INTEGRATED CIRCUITS

DATA SHEET

For a complete data sheet, please also download:

- The IC04 LOCMOS HE4000B Logic Family Specifications HEF, HEC
- The IC04 LOCMOS HE4000B Logic Package Outlines/Information HEF, HEC

HEF4052B MSI

Dual 4-channel analogue multiplexer/demultiplexer

Product specification
File under Integrated Circuits, IC04

January 1995





Dual 4-channel analogue multiplexer/demultiplexer

HEF4052B MSI

DESCRIPTION

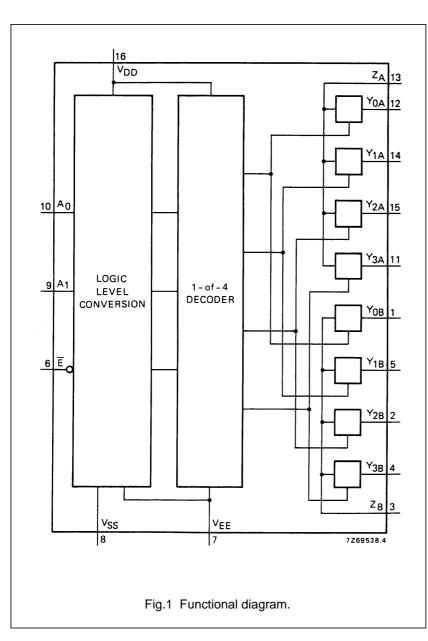
The HEF4052B is a dual 4-channel analogue multiplexer/demultiplexer with common channel select logic. Each multiplexer/demultiplexer has four independent inputs/outputs $(Y_0 \text{ to } Y_3)$ and a common input/output (Z). The common channel select logic includes two address inputs $(A_0 \text{ and } A_1)$ and an active LOW enable input (\overline{E}) .

Both multiplexers/demultiplexers contain four bidirectional analogue switches, each with one side connected to an independent input/output (Y_0 to Y_3) and the other side connected to a common input/output (Z).

With \overline{E} LOW, one of the four switches is selected (low impedance ON-state) by A_0 and A_1 . With \overline{E} HIGH, all switches are in the high impedance OFF-state, independent of A_0 and A_1 .

 V_{DD} and V_{SS} are the supply voltage connections for the digital control inputs $(A_0,\,A_1$ and $\overline{E}).$ The V_{DD} to V_{SS} range is 3 to 15 V. The analogue inputs/outputs $(Y_0$ to $Y_3,$ and Z) can swing between V_{DD} as a positive limit and V_{EE} as a negative limit. $V_{DD}-V_{EE}$ may not exceed 15 V.

For operation as a digital multiplexer/demultiplexer, V_{EE} is connected to V_{SS} (typically ground).



PINNING

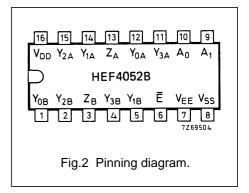
 $\begin{array}{ll} Y_{0\text{A}} \text{ to } Y_{3\text{A}} & \text{independent inputs/outputs} \\ Y_{0\text{B}} \text{ to } Y_{3\text{B}} & \text{independent inputs/outputs} \end{array}$

A₀, A₁ address inputs

E enable input (active LOW)
Z_A, Z_B common inputs/outputs

FAMILY DATA, I_{DD} LIMITS category MSI

See Family Specifications



HEF4052BP(N): 16-lead DIL; plastic

(SOT38-1)

HEF4052BD(F): 16-lead DIL; ceramic

(cerdip)

(SOT74)

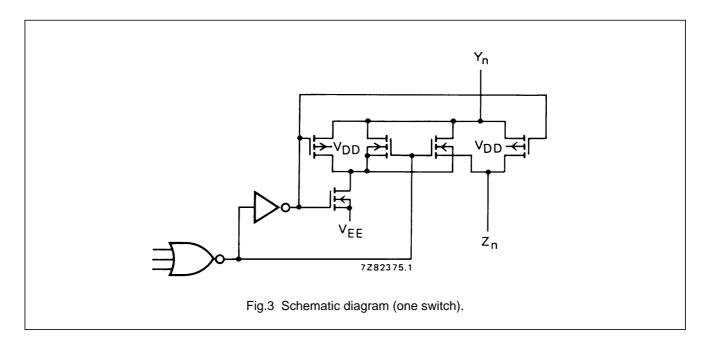
HEF4052BT(D): 16-lead SO; plastic

(SOT109-1)

(): Package Designator North America

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FUNCTION TABLE

INPUTS			CHANNEL		
Ē	A ₁	A ₀	ON		
L	L	L	Y _{0A} –Z _A ; Y _{0B} –Z _B		
L	L	Н	$Y_{1A}-Z_{A}; Y_{1B}-Z_{B}$		
L	Н	L	$Y_{2A}-Z_{A}; Y_{2B}-Z_{B}$		
L	Н	Н	$Y_{3A}-Z_A; Y_{3B}-Z_B$		
Н	Х	X	none		

Notes

1. H = HIGH state (the more positive voltage)

L = LOW state (the less positive voltage)

X = state is immaterial

RATINGS

Limiting values in accordance with the Absolute Maximum System (IEC 134)

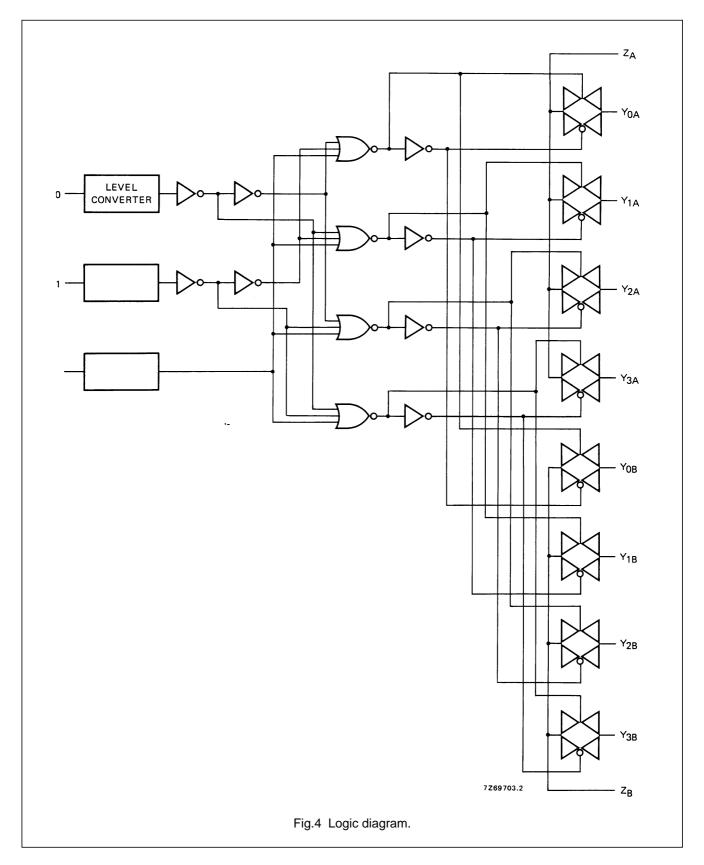
Supply voltage (with reference to V_{DD}) V_{EE} -18 to + 0,5 V

Note

To avoid drawing V_{DD} current out of terminal Z, when switch current flows into terminals Y, the voltage drop across
the bidirectional switch must not exceed 0,4 V. If the switch current flows into terminal Z, no V_{DD} current will flow out
of terminals Y, in this case there is no limit for the voltage drop across the switch, but the voltages at Y and Z may
not exceed V_{DD} or V_{EE}.

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DC CHARACTERISTICS

 T_{amb} = 25 °C

	V _{DD} -V _{EE}	SYMBOL	TYP.	MAX.		CONDITIONS
	5		350	2500	Ω	V 0. V V
ON resistance	10	R _{ON}	80	245	Ω	$V_{is} = 0$ to $V_{DD} - V_{EE}$ see Fig.6
	15		60	175	Ω	1 ig.0
	5		115	340	Ω	V 0
ON resistance	10	R _{ON}	50	160	Ω	V _{is} = 0 see Fig.6
	15		40	115	Ω	19.0
	5		120	365	Ω	W W
ON resistance	10	R _{ON}	65	200	Ω	$V_{is} = V_{DD} - V_{EE}$ see Fig.6
	15		50	155	Ω	19.0
'Δ' ON resistance	5		25	_	Ω	V 045 V V
between any two	10	ΔR_{ON}	10	_	Ω	$V_{is} = 0$ to $V_{DD} - V_{EE}$ see Fig.6
channels	15		5	_	Ω	19.0
OFF-state leakage	5		-	_	nA	
current, all	10	l _{OZZ}	_	_	nA	E at V _{DD}
channels OFF	15		-	1000	nA	
OFF-state leakage	5		_	_	nA	
current, any	10	I _{OZY}	_	_	nA	E at V _{SS}
channel	15		_	200	nA	

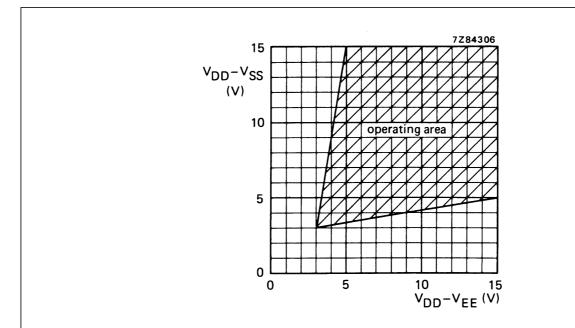
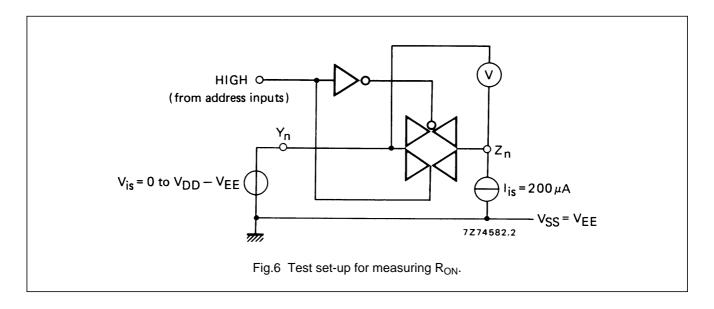
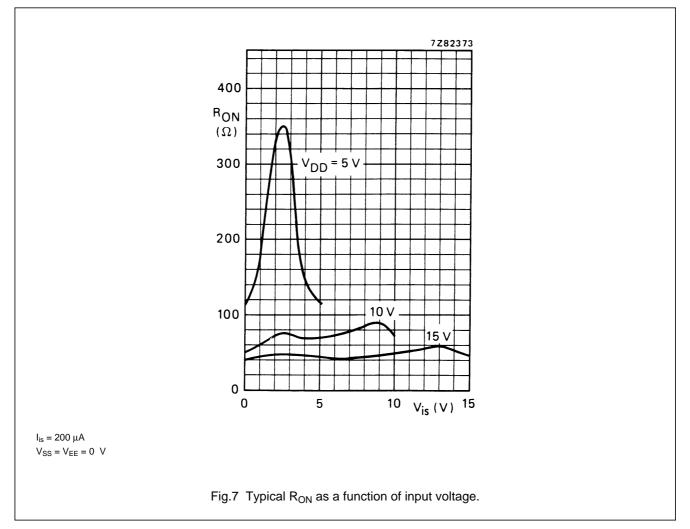


Fig.5 Operating area as a function of the supply voltages.

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AC CHARACTERISTICS

 V_{EE} = V_{SS} = 0 V; T_{amb} = 25 °C; input transition times \leq 20 ns

	V _{DD}	TYPICAL FORMULA FOR P (μW)	
Dynamic power	5	1 300 $f_i + \sum (f_0 C_L) \times V_{DD}^2$	where
dissipation per	10	6 100 $f_i + \sum (f_o C_L) \times V_{DD}^2$	f _i = input freq. (MHz)
package (P)	15	15 600 $f_i + \sum (f_0 C_L) \times V_{DD}^2$	f _o = output freq. (MHz)
			C _L = load capacitance (pF)
			$\Sigma(f_0C_L)$ = sum of outputs
			V _{DD} = supply voltage (V)

AC CHARACTERISTICS

 V_{EE} = V_{SS} = 0 V; T_{amb} = 25 $^{\circ}C;$ input transition times \leq 20 ns

	V _{DD}	SYMBOL	TYP.	MAX.		
Propagation delays						
$V_{is} \rightarrow V_{os}$	5		10	20	ns	
HIGH to LOW	10	t _{PHL}	5	10	ns	note 1
	15		5	10	ns	
	5		10	20	ns	
LOW to HIGH	10	t _{PLH}	5	10	ns	note 1
	15		5	10	ns	
$A_n \rightarrow V_{os}$	5		150	305	ns	
HIGH to LOW	10	t _{PHL}	65	135	ns	note 2
	15		50	100	ns	
	5		150	300	ns	
LOW to HIGH	10	t _{PLH}	75	150	ns	note 2
	15		50	100	ns	
Output disable times						
$\overline{E} o V_{os}$	5		95	190	ns	
HIGH	10	t _{PHZ}	90	180	ns	note 3
	15		90	180	ns	
	5		100	205	ns	
LOW	10	t _{PLZ}	90	180	ns	note 3
	15		90	180	ns	
Output enable times						
$\overline{E} \to V_{os}$	5		130	260	ns	
HIGH	10	t _{PZH}	55	115	ns	note 3
	15		45	85	ns	
	5		120	240	ns	
LOW	10	t _{PZL}	50	100	ns	note 3
	15		35	75	ns	

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	V _{DD}	SYMBOL	TYP.	MAX.		
Distortion, sine-wave	5		0,25	%	,	
response	10		0,04	%	,	note 4
	15		0,04	%	,	
Crosstalk between	5		_	М	Hz	
any two channels	10		1	M	Hz	note 5
	15		_	M	Hz	
Crosstalk; enable	5		_	m	٧	
or address input	10		50	m	V	note 6
to output	15		_	m	V	
OFF-state	5		_	М	Hz	
feed-through	10		1	M	Hz	note 7
	15		_	M	Hz	
ON-state frequency	5		13	М	Hz	
response	10		40	M	Hz	note 8
	15		70	M	Hz	

Notes

Vis is the input voltage at a Y or Z terminal, whichever is assigned as input.

 V_{os} is the output voltage at a Y or Z terminal, whichever is assigned as output.

- 1. $R_L = 10 \text{ k}\Omega$ to V_{EE} ; $C_L = 50 \text{ pF}$ to V_{EE} ; $\overline{E} = V_{SS}$; $V_{is} = V_{DD}$ (square-wave); see Fig.8.
- 2. $R_L = 10 \text{ k}\Omega$; $C_L = 50 \text{ pF to V}_{EE}$; $\overline{E} = V_{SS}$; $A_n = V_{DD}$ (square-wave); $V_{is} = V_{DD}$ and R_L to V_{EE} for t_{PLH} ; $V_{is} = V_{EE}$ and R_L to V_{DD} for t_{PHL} ; see Fig.8.
- 3. $R_L = 10 \text{ k}\Omega$; $C_L = 50 \text{ pF to } V_{EE}$; $\overline{E} = V_{DD}$ (square-wave);
 - $V_{is} = V_{DD}$ and R_L to V_{EE} for t_{PHZ} and t_{PZH} ;
 - V_{is} = V_{EE} and R_L to V_{DD} for t_{PLZ} and t_{PZL} ; see Fig.8.
- 4. $R_L = 10 \text{ k}\Omega$; $C_L = 15 \text{ pF}$; channel ON; $V_{is} = \frac{1}{2} V_{DD \text{ (p-p)}}$ (sine-wave, symmetrical about $\frac{1}{2} V_{DD}$); $f_{is} = 1 \text{ kHz}$; see Fig.9.
- 5. $R_L = 1 \text{ k}\Omega$; $V_{is} = \frac{1}{2} V_{DD (p-p)}$ (sine-wave, symmetrical about $\frac{1}{2} V_{DD}$);

$$20 \log \frac{V_{os}}{V_{is}} = -50 \text{ dB}$$
; see Fig. 10.

- 6. $R_L = 10 \text{ k}\Omega$ to V_{EE} ; $C_L = 15 \text{ pF}$ to V_{EE} ; \overline{E} or $A_n = V_{DD}$ (square-wave); crosstalk is $|V_{os}|$ (peak value); see Fig.8.
- 7. $R_L = 1 \text{ k}\Omega$; $C_L = 5 \text{ pF}$; channel OFF; $V_{is} = \frac{1}{2} V_{DD (p-p)}$ (sine-wave, symmetrical about $\frac{1}{2} V_{DD}$);

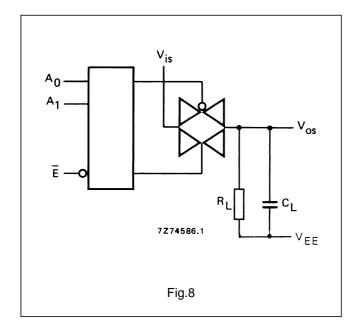
$$20 \log \frac{V_{os}}{V_{is}} = -50 \text{ dB; see Fig. 9.}$$

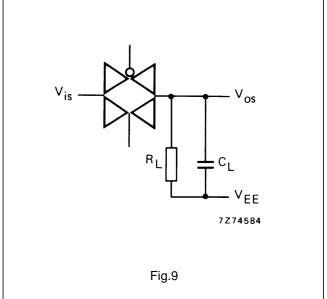
8. $R_L = 1 \text{ k}\Omega$; $C_L = 5 \text{ pF}$; channel ON; $V_{is} = \frac{1}{2} V_{DD \text{ (p-p)}}$ (sine-wave, symmetrical about $\frac{1}{2} V_{DD}$);

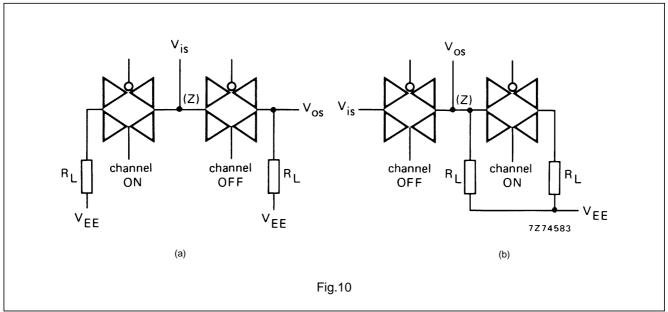
$$20 \log \frac{V_{os}}{V_{is}} = -3 \text{ dB; see Fig. 9.}$$

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APPLICATION INFORMATION

Some examples of applications for the HEF4052B are:

- Analogue multiplexing and demultiplexing.
- Digital multiplexing and demultiplexing.
- Signal gating.

NOTE

If break before make is needed, then it is necessary to use the enable input.

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