# MC34C87

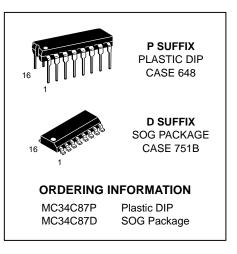
## Product Preview Quad EIA-422-A Line Driver CMOS

The MC34C87 is a quad differential line driver designed for digital data transmission over balanced lines. The MC34C87 meets all the requirements of standard EIA–422–A while retaining the low–power characteristics of CMOS.

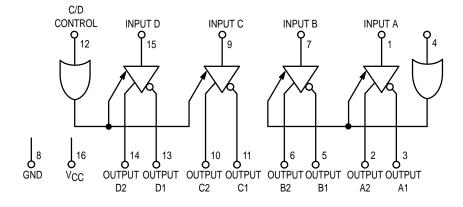
The MC34C87 accepts TTL or CMOS input levels and translates these to EIA–422–A output level. This part uses special output circuitry that enables the individual drivers to power down without loading down the bus. The MC34C87 also includes special circuitry which will set the outputs to a high impedance mode during power up or down, preventing spurious glitches. Each enable pin controls two drivers.

The MC34C87 is pin compatible with the MC3487. All pins are protected against damage due to electrostatic discharges.

- Maximum Power Supply Current: 3 mA
- 2000 V ESD Protection on the Inputs and the Outputs
- TTL/CMOS Input Compatible
- Typical Propagation Delay: 6 ns
- Typical Output Skew: 1 ns
- Meets V<sub>O</sub> = 6.0 V (and V<sub>O</sub> = -0.25 V), V<sub>CC</sub> = 0 V, I<sub>O</sub> < 100  $\mu$ A Requirement
- Operation from Single 5 V Supply
- High Impedance Mode for Outputs Connected to System Buses



### BLOCK DIAGRAM



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REV 3 1993

### **TRUTH TABLE**

Control Input	Input	Non–Inverting Output	Inverting Output
L	Х	Z	Z
Н	Н	Н	L
Н	L	L	Н

X = Don't Care Z = High Impedance H = High Logic State L = Low Logic State

MAXIMUM RATINGS

#### Rating Symbol Value Unit V **Power Supply Voltage** 7 Vcc V **DC Input Voltage** Vin – 1.5 to V<sub>CC</sub> + 1.5 - 0.5 to V<sub>CC</sub> + 0.5 V DC Output Voltage\* Vout DC Output Current, per Pin mΑ lout 150 DC V<sub>CC</sub> or GND Current, per Pin IDD 150 mΑ Storage Temperature - 65 to + 150 °C Tstg **Power Dissipation** PD 500 mW ESD (Human Body Model) 2000 V

This device contains circuitry to protect the inputs against damage due to high static voltages or electric fields; however, it is advised that normal precautions be taken to avoid applications of any voltage higher than the maximum rated voltages to this high impedance circuit.

For proper operation it is recommended that  $V_{in}$  and  $V_{out}$  be constrained to the range  $V_{SS} \leq (V_{in} \text{ or } V_{out}) \leq V_{DD}$ . Reliability of operation is enhanced if unused inputs are tied to and appropriate logic voltage level (e.g., either  $V_{SS}$  or  $V_{DD}$ ).

\* Power-on conditions.

### **OPERATING CONDITIONS**

Rating	Symbol	Min	Мах	Unit
Power Supply Voltage	VCC	4.5	5.5	V
DC Input Voltage	V <sub>in</sub>	0	VCC	V
Operating Temperature Range	TA	- 40	+ 85	°C
Input Rise and Fall Time	t <sub>r</sub> , t <sub>f</sub>	_	500	ns

## DC CHARACTERISTICS (V\_{CC} = 4.5 to 5.5 V, T\_A = -40 to + 85°C, unless otherwise stated)

Parameter	5	Symbol	Min	Тур	Мах	Unit
Input Voltage (Low Logic State)		VIL	—	_	0.8	V
Input Voltage (High Logic State)		VIH	2.0	—	_	V
Output Voltage (Low Logic State) I <sub>SINK</sub> = 20 mA		VOL	—	0.3	0.5	V
Output Voltage (High Logic State) I <sub>SOURCE</sub> = - 20 mA		VOH	2.5	2.8	_	V
Output Differential Voltage $R_L = 100 \Omega$ (Note 1)		V <sub>OD</sub>	2.0	—	_	V
Output Differential Voltage Difference $R_L = 100 \Omega$ (Note 1)		D(V <sub>OD</sub> )	—	—	± 0.4	V
Output Offset Voltage $R_L = 100 \Omega$ (Note 1)		VOS	—	—	3.0	V
Output Offset Voltage Difference $R_L = 100 \Omega$ (Note 1)		D(V <sub>OS</sub> )	—	—	± 0.4	V
Input Current V <sub>in</sub> = V <sub>CC</sub> , GND, V <sub>IH</sub> or V <sub>IL</sub>		l <sub>in</sub>	—	—	± 1.0	μA
Quiescent Supply Current I <sub>Out</sub> = 0 μA		ICC	—	—	3.0	mA
Output Short Circuit Current (Note 2)		los	- 30	- 100	- 150	mA
Output Leakage Current (High–Z State) Vout = VCC or GND		IO(Z)	—	—	± 1.0	μΑ
	/ <sub>out</sub> = 6 V = - 0.25 V	l <sub>oxh</sub> I <sub>oxl</sub>	_	_	100 - 100	μΑ

NOTES:

1. See EIA specifications EIA-422-A for exact test conditions.

2. Only one output may be shorted at a time.

AC CHARACTERISTICS (V<sub>CC</sub> = 4.5 to 5.5 V,  $T_A$  = – 40 to + 85°C, unless otherwise stated)

Parameter	Symbol	Min	Тур	Max	Unit
Propagation Delay Input to Output (S1 Open)	<sup>t</sup> PLH <sup>t</sup> PHL	_	6	12	ns
Output Skew (S1 Open)*	Skew	—	1.0	4	ns
Differential Output Rise Time Fall Time (S1 Open)	ttlH ttHL	_	4	8	ns
Output Enable Time (S1 Closed)	<sup>t</sup> PZH <sup>t</sup> PZL	_	16 15	_	ns
Output Disable Time (S1 Closed)	<sup>t</sup> PHZ <sup>t</sup> PLZ		6 9		ns

\* Skew: difference in propagation delays between complementary outputs.

AC TEST CIRCUIT AND SWITCHING TIME WAVEFORMS

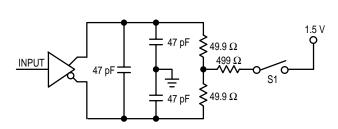
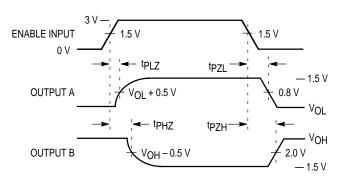
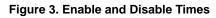


Figure 1. AC Test Circuit





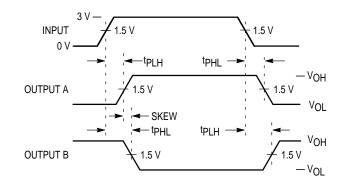


Figure 2. Propagation Delays and Skew Waveforms

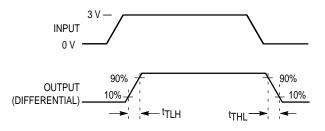
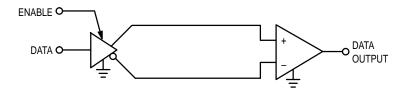
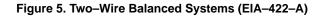


Figure 4. Differential Rise and Fall Times

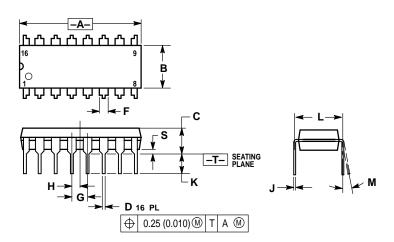
**TYPICAL APPLICATIONS** 





**P SUFFIX** PLASTIC DIP CASE 648-08

**D SUFFIX** SOG PACKAGE CASE 751B-05

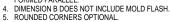


NOTES:

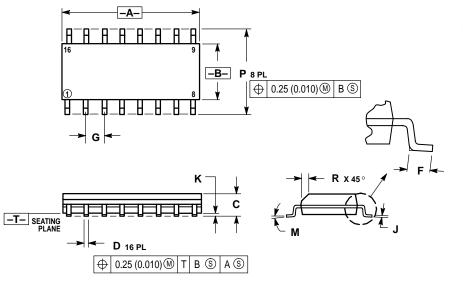
1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.

CONTROLLING DIMENSION: INCH. 2 3

DIMENSION L TO CENTER OF LEADS WHEN FORMED PARALLEL



	INC	HES	MILLIMETERS		
DIM	MIN	MIN MAX		MAX	
Α	0.740	0.770	18.80	19.55	
В	0.250	0.270	6.35	6.85	
С	0.145	0.175	3.69	4.44	
D	0.015	0.021	0.39	0.53	
F	0.040	0.70	1.02	1.77	
G	0.100 BSC		2.54 BSC		
Н	0.050 BSC		1.27 BSC		
J	0.008	0.015	0.21	0.38	
Κ	0.110	0.130	2.80	3.30	
L	0.295	0.305	7.50	7.74	
М	0°	10 °	0°	10 °	
S	0.020	0.040	0.51	1.01	



NOTES

- DIMENSIONING AND TOLERANCING PER ANSI 1. Y14.5M, 1982. CONTROLLING DIMENSION: MILLIMETER.
- 2. 3 DIMENSIONS A AND B DO NOT INCLUDE MOLD PROTRUSION.
- MAXIMUM MOLD PROTRUSION 0.15 (0.006) PER SIDE. 4.
- DIMENSION D DOES NOT INCLUDE DAMBAR 5. PROTRUSION ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.127 (0.005) TOTAL IN EXCESS OF THE D DIMENSION AT MAXIMUM MATERIAL CONDITION.

	MILLIMETERS		INCHES	
DIM	MIN	MAX	MIN	MAX
Α	9.80	10.00	0.386	0.393
В	3.80	4.00	0.150	0.157
C	1.35	1.75	0.054	0.068
D	0.35	0.49	0.014	0.019
F	0.40	1.25	0.016	0.049
G	1.27	BSC	0.050 BSC	
J	0.19	0.25	0.008	0.009
K	0.10	0.25	0.004	0.009
М	0 °	7°	0°	7°
Р	5.80	6.20	0.229	0.244
R	0.25	0.50	0.010	0.019

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