



# LD7552

2/21/2005

## Green-Mode PWM Controller

### General Description

The LD7552 is a low cost, low startup current, current mode PWM controller with green-mode power-saving operation. The integrated functions such as the leading-edge blanking of the current sensing, internal slope compensation and the small package provide the users a high efficiency, minimum external component counts, and low cost solution for AC/DC power applications.

The special green-mode control does not only achieve low power consumption but also offer a non-audible-noise operation when the LD7552 operates under light load or no load condition.

The LD7552 is designed for the switching adaptor with 30W~60W output. The LD7552 is offered in both SOP-8 and DIP-8 package.

† Patent pending

### Features

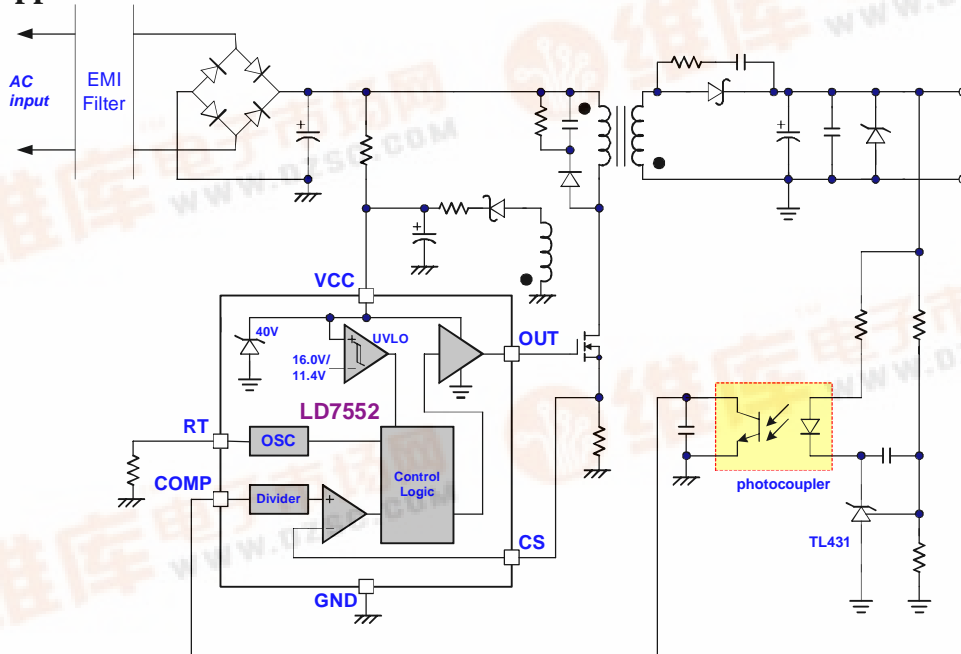
- High-Voltage CMOS Process with Excellent ESD Protection
- Very Low Startup Current (Typical 5μA)
- Under Voltage Lockout (UVLO)
- Current Mode Control with Cycle-by-Cycle Peak Current Limiting
- Leading-Edge Blanking on CS Pin
- Programmable Switching Frequency
- Internal Slope Compensation
- Proprietary Green-Mode Control for Power Saving<sup>①</sup>
- Non-audible-noise Green Mode Control
- 500mA Driving Capability

### Applications

- Switching AC/DC Adaptor and Battery Charger
- Open Frame Switching Power Supply
- 384X Replacement

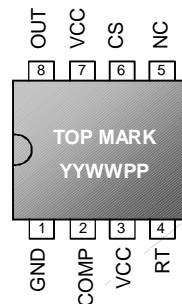
<sup>①</sup> Note: Please see Application Information

### Typical Application



## Pin Configuration

SOP-8 & DIP-8 (TOP VIEW)



YY: Year code (D: 2004, E: 2005.....)  
WW: week code  
PP: production code

## Ordering Information

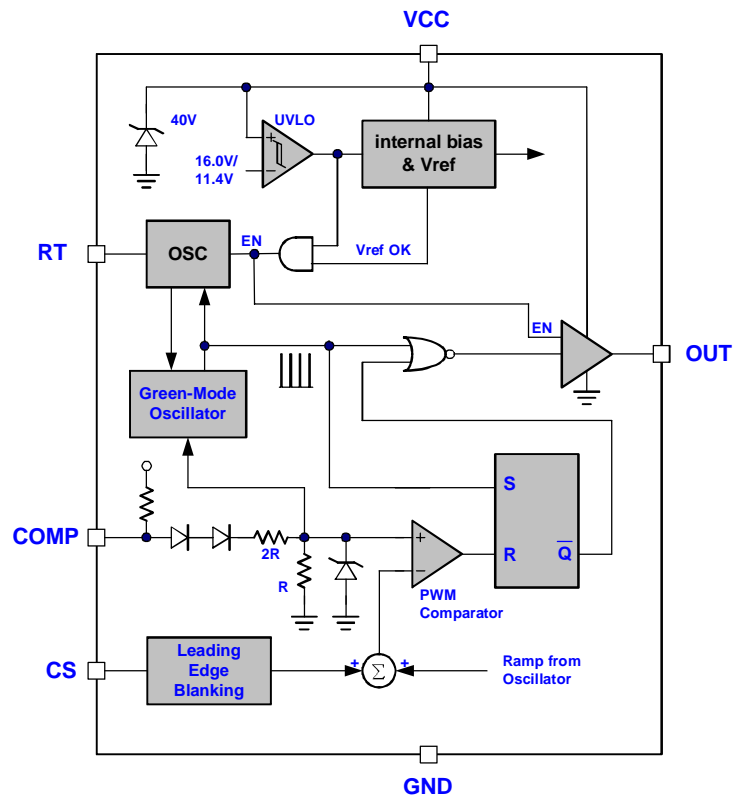
Part number	Package	TOP MARK	Shipping
LD7552 IS	SOP-8	LD7552IS	2500 /tape & reel
LD7552 BS	SOP-8 (PB Free)	LD7552BS	2500 /tape & reel
LD7552 IN	DIP-8	LD7552IN	3600 /tube /carton
LD7552 BN	DIP-8 (PB Free)	LD7552BN	3600 /tube /carton

## Pin Descriptions

PIN	NAME	FUNCTION
1	GND	Ground
2	COMP	Voltage feedback pin (same as the COMP pin in UC384X), By connecting a photo-coupler to close the control loop and achieve the regulation.
3	VCC	Supply voltage pin
4	RT	This pin is to program the switching frequency. By connecting a resistor to ground to set the switching frequency.
5	NC	Unconnected pin
6	CS	Current sense pin, connect to sense the MOSFET current
7	VCC	Supply voltage pin
8	OUT	Gate drive output to drive the external MOSFET



## Block Diagram



## Absolute Maximum Ratings

Supply Voltage VCC.....	36V
COMP, RT, CS.....	-0.3 ~7V
Operating Junction Temperature.....	150°C
Storage Temperature Range.....	-65°C to 150°C
Package thermal resistance (DIP-8).....	100°C/W
Package thermal resistance (SOP-8).....	160°C/W
Lead temperature (LD7552IS & LD7552IN, Soldering, 10sec).....	230°C
Lead temperature (LD7552BS & LD7552BN, Soldering, 10sec).....	260°C

### Caution:

Stresses beyond the ratings specified in "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress only rating and operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied.



## Electrical Characteristics

(T<sub>A</sub> = +25°C unless otherwise stated, V<sub>CC</sub>=15.0V)

PARAMETER	CONDITIONS	MIN	TYP	MAX	UNITS
<b>Supply Voltage (Vcc Pin)</b>					
Startup Current			5	25	μA
Operating Current	V <sub>COMP</sub> =0V		3	4	mA
	V <sub>COMP</sub> =3V		2		mA
	V <sub>COMP</sub> =open		0.7		mA
UVLO (off)		10.4	11.4	12.4	V
UVLO (on)		14.8	16.0	17.5	V
<b>Voltage Feedback (Comp Pin)</b>					
Short Circuit Current	V <sub>COMP</sub> =0V		2.2	3.0	mA
Open Loop Voltage	COMP pin open		5.0		V
Green Mode Threshold VCOMP			2.35		V
<b>Current Sensing (CS Pin)</b>					
Maximum Input Voltage		0.80	0.85	0.90	V
Leading Edge Blanking Time			250		nS
Input impedance			50		KΩ
Delay to Output			300		nS
<b>Oscillator (RT pin)</b>					
Frequency	RT=100KΩ	61.5	66.5	71.5	KHz
Green Mode Frequency	Fs=66.5KHz		20		KHz
Temp. Stability	(-30°C ~85°C)			5	%
Voltage Stability	(VCC=12V-30V)			2	%
<b>Gate Drive Output (OUT Pin)</b>					
Output Low Level	VCC=15V, I <sub>o</sub> =20mA			1	V
Output High Level	VCC=15V, I <sub>o</sub> =20mA	9			V
Rising Time	Load Capacitance=1000pF			160	nS
Falling Time	Load Capacitance=1000pF			60	nS



### Typical Performance Characteristics

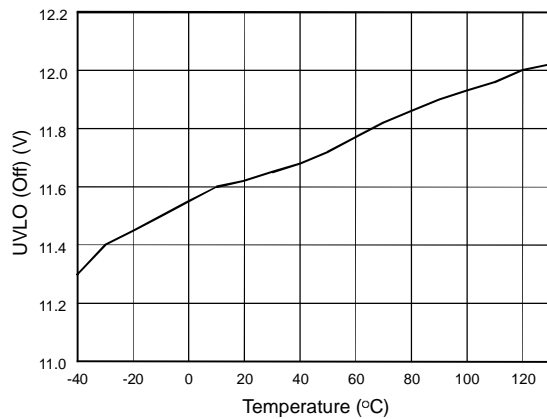


Fig. 1 UVLO (Off) vs. Temperature

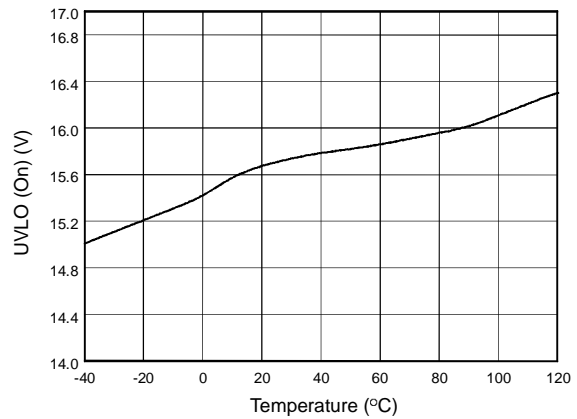


Fig. 2 UVLO (On) vs. Temperature

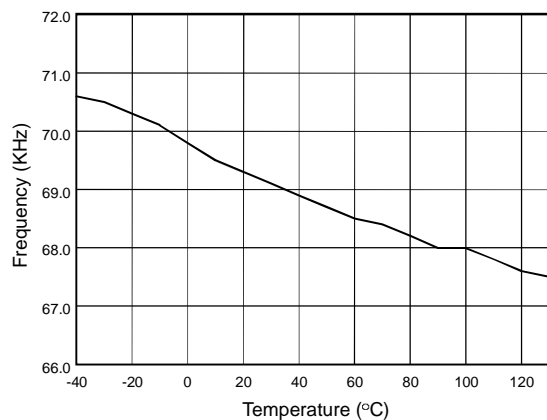


Fig. 3 Frequency vs. Temperature

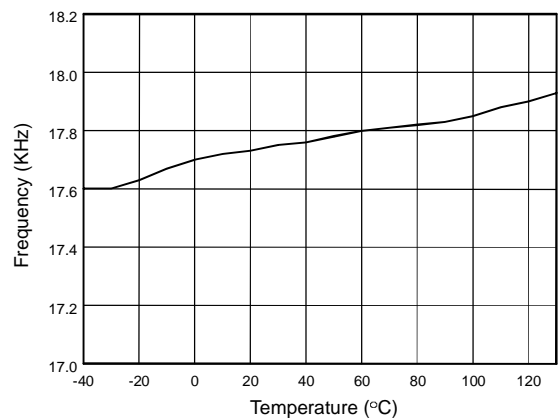


Fig. 4 Green-Mode Frequency vs. Temperature

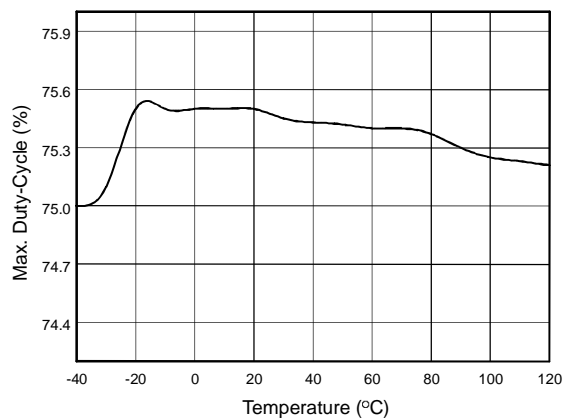


Fig. 5 Duty-Cycle (max.) vs. Temperature



## Application Information

### Operation Overview

The LD7552 is optimized to achieve power saving and minimize the external components counts. The device incorporated several functions to make it ideal to use in switching power supplies and switching adaptors.

### Under Voltage Lockout (UVLO)

An UVLO comparator is included to detect the voltage on the Vcc pin to ensure the supply voltage enough to power on the LD7552 PWM controller and in addition to drive the power MOSFET. As shown in Fig. 6, a hysteresis is provided to prevent the shutdown from the voltage dip during startup. The turn-on and turn-off threshold level are set at 16V and 11.4V, respectively.

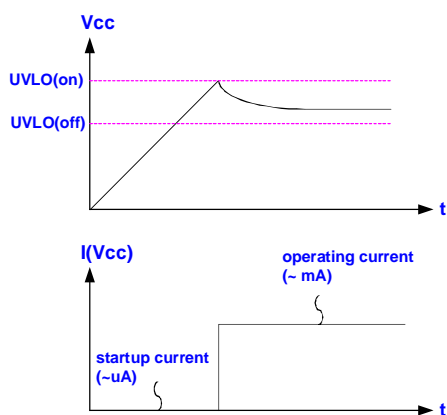


Fig. 6

### Startup Current and Startup Circuit

The typical startup circuit as shown in Fig. 7 powers up the LD7552. During the startup transient, the Vcc is lower than the UVLO threshold thus there is no gate pulse generated from LD7552 to drive power MOSFET. Therefore, the current through R1 is to provide the startup current as well as charge the capacitor C1. Whenever the Vcc voltage is higher enough to power on the LD7552 and further to deliver the gate drive signal, the supply current is provided from the auxiliary winding of the transformer. The lower startup current requirement on the PWM controller will help to increase the R1 value and then reduce the power consumption on R1. By using CMOS process and the

special circuit design, the maximum startup current of LD7552 is only 25μA.

Theoretically, R1 can be very high resistance value. However, higher R1 will cause longer startup time. By properly select the value of R1 and C1, it can be optimized under the consideration of R1 power consumption and the startup time.

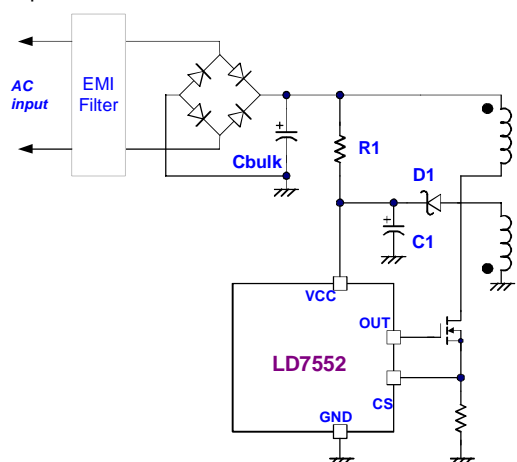


Fig. 7

### Current Sensing and Leading-edge Blanking

The typical current mode PWM controller feedbacks both current signal and voltage signal to close the control loop and achieve regulation. As shown in Fig. 8, the LD7552 detects the primary MOSFET current from the CS pin, which is not only for the peak current mode control but also for the pulse-by-pulse current limit. The maximum voltage threshold of the current sensing pin is set as 0.85V. Thus the MOSFET peak current can be calculated as:

$$I_{PEAK(MAX)} = \frac{0.85V}{R_S}$$

A 250nS leading-edge blanking time is included in the input of CS pin to prevent the false-trigger caused by the current spike and further to eliminate the need of R-C filter which is usually needed in the typical UC384X application (Fig. 9).



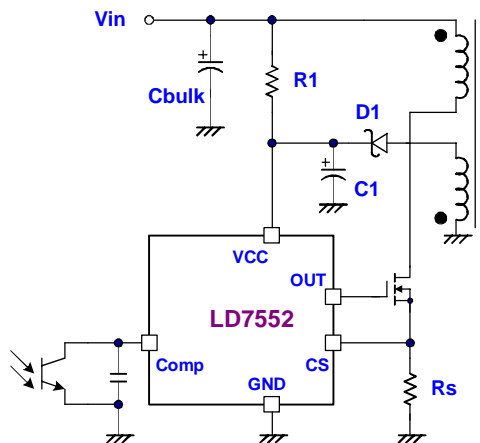


Fig. 8

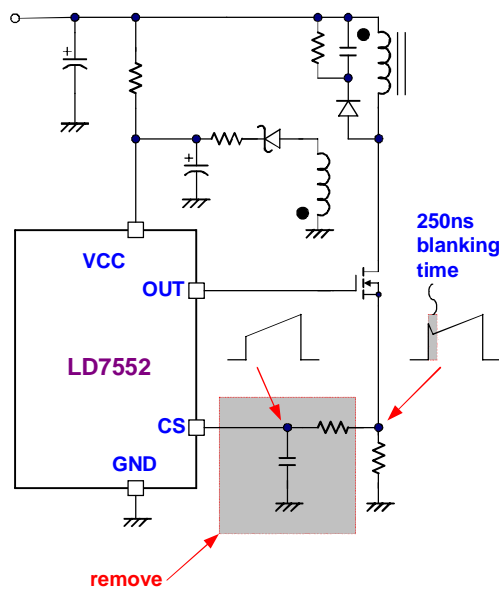


Fig. 9

## Output Stage and Maximum Duty-Cycle

An output stage of a CMOS buffer, with typical 500mA driving capability, is incorporated to drive a power MOSFET directly. And the maximum duty-cycle of LD7552 is limited to 75% to avoid the transformer saturation.

## Oscillator and Switching Frequency

Connecting a resistor from RT pin to GND according to the equation can program the normal switching frequency:

$$f_{SW} = \frac{66.5}{RT(K\Omega)} \times 100(KHz)$$

The suggested operating frequency range of LD7552 is within 50KHz to 130KHz.

## Voltage Feedback Loop

The voltage feedback signal is provided from the TL431 in the secondary side through the photocoupler to the COMP pin of LD7552. The input stage of LD7552, like the UC384X, is with 2 diodes voltage offset then feeding into the voltage divider with 1/3 ratio, that is,

$$V_{+(PWM\text{COMPARATOR})} = \frac{1}{3} \times (V_{COMP} - 2V_F)$$

A pull-high resistor is embedded internally thus can be eliminated on the external circuit.

## Internal Slope Compensation

A fundamental issue of current mode control is the stability problem when its duty-cycle is operated more than 50%. To stabilize the control loop, the slope compensation is needed in the traditional UC384X design by injecting the ramp signal from the RT/CT pin through a coupling capacitor. In LD7552, the internal slope compensation circuit has been implemented to simplify the external circuit design.

## On/Off Control

The LD7552 can be controlled to turn off by pulling COMP pin to lower than 1.2V. The gate output pin of LD7552 will be disabled immediately under such condition. The off mode can be released when the pull-low signal is removed.

## Dual-Oscillator Green-Mode Operation

There are many difference topologies has been implemented in different chips for the green-mode or power saving requirements such as "burst-mode control", "skipping-cycle Mode", "variable off-time control "...etc. The



basic operation theory of all these approaches intended to reduce the switching cycles under light-load or no-load condition either by skip some switching pulses or reduce the switching frequency.

What LD7552 used to implement the power-saving operation is Leadtrend Technology's own IP<sup>②</sup>. In such approach, as shown in the block diagram, 2 oscillators are implemented in LD7552. The first oscillator is to take care the normal switching frequency, which can be set by the RT pin through an external resistor. Under this operation mode, as shown in Fig. 10, the 2nd oscillation (green-mode oscillator) is not activated. Therefore, the rising-time and the falling-time of the internal ramp will be constant to achieve good stability over all temperature range. Under the normal operation, this oscillator is dominated the switching frequency.

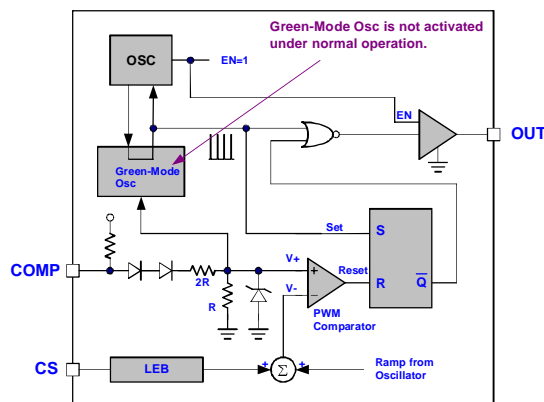


Fig. 10

As shown in Fig. 11, the green-mode oscillator detects the Comp pin signal to determine if it is within the green-mode operation. When the detected signal  $V_+$  is lower than the green-mode threshold  $V_{green}$ , the green-mode oscillator is on. The green-mode oscillator, implemented by a VCO (voltage controlled oscillator), is a variable frequency oscillator. The rising time of the VCO is proportional to  $(V_{green} - V_+)$ , thus the lower voltage on  $V_+$  will generate longer rising time on VCO as well as lower frequency on VCO.

By using this dual-oscillator control, the green-mode frequency can be well controlled and further to avoid the generation of audible noise.

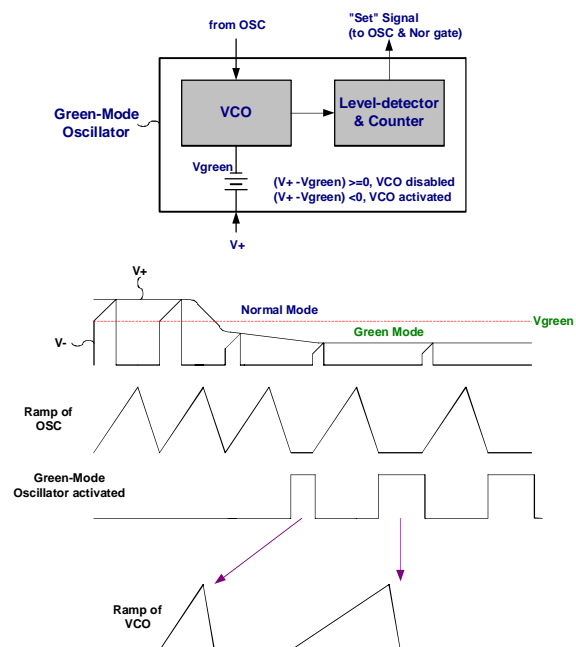
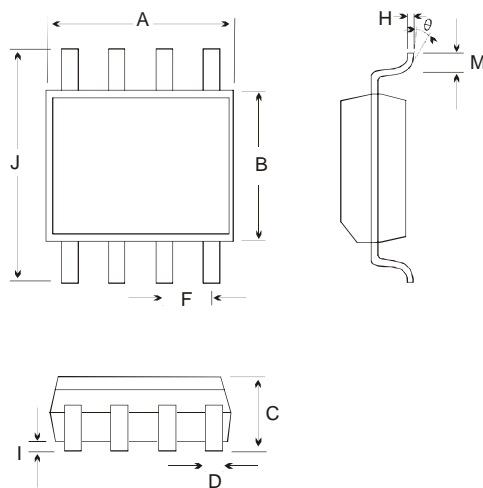


Fig. 11

② Note: Patent pending



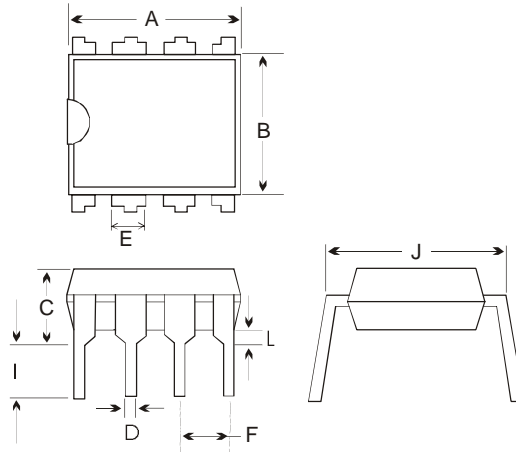


**Package Information**
**SOP-8**


Symbols	Dimensions in Millimeters		Dimensions in Inch	
	MIN	MAX	MIN	MAX
A	4.801	5.004	0.189	0.197
B	3.810	3.988	0.150	0.157
C	1.346	1.753	0.053	0.069
D	0.330	0.508	0.013	0.020
F	1.194	1.346	0.047	0.053
H	0.178	0.229	0.007	0.009
I	0.102	0.254	0.004	0.010
J	5.791	6.198	0.228	0.244
M	0.406	1.270	0.016	0.050
θ	0°	8°	0°	8°



## DIP-8



Symbol	Dimension in Millimeters		Dimensions in Inches	
	Min	Max	Min	Max
A	9.017	10.160	0.355	0.400
B	6.096	7.112	0.240	0.280
C	-----	5.334	-----	0.210
D	0.356	0.584	0.014	0.023
E	1.143	1.778	0.045	0.070
F	2.337	2.743	0.092	0.108
I	2.921	3.556	0.115	0.14
J	7.366	8.255	0.29	0.325
L	0.381	-----	0.015	-----

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