

Servo signal processor for CD use

BU9321BKS

The BU9321BKS is a servo signal processor for CD players that incorporates a double-speed, no-adjustment PLL, program servo, and signal processing block on one chip. It operates off a low power supply voltage, and has low power consumption.

●Applications

Portable CD players, radio cassette players, and mini-component systems.

●Features

- 1) PLL on chip. Bit clock extraction possible with just a few external components. EFM data modulation is possible.
- 2) Frame synchronizing signal detection and protection.
- 3) Servo filters for focus, tracking, and sled are on chip. Characteristics can be controlled using commands from the controller.
- 4) Sub-code serial output pin provided.
- 5) Output pins for both P-code and Q-code.
- 6) CLV sequencer automatically determines the CLV mode.
- 7) Track jump sequencer on chip. Possible to jump any number of tracks.
- 8) De-interleave function, and 2-level error detection, correction and flag processing for C1 and C2.
- 9) The signal to the DAC is output by the MSB first 2'SCOMP serial out, and offset circuit ON and OFF can be controlled for CD-ROM compatibility.
- 10) 16 kilobits of on-chip SRAM absorb ± 4 frames of jitter.
- 11) Double-speed playback is possible.

●Absolute maximum ratings (Ta = 25°C)

Parameter	Symbol	Limits	Unit
Power supply voltage	V _{DD}	4.5	V
Power dissipation	P _d	400 *	mW
Operating temperature	T _{opr}	-25~+75	°C
Storage temperature	T _{stg}	-55~+125	°C

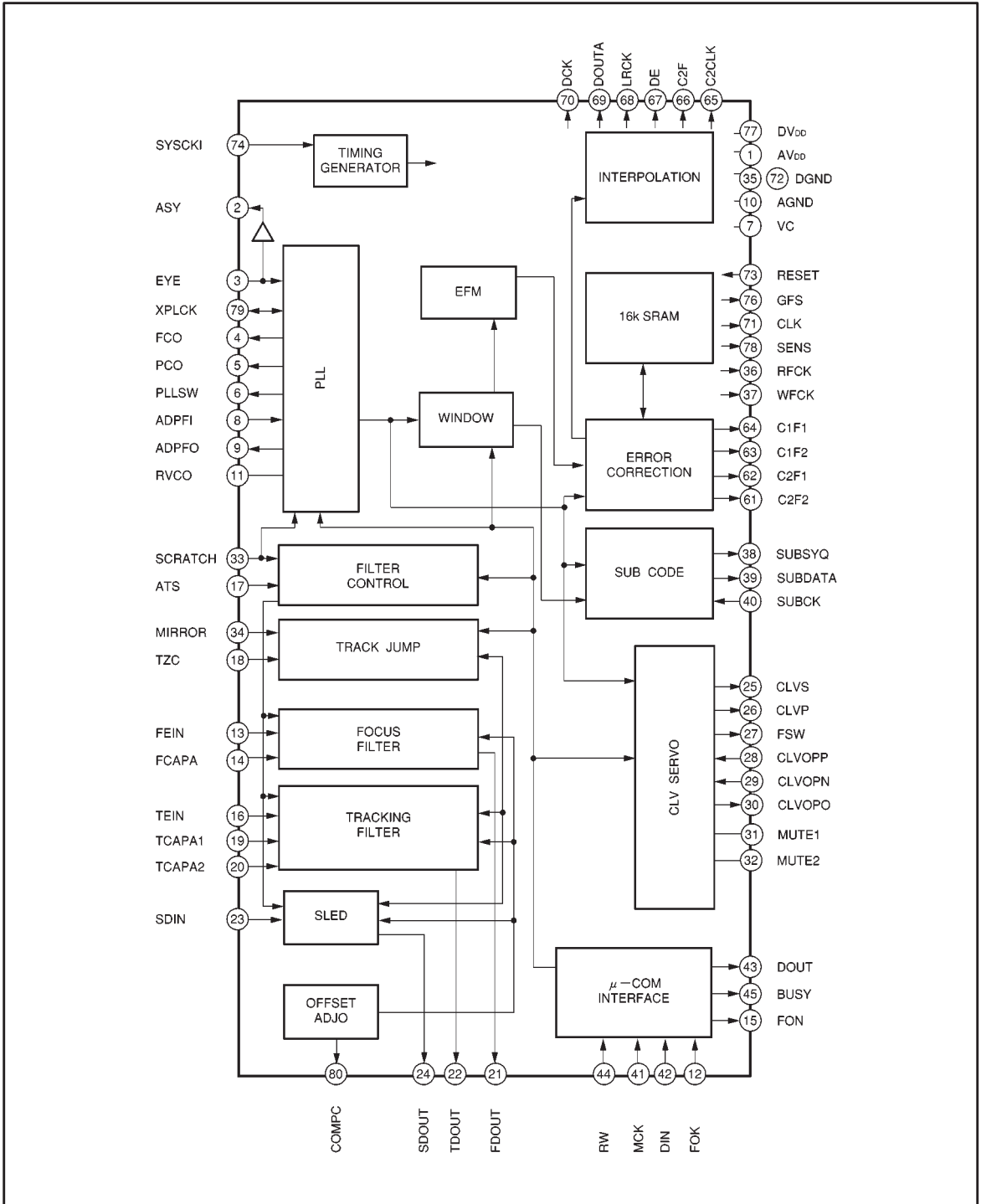
* Reduced by 4mW for each increase in Ta of 1°C over 25°C.

●Recommended operating conditions (Ta = 25°C)

Parameter	Symbol	Min.	Typ.	Max.	Unit
Power supply voltage	V _{DD}	2.6	—	3.5	V



● Block diagram



● Pin descriptions

Pin No.	Pin name	Analog/digital	I / O	Function	I/O circuit
1	AV _{DD}	—	—	Analog power supply	—
2	ASY	Digital	O	EFM signal slice level control output	4
3	EYE	Digital	I	EFM signal input pin from the RF amplifier	1
4	FCO	Analog	O	PLL frequency comparator output (R=15 Ω)	8
5	PCO	Analog	O	PLL phase comparison error voltage output (R=5 Ω)	8
6	PLLSW	Analog	O	PLL time constant switch pin	6
7	VC	Analog	I	Bias voltage input	7
8	ADPFI	Analog	I	PLL addition amplifier inversion signal	7
9	ADPFO	Analog	O	PLL addition amplifier output	7
10	AGND	—	I	Analog ground	—
11	RVCO	Analog	I	PLL VCO oscillator frequency adjustment	7
12	FOK	Digital	I	Focus OK signal input	1
13	FEIN	Analog	I	Focus error signal input	7
14	FCAPA	Analog	O	For connection of capacitor for focus servo filter	7
15	FON	Digital	O	Focus on signal output	2
16	TEIN	Analog	I	Tracking error signal input	7
17	ATS	Analog	I	Anti-shock detector window comparator input	7
18	TZC	Analog	I	Tracking/zero cross comparator input	7
19	TCAPA1	Analog	O	For connection of switch 1 for tracking servo filter	7
20	TCAPA2	Analog	O	For connection of switch 2 for tracking servo filter	7
21	FDOUT	Analog	O	Focus drive output	7
22	TDOUT	Analog	O	Tracking drive output	7
23	SDIN	Analog	I	Sled amplifier input	7
24	SDOUT	Analog	O	Sled drive output	7
25	CLVS	Analog	O	CLV speed control output	7
26	CLVP	Analog	O	CLV phase control output	7
27	FSW	Analog	O	CLV filter time constant switch	6
28	CLVOPP	Analog	I	CLV addition amplifier non-inverted input	7
29	CLVOPN	Analog	I	CLV addition amplifier inverted input	7
30	CLVOPO	Analog	O	CLV addition amplifier output	7
31	MUTE1	Analog	I / O	CLV mute switch 1	7
32	MUTE2	Analog	I / O	CLV mute switch 2	7
33	SCRATCH	Digital	I	Scratch signal input	1
34	MIRROR	Digital	I	Mirror signal input	1
35	DGND	—	—	Digital ground	—
36	RFCK	Digital	O	Read frame clock output	2
37	WFCK	Digital	O	Write frame clock output	2
38	SUBSYQ	Digital	O	Sub-code sync signal S1 output	2
39	SUBDATA	Digital	O	Sub-code serial output	2
40	SUBCK	Digital	I	Clock input for sub-code read	1

Optical disc ICs

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Pin No.	Pin name	Analog/digital	I / O	Function	I/O circuit
41	MCK	Digital	I	Clock input for command read and sub-code read	1
42	DIN	Digital	I	Command serial input from microprocessor	1
43	DOUT	Digital	O	Sub-Q code serial output	4
44	RW	Digital	O	Read/write switch input	1
45	BUSY	Digital	O	Busy output ("L" during track jump)	2
46	N.C.	—	—	—	—
47	N.C.	—	—	—	—
48	N.C.	—	—	—	—
49	N.C.	—	—	—	—
50	N.C.	—	—	—	—
51	N.C.	—	—	—	—
52	N.C.	—	—	—	—
53	N.C.	—	—	—	—
54	N.C.	—	—	—	—
55	N.C.	—	—	—	—
56	N.C.	—	—	—	—
57	N.C.	—	—	—	—
58	N.C.	—	—	—	—
59	N.C.	—	—	—	—
60	N.C.	—	—	—	—
61	C2F2	Digital	O	C22 correction flag output	2
62	C2F1	Digital	O	C21 correction flag output	2
63	C1F2	Digital	O	C12 correction flag output	2
64	C1F1	Digital	O	C11 correction flag output	2
65	C2CLK	Digital	O	Strobe signal (f=176.4kHz)	2
66	C2F	Digital	O	Correction status output	2
67	DE	Digital	O	Strobe signal (f=88.2kHz)	2
68	LRCK	Digital	O	Strobe signal (f=44.1kHz)	2
69	DOUTA	Digital	O	Audio data output (2'SCOMP)	2
70	DOCK	Digital	O	Bit clock for DOUT (f=2.1168MHz)	2
71	CLK	Digital	O	Clock output (select from four types using &hE4 command)	2
72	DGND2	—	—	Digital ground	—
73	RESET	Digital	I	Internal circuit reset	3
74	SYSCKI	Digital	I	System clock input (f=16.93MHz)	1
75	N.C.	—	—	—	—
76	GFS	Digital	O	GFS monitor output (select from four types using &hE4 command)	2
77	DV _{DD}	—	—	Digital power supply	—
78	SENS	Digital	O	Monitor output pin (&hE4 command setting or offset comparator output)	2
79	XPLCK	Digital	I / O	PLL playback clock output or external PLL playback clock input	5
80	COMPC	Analog	O	Offset adjustment smoothing (analog offset measurement is possible)	7

● Input / output circuits

<p>1</p>		<p>5</p>
<p>2</p>		<p>6</p>
<p>3</p>		<p>7</p>
<p>4</p>		<p>8</p>

Pin types

- * 1 CMOS inputs.
EYE (3pin), FOK (12pin), SCRATCH (33pin), MIRROR (34pin), SUBCK (40pin), MCK (41pin), DIN (42pin), RW (44pin), SYSCKI (74pin)
- * 2 Inputs with pullups.
RESET (73pin)
- * 3 CMOS outputs.
FON (15pin), RFCK (36pin), WFCK (37pin), SUBSYQ (38pin), SUBDATA (39pin), BUSY (45pin), C2F2 (61pin), C2F1 (62pin), C1F2 (63pin), C1F1 (64pin), C2CLK (65pin), C2F (66pin), DE (67pin), LRCK (68pin), DOUTA (69pin), DOCK (70pin), CLK (71pin), GFS (76pin), SENS (78pin), XPLCK (79pin)
- * 4 Tri-state outputs.
ASY (2pin), DOUT (43pin)
- * 5 Open drain.
PLLSW (6pin), FSW (27pin)

●Electrical characteristics (digital system)

DC characteristics (unless otherwise noted, $T_a = 25^\circ\text{C}$ and $V_{DD} = 2.6\text{V}$)

Parameter		Symbol	Min.	Typ.	Max.	Unit	Conditions	Applicable pin
Input voltage	High level voltage	V_{IH}	1.9	—	—	V	$I_o = 1\text{mA}$	*1, 2
	Low level voltage	V_{IL}	—	—	0.5	V	$I_o = -1\text{mA}$	*1, 2
Reset pin input current		I_{IH}	15	40	100	μA	$V_{IN} = 0\text{V}$	*2
Input current		I_{LI}	—	—	± 5	μA	$V_{IN} = 0 \sim 2.6\text{V}$	*1
Output voltage	High level voltage	V_{OH}	2.2	—	—	V	—	*3, 4
	Low level voltage	V_{OL}	—	—	0.5	V	—	*3, 4, 5
Tri-state output leak current		I_{OZH}	—	—	± 5	μV	$V_o = 0 \sim 2.6\text{V}$	*4, 5

● Electrical characteristics (analog system)

(unless otherwise noted, $T_a = 25^\circ\text{C}$, $V_{DD} = 2.6\text{V}$, $R_L = 10\text{k}\Omega$ and V_C reference)

Parameter	Symbol	Min.	Typ.	Max.	Unit	Conditions	Setting command
Quiescent current	I_Q	3.0	6.5	10	mA	—	—
〈Focus servo〉							
DC voltage gain	G_{FD1}	23	26	29	dB	$I_N = 1\text{Hz}$, 20mV_{P-P}	$10\times F$, 1462
AC voltage gain 1	G_{FDF1}	3	6	9	dB	$I_N = 1\text{kHz}$, 100mV_{P-P}	$10\times F$, 1462
AC voltage gain 2	G_{FDF2}	-4	-1	2	dB	$I_N = 300\text{Hz}$, 100mV_{P-P}	$10\times F$, 1462
Maximum output voltage	V_{FD1}	1.0	—	—	V	—	—
Minimum output voltage	V_{FD2}	—	—	-1.0	V	—	—
Offset voltage	V_{FOF}	-600	—	600	mV	—	$10\times F$, 1462
〈Tracking servo〉							
DC voltage gain	G_{TD1}	22	25	28	dB	$I_N = 1\text{Hz}$, 20mV_{P-P}	$10D\times$, 1159, 1207
AC voltage gain 1	G_{TDF1}	4	7	10	dB	$I_N = 1\text{kHz}$, 100mV_{P-P}	$10D\times$, 1159, 1207
AC voltage gain 2	G_{TDF2}	-3	0	3	dB	$I_N = 300\text{Hz}$, 100mV_{P-P}	$10D\times$, 1159, 1207
AC voltage gain 3	G_{TDF3}	25	28	31	dB	$I_N = 1\text{kHz}$, 20mV_{P-P}^{*1}	$10D\times$, 1159, 1207
AC voltage gain 4	G_{TDF4}	20	23	26	dB	$I_N = 300\text{Hz}$, 20mV_{P-P}^{*1}	$10D\times$, 1159, 1207
Maximum output voltage	V_{TD1}	1.0	—	—	V	—	—
Minimum output voltage	V_{TD2}	—	—	-1.0	V	—	—
Offset voltage	V_{TOF}	-530	—	530	mV	—	$10D\times$, 1159, 1207
Jump output voltage	V_{JP1}	1.0	1.2	—	V	—	$13\times F$
Jump output voltage	V_{JP2}	—	-1.2	-1.0	V	—	$13F\times$
ATS threshold voltage 1	V_{ATS1}	10	—	50	mV	—	—
ATS threshold voltage 2	V_{ATS2}	-50	—	-10	mV	—	—
TZC threshold voltage	V_{TZC}	-50	—	50	mV	—	—
ON resistance between TCAPA1 and TCAPA2	R_{TON}	—	50	150	Ω	$I = 0.1\text{mA}$	$1E\times 1$
〈Sled servo〉							
DC voltage gain	G_{SD1}	23	26	29	dB	$I_N = 100\text{Hz}$, 20mV_{P-P}	$124\times$
Maximum output voltage	V_{SD1}	1.0	—	—	V	—	—
Minimum output voltage	V_{SD2}	—	—	-1.0	V	—	—
Offset voltage	V_{SOF}	-200	0	200	mV	—	$124\times$
Kick output voltage 1	V_{KC1}	1.0	1.2	—	V	—	$18\times F$
Kick output voltage 2	V_{KC2}	—	-1.2	-1.0	V	—	$18F\times$

*1 AC gain for gain amplifier (100k Ω between TCAPA1 and TCAPA2).

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Parameter	Symbol	Min.	Typ.	Max.	Unit	Conditions	Setting command
〈CLV amplifier〉							
Maximum output voltage	V _{OPD1}	1.0	—	—	V	—	—
Minimum output voltage	V _{OPD2}	—	—	1.0	V	—	—
Input offset voltage	V _{OPOF}	−15	0	15	mV	—	—
〈CLV mute switch〉							
ON resistance	R _{ON}	—	260	800	Ω	I=1mA	E0
〈Offset adjustment block〉							
Offset variable range 1	ΔV _{OF1}	±620	±710	—	mV	Focus, tracking	
Offset variable range 2	ΔV _{OF2}	±300	±390	—	mV	Sled	124×
〈PLL block〉							
VCO oscillator frequency	f _{VCO}	13	—	21	MHz	—	—

*1 AC gain for gain amplifier (100kΩ between TCAPA1 and TCAPA2).

⊙Not designed for radiation resistance.

●External dimensions (Units: mm)

