



GM3321

FAST PFET BUCK CONTROLLER

Power Management

Description

The GM3321 is a switching controller for use in DC-DC converters. It can be used in the buck topology with a minimum number of external components.

The GM3321 consists of a V_{CC} monitor for controlling the state of the device, 1.0 A power driver for controlling the gate of a discrete P-channel transistor, fixed frequency oscillator, short circuit protection timer, programmable soft start, precision reference, fast output voltage monitoring comparator, and output stage driver logic with latch.

The high frequency oscillator allows the use of small inductors and output capacitors, minimizing PC board area and systems cost. The programmable soft start reduces current surges at start up. The short circuit protection timer significantly reduces the duty cycle to approximately 1/30 of its cycle during short circuit conditions.

The GM3321 is available in an 8 Lead SOP package.

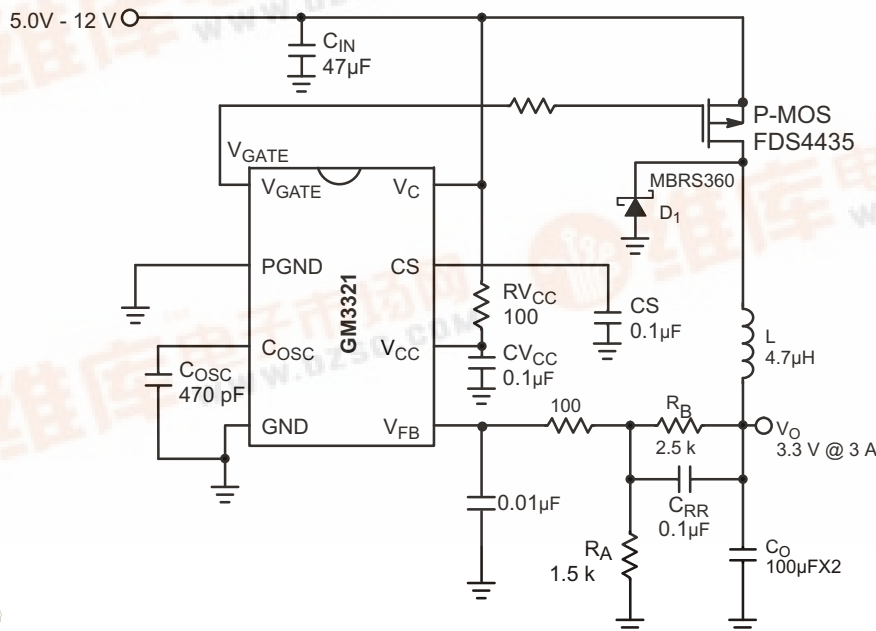
Features

- ◆ 1.0 A Totem Pole Output Driver
- ◆ High Speed Oscillator (700 kHz max)
- ◆ No Stability Compensation Required
- ◆ Lossless Short Circuit Protection
- ◆ V_{CC} Monitor
- ◆ 2.0% Precision Reference
- ◆ Programmable Soft Start
- ◆ Wide Ambient Temperature Range:
 - Industrial Grade: -40°C to 85°C
 - Commercial Grade: 0°C to 70°C

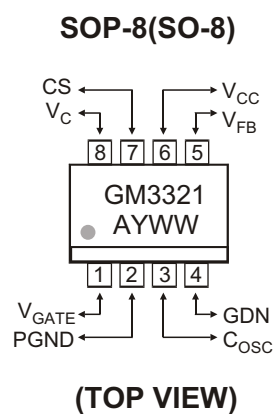
Application

Set - Top Box
DSL/ Cable Modem
PC/ IA
Auto PC
TFT Monitor
Battery Powered Portable Applications
Distributed Power Systems
Always On Power

TYPICAL APPLICATION CIRCUITS



◆ MARKING INFORMATION & PIN CONFIGURATIONS



A = Assembly Location
Y = Year
W W = Work Week

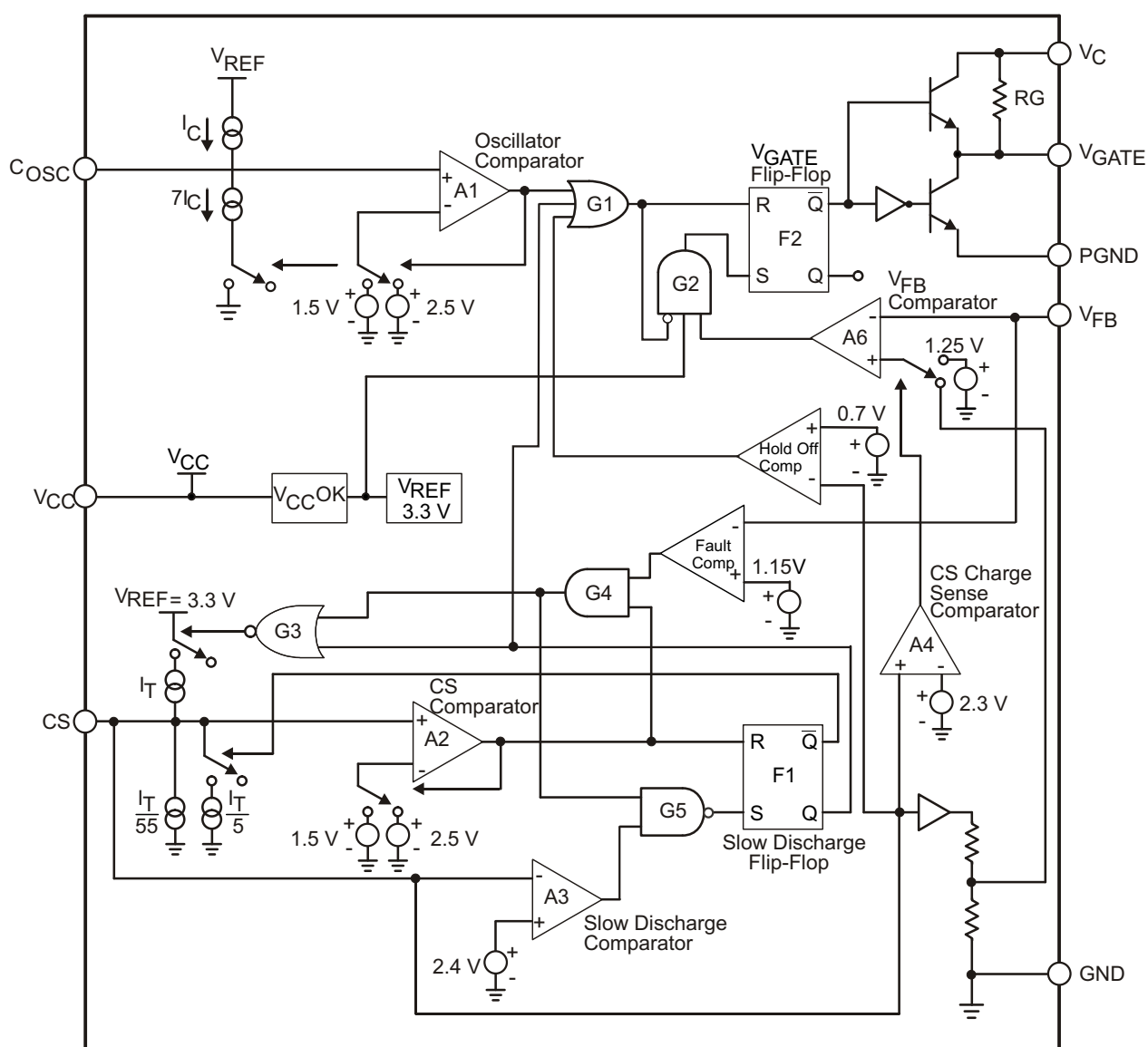
◆ ORDERING INFORMATION

Ordering Number	Package	Shipping
GM3321S8T	SO - 8	100 Units / Tube
GM3321S8R	SO - 8	2,500 Units / Tape & Reel

* For detail Ordering Number identification, please see last page.



◆ BLOCK DIAGRAM



◆ PIN DESCRIPTION

PIN NUMBER	PIN SYMBOL	FUNCTION
1	V_{GATE}	Driver pin to gate of external PFET.
2	PGND	Output power stage ground connection.
3	C_{OSC}	Oscillator frequency programming capacitor.
4	GND	Logic ground.
5	V_{FB}	Feedback voltage input.
6	V_{CC}	Logic supply voltage.
7	CS	Soft start and fault timing capacitor.
8	V_C	Driver supply voltage.

◆ ABSOLUTE MAXIMUM RATINGS

PARAMETER	VALUE	UNITS
Power Supply Voltage, V_{CC}	20	V
Driver Supply Voltage, V_C	20	V
Driver Output Voltage, V_{GATE}	20	V
C_{OSC} , CS, V_{FB} (Logic Pins)	6.0	V
Peak Output Current	1.0	A
Steady State Output Current	200	mA
Operating Junction Temperature, T_J	150	°C
Operating Temperature Range, T_A	-40 to +85	°C
Storage Temperature Range, T_S	-65 to +150	°C
ESD (Hunam Body Model)	2.0	kV
Lead Temperature Soldering : Wave Solder:(through hole styles only) (Note 1) Reflow (SMD styles only) (Note 2)	260 Peak 230 Peak	°C

Note 1: 10 Second maximum.

Note 2: 60 Second maximum above 183°C

* The maximum package power dissipation must be observed.

◆ OPERATING CONDITIONS

PARAMETER	VALUE	UNITS
Power Supply Voltage, V_{CC}	16	V
Driver Supply Voltage, V_C	16	V
Driver Output Voltage, V_{GATE}	16	V



◆ ELECTRICAL CHARACTERISTICS

Specifications apply for $4.5 \leq V_{CC} \leq 16V$, $3.0V \leq V_C \leq 16V$;

Industrial Grade: $-40^\circ C < T_A < 85^\circ C$; $-40^\circ C < T_J < 125^\circ C$; Commercial Grade: $0^\circ C < T_A < 70^\circ C$; $0^\circ C < T_J < 125^\circ C$, unless otherwise specified.)

CHARACTERISTICS	TEST CONDITIONS	MIN	TYP	MAX	UNIT
Oscillator $V_{FB} = 1.2V$					
Frequency	$C_{OSC} = 470pF$	160	200	240	kHz
Charge Current	$1.4V < V_{COSC} < 2.0V$	-	110	-	μA
Discharge Current	$2.7V > V_{COSC} > 2.0V$	-	660	-	μA
Maximum Duty Cycle	$1 - (t_{OFF}/t_{ON})$	80.0	83.3	-	%
Short Circuit Timer $V_{FB} = 1.0V$; $CS = 0.1\mu F$; $V_{COSC} = 2.0V$					
Charge Current	$1.0V < V_{CS} < 2.0V$	175	264	325	μA
Fast Discharge Current	$2.55V < V_{CS} < 2.4V$	40	66	80	μA
Slow Discharge Current	$2.4V < V_{CS} < 1.5V$	4.0	6.0	10	μA
Start Fault Inhibit Time	$0V < V_{CS} < 2.5V$	0.70	0.85	1.40	ms
Valid Fault Time	$2.6V < V_{CS} < 2.4V$	0.2	0.3	0.45	ms
GATE Inhibit Time	$2.4V < V_{CS} < 1.5V$	9.0	15	23	ms
Fault Duty Cycle	-	2.5	3.1	4.6	%
CS Comparator $V_{FB} = 1.0V$					
Fault Enable CS Voltage	-	-	2.5	-	V
Max. CS Voltage	$V_{FB} = 1.5V$	-	2.6	-	V
Fault Detect Voltage	V_{CS} when GATE goes high	-	2.4	-	V
Fault Inhibit Voltage	Minimum V_{CS}	-	1.5	-	V
Hold Off Release Voltage	$V_{FB} = 0V$	0.4	0.7	1.0	V
Regulator Threshold Voltage Clamp	$V_{CS} = 1.5V$	0.725	0.866	1.035	V
V_{FB} Comparators $V_{OSC} = V_{CS} = 2.0V$					
Regulator Threshold Voltage	$T_J = 25^\circ C$ (Note 3) $T_J = -40$ to $+125^\circ C$	1.225 1.210	1.250 1.250	1.275 1.290	V
Fault Threshold Voltage	$T_J = 25^\circ C$ (Note 3) $T_J = -40$ to $+125^\circ C$	1.12 1.10	1.15 1.15	1.17 1.19	V
Threshold Line Regulation	$4.5V \leq V_{CC} \leq 16V$	-	6.0	1.5	mV
Input Bias Current	$V_{FB} = 0V$	-	1.0	4.0	μA
Voltage Tracking	(Regulator Threshold- Fault threshold Voltage)	70	100	120	mV
Input Hysteresis Voltage	-	-	4.0	20	mV

Note 3: Guaranteed by design, not 100% tested in production.

◆ ELECTRICAL CHARACTERISTICS

Specifications apply for $4.5 \leq V_{CC} \leq 16V$, $3.0V \leq V_C \leq 16V$;

Industrial Grade: $-40^{\circ}C < T_A < 85^{\circ}C$; $-40^{\circ}C < T_J < 125^{\circ}C$; Commercial Grade: $0^{\circ}C < T_A < 70^{\circ}C$; $0^{\circ}C < T_J < 125^{\circ}C$, unless otherwise specified.)

CHARACTERISTICS	TEST CONDITIONS	Min	Typ	Max	Unit
Power Stage $V_{CC} = V_C = 10V$, $V_{FB} = 1.2V$					
GATE DC Low Saturation Voltage	$V_{COSC} = 1.0V$; 200mA Sink	-	1.2	1.5	V
GATE DC High Saturation Voltage	$V_{COSC} = 2.7V$; 200mA source; $V_C = V_{GATE}$	-	1.5	2.1	V
Rise Time	$C_{GATE} = 1.0nF$; $1.5V < V_{GATE} < 9.0V$	-	25	60	ns
Fall Time	$C_{GATE} = 1.0nF$; $9.0V < V_{GATE} < 1.5V$	-	25	60	ns
V_{CC} Monitor					
Turn On Threshold	-	4.100	4.300	4.500	V
Turn Off Threshold	-	4.085	4.200	4.415	V
Hysteresis	-	65	130	200	mV
Current Drain					
I_{CC}	$4.5V < V_{CC} < 16V$, Gate Switching	-	4.5	6.0	mA
I_C	$3.0V < V_C < 16V$, Gate non- Switching	-	2.7	4.0	mA
Shutdown I_C	$V_{CC} = 4.0V$	-	500	900	μA



◆ CIRCUIT DESCRIPTION

THEORY OF OPERATION

Control Scheme

The GM3321 monitors the output voltage to determine when to turn on the PFET. If V_{FB} falls below the internal reference voltage of 1.25V during the oscillator's charge cycle, the PFET is turned on and remains on for the duration of the charge time. The PFET gets turned off and remains off during the oscillator's discharge time with the maximum duty cycle to 80%. It requires 7.0mV typical, and 20mV maximum ripple on the V_{FB} pin is required to operate. This method of control does not require any loop stability compensation.

Startup

The GM3321 has an externally programmable soft start feature that allows the output voltage to come up slowly, preventing voltage overshoot on the output.

At startup, the voltage on all pins is zero. As V_{CC} rises, the V_C voltage along with the internal resistor R_G keeps the PFET off. As V_{CC} and V_C continue to rise, the oscillator capacitor (C_{OSC}) and the Soft Start/ Fault Timing capacitor (CS) charges via internal current sources. C_{OSC} gets charged by the current source IC and CS gets charged by the I_T source combination described by:

$$I_{CS} = I_T - \left(\frac{I_T}{55} + \frac{I_T}{5} \right)$$

The internal Holdoff Comparator ensures that the external PFET is off until $V_{CS} > 0.7V$, preventing the GATE flip-flop (F2) from being set. This allows the oscillator to reach its operating frequency before enabling the drive output. Soft start is obtained by clamping the V_{FB} comparator's (A6) reference input to approximately 1/2 of the voltage at the CS pin during startup, permitting the control loop and the output voltage to slowly increase. Once the CS pin charges above the Holdoff Comparator trip point of 0.7V, the low feedback to the V_{FB} Comparator sets the GATE flip-flop during C_{OSC} 's charge cycle. Once the GATE flip-flop is set, V_{GATE} goes low and turns on the PFET. When V_{CS} exceeds 2.3V, the CS charge sense comparator (A4) sets the V_{FB} Comparator reference to 1.25V Completing the startup cycle.

Lossless Short Circuit Protection

The GM3321 has "lossless" short circuit protection since there is no current sense resistor required. When the voltage at the CS pin (the fault timing capacitor voltage) reaches 2.5V during startup, the fault timing circuitry is enabled by A2. During normal operation the CS voltage is 2.6V. During a short circuit or a transient condition, the output voltage moves lower and the voltage at V_{FB} drops. If V_{FB} drops below 1.15V, the output of the fault comparator goes high and the GM3321 goes into a fast discharge mode. The fault timing capacitor, CS, discharges to 2.4V. If the V_{FB} voltage is still below 1.15V when the CS pin reaches 2.4V, a valid fault condition has been detected. The slow discharge comparator output goes high and enables gate G5 which sets the slow discharge flip flop. The V_{GATE} flip flop resets and the output switch is turned off. The fault timing capacitor is slowly discharged to 1.5V. The GM3321 then enters a normal startup routine. If the fault is still present when the fault timing capacitor voltage reaches 2.5V, the fast and slow discharge cycles repeat as shown in figure 1.

If the V_{FB} voltage is above 1.15V when CS reaches 2.4V a fault condition is not detected, normal operation resumes and CS charges back to 2.6V. This reduces the chance of erroneously detecting a load transient as a fault condition.



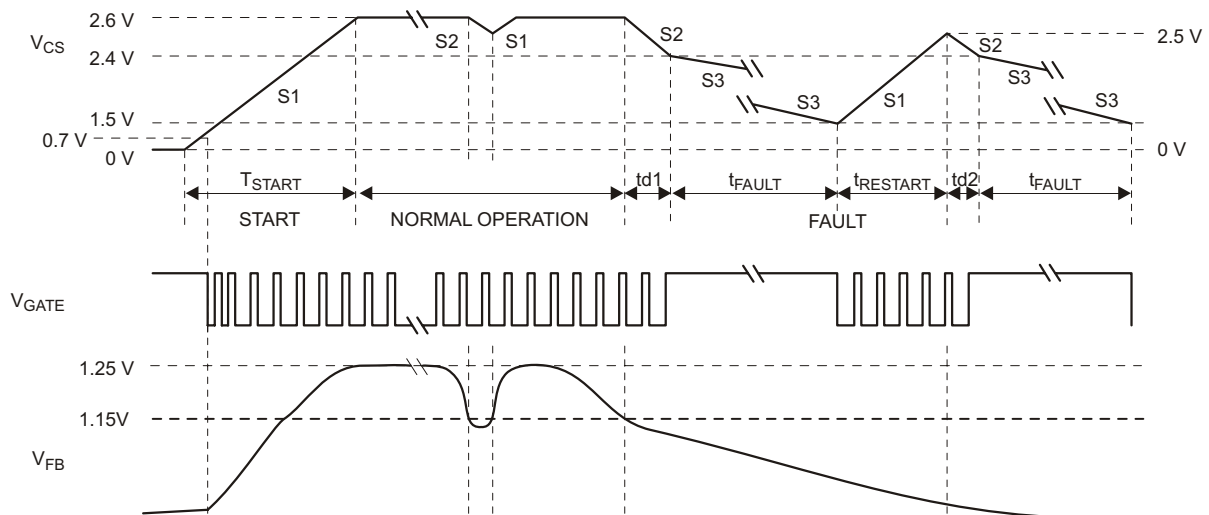


Figure 1. Voltage on Start Capacitor (V_{GS}), the Gate (V_{GATE}), and in the Feedback Loop (V_{FB}), During Startup, Normal and Fault Conditions.

Buck Regulator Operation

A block diagram of a typical buck regulator is shown in Figure 2. If we assume that the output transistor is initially off, and the system is in discontinuous operation, the inductor current I_L is zero and the output voltage is at its nominal value. The current drawn by the load is supplied by the output capacitor C_O . When the voltage across C_O below the threshold established by the feedback resistors R_1 and the reference voltage V_{REF} , the power transistor Q_1 switches on and current flows through the inductor to the output. The inductor current rises at a rate determined by $(V_{IN} - V_{OUT})/L$. The duty cycle (or "on" time) for the GM3321 is limited to 80%. If output voltage remains higher than nominal during the entire C_{OSC} change time, the Q_1 does not turn on, skipping the pulse.

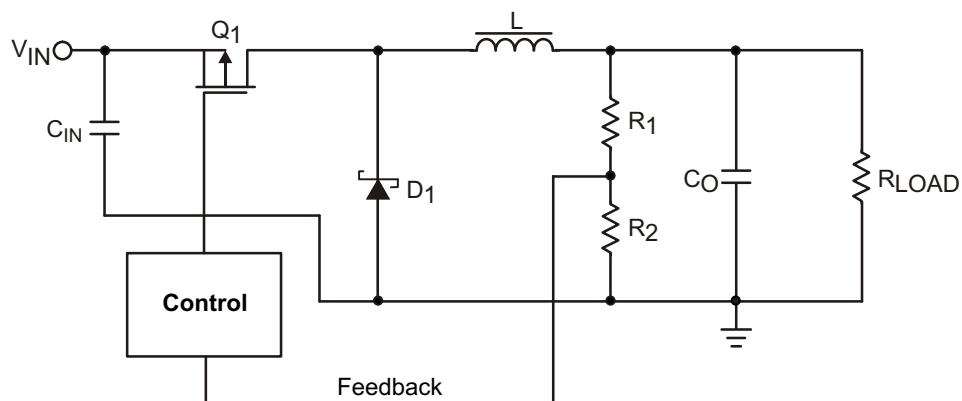


Figure 2. Buck Regulator Block Diagram.

◆ APPLICATIONS INFORMATION

GM3321 DESIGN EXAMPLE

Specifications 12V to 5.0V, 3.0A Buck Controller

- $V_{IN} = 12V \pm 20\%$ (i.e. 14.4V max., 12V nom., 9.6V min.)
- $V_{OUT} = 5.0V \pm 2\%$
- $I_{OUT} = 0.3A$ to 3.0A
- Output ripple voltage < 50mV max.
- Efficiency > 80%
- $F_{SW} = 200kHz$

(1) Duty Cycle Estimates

Since the maximum duty cycle D, of the GM3321 is limited to 80% min., It is necessary to estimate the duty cycle for the various input conditions over the complete operating range.

The duty cycle for a buck regulator operating in a continuous conduction mode is given by:

$$D = \frac{V_{OUT} + V_F}{V_{IN} - V_{SAT}}$$

where:

$V_{SAT} = R_{ds(on)} \times I_{OUT}$ max. And $R_{ds(on)}$ is the value at T_J 100°C.

If $V_F = 0.60V$ and V and $V_{SAT} = 0.60V$ then the above equation becomes:

$$D_{MAX} = \frac{5.6}{9.0} = 0.62$$

$$D_{MIN} = \frac{5.6}{13.8} = 0.40$$

(2) Switching Frequency and On and Off Time Calculations

Given that $f_{SW} = 200kHz$ and $D_{MAX} = 0.80$

$$T = \frac{1.0}{f_{SW}} = 5.0\mu s$$

$$T_{ON(max)} = T \times D_{MAX} = 5.0\mu s \times 0.62 \cong 3.0\mu s$$

$$T_{ON(min)} = T \times D_{MIN} = 5.0\mu s \times 0.40 \cong 2.0\mu s$$

$$T_{OFF(max)} = T - T_{ON} (min) = 5.0\mu s - 2.0\mu s = 3.0\mu s$$

(3) Oscillator Capacitor Selection

The switching frequency is set by C_{OSC} , whose value is given by:

$$C_{OSC} \text{ in pF} = \frac{95 \times 10^{-6}}{F_{SW} \left(1 + \frac{F_{SW}}{3 \times 10^6} - \left(\frac{30 \times 10^3}{F_{SW}} \right)^2 \right)}$$

(4) Inductor Selection

The inductor value is chosen for continuous mode operation down to 0.3Amps.

The ripple current $I = 2 \times I_{OUTmin} = 2 \times 0.3A = 0.6A$.

$$L_{min} = \frac{(V_{OUT} + V_F) \times T_{OFF(max)}}{I} = \frac{5.6V \times 3.0\mu s}{0.6A} = 28\mu H$$

This is the minimum value of inductor to keep the ripple current < 0.6A during normal operation.

A smaller inductor will result in larger ripple current. Ripple current at a minimum on time is.

$$I = \frac{(V_{OUT} + V_F) \times T_{ON(max)}}{L_{MIN}} = \frac{5.6V \times 2.0\mu s}{28\mu H} = 0.4A$$

The core must not saturate with the maximum expected current, here given by:

$$I_{MAX} = I_{OUT} + I/2 = 3.0A + 0.4A/2 = 3.2A$$

(5) Output Capacitor

The Output Capacitor and the inductor form a low pass filter. The output capacitor should have a low ESL and ESR. Low impedance aluminum electrolytic, tantalum or organic semiconductor capacitors are a good choice for and output capacitor. Low impedance aluminum ate less expensive. Solid tantalum chip capacitors are available from a number of suppliers and are the best choice for surface mount applications.

The output capacitor limits the output ripple voltage. The GM3321 needs a maximum of 20 mV of output ripple for the feedback comparator to change state. If we assume that all the inductor ripple current flows through the output capacitor and that it is an ideal capacitor(i.e.zero ESR), the minimum capacitance needed to limit the output ripple to 50mV peak to peak is given by:

$$C = \frac{I}{8.0 \times f_{SW} \times V} = \frac{0.6A}{8.0 \times (200 \times 10^3 \text{ Hz}) \times (50 \times 10^{-3} \text{ V})} = 7.5\mu F$$

The minimum ESR needed to limit the output voltage ripple to 50mV peak to peak is:

$$ESR = \frac{V}{I} = \frac{50 \times 10^{-3}}{0.6A} = 83m$$

The output capacitor should be chosen so that its ESR is less than 83m .

During the minimum off time, the ripple current is 0.4A and the output voltage ripple will be:

$$V = ESR \times I = 83m \times 0.4 = 33mV$$



(6) V_{FB} Divider

$$V_{OUT} = 1.25V \left(\frac{R1 + R2}{R2} \right) = 1.25V \left(\frac{R1}{R2} + 1.0 \right)$$

The input bias current to the comparator is $4.0\mu A$. The resistor divider current should be considerably higher than this to ensure that there is sufficient bias current. If we choose the divider current to be at least 250 times the bias current this permits a divider current of $1mA$ and simplifies the calculations.

$$\frac{5.0V}{1.0mA} = R1 + R2 = 5.0K$$

Let $R2 = 1.0K$

Rearranging the divider equation gives:

$$R1 = R2 \left(\frac{V_{OUT}}{1.25} - 1.0 \right) = 1.0K \left(\frac{5.0V}{1.25} - 1.0 \right) = 3.0K$$

(7) Divider Bypass Capacitor CRR

Since the feedback resistors divide the output voltage by a factor of 4.0, i.e. $5.0V/1.25V = 4.0$, it follows that the output ripple is also divided by four. This would require that the output ripple be at least $60mV(4.0 \times 15mV)$ to trip the feedback comparator. We use a capacitor C_{RR} to act as an AC short.

The ripple voltage frequency is equal to the switching frequency so we choose $C_{RR} = 1.0nF$.

(8) Soft Start and Fault Timing Capacitor CS

CS performs several important functions. First it provides a delay time for load transients so that the IC does not enter a fault mode every time the load changes abruptly. Secondly it disables the fault circuitry during startup, it also provides soft start by clamping the reference voltage during startup, allowing it to rise slowly, and, finally it controls the hiccup short circuit protection circuitry. This reduces the duty cycle to approximately 0.035 during short circuit conditions.

An important consideration in calculating CS is that it's voltage does not reach $2.5V$ (the voltage at which the fault detect circuitry is enable) before V_{FB} reaches $1.15V$ otherwise the power supply will never start.

If the V_{FB} pin reaches $1.15V$, the fault timing comparator will discharge CS and the supply will not start. For the V_{FB} voltage to reach $1.15V$ the output voltage must be at least $4 \times 1.15 = 4.6V$.

If we choose an arbitrary startup time of $900\mu s$, the value of CS is:

$$t_{Startup} = \frac{CS \times 2.5V}{I_{Charge}}$$

$$CS_{min} = \frac{900\mu s \times 264\mu A}{2.5V} = 950nF \approx 0.1\mu F$$

The fault time is the sum of the slow discharge time the fast discharge time and the recharge time. It is dominated by the slow discharge time.

The first parameter is the slow discharge time, it is the time for the CS capacitor to discharge from $2.4V$ to $1.5V$ and is given by:

$$t_{SlowDischarge}(t) = \frac{CS \times (2.4V - 1.5V)}{I_{Discharge}}$$

where $I_{Discharge}$ is $6.0\mu A$ typical.

$$t_{SlowDischarge}(t) = CS \times 1.5 \times 10^5$$

The fast discharge time occurs when a fault is first detected. The CS capacitor is discharged from $2.5V$ to $2.4V$.

$$t_{FastDischarge}(t) = \frac{CS \times (2.5V - 2.4V)}{I_{FastDischarge}}$$

where $I_{FastDischarge}$ is $66\mu A$ typical.

$$t_{FastDischarge}(t) = CS \times 1515$$

The recharge time is the time for CS to charge from $1.5V$ to $2.5V$.

$$t_{Charge}(t) = \frac{CS \times (2.5V - 1.5V)}{I_{FastDischarge}}$$

where I_{Charge} is $246\mu A$ typical.

$$t_{Charge}(t) = CS \times 3787$$

The fault time is given by:

$$t_{Fault} = CS \times (3787 + 1515 + 1.5 \times 10^5)$$

$$t_{Fault} = CS \times (1.55 \times 10^5)$$

For this circuit

$$t_{Fault} = 0.1 \times 10^{-6} \times 1.55 \times 10^5 = 15.5\mu s$$

A larger value of CS will increase the fault time out time but will also increase the soft start time.



(9) Input Capacitor

The input capacitor reduces the peak currents drawn from the input supply and reduces the noise and ripple voltage on the V_{CC} and V_C pins. This capacitor must also ensure that the V_{CC} remains above the UVLO voltage in the event of an output short circuit. A low ESR capacitor of at least 100 μ F is good. A ceramic surface mount capacitor should also be connected between V_{CC} and ground to filter high frequency noise.

(10) MOSFET Selection

The GM3321 drives a P-channel MOSFET. The V_{GATE} pin swings from GND to VC. The type of PEFT used depends on the operating conditions but for input voltages below 7.0V a logic level FET should be used.

A PEFT with a continuous drain current (I_D) rating greater than the maximum output current is required.

The Gate-to-Source voltage V_{GS} and the Drain - to Source Breakdown Voltage should be chosen based on the input supply voltage.

The power dissipation due to the conduction losses is given by:

$$P_D = I_{OUT}^2 \times R_{DS(ON)} \times D$$

where

$R_{DS(ON)}$ is the value at $T_J = 100^\circ\text{C}$

The power dissipation of the PFET due to the switching losses is given by:

$$P_D = 0.5 \times V_{IN} \times I_{OUT} \times (tr) \times f_{SW}$$

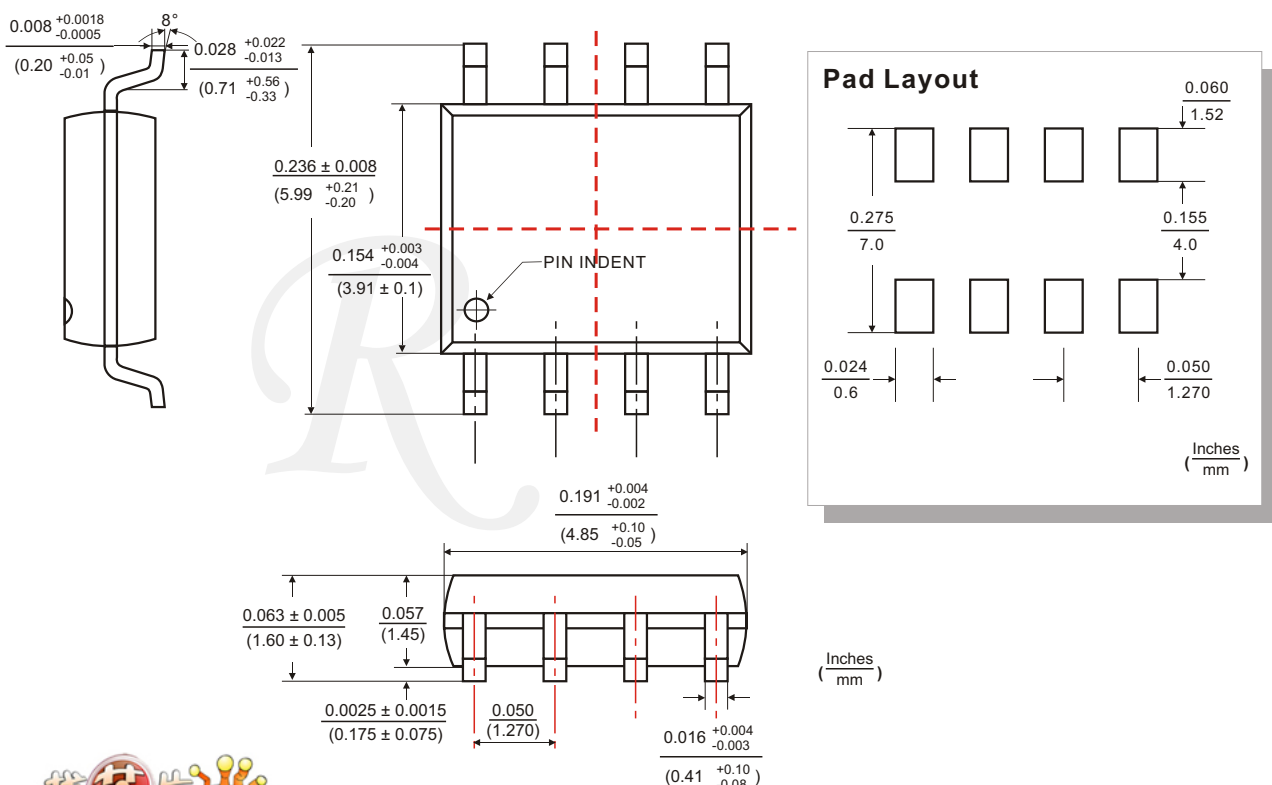
Where t_r = Rise Time.

(11) Diode Selection

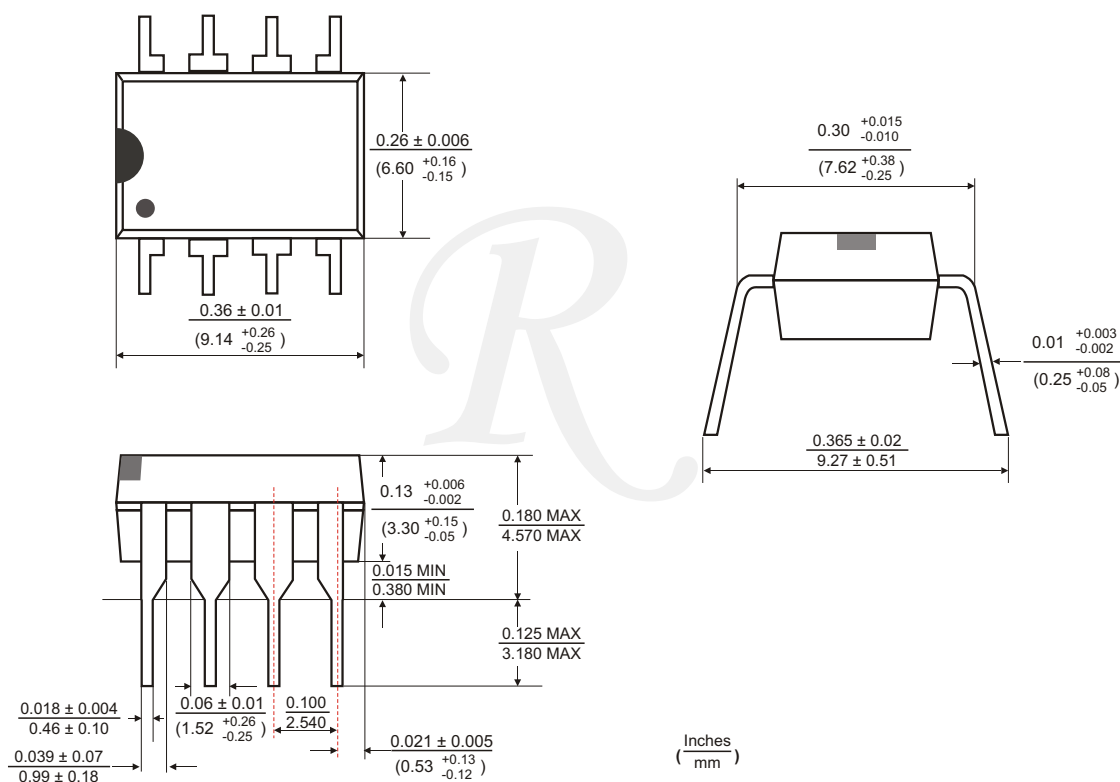
The flyback or catch diode should be a Schottky diode because of its fast switching ability and low forward voltage drop. The current rating must be at least equal to the maximum output current. The breakdown voltage should be at least 20V for this 12V application.

The diode power dissipation is given by:

$$P_D = I_{OUT} \times V_D \times (1.0 - D_{min})$$

◆ SOP-8(SO-8) PACKAGE OUTLINE DIMENSIONS

◆ DIP-8 PACKAGE OUTLINE DIMENSIONS



◆ ORDERING NUMBER

