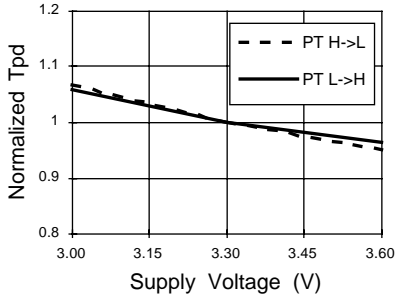
Normalized Tpd vs Vcc
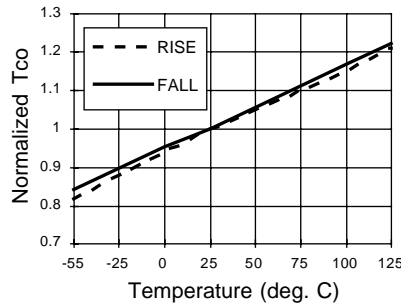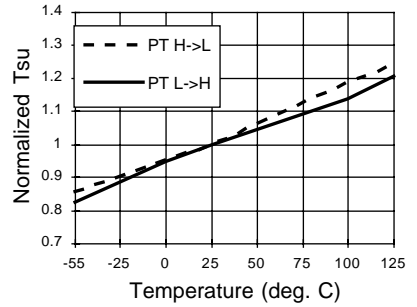
Normalized Tco vs Vcc
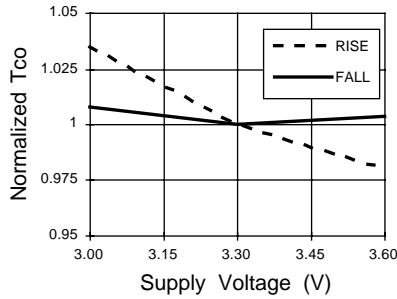
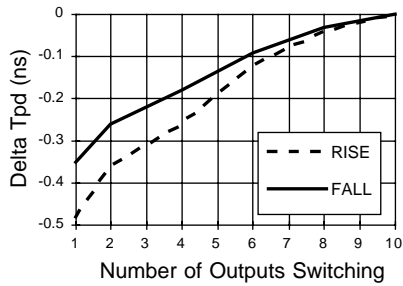**Normalized Tsu vs Vcc**
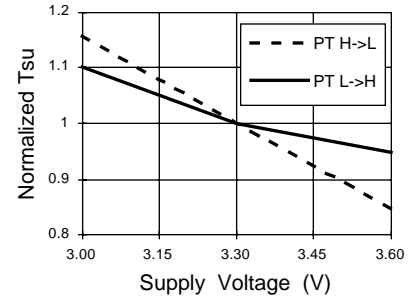
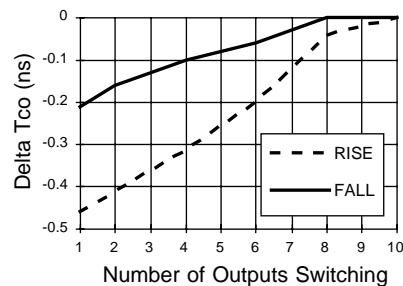**Normalized Tpd vs Temp**
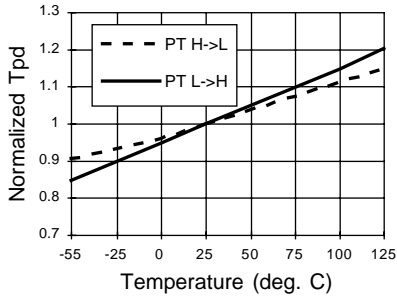
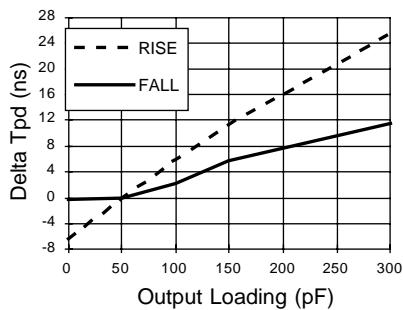**Normalized Tco vs Temp**
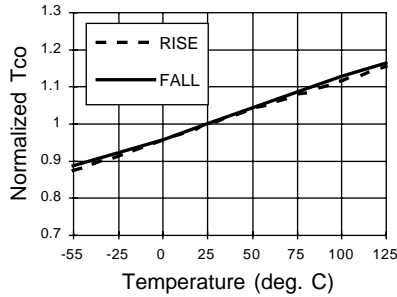
Normalized Tsu vs Temp
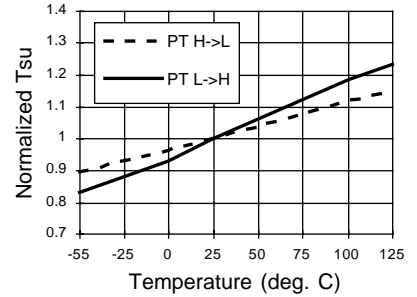
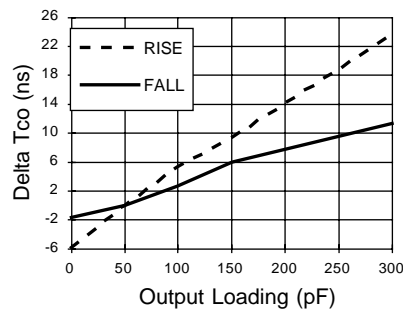**Delta Tpd vs # of Outputs Switching**
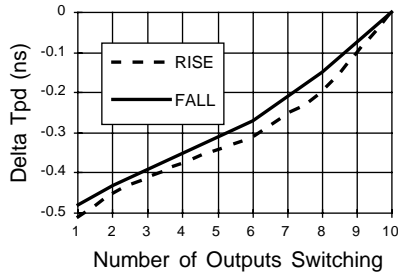
Delta Tco vs # of Outputs Switching
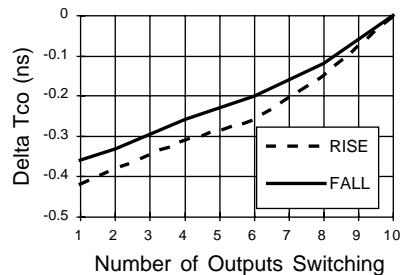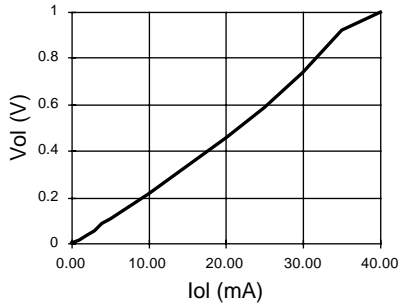
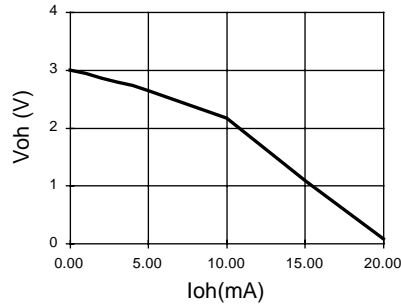**Delta Tpd vs Output Loading**
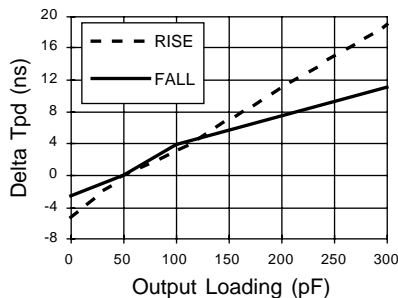
Delta Tco vs Output Loading
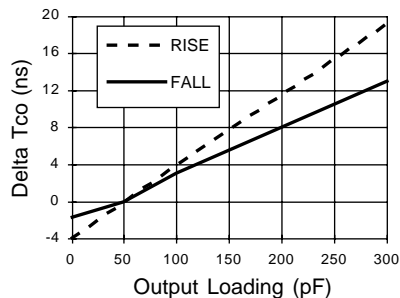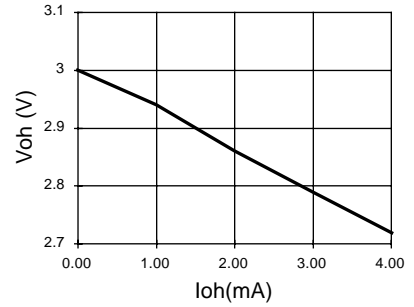
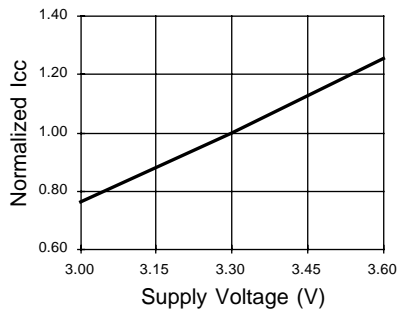## GAL22LV10D: TYPICAL AC AND DC CHARACTERISTIC DIAGRAMS
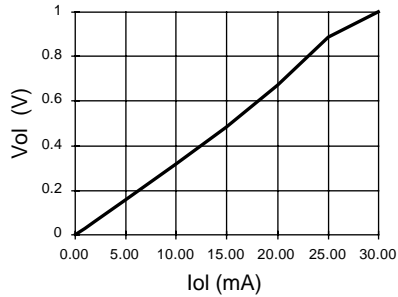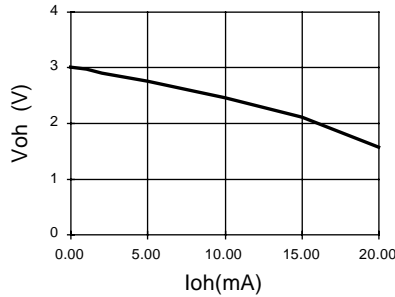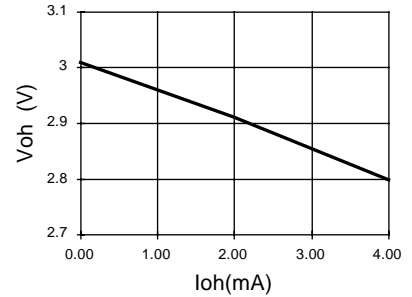
Vol vs Iol

Voh vs Ioh

Voh vs Ioh

Normalized Icc vs Vcc
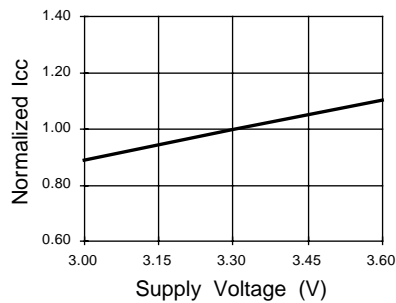
Normalized Icc vs Temp
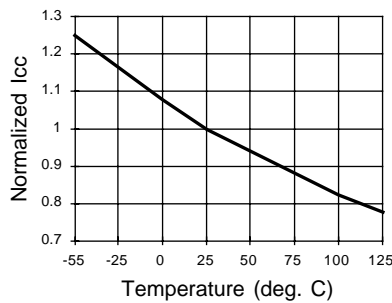
Normalized Icc vs Freq.
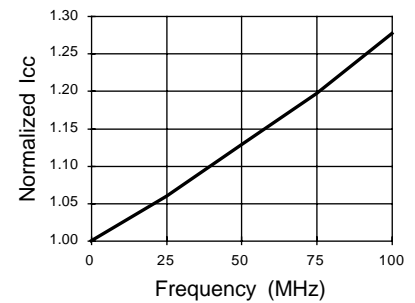
Delta Icc vs Vin (1 input)
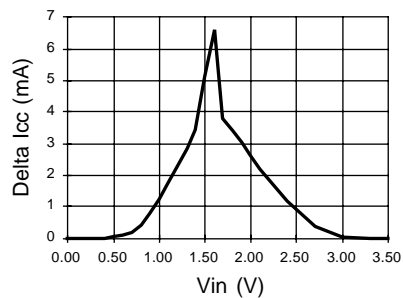
Input Clamp (Vik)

GAL22LV10C: TYPICAL AC AND DC CHARACTERISTIC DIAGRAMS
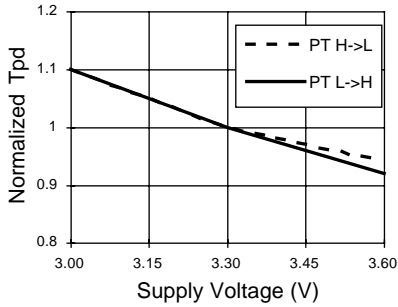
Normalized Tpd vs Vcc

Normalized Tco vs Vcc
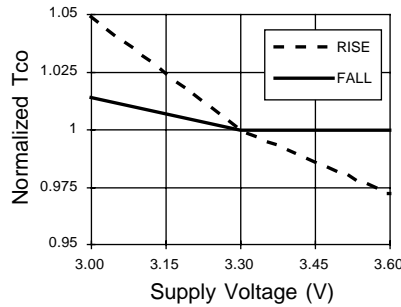
Normalized Tsu vs Vcc
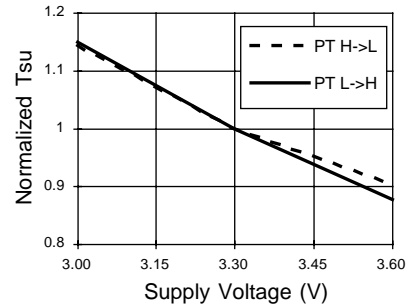
Normalized Tpd vs Temp
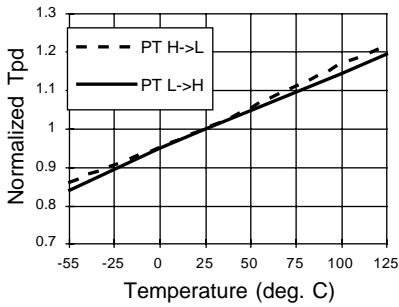
Normalized Tco vs Temp

Normalized Tsu vs Temp

Delta Tpd vs # of Outputs Switching

Delta Tco vs # of Outputs Switching

Delta Tpd vs Output Loading

Delta Tco vs Output Loading

GAL22LV10C: TYPICAL AC AND DC CHARACTERISTIC DIAGRAMS
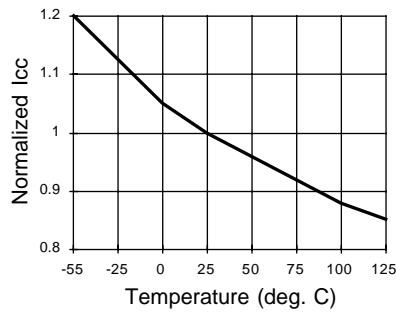
Vol vs Iol

Voh vs Ioh

Voh vs Ioh

Normalized Icc vs Vcc

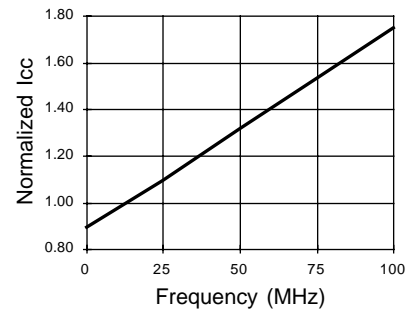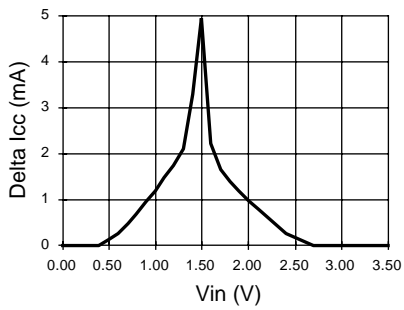**Normalized Icc vs Temp**

Normalized Icc vs Freq.

Delta Icc vs Vin (1 input)

Input Clamp (Vik)