

**Phase Control Thyristor** **$V_{RRM} = 800-1600 \text{ V}$**  **$I_{T(RMS)} = 75 \text{ A}$**  **$I_{T(AV)M} = 48 \text{ A}$** 

$V_{RSM}$	$V_{RRM}$	Type
$V_{DSM}$	$V_{DRM}$	
V	V	
900	800	CS 45-08io1
1300	1200	CS 45-12io1
1700	1600	CS 45-16io1 CS 45-16io1R

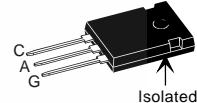
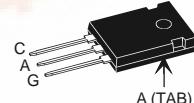


TO-247 AD

Version io1

ISOPLUS 247™

Version io1R



\* Patent pending

C = Cathode, A = Anode, G = Gate

Symbol	Conditions	Maximum Ratings			Features
$I_{T(RMS)}$	$T_{VJ} = T_{VJM}$	75	A		• Thyristor for line frequency
$I_{T(AV)M}$	$T_c = 75^\circ\text{C}; 180^\circ \text{ sine}$	48	A		• International standard package JEDEC TO-247
$I_{TSM}$	$T_{VJ} = 45^\circ\text{C}$ $V_R = 0 \text{ V}$	520 560	A A		• Planar passivated chip
	$T_{VJ} = T_{VJM}$ $V_R = 0 \text{ V}$	460 500	A A		• Long-term stability of blocking currents and voltages
$I^2t$	$T_{VJ} = 45^\circ\text{C}$ $V_R = 0 \text{ V}$	1350 1300	A <sup>2</sup> s A <sup>2</sup> s		• Version AR isolated and UL registered E153432
	$T_{VJ} = T_{VJM}$ $V_R = 0 \text{ V}$	1050 1030	A <sup>2</sup> s A <sup>2</sup> s		• Epoxy meets UL 94V-0
$(di/dt)_{cr}$	$T_{VJ} = T_{VJM}$ $f = 50 \text{ Hz}, t_p = 200 \mu\text{s}$	repetitive, $I_T = 40 \text{ A}$	150	A/ $\mu\text{s}$	
	$V_D = \frac{2}{3} V_{DRM}$ $I_G = 0.3 \text{ A}$ $di_G/dt = 0.3 \text{ A}/\mu\text{s}$	non repetitive, $I_T = I_{T(AV)M}$	500	A/ $\mu\text{s}$	
$(dv/dt)_{cr}$	$T_{VJ} = T_{VJM};$ $R_{GK} = \infty; \text{method 1 (linear voltage rise)}$	$V_{DR} = \frac{2}{3} V_{DRM}$	1000	V/ $\mu\text{s}$	• Motor control • Power converter • AC power controller • Switch-mode and resonant mode power supplies • Light and temperature control
$P_{GM}$	$T_{VJ} = T_{VJM}$ $I_T = I_{T(AV)M}$	$t_p = 30 \mu\text{s}$ $t_p = 300 \mu\text{s}$	10 5	W W	
$P_{G(AV)}$			0.5	W	
$V_{RGM}$			10	V	
$T_{VJ}$			-40...+140	°C	
$T_{VJM}$			140	°C	
$T_{stg}$			-40...+125	°C	
$M_d$	Version io1: mounting torque M3	0.8...1.2	Nm		
$F_c$	Version io1R: mounting force with clip	20...120	N		
$V_{ISOL}^*$	50/60 Hz, RMS, $t = 1 \text{ minute}$ , leads-to-tab	2500	V~		
<b>Weight</b>		6	g		

\* Version io1R only

Data according to IEC 60747  
IXYS reserves the right to change limits, test conditions and dimensions

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Symbol	Conditions	Characteristic Values		
$I_R, I_D$	$T_{VJ} = T_{VJM}$ ; $V_R = V_{RRM}$ ; $V_D = V_{DRM}$	≤	5	mA
$V_T$	$I_T = 80 \text{ A}$ ; $T_{VJ} = 25^\circ\text{C}$	≤	1.64	V
$V_{TO}$	For power-loss calculations only ( $T_{VJ} = 125^\circ\text{C}$ )	0.85	V	
$r_T$		11	$\text{m}\Omega$	
$V_{GT}$	$V_D = 6 \text{ V}$ ; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = -40^\circ\text{C}$	≤	1.5	V
$I_{GT}$	$V_D = 6 \text{ V}$ ; $T_{VJ} = 25^\circ\text{C}$ $T_{VJ} = -40^\circ\text{C}$	≤	100	mA
$V_{GD}$	$T_{VJ} = T_{VJM}$ ;	≤	0.2	V
$I_{GD}$	$V_D = \frac{2}{3} V_{DRM}$	≤	10	mA
$I_L$	$T_{VJ} = 25^\circ\text{C}$ ; $t_p = 10 \mu\text{s}$ $I_G = 0.3 \text{ A}$ ; $di_G/dt = 0.3 \text{ A}/\mu\text{s}$	≤	150	mA
$I_H$	$T_{VJ} = 25^\circ\text{C}$ ; $V_D = 6 \text{ V}$ ; $R_{GK} = \infty$	≤	100	mA
$t_{gd}$	$T_{VJ} = 25^\circ\text{C}$ ; $V_D = \frac{1}{2} V_{DRM}$ $I_G = 0.3 \text{ A}$ ; $di_G/dt = 0.3 \text{ A}/\mu\text{s}$	≤	2	$\mu\text{s}$
$R_{thJC}$	DC current	0.62	K/W	
$R_{thJH}$	DC current	0.82	K/W	
$a$	Max. acceleration, 50 Hz	50	$\text{m/s}^2$	

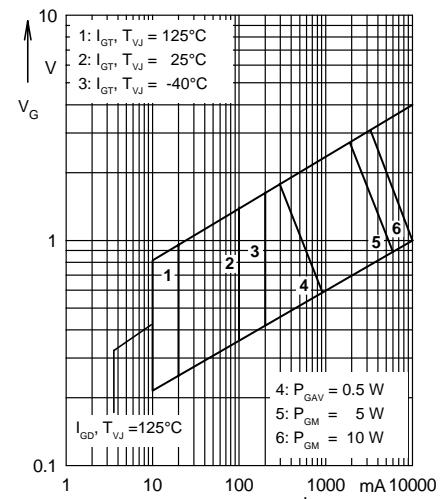
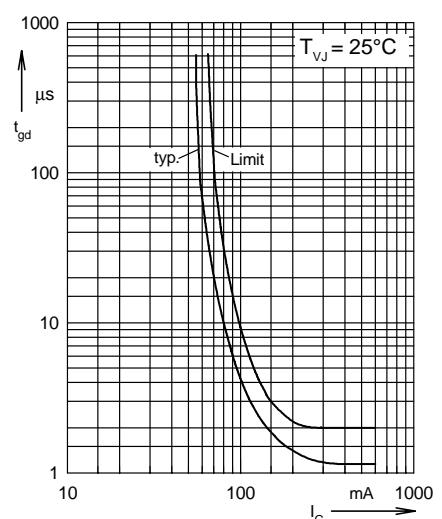
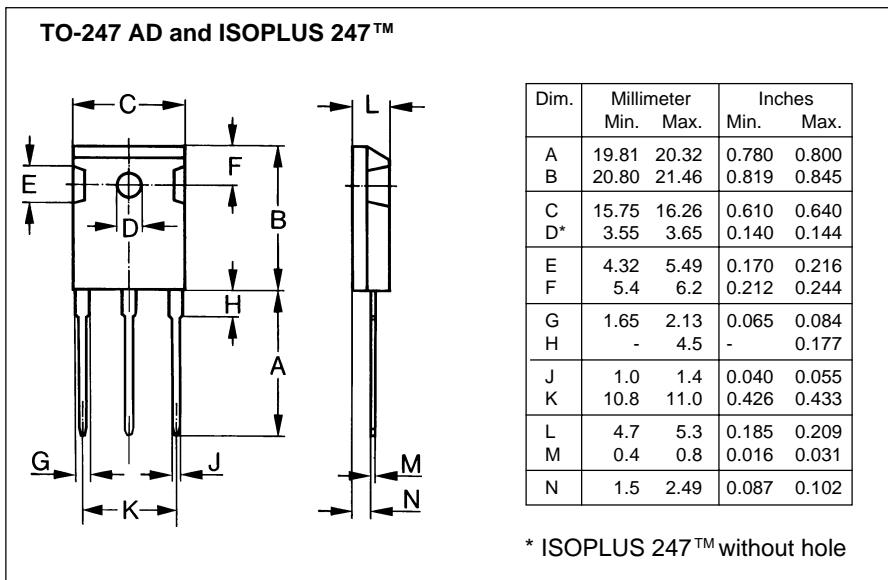


Fig. 1 Gate trigger range


Fig. 2 Gate controlled delay time  $t_{gd}$ 


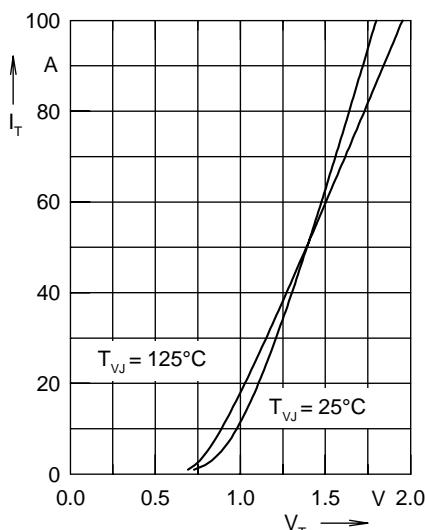


Fig. 3 Forward characteristics

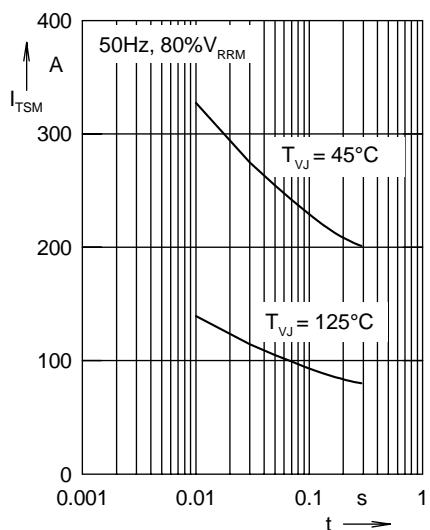


Fig. 4 Surge overload current  
 $I_{TSM}$ : crest value, t: duration

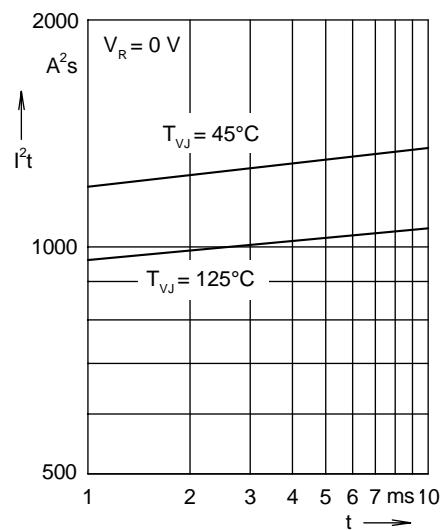


Fig. 5  $I^2t$  versus time (1-10 ms)

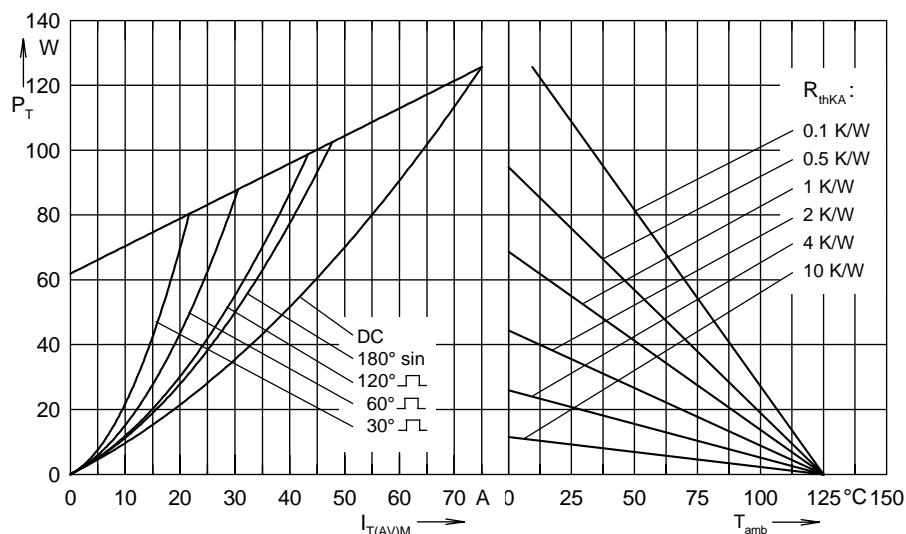


Fig. 6 Power dissipation versus forward current and ambient temperature

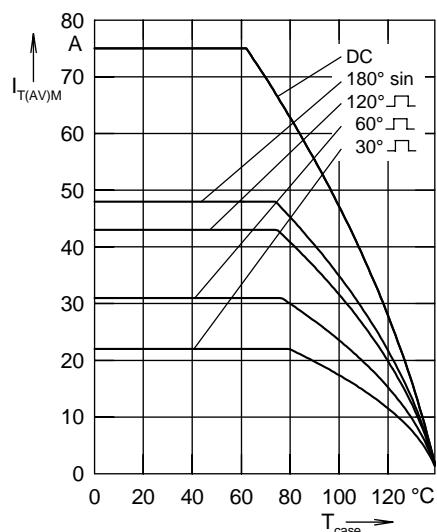


Fig. 7 Max. forward current at case temperature

$R_{thJC}$  for various conduction angles  $d$ :

$d$	$R_{thJC}$ (K/W)
DC	0.62
180°	0.71
120°	0.748
60°	0.793
30°	0.817

Constants for  $Z_{thJC}$  calculation:

$i$	$R_{thi}$ (K/W)	$t_i$ (s)
1	0.206	0.013
2	0.362	0.118
3	0.052	1.488

Fig. 8 Transient thermal impedance junction to case