8-Bit Parallel-to-Serial Shift Register

The SN74LS165 is an 8-bit parallel load or serial-in register with complementary outputs available from the last stage. Parallel inputing occurs asynchronously when the Parallel Load (\overline{PL}) input is LOW. With \overline{PL} HIGH, serial shifting occurs on the rising edge of the clock; new data enters via the Serial Data (DS) input. The 2-input OR clock can be used to combine two independent clock sources, or one input can act as an active LOW clock enable.

GUARANTEED OPERATING RANGES

| Symbol | Parameter | Min | Тур | Max | Unit |
|-----------------|--|------|------|------|------|
| V _{CC} | Supply Voltage | 4.75 | 5.0 | 5.25 | V |
| T _A | Operating Ambient Temperature Range | 0 | 25 | 70 | °C |
| I _{OH} | Output Current – High | | 431 | -0.4 | mA |
| I _{OL} | Output Current – Low | -11 | - G1 | 8.0 | mA |



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LOW POWER SCHOTTKY



PLASTIC N SUFFIX CASE 648



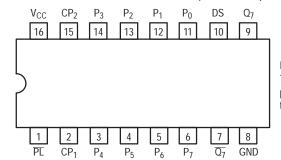
SOIC D SUFFIX CASE 751B

ORDERING INFORMATION

| Device | Package | Shipping | | |
|------------|------------|------------------|--|--|
| SN74LS165N | 16 Pin DIP | 2000 Units/Box | | |
| SN74LS165D | 16 Pin | 2500/Tape & Reel | | |



CONNECTION DIAGRAM DIP (TOP VIEW)



NOTE:

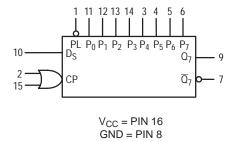
The Flatpak version has the same pinouts (Connection Diagram) as the Dual In-Line Package.

| | | LOADING | (Note a) |
|---|--|--|--|
| PIN NAMES | | HIGH | LOW |
| $\begin{array}{c} \text{CP}_1, \text{CP}_2 \\ \text{DS} \\ \overline{\text{PL}} \\ \text{P}_0 - \text{P}_7 \\ \overline{\text{Q}}_7 \\ \overline{\text{Q}}_7 \end{array}$ | Clock (LOW-to-HIGH Going Edge) Inputs Serial Data Input Asynchronous Parallel Load (Active LOW) Input Parallel Data Inputs Serial Output from Last State Complementary Output | 0.5 U.L. 0.5 U.L. 1.5 U.L. 0.5 U.L. 10 U.L. 10 U.L. | 0.25 U.L. 0.25 U.L. 0.75 U.L. 0.25 U.L. 5 U.L. 5 U.L. |

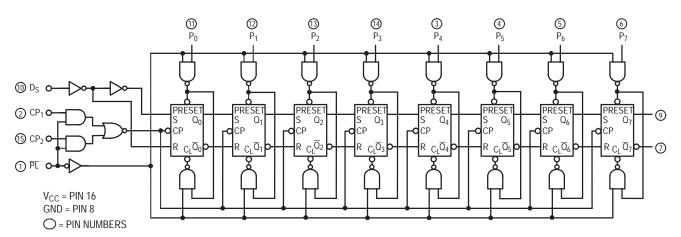
NOTES

a) 1 TTL Unit Load (U.L.) = 40 μ A HIGH/1.6 mA LOW.

LOGIC SYMBOL



LOGIC DIAGRAM



FUNCTIONAL DESCRIPTION

The SN74LS165 contains eight clocked master/slave RS flip-flops connected as a shift register, with auxiliary gating to provide overriding asynchronous parallel entry. Parallel data enters when the \overline{PL} signal is LOW. The parallel data can change while \overline{PL} is LOW, provided that the recommended setup and hold times are observed.

For clock operation, \overline{PL} must be HIGH. The two clock inputs perform identically; one can be used as a clock inhibit

by applying a HIGH signal. To avoid double clocking, however, the inhibit signal should only go HIGH while the clock is HIGH. Otherwise, the rising inhibit signal will cause the same response as a rising clock edge. The flip-flops are edge-triggered for serial operations. The serial input data can change at any time, provided only that the recommended setup and hold times are observed, with respect to the rising edge of the clock.

TRUTH TABLE

| PL | С | P | | | RESPONSE | | | | | | | |
|----|---|---|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|----------------|--|
| | 1 | 2 | Q_0 | Q ₁ | Q ₂ | Q_3 | Q_4 | Q ₅ | Q_6 | Q ₇ | RESPONSE | |
| L | Х | Х | P ₀ | P ₁ | P ₂ | P ₃ | P ₄ | P ₅ | P ₆ | P ₇ | Parallel Entry | |
| Н | L | | D_S | Q_0 | Q_1 | Q_2 | Q_3 | Q_4 | Q_5 | Q_6 | Right Shift | |
| Н | Н | | Q_0 | Q_1 | Q_2 | Q_3 | Q_4 | Q_5 | Q_6 | Q ₇ | No Change | |
| Н | | L | D_S | Q_0 | Q_1 | Q_2 | Q_3 | Q_4 | Q_5 | Q_6 | Right Shift | |
| Н | | Н | Q_0 | Q_1 | Q_2 | Q_3 | Q_4 | Q_5 | Q_6 | Q ₇ | No Change | |

H = HIGH Voltage Level

L = LOW Voltage Level

X = Immaterial

DC CHARACTERISTICS OVER OPERATING TEMPERATURE RANGE (unless otherwise specified)

| | | | Limits | | | | | |
|-----------------|--|-----|--------|--------------|------|---|---|--|
| Symbol | Parameter | Min | Тур | Max | Unit | Tes | t Conditions | |
| V _{IH} | Input HIGH Voltage | 2.0 | | | V | Guaranteed Input All Inputs | t HIGH Voltage for | |
| V _{IL} | Input LOW Voltage | | | 0.8 | V | Guaranteed Input All Inputs | LOW Voltage for | |
| V _{IK} | Input Clamp Diode Voltage | | -0.65 | -1.5 | V | V _{CC} = MIN, I _{IN} = | –18 mA | |
| V _{OH} | Output HIGH Voltage | 2.7 | 3.5 | | V | V_{CC} = MIN, I_{OH} = MAX, V_{IN} = V_{IH} or V_{IL} per Truth Table | | |
| ., | Output LOW Voltage | | 0.25 | 0.4 | V | I _{OL} = 4.0 mA | $V_{CC} = V_{CC} MIN,$ | |
| V _{OL} | | | 0.35 | 0.5 | ٧ | I _{OL} = 8.0 mA | $V_{IN} = V_{IL}$ or V_{IH} per Truth Table | |
| l _{IH} | Input HIGH Current Other Inputs PL Input | | | 20 60 | μΑ | $V_{CC} = MAX, V_{IN} = 2.7 V$ | | |
| | Other Inputs PL Input | | | 0.1 0.3 | mA | V _{CC} = MAX, V _{IN} = 7.0 V | | |
| I _{IL} | Input LOW Current Other Inputs PL Input | | | -0.4 -1.2 | mA | V _{CC} = MAX, V _{IN} = 0.4 V | | |
| I _{OS} | Short Circuit Current (Note 1) | -20 | | -100 | mA | V _{CC} = MAX | | |
| Icc | Power Supply Current | | | 36 | mA | V _{CC} = MAX | | |

Note 1: Not more than one output should be shorted at a time, nor for more than 1 second.

AC CHARACTERISTICS $(T_A = 25^{\circ}C)$

| | | | Limits | | | |
|--------------------------------------|---|-----|----------|----------|------|--|
| Symbol | Parameter | Min | Тур | Max | Unit | Test Conditions |
| f _{MAX} | Maximum Input Clock Frequency | 25 | 35 | | MHz | |
| t _{PLH} t _{PHL} | Propagation Delay PL to Output | | 22 22 | 35 35 | ns | |
| t _{PLH} t _{PHL} | Propagation Delay Clock to Output | | 27 28 | 40 40 | ns | $V_{CC} = 5.0 \text{ V}$ $C_{L} = 15 \text{ pF}$ |
| t _{PLH} t _{PHL} | Propagation Delay P_7 to Q_7 | | 14 21 | 25 30 | ns | - ' |
| t _{PLH} t _{PHL} | Propagation Delay P_7 to \overline{Q}_7 | | 21 16 | 30 25 | ns | |

AC SETUP REQUIREMENTS $(T_A = 25^{\circ}C)$

| | | Limits | | | | |
|------------------|--|--------|-----|-----|------|-------------------------|
| Symbol | Parameter | Min | Тур | Max | Unit | Test Conditions |
| t _W | CP Clock Pulse Width | 25 | | | ns | |
| t _W | PL Pulse Width | 15 | | | ns | |
| ts | Parallel Data Setup Time | 10 | | | ns | |
| ts | Serial Data Setup Time | 20 | | | ns | V _{CC} = 5.0 V |
| ts | CP ₁ to CP ₂ Setup Time ¹ | 30 | | | ns | |
| t _h | Hold Time | 0 | | | ns | |
| t _{rec} | Recovery Time, PL to CP | 45 | | | ns | |

¹The role of CP₁ and CP₂ in an application may be interchanged.

DEFINITION OF TERMS:

SETUP TIME (t_s) — is defined as the minimum time required for the correct logic level to be present at the logic input prior to the clock transition from LOW-to-HIGH in order to be recognized and transferred to the outputs.

HOLD TIME (t_h) — is defined as the minimum time following the clock transition from LOW-to-HIGH that the logic level must be maintained at the input in order to ensure

continued recognition. A negative hold time indicates that the correct logic level may be released prior to the clock transition from LOW-to-HIGH and still be recognized.

RECOVERY TIME (t_{rec})—is defined as the minimum time required between the end of the \overline{PL} pulse and the clock transition from LOW-to-HIGH in order to recognize and transfer loaded Data to the Q outputs.

AC WAVEFORMS

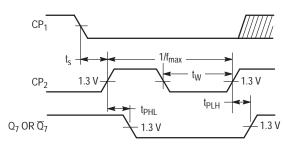


Figure 1.

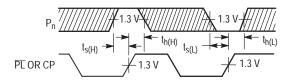


Figure 3.

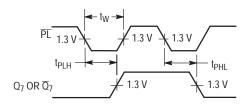


Figure 2.

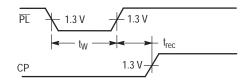
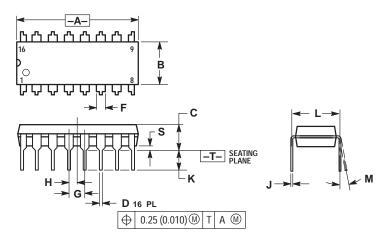


Figure 4.

PACKAGE DIMENSIONS

N SUFFIX PLASTIC PACKAGE CASE 648-08 ISSUE R

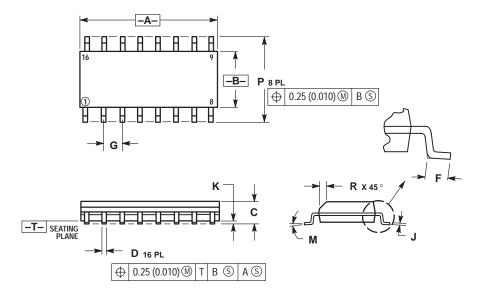


- NOTES:
 1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
 2. CONTROLLING DIMENSION: INCH.
 3. DIMENSION L TO CENTER OF LEADS WHEN FORMED PARALLEL.
 4. DIMENSION B DOES NOT INCLUDE MOLD FLASH.
 5. ROUNDED CORNERS OPTIONAL.

| | INC | HES | MILLIN | IETERS | |
|-----|-------|-------|----------|--------|--|
| DIM | MIN | MAX | MIN | MAX | |
| Α | 0.740 | 0.770 | 18.80 | 19.55 | |
| В | 0.250 | 0.270 | 6.35 | 6.85 | |
| С | 0.145 | 0.175 | 3.69 | 4.44 | |
| D | 0.015 | 0.021 | 0.39 | 0.53 | |
| F | 0.040 | 0.70 | 1.02 | 1.77 | |
| G | 0.100 | BSC | 2.54 BSC | | |
| Н | 0.050 | BSC | 1.27 | BSC | |
| J | 0.008 | 0.015 | 0.21 | 0.38 | |
| K | 0.110 | 0.130 | 2.80 | 3.30 | |
| L | 0.295 | 0.305 | 7.50 | 7.74 | |
| M | 0° | 10 ° | 0 ° | 10 ° | |
| S | 0.020 | 0.040 | 0.51 | 1.01 | |

PACKAGE DIMENSIONS

D SUFFIX PLASTIC SOIC PACKAGE CASE 751B-05 **ISSUE J**



NOTES:

- NOTES:

 1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
 2. CONTROLLING DIMENSION: MILLIMETER.
 3. DIMENSIONS A AND B DO NOT INCLUDE MOLD PROTRUSION.
 4. MAXIMUM MOLD PROTRUSION 0.15 (0.006) PER SIDE.
 5. DIMENSION D DOES NOT INCLUDE DAMBAR PROTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.127 (0.005) TOTAL IN EXCESS OF THE D DIMENSION AT MAXIMUM MATERIAL CONDITION.

| | MILLIN | IETERS | INC | HES | |
|-----|--------|--------|-----------|-------|--|
| DIM | MIN | MAX | MIN | MAX | |
| Α | 9.80 | 10.00 | 0.386 | 0.393 | |
| В | 3.80 | 4.00 | 0.150 | 0.157 | |
| С | 1.35 | 1.75 | 0.054 | 0.068 | |
| D | 0.35 | 0.49 | 0.014 | 0.019 | |
| F | 0.40 | 1.25 | 0.016 | 0.049 | |
| G | 1.27 | BSC | 0.050 BSC | | |
| J | 0.19 | 0.25 | 0.008 | 0.009 | |
| K | 0.10 | 0.25 | 0.004 | 0.009 | |
| M | 0° | 7° | 0° | 7° | |
| Р | 5.80 | 6.20 | 0.229 | 0.244 | |
| R | 0.25 | 0.50 | 0.010 | 0.019 | |

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