ECN3053 is a single chip driver IC which has 6 MOS-Gated devices for its output. It is suitable for controlling 3-phase DC brushless motors and 3-phase induction motors.

#### Functions

- Lower arm Over current (OC) Protection
- Under voltage Protection
- Fault Output function

#### Features

- It can be controlled by PWM with 6 inputs from an external microprocessor.
- 6 logic inputs are compatible with 5V CMOS and LSTTL outputs.



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SOP-28

#### 1. General

This specification shall be applied to the following semiconductor integrated circuits.

- 1) Type : ECN3053F
- 2) Application : 3-phase Brushless Motor, 3-phase Induction Motor
- 3) Structure : Monolithic IC
- 4) Package : SOP28

#### 2. Maximum Allowable Ratings (Ta=25°C)

No.	ITEMS	SYMBOLS	UNIT	VALUES	CONDITIONS
1	Output Device Breakdown	Vbv	V	620	Between Vcu,v,w & GL1
	voltage				
2	GL2 terminal voltage	Vgl2	V	-5~Vcc	Vcc=18Vmax at GL2=-5V
3	U,V,W terminal Voltage	Vu,v,w	V	-5~600	
4	Supply voltage	Vcc	V	20	
5	Input voltage	Vin	V	-0.5~Vcc+0.5	
6	Operating Junction Temperature	Tjop	°C	-20~125	
7	Storage Temperature	Tstg	°C	-40~150	

Note 1 : Thermal resistance Rja

PACKAGE	SOP28	Unit
Single	121	°C/W
Mounted	84	°C/W
PCB size, Density *	120x21x1.6 (30%)	mm

\* This figure varies depending on the mounting condition.

#### 3. Electrical Characteristics

Unless otherwise noted, Ta=25 C, Vu,v,w to GL1=374V,Vcc=15V.(suffix T=top, B=bottom arm)

No	o ITEMS		SYMBOLS	UNIT	MIN.	TYP.	MAX.	CONDITIONS
1	Stand-by current		Is1	mA	-	6.5	10	Vin=H or L , Between Vcc-GL1
			Is2	μΑ	-	15	30	Between Vcu-U,Vcv-V,Vcw-W 15V, Vin=H or L
2	Input Voltage (Output is	sL)	VIH	V	3.5	-	-	Input=H or L
	Input Voltage (Output i	s H)	VIL	V	-	-	1.5	
3	Output Source Current		Io+	А	0.2	0.25	-	Vcu-PGU,Vcv-PGV, Vcw-PGW =15V, Vcc-NGU,V,W =15V PW<10µs
4	Output Sink Current		Io-	А	0.4	0.5	-	PGU-U,PGV-V, PGW-W =15V, NGU,V,W -GL2=15V PW<10µs
5	High level Output Volta	lge	VOH	mV	-	-	100	Vcu,v,w-PGU,V, W & Vcc-NGU,V,W Vin=0, Io=0
6	Low level Output Volta	ge	VOL	mV	-	-	100	PGU,V,W-U,V,W & NGU,V,W -GL2 Vin=5V,Io=0
7	Leakage Current at HV	terminal	IL	μA	-	-	50	Vcu,v,w=U,V,W=600V
8	Input Current		IIL	μΑ	-200	-	-	Vin=0V Internal Pull up R=200kΩ
9	Input Current		IIH	μΑ	-120	-	-	Vin=5V Internal Pull up R=200kΩ
10	Vcc Under voltage	Negative Going	Vuvb	V	9.5	10.5	11.6	
		<b>Reset Hysterisis</b>	Vrhb	V	0.1	0.4	0.9	
11	Vcu,v,w Under Voltage	Negative Going	Vuvt	V	8.9	10.5	12.1	
		<b>Reset Hysterisis</b>	Vrht	V	0.1	0.4	0.9	
12	2 OC Input Positive Going threshold		Voc	V	0.44	0.49	0.54	
13	Fault Output On Resista	ince	Ronf	Ω	-	300	400	F-GL1=0.5V
14	Turn On Delay Time		ton	μs	-	0.8	1.5	CL=1000pF RL=0
15	Turn Off Delay Time		toff	μs	-	0.5	1.2	CL=1000pF RL=0
16	OC Output to Output Sh	utdown Delay	toc	μs	-	0.7	1.7	CL=1000pF RL=0
17	OC to Fault Delay		tflt	μs	-	0.6	1.6	CL=1000pF RL=0
18	Fault Reset Delay Time		tflrs	μs	6.5	10	20	CL=1000pF RL=0
19	Fault Output terminal V	oltage	Vflt	V	-0.5	-	Vcc+0.5	
20	Fault Output Sink Curre	Iflt	mA	4	-	-	V(F&GL)=2V	
21	VB Output Voltage	VB	V	6.8	7.5	8.2		
22	22 VB Output Current			mA	25	-	-	Delta Vload=0.1V
23	23 Op-Amp Input Offset Voltage			mV	-	-	30	GL2=A-=0.2V
24	24 Op-Amp High Level Output Voltage			V	5.0	7.5	-	A-=0V GL2=1V
25	25 Op-Amp Low Level Output Voltage			mV	-	-	20	A-=1V GL2=0V
26	26 Op-Amp Output Source Current			mA	1.0	-	-	A-=0V GL2=1V AO=4V
27	<b>Op-Amp Output Sink C</b>	urrent	Isnka	mA	1.0	-	-	A-=1V GL2=0V AO=2V

Note 1: Vuvb, Vrhb, Vuvt and Vrht are defined and shown in Fig. 1.





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#### 4. Truth Table

INPUT		OC	U phase		V phase		W phase	
		Input	Top arm	Bot.arm	Top arm	Bot.arm	Top arm	Bot.arm
SUT	L		ON	-	-	-	-	-
	Н		OFF	-	-	-	-	-
SUB	L		-	ON	-	-	-	-
	Н		-	OFF	-	-	-	-
SVT	L		-	-	ON	-	-	-
	Н		-	-	OFF	-	-	-
SVB	L	L	-	-	-	ON	-	-
	Н		-	-	-	OFF	-	-
SWT	L		-	-	-	-	ON	-
	Н		-	-	-	-	OFF	-
SWB	L		-	-	-	-	-	ON
	Н		-	-	-	-	-	OFF
-	-	Н	OFF	OFF	OFF	OFF	OFF	OFF
SUT,SUB	L	-	OFF	OFF	-	-	-	-
SVT,SVB	L	-	_	-	OFF	OFF	-	-
SWT,SWB	L	-	-	-	-	-	OFF	OFF

Note 1: Fault output level is referenced Low when over current or under voltage for Vcc is detected.

Note 2: Over current protection works when the voltage drop of the external sensing resistor exceeds the threshold voltage Voc(typical 0.49V). In this case all six outputs are turned off and Fault output level becomes low.

Reset after detection is done by feeding high signal to all six inputs or re-supplying Vcc voltage. Note 3: The output signal for Fault is reset by feeding high signal to all six inputs.

5. Definition of switching delay





#### 6. Recommended Operating Conditions

ЪT		arn an ar a			
NO.	ITEMS	SYMBOLS	UNIT	VALUES TOL.	CONDITIONS
1	Power Supply Voltage	Vcc	V	13.5~16.5	
2	PWM Frequency	fpwm	kHz	1~20	
3	VB Smoothing Capacitor	Со	μF	> 0.22	Stress voltage:VB
4	Boot Strap Capacitor	Cb	μF	3.3	Stress voltage:Vcc
5	Boot Strap Diodes	Db	Hitach	ni DFG1C6	600V/1.0A
			DFM1	F6 or equivalent	$\leq 0.1 \mu s$
6	Sensing Resistor	Rs	Ω	Note 1	
7	OC Filtering Resistor	R1	Ω	Note 2	
8	OC Filtering Capacitor	C1	μF	Note 2	
9	Load resistor for F terminal	Rf	kΩ	<u>≥</u> 5.6	

Note 1. Over-current detection level is determined by the following equation Ioc=Voc/Rs

Note.2 This IC has filters of 0.4us for noise reduction.

But appropriate R1, C1 should be added when noise can not be removed.

#### 7. Pin Assignment

<SOP28>

	-			
1	VCC	•	VCU	28
2	SUT		PGU	27
3	SVT		U	26
4	SWT		N.C.	25
5	SUB		VCV	24
6	SVB		PGV	23
7	SWB		V	22
8	F		VCW	21
9	OC		PGW	20
10	CB		W	19
11	AO		N.C.	18
12	A-		NGU	17
13	GL1		NGV	16
14	GL2		NG	15
				1

#### 8. Outline Drawing



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