# **Binary to 1-8 Decoder (Low)**

The MC10161 is designed to decode a three bit input word to a one of eight line output. The selected output will be low while all other outputs will be high. The enable inputs, when either or both are high, force all outputs high.

The MC10161 is a true parallel decoder. No series gating is used internally, eliminating unequal delay times found in other decoders. This design provides the identical 4 ns delay from any address or enable input to any output.

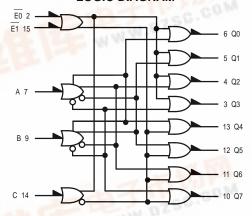
A complete mux/demux operation on 16 bits for data distribution is illustrated in Figure 1. This system, using the MC10136 control counters, has the capability of incrementing, decrementing or holding data channels. When both S0 and S1 are low, the index counters reset, thus initializing both the mux and demux units. The four binary outputs of the counter are buffered by the MC10101s to send twisted–pair select data to the multiplexer/demultiplexer to units.

 $P_D = 315 \text{ mW typ/pkg (No Load)}$ 

 $t_{Dd} = 4.0 \text{ ns typ}$ 

 $t_f$ ,  $t_f = 2.0$  ns typ (20%–80%)

#### LOGIC DIAGRAM

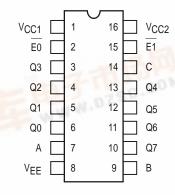


V<sub>CC1</sub> = PIN 1 V<sub>CC2</sub> = PIN 16 V<sub>EE</sub> = PIN 8

# MC10161



### DIP PIN ASSIGNMENT



Pin assignment is for Dual–in–Line Package.
For PLCC pin assignment, see the Pin Conversion
Tables on page 6–11 of the Motorola MECL Data
Book (DL122/D).

### **TRUTH TABLE**

ENABLE INPUTS IN			INPUTS			OUTPUTS						
E1	E0	С	В	Α	Q0	Q1	Q2	Q3	Q4	Q5	Q6	Q7
L	L	L	L	L	L	Н	Н	Н	Н	Н	Н	Н
L	L	L	L	Н	Н	L	Н	Н	Н	Н	Н	Н
L	L	L	Н	L	Н	Н	L	Н	Н	Н	Н	Н
L	L	L	Н	Н	Н	Н	Н	40	Н	Н	Н	н
L	L	Н	L	L	Н	Н	H	Н	L	Н	Н	H
L	L	Н	L	Н	н	Н	Н	Н	Н	L	Н	H
L	L	Н	Н	L	Н	Н	Н	Н	Н	Н	L	н
L	L	Н	Н	Н	Н	Н	Н	Н	Н	Н	Н	L
Н	Х	Χ	Х	Х	Н	Н	Н	Н	Н	Н	Н	н
Х	Н	Χ	Х	Х	Н	Н	Н	Н	Н	Н	Н	Н



# MC10161

# **ELECTRICAL CHARACTERISTICS**

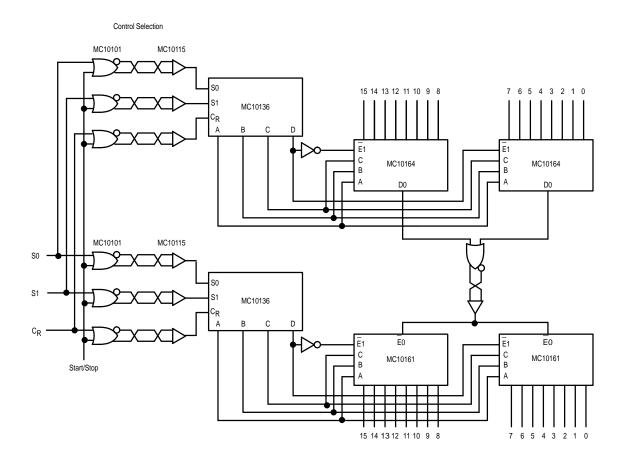
				Test Limits							
			Pin Under	–30°C		+25°C			+85°C		1
Characteris	stic	Symbol	Test	Min	Max	Min	Тур	Max	Min	Max	Unit
Power Supply Drain Current		ΙE	8		84		61	76		84	mAdc
Input Current		linH	14		350			220		220	μAdc
		l <sub>inL</sub>	14	0.5		0.5			0.3		μAdc
Output Voltage	Logic 1	Vон	13 13	-1.060 -1.060	-0.890 -0.890	-0.960 -0.960		-0.810 -0.810	-0.890 -0.890	-0.700 -0.700	Vdc
Output Voltage	Logic 0	V <sub>OL</sub>	13	-1.890	-1.675	-1.850		-1.650	-1.825	-1.615	Vdc
Threshold Voltage	Logic 1	Vона	13 13	-1.080 -1.080		-0.980 -0.980			-0.910 -0.910		Vdc
Threshold Voltage	Logic 0	VOLA	13		-1.655			-1.630		-1.595	Vdc
Switching Times (	50Ω Load)										ns
Propagation Delay		t <sub>14+13</sub> - t <sub>14-13+</sub>	13 13	1.5 1.5	6.2 6.2	1.5 1.5	4.0 4.0	6.0 6.0	1.5 1.5	6.4 6.4	
Rise Time (	20 to 80%)	t <sub>13+</sub>	13	1.0	3.3	1.1	2.0	3.3	1.1	3.5	
Fall Time (	20 to 80%)	t <sub>13</sub> _	13	1.0	3.3	1.1	2.0	3.3	1.1	3.5	

# **ELECTRICAL CHARACTERISTICS** (continued)

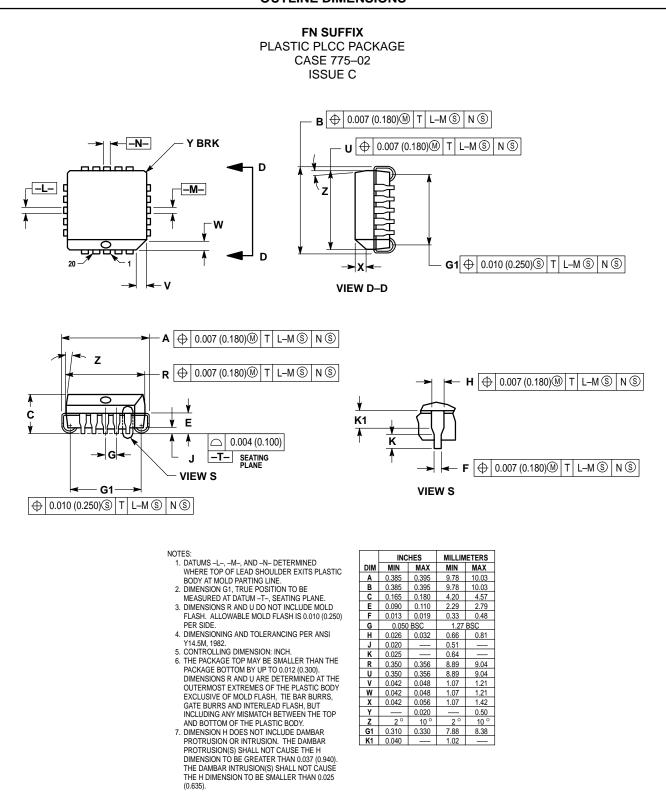
					TEST VOL	TAGE VALU	ES (Volts)		
	@ Test Temperature		V <sub>IHmax</sub>	V <sub>ILmin</sub>	V <sub>IHAmin</sub>	V <sub>ILAmax</sub>	V <sub>EE</sub>		
			–30°C	-0.890	-1.890	-1.205	-1.500	-5.2	
			+25°C	-0.810	-1.850	-1.105	-1.475	-5.2	
			+85°C	-0.700	-1.825	-1.035	-1.440	-5.2	
Pin			TEST VC	LTAGE APF	PLIED TO PII	NS LISTED B	ELOW		
Characteris	stic	Symbol	Under Test	V <sub>IHmax</sub>	V <sub>ILmin</sub>	VIHAmin	V <sub>ILAmax</sub>	VEE	(V <sub>CC</sub> ) Gnd
Power Supply Drain Cu	Power Supply Drain Current		8	2,7,9,14,15				8	1,16
Input Current		linH	14	14				8	1,16
		l <sub>inL</sub>	14		14			8	1,16
Output Voltage	Logic 1	Vон	13 13	2 15				8 8	1,16 1,16
Output Voltage	Logic 0	VOL	13	14				8	1,16
Threshold Voltage	Logic 1	Vона	13 13			2 15		8 8	1,16 1,16
Threshold Voltage	Logic 0	VOLA	13			14		8	1,16
Switching Times	(50Ω Load)					Pulse In	Pulse Out	-3.2 V	+2.0 V
Propagation Delay		<sup>t</sup> 14+13– <sup>t</sup> 14–13+	13 13			14 14	13 13	8 8	1,16 1,16
Rise Time	(20 to 80%)	t <sub>13+</sub>	13			14	13	8	1,16
Fall Time	(20 to 80%)	t <sub>13</sub> _	13			14	13	8	1,16

Each MECL 10,000 series circuit has been designed to meet the dc specifications shown in the test table, after thermal equilibrium has been established. The circuit is in a test socket or mounted on a printed circuit board and transverse air flow greater than 500 linear fpm is maintained. Outputs are terminated through a 50–ohm resistor to –2.0 volts. Test procedures are shown for only one gate. The other gates are tested in the same manner.

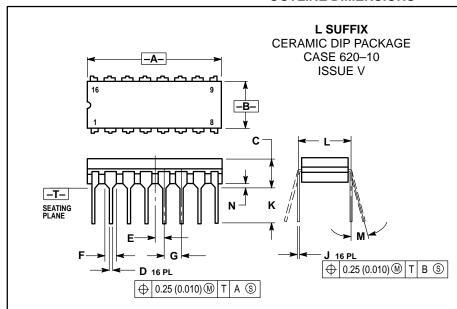
# FIGURE 1 — HIGH SPEED 16-BIT MULTIPLEXER/DEMULTIPLEXER



#### **OUTLINE DIMENSIONS**



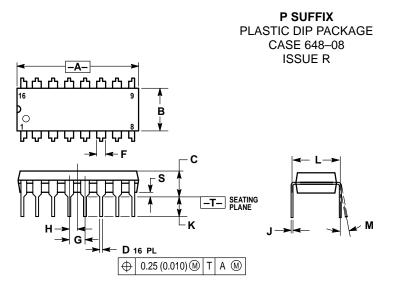
#### **OUTLINE DIMENSIONS**



#### NOTES:

- DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
- CONTROLLING DIMENSION: INCH.
- DIMENSION L TO CENTER OF LEAD WHEN FORMED PARALLEL.
- DIMENSION F MAY NARROW TO 0.76 (0.030) WHERE THE LEAD ENTERS THE CERAMIC

	INC	HES	MILLIMETERS			
DIM	MIN	MAX	MIN	MAX		
Α	0.750	0.785	19.05	19.93		
В	0.240	0.295	6.10	7.49		
С		0.200	_	5.08		
D	0.015	0.020	0.39	0.50		
Е	0.050	BSC	1.27 BSC			
F	0.055	0.065	1.40	1.65		
G	0.100	BSC	2.54 BSC			
Н	0.008	0.015	0.21	0.38		
K	0.125	0.170	3.18	4.31		
L	0.300	BSC	7.62 BSC			
M	0 °	15°	0 °	15°		
N	0.020	0.040	0.51	1.01		



- DIMENSIONING AND TOLERANCING PER ANSI
- Y14.5M, 1982. CONTROLLING DIMENSION: INCH. DIMENSION L TO CENTER OF LEADS WHEN
- FORMED PARALLEL.
  DIMENSION B DOES NOT INCLUDE MOLD FLASH.
- ROUNDED CORNERS OPTIONAL

	INC	HES	MILLIMETERS			
DIM	MIN	MAX	MIN	MAX		
Α	0.740	0.770	18.80	19.55		
В	0.250	0.270	6.35	6.85		
С	0.145	0.175	3.69	4.44		
D	0.015	0.021	0.39	0.53		
F	0.040	0.70	1.02	1.77		
G	0.100	BSC	2.54 BSC			
Н	0.050	BSC	1.27 BSC			
J	0.008	0.015	0.21	0.38		
K	0.110	0.130	2.80	3.30		
L	0.295	0.305	7.50	7.74		
M	0°	10°	0°	10 °		
S	0.020	0.040	0.51	1.01		

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