

October 1991

TP3064, TP3067 "Enhanced" Serial Interface CMOS CODEC/Filter COMBO®

General Description

The TP3064 (μ -law) and TP3067 (A-law) are monolithic PCM CODEC/Filters utilizing the A/D and D/A conversion architecture shown in *Figure 1*, and a serial PCM interface. The devices are fabricated using National's advanced double-poly CMOS process (microCMOS).

Similar to the TP305X family, these devices feature an additional Receive Power Amplifier to provide push-pull balanced output drive capability. The receive gain can be adjusted by means of two external resistors for an output level of up to $\pm 6.6 \text{V}$ across a balanced 600Ω load.

Also included is an Analog Loopback switch and a $\overline{TS_X}$ output.

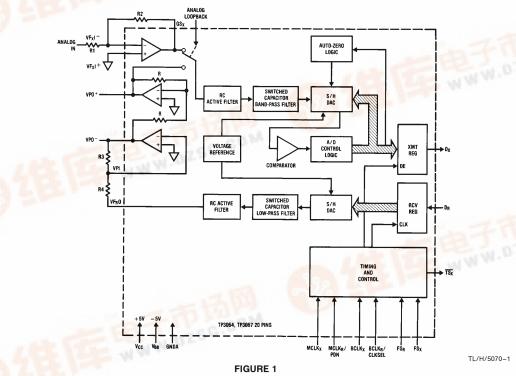
See also AN-370, "Techniques for Designing with CODEC/Filter COMBO Circuits."

COMBO® and TRI-STATE® are registered trademarks of National Semiconductor Corporation.

Features

- Complete CODEC and filtering system including:
 - Transmit high-pass and low-pass filtering
 - Receive low-pass filter with sin x/x correction
 - Active RC noise filters
 - μ-law or A-law compatible COder and DECoder
 - Internal precision voltage reference
 - Serial I/O interface
 - Internal auto-zero circuitry
 - Receive push-pull power amplifiers
- µ-law—TP3064
- A-law—TP3067
- Designed for D3/D4 and CCITT applications
- ±5V operation
- Low operating power—typically 70 mW
- Power-down standby mode—typically 3 mW
- Automatic power-down
- TTL or CMOS compatible digital interfaces
- Maximizes line interface card circuit density

Block Diagram



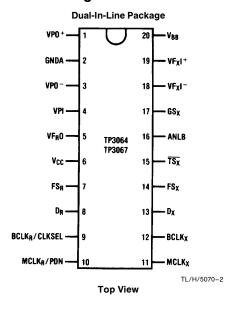
©1995 National Semiconductor Corporation

TL/H/5070

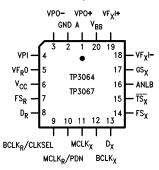
RRD-B30M115/Printed in U. S. A.



Connection Diagrams



Plastic Chip Carrier



TL/H/5070-6

Top View

Order Number TP3064J or TP3067J See NS Package J20A

Order Number TP3064WM or TP3067WM See NS Package M20B

Order Number TP3064N or TP3067N See NS Package N20A

Order Number TP3064V or TP3067V See NS Package V20A

Pin Description

Symbol	Function	Symbol	Function
VPO+	The non-inverted output of the receive power amplifier.	MCLK _X	Transmit master clock. Must be 1.536 MHz, 1.544 MHz or 2.048 MHz. May be asynchronous with MCLK _B . Best
GNDA	Analog ground. All signals are referenced to this pin.		performance is realized from synchronous operation.
VPO-	The inverted output of the receive power amplifier.	BCLK _X	The bit clock which shifts out the PCM data on D_X . May vary from 64 kHz to 2.048 MHz,
VPI	Inverting input to the receive power amplifier.		but must be synchronous with MCLKX.
VF _R O V _{CC}	Analog output of the receive filter. Positive power supply pin. $V_{CC} = +5V \pm 5\%$.	D_X	The TRI-STATE® PCM data output which is enabled by FS _X .
FS _R	Receive frame sync pulse which enables BCLK _R to shift PCM data into D _R . FS _R is an 8 kHz pulse train. See <i>Figures 2</i> and <i>3</i> for timing details.	FS _X	Transmit frame sync pulse input which enables $BCLK_X$ to shift out the PCM data on D_X . FS_X is an 8 kHz pulse train, see <i>Figures 2</i> and <i>3</i> for timing details.
D _R	Receive data input. PCM data is shifted into D_R following the FS $_R$ leading edge.	TS _X	Open drain output which pulses low during the encoder time slot.
BCLK _R / CLKSEL	The bit clock which shifts data into D _R after the FS _R leading edge. May vary from 64 kHz to 2.048 MHz. Alternatively, may be a logic input which selects either 1.536 MHz/1.544 MHz or 2.048 MHz for master clock in synchronous mode and	ANLB	Analog Loopback control input. Must be set to logic '0' for normal operation. When pulled to logic '1', the transmit filter input is disconnected from the output of the transmit preamplifier and connected to the VPO + output of the receive power amplifier.
	$BCLK_X$ is used for both transmit and receive directions (see Table I).	GS _X	Analog output of the transmit input amplifier. Used to externally set gain.
MCLK _R /	Receive master clock. Must be 1.536 MHz,	VF_XI^-	Inverting input of the transmit input amplifier.
PDN	1.544 MHz or 2.048 MHz. May be asynchronous with MCLK _X , but should be	VF _X I+	Non-inverting input of the transmit input amplifier.
	synchronous with MCLK $_{\rm X}$ for best performance. When MCLK $_{\rm R}$ is connected continuously low, MCLK $_{\rm X}$ is selected for all internal timing. When MCLK $_{\rm R}$ is connected continuously high, the device is powered down.	V _{BB}	Negative power supply pin. $V_{BB} = -5V \pm 5\%$

Functional Description

POWER-UP

When power is first applied, power-on reset circuitry initializes the COMBOTM and places it into a power-down state. All non-essential circuits are deactivated and the D_X , VF_RO , VPO^- and VPO^+ outputs are put in high impedance states. To power-up the device, a logical low level or clock must be applied to the MCLK $_R/PDN$ pin and FS_X and/or FS_R pulses must be present. Thus, 2 power-down control modes are available. The first is to pull the MCLK $_R/PDN$ pin high; the alternative is to hold both FS_X and FS_R inputs continuously low—the device will power-down approximately 2 ms after the last FS_X or FS_R pulse. Power-up will occur on the first FS_X or FS_R pulse. The TRI-STATE PCM data output, D_X , will remain in the high impedance state until the second FS_X pulse.

SYNCHRONOUS OPERATION

For synchronous operation, the same master clock and bit clock should be used for both the transmit and receive directions. In this mode, a clock must be applied to MCLK_X and the MCLK_R/PDN pin can be used as a power-down control. A low level on MCLK_R/PDN powers up the device and a high level powers down the device. In either case, MCLK_X will be selected as the master clock for both the transmit and receive circuits. A bit clock must also be applied to BCLK_X and the BCLK_R/CLKSEL can be used to select the proper internal divider for a master clock of 1.536 MHz, 1.544 MHz or 2.048 MHz. For 1.544 MHz operation, the device automatically compensates for the 193rd clock pulse each frame.

With a fixed level on the BCLK $_{\rm R}$ /CLKSEL pin, BLCK $_{\rm X}$ will be selected as the bit clock for both the transmit and receive directions. Table I indicates the frequencies of operation which can be selected, depending on the state of BCLK $_{\rm R}$ /CLKSEL. In this synchronous mode, the bit clock, BCLK $_{\rm X}$, may be from 64 kHz to 2.048 MHz, but must be synchronous with MCLK $_{\rm X}$.

Each FS $_{\rm X}$ pulse begins the encoding cycle and the PCM data from the previous encode cycle is shifted out of the enabled D $_{\rm X}$ output on the positive edge of BCLK $_{\rm X}$. After 8 bit clock periods, the TRI-STATE D $_{\rm X}$ output is returned to a high impedance state. With an FS $_{\rm R}$ pulse, PCM data is latched via the D $_{\rm R}$ input on the negative edge of BCLK $_{\rm X}$ (or BCLK $_{\rm R}$ if running). FS $_{\rm X}$ and FS $_{\rm R}$ must be synchronous with MCLK $_{\rm X/R}$.

TABLE I. Selection of Master Clock Frequencies

THE LET IN CONTROL OF MAGNETON CONTROL OF THE CONTR							
BCLK _R /CLKSEL	Master Clock Frequency Selected						
BOLKR/OLKSEL	TP3067	TP3064					
Clocked	2.048 MHz	1.536 MHz or					
		1.544 MHz					
0	1.536 MHz or	2.048 MHz					
	1.544 MHz						
1	2.048 MHz	1.536 MHz or					
		1.544 MHz					

ASYNCHRONOUS OPERATION

For asynchronous operation, separate transmit and receive clocks may be applied. $MCLK_X$ and $MCLK_R$ must be 2.048 MHz for the TP3067, or 1.536 MHZ, 1.544 MHz for the TP3064, and need not be synchronous. For best transmis-

sion performance, however, MCLK $_{\rm R}$ should be synchronous with MCLK $_{\rm X}$, which is easily achieved by applying only static logic levels to the MCLK $_{\rm R}$ /PDN pin. This will automatically connect MCLK $_{\rm X}$ to all internal MCLK $_{\rm R}$ functions (see Pin Description). For 1.544 MHz operation, the device automatically compensates for the 193rd clock pulse each frame. FS $_{\rm X}$ starts each encoding cycle and must be synchronous with MCLK $_{\rm X}$ and BCLK $_{\rm X}$. FS $_{\rm R}$ starts each decoding cycle and must be synchronous with BCLK $_{\rm R}$. BCLK $_{\rm R}$ must be a clock, the logic levels shown in Table I are not valid in asynchronous mode. BCLK $_{\rm X}$ and BCLK $_{\rm R}$ may operate from 64 kHz to 2.048 MHz.

SHORT FRAME SYNC OPERATION

The COMBO can utilize either a short frame sync pulse (the same as the TP3020/21 CODECs) or a long frame sync pulse. Upon power initialization, the device assumes a short frame mode. In this mode, both frame sync pulses, FS_X and FS_R, must be one bit clock period long, with timing relationships specified in Figure 2. With FSX high during a falling edge of BCLK_X , the next rising edge of BCLK_X enables the DX TRI-STATE output buffer, which will output the sign bit. The following seven rising edges clock out the remaining seven bits, and the next falling edge disables the DX output. With FSR high during a falling edge of BCLKR (BCLKX in synchronous mode), the next falling edge of BCLKR latches in the sign bit. The following seven falling edges latch in the seven remaining bits. All devices may utilize the short frame sync pulse in synchronous or asynchronous operating mode.

LONG FRAME SYNC OPERATION

To use the long (TP5116A/56 CODECs) frame mode, both the frame sync pulses, FS_X and FS_R , must be three or more bit clock periods long, with timing relationships specified in Figure 3. Based on the transmit frame sync, FS_X , the COM-BO will sense whether short or long frame sync pulses are being used. For 64 kHz operation, the frame sync pulse must be kept low for a minimum of 160 ns. The D_X TRI-STATE output buffer is enabled with the rising edge of FS_X or the rising edge of BCLKX, whichever comes later, and the first bit clocked out is the sign bit. The following seven BCLK_X rising edges clock out the remaining seven bits. The D_X output is disabled by the falling $BCLK_X$ edge following the eighth rising edge, or by FS_X going low, whichever comes later. A rising edge on the receive frame sync pulse, FSR, will cause the PCM data at DR to be latched in on the next eight falling edges of BCLK_R(BCLK_X in synchronous mode). All devices may utilize the long frame sync pulse in synchronous or asynchronous mode.

TRANSMIT SECTION

The transmit section input is an operational amplifier with provision for gain adjustment using two external resistors, see Figure 4. The low noise and wide bandwidth allow gains in excess of 20 dB across the audio passband to be realized. The op amp drives a unity-gain filter consisting of RC active pre-filter, followed by an eighth order switched-capacitor bandpass filter clocked at 256 kHz. The output of this filter directly drives the encoder sample-and-hold circuit. The A/D is of companding type according to μ -law (TP3064) or A-law (TP3067) coding conventions. A precision voltage reference is trimmed in manufacturing to provide an input overload ($t_{\rm MAX}$) of nominally 2.5V peak (see

Functional Description (Continued)

table of Transmission Characteristics). The FS $_X$ frame sync pulse controls the sampling of the filter output, and then the successive-approximation encoding cycle begins. The 8-bit code is then loaded into a buffer and shifted out through D $_X$ at the next FS $_X$ pulse. The total encoding delay will be approximately 165 μ s (due to the transmit filter) plus 125 μ s (due to encoding delay), which totals 290 μ s. Any offset voltage due to the filters or comparator is cancelled by sign bit integration.

RECEIVE SECTION

The receive section consists of an expanding DAC which drives a fifth order switched-capacitor low pass filter clocked at 256 kHz. The decoder is A-law (TP3067) or μ -law (TP3064) and the 5th order low pass filter corrects for the sin x/x attenuation due to the 8 kHz sample/hold. The filter is then followed by a 2nd order RC active post-filter with its output at VF $_R$ O. The receive section is unity-gain, but gain can be added by using the power amplifiers. Upon the occurrence of FS $_R$, the data at the D $_R$ input is clocked in on the falling edge of the next eight BCLK $_R$ (BCLK $_X$) peri-

ods. At the end of the decoder time slot, the decoding cycle begins, and 10 μs later the decoder DAC output is updated. The total decoder delay is \sim 10 μs (decoder update) plus 110 μs (filter delay) plus 62.5 μs (½ frame), which gives approximately 180 μs .

RECEIVE POWER AMPLIFIERS

Two inverting mode power amplifiers are provided for directly driving a matched line interface transformer. The gain of the first power amplifier can be adjusted to boost the $\pm 2.5 V$ peak output signal from the receive filter up to $\pm 3.3 V$ peak into an unbalanced 300Ω load, or $\pm 4.0 V$ into an unbalanced 15 $\rm k\Omega$ load. The second power amplifier is internally connected in unity-gain inverting mode to give 6 dB of signal gain for balanced loads.

Maximum power transfer to a 600 Ω subscriber line termination is obtained by differentially driving a balanced transformer with a $\sqrt{2}$:1 turns ratio, as shown in *Figure 4*. A total peak power of 15.6 dBm can be delivered to the load plus termination.

ENCODING FORMAT AT D_X OUTPUT

	TP3064 μ-Law					(II	nclude	A-L	8067 ∟aw n Bit In	versio	n)					
V _{IN} = +Full-Scale	1	0	0	0	0	0	0	0	1	0	1	0	1	0	1	0
$V_{IN} = 0V$	∫1	1	1	1	1	1	1	1	1	1	0	1	0	1	0	1
	lo	1	1	1	1	1	1	1	0	1	0	1	0	1	0	1
$V_{IN} = -Full-Scale$	0	0	0	0	0	0	0	0	0	0	1	0	1	0	1	0

Absolute Maximum Ratings

If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/Distributors for availability and specifications.

V_{CC} to GNDA $V_{\mbox{\footnotesize{BB}}}$ to GNDA -7V Voltage at any Analog Input

 $V_{\mbox{\footnotesize CC}}\!+\!0.3\mbox{\footnotesize V}$ to $V_{\mbox{\footnotesize BB}}\!-\!0.3\mbox{\footnotesize V}$ or Output

Voltage at any Digital Input V_{CC} + 0.3V to GNDA - 0.3V or Output Operating Temperature Range

-25°C to +125°C

Storage Temperature Range -65°C to +150°C Lead Temp. (Soldering, 10 sec.) 300°C ESD (Human Body Model) J 1000V ESD (Human Body Model) N 1500V

Latch-Up Immunity 100 mA on Any Pin

 \pm 5.0V \pm 5%, V_{BB} = \pm 5.0V \pm 5%; T_A = 0°C to 70°C by correlation with 100% electrical testing at T_A = 25°C. All other limits are assured by correlation with other production tests and/or product design and characterization. All signals referenced to GNDA. Typicals specified at $V_{CC} = +5.0V$, $V_{BB} = -5.0V$, $T_A = 25^{\circ}C$.

Symbol	Parameter	Conditions	Min	Тур	Max	Units			
POWER I	POWER DISSIPATION (ALL DEVICES)								
I _{CC} 0	Power-Down Current	(Note)		0.5	1.5	mA			
I _{BB} 0	Power-Down Current	(Note)		0.05	0.3	mA			
I _{CC} 1	Active Current	VPI=0V; VF _R O, VPO+ and VPO- unloaded		7.0	10.0	mA			
I _{BB} 1	Active Current	VPI=0V; VF _R O, VPO ⁺ and VPO ⁻ unloaded		7.0	10.0	mA			
DIGITAL	DIGITAL INTERFACE								
V _{IL}	Input Low Voltage				0.6	V			
V _{IH}	Input High Voltage		2.2			V			
V _{OL}	Output Low Voltage	D_{X} , $I_{L} = 3.2 \text{ mA}$ $\overline{TS_{X}}$, $I_{L} = 3.2 \text{ mA}$, Open Drain			0.4 0.4	V			
V _{OH}	Output High Voltage	D_X , $I_H = -3.2 \text{ mA}$	2.4			V			
I _{IL}	Input Low Current	GNDA≤V _{IN} ≤V _{IL} , All Digital Inputs	-10		10	μΑ			
I _{IH}	Input High Current	V _{IH} ≤ V _{IN} ≤ V _{CC}	-10		10	μΑ			
loz	Output Current in High Impedance State (TRI-STATE)	D_X , $GNDA \le V_O \le V_{CC}$	-10		10	μΑ			

Note: I_{CC0} and I_{BB0} are measured after first achieving a power-up state.

Electrical Characteristics (Continued)

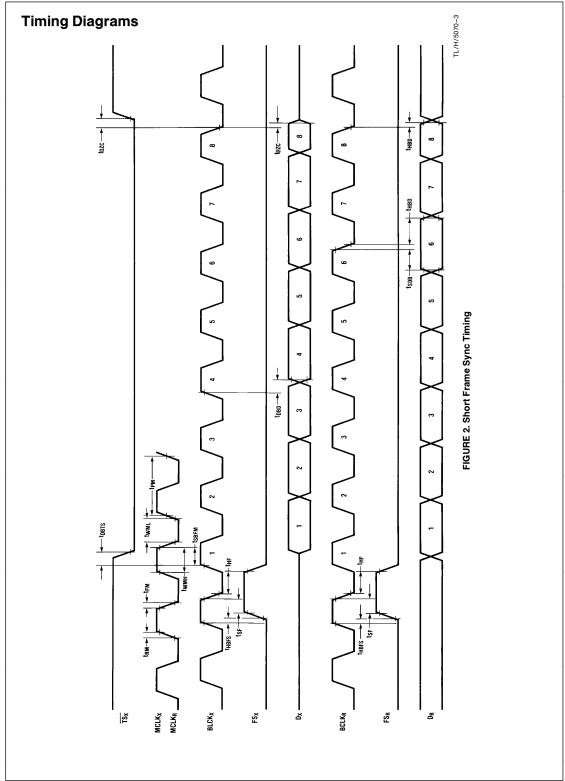
Unless otherwise noted, limits printed in **BOLD** characters are guaranteed for $V_{CC}=+5.0V\pm5\%$, $V_{BB}=-5.0V\pm5\%$; $T_A=0^{\circ}C$ to 70°C by correlation with 100% electrical testing at $T_A=25^{\circ}C$. All other limits are assured by correlation with other production tests and/or product design and characterization. All signals referenced to GNDA. Typicals specified at $V_{CC}=+5.0V$, $V_{BB}=-5.0V$, $T_{AB}=25^{\circ}C$.

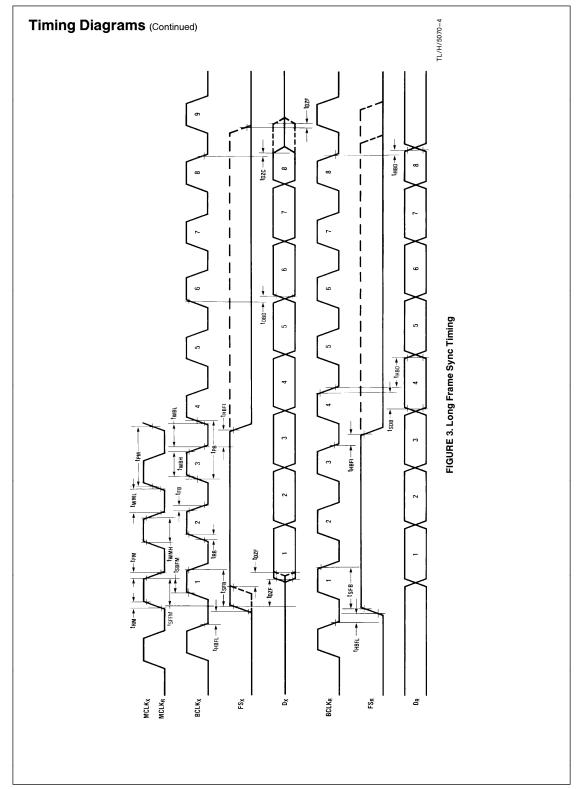
Symbol	Parameter	Conditions	Min	Тур	Max	Units
ANALOG IN	NTERFACE WITH TRANSMIT INPU	T AMPLIFIER (ALL DEVICES)				
I _I XA	Input Leakage Current	-2.5 V \leq V \leq $+2.5$ V, VF $_X$ I $^+$ or VF $_X$ I $^-$	-200		200	nA
R _I XA	Input Resistance	-2.5 V \leq V \leq $+2.5$ V, VF _X I $^+$ or VF _X I $^-$	10			МΩ
R _O XA	Output Resistance	Closed Loop, Unity Gain		1	3	Ω
R _L XA	Load Resistance	GS _X	10			kΩ
C _L XA	Load Capacitance	GS _X			50	pF
V _O XA	Output Dynamic Range	GS_X , R_L ≥10 k $Ω$	-2.8		+ 2.8	٧
A _V XA	Voltage Gain	VF _X I ⁺ to GS _X	5000			V/V
F _U XA	Unity-Gain Bandwidth		1	2		MHz
V _{OS} XA	Offset Voltage		-20		20	mV
V _{CM} XA	Common-Mode Voltage	CMRRXA > 60 dB	- 2.5		2.5	٧
CMRRXA	Common-Mode Rejection Ratio	DC Test	60			dB
PSRRXA	Power Supply Rejection Ratio	DC Test	60			dB
ANALOG IN	NTERFACE WITH RECEIVE FILTER	R (ALL DEVICES)				
R _O RF	Output Resistance	Pin VF _R O		1	3	Ω
R _L RF	Load Resistance	VF _R O = ±2.5V	10			kΩ
C _L RF	Load Capacitance	Connect from VF _R O to GNDA			25	pF
VOS _R O	Output DC Offset Voltage	Measure from VF _R O to GNDA	-200		200	mV
ANALOG IN	NTERFACE WITH POWER AMPLIF	ERS (ALL DEVICES)				
IPI	Input Leakage Current	-1.0V≤VPI≤1.0V	-100		100	nA
RIPI	Input Resistance	-1.0V≤VPI≤1.0V	10			МΩ
VIOS	Input Offset Voltage		-25		25	mV
ROP	Output Resistance	Inverting Unity-Gain at VPO+ or VPO-		1		Ω
F _C	Unity-Gain Bandwidth	Open Loop (VPO ⁻)		400		kHz
C _L P	Load Capacitance				100	pF
GA _P +	Gain from VPO- to VPO+	$R_L = 600\Omega \text{ VPO}^+ \text{ to VPO}^-$ Level at $VPO^- = 1.77 \text{ Vrms}$		-1		V/V
PSRR _P	Power Supply Rejection of V _{CC} or V _{BB}	VPO ⁻ Connected to VPI 0 kHz - 4 kHz 4 kHz - 50 kHz	60 36			dB dB
R _I P	Load Resistance	Connect from VPO+ to VPO-	600			Ω

Timing Specifications

Unless otherwise noted, limits printed in **BOLD** characters are guaranteed for $V_{CC} = +5.0V \pm 5\%$, $V_{BB} = -5.0V \pm 5\%$, $T_A = 0^{\circ}$ C to 70° C by correlation with 100% electrical testing at $T_A = 25^{\circ}$ C. All other limits are assured by correlation with other production tests and/or product design and characterization. All signals are referenced to GNDA. Typicals specified at $V_{CC} = +5.0V$, $V_{BB} = -5.0V$, $V_{AB} = 25^{\circ}$ C. All timing parameters are measured at $V_{CB} = 2.0V$ and $V_{CC} = 0.7V$. See Definitions and Timing Conventions section for test methods information.

Symbol	Parameter	Conditions	Min	Тур	Max	Units
1/t _{PM}	Frequency of Master Clock			1.536		MHz
		MCLK _X and MCLK _R		1.544 2.048		MHz MHz
t _{RM}	Rise Time of Master Clock	MCLK _X and MCLK _R			50	ns
t_{FM}	Fall Time of Master Clock	MCLK _X and MCLK _R			50	ns
t _{PB}	Period Bit of Clock		485	488	15725	ns
t _{RB}	Rise Time of Bit Clock	BCLK _X and BCLK _R			50	ns
t_{FB}	Fall Time of Bit Clock	BCLK _X and BCLK _R			50	ns
t_{WMH}	Width of Master Clock High	MCLK _X and MCLK _R	160			ns
t _{WML}	Width of Master Clock Low	MCLK _X and MCLK _R	160			ns
t _{SBFM}	Set-Up Time from $BCLK_X$ High to $MCLK_X$ Falling Edge		100			ns
t _{SFFM}	Set-Up Time from FS_X High to $MCLK_X$ Falling Edge	Long Frame Only	100			ns
t _{WBH}	Width of Bit Clock High		160			ns
t _{WBL}	Width of Bit Clock Low		160			ns
t _{HBFL}	Holding Time from Bit Clock Low to Frame Sync	Long Frame Only	0			ns
t _{HBFS}	Holding Time from Bit Clock High to Frame Sync	Short Frame Only	0			ns
t _{SFB}	Set-Up Time for Frame Sync to Bit Clock Low	Long Frame Only	80			ns
t _{DBD}	Delay Time from BCLK _X High to Data Valid	Load = 150 pF plus 2 LSTTL Loads	0		180	ns
t _{DBTS}	Delay Time to $\overline{TS_X}$ Low	Load = 150 pF plus 2 LSTTL Loads			140	ns
t _{DZC}	Delay Time from BCLK _X Low to Data Output Disabled		50		165	ns
t _{DZF}	Delay Time to Valid Data from FS_X or $BCLK_X$, Whichever Comes Later	C _L = 0 pF to 150 pF	20		165	ns
t _{SDB}	Set-Up Time from D_R Valid to $BCLK_{R/X}$ Low		50			ns
t _{HBD}	Hold Time from $\operatorname{BCLK}_{R/X}$ Low to D_R Invalid		50			ns
t _{SF}	Set-Up Time from $FS_{X/R}$ to $BCLK_{X/R}$ Low	Short Frame Sync Pulse (1 Bit Clock Period Long)	50			ns
t _{HF}	Hold Time from $\operatorname{BCLK}_{X/R}$ Low to $\operatorname{FS}_{X/R}$ Low	Short Frame Sync Pulse (1 Bit Clock Period Long)	100			ns
t _{HBFI}	Hold Time from 3rd Period of Bit Clock Low to Frame Sync (FS _X or FS _R)	Long Frame Sync Pulse (from 3 to 8 Bit Clock Periods Long)	100			ns
t _{WFL}	Minimum Width of the Frame Sync Pulse (Low Level)	64k Bit/s Operating Mode	160			ns





Transmission Characteristics

Unless otherwise noted, limits printed in **BOLD** characters are guaranteed for $V_{CC} = +5.0V \pm 5\%$, $V_{BB} = -5.0V \pm 5\%$; $T_A = 0^{\circ}C$ to 70°C by correlation with 100% electrical testing at $T_A = 25^{\circ}C$. All other limits are assured by correlation with other production tests and/or product design and characterization. GNDA = 0V, f = 1.02 kHz, $V_{IN} = 0$ dbm0, transmit input amplifier connected for unity gain non-inverting. Typicals specified at $V_{CC} = +5.0V$, $V_{BB} = -5.0V$, $V_{AB} = -5.0V$, $V_{AB} = -5.0V$.

Symbol	Parameter	Conditions	Min	Тур	Max	Units
AMPLITU	IDE RESPONSE					
	Absolute Levels (Definition of nominal gain)	Nominal 0 dBm0 Level is 4 dBm (600 Ω) 0 dBm0		1.2276		Vrms
t _{MAX}	Virtual Decision Value Defined per CCITT Rec. G711	Max Transmit Overload Level TP3064 (3.17 dBm0) TP3067 (3.14 dBm0)		2.501 2.492		V _{PK} V _{PK}
G _{XA}	Transmit Gain, Absolute	$T_A = 25$ °C, $V_{CC} = 5V$, $V_{BB} = -5V$	-0.15		0.15	dB
G _{XR}	Transmit Gain, Relative to G _{XA}	f = 16 Hz f = 50 Hz f = 60 Hz f = 200 Hz f = 300 Hz-3000 Hz f = 3300 Hz f = 3400 Hz f = 4000 Hz f = 4600 Hz and Up, Measure Response from 0 Hz to 4000 Hz	-1.8 -0.15 -0.35 -0.7		-40 -30 -26 -0.1 0.15 0.05 0 -14 -32	dB dB dB dB dB dB dB dB
G _{XAT}	Absolute Transmit Gain Variation with Temperature	Relative to G _{XA}	-0.1		0.1	dB
G _{XAV}	Absolute Transmit Gain Variation with Supply Voltage	Relative to G _{XA}	-0.05		0.05	dB
G _{XRL}	Transmit Gain Variations with Level Receive Gain, Absolute	Sinusoidal Test Method Reference Level = -10 dBm0 VF _X I + = -40 dBm0 to $+3$ dBm0 VF _X I + = -50 dBm0 to -40 dBm0 VF _X I + = -55 dBm0 to -50 dBm0 T _A = 25° C, V _{CC} = 5 V, V _{BR} = -5 V	- 0.2 - 0.4 - 1.2		0.2 0.4 1.2	dB dB dB
GRA	neceive daili, Absolute	Input = Digital Code Sequence for 0 dBm0 Signal	-0.13		0.13	ub
G _{RR}	Receive Gain, Relative to G _{RA}	f=0 Hz to 3000 Hz f=3300 Hz f=3400 Hz f=4000 Hz	-0.15 -0.35 -0.7		0.15 0.05 0 -14	dB dB dB dB
G _{RAT}	Absolute Receive Gain Variation with Temperature	Relative to G _{RA}	-0.1		0.1	dB
G _{RAV}	Absolute Receive Gain Variation with Supply Voltage	Relative to G _{RA}	-0.05		0.05	dB
G _{RRL}	Receive Gain Variations with Level	Sinusoidal Test Method; Reference Input PCM Code Corresponds to an Ideally Encoded — 10 dBm0 Signal PCM Level = -40 dBm0 to +3 dBm0 PCM Level = -50 dBm0 to -40 dBm0 PCM Level = -55 dBm0 to -50 dBm0	- 0.2 - 0.4 - 1.2		0.2 0.4 1.2	dB dB dB
V _{RO}	Receive Filter Output at VF _R O	RL=10 kΩ	-2.5		2.5	V

Transmission Characteristics (Continued)

Unless otherwise noted, limits printed in **BOLD** characters are guaranteed for $V_{CC} = +5.0V \pm 5\%$, $V_{BB} = -5.0V \pm 5\%$; $T_A = 0^{\circ}C$ to 70°C by correlation with 100% electrical testing at $T_A = 25^{\circ}C$. All other limits are assured by correlation with other production tests and/or product design and characterization. GNDA = 0V, f = 1.02 kHz, $V_{IN} = 0$ dbm0, transmit input amplifier connected for unity gain non-inverting. Typicals specified at $V_{CC} = +5.0V$, $V_{BB} = -5.0V$, $V_{AB} = 25^{\circ}C$.

Symbol	Parameter	Conditions	Min	Тур	Max	Units		
ENVELOPE DELAY DISTORTION WITH FREQUENCY								
D_{XA}	Transmit Delay, Absolute	f=1600 Hz		290	315	μs		
D _{XR}	Transmit Delay, Relative to D _{XA}	f=500 Hz-600 Hz f=600 Hz-800 Hz f=800 Hz-1000 Hz f=1000 Hz-1600 Hz f=1600 Hz-2600 Hz f=2600 Hz-2800 Hz f=2800 Hz-3000 Hz		195 120 50 20 55 80 130	220 145 75 40 75 105	μs μs μs μs μs μs		
D _{RA}	Receive Delay, Absolute	f=1600 Hz		180	200	μs		
D _{RR}	Receive Delay, Relative to D _{RA}	f=500 Hz -1000 Hz f=1000 Hz -1600 Hz f=1600 Hz -2600 Hz f=2600 Hz -2800 Hz f=2800 Hz -3000 Hz	-40 -30	-25 -20 70 100 145	90 125 175	μs μs μs μs μs		
NOISE					•			
N _{XC}	Transmit Noise, C Message Weighted	TP3064 (Note 1)		12	15	dBrnC0		
N_{XP}	Transmit Noise, Psophometric Weighted	TP3067 (Note 1)		-74	-67	dBm0p		
N _{RC}	Receive Noise, C Message Weighted	PCM Code Equals Alternating Positive and Negative Zero TP3064		8	11	dBrnCO		
N _{RP}	Receive Noise, Psophometric Weighted	PCM Code Equals Positive Zero TP3067		-82	-79	dBm0p		
N _{RS}	Noise, Single Frequency	$f=0$ kHz to 100 kHz, Loop Around Measurement, $VF_XI^+=0$ Vrms			-53	dBm0		
PPSRX	Positive Power Supply Rejection, Transmit	$V_{CC} = 5.0 V_{DC} + 100 \text{ mVrms}$ f = 0 kHz - 50 kHz (Note 2)	40			dBC		
NPSRX	Negative Power Supply Rejection, Transmit	$V_{BB} = -5.0 V_{DC} + 100 \text{ mVrms}$ f = 0 kHz -50 kHz (Note 2)	40			dBC		
PPSR _R	Positive Power Supply Rejection, Receive	PCM Code Equals Positive Zero $V_{CC} = 5.0 \ V_{DC} + 100 \ mVrms$ $Measure \ VF_{RO}$ $f = 0 \ Hz - 4000 \ Hz$ $f = 4 \ kHz - 50 \ kHz$	38 25			dBC dB		
NPSR _R	Negative Power Supply Rejection, Receive	PCM Code Equals Positive Zero $V_{BB} = -5.0 \ V_{DC} + 100 \ mVrms$ $Measure \ VF_{RO}$ $f = 0 \ Hz - 4000 \ Hz$ $f = 4 \ kHz - 25 \ kHz$ $f = 25 \ kHz - 50 \ kHz$	40 40 36			dBC dB dB		
SOS	Spurious Out-of-Band Signals at the Channel Output	0 dBm0, 300 Hz – 3400 Hz Input PCM Code Applied at DR Measure Individual Image Signals at VF _R O 4600 Hz – 7600 Hz 7600 Hz – 8400 Hz 8400 Hz – 100,000 Hz			-32 -40 -32	dB dB dB		

Transmission Characteristics (Continued)

Unless otherwise noted, limits printed in **BOLD** characters are guaranteed for $V_{CC}=+5.0V\pm5\%$, $V_{BB}=-5.0V\pm5\%$; $T_A=0^{\circ}C$ to 70°C by correlation with 100% electrical testing at $T_A=25^{\circ}C$. All other limits are assured by correlation with other production tests and/or product design and characterization. GNDA = 0V, f = 1.02 kHz, $V_{IN}=0$ dbm0, transmit input amplifier connected for unity gain non-inverting. Typicals specified at $V_{CC}=+5.0V$, $V_{BB}=-5.0V$, $T_A=25^{\circ}C$.

Symbol	Parameter	Conditions	Min	Тур	Max	Units
DISTORT	TON		•	•		
STD _X , STD _R	Signal to Total Distortion Transmit or Receive Half-Channel	Sinusoidal Test Method (Note 3) Level = 3.0 dBm0 = 0 dBm0 to -30 dBm0 = -40 dBm0 XMT RCV = -55 dBm0 XMT RCV	33 36 29 30 14			dBC dBC dBC dBC dBC dBC
SFD _X	Single Frequency Distortion, Transmit				-46	dB
SFDR	Single Frequency Distortion, Receive				-46	dB
IMD	Intermodulation Distortion	Loop Around Measurement, $VF_XI^+=-4$ dBm0 to -21 dBm0, Two Frequencies in the Range 300 Hz -3400 Hz			-41	dB
CROSSTA	ALK					
CT _{X-R}	Transmit to Receive Crosstalk	f=300 Hz-3000 Hz D _R =Quiet PCM Code		-90	-75	dB
CT _{R-X}	Receive to Transmit Crosstalk	f=300 Hz-3000 Hz, VF _X I=0V (Note 2)		-90	-70	dB
POWER A	AMPLIFIERS					
V _O PA	Maximum 0 dBm0 Level (Better than ±0.1 dB Linearity over the Range -10 dBm0 to +3 dBm0)	Balanced Load, R _L Connected Between VPO+ and VPO $R_L = 600\Omega$ $R_L = 1200\Omega$	3.3 3.5			Vrms Vrms
S/D _P	Signal/Distortion	$R_L = 600\Omega$	50			dB

Note 1: Measured by extrapolation from the distortion test result at $-50\ \mathrm{dBm0}.$

Note 2: PPSR $_{X}$, NPSR $_{X}$, and CT $_{R-X}$ are measured with a -50 dBm0 activation signal applied to VF $_{X}$ I $^{+}$.

Note 3: TP3064 is measured using C message weighted filter. TP3067 is measured using psophometric weighted filter.

Applications Information

POWER SUPPLIES

While the pins of the TP3060 family are well protected against electrical misuse, it is recommended that the standard CMOS practice be followed, ensuring that ground is connected to the device before any other connections are made. In applications where the printed circuit board may be plugged into a "hot" socket with power and clocks already present, an extra long ground pin in the connector should be used

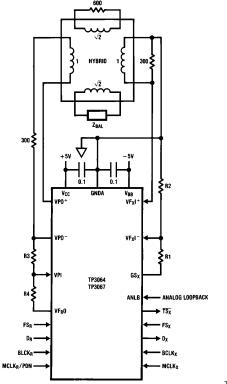
All ground connections to each device should meet at a common point as close as possible to the GNDA pin. This

minimizes the interaction of ground return currents flowing through a common bus impedance. 0.1 μF supply decoupling capacitors should be connected from this common ground point to V_{CC} and V_{BB}, as close to the device as nossible

For best performance, the ground point of each CODEC/FILTER on a card should be connected to a common card ground in "STAR" formation, rather than via a ground bus. This common ground point should be decoupled to V_{CC} and V_{BB} with 10 μF capacitors.

Note: See Application Note 370 for further details

Typical Asynchronous Application



 $\label{eq:Note 1: Transmit gain} \begin{array}{l} \text{TL/H/5070-5} \\ \text{Note 1: Transmit gain} = 20 \times log \left(\frac{\text{R1} + \text{R2}}{\text{R2}}\right), & (\text{R1} + \text{R2}) \geq 10 \text{ k}\Omega \\ \\ \text{Note 2: Receive gain} = 20 \times log \left(\frac{2 \times \text{R3}}{\text{R4}}\right), & \text{R4} \geq 10 \text{ k}\Omega \\ \end{array}$

FIGURE 4

Definitions and Timing Conventions

DEFINITIONS

VOL

 V_{IH} VIH is the d.c. input level above which an input level is guaranteed to appear

> as a logical one. This parameter is to be measured by performing a functional test at reduced clock speeds and nominal timing, (i.e. not minimum setup and hold times or output strobes), with the high level of all driving signals set to VIH and maximum supply voltages applied to

the device

 V_{IL} V_{IL} is the d.c. input level below which

an input level is guaranteed to appear as a logical zero to the device. This parameter is measured in the same manner as VIH but with all driving signal low levels set to V_{IL} and minimum supply voltages applied to

the device.

 V_{OH} VOH is the minimum d.c. output level Pulse Width High The high pulse width is designated as

to which an output placed in a logical one state will converge when loaded at the maximum specified load current. VOL is the maximum d.c. output level

to which an output placed in a logical zero state will converge when loaded at the maximum specified load current.

Threshold Region The threshold region is the range of

input voltages between V_{IL} and $V_{\text{IH}}. \label{eq:VIII}$ Valid Signal A signal is Valid if it is in one of the

valid logic states, (i.e. above VIH or below V_{IL}). In timing specifiations, a signal is deemed valid at the instant it

enters a valid state.

Invalid Signal A signal is Invalid if it is not in a valid

> logic state, i.e. when it is in in the threshold region between VIL and VIH. In timing specifications, a signal is deemed Invalid at the instant it enters

the threshold region.

TIMING CONVENTIONS

For the purposes of this timing specification, the following

conventions apply:

Fall Time

Input Signals All input signals may be characterized

as: $V_L = 0.4V$, $V_H = 2.4V$, $t_R < 10$ ns,

 $t_{F} < 10 \text{ ns.}$

Period The period of clock signal is designated as t_{Pxx} where xx

represents the mnemonic of the clock

signal being specified.

Rise times are designated as t_{Ryy} , Rise Time

where yy represents a mnemonic of the signal whose rise time is being specified. $t_{\mbox{\scriptsize Ryy}}$ is measured from $V_{\mbox{\scriptsize IL}}$ to

 V_{IH} .

Fall times are designated as t_{Fyy}, where yy represents a mnemonic of

the signal whose fall time is being specified. t_{FVV} is measured from V_{IH} to

VII.

t_{WzzH}, where zz represents the mnemonic of the input or output signal whose pulse width is being specified. High pulse widths are measured from

 V_{IH} to V_{IH} .

Pulse Width Low The low pulse width is designated as

t_{WzzL}, where zz represents the mnemonic of the input or output signal whose pulse width is being specified. Low pulse widths are measured from

V_{IL} to V_{IL}.

Setup times are designated as t_{Swwxx}, Setup Time

where ww represents the mnemonic of the input signal whose setup time is being specified relative to a clock or strobe input represented by mnemonic xx. Setup times are measured from the

ww Valid to xx Invalid.

Hold times are designated as t_{Hxxww} , Hold Time where ww represents the mnemonic of

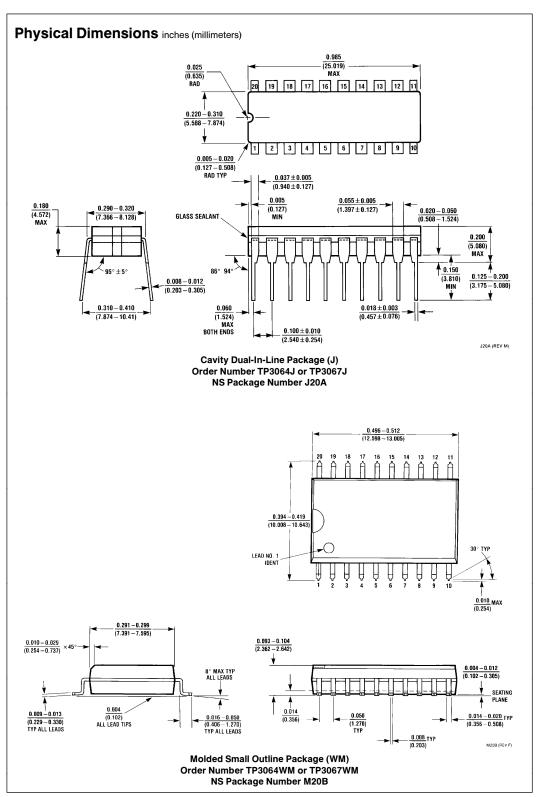
the input signal whose hold time is being specified relative to a clock or strobe input represented by mnemonic xx. Hold times are measured from xx

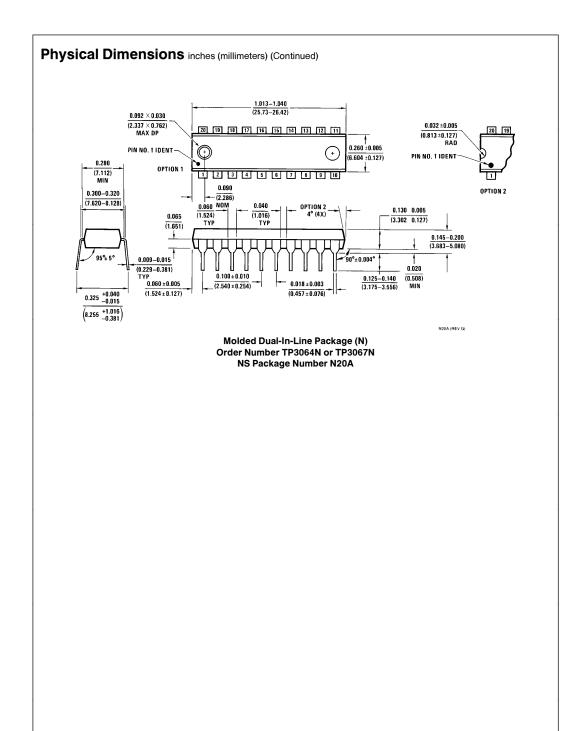
Valid to ww Invalid.

Delay times are designated as t_{Dxxyy} **Delay Time** Hi to Low, where xx represents the

mnemonic of the input reference signal and yy represents the mnemonic of the output signal whose timing is being specified relative to xx. The mnemonic may optionally be terminated by an H or L to specify the high going or low going transition of the output signal. Maximum delay times are measured from xx Valid to yy Valid. Minimum delay times are measured from xx Valid to yy Invalid. This parameter is tested under the load conditions specified in the Conditions column of the Timing

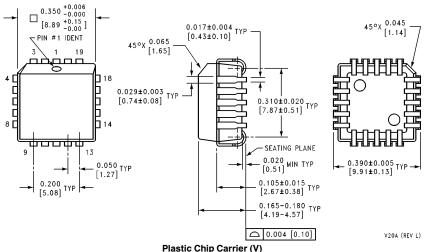
Specifications section of this data sheet.





Physical Dimensions inches (millimeters) (Continued)

Lit. # 113975



Plastic Chip Carrier (V) Order Number TP3064V or TP3067V NS Package Number V20A

LIFE SUPPORT POLICY

NATIONAL'S PRODUCTS ARE NOT AUTHORIZED FOR USE AS CRITICAL COMPONENTS IN LIFE SUPPORT DEVICES OR SYSTEMS WITHOUT THE EXPRESS WRITTEN APPROVAL OF THE PRESIDENT OF NATIONAL SEMICONDUCTOR CORPORATION. As used herein:

- Life support devices or systems are devices or systems which, (a) are intended for surgical implant into the body, or (b) support or sustain life, and whose failure to perform, when properly used in accordance with instructions for use provided in the labeling, can be reasonably expected to result in a significant injury to the user.
- A critical component is any component of a life support device or system whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.



National Semiconductor Corporation 1111 West Bardin Road Arlington, TX 76017 Tel: 1(800) 272-9959 Fax: 1(800) 737-7018 National Semiconductor Europe

Fax: (+49) 0-180-530 85 86
Email: cnjwge@tevm2.nsc.com
Deutsch Tel: (+49) 0-180-530 85 85
English Tel: (+49) 0-180-532 78 32
Français Tel: (+49) 0-180-532 78 61
Italiano Tel: (+49) 0-180-534 16 80

National Semiconductor Hong Kong Ltd. 13th Floor, Straight Block, Ocean Centre, 5 Canton Rd. Tsimshatsui, Kowloon Hong Kong Tel: (852) 2737-1600 Fax: (852) 2736-9960 National Semiconductor Japan Ltd. Tel: 81-043-299-2309 Fax: 81-043-299-2408