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The LTC485 is a low power differential bus/line transceiver

designed for multipoint data transmission standard RS485 applications with extended common-mode range (12V to

The CMOS design offers significant power savings over its

bipolar counterpart without sacrificing ruggedness against

The driver and receiver feature three-state outputs, with

the driver outputs maintaining high impedance over the

entire common-mode range. Excessive power dissipation

caused by bus contention or faults is prevented by a thermal shutdown circuit which forces the driver outputs

The receiver has a fail-safe feature which guarantees a

The LTC485 is fully specified over the commercial and

high output state when the inputs are left open.

extended industrial temperature range.

-7V). It also meets the requirements of RS422.

DESCRIPTION

overload of ESD damage.

into a high impedance state.



LTC485

Low Power RS485 Interface Transceiver

FEATURES

- Low Power: I_{CC} = 300µA Typ
- Designed for RS485 Interface Applications
- Single 5V supply
- -7V to 12V Bus Common-Mode Range Permits ±7V Ground Difference Between Devices on the Bus
- Thermal Shutdown Protection
- Power-Up/Down Glitch-Free Driver Outputs Permit Live Insertion or Removal of Transceiver
- Driver Maintains High Impedance in Three-State or with the Power Off
- Combined Impedance of a Driver Output and Receiver Allows Up to 32 Transceivers on the Bus
- 70mV Typical Input Hysteresis
- 30ns Typical Driver Propagation Delays with 5ns Skew
- Pin Compatible with the SN75176A, DS75176A and µA96176

V_{CC1}

GND1

V_{CC2}

GND2

Rt

Rt

1 TC485 • TA01

APPLICATIONS

R01

RE1

DF1

DI1

R02

RE2 DE2

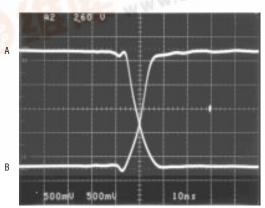
DI2

'sc.con

- Low Power RS485/RS422 Transceiver
- Level Translator

TYPICAL APPLICATION

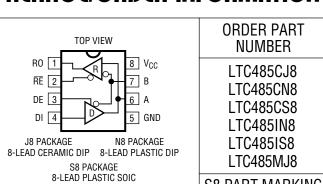
Driver Outputs



LTC485 • TA02

ABSOLUTE MAXIMUM RATINGS

(Note 1)
Supply Voltage 12V
Control Input Voltages –0.5V to V _{CC} + 0.5V
Driver Input Voltage0.5V to V _{CC} + 0.5V
Driver Output Voltage ±14V
Receiver Input Voltage ±14V
Receiver Output Voltages0.5V to V _{CC} + 0.5V
Operating Temperature Range
$LTC485I\dots -40^{\circ}C \le T_A \le 85^{\circ}C$
$LTC485C0°C \le T_A \le 70°C$
$LTC485M$ $-55^{\circ}C \le T_{A} \le 125^{\circ}C$
Lead Temperature (Soldering, 10 sec) 300°C



 $\begin{array}{l} T_{JMAX} = 155^\circ C, \ \theta_{JA} = 100^\circ C/ \ W \ (J) \\ T_{JMAX} = 100^\circ C, \ \theta_{JA} = 130^\circ C/ \ W \ (N) \end{array}$ $T_{JMAX} = 100^{\circ}C, \ \theta_{JA} = 170^{\circ}C/W$ (S)

S8 PART MARKING

485

4851

ELECTRICAL CHARACTERISTICS $V_{CC} = 5V \pm 5\%$, unless otherwise noted. (Notes 2 and 3)

SYMBOL	PARAMETER	CONDITIONS			MIN	ТҮР	MAX	UNITS
V _{OD1}	Differential Driver Output Voltage (Unloaded)	l ₀ = 0		•			5	V
V _{0D2}	Differential Driver Output Voltage (with Load)	R = 50Ω (RS422) R = 27Ω (RS485), Figure 1		•	2 1.5		5	V V
ΔV _{OD}	Change in Magnitude of Driver DifferentialOutput Voltage for Complementary States	R = 27 Ω or R = 50 $\Omega,$ Figure 1		•			0.2	V
V _{OC}	Driver Common-Mode Output Voltage	$R = 27\Omega \text{ or } R = 50$	$\Omega\Omega$, Figure 1	•			3	V
$\Delta V_{0C} $	Change in Magnitude of Driver Common-Mode Output Voltage for Complementary States	R = 27 Ω or R = 50 $\Omega,$ Figure 1		•			0.2	V
VIH	Input High Voltage	DE, DI, RE		•	2			V
V _{IL}	Input Low Voltage	DE, DI, RE		•			0.8	V
I _{IN1}	Input Current	DE, DI, RE		•			±2	μA
I _{IN2}	Input Current (A, B)	$DE = 0, V_{CC} = 0V V_{IN} = 12V \qquad \bullet$	•			±1	mA	
		or 5.25V	$V_{IN} = -7V$	•			-0.8	mA
V _{TH}	Differential Input Threshold Voltage for Receiver	$-7V \le V_{CM} \le 12V$		•	-0.2		0.2	V
ΔV_{TH}	Receiver Input Hysteresis	V _{CM} = 0V		•		70		mV
V _{OH}	Receiver Output High Voltage	$I_0 = -4mA, V_{ID} = 200mV$		•	3.5			V
V _{OL}	Receiver Outpu Low Voltage	$I_0 = 4mA, V_{ID} = -200mV$		•			0.4	V
I _{OZR}	Three-State (High Impedance) Output Current at Receiver	V_{CC} = Max, $0.4V \le V_0 \le 2.4V$		•			±1	μA
R _{IN}	Receiver Input Resistance	$-7V \le V_{CM} \le 12V$		•	12			kΩ
I _{CC}	Supply Current	No Load, Pins 2,	Outputs Enabled	•		500	900	μA
		3, 4 = 0V or 5V	Outputs Disabled	•		300	500	μA
I _{OSD1}	Driver Short-Circuit Current, V _{OUT} = HIGH	$V_0 = -7V$		•	35	100	250	mA
I _{OSD2}	Driver Short-Circuit Current, V _{OUT} = LOW	V ₀ = 10V		•	35	100	250	mA
I _{OSR}	Receiver Short-Circuit Current	$0V \le V_0 \le V_{CC}$		•	7		85	mA

PACKAGE/ORDER INFORMATION

SWITCHING CHARACTERISTICS $V_{CC} = 5V \pm 5\%$, unless otherwise noted. (Notes 2 and 3)

SYMBOL	PARAMETER	CONDITIONS		MIN	ТҮР	MAX	UNITS
t _{PLH}	Driver Input to Output	$R_{DIFF} = 54\Omega, C_{L1} = C_{L2} = 100 pF,$	•	10	30	50	ns
t _{PHL}	Driver Input to Output	(Figures 3 and 5)	•	10	30	50	ns
t _{SKEW}	Driver Output to Output		•		5	10	ns
t _r , t _f	Driver Rise or Fall Time	1		3	15	25	ns
t _{ZH}	Driver Enable to Output High	C _L = 100pF (Figures 4 and 6) S2 Closed	•		40	70	ns
t _{ZL}	Driver Enable to Output Low	C _L = 100pF (Figures 4 and 6) S1 Closed	•		40	70	ns
t _{LZ}	Driver Disable Time from Low	$C_L = 15 pF$ (Figures 4 and 6) S1 Closed	•		40	70	ns
t _{HZ}	Driver Disable Time from High	$C_L = 15 pF$ (Figures 4 and 6) S2 Closed	•		40	70	ns
t _{PLH}	Receiver Input to Output	$R_{DIFF} = 54\Omega, C_{L1} = C_{L2} = 100 pF,$	•	30	90	200	ns
t _{PHL}		(Figures 3 and 7)		30	90	200	ns
t _{SKD}	t _{PLH} – t _{PHL} Differential Receiver Skew				13		ns
t _{ZL}	Receiver Enable to Output Low	C _{RL} = 15pF (Figures 2 and 8) S1 Closed	•		20	50	ns
t _{ZH}	Receiver Enable to Output High	C _{RL} = 15pF (Figures 2 and 8) S2 Closed	•		20	50	ns
t _{LZ}	Receiver Disable from Low	C _{RL} = 15pF (Figures 2 and 8) S1 Closed	•		20	50	ns
t _{HZ}	Receiver Disable from High	C _{RL} = 15pF (Figures 2 and 8) S2 Closed	•		20	50	ns

The
denotes specifications which apply over the full operating temperature range.

Note 3: All typicals are given for $V_{CC} = 5V$ and $T_A = 25^{\circ}C$.

Note 1: Absolute maximum ratings are those beyond which the safety of the device cannot be guaranteed.

Note 2: All currents into device pins are positive; all currents out ot device pins are negative. All voltages are referenced to device ground unless

otherwise specified.

Note 4: The LTC485 is guaranteed by design to be functional over a supply voltage range of 5V \pm 10%. Data sheet parameters are guaranteed over the tested supply voltage range of 5V \pm 5%.

TEST CIRCUITS

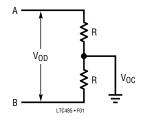


Figure 1. Driver DC Test Load

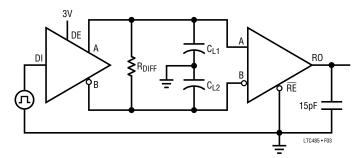


Figure 3. Driver/Receiver Timing Test Circuit

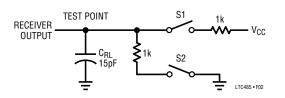


Figure 2. Receiver Timing Test Load

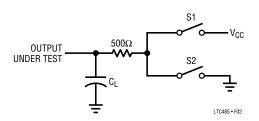


Figure 4. Driver Timing Test Load #2

SWITCHING TIME WAVEFORMS

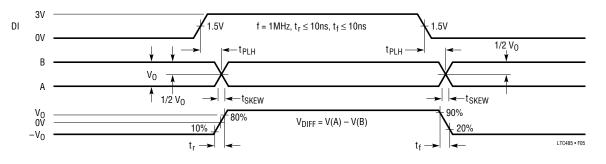


Figure 5. Driver Propagation Delays

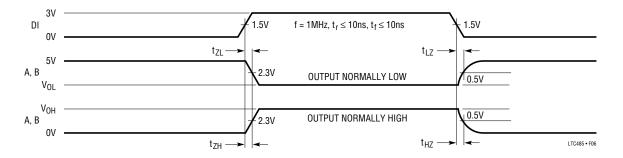


Figure 6. Driver Enable and Disable Times

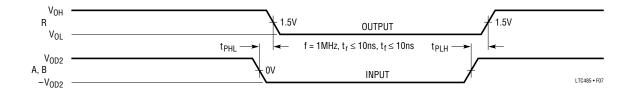


Figure 7. Receiver Propagation Delays

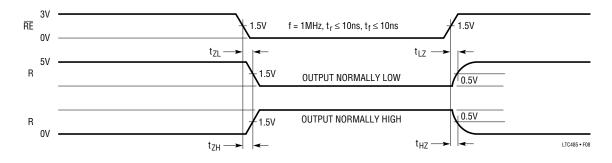


Figure 8. Receiver Enable and Disable Times

FUNCTION TABLES

PIN FUNCTIONS

LTC485 Transmitting

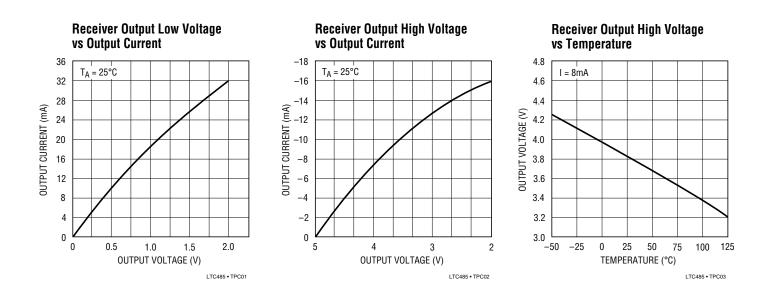
INPUTS			LINE	OUTPUTS		
RE	DE	DI	CONDITION	В	A	
Х	1	1	No Fault	0	1	
Х	1	0	No Fault	1	0	
Х	0	Х	Х	Z	Z	
Х	1	Х	Fault	Z	Z	

LTC485 Receiving

	OUTPUTS		
RE	DE	A – B	R
0	0	≥0.2V	1
0	0	≤-0.2V	0
0	0	Inputs Open	1
1	0	Х	Z

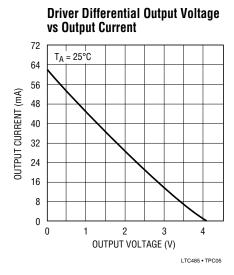
PIN #	NAME	DESCRIPTION
1	RO	Receiver Output. If the receiver output is enabled $(\overline{RE} \text{ low})$, then if A > B by 200mV, RO will be high. If A < B by 200mV, then RO will be low.
2	RE	Receiver Output Enable. A low enables the receiver output, RO. A high input forces the receiver output into a high impedance state.
3	DE	Driver Outputs Enable. A high on DE enables the driver output. A and B, and the chip will function as a line driver. A low input will force the driver outputs into a high impedance state and the chip will function as a line receiver.
4	DI	Driver Input. If the driver outputs are enabled (DE high), then a low on DI forces the outputs A low and B high. A high on DI with the driver outputs enabled will force A high and B low.
5	GND	Ground Connection.
6	А	Driver Output/Receiver Input.
7	В	Driver Output/Receiver Input.
8	V _{CC}	Positive Supply; 4.75 < V _{CC} < 5.25

TYPICAL PERFORMANCE CHARACTERISTICS

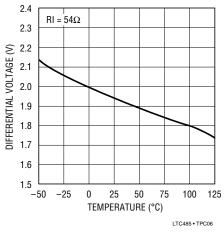


TYPICAL PERFORMANCE CHARACTERISTICS

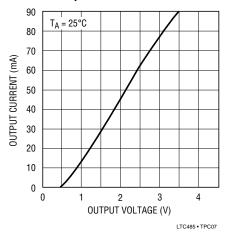
Receiver Output Low Voltage vs Temperature 0.9 I = 8mA 0.8 0.7 OUTPUT VOLTAGE (V) 0.6 0.5 0.4 0.3 0.2 0.1 0 -25 50 75 -50 0 25 100 125 TEMPERATURE (°C) LTC485 • TPC03



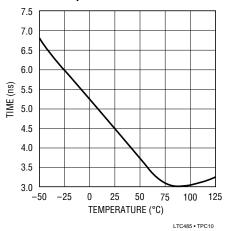
Driver Differential Output Voltage vs Temperature



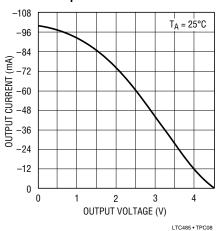
Driver Output Low Voltage vs Output Current



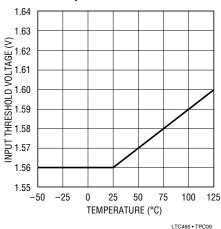
Receiver $|t_{PLH} - t_{PHL}|$ vs Temperature



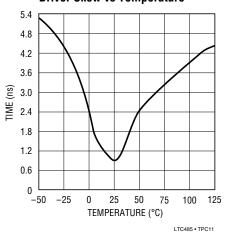
Driver Output High Voltage vs Output Current



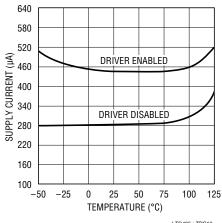
TTL Input Threshold vs Temperature



Driver Skew vs Temperature



Supply Current vs Temperature



LTC485 • TPC12

APPLICATIONS INFORMATION

Basic Theory of Operation

Previous RS485 transceivers have been designed using bipolar technology because the common-mode range of the device must extend beyond the supplies and the device must be immune to ESD damage and latchup. Unfortunately, the bipolar devices draw a large amount of supply current, which is unacceptable for the numerous applications that require low power consumption. The LTC485 is the first CMOS RS485/RS422 transceiver which features ultra-low power consumption without sacrificing ESD and latchup immunity.

The LTC485 uses a proprietary driver output stage, which allows a common-mode range that extends beyond the power supplies while virtually eliminating latchup and providing excellent ESD protection. Figure 9 shows the LTC485 output stage while Figure 10 shows a conventional CMOS output stage.

When the conventional CMOS output stage of Figure 10 enters a high impedance state, both the P-channel (P1) and the N-channel (N1) are turned off. If the output is then driven above V_{CC} or below ground, the P + /N-well diode

(D1) or the N + /P-substrate diode (D2) respectively will turn on and clamp the output to the supply. Thus, the output stage is no longer in a high impedance state and is not able to meet the RS485 common-mode range requirement. In addition, the large amount of current flowing through either diode will induce the well known CMOS latchup condition, which could destroy the device.

The LTC485 output stage of Figure 9 eliminates these problems by adding two Schottky diodes, SD3 and SD4. The Schottky diodes are fabricated by a proprietary modification to the standard N-well CMOS process. When the output stage is operating normally, the Schottky diodes are forward biased and have a small voltage drop across them. When the output is in the high impedance state and is driven above V_{CC} or below ground, the parasitic diodes D1 or D2 still turn on, but SD3 or SD4 will reverse bias and prevent current from flowing into the N-well or the substrate. Thus, the high impedance state is maintained even with the output voltage beyond the supplies. With no minority carrier current flowing into the N-well or substrate, latchup is virtually eliminated under power-up or power-down conditions.

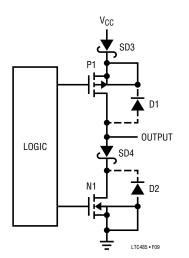


Figure 9. LTC485 Output Stage

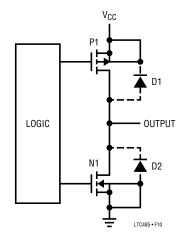


Figure 10. Conventional CMOS Output Stage

APPLICATIONS INFORMATION

The LTC485 output stage will maintain a high impedance state until the breakdown of the N-channel or P-channel is reached when going positive or negative respectively. The output will be clamped to either V_{CC} or ground by a Zener voltage plus a Schottky diode drop, but this voltage is way beyond the RS485 operating range. This clamp protects the MOS gates from ESD voltages well over 2000V. Because the ESD injected current in the N-well or substrate consists of majority carriers, latchup is prevented by careful layout techniques.

Propagation Delay

Many digital encoding schemes are dependent upon the difference in the propagation delay times of the driver and the receiver. Using the test circuit of Figure 13, Figures 11 and 12 show the typical LTC485 receiver propagation delay.

The receiver delay times are:

$$|t_{PLH} - t_{PHL}| = 9$$
ns Typ, $V_{CC} = 5V$

The driver skew times are:

Skew = 5ns Typ,
$$V_{CC}$$
 = 5V
10ns Max, V_{CC} = 5V, T_A = -40°C to 85°C

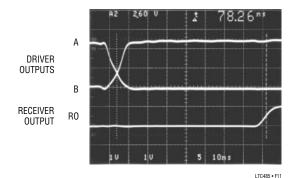


Figure 11. Receiver t_{PHL}

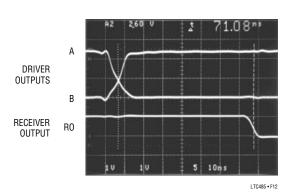


Figure 12. Receiver t_{PLH}

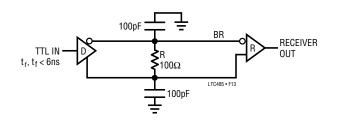


Figure 13. Receiver Propagation Delay Test Circuit

APPLICATIONS INFORMATION

LTC485 Line Length vs Data Rate

The maximum line length allowable for the RS422/RS485 standard is 4000 feet.

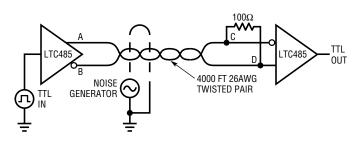


Figure 14. Line Length Test Circuit

Using the test circuit in Figure 14, Figures 15 and 16 show that with ~ $20V_{P-P}$ common-mode noise injected on the line, The LTC485 is able to reconstruct the data stream at the end of 4000 feet of twisted pair wire.

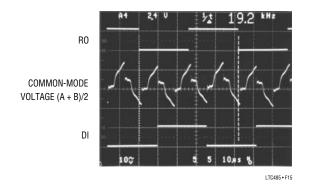


Figure 15. System Common-Mode Voltage at 19.2kHz

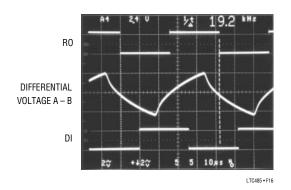


Figure 16. System Differential Voltage at 19.2kHz

Figures 17 and 18 show that the LTC485 is able to comfortably drive 4000 feet of wire at 110kHz.

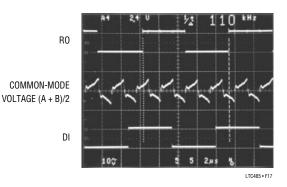


Figure 17. System Common-Mode Voltage at 110kHz

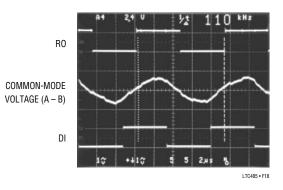


Figure 18. System Differential Voltage at 110kHz

When specifying line length vs maximum data rate the curve in Figure 19 should be used:

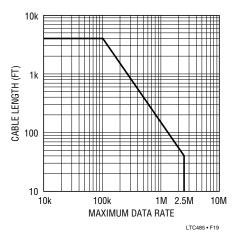
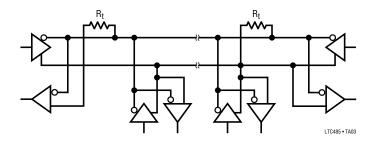


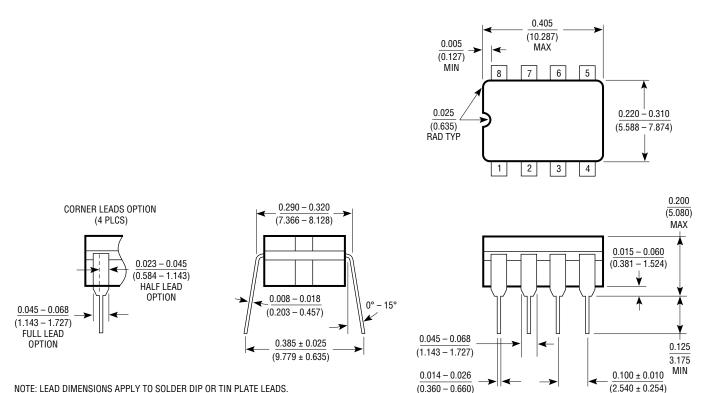
Figure 19. Cable Length vs Maximum Data Rate

TYPICAL APPLICATIONS

Typical RS485 Network



PACKAGE DESCRIPTION Dimensions in inches (millimeters) unless otherwise noted.

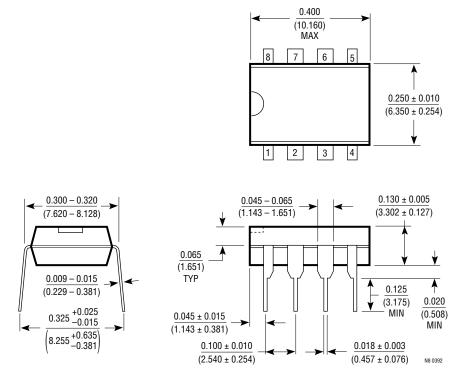


J8 Package 8-Lead Ceramic DIP

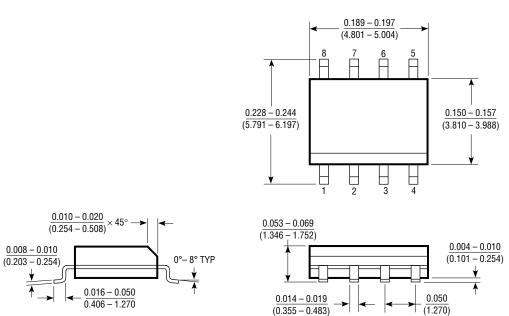
J8 0293

PACKAGE DESCRIPTION Dimensions in inches (millimeters) unless otherwise noted.

N8 Package 8-Lead Plastic DIP



S8 Package 8-Lead Plastic SOIC



BSC

SO8 0392

NORTHEAST REGION

Linear Technology Corporation One Oxford Valley 2300 E. Lincoln Hwy.,Suite 306 Langhorne, PA 19047 Phone: (215) 757-8578 FAX: (215) 757-5631

Linear Technology Corporation

266 Lowell St., Suite B-8 Wilmington, MA 01887 Phone: (508) 658-3881 FAX: (508) 658-2701

FRANCE

Linear Technology S.A.R.L. Immeuble "Le Quartz" 58 Chemin de la Justice 92290 Chatenay Malabry France Phone: 33-1-41079555 FAX: 33-1-46314613

GERMANY

Linear Techonolgy GMBH

Untere Hauptstr. 9 D-85386 Eching Germany Phone: 49-89-3197410 FAX: 49-89-3194821

JAPAN

Linear Technology KK 5F YZ Bldg. lidabashi, Chiyoda-Ku Tokyo, 102 Japan Phone: 81-3-3237-7891 FAX: 81-3-3237-8010

U.S. Area Sales Offices

SOUTHEAST REGION Linear Technology Corporation 17060 Dallas Parkway Suite 208 Dallas, TX 75248 Phone: (214) 733-3071 FAX: (214) 380-5138

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International Sales Offices

KOREA

Linear Technology Korea Branch Namsong Building, #505 Itaewon-Dong 260-199 Yongsan-Ku, Seoul Korea Phone: 82-2-792-1617 FAX: 82-2-792-1619

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Linear Technology Corporation 782 Sycamore Dr. Milpitas, CA 95035 Phone: (408) 428-2050 FAX: (408) 432-6331

TAIWAN

Linear Technology Corporation Rm. 801, No. 46, Sec. 2 Chung Shan N. Rd. Taipei, Taiwan, R.O.C. Phone: 886-2-521-7575 FAX: 886-2-562-2285

UNITED KINGDOM

Linear Technology (UK) Ltd. The Coliseum, Riverside Way Camberley, Surrey GU15 3YL United Kingdom Phone: 44-276-677676 FAX: 44-276-64851

World Headquarters

Linear Technology Corporation 1630 McCarthy Blvd. Milpitas, CA 95035-7487 Phone: (408) 432-1900 FAX: (408) 434-0507