SLAS073C - DECEMBER 1995 - REVISED AUGUST 1996

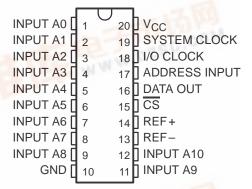
- 10-Bit Resolution A/D Converter
- Microprocessor Peripheral or Standalone Operation
- On-Chip 12-Channel Analog Multiplexer
- Built-In Self-Test Mode
- Software-Controllable Sample-and-Hold Function
- Total Unadjusted Error . . . ±1 LSB Max
- Pinout and Control Signals Compatible
 With TLC540 and TLC549 Families of 8-Bit
 A/D Converters
- CMOS Technology

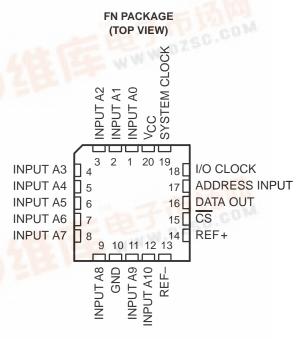
PARAMETER	VALUE
Channel Acquisition Sample Time	5.5 μs
Conversion Time (Max)	21 μs 32 × 10 ³
Samples Per Second (Max)	32×10^{3}
Power Dissipation (Max)	6 mW

description

The TLC1541 is a CMOS A/D converter built around a 10-bit switched-capacitor successiveapproximation A/D converter. The device is designed for serial interface to a microprocessor or peripheral using a 3-state output with up to four control inputs (including independent SYSTEM CLOCK, I/O CLOCK, chip select [CS], and ADDRESS INPUT). A 2.1-MHz system clock for the TLC1541, with a design that includes simultaneous read/write operation, allows highspeed data transfers and sample rates up to 32 258 samples per second. In addition to the high-speed converter and versatile control logic, there is an on-chip, 12-channel analog multiplexer that can be used to sample any one of 11 inputs or an internal self-test voltage and a sample-andhold function that operates automatically.

DW OR N PACKAGE (TOP VIEW)





AVAILABLE OPTIONS

	PACKAGE			
TA	SMALL OUTLINE (DW)	PLASTIC CHIP CARRIER (FN)	PLASTIC DIP (N)	
0°C to 70°C	TLC1541CDW	TLC1541CFN	TLC1541CN	
-40°C to 85°C	TLC1541IDW	TLC1541IFN	TLC1541IN	

Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.



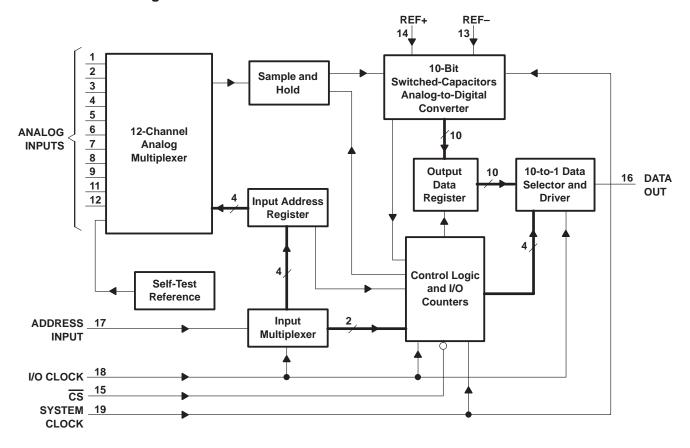
SLAS073C - DECEMBER 1995 - REVISED AUGUST 1996

description (continued)

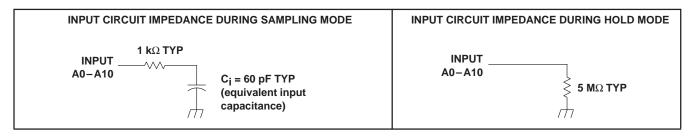
The converters incorporated in the TLC1541 feature differential high-impedance reference inputs that facilitate ratiometric conversion, scaling, and analog circuitry isolation from logic and supply noises. A totally switched-capacitor design allows low-error conversion in 21 µs over the full operating temperature range.

The TLC1541 is available in DW, FN, and N packages. The C-suffix versions are characterized for operation from 0°C to 70°C. The I-suffix versions are characterized for operation from –40°C to 85°C.

functional block diagram



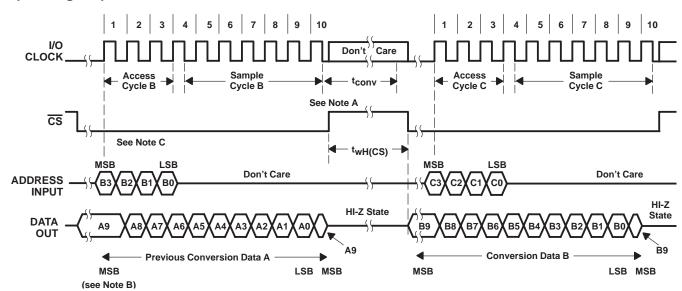
typical equivalent inputs





SLAS073C - DECEMBER 1995 - REVISED AUGUST 1996

operating sequence



- NOTES: A. The conversion cycle, which requires 44 system clock periods, initiates on the tenth falling edge of the I/O clock after CS goes low for the channel whose address exists in memory at that time. When CS is kept low during conversion, the I/O clock must remain low for at least 44 system clock cycles to allow the conversion to complete.
 - B. The most significant bit (MSB) is automatically placed on the DATA OUT bus after \overline{CS} is brought low. The remaining nine bits (A8–A0) clock out on the first nine I/O clock falling edges.
 - C. To minimize errors caused by noise at the CS input, the internal circuitry waits for three system clock cycles (or less) after a chip-select falling edge is detected before responding to control input signals. Therefore, no attempt should be made to clock-in address data until the minimum chip-select setup time elapses.

absolute maximum ratings over operating free-air temperature range (unless otherwise noted)†

Supply voltage, V _{CC} (see Note 1)	6.5 V
Input voltage range, V _I (any input)	$-0.3 \text{ V to V}_{CC} + 0.3 \text{ V}$
Output voltage range, VO	$-0.3 \text{ V to V}_{CC} + 0.3 \text{ V}$
Peak input current (any input)	±10 mA
Peak total input current (all inputs)	±30 mA
Operating free-air temperature range, T _A : C suffix	0°C to 70°C
I suffix	40°C to 85°C
Storage temperature range, T _{stq}	65°C to 150°C
Case temperature for 10 seconds, T _C : FN package	260°C
Lead temperature 1,6 mm (1/16 inch) from the case for 10 seconds: D	DW or N package 260°C

[†] Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

NOTE 1: All voltage values are with respect to digital ground with REF - and GND wired together (unless otherwise noted).



SLAS073C - DECEMBER 1995 - REVISED AUGUST 1996

recommended operating conditions

			MIN	NOM	MAX	UNIT	
Supply voltage, V _{CC}			4.75	5	5.5	V	
Positive reference voltage, V _{ref+} (see No	ote 2)		2.5	VCC	V _{CC} +0.1	V	
Negative reference voltage, V _{ref} (see N	ve reference voltage, V _{ref} (see Note 2) -0.1 0 2.5		2.5	V			
Differential reference voltage, V _{ref+} – V _{ref} (see Note 2)				VCC	V _{CC} +0.2	V	
Analog input voltage (see Note 2)			0		Vcc	V	
High-level control input voltage, VIH			2			V	
Low-level control input voltage, V _{IL}					0.8	V	
Input/output clock frequency, fclock(I/O)			0		1.1	MHz	
System clock frequency, fclock(SYS)			fclock(I/O)		2.1	MHz	
Setup time, address bits before I/O CLOO	CK↑, t _{su(A)}		400			ns	
Hold time, address bits after I/O CLOCK1	`, th(A)		0			ns	
Setup time, \overline{CS} low before clocking in first address bit, $t_{SU}(CS)$ (see Note 3 and Operating Sequence)		3			System clock cycles		
Pulse duration, CS high during conversion, t _{WH(CS)} (see Operating Sequence)		44			System clock cycles		
Pulse duration, SYSTEM CLOCK high, t _V	vH(SYS)		210			ns	
Pulse duration, SYSTEM CLOCK low, t_W	L(SYS)		190			ns	
Pulse duration, I/O CLOCK high, twH(I/O)		404			ns	
Pulse duration, I/O CLOCK low, t _{WL(I/O)}			404			ns	
	System	f _{clock(SYS)} ≤ 1048 kHz			30	ns	
Clock transition time (see Note 4)	System	f _{clock} (SYS) > 1048 kHz			20	113	
	1/0	$f_{Clock(I/O)} \le 525 \text{ kHz}$			100	ns	
	1//0	$f_{clock(I/O)} > 525 \text{ kHz}$			40	113	
Operating free-air temperature, T _A	C suffix	C suffix			70	°C	
Operating nee-all temperature, 14	I suffix	I suffix			85		

- NOTES: 2. Analog input voltages greater than that applied to REF+ convert as all ones (1111111111), while input voltages less than that applied to REF- convert as all zeros (0000000000). For proper operation, REF+ voltage must be at least 1 V higher than REF- voltage. Also, the total unadjusted error may increase as this differential reference voltage falls below 4.75 V.
 - 3. To minimize errors caused by noise at the chip select input, the internal circuitry waits for three system clock cycles (or less) after a chip select falling edge is detected before responding to control input signals. Therefore, no attempt should be made to clock in an address until the minimum chip select setup time elapses.
 - 4. The amount of time required for the clock input signal to fall from V_{IL} mix or to rise from V_{IL} max to V_{IH} min. In the vicinity of normal room temperature, the devices function with input clock transition time as slow as 2 μs for remote data acquisition applications where the sensor and the A/D converter are placed several feet away from the controlling microprocessor.



TLC1541 10-BIT ANALOG-TO-DIGITAL CONVERTER WITH SERIAL CONTROL AND 11 INPUTS SLAS073C - DECEMBER 1995 - REVISED AUGUST 1996

electrical characteristics over recommended operating temperature range, $V_{CC} = V_{ref+} = 4.75 \text{ V}$ to 5.5 V, $f_{clock(I/O)} = 1.1 \text{ MHz}$, $f_{clock(SYS)} = 2.1 \text{ MHz}$ (unless otherwise noted)

	PARAMETER		TEST CONDITIONS	MIN	TYP [†]	MAX	UNIT
Vон	High-level output voltage (termina	l 16)	V _{CC} = 4.75 V, I _{OH} = 360 μ/	2.4			V
VOL	Low-level output voltage		$V_{CC} = 4.75 \text{ V}, I_{OL} = 3.2 \text{ m/s}$			0.4	V
lo=	High-impedance-state output current		$V_O = V_{CC}$, \overline{CS} at V_{CC}			10	μΑ
loz			$V_O = 0$, \overline{CS} at V_{CC}			-10	
lн	High-level input current		VI = VCC		0.005	2.5	μΑ
I _Ι L	Low-level input current		V _I = 0		-0.005	-2.5	μΑ
Icc	Operating supply current		CS at 0 V		1.2	2.5	mA
	Calastad share all lasters as surrent		Selected channel at V _{CC} , Unselected channel at 0 V		0.4	1	A
	Selected channel leakage current		Selected channel at 0 V, Unselected channel at V _{CC}		-0.4		μΑ
ICC + Iref	Supply and reference current		$V_{ref+} = V_{CC}$, \overline{CS} at 0 V		1.3	3	mA
Ci	Input capacitance	Analog inputs			7	55	n.E
		Control inputs			5	15	pF

[†] All typical values are at $V_{CC} = 5 \text{ V}$ and $T_A = 25^{\circ}\text{C}$.

SLAS073C - DECEMBER 1995 - REVISED AUGUST 1996

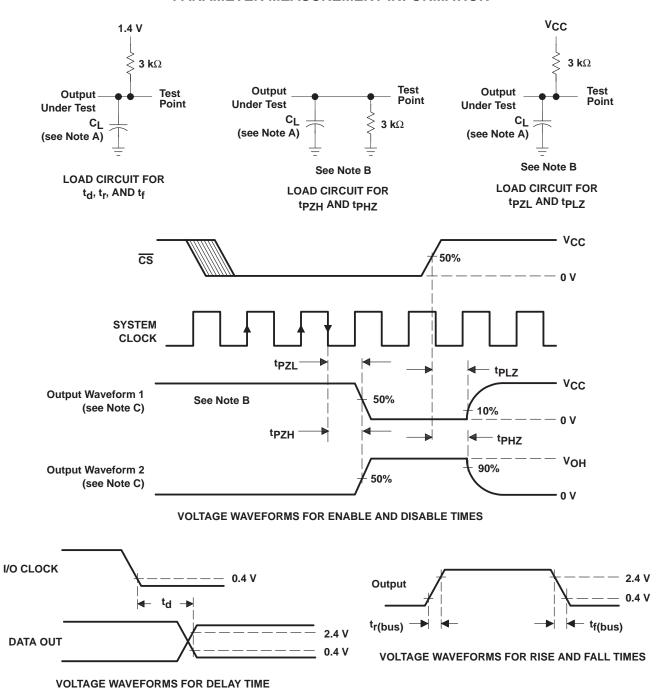
operating characteristics over recommended operating temperature range, $V_{CC} = V_{ref+} = 4.75 \text{ V to } 5.5 \text{ V}, f_{clock(I/O)} = 1.1 \text{ MHz}, f_{clock(SYS)} = 2.1 \text{ MHz}$

	PARAMETER	TEST CONDITIONS	MIN	MAX	UNIT
EL	Linearity error	See Note 5		±1	LSB
EZS	Zero-scale error	See Notes 2 and 6		±1	LSB
E _{FS}	Full-scale error	See Notes 2 and 6		±1	LSB
ET	Total unadjusted error	See Note 7		±1	LSB
	Self-test output code	Input A11 address = 1011 (see Note 8)	0111110100 (500)	1000001100 (524)	
t _{conv}	Conversion time			21	μs
	Total access and conversion time			31	μs
	Channel acquisition time (sample cycle)	See Operating Sequence		6	I/O clock cycles
t _V	Time output data remains valid after I/O CLOCK↓		10		ns
t _d	Delay time, I/O CLOCK↓ to DATA OUT valid			400	ns
t _{en}	Output enable time]		150	ns
tdis	Output disable time	See Figure 1		150	ns
t _r (bus)	Data bus rise time			300	ns
t _f (bus)	Data bus fall time			300	ns

- NOTES: 2. Analog input voltages greater than that applied to REF+ convert as all ones (1111111111), while input voltages less than that applied to REF - convert as all zeros (0000000000). For proper operation, REF + voltage must be at least 1 V higher than REF - voltage. Also, the total unadjusted error may increase as this differential reference voltage falls below 4.75 V.
 - 5. Linearity error is the maximum deviation from the best straight line through the A/D transfer characteristics.
 - 6. Zero-scale error is the difference between 0000000000 and the converted output for zero input voltage; full-scale error is the difference between 1111111111 and the converted output for full-scale input voltage.
 - 7. Total unadjusted error includes linearity, zero-scale, and full-scale errors.
 - 8. Both the input address and the output codes are expressed in positive logic. The A11 analog input signal is internally generated and used for test purposes.

SLAS073C - DECEMBER 1995 - REVISED AUGUST 1996

PARAMETER MEASUREMENT INFORMATION



NOTES: A. C_L = 50 pF

B. $t_{en} = t_{PZH}$ or t_{PZL} and $t_{dis} = t_{PHZ}$ or t_{PLZ} .

C. Waveform 1 is for an output with internal conditions such that the output is low except when disabled by the output control. Waveform 2 is for an output with internal conditions such that the output is high except when disabled by the output control.

Figure 1. Load Circuits and Voltage Waveforms



APPLICATION INFORMATION

simplified analog input analysis

SLAS073C - DECEMBER 1995 - REVISED AUGUST 1996

Using the equivalent circuit in Figure 2, the time required to charge the analog input capacitance from 0 V to V_S within 1/2 LSB can be derived as follows:

The capacitance charging voltage is given by

$$V_{C} = V_{S} \left(1 - e^{-t_{C}/R_{t}C_{i}} \right)$$
 (1)

where

$$R_t = R_s + r_i$$

The final voltage to 1/2 LSB is given by

$$V_C (1/2 LSB) = V_S - (V_S/2048)$$
 (2)

Equating equation 1 to equation 2 and solving for time (t_C) gives

$$V_{S} - (V_{S}/2048) = V_{S} \left(1 - e^{-t_{C}/R_{t}C_{i}} \right)$$
(3)

and

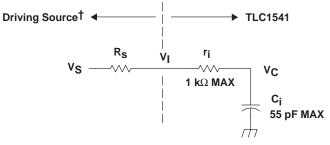
$$t_{c} (1/2 LSB) = R_{t} \times C_{i} \times ln(2048)$$

$$\tag{4}$$

Therefore, with the values given, the time for the analog input signal to settle is

$$t_{\rm C} (1/2 \text{ LSB}) = (R_{\rm S} + 1 \text{ k}\Omega) \times 55 \text{ pF} \times \ln(2048)$$
 (5)

This time must be less than the converter sample time shown in the timing diagrams.



V_I = Input Voltage at INPUT A0-A10

V_S = External Driving Source Voltage

R_S = Source Resistance

ri = Input Resistance

Ci = Input Capacitance

† Driving source requirements:

- Noise and distortion levels for the source must be at least equivalent to the resolution of the converter.
- R_S must be real at the input frequency.

Figure 2. Equivalent Input Circuit Including the Driving Source



SLAS073C - DECEMBER 1995 - REVISED AUGUST 1996

PRINCIPLES OF OPERATION

The TLC1541 is a complete data acquisition system on a single chip. The device includes such functions as sample and hold, 10-bit A/D converter, data and control registers, and control logic. For flexibility and access speed, there are four control inputs: chip select (\overline{CS}) , address input, I/O clock, and system clock. These control inputs and a TTL-compatible, 3-state output are intended for serial communications with a microprocessor or microcomputer. The TLC1541 can complete conversions in a maximum of 21 μ s, while complete input-conversion output cycles can be repeated at a maximum of 31 μ s.

The system and I/O clocks are normally used independently and do not require any special speed or phase relationships between them. This independence simplifies the hardware and software control tasks for the device. Once a clock signal within the specification range is applied to the SYSTEM CLOCK input, the control hardware and software need only be concerned with addressing the desired analog channel, reading the previous conversion result, and starting the conversion by using I/O CLOCK. SYSTEM CLOCK drives the conversion-crunching circuitry so that the control hardware and software need not be concerned with this task.

When \overline{CS} is high, DATA OUT is in a 3-state condition and ADDRESS INPUT and I/O CLOCK are disabled. This feature allows each of these terminals, with the exception of the \overline{CS} terminal, to share a control logic point with its counterpart terminals on additional A/D devices when using additional TLC1541 devices. In this way, the above feature serves to minimize the required control logic terminals when using multiple A/D devices.

The control sequence has been designed to minimize the time and effort required to initiate conversion and obtain the conversion result. A normal control sequence is:

- 1. $\overline{\text{CS}}$ is brought low. To minimize errors caused by noise at the $\overline{\text{CS}}$ input, the internal circuitry waits for two rising edges and then a falling edge of SYSTEM CLOCK after a low $\overline{\text{CS}}$ transition before recognizing the low transition. This technique protects the device against noise when the device is used in a noisy environment. The MSB of the previous conversion result automatically appears on DATA OUT.
- 2. A new positive-logic multiplexer address shifts in on the first four rising edges of I/O CLOCK. The MSB of the address shifts in first. The negative edges of these four I/O clock pulses shift out the second, third, fourth, and fifth most-significant bits of the previous conversion result. The on-chip sample-and-hold begins sampling the newly addressed analog input after the fourth falling edge. The sampling operation basically involves the charging of internal capacitors to the level of the analog input voltage.
- 3. Five clock cycles are then applied to the I/O CLOCK, and the sixth, seventh, eighth, ninth, and tenth conversion bits shift out on the negative edges of these clock cycles.
- 4. The final tenth-clock cycle is applied to the I/O CLOCK. The falling edge of this clock cycle completes the analog sampling process and initiates the hold function. Conversion is then performed during the next 44 system clock cycles. After this final I/O clock cycle, CS must go high or the I/O CLOCK must remain low for at least 44 system-clock cycles to allow for the conversion function.

CS can be kept low during periods of multiple conversion. When keeping CS low during periods of multiple conversion, special care must be exercised to prevent noise glitches on I/O CLOCK. When glitches occur on I/O CLOCK, the I/O sequence between the microprocessor/controller and the device loses synchronization. Also, when $\overline{\text{CS}}$ goes high, it must remain high until the end of the conversion. Otherwise, a valid falling edge of $\overline{\text{CS}}$ causes a reset condition, which aborts the conversion in progress.

A new conversion may be started and the ongoing conversion simultaneously aborted by performing steps 1 through 4 before the 44 system-clock cycles occur. Such action yields the conversion result of the previous conversion and not the ongoing conversion.



SLAS073C - DECEMBER 1995 - REVISED AUGUST 1996

PRINCIPLES OF OPERATION

It is possible to connect SYSTEM CLOCK and I/O CLOCK together in special situations in which controlling-circuitry points must be minimized. In this case, the following special points must be considered in addition to the requirements of the normal control sequence previously described.

- 1. This device requires the first two clocks to recognize that \overline{CS} is at a valid low level when the common clock signal is used as an I/O CLOCK. When \overline{CS} is recognized by the device to be at a high level, the common clock signal is used for the conversion clock also.
- 2. A low $\overline{\text{CS}}$ must be recognized before the I/O CLOCK can shift in an analog channel address. The device recognizes a $\overline{\text{CS}}$ transition when the SYSTEM CLOCK terminal receives two positive edges and then a negative edge. For this reason, after a $\overline{\text{CS}}$ negative edge, the first two clock cycles do not shift in the address. Also, upon shifting in the address, $\overline{\text{CS}}$ must be raised after the tenth valid (12 total) I/O CLOCK. Otherwise, additional common-clock cycles are recognized as I/O CLOCK cycles and shift in an erroneous address.

For certain applications, such as strobing applications, it is necessary to start conversion at a specific point in time. This device accommodates these applications. Although the on-chip sample-and-hold begins sampling upon the negative edge of the fourth valid I/O CLOCK cycle, the hold function does not initiate until the negative edge of the tenth valid I/O CLOCK cycle. Thus, the control circuitry can leave the I/O CLOCK signal in its high state during the tenth valid I/O CLOCK cycle until the moment at which the analog signal must be converted. The TLC1541 continues sampling the analog input until the eighth valid falling edge of the I/O CLOCK. The control circuitry or software then immediately lowers the I/O CLOCK signal and holds the analog signal at the desired point in time and starts the conversion.



IMPORTANT NOTICE

Texas Instruments and its subsidiaries (TI) reserve the right to make changes to their products or to discontinue any product or service without notice, and advise customers to obtain the latest version of relevant information to verify, before placing orders, that information being relied on is current and complete. All products are sold subject to the terms and conditions of sale supplied at the time of order acknowledgement, including those pertaining to warranty, patent infringement, and limitation of liability.

TI warrants performance of its semiconductor products to the specifications applicable at the time of sale in accordance with TI's standard warranty. Testing and other quality control techniques are utilized to the extent TI deems necessary to support this warranty. Specific testing of all parameters of each device is not necessarily performed, except those mandated by government requirements.

CERTAIN APPLICATIONS USING SEMICONDUCTOR PRODUCTS MAY INVOLVE POTENTIAL RISKS OF DEATH, PERSONAL INJURY, OR SEVERE PROPERTY OR ENVIRONMENTAL DAMAGE ("CRITICAL APPLICATIONS"). TI SEMICONDUCTOR PRODUCTS ARE NOT DESIGNED, AUTHORIZED, OR WARRANTED TO BE SUITABLE FOR USE IN LIFE-SUPPORT DEVICES OR SYSTEMS OR OTHER CRITICAL APPLICATIONS. INCLUSION OF TI PRODUCTS IN SUCH APPLICATIONS IS UNDERSTOOD TO BE FULLY AT THE CUSTOMER'S RISK.

In order to minimize risks associated with the customer's applications, adequate design and operating safeguards must be provided by the customer to minimize inherent or procedural hazards.

TI assumes no liability for applications assistance or customer product design. TI does not warrant or represent that any license, either express or implied, is granted under any patent right, copyright, mask work right, or other intellectual property right of TI covering or relating to any combination, machine, or process in which such semiconductor products or services might be or are used. TI's publication of information regarding any third party's products or services does not constitute TI's approval, warranty or endorsement thereof.

Copyright © 1998, Texas Instruments Incorporated