捷多邦,专业PCB打**塔N75ALS470章SN75ALS170A**TRIPLE DIFFERENTIAL BUS TRANSCEIVER

DW PACKAGE

(TOP VIEW)

SLLS055D - AUGUST 1987 - REVISED SEPTEMBER 1995

- Three Bidirectional Transceivers
- Driver Meets or Exceeds ANSI Standard EIA/TIA-422-B and RS-485 and ITU Recommendation V.11
- Two Skew Limits Available
- Designed to Operate Up to 20 Million Data Transfers per Second (FAST-20 SCSI)
- High-Speed Advanced Low-Power Schottky Circuitry
- Designed for Multipoint Transmission on Long Bus Lines in Noisy Environments
- Wide Positive and Negative Input/Output Bus Voltage Ranges
- Driver Output Capacity . . . ±60 mA
- Thermal Shutdown Protection
- Driver Positive- and Negative-Current Limiting
- Receiver Input Impedances . . . 12 kΩ Min
- Receiver Input Sensitivity . . . ±300 mV Max
- Receiver Input Hysteresis . . . 60 mV Typ
- Operate From a Single 5-V Supply
- Glitch-Free Power-Up and Power-Down Protection
- Feature Independent Direction Controls for Each Channel

1D 19 1 1A 1DIR [2 NC 3 18 NC GND I 4 17 NC NC [16 □ v_{cc} 2D ∏ **∏** 2B 6 15 2DIR **∏** 7 14 1 2A NC [] 8 13**∏** 3B

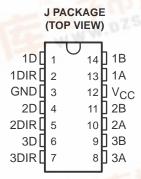
NC - No internal connection

12**∏** 3A

11 ∏ NC

3D **1** 9

3DIR **1** 10



description

The SN75ALS170 and SN75ALS170A triple differential bus transceivers are monolithic integrated circuits designed for bidirectional data communication on multipoint bus transmission lines. It is designed for balanced transmission lines and the driver meets ANSI Standards EIA/TIA-422-B and RS-485 and both the driver and receiver meet ITU Recommendation V.11. The SN75ALS170A is designed for FAST-20 SCSI and can transmit or receive data pulses as short as 30 ns with a maximum skew of 5 ns.

The SN75ALS170 and SN75ALS170A operate from a single 5-V power supply. The drivers and receivers have active-high and active-low enables, respectively, which are internally connected together to function as a direction control. The driver differential outputs and the receiver differential inputs are connected internally to form differential input/output (I/O) bus ports that are designed to offer minimum loading to the bus when the driver is disabled or $V_{CC} = 0$. These ports feature wide positive and negative common-mode voltage ranges making the device suitable for party-line applications.

The SN75ALS170 and the SN75ALS170A are characterized for operation from 0°C to 70°C.

AVAILABLE OPTIONS

| SKEW LIMIT | PART NUMBER | | | | | |
|------------|---------------|-------------|--|--|--|--|
| 10 ns | SN75ALS170DW | SN75ALS170J | | | | |
| 5 ns | SN75ALS170ADW | | | | | |

Please be aware that an important notice concerning availability, standard warranty, and use in critical applications of Texas Instruments semiconductor products and disclaimers thereto appears at the end of this data sheet.



Function Tables

EACH DRIVER

| INPUT | DIR | OUT | PUTS |
|-------|-----|-----|------|
| D | DIK | Α | В |
| Н | Н | Н | L |
| L | Н | L | Н |
| Х | L | Z | Z |

EACH RECEIVER

| DIFFERENTIAL INPUTS A – B | DIR | OUTPUT R |
|---|-----|-------------|
| V _{ID} ≥ 0.3 V | L | Н |
| $-0.3 \text{ V} < \text{V}_{\text{ID}} < 0.3 \text{ V}$ | L | ? |
| $V_{ID} \le -0.3 V$ | L | L |
| X | Н | Z |
| Open | L | Н |

H = high level, L = low level, ? = indeterminate,

X = irrelevant, Z = high impedance (off)

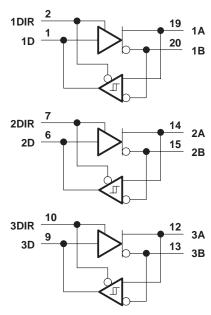
logic symbol†

1DIR ∇ ΕN \triangleright 1D ∇ ΕN 1 ┰ ∇ \triangleright 2DIR ΕN ∇ 2D ∇ ΕN 1 ┚ ∇ 3DIR ____ EN ∇ 3A \triangleright 3D ∇ ΕN 1 ┚

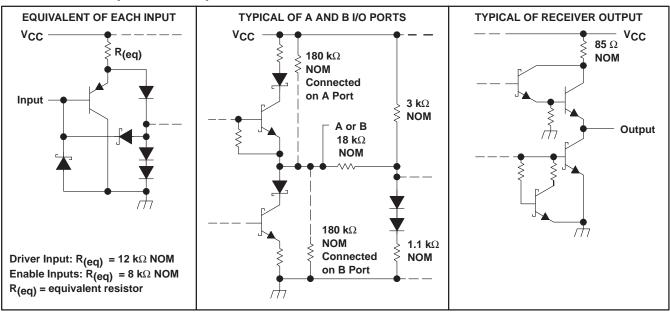
† This symbol is in accordance with ANSI/IEEE Std 91-1984 and IEC Publication 617-12.

Pin numbers shown are for the DW package.

logic diagram (positive logic)



schematics of inputs and outputs



absolute maximum ratings over operating free-air temperature range (unless otherwise noted)†

| Supply voltage, V _{CC} (see Note 1) | 7 V |
|--|------------------------------|
| Voltage range at any bus terminal | |
| Enable input voltage, V _I | 5.5 V |
| Continuous total power dissipation | See Dissipation Rating Table |
| Operating free-air temperature range, T _A | 0°C to 70°C |
| Storage temperature range, T _{Stq} | –65°C to 150°C |
| Lead temperature 1,6 mm (1/16 inch) from case for 10 seconds: DW package | |
| Lead temperature 1,6 mm (1/16 inch) from case for 60 seconds: J package | 300°C |

[†] Stresses beyond those listed under "absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under "recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

NOTE 1: All voltage values, except differential I/O bus voltage, are with respect to network ground terminal.

DISSIPATION RATING TABLE

| PACKAGE | PACKAGE T _A ≤ 25°C POWER RATING | | T _A = 70°C POWER RATING |
|---------|---|-----------|---------------------------------------|
| DW | 1125 mW | 9.0 mW/°C | 720 mW |
| J | 1025 mW | 8.2 mW/°C | 656 mW |



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recommended operating conditions

| | | | MIN | TYP | MAX | UNIT |
|--|------------------------|----|------|-----|------|------|
| Supply voltage, V _{CC} | | | 4.75 | 5 | 5.25 | V |
| Voltage at any bus terminal (separately or o | ommon modo). Vi or Vio | | | | 12 | V |
| voltage at any bus terminal (separately of c | ommon mode), vi or viC | | | | -7 | V |
| High-level input voltage, V _{IH} | D, DIR | | 2 | | | V |
| Low-level input voltage, V _{IL} | D, DIR | | | | 0.8 | V |
| Differential input voltage, V _{ID} (see Note 2) | | | | | ±12 | V |
| High-level output current, IOH | Driver | | | | -60 | mA |
| night-level output current, IOH | Receiver | | | | -400 | μΑ |
| Low lovel output outropt lov | Driver | | | | 60 | mA |
| Low-level output current, IOL | 12 -7 | ША | | | | |
| Operating free-air temperature, TA | | · | 0 | | 70 | °C |

NOTE 2: Differential-input/output bus voltage is measured at the noninverting terminal A with respect to the inverting terminal B.

DRIVER SECTION

electrical characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

| | PARAMETER | TEST CONI | TEST CONDITIONS [†] | | гүр‡ | MAX | UNIT |
|-------------------|---|---|--|-------------------------------|------|------------|------|
| ۷ıK | Input clamp voltage | I _I = -19 mA | | | | -1.5 | V |
| ٧o | Output voltage | IO = 0 | | 0 | | 6 | V |
| Vон | High-level output voltage | V _{CC} = 4.75 V, V _{IL} = 0.8 V, | V _{IH} = 2 V, I _{OH} = -55 mA | 2.7 | | | V |
| V _{OL} | Low-level output voltage | V _{CC} = 4.75 V, V _{IL} = 0.8 V, | V _{IH} = 2 V, I _{OL} = 55 mA | | | 1.7 | V |
| V _{OD1} | Differential output voltage | IO = 0 | | 1.5 | | 6 | V |
| V _{OD2} | Differential output voltage | R _L = 100 Ω, | See Figure 1 | 1/2 V _{OD1} or 2§ | | | V |
| | | $R_L = 54 \Omega$, | See Figure 1 | 1.5 | 2.5 | 5 | V |
| V _{OD3} | Differential output voltage | $V_{\text{test}} = -7 \text{ V to } 12 \text{ V},$ | See Figure 2 | 1.5 | | 5 | V |
| Δ V _{OD} | Change in magnitude of differential output voltage¶ | | | | | ±0.2 | V |
| Voc | Common-mode output voltage | $R_1 = 540 \Omega \text{ or } 100 \Omega,$ | See Figure 1 | | | 3 | V |
| Δ V _{OC} | Change in magnitude of common-mode output voltage¶ | ⁻ | | | | -1 ±0.2 | V |
| | | Output disabled, | V _O = 12 V | | | 1 | |
| IO | Output current | See Note 3 | V _O = -7 V | | | -0.8 | mA |
| lн | High-level input current | V _I = 2.4 V | • | | | 20 | μΑ |
| I _{IL} | Low-level input current | V _I = 0.4 V | | | | -400 | μΑ |
| | | V _O = -6 V | | | | -250 | |
| l. | | V _O = 0 | | | | -150 | 0 |
| los | Short-circuit output current | VO = VCC | | | | 250 | mA |
| | | V _O = 8 V | | | | 250 | |
| la a | Cumply current | Notood | Outputs enabled | | 69 | 90 | A |
| Icc | Supply current | No load | Outputs disabled | | 57 | 78 | mA |

[†] The power-off measurement in ANSI Standard EIA/TIA-422-B applies to disabled outputs only and is not applied to combined inputs and outputs.

NOTE 3: This applies for both power on and off; refer to EIA Standard RS-485 for exact conditions. The EIA/TIA-422-B limit does not apply for a combined driver and receiver terminal.



[‡] All typical values are at $V_{CC} = 5 \text{ V}$ and $T_A = 25^{\circ}\text{C}$.

[§] The minimum V_{OD2} with a 100- Ω load is either 1/2 V_{OD1} or 2 V, whichever is greater.

[¶] Δ | VOD | and Δ | VOC | are the changes in magnitude of VOD and VOC respectively, that occur when the input is changed from a high level to a

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switching characteristics over recommended ranges of supply voltage and operating free-air temperature (unless otherwise noted)

| PARAMETER | | | TEST CONDITIONS | | MIN | TYP† | MAX | UNIT |
|---------------------|---|--|---|---|-----|------|------|------|
| | | ALS170 | $R_L = 54 \Omega$, | C _L = 50 pF, | 3 | 8 | 13 | |
| | | ALS170A | T _A =25°C, | See Figure 3 | 5.5 | 8 | 10.5 | |
| td(OD) | t _{d(OD)} Differential output delay time | ALS170 | $R_{L1} = R_{L3} = 165 \Omega,$ $C_{L} = 60 \text{ pF},$ | $R_{L2} = 75 \Omega,$ $T_A = 25^{\circ}C,$ | 3 | 8 | 13 | ns |
| | | ALS170A | See Figure 4 | тд =25 О, | 5.5 | 8 | 10.5 | |
| | District | | $R_L = 54 \Omega$, See Figure 3 | $C_L = 50 \text{ pF},$ | | 1 | 5 | ns |
| t _{sk(p)} | Pulse skew [‡] | $R_{L1} = R_{L3} = 165 \Omega$, $C_{L} = 60 pF$, | | R_{L2} = 75 Ω, See Figure 4 | | 1 | 5 | ns |
| | | ALS170 | $R_L = 54 \Omega$ | $C_L = 50 \text{ pF},$ | | | 10 | |
| | Skew limit§ | ALS170A | See Figure 3 | | | | 5 | no |
| tsk(lim) | Skew IIIIIII3 | ALS170 | $R_{L1} = R_{L3} = 165 \Omega$, | $R_{L2} = 75 \Omega$, | | | 10 | ns |
| | | ALS170A | $C_L = 60 \text{ pF},$ | See Figure 4 | | | 5 | |
| t.(05) | Differential output transition time | | $R_L = 54 \Omega$, See Figure 3 | C _L = 50 pF, | 3 | 8 | 13 | no |
| t _t (OD) | Differential-output transition time | | $R_{L1} = R_{L3} = 165 \Omega$, $C_{L} = 60 pF$, | R_{L2} = 75 Ω, See Figure 4 | 3 | 8 | 13 | ns |

SYMBOL EQUIVALENTS

| DATA SHEET PARAMETER | EIA/TIA-422-B | RS-485 |
|----------------------|--|--|
| Vo | V_{oa} , V_{ob} | V_{oa}, V_{ob} |
| V _{OD1} | VO | VO |
| VOD2 | $V_t (R_L = 100 \Omega)$ | $V_t (R_L = 54 \Omega)$ |
| V _{OD3} | | V _t (Test Termination Measurement 2) |
| V _{test} | | V_{tst} |
| Δ V _{OD} | $ \vee_t - \overline{\vee}_t $ | $ \vee_t - \overline{\vee}_t $ |
| Voc | Vos | V _{os} |
| Δ V _{OC} | $ V_{OS} - \overline{V}_{OS} $ | $ V_{OS} - \overline{V}_{OS} $ |
| los | I _{sa} , I _{sb} | |
| IO | I _{xa} , I _{xb} | I _{ia} , I _{ib} |

[†] All typical values are at V_{CC} = 5 V and T_A = 25°C.
‡ Pulse skew is defined as the |t_d(ODH)-t_d(ODL)| of each channel.
§ Skew limit is the maximum difference in propagation delay times between any two channels of one device and between any two devices. This parameter is applicable at one V_{CC} and operating temperature within the recommended operating conditions.

RECEIVER SECTION

electrical characteristics over recommended ranges of common-mode input voltage, supply voltage, and operating free-air temperature (unless otherwise noted)

| | PARAMETER | TEST CO | TEST CONDITIONS | | TYP [†] | MAX | UNIT |
|------------------|---|--|---------------------------|-------|------------------|------|------|
| VIT+ | Positive-going input threshold voltage | $V_0 = 2.7 V$, | $I_{O} = -0.4 \text{ mA}$ | | | 0.3 | V |
| VIT- | Negative-going input threshold voltage | $V_0 = 0.5 V$, | IO = 8 mA | -0.3‡ | | | V |
| V _{hys} | Hysteresis voltage (V _{IT+} - V _{IT-}) | | | | 60 | | mV |
| VIK | Enable-input clamp voltage | I _I = -18 mA | | | | -1.5 | V |
| Vон | High-level output voltage | V _{ID} = 300 mV, See Figure 5 | $I_{OH} = -400 \mu A,$ | 2.7 | | | V |
| VOL | Low-level output voltage | V _{ID} = −300 mV, See Figure 5 | I _{OL} = 8 mA, | | | 0.45 | V |
| | High impedance state output ourrent | V _O = 2.4 V | | | | 20 | |
| loz | High-impedance-state output current | V _O = 0.4 V | | | | -400 | μΑ |
| 1. | Line input current | Other input = 0, | V _I = 12 V | | | 1 | mA |
| <u> </u> | Line input current | See Note 4 | $V_I = -7 V$ | | | -0.8 | IIIA |
| l _{IH} | High-level enable-input current | V _{IH} = 2.7 V | | | | 20 | μΑ |
| I _{IL} | Low-level enable-input current | V _{IL} = 0.4 V | | | | -100 | μΑ |
| rı | Input resistance | | | 12 | | | kΩ |
| los | Short-circuit output current | V _{ID} = 300 mV, | V _O = 0 | -15 | | -85 | mA |
| laa | Supply ourrent | Madaad | Outputs enabled | | 69 | 90 | mA |
| Icc | Supply current | No load | Outputs disabled | | 57 | 78 | IIIA |

 $^{^{\}dagger}$ All typical values are at V_{CC} = 5 V and T_A = 25°C.

NOTE 4: This applies for both power on and off; refer to EIA Standard RS-485 for exact conditions.

switching characteristics over recommended ranges of supply voltage and operating free-air temperature range

| | PARAMETER | | TEST CONDITIONS | MIN | TYP | MAX | UNIT |
|----------------------|---|---------|--|------|-----|------|------|
| tou | Propagation delay time, low-to-high-level | ALS170 | | 9 | | 19 | ns |
| ^t PLH | output | ALS170A | $V_{ID} = -1.5 \text{ V to } 1.5 \text{ V},$ $C_L = 15 \text{ pF}, \qquad T_A = 25^{\circ}\text{C},$ | 11.5 | | 16.5 | 115 |
| | Propagation delay time, high-to-low-level | ALS170 | See Figure 6 | 9 | | 19 | no |
| ^t PHL | - output A | ALS170A | | 11.5 | | 16.5 | ns |
| 4 | Pulse skew§ | ALS170 | | | 2 | 6 | |
| tsk(p) | Pulse skews | ALS170A | $V_{ID} = -1.5 \text{ V to } 1.5 \text{ V},$ | | | 5 | ns |
| t \ | Skew limit¶ | ALS170 | C _L = 15 pF, See Figure 6 | | | 10 | ns |
| ^t sk(lim) | Skew III III. I | ALS170A | | | | 5 | 115 |

 $^{^{\}dagger}$ All typical values are at V_{CC} = 5 V and T_A = 25°C.



[‡] The algebraic convention, in which the less-positive (more-negative) limit is designated minimum, is used in this data sheet for common-mode input voltage and threshold voltage levels only.

[§] Pulse skew is defined as the |tpLH-tpHL| of each channel.

Skew limit is the maximum difference in propagation delay times between any two channels of one device and between any two devices. This parameter is applicable at one V_{CC} and operating temperature within the recommended operating conditions.

PARAMETER MEASUREMENT INFORMATION

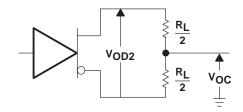


Figure 1. Driver V_{OD} and V_{OC}

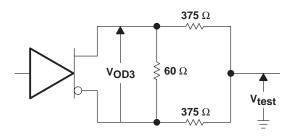
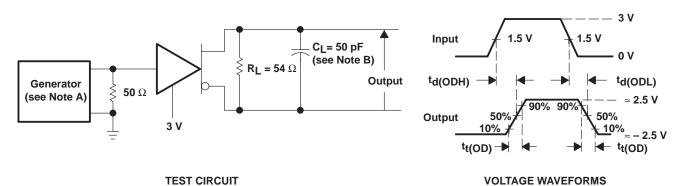


Figure 2. Driver V_{OD3}



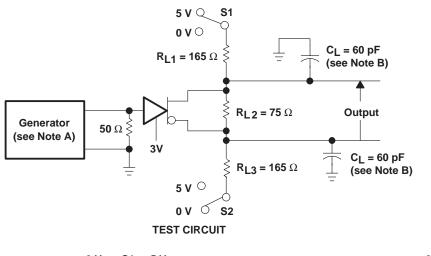
NOTES: A. The input pulse is supplied by a generator having the following characteristics: PRR \leq 1 MHz, 50% duty cycle, $t_f \leq$ 6 ns, $t_f \leq$ 7 ns, $t_f \leq$ 8 ns, $t_f \leq$ 8 ns, $t_f \leq$ 8 ns, $t_f \leq$ 9 ns, t_f

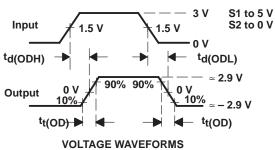
B. CL includes probe and jig capacitance.

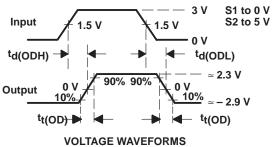
Figure 3. Driver Test Circuit and Voltage Waveforms



PARAMETER MEASUREMENT INFORMATION







NOTES: A. The input pulse is supplied by a generator having the following characteristics: PRR \leq 1 MHz, 50% duty cycle, $t_f \leq$ 6 ns, $t_f \leq$ 8 ns, $t_f \leq$ 8 ns, $t_f \leq$ 9 ns, t_f

B. C_I includes probe and jig capacitance.

Figure 4. Driver Test Circuit and Voltage Waveforms With Double-Differential-SCSI Termination for the Load

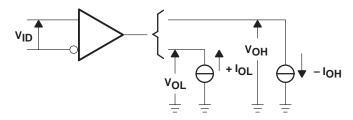
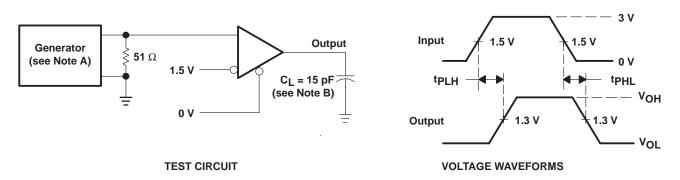


Figure 5. Receiver VOH and VOL

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PARAMETER MEASUREMENT INFORMATION

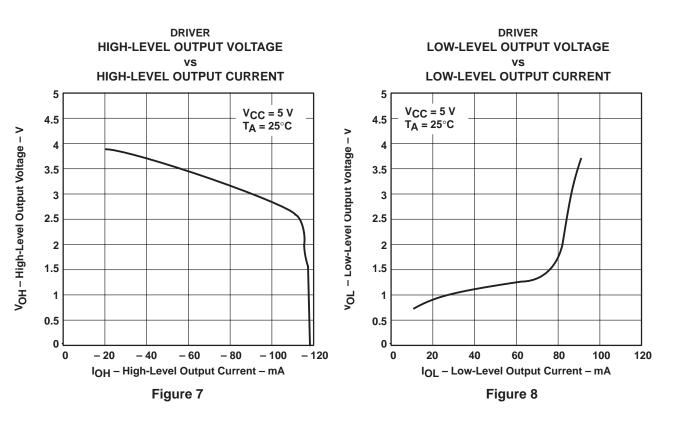


NOTES: A. The input pulse is supplied by a generator having the following characteristics: PRR \leq 1 MHz, 50% duty cycle, $t_f \leq$ 6 ns, $t_f \leq$ 8 ns, $t_f \leq$ 8 ns, $t_f \leq$ 9 ns, t_f

B. CL includes probe and jig capacitance.

Figure 6. Receiver Test Circuit and Voltage Waveforms

TYPICAL CHARACTERISTICS





TYPICAL CHARACTERISTICS

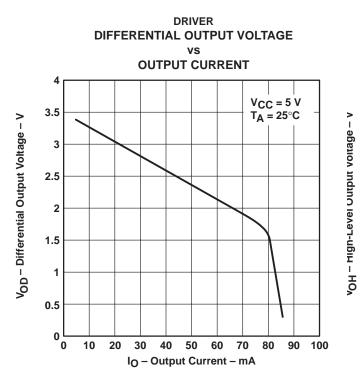
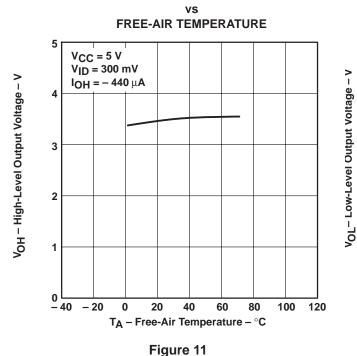


Figure 9

RECEIVER

HIGH-LEVEL OUTPUT VOLTAGE



RECEIVER
HIGH-LEVEL OUTPUT VOLTAGE
VS
HIGH-LEVEL OUTPUT CURRENT

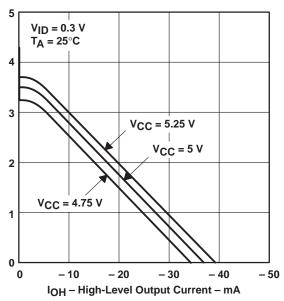


Figure 10

RECEIVER LOW-LEVEL OUTPUT VOLTAGE vs LOW-LEVEL OUTPUT CURRENT

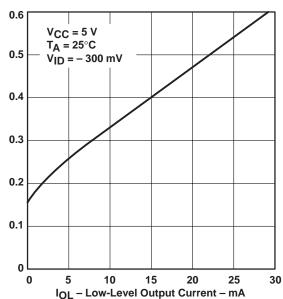
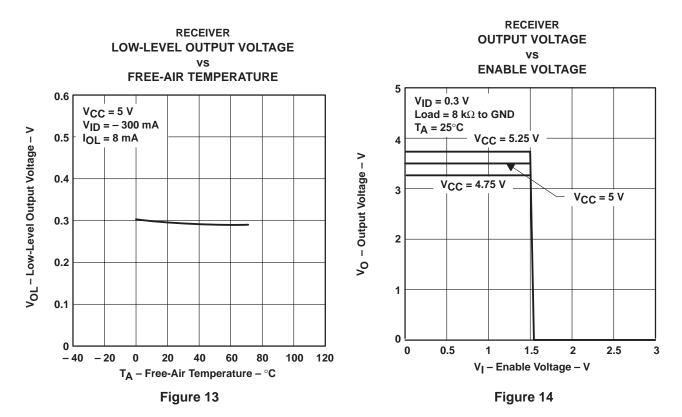


Figure 12

TYPICAL CHARACTERISTICS



RECEIVER
OUTPUT VOLTAGE
vs
ENABLE VOLTAGE

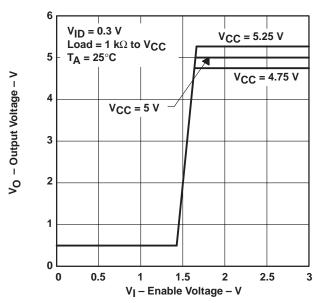
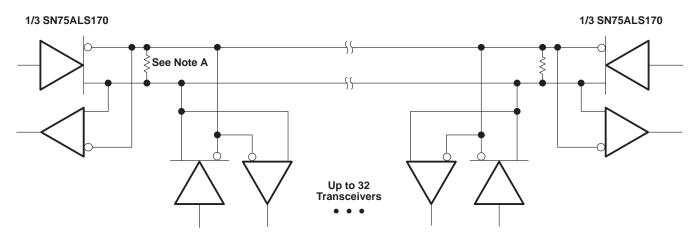


Figure 15



APPLICATION INFORMATION



NOTE A: The line should be terminated at both ends in its characteristic impedance. Stub lengths off the main line should be kept as short as possible.

Figure 16. Typical Application Circuit

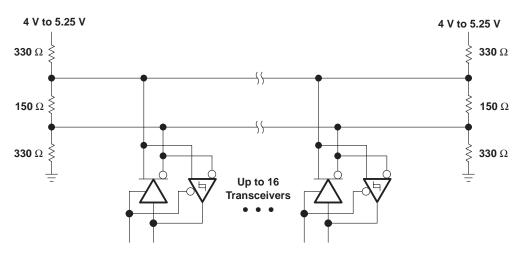


Figure 17. Typical Differential SCSI Application Circuit

APPLICATION INFORMATION

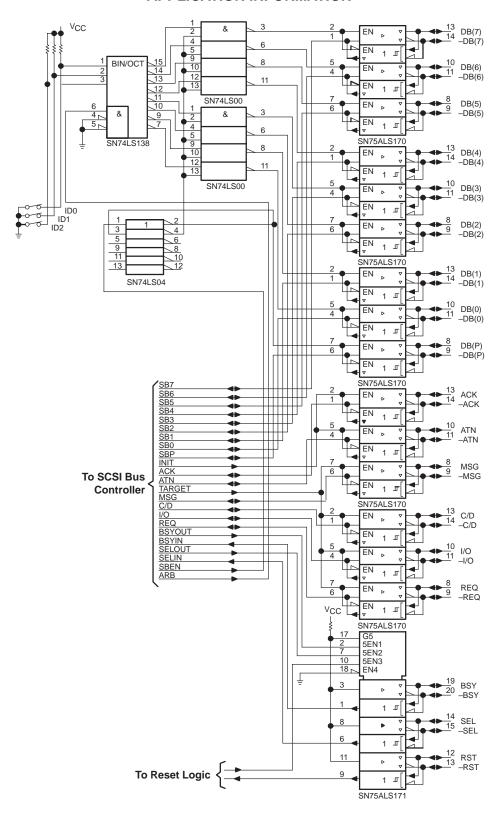


Figure 18. Typical Differential SCSI Bus Interface Implementation



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