

<u>捷多邦, 专业PCB打样工厂, 24小时</u> Am26S02 加急出货

Am26S02

Schottky Dual Retriggerable, Resettable Monostable Multivibrator

DISTINCTIVE CHARACTERISTICS

- Advanced Schottky technology with PNP inputs
- Retriggerable 0% to 100% duty cycle
- 28ns to ∞ output pulse width range
- 100kΩ maximum timing resistor value
- Am26S02XM typical pulse width change of only 1.0% over -55°C to + 125°C with R_x = 100kΩ
- Am26S02XC typical pulse width change of only 0.4% over 0°C to + 70°C with $R_x = 100K\Omega$

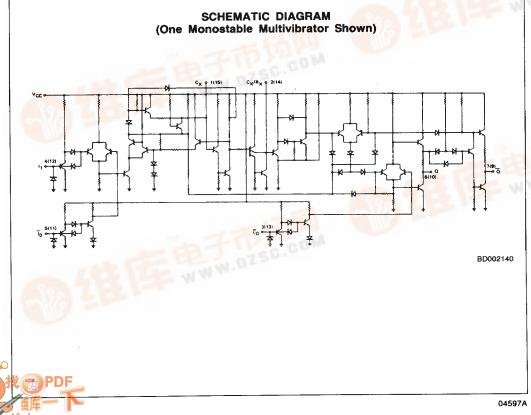
GENERAL DESCRIPTION

The Am26S02 is a dual DC level sensitive, retriggerable, resettable monostable multivibrator built using advanced Schottky technology. The output pulse duration and accuracy depend on the external timing components of each multivibrator. The Am26S02 features PNP inputs to reduce the input loading.

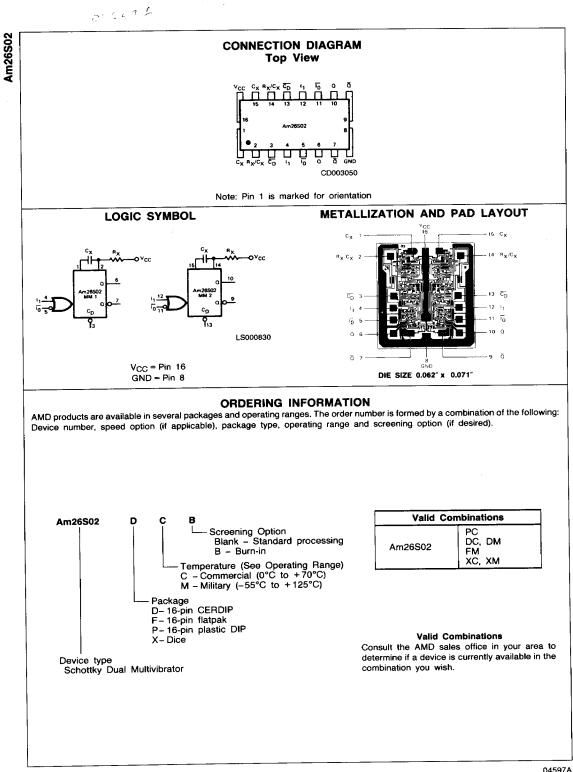
Provision is made on each multivibrator circuit for triggering the PNP inputs on either the rising or falling edge of an input signal by including an inverting and non-inverting trigger input. These PNP inputs are DC coupled making triggering independent of the input rise or fall time. Each time the monostable trigger input is activated from the OR trigger gate, full pulse length triggering occurs independent of the present state of the monostable.

The direct clear PNP input allows a timing cycle to be terminated at any time during the cycle. A LOW on the clear input forces the Q output LOW regardless of the \overline{i}_0 or \overline{i}_1 inputs.

The Am26S02XM has a typical pulse width change of only 1.0% over the full military -55°C to + 125°C temperature range and the Am26S02XC has a typical pulse width change of only 0.4% over the commercial 0°C to + 70°C temperature range with a $R_x = 100 k \Omega$.



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PIN DESCRIPTION

Pin No.	Name	1/0	Description
13	C _D	1	Asynchronous direct CLEAR. A LOW on the clear input resets the monostable regardless of the other inputs
11	Ĩ0	1	Active-LOW input. With I1 LOW, a HIGH-to-LOW transition will trigger the monostable.
12	11	1	Active-HIGH input. With I0 HIGH, a LOW-to-HIGH transition will trigger the monostable.
10	Q	0	The TRUE monostable output.
9	a	0	The Complement monostable output.

Input/

Output

ā

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Q

Îο

h.

ČD

Сх

R_X/C_X

GND

FUNCTION TABLE

2

	INPUTS			OUTPUTS		
OSCD	Ч	4	l _o	Q		
L	x	х	L	н		
н	н	х	L	н		
н	L	Ţ	Л	J		
н	х	L	L	н		
н	t	н	л	പ		

- = HIGH н
- = LOW L
- = LOW-to-HIGH Transition t

= HIGH-to-LOW Transition ţ = LOW-HIGH-LOW Pulse

П പ = HIGH-LOW-HIGH Pulse

= Don't Care х

Сх Mono 1 1 _ R_X/C_X 2 _ C̄D 3 0.4 0.4 4 I₁ Îο 5 0.4 6 Q -

Mono 2

7

8

9

10

11

12

13

14

15

Pins No.'s

Vcc 16 --A Schottky TTL Unit Load is defined as 50µA measured at 2.7V HIGH and -2.0mA measured at 0.5V LOW.

2. Remote adjustment of timing.

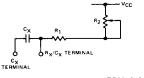
OPERATION RULES

TIMING

1. Timing components C_x and R_x values.

Operating Temperature Range

	0°C to 70°C	-55°C to +125°C		
R _X MIN	5kΩ	5kΩ		
RX MAX	100kΩ	50kΩ		
Cx	any value	any value		



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$$R_1 + R_2 = R_x$$

$$R_1 \ge R_x MIN.$$

$$R_2 < R_x MAX. - R_1$$

In the above arrangement, R1 and Cx should be as close as possible to the device pins to minimize stray capacitance and external noise pickup. The variable resistor R_2 can be located remotely from the device if reasonable care is used.



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LOADING RULES (In Unit Loads)

Input

Unit Load

_

_

-

_

0.4

0.4

0.4

-

_

Fan-out

Output

LOW

_

_

_

_

_

10

10

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10

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-

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Output

HIGH

_

_

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_

40

40

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40 40

_

_

_

_

_

_

OPERATION RULES (Cont.)

3. Pulse width change measurements.

The pulse width $t_{pw}\Omega$ is specified and measured with components of better than 0.1% accuracy. If measurements are made with reduced component tolerances, the expected accuracy should be adjusted accordingly. Note that pulse width temperature stability improves as $R_{\rm X}$ increases.

4. Timing for $C_x \leq 1000 \text{ pF}$.

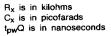
When using capacitor of less than or equal to 1000 pF in value, the output pulse width should be determined from the output pulse width versus external timing capacitance graph.

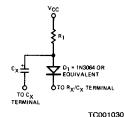
5. Timing for $C_x > 1000 \text{ pF}$.

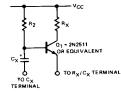
For capacitors of greater than 1000 pF in value, the output pulse width, $t_{pw}Q$, is determined by:

$$t_{pw}Q = 0.30C_xR_x \left(1 + \frac{0.11}{R_x}\right)$$

where







TC001020

$$R_2 < 0.7 \text{ x h}_{FEQ1} \text{ x } R_x$$

6. Protection of electrolytic timing capacitors.

If the electrolytic capacitor to be used as C_x cannot withstand 1.0 volt reverse bias, one of the two circuit techniques shown below should be used to protect the electrolytic capacitor from the reverse voltage. The accuracy of the pulse width may be dependent on the diode (transistor) characteristics. The output pulse width, $t_{pw}Q$ for the diode circuit modifies the previous timing equation as follows:

$$t_{pw}Q = 0.26C_xR_x \left(1 + \frac{0.13}{R_x}\right)$$

The output pulse width for the transistor circuit is:

$$t_{pw}Q = 0.21C_{X}R_{X}\left(1 + \frac{0.16}{R_{X}}\right)$$

Notice that the transistor circuit allows values of timing resistor R₂ larger than the R_x MIN. < R_x < R_xMAX. to obtain longer output pulse widths for a given C_x.

TRIGGER AND RETRIGGER

1. Triggering.

The minimum pulse width signal into input \tilde{I}_0 or input I_1 to cause the device to trigger is 20ns. Refer to the truth table for the appropriate input conditions.

2. Retriggering.

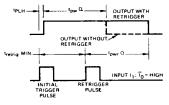
The retriggered pulse width, t_{pwr} Q, is the time during which the output is active after the device is retriggered during a timing cycle. It differs from the initial pulse width t_{pw} Q timing equations as follows:

where t_{PLH} is the propagation delay time from the \overline{I}_0 or I_1 input to the output. Note that t_{PLH} is typically 14ns and therefore becomes relatively unimportant as $t_{pw}Q$ increases.

3. Rapid retriggering.

A minimum retriggering time does exist. That is, the device cannot be retriggered until a minimum recovery time has elapsed. The minimum retrigger time is approximately:





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CLEAR

A LOW on the clear inputs terminates the timing cycle. A new trigger cycle cannot be initiated while the clear is LOW. With the clear HIGH, the device is under the command of the I_1 and \overline{I}_0 inputs.



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ABSOLUTE MAXIMUM RATINGS

Storage Temperature65°C to +150°C
Ambient Temperature Under Bias 55°C to + 125°C
Supply Voltage to Ground Potential
(Pin 16 to Pin 8) Continuous0.5V to +7.0V
DC Voltage Applied to Outputs For
HIGH Output State0.5V to +V _{CC} max
DC Input Voltage0.5V to +5.5V

DC Output Current, Into Outputs 30mA DC Input Current-30mA to +5.0mA

Stresses above those listed under ABSOLUTE MAXIMUM RATINGS may cause permanent device failure. Functionality at or above these limits is not implied. Exposure to absolute maximum ratings for extended periods may affect device reliability.

OPERATING RANGES

Commercial (C) Devices	
Temperature	0°C to +70°C
Supply Voltage	
Militony (M) Dovices	

Military (M) Devices

Temperature-55°C to +125°C Supply Voltage+4.5V to +5.5V Operating ranges define those limits over which the functionality of the device is guaranteed.

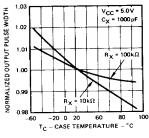
DC CHARACTERISTICS over operating range unless otherwise specified

Parameters	Description	Test Conditions (Note 2)	Min	Typ (Note 1)	Max	Units
VOH	Output HIGH Voltage	V _{CC} = MIN, I _{OH} = -2mA V _{IN} ≖ V _{IH} or V _{IL}	2.5	2.8		Volts
VOL	Output LOW Voltage	V _{CC} = MIN, I _{OL} = 20mA V _{IN} = V _{IH} or V _{IL}		0.38	0.5	Volts
VIH	Input HIGH Level	Guaranteed input logical HIGH voltage for all inputs	2.0			Volts
VIL	Input LOW Level	Guaranteed input logical LOW voltage for all inputs			0.8	Volts
Vi	input Clamp Voltage	V _{CC} = MIN, I _{IN} = -18mA		-0.4	- 1.2	Volts
III (Note 3)	Input LOW Current	$V_{CC} = MAX, V_{IN} = 0.5V$		-0.15	-0.4	mA
IIH (Note 3)	Input HIGH Current	$V_{CC} = MAX, V_{IN} = 2.7V$		0.1	20	μA
h	Input HIGH Current	$V_{CC} = MAX, V_{IN} = 5.5V$			1.0	mA
Isc	Output Short Circuit Current (Note 4)	$V_{CC} = MAX, V_{OUT} = 1.0V$ T _A = 25°C Only	-8	- 15	- 35	mA
lcc	Power Supply Current	V _{CC} = 5.0V, 1 _{IX} = 0.33mA (Notes 5 & 6)		48	69	mA

- Notes: 1. Typical limits are at V_{CC} = 5.0V, 25°C ambient and maximum loading. 2. For conditions shown as MIN, or MAX, use the appropriate value specified under Electrical Characteristics for the applicable device type. Actual input currents - Unit Load x Input Load Factor (See Loading Rules).
 Not more than one output should be shorted at a time. Duration of the short circuit test should not exceed one second.
 I_{CC} is measured with pin 5 and 11 grounded and I_{IX} applied to pins 2 and 14.
 I_{IX} is the current into the R_XC_X node to simulate R_X.

TYPICAL PERFORMANCE CURVES

Typical Normalized Output Pulse Width Versus Case Temperature



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