

TOSHIBA

TA8859CP

TENTATIVE TOSHIBA BIPOLAR LINEAR INTEGRATED CIRCUIT SILICON MONOLITHIC

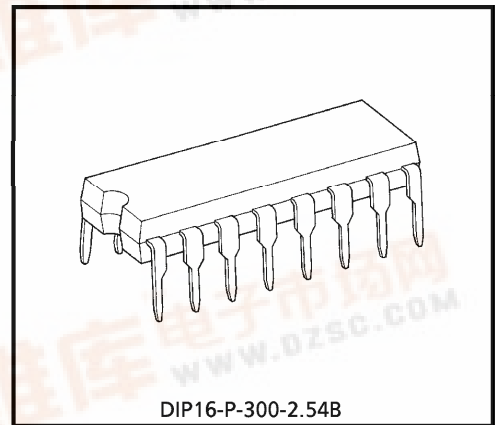
TA8859CP

TV BIAS DISTORTION COMPENSATION IC

The TA8859CP is an IC for TV deflection stage to compensate various horizontal, vertical distortion, with a package of 16 pin DIP, controlled via I²C bus.

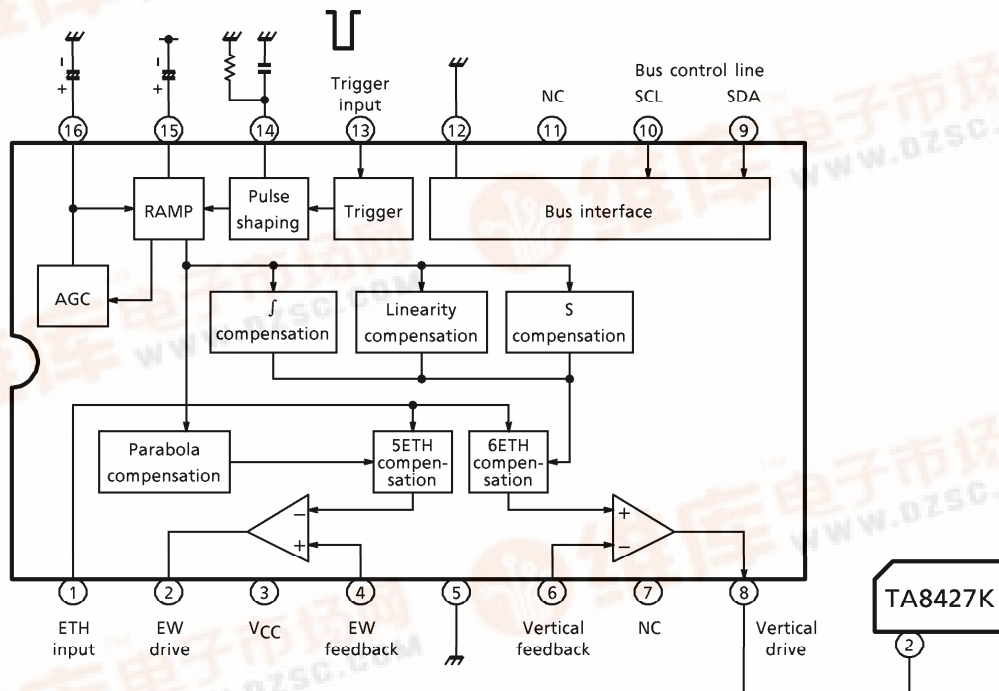
FEATURES

- Vertical linearity correction
- Vertical S correction
- E-W parabola
- E-W corner
- Trapezium distortion compensation

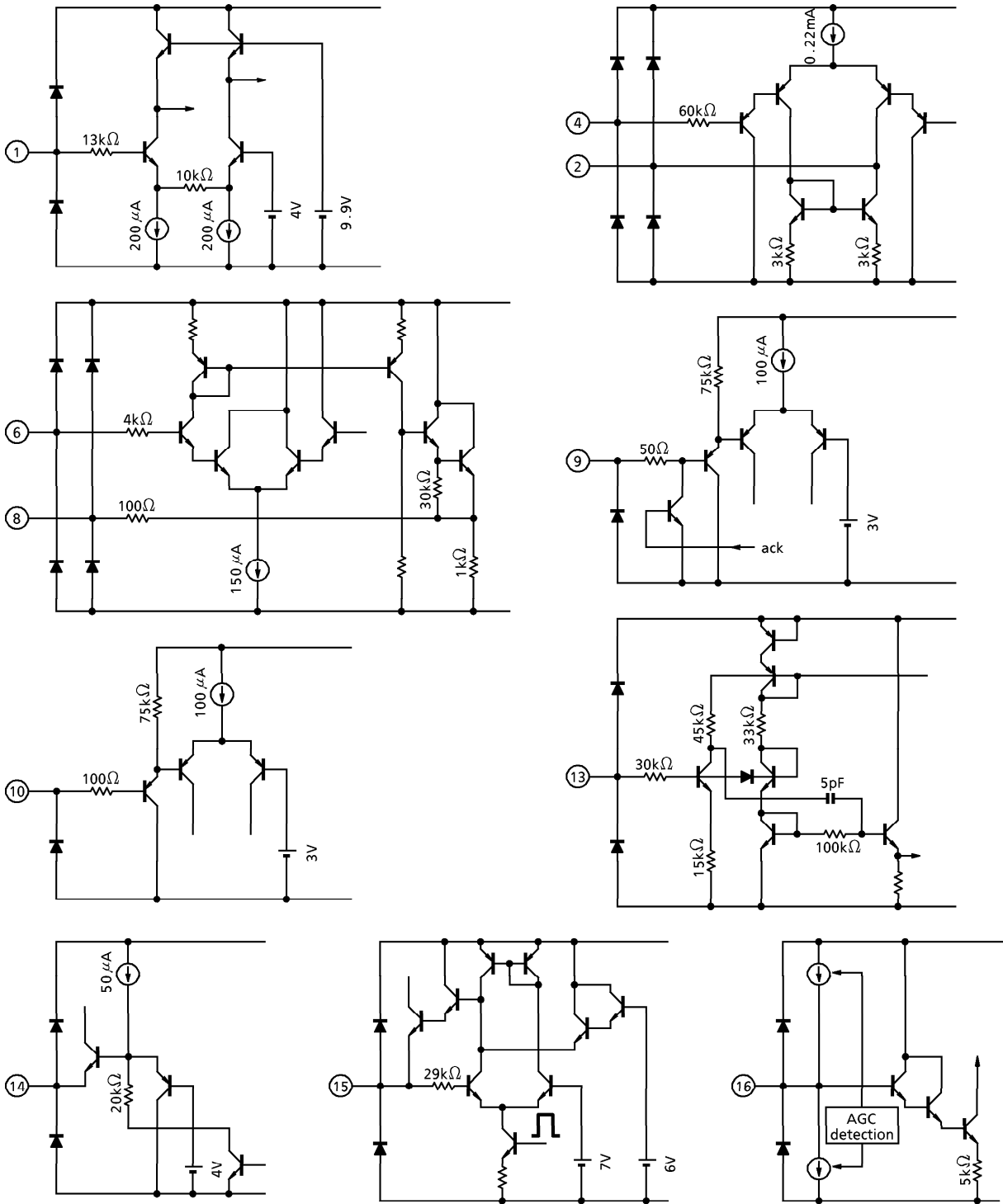


Weight : 1.11g (Typ.)

BLOCK DIAGRAM


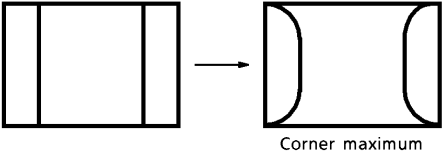

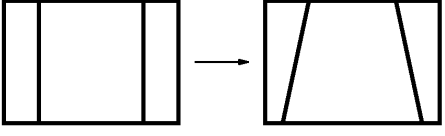

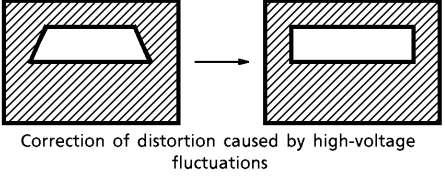
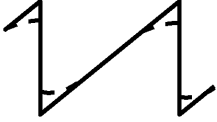
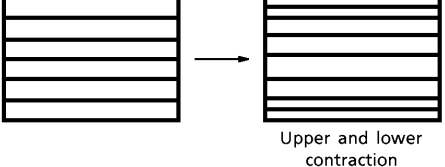


TERMINAL INTERFACE



OUTLINE OF FUNCTIONS

FUNCTION	SUB ADDRESS	BIT	OUTPUT WAVEFORM	PICTURE
Picture Height Adjustment	0010	6		
Vertical Linearity correction	0011	5		
Vertical "S" Correction (X ³)	0100	5		
Vertical Shift	0101	3		
Vertical Compensation	0110	—		
Picture Width Adjustment	0111	6		
E-W Parabola	1000	6		

FUNCTION	SUB ADDRESS	BIT	OUTPUT WAVEFORM	PICTURE
E-W Corner Correction	1001	4		 Corner maximum
Trapezium Distortion Compensation	1010	6		
Horizontal Compensation	1011	—		 Correction of distortion caused by high-voltage fluctuations
Vertical f Correction (X ⁵)	1110	4		 Upper and lower contraction

I²C BUS CONTROL FUNCTIONS

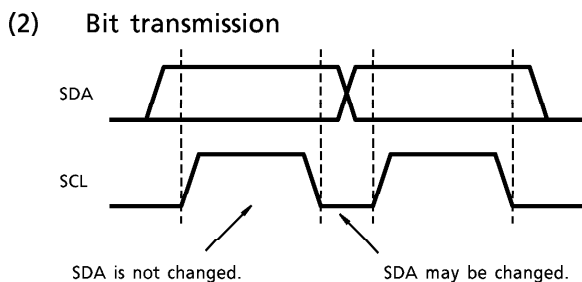
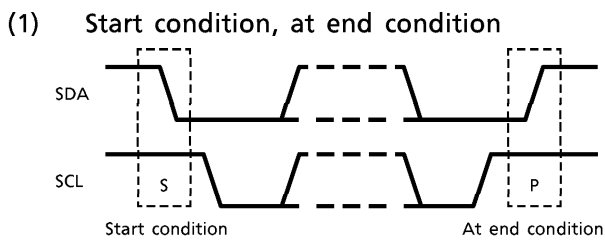
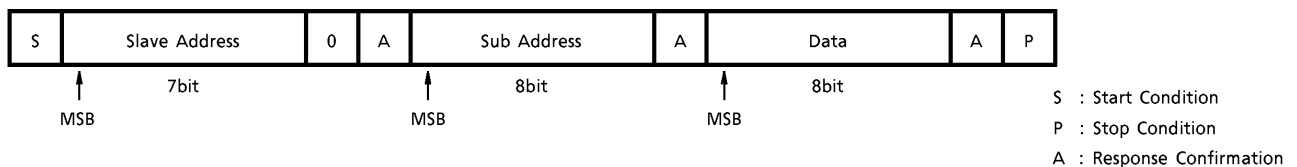
FUNCTION	SUB ADDRESS	DATA	PRESET	RANGE
Picture Height	00000010	x-x-7bit	01000000	-48~48%
V-linearity	00000011	x-x-x-5bit	00010000	-13~13%
V-S Correction	00000100	x-x-x-5bit	00000000	0~22%
V-shift	00000101	x-x-x-AGC-3bit-x	00001000	-800~800mV
V-compensation	00000110	x-x-x-x-4bit	00000000	0~9%
Picture Width	00000111	x-x-6bit	00100000	1.6~7.3V
E-W Parabola	00001000	x-x-6bit	00100000	0~5.6V
E-W Corner	00001001	x-x-x-x-4bit	00000000	0~3.2V
Trapezium	00001010	x-x-6bit	00100000	0~1.2V
H-compensation	00001011	x-x-x-x-4bit	00000000	0~9%
V-f Correction	00001100	x-x-x-x-4bit	00000000	0~4%

- (Note 1) Vertical Height is controlled by Sub Address 02 (H), so no external control is required.
- (Note 2) AGC bit determines vertical AGC response speed.
 0 : High speed for Channel/Mode change
 1 : Low speed (1/5×High speed). for Normal reception/Text Mode.
- (Note 3) All registers are cleared into the preset value under the condition of $V_{CC} \leq 3V$.

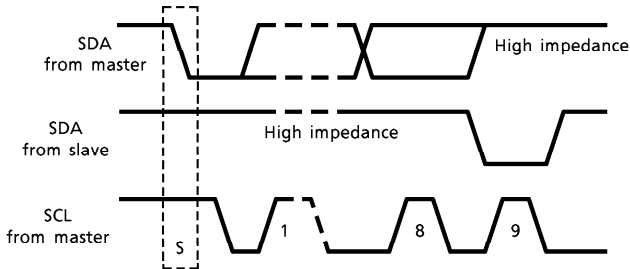
I²C BUS CONTROL FORMAT OUTLINE

Bus controlled format of TA8859CP is based on I²C Bus Control format of PHILIPS.

Data transmission format



(3) Verification response



(4) Slave address

A6	A5	A4	A3	A2	A1	A0	R/ \bar{W}
1	0	0	0	1	1	0	0

Purchase of TOSHIBA I²C components conveys a license under the Philips I²C Patent Rights to use these components in an I²C system, provided that the system conforms to the I²C Standard Specification as defined by Philips.

MAXIMUM RATINGS (Ta = 25°C, VCC = 12V)

CHARACTERISTIC	SYMBOL	RATING	UNIT
Supply Voltage	VCC	15	V
Power Dissipation	PD max	1.4 (Note)	W
Input Signal Voltage	e _{in}	5	V _{p-p}
Operating Temperature	T _{opr}	-20~65	°C
Storage Temperature	T _{stg}	-55~150	°C

(Note) Derated above Ta = 25°C, in the proportion of 11.2mW/°C.

RECOMMENDED POWER SUPPLY VOLTAGE

CHARACTERISTIC	SYMBOL	MIN.	TYP.	MAX.	UNIT
Supply Voltage	VCC	10.8	12	13.2	V

ELECTRICAL CHARACTERISTICS(Unless otherwise specified, $V_{CC} = 12V$, $T_a = 25^\circ C$)

Power supply current

CHARACTERISTIC	SYMBOL	MIN.	TYP.	MAX.	UNIT
Supply Current	I_{CC}	20	30	45	mA


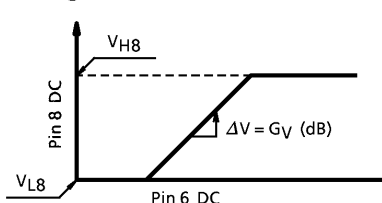
Terminal voltage

No.	ITEM	SYMBOL	MIN.	TYP.	MAX.	UNIT	NOTE
1	ΔEHT	V_1	7.5	8.0	8.5	V	—
2	EW-OUT	V_2	5.8	6.1	6.4		—
3	V_{CC} (12V)	V_3	—	12.0	—		Terminal = V_{CC} (12.0V)
4	EW-FB	V_4	—	12.0	—		Terminal = V_{CC} (12.0V)
5	GND	V_5	—	0.0	—		Terminal = GND
6	V.FB	V_6	2.0	2.4	2.8		—
7	N.C.	V_7	—	0.0	—		Terminal = GND
8	V.OUT	V_8	2.8	3.5	4.3		—
9	SDA	V_9	4.8	5.1	5.4		—
10	SCL	V_{10}	4.8	5.1	5.4		—
11	N.C.	V_{11}	—	0.0	—		Terminal = GND
12	I ² L GND	V_{12}	—	0.0	—		Terminal = GND
13	V.IN	V_{13}	—	0.0	—		Terminal = GND
14	T.C.	V_{14}	3.7	4.0	4.3		—
15	V.RAMP	V_{15}	3.7	4.0	4.3		—
16	V.AGC	V_{16}	—	0.0	—		Terminal = GND

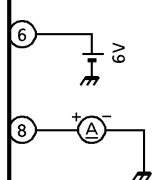
(Note) Data : Preset

AC CHARACTERISTICS

No.	ITEM	SYMBOL	BUS CONTROL DATA				TEST METHOD	MIN.	TYP.	MAX.	UNIT
1	Vertical Trigger Input Threshold Voltage	V _{TH13}	02	03	04	05	<ul style="list-style-type: none"> Change the height of trigger pulse given to TP13, and measure the time pulse height when a timing pulse is output. <p>(*) All data are preset.</p>	0.7	1.0	1.4	V
			40	10	00	08					
			06	07	08	09					
			00	20	00	00					
			0A	0B	0C						
			20	00	00						
2	Clamp Voltage At TP14	V _{H14}	02	03	04	05	<ul style="list-style-type: none"> Give the trigger pulse to TP13. (Pulse width : 640 μs, cycle : 20ms, Low level : 0V, High level : 3V). Observe the wave shape at TP14. 	3.7	4.0	4.2	V
			40	10	00	08					
			06	07	08	09					
			00	20	00	00					
			0A	0B	0C						
			20	00	00						
3	Threshold Voltage I At TP14	V _{M14}	02	03	04	05	<ul style="list-style-type: none"> Same as No.2. Observe the wave shape at TP14 and TP15. <p>V.RAMP Charging start point</p>	2.8	3.0	3.2	V
			40	10	00	08					
			06	07	08	09					
			00	20	00	00					
			0A	0B	0C						
			20	00	00						

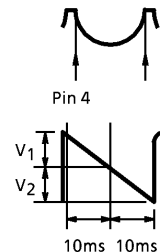
No.	ITEM	SYM-BOL	BUS CONTROL DATA				TEST METHOD	MIN.	TYP.	MAX.	UNIT
4	Threshold Voltage II At TP14	V _{L14}	02	03	04	05	<ul style="list-style-type: none"> • Same as No.3. 	0.9	1.0	1.1	V
			40	10	00	08					
			06	07	08	09					
			00	20	00	00					
			0A	0B	0C						
			20	00	00						
5	Vertical Ramp Pulse Amplitude	V _{P15}	02	03	04	05	<ul style="list-style-type: none"> • Measure the vertical ramp pulse amplitude at TP15.  <p>(*) All data are preset.</p>	1.9	2.0	2.1	V _{p-p}
			40	10	00	08					
			06	07	08	09					
			00	20	00	00					
			0A	0B	0C						
			20	00	00						
6	Vertical Amplifier Gain	G _V	02	03	04	05	<ul style="list-style-type: none"> • Give no pulse to TP13. • Connect an external power supply to TP6. • Measure the voltage of TP8 when the voltage of TP6 is changed from 0V to 6V. 	22	26	30	dB
			40	10	00	08					
			06	07	08	09					
			00	20	00	00					
			0A	0B	0C						
			20	00	00						

No.	ITEM	SYM-BOL	BUS CONTROL DATA				TEST METHOD	MIN.	TYP.	MAX.	UNIT
7	Vertical Amplifier Max. Output Voltage	V _{H8}	02	03	04	05	<ul style="list-style-type: none"> • Same as No.6. (*) All data are preset. 	2.9	3.6	4.5	V
			40	10	00	08					
			06	07	08	09					
			00	20	00	00					
			0A	0B	0C						
			20	00	00						
8	Vertical Amplifier Min. Output Voltage	V _{L8}	02	03	04	05	<ul style="list-style-type: none"> • Same as No.6. 	0	0	0.3	V
			40	10	00	08					
			06	07	08	09					
			00	20	00	00					
			0A	0B	0C						
			20	00	00	00					
9	Vertical Amplifier Max. Output Current	I _{max8}	02	03	04	05	<ul style="list-style-type: none"> • Same as No.6. • Measure the current between TP8 and GND when the voltage of TP6 is 6V. 	20	40	—	mA
			40	10	00	08					
			06	07	08	09					
			00	20	00	00					
			0A	0B	0C						
			20	00	00						

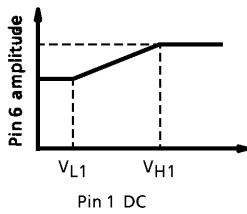


(*) All data are preset.

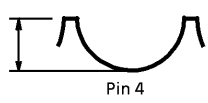
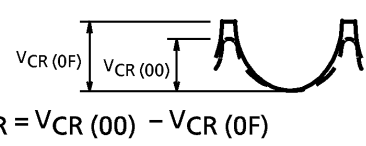
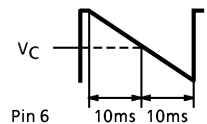
No.	ITEM	SYM-BOL	BUS CONTROL DATA				TEST METHOD	MIN.	TYP.	MAX.	UNIT
10	Vertical Saw Wave Amplitude	V _{P6}	02	03	04	05	<ul style="list-style-type: none"> Same as No.2. Measure the amplitude of saw wave at TP6. (*) All data are preset. 	1.7	1.9	2.2	V _{p-p}
			40	10	00	08					
			06	07	08	09					
			00	20	00	00					
			0A	0B	0C						
			20	00	00						
11	Vertical Amplitude Variable Range	V _{PH}	02	03	04	05	<ul style="list-style-type: none"> Same as No.10. Measure the amplitude V_{P6} (00) at TP6 when the data of sub address (02) is turned to (00). Measure the amplitude V_{P6} (3F) at TP6 when the data of sub address (02) is turned to (00). $V_{PH} = \pm \frac{V_{P6} (3F) - V_{P6} (00)}{V_{P6} (3F) + V_{P6} (00)} \times 100\%$	+ 45 - 45	+ 48 - 48	+ 51 - 51	%
			7F	10	00	08					
			00								
			06	07	08	09					
			00	20	00	00					
			0A	0B	0C						
			20	00	00						
12	Vertical Linearity Max. Correction	V _ℓ	02	03	04	05	<ul style="list-style-type: none"> Turn it to (3F) the data of sub address (08) and adjust the data of sub address (0A) for making the shape of parabolic wave of TP4 symmetrical. Turn it to (00) the data of sub address (08). Measure V₁ (10) and V₂ (10) at TP6 when the data of sub address (03) is (10). Similarly measure V₁ (00), V₂ (CC), V₁ (1F) and V₂ (1F). (00) and (1F) are the data of sub address (08). $V_{\ell} = \pm 100 \times \frac{V_1 (00) - V_1 (1F) + V_2 (1F) - V_2 (00)}{2 \times (V_1 (10) + V_2 (10))}$	+ 10.0 - 10.0	+ 12.5 - 12.5	+ 15.0 - 15.0	%
			40	1F	00	08					
			06	07	08	09					
			00	20	00	00					
			0A	0B	0C						
	Adjust		00	00							

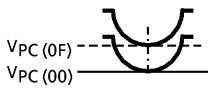
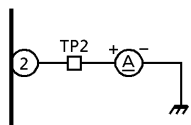


No.	ITEM	SYM-BOL	BUS CONTROL DATA				TEST METHOD	MIN.	TYP.	MAX.	UNIT
13	Max. Of Vertical S Correction	V _S	02	03	04	05	<ul style="list-style-type: none"> Same as No.12. Measure the amplitude V_{S6} (00) at TP6 when the data of sub address (04) is (00). Measure the amplitude V_{S6} (1F) at TP6 when the data of sub address (04) is (00). $V_S = \frac{V_{S6(00)} - V_{S6(1F)}}{V_{S6(00)}} \times 100 (\%)$	20	24	28	%
			40	10	1F	08					
			06	07	08	09					
			00	20	00	00					
			0A	0B	0C						
			Adjust	00	00						
14	Max. Of Vertical f Correction	V _f	02	03	04	05	<ul style="list-style-type: none"> Same as No.13. Measure the amplitude V_{f6} (00) at TP6 when the data of sub address (0C) is (00). Measure the amplitude V_{f6} (0F) at TP6 when the data of sub address (0C) is (0F). $V_f = \frac{V_{f6(0F)} - V_{f6(00)}}{V_{f6(00)}} \times 100 (\%)$	3	—	—	%
			40	10	00	08					
			06	07	08	09					
			00	20	00	00					
			0A	0B	0C						
			Adjust	00	0F	00					
15	Vertical NF Center Voltage	V _C	02	03	04	05	<ul style="list-style-type: none"> Same as No.12. Observe the wave shape at TP6. 	3.8	4.1	4.4	V
			40	10	00	08					
			06	07	08	09					
			00	20	00	00					
			0A	0B	0C						
			Adjust	00	00						

No.	ITEM	SYM-BOL	BUS CONTROL DATA				TEST METHOD	MIN.	TYP.	MAX.	UNIT
16	Vertical NF DC Variation	V _{DC}	02	03	04	05	<ul style="list-style-type: none"> • Same as No.15. • Measure the vertical NF center voltage V_C(00) when the data of sub address(05) is (00). • Measure the vertical NF center voltage V_C(0F) when the data of sub address (05) is (00). $V_{DC} = \pm \frac{V_C(0F) - V_C(00)}{2} (V)$	± 720	± 800	± 880	mV
			40	10	00	0F					
			06	07	08	09					
			00	20	00	00					
			0A	0B	0C						
			Adjust	00	00						
17	Vertical Amplitude EHT Correction	V _{EHT}	02	03	04	05	<ul style="list-style-type: none"> • Same as No.12. • Connect an external power supply to TP1 and turn its voltage to 0V. • Measure the amplitude V_{EHT}(00) at TP6 when the data of sub address (06) is (00). • Measure the amplitude V_{EHT}(0F) at TP6 when the data of sub address (06) is (0F). $V_{EHT} = \frac{V_{EHT}(00) - V_{EHT}(0F)}{V_{EHT}(00)} \times 100 (\%)$	8	9	10	V
			40	10	00	08					
			06	07	08	09					
			0F	20	00	00					
			0A	0B	0C						
			Adjust	00	00						
18	EHT Input Dynamic Range I	V _{H1}	02	03	04	05	<ul style="list-style-type: none"> • Same as No.17. • Change it from 1V to 7V the voltage of the external power supply connected with TP1. • At this time, measure the variation of amplitude at TP6. 	6.0	6.5	7.0	V
			40	10	00	08					
			06	07	08	09					
			0F	20	00	00					
			0A	0B	0C						
			Adjust	00	00						

No.	ITEM	SYM-BOL	BUS CONTROL DATA				TEST METHOD	MIN.	TYP.	MAX.	UNIT
19	EHT Input Dynamic Range II	VL1	02	03	04	05	● Same as No.18.	1.3	1.8	2.3	V
			40	10	00	08					
			06	07	08	09					
			0F	20	00	00					
			0A	0B	0C						
			Adjust	00	00						
20	E-W NF Max. DC (Picture Width)	—	02	03	04	05	● Same as No.12. ● Measure the voltage at TP4.	6.8	7.4	8.0	V
			40	10	00	08					
			06	07	08	09					
			00	00	00	00					
			0A	0B	0C						
			Adjust	00	00						
21	E-W NF Min. DC (Picture Width)	VL4	02	03	04	05	● Measure the voltage at TP4.	1.4	1.5	1.7	V
			40	10	00	08					
			06	07	08	09					
			00	3F	00	00					
			0A	0B	0C						
			Adjust	00	00						

No.	ITEM	SYM-BOL	BUS CONTROL DATA				TEST METHOD	MIN.	TYP.	MAX.	UNIT
22	E-W NF Max. Parabolic Correction (Parabola)	V _{PB}	02	03	04	05	<ul style="list-style-type: none"> Give 7V to TP1. Measure the parabolic amplitude at TP4. 	4.8	5.6	6.6	V _{p-p}
			40	10	00	08					
			06	07	08	09					
			00	3F	3F	00					
			0A	0B	0C						
			Adjust	00	00						
23	E-W NF Corner Correction (Corner)	V _{CR}	02	03	04	05	<ul style="list-style-type: none"> Give 7V to TP1. Measure the parabolic amplitude at TP4. Measure the amplitude V_{CR}(00) when the data of sub address (09) is (00). Measure the amplitude V_{CR}(0F) when data of sub address (09) is (0F).  $V_{CR} = V_{CR}(00) - V_{CR}(0F)$	2.5	3.2	4.1	V _{p-p}
			40	10	00	08					
			06	07	08	09					
			00	3F	3F	0F					
			00			00					
			0A	0B	0C						
Adjust	00	00									
24	Parabolic Symmetry Correction	V _{TR}	02	03	04	05	<ul style="list-style-type: none"> Same as No.10. Measure the vertical scan center voltage V_C(00) at TP6 when the data of sub address (0A) is (00). Measure the vertical scan center voltage V_C(3F) at TP6 when the data of sub address (0A) is (3F). $V_{TR} = \pm \frac{V_C(00) - V_C(3F)}{2 \times V_{P6}} \times 100 (\%)$ 	± 3	± 4.5	± 6	%
			40	10	00	08					
			06	07	08	09					
			00	20	00	00					
			0A	0B	0C						
			3F	00	00						
00											

No.	ITEM	SYM-BOL	BUS CONTROL DATA				TEST METHOD	MIN.	TYP.	MAX.	UNIT
25	E-W Parabolic EHT Correction	V _{EH1}	02	03	04	05	<ul style="list-style-type: none"> • Same as No.22. • Connect an external power supply to TP1. • Measure the parabolic amplitude V_{EH}(7) at TP4 when the voltage of TP1 is 7V. • Measure the amplitude V_{EH}(1) when the voltage of TP1 is 1V. $V_{EH1} = \frac{V_{EH}(7) - V_{EH}(1)}{V_{EH}(7)} \times 100 (\%)$	—	4.7	—	%
			40	10	00	08					
			06	07	08	09					
			00	00	3F	00					
			0A	0B	0C						
Adjust	00	00									
26	E-W DC EHT Correction	V _{EH2}	02	03	04	05	<ul style="list-style-type: none"> • Give 1V to TP1. • Measure the parabolic phase center voltage V_{PC}(00) at TP4 when the data of sub address (0B) is (00). • Measure the voltage V_{PC}(0F) when the data is (0F). $V_{EH2} = V_{PC}(0F) - V_{PC}(00)$ 	1.0	1.4	1.8	V
			40	10	00	08					
			06	07	08	09					
			00	3F	3F	00					
			0A	0B	0C						
Adjust	00 ↑ 0F	00									
27	Max. Of E-W Amplifier Output Current	I _{max2}	02	03	04	05	<ul style="list-style-type: none"> • Connect an ampere meter between TP2 and GND. • Measure the current. 	0.14	0.2	0.27	mA
			40	10	00	10					
			06	07	08	09					
			00	20	00	00					
			0A	0B	0C						
	20	00	00								

(Note) Concerning fall time

When used in actual applications, if the fall time for input pulse becomes greater output may not be generated in some cases, so please take care.

CHARACTERISTIC	TEST METHOD	MIN.	TYP.	MAX.	UNIT
Trigger Input Fall Time	As below	—	1.0	7.6	μs

While monitoring the input waveform of Pin 13 oscilloscope, please measure fall time from 10% to 90%.

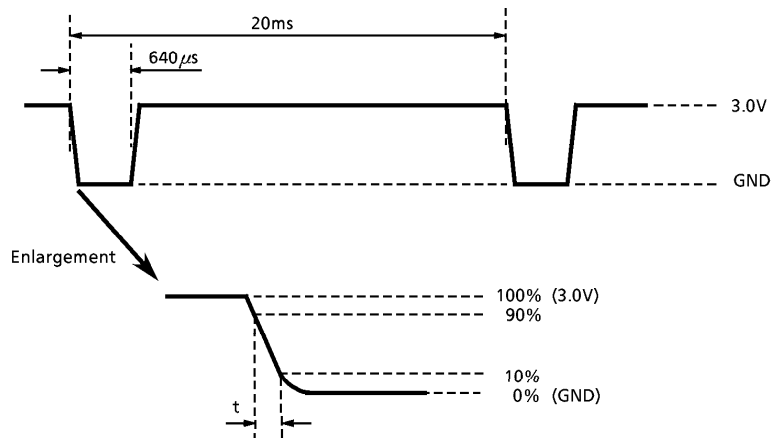
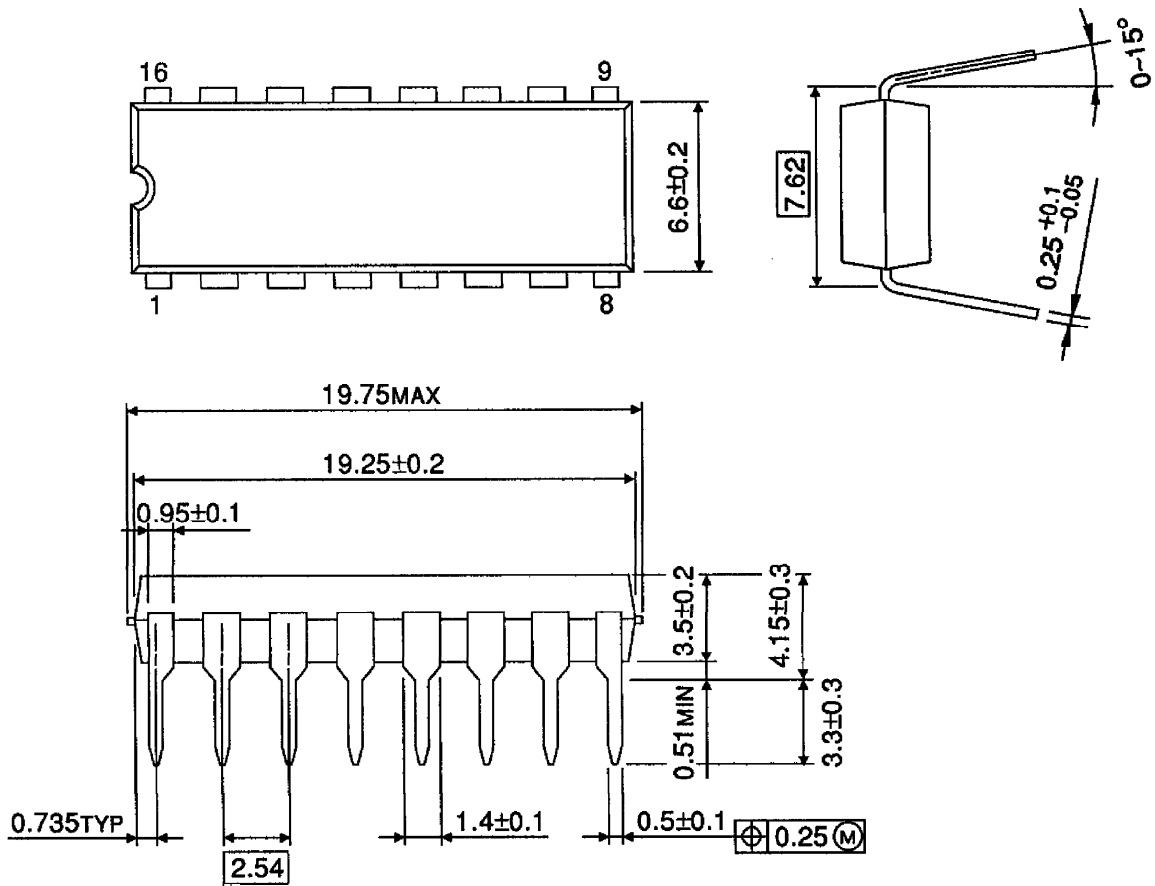


Fig.

PACKAGE DIMENSIONS
DIP16-P-300-2.54B

UNIT : mm



Weight : 1.11g (Typ.)

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000707EBA

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