# 2878 AND 2879 

## QUAD HIGH－CURRENT DARLINGTON SWITCHES



Dwg．No．A－11，974


These quad Darlington arrays are designed to serve as interface between low－level logic and peripheral power devices such as sole－ noids，motors，incandescent displays，heaters，and similar loads of up to 320 W per channel．Both integrated circuits include transient－ suppression diodes that enable use with inductive loads．The input logic is compatible with most TTL，DTL，LSTTL，and 5 V CMOS logic．

Type UDN2878W and UDN2879W 4 A arrays are identical except for output－voltage ratings．The former is rated for operation to 50 V （ 35 V sustaining），while the latter has a minimum output breakdown rating of 80 V （ 50 V sustaining）．The lower－cost UDN2879W－2 is recommended for applications requiring load currents of 3 A or less． These less expensive devices are identical to the basic parts except for the maximum allowable load－current rating．

For maximum power－handling capability，all drivers are supplied in a 12－pin single in－line power－tab package．The tab needs no insulation． External heat sinks are usually required for proper operation of these devices．

## FEATURES

■ Output Currents to 4 A
－Output Voltages to 80 V
－Loads to 1280 W
－TTL，DTL，or CMOS Compatible Inputs
－Internal Clamp Diodes
－Plastic Single In－Line Package
－Heat－Sink Tab

Always order by complete part number：

| Part Number | Max． $\mathrm{I}_{\mathrm{C}}$ | Max． $\mathrm{V}_{\text {CEx }}$ | Min． $\mathrm{V}_{\text {CE（sus）}}$ |
| :--- | :---: | :---: | :---: |
| UDN2878W | 5.0 A | 50 V | 35 V |
| UDN2879W | 5.0 A | 80 V | 50 V |
| UDN2879W－2 | 4.0 A | 80 V | 50 V |



PARTIAL SCHEMATIC
One of 4 Drivers


Dwg. No. A-12,037
NOTE: Pin 3 must be connected to ground for proper operation.

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ELECTRICAL CHARACTERISTICS at $\mathrm{V}_{\mathrm{S}}=5.0 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=+25^{\circ} \mathrm{C}$ (unless otherwise noted).

| Characteristic | Symbol | Test <br> Fig. | Applicable Devices | Test Conditions | Limits |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  |  |  | Min. | Max. | Units |
| Output Leakage Current | $I_{\text {CEX }}$ | 1 | UDN2878W | $\mathrm{V}_{\text {CE }}=50 \mathrm{~V}$ | - | 100 | $\mu \mathrm{A}$ |
|  |  |  |  | $\mathrm{V}_{\mathrm{CE}}=50 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=+70^{\circ} \mathrm{C}$ | - | 500 | $\mu \mathrm{A}$ |
|  |  |  | UDN2879W/W-2 | $\mathrm{V}_{C E}=80 \mathrm{~V}$ | - | 100 | $\mu \mathrm{A}$ |
|  |  |  |  | $\mathrm{V}_{C E}=80 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=+70^{\circ} \mathrm{C}$ | - | 500 | $\mu \mathrm{A}$ |
| Output Sustaining Voltage | $\mathrm{V}_{\text {CE(sus) }}$ | - | UDN2878W | $\mathrm{I}_{\mathrm{C}}=4 \mathrm{~A}, \mathrm{~L}=10 \mathrm{mH}$ | 35 | - | V |
|  |  |  | UDN2879W | $\mathrm{I}_{\mathrm{C}}=4 \mathrm{~A}, \mathrm{~L}=10 \mathrm{mH}$ | 50 | - | V |
|  |  |  | UDN2879W-2 | $\mathrm{I}_{\mathrm{C}}=3 \mathrm{~A}, \mathrm{~L}=10 \mathrm{mH}$ | 50 | - | V |
| Collector-Emitter Saturation Voltage | $\mathrm{V}_{\text {CE(SAT) }}$ | 2 | All | $\mathrm{I}_{\mathrm{C}}=500 \mathrm{~mA}, \mathrm{~V}_{\text {IN }}=2.75 \mathrm{~V}$ | - | 1.1 | V |
|  |  |  |  | $\mathrm{I}_{\mathrm{C}}=1.0 \mathrm{~A}, \mathrm{~V}_{\text {IN }}=2.75 \mathrm{~V}$ | - | 1.3 | V |
|  |  |  |  | $\mathrm{I}_{\mathrm{C}}=2.0 \mathrm{~A}, \mathrm{~V}_{\text {IN }}=2.75 \mathrm{~V}$ | - | 1.5 | V |
|  |  |  |  | $\mathrm{I}_{\mathrm{C}}=3.0 \mathrm{~A}, \mathrm{~V}_{\text {IN }}=2.75 \mathrm{~V}$ | - | 1.9 | V |
|  |  |  | UDN2878/79W | $\mathrm{I}_{\mathrm{C}}=4.0 \mathrm{~A}, \mathrm{~V}_{\text {IN }}=3.0 \mathrm{~V}$ | - | 2.4 | V |
| Input Current | $\mathrm{I}_{\mathrm{N}}$ | 3 | All | $\mathrm{V}_{\text {IN }}=2.75 \mathrm{~V}$ | - | 550 | $\mu \mathrm{A}$ |
|  |  |  |  | $\mathrm{V}_{\text {IN }}=3.75 \mathrm{~V}$ | - | 1000 | $\mu \mathrm{A}$ |
| Input Voltage | $\mathrm{V}_{\text {IN(ON }}$ | 4 | All | $\mathrm{V}_{\mathrm{CE}}=2.2 \mathrm{~V}, \mathrm{I}_{\mathrm{C}}=3.0 \mathrm{~A}$ | - | 2.75 | V |
|  |  |  | UDN2878/79W | $\mathrm{V}_{\mathrm{CE}}=2.2 \mathrm{~V}, \mathrm{I}_{\mathrm{C}}=4.0 \mathrm{~A}$ | - | 2.75 | V |
| Supply Current per Driver | $\mathrm{I}_{\text {S }}$ | 7 | All | $\mathrm{I}_{\mathrm{C}}=500 \mathrm{~mA}, \mathrm{~V}_{\text {IN }}=2.75 \mathrm{~V}$ | - | 6.0 | mA |
| Turn-On Delay | $t_{\text {PLH }}$ | - | All | $0.5 \mathrm{E}_{\text {in }}$ to $0.5 \mathrm{E}_{\text {out }}$ | - | 1.0 | $\mu \mathrm{s}$ |
| Turn-Off Delay | $\mathrm{t}_{\text {PHL }}$ | - | All | $0.5 \mathrm{E}_{\text {in }}$ to $0.5 \mathrm{E}_{\text {out }}, \mathrm{I}_{\mathrm{C}}=3.0 \mathrm{~A}$ | - | 1.5 | $\mu \mathrm{s}$ |
| Clamp Diode Leakage Current | $\mathrm{I}_{\mathrm{R}}$ | 5 | All | $\mathrm{V}_{\mathrm{R}}=50 \mathrm{~V}$ | - | 50 | $\mu \mathrm{A}$ |
|  |  |  |  | $\mathrm{V}_{\mathrm{R}}=50 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=+70^{\circ} \mathrm{C}$ | - | 100 | $\mu \mathrm{A}$ |
|  |  |  | UDN2879W/W-2 | $\mathrm{V}_{\mathrm{R}}=80 \mathrm{~V}$ | - | 50 | $\mu \mathrm{A}$ |
|  |  |  |  | $\mathrm{V}_{\mathrm{R}}=80 \mathrm{~V}, \mathrm{~T}_{\mathrm{A}}=+70^{\circ} \mathrm{C}$ | - | 100 | $\mu \mathrm{A}$ |
| Clamp Diode Forward Voltage | $\mathrm{V}_{\mathrm{F}}$ | 6 | All | $\mathrm{I}_{\mathrm{F}}=3.0 \mathrm{~A}$ | - | 2.5 | V |
|  |  |  | UDN2878/79W | $\mathrm{I}_{\mathrm{F}}=4.0 \mathrm{~A}$ | - | 3.0 | V |

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## TEST FIGURES



Dwg. No. A-9729A
FIGURE 1


FIGURE 4


Dwg. No. A-10,350
FIGURE 2


FIGURE 5


Dwg. No. A-9732
FIGURE 3


FIGURE 6


FIGURE 7

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## TYPICAL APPLICATIONS



Dwg. No. A-11,975

PRINT-HAMMER DRIVER


STEPPER-MOTOR DRIVER


Dwg. No. A-11,795

DIGIT DRIVER FOR MULTIPLEXED INCANDESCENT LAMP DISPLAY


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## Dimensions in Inches

(controlling dimensions)


NOTES: 1. Lead thickness is measured at seating plane or below.
2. Lead spacing tolerance is non-cumulative
3. Exact body and lead configuration at vendor's option within limits shown.
4. Lead gauge plane is 0.030 " below seating plane.

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## Dimensions in Millimeters <br> (for reference only)



NOTES: 1. Lead thickness is measured at seating plane or below.
2. Lead spacing tolerance is non-cumulative
3. Exact body and lead configuration at vendor's option within limits shown.
4. Lead gauge plane is 0.762 mm below seating plane.

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## POWER SINK DRIVERS SELECTION GUIDE

IN ORDER OF 1) OUTPUT CURRENT, 2) OUTPUT VOLTAGE, 3) NUMBER OF DRIVERS

| Output Ratings * |  |  | Features |  |  |  |  | Part Number ${ }^{\dagger}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| mA | V | \# | Serial Input | Latched Drivers | Diode <br> Clamp | Saturated Outputs | Internal Protection |  |
| 100 | 20 | 8 | - | - | - | X | - | 2595 |
|  | 30 | 32 | X | X | - | - | - | 5833 |
|  | 40 | 32 | X | X | - | X | - | 5832 |
| 250 | 135 | 7 | - | - | X | - | - | 7003 |
| 300 | 45 | 1 | Hall Sensor/Driver |  | X | - | X | 5140 |
|  | 50 | 7 | - | - | X | - | - | 2003 |
|  | 50 | 8 | - | - | X | - | - | 2803 |
|  | 50 | 8 | - | - | X | X | - | 2596 |
|  | 60 | 2 | Hall Sensor/Driver |  | - | X | - | 5275 |
|  | 60 | 4 | - | - | X | X | X | 2557 |
|  | 95 | 7 | - | - | X | - | x | 2023 |
|  | 95 | 8 | - | - | X | - | - | 2823 |
| 350 | 50 | 4 | - | X | X | - | - | 5800 |
|  | 50 | 7 | - | - | X | - | - | 2004 |
|  | 50 | 8 | - | - | X | - | - | 2804 |
|  | 50 | 8 | - | X | X | - | - | 5801 |
|  | 50 | 8 | X | X | - | - | - | 5821 |
|  | 80 | 8 | X | X | - | - | - | 5822 |
|  | 50 | 8 | X | X | X | - | - | 5841 |
|  | 80 | 8 | X | X | X | - | - | 5842 |
|  | 95 | 7 | X | - | X | - | - | 2024 |
|  | 95 | 8 | - | - | X | - | - | 2824 |
| 450 | 30 | 28 | Dual 4 to 14-Line Decoder/Drive |  |  | er - | - | 6817 |
| 600 | 60 | 4 | - | - | - | X | X | 2547 |
|  | 60 | 4 | - | - | X | X | X | 2549 |
| 700 | 60 | 4 | - | - | X | X | X | 2543 and 2559 |
| 750 | 50 | 8 | - | - | X | X | - | 2597 |
| 900 | 14 | 2 | Hall Sensor/DriverHall Sensor/Driver |  | X | X | X | 3625 |
|  | 26 | 2 |  |  | X | X | X | 3626 |
| 1000 | 46 | 4 | Stepper Motor Controller/Driver |  |  | MOS | - | 7024 and 7029 |
| 1200 | 46 | 4 | Microstepping Controller/Drive |  |  | MOS | - | 7042 |
| 1250 | 50 | 4 |  |  |  | r | X | 5804 |
|  | 50 | 4 | Stepper Motor Translator/Driver |  |  | - | - | 2064 and 2068 |
| 1500 | 80 | 4 | - | - | X | - | - | 2065 and 2069 |
| 1600 | 50 | 9 | X | X | - | - | X | 5829 |
| 1800 | 50 | 4 | - | - | X | - | - | 2544 |
|  | 50 | 4 | - | - | X | - | - | 2540 |
| 3000 | 46 | 4 | Stepper Motor Controller/Driver |  |  | MOS | - | 7026 |
| 4000 | 50 | 4 | - | - | X | - | - | 2878 |
|  | 80 | 4 | - | - | X | - | - | 2879 |

[^1]
[^0]:    Caution: High-current tests are pulse tests or require heat sinking.

[^1]:    * Current is maximum specified test condition, voltage is maximum rating. See specification for sustaining voltage limits or over-current protection voltage limits.
    $\dagger$ Complete part number includes additional characters to indicate operating temperature range and package style.

