Ordering number : ENN7193

Monolithic Digital IC



LB1941T

Constant Current Forward/Reverse Driver IC for Digital Cameras

Overview

The LB1941T is a single-channel forward/reverse driver IC that provides a constant current control function. Its low-saturation output makes it appropriate for voice coil motor control, and it is optimal for use as the shutter driver IC in digital cameras.

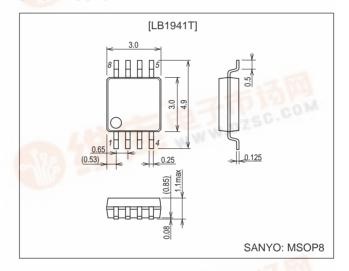
Functions and Features

- Constant current control ($I_O = 400 \text{ mA}$ when $R_f = 0.5 \Omega$)
- Ultraminiature package (MSOP8: 150 mil)
- · Built-in thermal protection circuit
- Includes a rapid charge/rapid discharge circuit for stable shutter operation.
- Built-in reference voltage circuit (0.2 V typical) WWW.DZSC.COM

Package Dimensions

unit: mm

3245A-MSOP8



Specifications

Absolute Maximum Ratings at Ta = 25°C

Parameter	Symbol	Conditions	Ratings	Unit
Maximum supply voltage	V _{CC} max	COM	-0.3 to +10.5	V
Output current	I _O max		600	mA
Output applied voltage	V _O max		-0.3 to V _{CC} + 0.3	V
Input applied voltage	V _{IN} max	IN1, IN2	-0.3 to +10.5	V
Allowable power dissipation	Pd max	Mounted on a specified board.*	400	mW
Operating temperature	Topr		-20 to +75	°C
Storage temperature	Tstg		-55 to +150	°C

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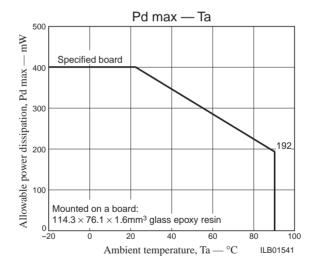
Allowable Operating Range at $Ta = 25^{\circ}C$

Parameter	Symbol	Conditions	Ratings	Unit
Function-guaranteed voltage range VOPR			2.5 to 10	V
Constant-current set range	I _{OUT}	Set with RFG-GND resistance	50 to 500	mA
Input low level voltage V _{IL}		IN1, IN2	-0.3 to +0.5	V
Input high level voltage	V _{IH}	IN1, IN2	2.0 to 10	V

Electrical Characteristics at $Ta = 25^{\circ}C$

Doromotor	0	0 111	Ratings			11.3	
Parameter	Symbol Conditions		min	typ	max	Unit	
Standby Current dissipation	ISTB	V _{CC} = 8.5 V	_	_	1.0	μA	
[Constant-current H bridge drive circuit]							
Outrot saturation will	V _O (sat)1	V _{CC} = 3 V, I _O = 200 mA (Upper + Lower side)	_	0.20	0.35	.,	
Output saturation voltage	V _O (sat)2	V _{CC} = 4 V, I _O = 400 mA (Upper + Lower side)	_	0.50	0.70	V	
Output constant current	I _{OUT}	$V_{CC} = 4 \text{ V}, \text{ R}_{L} = 3 \Omega, \text{ RF} = 0.5 \Omega$	375	400	424	mA	
Temperature dependence of output constant current (reference Ta = 25°C)	Δl _O	$V_{CC} = 4 \text{ V}, R_L = 3 \Omega, RF = 0.5 \Omega^*$ (Ta = -10 to +60°C)	-2	_	+2	%	
Operating current dissipation		$V_{CC} = 4 \text{ V}, R_L = 0 \Omega \text{ (No load, full drive)}$	_	14	21	mA	
Thermal protection operating temperature TSD		*	150	180	210	°C	
[Control input circuit]							
Control nin movimum input ourrent	I _{IH}	V _{IH} = 5.5 V, V _{CC} = 5.5 V	_	80	100		
Control pin maximum input current	I _{IL}	V _{IL} = GND	-1	_	0	μA	

Note*: Design guarantee: Characteristics shown here are design targets and measurement with independent unit is not made before shipment.



Truth Table

	Input		Output		Mode
	IN1	IN2	OUT1	OUT2	iviode
	L	L	OFF	OFF	Standby 1*
	Н	L	Н	L	Forward rotation
Г	L	Н	L	Н	Reverse rotation
Г	Н	Н	OFF	OFF	Standby 2*

Cautions for use

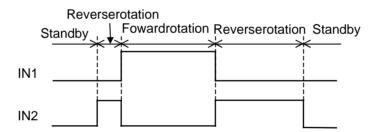
Standby states 1 and 2 in the above truth table differ as follows:

Standby state 1All circuits in IC are not operating and the current dissipation is almost zero.

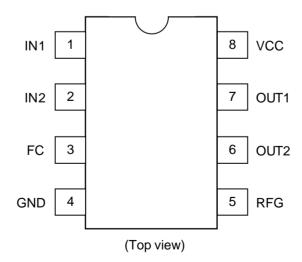
Standby state 2The constant-current control amplifier output in IC is in the full drive condition. Both OUT1 and OUT2 are OFF. The current dissipation is a few mA.

During mode transfer from the standby state 1 to forward (reverse) rotation, the current rises from the output current zero condition to the required constant current value. On the other hand, during mode transfer from the standby state 2 to forward (reverse) rotation, full drive is applied once to the output, then the current lowers to the required current value.

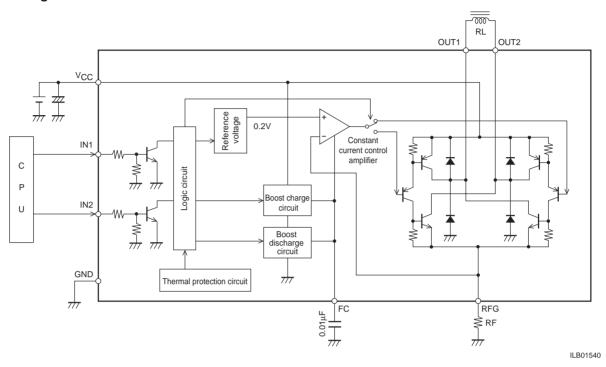
Therefore, select the standby 1 state when putting IC in the standby state. A typical drive sequence is shown in the figure below.



Pin Assignment



Block Diagram



[Boost charge and discharge circuits]

In order to keep the output response time constant during mode transfer from the standby state to forward (reverse) rotation, this IC incorporates boost charge and discharge circuits for external capacitor connected to the FC pin.

The external capacitor connected to the FC pin is for output phase compensation (to suppress oscillation), for which $0.01 \text{ to } 0.1 \text{ }\mu\text{F}$ is recommended. Note that increase in the capacitor value results in increase in the time necessary for the constant current control to rise.

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