## 2 GHz Ultralow Distortion Differential RF／IF Amplifier

## ANALOG DEVICES

## FEATURES

-3 dB bandwidth of $2.2 \mathrm{GHz}\left(\mathrm{A}_{\mathrm{v}}=10 \mathrm{~dB}\right)$
Single resistor gain adjust $\mathbf{3 d B} \leq A_{v} \leq 21 \mathrm{~dB}$
Single resistor and capacitor distortion adjust
Input resistance $3 \mathrm{k} \Omega$ ，independent of gain（ Av ） Differential or single－ended input to differential output Low noise input stage $\mathbf{2 . 7 n V / \sqrt { H z } R T I ~ @ ~} A_{v}=10 \mathrm{~dB}$ Low broadband distortion
$10 \mathrm{MHz}:-86 \mathrm{dBc}$ HD2，-82 dBc HD3
70 MHz ： $\mathbf{8 4}$ dBc HD2， $\mathbf{- 8 2 \mathrm { dBc } \text { HD3 }}$
190 MHz ：-81 dBc HD2，-87 dBc HD3
OIP3 of $\mathbf{4 1}$ dBm＠ $150 \mathbf{~ M H z}$
Slew rate $8 \mathrm{~V} / \mathrm{ns}$
Fast settling and overdrive recovery of 2 ns
Single－supply operation： 3 V to 5.0 V
Low power dissipation： 37 mA ＠ 5 V
Power down capability： 5 mA ＠ 5 V
Fabricated using the high speed XFCB3 SiGe process

## APPLICATIONS

## Differential ADC drivers

Single－ended to differential conversion
RF／IF gain blocks
SAW filter interfacing

FUNCTIONAL BLOCK DIAGRAM


Figure 1.


Figure 2．IP3 and Third Harmonic Distortion vs．Frequency， Measured Differentially

The device is optimized for wide band，low distortion performance at frequencies beyond 500 MHz ．These attributes， together with its wide gain adjust capability，make this device the amplifier of choice for general－purpose IF and broadband applications where low distortion，noise，and power are critical． In particular，it is ideally suited for driving not only ADCs，but also mixers，pin diode attenuators，SAW filters，and multielement discrete devices．The device comes in a compact $3 \mathrm{~mm} \times 3 \mathrm{~mm}$ ， 16－lead LFCSP package and operates over a temperature range of $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ ．
． drive requirements．The AD8352 has a nominal $100 \Omega$ differential output resistance．

## AD8352

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## REVISION HISTORY

## 1/06-Revision 0: Initial Version

## SPECIFICATIONS

$\mathrm{V}_{\mathrm{s}}=5 \mathrm{~V}, \mathrm{R}_{\mathrm{L}}=200 \Omega$ differential, $\mathrm{R}_{\mathrm{G}}=118 \Omega\left(\mathrm{~A}_{\mathrm{v}}=10 \mathrm{~dB}\right), f=100 \mathrm{MHz}, \mathrm{T}=25^{\circ} \mathrm{C}$; parameters specified differentially (in/out), unless otherwise noted. $C_{D}$ and $R_{D}$ are selected for differential broadband operation (see Table 6 and Table 7).
Table 1.

| Parameter | Conditions | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: |
| DYNAMIC PERFORMANCE |  |  |  |  |  |
| -3 dB Bandwidth | $\mathrm{Al}_{\mathrm{v}}=6 \mathrm{~dB}, \mathrm{~V}_{\text {out }} \leq 1.0 \mathrm{~V}$ p-p |  | 2500 |  | MHz |
|  | $\mathrm{A}_{\mathrm{v}}=10 \mathrm{~dB}, \mathrm{~V}_{\text {out }} \leq 1.0 \mathrm{Vp-p}$ |  | 2200 |  | MHz |
|  | $\mathrm{A}_{\mathrm{v}}=14 \mathrm{~dB}, \mathrm{~V}_{\text {out }} \leq 1.0 \mathrm{~V}$ p-p |  | 1800 |  | MHz |
| Bandwidth for 0.1 dB Flatness | $3 \mathrm{~dB} \leq \mathrm{A}_{\mathrm{v}} \leq 20 \mathrm{~dB}, \mathrm{~V}_{\text {out }} \leq 1.0 \mathrm{~V}$ p-p |  | 190 |  | MHz |
| Bandwidth for 0.2 dB Flatness | $3 \mathrm{~dB} \leq \mathrm{A}_{\mathrm{v}} \leq 20 \mathrm{~dB}, \mathrm{~V}_{\text {out }} \leq 1.0 \mathrm{~V}$ p-p |  | 300 |  | MHz |
| Gain Accuracy | Using 1\% resistor for $\mathrm{R}_{\mathrm{G}}, 0 \mathrm{~dB} \leq \mathrm{A}_{v} \leq 20 \mathrm{~dB}$ |  | $\pm 1$ |  | dB |
| Gain Supply Sensitivity | $V_{s} \pm 5 \%$ |  | . 06 |  | dB/V |
| Gain Temperature Sensitivity | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ |  | 4 |  | $\mathrm{mdB} /{ }^{\circ} \mathrm{C}$ |
| Slew Rate | $\mathrm{R}_{\mathrm{L}}=1 \mathrm{k} \Omega$, $\mathrm{V}_{\text {out }}=2 \mathrm{~V}$ step |  | 9 |  | V/ns |
|  | $\mathrm{R}_{\mathrm{L}}=200 \Omega, \mathrm{~V}_{\text {out }}=2 \mathrm{~V}$ step |  | 8 |  | V/ns |
| Settling Time | 2 V step to $1 \%$ |  | <2 |  | ns |
| Overdrive Recovery Time | $\mathrm{V}_{\text {IN }}=4 \mathrm{~V}$ to 0 V step, $\mathrm{V}_{\text {out }} \leq \pm 10 \mathrm{mV}$ |  | <3 |  | ns |
| Reverse Isolation (S12) |  |  | -80 |  | dB |
| INPUT/OUTPUT CHARACTERISTICS |  |  |  |  |  |
| Common-Mode Nominal |  |  | VCC/2 |  | V |
| Voltage Adjustment Range |  |  | 1.2 to 3.8 |  | V |
| Maximum Output Voltage Swing | 1 dB compressed |  | 6 |  | $\checkmark \mathrm{p}$-p |
| Output Common-Mode Offset | Referenced to VCC/2 | -100 |  | +20 | mV |
| Output Common-Mode Drift | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ |  | . 25 |  | $\mathrm{mV} /{ }^{\circ} \mathrm{C}$ |
| Output Differential Offset Voltage |  | -20 |  | +20 | mV |
| CMRR |  |  | 57 |  | dB |
| Output Differential Offset Drift | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ |  | . 15 |  | $\mathrm{mV} /{ }^{\circ} \mathrm{C}$ |
| Input Bias Current |  |  | $\pm 5$ |  |  |
| Input Resistance |  |  | 3 |  | k $\Omega$ |
| Input Capacitance (Single-Ended) |  |  | 0.9 |  | pF |
| Output Resistance |  |  | 100 |  | $\Omega$ |
| Output Capacitance |  |  | 3 |  | pF |
| POWER INTERFACE |  |  |  |  |  |
| Supply Voltage |  | 3 | 5 | 5.5 | V |
| ENB Threshold |  |  | 1.5 |  | V |
| ENB Input Bias Current | ENB at 3 V |  | 75 |  | nA |
|  | ENB at 0.6 V |  | -125 |  | $\mu \mathrm{A}$ |
| Quiescent Current | ENB at 3 V | 35 | 37 | 39 | mA |
|  | ENB at 0.6 V |  | 5.3 |  | mA |

## AD8352

## NOISE DISTORTION SPECIFICATIONS

$\mathrm{V}_{\mathrm{S}}=5 \mathrm{~V}, \mathrm{R}_{\mathrm{L}}=200 \Omega$ differential, $\mathrm{R}_{\mathrm{G}}=118 \Omega\left(\mathrm{~A}_{\mathrm{v}}=10 \mathrm{~dB}\right)$, $\mathrm{V}_{\text {out }}=2 \mathrm{~V}$ p-p composite, $\mathrm{T}=25^{\circ} \mathrm{C}$; parameters specified differentially, unless otherwise noted. $C_{D}$ and $R_{D}$ are selected for differential broadband operation (see Table 6 and Table 7).

Table 2.

| Parameter | Conditions | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 10 MHz <br> Second/Third Harmonic Distortion ${ }^{1}$ <br> Output Third-Order Intercept Third-Order IMD <br> Noise Spectral Density (RTI) <br> 1 dB Compression Point (RTO) | $\begin{aligned} & \mathrm{R}_{\mathrm{L}}=1 \mathrm{k} \Omega, \mathrm{~V}_{\text {out }}=2 \mathrm{~V} \text { p-p } \\ & \mathrm{R}_{\mathrm{L}}=200 \Omega, \mathrm{~V}_{\text {out }}=2 \mathrm{~V} \mathrm{p}-\mathrm{p} \\ & \mathrm{R}_{\mathrm{L}}=200 \Omega, f_{1}=9.5 \mathrm{MHz}, f_{2}=10.5 \mathrm{MHz} \\ & \mathrm{R}_{\mathrm{L}}=1 \mathrm{k} \Omega, f_{1}=9.5 \mathrm{MHz}, f_{2}=10.5 \mathrm{MHz}, \mathrm{~V}_{\text {out }}=2 \mathrm{~V} \text { p-p composite } \\ & \mathrm{R}_{\mathrm{L}}=200 \Omega, f_{1}=9.5 \mathrm{MHz}, f_{2}=10.5 \mathrm{MHz}, \mathrm{~V}_{\text {out }}=2 \mathrm{~V} \text { p-p composite } \end{aligned}$ |  | $\begin{aligned} & -88 /-95 \\ & -86 /-82 \\ & +38 \\ & -86 \\ & -81 \\ & +2.7 \\ & +15.7 \end{aligned}$ |  | dBc <br> dBc <br> dBm <br> dBc <br> dBc <br> $\mathrm{nV} / \sqrt{ } \mathrm{Hz}$ <br> dBm |
| 70 MHz <br> Second/Third HarmonicDistortion ${ }^{1}$ <br> Output Third-Order Intercept Third-Order IMD <br> Noise Spectral Density (RTI) 1 dB Compression Point (RTO) | $\begin{aligned} & \mathrm{R}_{\mathrm{L}}=1 \mathrm{k} \Omega, \mathrm{R}_{\mathrm{G}}=178 \Omega, \mathrm{~V}_{\text {OUT }}=2 \mathrm{~V} \text { p-p } \\ & \mathrm{R}_{\mathrm{L}}=200 \Omega, \mathrm{R}_{\mathrm{G}}=115 \Omega, \mathrm{~V}_{\text {OUT }}=2 \mathrm{~V} \mathrm{p}-\mathrm{p} \\ & \mathrm{R}_{\mathrm{L}}=200 \Omega f_{1}=69.5 \mathrm{MHz}, f_{2}=70.5 \mathrm{MHz} \\ & \mathrm{R}_{\mathrm{L}}=1 \mathrm{k} \Omega, f_{1}=69.5 \mathrm{MHz}, f_{2}=70.5 \mathrm{MHz}, \mathrm{~V}_{\text {out }}=2 \mathrm{~V} \text { p-p composite } \\ & \mathrm{R}_{\mathrm{L}}=200 \Omega, f_{1}=69.5 \mathrm{MHz}, f_{2}=70.5 \mathrm{MHz}, \mathrm{~V}_{\text {out }}=2 \mathrm{~V} \text { p-p composite } \end{aligned}$ |  | $\begin{aligned} & -83 /-84 \\ & -84 /-82 \\ & +40 \\ & -91 \\ & -83 \\ & +2.7 \\ & +15.7 \end{aligned}$ |  | dBc <br> dBc <br> dBm <br> dBc <br> dBc <br> $\mathrm{nV} / \sqrt{ } \mathrm{Hz}$ <br> dBm |
| 100 MHz <br> Second/Third Harmonic Distortion <br> Output Third-Order Intercept Third-Order IMD <br> Noise Spectral Density (RTI) 1 dB Compression Point (RTO) | $\begin{aligned} & \mathrm{R}_{\mathrm{L}}=1 \mathrm{k} \Omega, \mathrm{~V}_{\text {out }}=2 \mathrm{~V} \text { p-p } \\ & \mathrm{R}_{\mathrm{L}}=200 \Omega, \mathrm{~V}_{\text {out }}=2 \mathrm{~V} \text { p-p } \\ & \mathrm{R}_{\mathrm{L}}=200 \Omega, f_{1}=99.5 \mathrm{MHz}, f_{2}=100.5 \mathrm{MHz} \\ & \mathrm{R}_{\mathrm{L}}=1 \mathrm{k} \Omega, f_{1}=99.5 \mathrm{MHz}, f_{2}=100.5 \mathrm{MHz}, \mathrm{~V}_{\text {out }}=2 \mathrm{~V} \text { p-p composite } \\ & \mathrm{R}_{\mathrm{L}}=200 \Omega, f_{1}=99.5 \mathrm{MHz}, f_{2}=100.5 \mathrm{MHz}, \mathrm{~V}_{\text {out }}=2 \mathrm{~V} \text { p-p composite } \end{aligned}$ |  | $\begin{aligned} & -83 /-83 \\ & -84 /-82 \\ & +40 \\ & -91 \\ & -84 \\ & +2.7 \\ & +15.6 \end{aligned}$ |  | dBc <br> dBc <br> dBm <br> dBc <br> dBc <br> $\mathrm{nV} / \sqrt{ } \mathrm{Hz}$ <br> dBm |
| 140 MHz <br> Second/Third Harmonic Distortion ${ }^{2}$ <br> Output Third-Order Intercept <br> Third-Order IMD <br> Noise Spectral Density (RTI) <br> 1 dB Compression Point (RTO) | $\begin{aligned} & \mathrm{R}_{\mathrm{L}}=1 \mathrm{k} \Omega, \mathrm{~V}_{\text {out }}=2 \mathrm{~V} \text { p-p } \\ & \mathrm{R}_{\mathrm{L}}=200 \Omega, \mathrm{~V}_{\text {out }}=2 \mathrm{~V} \text { p-p } \\ & \mathrm{R}_{\mathrm{L}}=200 \Omega, f_{1}=139.5 \mathrm{MHz}, f_{2}=140.5 \mathrm{MHz} \\ & \mathrm{R}_{\mathrm{L}}=1 \mathrm{k} \Omega, f_{1}=139.5 \mathrm{MHz}, \mathrm{f}_{2}=140.5 \mathrm{MHz}, \mathrm{~V}_{\text {out }}=2 \mathrm{~V} \mathrm{p} \text {-p composite } \\ & \mathrm{R}_{\mathrm{L}}=200 \Omega, f_{1}=139.5 \mathrm{MHz}, f_{2}=140.5 \mathrm{MHz}, \mathrm{~V}_{\text {out }}=2 \mathrm{~V} \mathrm{p-p} \\ & \text { composite } \end{aligned}$ |  | $\begin{aligned} & -83 /-82 \\ & -82 /-84 \\ & +41 \\ & -89 \\ & -85 \\ & +2.7 \\ & +15.5 \end{aligned}$ |  | dBc <br> dBc <br> dBm <br> dBC <br> dBc <br> $\mathrm{nV} / \sqrt{ } \mathrm{Hz}$ <br> dBm |

[^0]$\mathrm{V}_{\mathrm{s}}=5 \mathrm{~V}, \mathrm{R}_{\mathrm{L}}=200 \Omega$ differential, $\mathrm{R}_{\mathrm{G}}=118 \Omega\left(\mathrm{Av}_{\mathrm{V}}=10 \mathrm{~dB}\right)$, Vout $=2 \mathrm{~V}$ p-p composite, $\mathrm{T}=25^{\circ} \mathrm{C}$; parameters specified differentially, unless otherwise noted. $C_{D}$ and $R_{D}$ are selected for differential broadband operation (see Table 6 and Table 7). See the Applications section for single-ended to differential performance characteristics.
Table 3.

| Parameter | Conditions | Min | Typ | Max | Unit |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 190 MHz <br> Second/Third Harmonic Distortion ${ }^{1}$ <br> Output Third-Order Intercept Third-Order IMD <br> Noise Spectral Density (RTI) 1 dB Compression Point (RTO) | $\begin{aligned} & \mathrm{R}_{\mathrm{L}}=1 \mathrm{k} \Omega, \mathrm{~V}_{\text {out }}=2 \mathrm{~V} \text { p-p } \\ & \mathrm{R}_{\mathrm{L}}=200 \Omega, \mathrm{~V}_{\text {out }}=2 \mathrm{~V} \text { p-p } \\ & \mathrm{R}_{\mathrm{L}}=200 \Omega, f_{1}=180.5 \mathrm{MHz}, f_{2}=190.5 \mathrm{MHz} \\ & \mathrm{R}_{\mathrm{L}}=1 \mathrm{k} \Omega, f_{1}=180.5 \mathrm{MHz}, f_{2}=190.5 \mathrm{MHz}, \mathrm{~V}_{\text {out }}=2 \mathrm{~V} \text { p-p composite } \\ & \mathrm{R}_{\mathrm{L}}=200 \Omega, f_{1}=180.5 \mathrm{MHz}, f_{2}=190.5 \mathrm{MHz}, \mathrm{~V}_{\text {out }}=2 \mathrm{~V} \text { p-p composite } \end{aligned}$ |  | $\begin{aligned} & -82 /-85 \\ & -81 /-87 \\ & +39 \\ & -83 \\ & -81 \\ & +2.7 \\ & +15.4 \\ & \hline \end{aligned}$ |  | dBc <br> dBc <br> dBm <br> dBc <br> dBc <br> $\mathrm{nV} / \sqrt{ } \mathrm{Hz}$ <br> dBm |
| 240 MHz <br> Second/Third Harmonic Distortion ${ }^{1}$ <br> Output Third-Order Intercept Third-Order IMD <br> Noise Spectral Density (RTI) 1 dB Compression Point (RTO) | $\begin{aligned} & \mathrm{R}_{\mathrm{L}}=1 \mathrm{k} \Omega, \mathrm{~V}_{\text {out }}=2 \mathrm{~V} \text { p-p } \\ & \mathrm{R}_{\mathrm{L}}=200 \Omega, \mathrm{~V}_{\text {out }}=2 \mathrm{~V} \mathrm{p} \text {-p } \\ & \mathrm{R}_{\mathrm{L}}=200 \Omega, f_{1}=239.5 \mathrm{MHz}, f_{2}=240.5 \mathrm{MHz} \\ & \mathrm{R}_{\mathrm{L}}=1 \mathrm{k} \Omega, f_{1}=239.5 \mathrm{MHz}, f_{2}=240.5 \mathrm{MHz}, \mathrm{~V}_{\text {out }}=2 \mathrm{~V} \text { p-p composite } \\ & \mathrm{R}_{\mathrm{L}}=200 \Omega, f_{1}=239.5 \mathrm{MHz}, f_{2}=240.5 \mathrm{MHz}, \mathrm{~V}_{\text {out }}=2 \mathrm{~V} \text { p-p composite } \end{aligned}$ |  | $\begin{aligned} & -82 /-76 \\ & -80 /-73 \\ & +36 \\ & -85 \\ & -77 \\ & +2.7 \\ & +15.3 \end{aligned}$ |  | dBc <br> dBc <br> dBm <br> dBc <br> dBc <br> $\mathrm{nV} / \sqrt{ } \mathrm{Hz}$ <br> dBm |
| 380 MHz <br> Second/Third Harmonic Distortion <br> Output Third-Order Intercept Third-Order IMD <br> Noise Spectral Density (RTI) 1 dB Compression Point (RTO) | $\begin{aligned} & \mathrm{R}_{\mathrm{L}}=1 \mathrm{k} \Omega, \mathrm{~V}_{\text {out }}=2 \mathrm{~V} \text { p-p } \\ & \mathrm{R}_{\mathrm{L}}=200 \Omega, \mathrm{~V}_{\text {out }}=2 \mathrm{~V} \mathrm{p-p} \\ & \mathrm{R}_{\mathrm{L}}=200 \Omega, f_{1}=379.5 \mathrm{MHz}, f_{2}=380.5 \mathrm{MHz} \\ & \mathrm{R}_{\mathrm{L}}=1 \mathrm{k} \Omega, f_{1}=379.5 \mathrm{MHz}, f_{2}=380.5 \mathrm{MHz}, \mathrm{~V}_{\text {out }}=2 \mathrm{~V} \text { p-p composite } \\ & \mathrm{R}_{\mathrm{L}}=200 \Omega, f_{1}=379.5 \mathrm{MHz}, f_{2}=380.5 \mathrm{MHz}, \mathrm{~V}_{\text {out }}=2 \mathrm{~V} \text { p-p composite } \end{aligned}$ |  | $\begin{aligned} & -72 /-68 \\ & -74 /-69 \\ & +33 \\ & -74 \\ & -70 \\ & +2.7 \\ & +14.6 \end{aligned}$ |  | dBc <br> dBc <br> dBm <br> dBc <br> dBc <br> $\mathrm{nV} / \sqrt{ } \mathrm{Hz}$ <br> dBm |
| 500 MHz <br> Second/Third Harmonic Distortion ${ }^{2}$ <br> Output Third-Order Intercept <br> Third-Order IMD <br> Noise Spectral Density (RTI) <br> 1 dB Compression Point (RTO) | $\begin{aligned} & \mathrm{R}_{\mathrm{L}}=200 \Omega, \mathrm{~V}_{\text {out }}=2 \mathrm{~V} \text { p-p } \\ & \mathrm{R}_{\mathrm{L}}=200 \Omega, f_{1}=499.5 \mathrm{MHz}, f_{2}=500.5 \mathrm{MHz} \\ & \mathrm{R}_{\mathrm{L}}=200 \Omega, f_{1}=499.5 \mathrm{MHz}, f_{2}=500.5 \mathrm{MHz}, \mathrm{~V}_{\text {out }}=2 \mathrm{~V} \text { p-p composite } \end{aligned}$ |  | $\begin{aligned} & -71 /-64 \\ & +28 \\ & -61 \\ & +2.7 \\ & +13.9 \end{aligned}$ |  | dBc <br> dBm <br> dBc <br> $\mathrm{nV} / \sqrt{ } \mathrm{Hz}$ <br> dBm |

[^1]
## ABSOLUTE MAXIMUM RATINGS

Table 4.

| Parameter | Rating |
| :--- | :--- |
| Supply Voltage VCC | 5.5 V |
| VIP, VIN | $\pm 5 \mathrm{~V}$ |
| Internal Power Dissipation | 210 mW |
| $\theta_{\mathrm{JA}}$ | $91.4^{\circ} \mathrm{C} / \mathrm{W}$ |
| Maximum Junction Temperature | $104^{\circ} \mathrm{C}$ |
| Operating Temperature Range | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ |
| Storage Temperature Range | $-65^{\circ} \mathrm{C}$ to $+150^{\circ} \mathrm{C}$ |
| Lead Temperature (Soldering 60 sec ) | $300^{\circ} \mathrm{C}$ |

Stresses above those listed under Absolute Maximum Ratings may cause permanent damage to the device. This is a stress rating only; functional operation of the device at these or any other conditions above those indicated in the operational section of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## ESD CAUTION

ESD (electrostatic discharge) sensitive device. Electrostatic charges as high as 4000 V readily accumulate on the human body and test equipment and can discharge without detection. Although this product features proprietary ESD protection circuitry, permanent damage may occur on devices subjected to high-energy electrostatic discharges. Therefore, proper ESD precautions are recommended to avoid performance degradation or loss of functionality.

## PIN CONFIGURATION AND FUNCTION DESCRIPTIONS



Table 5. Pin Function Descriptions

| Pin No. | Mnemonic | Description |
| :--- | :--- | :--- |
| 1 | RDP | Positive Distortion Adjust. |
| 2 | RGP | Positive Gain Adjust. |
| 3 | RGN | Negative Gain Adjust. |
| 4 | RDN | Negative Distortion Adjust. |
| 5 | VIN | Balanced Differential Input. Biased to VCM, typically ac-coupled. |
| $6,7,9,12$ | GND | Ground. Connect to low impedance GND. |
| 8,13 | VCC | Positive Supply. |
| 10 | VON | Balanced Differential Output. Biased to VCM, typically ac-coupled. |
| 11 | VOP | Balanced Differential Output. Biased to VCM, typically ac-coupled. |
| 14 | VCM | Common-Mode Voltage. A voltage applied to this pin sets the common-mode voltage of the input and output. |
|  |  | Typically decoupled to ground with a 0.1 $\mu$ F capacitor. With no reference applied, input and output common |
| 15 | mode floats to midsupply = VCC/2. |  |
| 16 | ENB | Enable. Apply positive voltage $(1.3 \mathrm{~V}$ < ENB < VCC) to activate device. |

## TYPICAL PERFORMANCE CHARACTERISTICS



Figure 4. Gain vs. Frequency for a 200 ת Differential Load with Baluns, $A_{v}=18 \mathrm{~dB}, 12 \mathrm{~dB}$, and 6 dB


Figure 5. Gain vs. Frequency for a $1 \mathrm{k} \Omega$ Differential Load with Baluns, $A_{v}=18 \mathrm{~dB}, 12 \mathrm{~dB}$, and 6 dB


Figure 6. Gain vs. Frequency for a $200 \Omega$ Differential Load Without Baluns, $R_{D} / C_{D}$ Open, $A_{v}=22 \mathrm{~dB}, 14 \mathrm{~dB}, 10 \mathrm{~dB}, 6 \mathrm{~dB}$, and 3 dB


Figure 7. Gain vs. Frequency for a $1 \mathrm{k} \Omega$ Differential Load Without Baluns, $R_{D} / C_{D}$ Open, $A v=25 d B, 14 d B, 10 d B, 6 d B$, and $3 d B$


Figure 8. Gain vs. Frequency over Temperature $\left(-40^{\circ} \mathrm{C},+25^{\circ} \mathrm{C},+85^{\circ} \mathrm{C}\right)$ Without Baluns, $A_{v}=10 \mathrm{~dB}, R_{L}=200 \Omega$ and $1 \mathrm{k} \Omega$


Figure 9. OIP3 vs. Frequency in dB, $2 \mathrm{~V} p$ - $p$ Composite, $R_{L}=200 \Omega$ $A_{v}=15 \mathrm{~dB}, 10 \mathrm{~dB}$, and 6 dB


Figure 10. Third-Order Harmonic Distortion HD3 vs. Frequency, $A_{v}=10 \mathrm{~dB}, R_{L}=200 \Omega$


Figure 11. Harmonic Distortion vs. Frequency for 2 V p-p into $R_{L}=200 \Omega$, $A_{V}=10 \mathrm{~dB}, R_{G}=115 \Omega, R_{D}=4.3 \mathrm{k} \Omega, C_{D}=0.2 \mathrm{pF}$


Figure 12. Harmonic Distortion vs. Frequency for $2 \mathrm{~V} p-p$ into $R_{L}=1 \mathrm{k} \Omega$,
$A_{v}=10 \mathrm{~dB}, 5 \mathrm{~V}$ Supply, $R_{G}=180 \Omega, R_{D}=6.8 \mathrm{k} \Omega, C_{D}=0.1 \mathrm{pF}$


Figure 13. Phase and Group Delay vs. Frequency, $A_{v}=10 \mathrm{~dB}, R_{L}=200 \Omega$


Figure 14. S11 Magnitude and Phase


Figure 15. S22 Magnitude and Phase


Figure 16 Large Signal Output Transient Response, $R_{L}=200 \Omega, A_{v}=10 \mathrm{~dB}$


Figure 17. 1\% Settling Time for a 2 V p-p Step Response, $A_{v}=10 \mathrm{~dB}, R_{L}=200 \Omega$


Figure 18. Noise Figure and Noise Spectral Density RTI vs. Frequency, $A_{V}=10 \mathrm{~dB}, R_{L}=200 \Omega$ and $1 \mathrm{k} \Omega$


Figure 19. CMRR vs. Frequency, $R_{L}=200 \Omega$ and $1 \mathrm{k} \Omega$, Differential Source Resistance

## APPLICATIONS

## GAIN AND DISTORTION ADJUSTMENT (DIFFERENTIAL INPUT)

Table 6 and Table 7 show the required value of $\mathrm{R}_{\mathrm{G}}$ for the gains specified at $200 \Omega$ and $1 \mathrm{k} \Omega$ loads. Figure 20 and Figure 22 plot $\mathrm{R}_{\mathrm{G}}$ vs. gain up to 18 dB for both load conditions. For other output loads ( $\mathrm{R}_{\mathrm{L}}$ ), use Equation 1 to compute gain vs. $\mathrm{R}_{\mathrm{G}}$.

$$
\begin{equation*}
A_{\text {VDifferential }}=\left(\frac{R_{G}+500}{\left(R_{G}+5\right)\left(R_{L}+53\right)+430}\right) R_{L} \tag{1}
\end{equation*}
$$

where:
$R_{L}=$ single-ended load.
$R_{G}=$ gain setting resistor.
The third-order harmonic distortion can be reduced by using external components $R_{D}$ and $C_{D}$. Table 6 and Table 7 show the required values for $R_{D}$ and $C_{D}$ vs. the specified gains to achieve (single tone) third-order distortion reduction at 180 MHz . Figure 21 and Figure 23 show $C_{D}$ vs. any gain (up to 18 dB ) for $200 \Omega$ and $1 \mathrm{k} \Omega$ loads, respectively. When these values are selected, they result in minimum single tone, third-order distortion at 180 MHz . This frequency point provides the best overall broadband distortion for the specified frequencies below and above this value. For applications above approximately $300 \mathrm{MHz}, \mathrm{C}_{\mathrm{D}}$ and $\mathrm{R}_{\mathrm{D}}$ are not required. See the Specifications section and third-order harmonic plots in the Typical Performance Characteristics section for more details.
$C_{D}$ can be further optimized for narrow-band tuning requirements below 180 MHz that result in relatively lower third-order (in-band) intermodulation distortion terms. See the Narrow-Band, Third-Order Intermodulation Cancellation section for more information. Though not shown, single tone, third-order optimization can also be improved for narrow-band frequency applications below 180 MHz with the proper selection of $C_{D}$, and 3 dB to 6 dB of relative third-order improvement can be realized at frequencies below approximately 140 MHz .

Using the information listed in Table 6 and Table 7, an extrapolated value for $\mathrm{R}_{\mathrm{D}}$ can be determined for loads between $200 \Omega$ and $1 \mathrm{k} \Omega$. For loads above $1 \mathrm{k} \Omega$, use the $1 \mathrm{k} \Omega R_{D}$ values listed in Table 7.

Table 6. Broadband Selection of $R_{G}, C_{D}$, and $R_{D}: 200 \Omega$ Load

| $\mathbf{A}_{\mathbf{V}}(\mathbf{d B})$ | $\mathbf{R}_{\mathbf{G}}(\mathbf{\Omega})$ | $\mathbf{C}_{\mathbf{D}}(\mathbf{p F})$ | $\mathbf{R}_{\mathbf{D}}(\mathbf{k} \boldsymbol{\Omega})$ |
| :--- | :--- | :--- | :--- |
| 3 | 390 | $0(\mathrm{DNP})$ | 6.8 |
| 6 | 220 | $0(\mathrm{DNP})$ | 4.3 |
| 9 | 140 | 0.1 | 4.3 |
| 10 | 115 | 0.2 | 4.3 |
| 12 | 86 | 0.3 | 4.3 |
| 15 | 56 | 0.6 | 4.3 |
| 18 | 35 | 1 | 4.3 |

Table 7. Broadband Selection of $R_{G}, C_{D}$, and $R_{D}: 1 \mathrm{k} \Omega$ Load

| $\mathbf{A}_{\mathbf{V}}(\mathbf{d B})$ | $\mathbf{R}_{\mathbf{G}}(\boldsymbol{\Omega})$ | $\mathbf{C}_{\mathbf{D}}(\mathbf{p F})$ | $\mathbf{R}_{\mathbf{D}}(\mathbf{k} \boldsymbol{\Omega})$ |
| :--- | :--- | :--- | :--- |
| 3 | 750 | 0 (DNP) | 6.8 |
| 6 | 360 | 0 (DNP) | 6.8 |
| 9 | 210 | 0 (DNP) | 6.8 |
| 10 | 180 | 0.05 | 6.8 |
| 12 | 130 | 0.1 | 6.8 |
| 15 | 82 | 0.3 | 6.8 |
| 18 | 54 | 0.5 | 6.8 |



Figure 20. $R_{G}$ vs. Gain, $R_{L}=200 \Omega$


Figure 21. CD vs. Gain, $R_{L}=200 \Omega$


Figure 22. $R_{G}$ vs. Gain, $R_{L}=1 \mathrm{k} \Omega$


Figure 23. $C_{D}$ vs. Gain, $R_{L}=1 \mathrm{k} \Omega$

## SINGLE-ENDED INPUT OPERATION

The AD8352 can be configured as a single-ended to differential amplifier as shown in Figure 24. To balance the outputs when driving only the VIP input, an external resistor $\left(\mathrm{R}_{\mathrm{N}}\right)$ of $200 \Omega$ is added between VIP and RGN. See Equation 2 to determine the single-ended input gain ( $\mathrm{A}_{\text {vsingle-ended }}$ ) for a given $\mathrm{R}_{\mathrm{G}}$ or $\mathrm{R}_{\mathrm{L}}$.

$$
\begin{equation*}
A_{\text {VSingle-ended }}=\left(\frac{R_{G}+500}{\left(R_{G}+5\right)\left(R_{L}+53\right)+430}\right) R_{L}+\frac{R_{L}}{R_{L}+30}(2) \tag{2}
\end{equation*}
$$

where:
$R_{L}=$ single-ended load.
$R_{G}=$ gain setting resistor.
Figure 25 plots gain vs. $\mathrm{R}_{\mathrm{G}}$ for $200 \Omega$ and $1 \mathrm{k} \Omega$ loads. Table 8 and Table 9 show the values of $C_{D}$ and $R_{D}$ required (for 180 MHz broadband third-order, single tone optimization) for $200 \Omega$ and $1 \mathrm{k} \Omega$ loads, respectively. This single-ended configuration provides -3 dB bandwidths similar to input differential drive. Figure 26 through Figure 28 show distortion levels at a gain of 12 dB for both $200 \Omega$ and $1 \mathrm{k} \Omega$ loads. Gains from 3 dB to 18 dB , using optimized $C_{D}$ and $R_{D}$ values, obtain similar distortion levels.


Figure 26. Single-Ended, Second-Order Harmonic Distortion, $200 \Omega$ Load

This broadband optimization was also performed at 180 MHz . As with differential input drive, the resulting distortion levels at lower frequencies are based on the $C_{D}$ and $R_{D}$ specified in Table 8 and Table 9. As with differential input drive, relative third-order reduction improvement at frequencies below 140 MHz are realized with proper selection of $C_{D}$ and $R_{D}$.


Figure 27. Single-Ended, Third-Order Harmonic Distortion, $200 \Omega$ Load


Figure 28. Single-Ended, Second-Order Harmonic Distortion, $1 \mathrm{k} \Omega$ Load


Figure 29. Single-Ended, Third-Order Harmonic Distortion, 1 k $\Omega$ Load
Table 8. Distortion Cancellation Selection Components ( $\mathrm{R}_{\mathrm{D}}$ and $\mathrm{C}_{\mathrm{D}}$ ) for Required Gain, $200 \Omega$ Load

| $\mathbf{A}_{\mathbf{V}}(\mathbf{d B})$ | $\mathbf{R}_{\mathbf{G}}(\mathbf{\Omega})$ | $\mathbf{C}_{\mathrm{D}}(\mathbf{p F})$ | $\mathbf{R}_{\mathbf{D}}(\mathbf{k} \boldsymbol{\Omega})$ |
| :--- | :--- | :--- | :--- |
| 3 | 4.3 k | $0(\mathrm{DNP})$ | 4.3 |
| 6 | 540 | $0(\mathrm{DNP})$ | 4.3 |
| 9 | 220 | 0.1 | 4.3 |
| 12 | 120 | 0.3 | 4.3 |
| 15 | 68 | 0.6 | 4.3 |
| 18 | 43 | 0.9 | 4.3 |

Table 9. Distortion Cancellation Selection Components ( $R_{D}$ and $C_{D}$ ) for Required Gain, $1 \mathrm{k} \Omega$ Load

| $\mathbf{A}_{\mathbf{V}}(\mathbf{d B})$ | $\mathbf{R}_{\mathbf{G}}(\mathbf{\Omega})$ | $\mathbf{C D}(\mathbf{p F})$ | $\mathbf{R}_{\mathbf{D}}(\mathbf{k} \boldsymbol{\Omega})$ |
| :--- | :--- | :--- | :--- |
| 6 | 3 k | $0(\mathrm{DNP})$ | 4.3 |
| 9 | 470 | $0($ DNP $)$ | 4.3 |
| 12 | 210 | 0.2 | 4.3 |
| 15 | 120 | 0.3 | 4.3 |
| 18 | 68 | 0.5 | 4.3 |

## NARROW-BAND, THIRD-ORDER INTERMODULATION CANCELLATION

Broadband, single tone, third-order harmonic optimization does not necessarily result in optimum (minimum) two tone, third-order intermodulation levels. The specified values for $C_{D}$ and $R_{D}$ in Table 6 and Table 7 were determined for minimizing broadband single tone, third-order levels.

Due to phase-related distortion coefficients, optimizing single tone, third-order distortion does not result in optimum in band ( $2 f_{1}-f_{2}$ and $2 f_{2}-f_{1}$ ), third-order distortion levels. By proper selection of $C_{D}$ (using a fixed $4.3 \mathrm{k} \Omega R_{D}$ ), IP 3 s of better than 45 dBm are achieved. This results in degraded out-of-band, third-order frequencies $\left(f_{2}+2 f_{1}, f_{1}+2 f_{2}, 3 f_{1}\right.$ and $\left.3 f_{2}\right)$. Thus, careful frequency planning is required to determine the tradeoffs.

Figure 30 shows narrow band ( 2 MHz spacing) OIP3 levels optimized at $32 \mathrm{MHz}, 70 \mathrm{MHz}, 100 \mathrm{MHz}$, and 180 MHz using the $C_{D}$ values specified in Figure 31. These four data points (the $C_{D}$ value and associated IP3 levels) are extrapolated to provide close estimates of IP3 levels for any specific frequency between 30 MHz and 180 MHz . For frequencies below approximately 140 MHz , narrow-band tuning of IP3 results in relatively higher IP3s (vs. the broadband results shown in Table 2 specifications). Though not shown, frequencies below 30 MHz also result in improved IP3s when using proper values for $\mathrm{C}_{\mathrm{D}}$.


Figure 30. Third-Order Intermodulation Distortion vs. Frequency for Various Gain Settings


Figure 31. Narrow-Band CD vs. Frequency for Various Gain Settings

## HIGH PERFORMANCE ADC DRIVING

The AD8352 provides the gain, isolation, and balanced low distortion output levels for efficiently driving wideband ADCs such as the AD9445.

Figure 32 and Figure 33 (single and differential input drive) illustrate the typical front-end circuit interface for the AD8352 differentially driving the AD9445 14-bit ADC at 105 MSPS. The AD8352, when used in the single-ended configuration shows little or no degradation in overall third-order harmonic performance (vs. differential drive). See the Single-Ended Input Operation section. The 100 MHz FFT plots shown in Figure 34 and Figure 35 display the results for the differential configuration. Though not shown, the single-ended third-order levels are similar.

The $50 \Omega$ resistor shown in Figure 32 provides a $50 \Omega$ differential input impedance to the source for matching considerations. When the driver is less than one eighth of the wavelength from the AD8352, impedance matching is not required thereby negating the need for this termination resistor. The output $24 \Omega$ resistors provide isolation from the analog-todigital input. Refer to the Layout and Transmission Line Effects section for more information. The circuit in Figure 33 represents a single-ended input to differential output configuration for driving the AD9445. In this case, the input $50 \Omega$ resistor with $\mathrm{R}_{\mathrm{N}}$ (typically $200 \Omega$ ) provide the input impedance match for a $50 \Omega$ system. Again, if input reflections are minimal, this impedance match is not required. A fixed $200 \Omega$ resistor $\left(R_{N}\right)$ is required to balance the output voltages that are required for second-order distortion cancellation. $\mathrm{R}_{\mathrm{G}}$ is the gain-setting resistor for the AD 8352 with the $\mathrm{R}_{\mathrm{D}}$ and $\mathrm{C}_{\mathrm{D}}$ components providing distortion cancellation. The AD9445 presents approximately $2 \mathrm{k} \Omega$ in parallel with $5 \mathrm{pF} /$ differential load to the AD8352 and requires a 2.0 V p-p differential signal $\left(\mathrm{V}_{\text {Ref }}=1 \mathrm{~V}\right)$ between VIN+ and VIN- for a full-scale output operation.

These AD8352 simplified circuits provide the gain, isolation, and distortion performance necessary for efficiently driving high linearity converters such as the AD9445. This device also provides balanced outputs whether driven differentially or single-ended, thereby maintaining excellent second-order distortion levels. Though at frequencies above approximately 100 MHz , due to phase related errors, single-ended, secondorder distortion is relatively higher. The output of the amplifier is ac-coupled to allow for an optimum common-mode setting at the ADC input. Input ac-coupling can be required if the source also requires a common-mode voltage that is outside the optimum range of the AD8352. A VCM common-mode pin is provided on the AD8352 that equally shifts both input and output common-mode levels. Increasing the gain of the AD8352 increases the system noise and, thus, decreases the SNR ( 3.5 dB at 100 MHz input for $\mathrm{Av}=10 \mathrm{~dB}$ ) of the AD9445 when no filtering is used. Note that amplifier gains from 3 dB to 18 dB , with proper selection of $C_{D}$ and $R_{D}$, do not appreciably affect distortion levels. These circuits, when configured properly, can result in SFDR performance of better than 87 dBc at 70 MHz and 82 dBc at 180 MHz input. Single-ended drive, with appropriate $C_{D}$ and $R_{D}$, give similar results for SFDR and third-order intermodulation levels shown in these figures.

Placing antialiasing filters between the ADC and the amplifier is a common approach for improving overall noise and broadband distortion performance for both band-pass and low-pass applications. For high frequency filtering, matching to the filter is required. The AD8352 maintains a $100 \Omega$ output impedance well beyond most applications and is well-suited to drive most filter configurations with little or no degradation in distortion.


Figure 32. Differential Input to the AD8352 Driving the AD9445


Figure 33. Single-Ended Input to the AD8352 Driving the AD9445


Figure 34. Single Tone Distortion AD8352 Driving AD9445, Encode Clock @ 105 MHz with Fc @ $100 \mathrm{MHz}\left(A_{v}=10 \mathrm{~dB}\right)$, See Figure 32


Figure 35. Two Tone Distortion AD8352 Driving AD9445, Encode Clock @ 105 MHz with Fc @ $100 \mathrm{MHz}\left(A_{v}=10 \mathrm{~dB}\right)$, Analog In $=98 \mathrm{MHz}$ and 101 MHz , See Figure 32

## LAYOUT AND TRANSMISSION LINE EFFECTS

High Q inductive drives and loads, as well as stray transmission line capacitance in combination with package parasitics, can potentially form a resonant circuit at high frequencies resulting in excessive gain peaking or possible oscillation. If RF transmission lines connecting the input or output are used, they should be designed such that stray capacitance at the I/O pins is minimized. In many board designs, the signal trace widths should be minimal where the driver/receiver is less than oneeighth of the wavelength from the AD8352. This non-transmission line configuration requires that underlying and adjacent ground and low impedance planes be far removed from the signal lines. In a similar fashion, stray capacitance should be minimized near the $R_{G}, C_{D}$, and $R_{D}$ components and associated traces. This also requires not placing low impedance planes near these components. Refer to the evaluation board layout (Figure 37 and Figure 38) for more information. Excessive stray capacitance at these nodes results in unwanted high frequency distortion. The $0.1 \mu \mathrm{~F}$ supply decoupling capacitors need to be close to the amplifier. This includes Signal Capacitor C2 through Signal Capacitor C5.

Parasitic suppressing resistors (R5, R6, R7, and R11) can be used at the device I/O pins. Use $25 \Omega$ series resistors (Size 0402) to adequately de-Q the input and output system from most parasitics without a significant decrease in gain. In general, if proper board layout techniques are used, the suppression resistors may not be required. Output Parasitic Suppression Resistor R7 and Output Parasitic Suppression Resistor R11 may be required for driving some switch cap ADCs. These suppressors, with Input $C$ of the converter (and possibly added External Shunt C), help provide charge kickback isolation and improve overall distortion at high encode rates.

## AD8352

## EVALUATION BOARD

An evaluation board is available for experimentation of various parameters such as gain, common-mode level, and distortion. The output network can be configured for different loads via minor output component changes. The schematic and evaluation board artwork are presented in Figure 36, Figure 37, and Figure 38. All discrete capacitors and resistors are Size 0402, except for C1 (3528-B).
Table 10. Evaluation Board Circuit Components and Functions

| Component | Name | Function | Additional Information |
| :---: | :---: | :---: | :---: |
| Pin 8 and Pin 13 | VCC | Supply VCC = +5 V. |  |
| Pin 6, Pin 7, <br> Pin 9 , $\operatorname{Pin} 12$ | GND | Connect to Low Impedance GND. |  |
| Pin 14, C9 | VCM, Capacitor | Common-Mode Offset Pin. Allows for monitoring or adjustment of the output common-mode voltage. C9 is a bypass capacitor. | $\mathrm{C} 9=0.1 \mu \mathrm{~F}$ |
| $\mathrm{R}_{\mathrm{D}} / \mathrm{C}_{\mathrm{D}}$ | Distortion <br> Tuning Components | Distortion Adjustment Components. Allows for third-order distortion adjustment HD3. | Typically, both are open above 300 MHz <br> $\mathrm{C}_{\mathrm{D}}=0.2 \mathrm{pF}, \mathrm{R}_{\mathrm{D}}=4.32 \mathrm{k} \Omega$ $\mathrm{C}_{\mathrm{D}}$ is Panasonic High Q (microwave) Multilayer Chip 402 capacitor |
| Pin 15, C8 | ENB, Capacitor | Enable. Apply positive voltage ( $1.3 \mathrm{~V}<\mathrm{ENB}<\mathrm{VCC}$ ) to activate device. Pull down to disable. Can be bypassed and float high ( 1.8 V ) for on state. C8 is a bypass capacitor. | Floats to 1.8 V to maintain device in power-up mode $\mathrm{C} 8=0.1 \mu \mathrm{~F}$ |
| $\begin{aligned} & \text { R1, R2, R3, R4, } \\ & \text { R5, R6, T2, C2, } \\ & \text { C3 } \end{aligned}$ | Resistors, Transformer, Capacitors | Input Interface. R1 and R4 ground one side of the differential drive interface for single-ended applications. T2 is a 1-to-1 impedance ratio balun to transform a single-ended input into a balanced differential signal. R2 and R3 provide a differential $50 \Omega$ input termination. R5 and R6 can be increased to reduce gain peaking when driving from a high source impedance. The $50 \Omega$ termination provides an insertion loss of 6 dB . C2 and C3 provide ac-coupling. | $\begin{aligned} & \mathrm{T} 2=\text { Macom }^{\text {TM }} \text { ETC1-1-13 } \\ & \mathrm{R} 1=\text { open, } \mathrm{R} 2=25 \Omega, \\ & \mathrm{R} 3=25 \Omega, \mathrm{R} 4=0 \Omega, \\ & \mathrm{R} 5=0 \Omega, \mathrm{R} 6=0 \Omega, \\ & \mathrm{C} 2=0.1 \mu \mathrm{~F}, \mathrm{C} 3=0.1 \mu \mathrm{~F} \end{aligned}$ |
| $\begin{aligned} & \text { R7, R8, R9, R11, } \\ & \text { R12, R13, R14, } \\ & \text { T1, C4, C5 } \end{aligned}$ | Resistors, Transformer, Capacitors | Output Interface. R13 and R14 ground one side of the differential output interface for single-ended applications. T1 is a 1 -to- 1 impedance ratio balun to transform a balanced differential signal to a single-ended signal. R8, R9, and R12 are provided for generic placement of matching components. R7 and R11 allow additional output series resistance when driving capacitive loads. The evaluation board is configured to provide a $150 \Omega$ to $50 \Omega$ impedance transformation with an insertion loss of 11.6 dB . C4 and C5 provide ac-coupling. R7 and R11 provide additional series resistance when driving capacitive loads. | $\begin{aligned} & \mathrm{T} 1=\text { Macom ETC1-1-13 } \\ & \mathrm{R} 7=0 \Omega, \mathrm{R} 8=86.6 \Omega, \\ & \mathrm{R} 9=57.6 \Omega, \\ & \mathrm{R} 11=0 \Omega, \mathrm{R} 12=86.6 \Omega, \\ & \mathrm{R} 13=0 \Omega, \mathrm{R} 14=\mathrm{open} \\ & \mathrm{C} 4=0.1 \mu \mathrm{~F}, \mathrm{C} 5=0.1 \mu \mathrm{~F} \end{aligned}$ |
| RG | Resistor | Gain Setting Resistor. Resistor $R_{G}$ is used to set the gain of the device. Refer to Table 6 and Table 7 when selecting the gain resistor. | $\mathrm{R}_{\mathrm{G}}=115 \Omega(\text { Size } 0402)$ <br> for a gain of 10 dB |
| C1, C6, C7 | Capacitors | Power Supply Decoupling. The supply decoupling consists of a $10 \mu \mathrm{~F}$ capacitor to ground. C6 and C7 are bypass capacitors. | $\begin{aligned} & C 1=10 \mu F \\ & C 6, C 7=0.1 \mu F \end{aligned}$ |
| Pin 14 | VCM | Common-Mode Offset Adjustment. Use Pin 14 to trim common-mode input/output levels. By applying a voltage to Pin 14, the input and output, common-mode voltage can be directly adjusted. | Typically decoupled to ground using a $0.1 \mu \mathrm{~F}$ capacitor with ac-coupled input/output ports |

## EVALUATION BOARD LOADING SCHEMES

The AD8352 evaluation board is characterized with two load configurations representing the most common ADC input resistance. The loads chosen are $200 \Omega$ and $1000 \Omega$ using a broadband resistive match. The loading can be changed via R8, R9, and R12 giving the flexibility to characterize the AD8352 evaluation board for the load in any given application. These loads are inherently lossy and thus must be accounted for in overall gain/loss for the entire evaluation board. Measure the gain of the AD8352 with an oscilloscope using the following procedure to determine the actual gain:

1. Measure the peak-to-peak voltage at the input node
(C2 or C3), and
2. Measure the peak-to-peak voltage at the output node (C4 or C5), then
3. Compute gain using the formula

Gain $=20 \log V_{\text {OUT }} / V_{\text {IN }}$

Table 11. Values Used for $200 \Omega$ and $1000 \Omega$ Loads

| Component | $\mathbf{2 0 0} \boldsymbol{\Omega}$ Load | $\mathbf{1 0 0 0} \boldsymbol{\Omega}$ Load |
| :--- | :--- | :--- |
| R8 | 86.6 | 487 |
| R9 | 57.6 | 51.1 |
| R12 | 86.6 | 487 |

## EVALUATION BOARD SCHEMATICS



Figure 36. Preliminary Characterization Board v.A01212A


Figure 37. Component Side Silk Screen


Figure 38. Far Side Showing Ground Plane Pull Back Around Critical Features

## AD8352

## OUTLINE DIMENSIONS



| ORDERING GUIDE | Temperature Range | Package Description | Package Option |
| :--- | :--- | :--- | :--- |
| Model | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 16 -Lead LFCSP_VQ | CP-16-3 |
| AD8352ACPZ-WP ${ }^{1}$ | $-40^{\circ} \mathrm{C}$ to $+85^{\circ} \mathrm{C}$ | 16-Lead LFCSP_VQ, $7^{\prime \prime}$ Tape and Reel | CP-16-3 |
| AD8352ACPZ-R7 ${ }^{1}$ | Evaluation Board |  |  |
| AD8352-EVAL |  |  |  |

${ }^{1} \mathrm{Z}=\mathrm{Pb}$-free part.


[^0]:    ${ }^{1}$ When using the evaluation board at frequencies below 50 MHz , replace the Output Balun T1 with a transformer such as Mini-Circuits ${ }^{\circledR}$ ADT1-1WT to obtain the low frequency balance required for differential HD2 cancellation.
    ${ }^{2} C_{D}$ and $R_{D}$ can be optimized for broadband operation below 180 MHz . For operation above $300 \mathrm{MHz}, C_{D}$ and $R_{D}$ components are not required.

[^1]:    ${ }^{1}$ When using the evaluation board at frequencies below 50 MHz , replace the Output Balun T1 with a transformer such as Mini-Circuits ADT1-1WT to obtain the low frequency balance required for differential HD2 cancellation.
    ${ }^{2} C_{D}$ and $R_{D}$ can be optimized for broadband operation below 180 MHz . For operation above $300 \mathrm{MHz}, C_{D}$ and $R_{D}$ components are not required.

