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# ICs for Communications

ISDN High Voltage Power Controller IHPC

PEB 2026 Version 1.1

Data Sheet 09.99

PEB 2026			
Revision His	story:	Current Version: 09.99	
Previous Ver	sion:	preliminary Data Sheet 02.96	
Page   Page   (in previous Version)   Version)		Subjects (major changes since last revision)	
3-2 I		Information added about thermal protection and life time	
	3-3	Information added about parasitic diodes	
	3-3	Extra paragraphfor subject "I <sub>BAT</sub> current peak"	
16	7-1	Some values for absolute maximum ratings are extended/adapted.	
17	7-4	The static thermal resistances are updated. The last two paragraphs on this page, explaning the reason for the different packages are additional.	

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Overview

### 1 Overview

The IHPC is an integrated power controller especially designed for feeding two-wire ISDN-transmission lines. One line can be powered by one IHPC. An external resistor defines the value of the current-limit for the line. Powering can be switched on or off by the logic inputs "PFEN" and "PFENQ". With a logic low at the "APFI" output the IHPC signals that current-limiting is active; this signal is low-pass filtered. An external capacitor defines the corner frequency of this low-pass filter and the resulting delay time respectively. A second external capacitor is needed to make sure that longitudinal disturbances (AC) will not produce a current limiting effect. Line current-limiting and reducing this limiting level in case of overtemperature guards the IHPC against overloads.



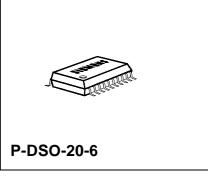
# ISDN High Voltage Power Controller IHPC

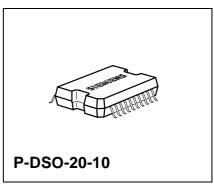
**PEB 2026** 

Version 1.1 CMOS

### 1.1 Features

- Battery voltage up to 130 V
- Supplies power for one transmission line
- Current limiting and chip temperature control
- Limiting current can be programmed by an external resistor
- Automatically reduced feeding current in case of overtemperature
- Reliable 170 V Smart Power Technology (SPT 170)
- Small P-DSO-20 package





Туре	Package
PEB 2026	P-DSO-20-6
	P-DSO-20-10



**Pin Description** 

# 2 Pin Description

### 2.1 Pin Configuration

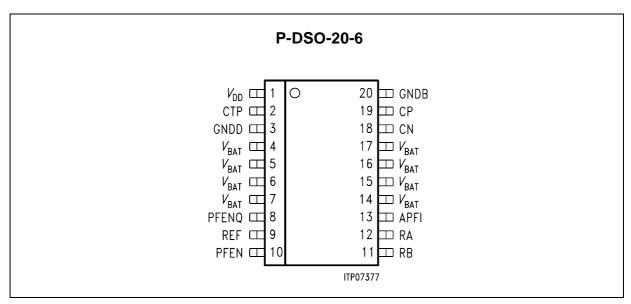


Figure 2-1 Pin Configuration P-DSO-20-6 (top view)

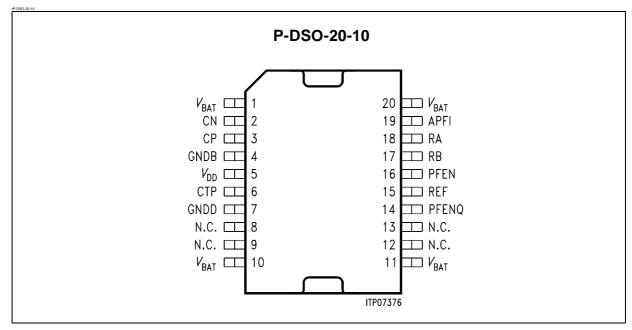


Figure 2-2 Pin Configuration P-DSO-20-10 (top view)



**Pin Description** 

### 2.2 Pin Definitions and Functions

Table 2-1 Pin Definitions and Functions P-DSO-20-6

Pin	Symbol	Туре	Description	
4-7, 14-17	$V_{\scriptscriptstyle BAT}$	Supply	Negative battery supply voltage (– 100 V), referred to GNDB	
20	GNDB	Supply	Battery ground: RB and RA refer to this pin	
1	$V_{\scriptscriptstyle DD}$	Supply	Positive supply voltage (+ 5 V), referred to GNDD	
3	GNDD	Supply	Digital ground: $V_{\rm DD}$ , REF, CP, CN, CTP, PFEN, PFENQ and APFI refer to this pin	
9	REF	0	Reference output, connected to GNDD via a resistor	
19	СР	0	Positive pole of the external capacitor $C_{\mbox{\tiny HP}}$	
18	CN	I	Negative pole of the external capacitor $C_{\mbox{\tiny HP}}$	
2	СТР	0	Positive pole of the external capacitor $C_{\scriptscriptstyleTP}$	
11	RB	0	Output for powering line b (tip), current sensing	
12	RA	0	High voltage output for powering line a (ring), current limiting/switching	
10	PFEN	I	Logic high on this pin switches on the current feeding	
8	PFENQ	I	Logic low on this pin switches on the current feeding	
13	APFI	0	Logic low on this pin signals active current-limiting	

Table 2-2 Pin Definitions and Functions P-DSO-20-10

Pin	Symbol	Туре	Description
1,10, 11,20	$V_{\scriptscriptstyle BAT}$	Supply	Negative battery supply voltage (– 100 V), referred to GNDB
4	GNDB	Supply	Battery ground: RB and RA refer to this pin
5	$V_{\scriptscriptstyle DD}$	Supply	Positive supply voltage (+ 5 V), referred to GNDD
7	GNDD	Supply	Digital ground: $V_{\rm DD}$ , REF, CP, CN, CTP, PFEN, PFENQ and APFI refer to this pin
15	REF	0	Reference output, connected to GNDD via a resistor
3	СР	0	Positive pole of the external capacitor $C_{\mbox{\tiny HP}}$
2	CN	1	Negative pole of the external capacitor $C_{\mbox{\tiny HP}}$
6	СТР	0	Positive pole of the external capacitor $C_{TP}$
17	RB	0	Output for powering line b (tip), current sensing



# **Pin Description**

Table 2-2 Pin Definitions and Functions P-DSO-20-10 (cont'd)

Pin	Symbol	Туре	Description
18	RA	0	High voltage output for powering line a (ring), current limiting/switching
16	PFEN	I	Logic high on this pin switches on the current feeding
14	PFENQ	I	Logic low on this pin switches on the current feeding
19	APFI	0	Logic low on this pin signals active current-limiting

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### **Functional Description**

# 3 Functional Description

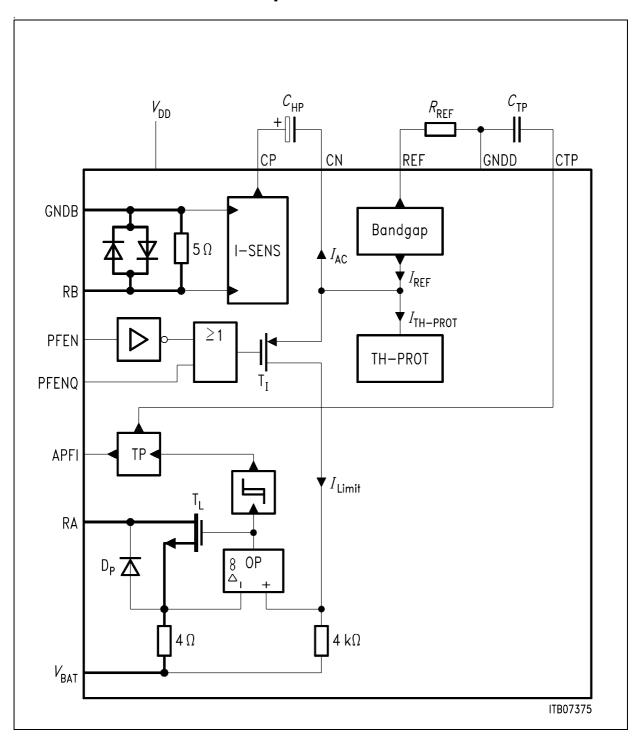


Figure 3-1 Block Diagram

The current flowing from GNDB to RB is measured. A down scaled image of this current is filtered by a high-pass filter with a corner frequency  $f_{CHP}$  of approximately 3 Hz (see



### **Functional Description**

Figure 5-4). This filter needs the external capacitor  $C_{\rm HP}$ . This "AC"-current is subtracted from the reference-current generated in the bandgap. The value of the reference-current is defined by the external resistor  $R_{\rm RFF}$ .

In case of overtemperature the thermal protection TH-PROT sinks a current, so that the current  $I_{\text{Limit}}$  is reduced. So in case of high power dissipation on chip the junction temperature is limited to about 165 °C.

This function is a protection against instant damages due to overload at the outputs. Continuous high temperatures during operation, however, will reduce the life time of the IHPC. A maximum junction temperature of 150°C shall not be exceeded (See section 7, "Electrical Characteristics")

Measures have to be taken to switch off the IHPC in case of a short-circuit. E.g. if pin APFI indicates active current-limiting, the IHPC should be deactivated after 1.5 sec using pin PFEN or PFENQ. A consecutive power-up attempt shall give enough time to the IHPC to cool down again (e.g. 30 sec).

The current  $I_{\text{Limit}}$  is reflected to the output current  $I_{\text{Line}}$  flowing from RA to  $V_{\text{BAT}}$  using the operational-amplifier OP, the transistor  $T_{\text{L}}$  and two resistors (4  $\Omega$ , 4 k $\Omega$ ).

$$I_{\mathrm{Line,max}}\left(\mathbf{t}\right)=1000\times I_{\mathrm{Limit}}\left(\mathbf{t}\right)=1000\times\left(I_{\mathrm{REF}}-I_{\mathrm{TH-PROT}}\left(\mathbf{t}\right)-I_{\mathrm{AC}}\left(\mathbf{t}\right)\right)$$

In case of "no current-limiting" the output voltage of the operational-amplifier OP is equal to the positive OP-supply voltage. The transistor  $T_{\scriptscriptstyle L}$  is "switched on".

If the output current  $I_{\text{Line}}$  rises to  $I_{\text{Line,max}}$  the current-mirror becomes active and keeps the output current at this level.

The voltage level at the gate of transistor  $T_{\rm L}$  shows the state of the current-limiter (current-limiting active or not). This state-signal is filtered by a low-pass filter and generates the logic output APFI. The external capacitor  $C_{\rm TP}$  of this low-pass filter defines the corner frequency and the resulting delay times  $t_{\rm LIMON}$  (Spec.-No.: 17) and  $t_{\rm LIMOFF}$  (Spec.-No.: 18) respectively.

Summarized, the current sensor I-SENS and the high-pass filter prevent, that a longitudinal disturbance in the frequency range from about  $(5*f_{CHP})$  to about 100kHz result in a current limitation. This applies if the maximum amplitude of the longitudinal current is lower than about half of the current limit (Spec.-No.: 3) defined by the external resistor  $R_{REF}$ , see also Spec.-No.: 15 and 16.

There is also another effect from the current sensing and high-pass filtering, which can be seen when changing from status LIMOFF to LIMON. This can occur by switching power on to the line (loading the line capacitor) or in case of short-circuiting the line. The resulting current transient starts at half of  $I_{\rm Line,max}$  and increases (capacitor loading function) to  $I_{\rm Line,max}$  with a time constant  $t_{\rm CHP}$  also defined by the value of  $C_{\rm HP}$ .



### **Functional Description**

The diodes connected to GNDB and RB protect the IHPC against lightning and overvoltages (see Absolute Maximum Ratings). The diode  $D_{\rm p}$  is the parasitic bulk-drain-diode of the DMOS-transistor  $T_{\rm L}$ .

Because of technology reasons ("p"-substrate, junction isolation) there are also parasitic diodes from pin  $V_{\rm BAT}$  to all other pins.

### $I_{\text{BAT}}$ current peak:

When line feeding is switched on (transistor  $T_{\rm L}$  is on) and a short circuit occurs between pins RA and GNDB (or GNDD) then it needs a certain time to unload the gate-source-capacitance of  $T_{\rm L}$  and to limit the current to the defined maximum value. In the meantime a current peak  $I_{\rm BAT}$  on the supply voltage  $V_{\rm BAT}$  can be seen.

An overvoltage protection circuit for pin RA, for example can produce such a short circuit between pins RA and GNDB.

In the IHPC a fast bipolar npn-transistor limits such current peaks. With  $V_{BAT}$  =100 V, the resulting  $I_{BAT}$  current transient has the profile of one triangular pulse with a peak value of about 1.5A and a time duration (50% to 50%) of about 130nsec.

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### **Operating Modes**

# 4 Operating Modes

Operating Mode	Status	PFEN	PFENQ	APFI
OFF, powering off		" $V_{\scriptscriptstyle IL}$ "	Don't care	" $V_{ extsf{oL}}$ "
OFF, powering off		Don't care	" $V_{ ext{ in}}$ "	" $V_{OL}$ "
ON, powering on	LIMON, limiter is active	" $V_{ ext{ in}}$ "	" $V_{\scriptscriptstyle IL}$ "	" $V_{OL}$ "
ON, powering on	LIMOFF, limiter isn't active	" $V_{ ext{IH}}$ "	" $V_{\scriptscriptstyle \rm IL}$ "	" $V_{OH}$ "

The logic input pins PFEN and PFENQ are connected to GNDD by integrated current sources. If these pins are not connected externally the logic level is " $V_{\rm L}$ ".

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# 5 Designing the External Components

Resistor  $R_{REF}$ :

The value of this resistor defines the current limit  $I_{\text{Limit,ON}}$  (Spec.-No.: 3) and it will also effect power supply currents  $I_{\text{BAT}}$  (Spec.-No.: 2) and  $I_{\text{DD}}$  (Spec.-No.: 1). For typical values of  $I_{\text{Limit,ON}}$ ,  $I_{\text{BAT}}$  and  $I_{\text{DD}}$  as a function of  $R_{\text{REF}}$  see the following diagrams.

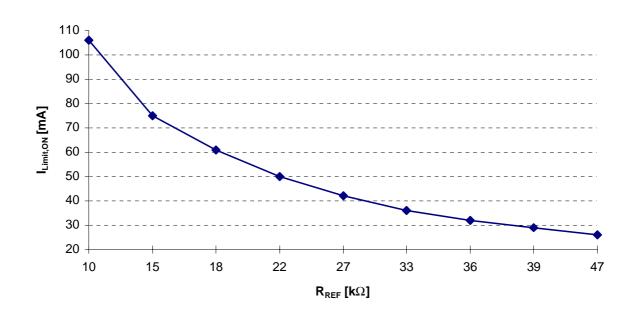


Figure 5-1 Current limit  $I_{Limit,ON}$  as a function of  $R_{REF}$  (typical values)



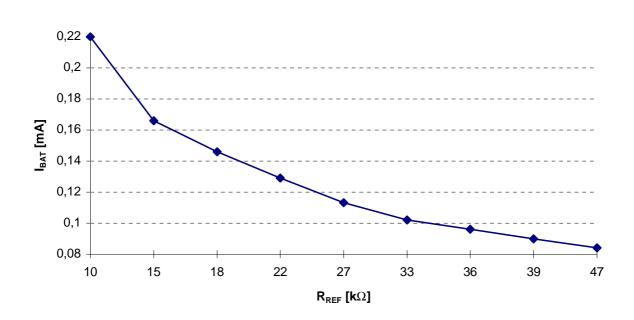


Figure 5-2 Power Supply Current  $I_{BAT}$  as a function of  $R_{REF}$  (typical values)

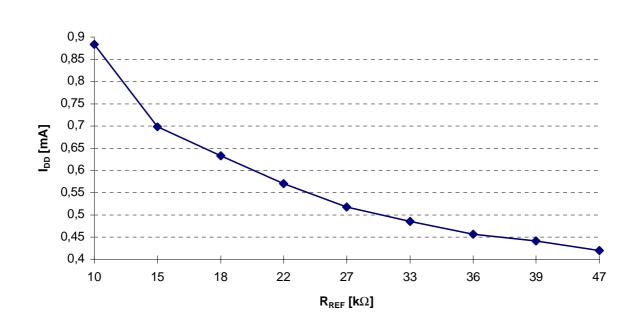


Figure 5-3 Power Supply Current  $I_{DD}$  as a function of  $R_{REF}$  (typical values)



### Capacitor $C_{HP}$ :

The value of this capacitor defines the corner frequency  $f_{CHP}$  of the high-pass filter and the time constant  $t_{CHP}$  of the current transient described at the last but one paragraph of chapter 2. The following diagrams show typical values of  $f_{CHP}$  and  $t_{CHP}$  as a function of  $C_{HP}$ .

45 40 35 30 25 20 15 10 0 0,33 0,47 0,68 2,2 3,3 4,7 6,8 C<sub>HP</sub> [µF]

Figure 5-4 Corner frequency of high-pass filter as a function of  $C_{\rm HP}$  (typical values)

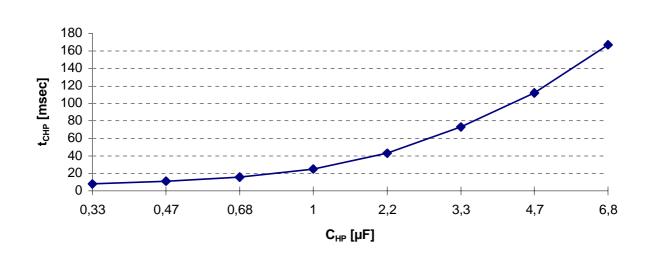


Figure 5-5 Time constant of high-pass filter as a function of  $C_{HP}$  (typical values)



### Capacitor $C_{TP}$ :

The value of this capacitor defines the corner frequency and the resulting delay times  $t_{\text{LIMON}}$  (Spec.-No.: 17) and  $t_{\text{LIMOFF}}$  (Spec.-No.: 18), of the low-pass filter. For typical values of  $t_{\text{LIMOFF}}$  as a function of  $C_{\text{TP}}$  see the following diagrams.

C<sub>TP</sub> [nF]

Figure 5-6 Delay time of the low-pass filter for the status output signal (typical values)

C<sub>TP</sub> [nF]

Figure 5-7 Delay time of the low-pass filter for the status output signal (typical values)

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### **Application Note**

# 6 Application Note

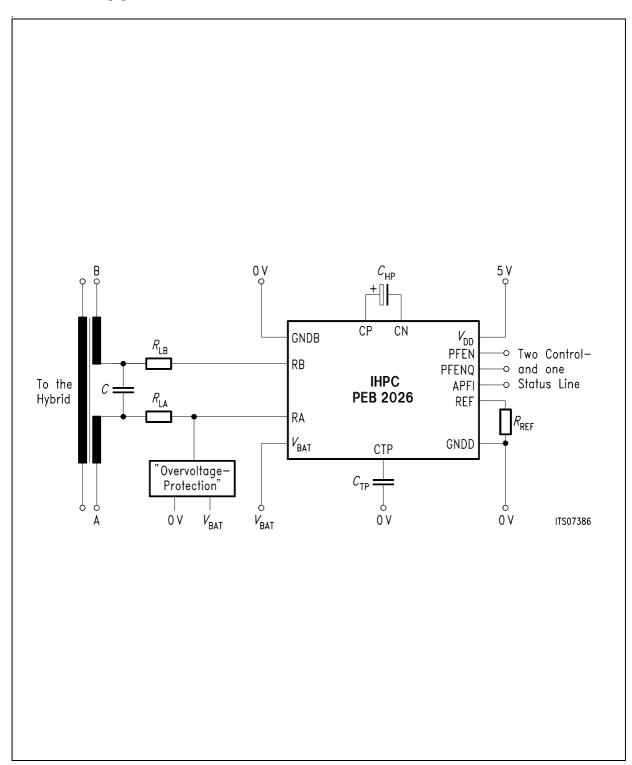


Figure 6-1 Application Circuit



### **Application Note**

 $R_{\text{\tiny RFF}}$  Defines the current-limit and the internal biasing currents. A

smaller/bigger value increases/decreases the current limit. It

will also effect power supply currents.

 $C_{\text{\tiny TP}}$  Defines with an internal resistor the delay time (a typical value

is 20 msec) from the low pass filter, whose output signal is called 'APFI'. Short disturbances will therefore be filtered. A smaller/bigger value decreases/increases the delay time.

 $C_{\rm HP}$  Defines with an internal resistor the corner frequency from a

high pass filter. It is used to make sure that longitudinal disturbances (AC) will not produce a current limiting effect. A smaller/bigger value decreases/increases the corner

frequency.

 $R_{LA}$ ,  $R_{LB}$  These resistors limit the peak currents during lightning

transients. The maximum value for these resistors is defined

by the allowed voltage drop on the resistors.

C The AC-signal-current will be shunted by this capacitor.

A, B A- and B-line to the subscriber

 $V_{\text{BAT}}$  The most negative supply voltage; also called battery voltage.

overvoltage protection This circuit makes sure that the voltage from  $R_{\rm A}$  to  $V_{\rm BAT}$  will not

exceed the defined limits in case of lightning (see Absolute

**Maximum Ratings).** 

### **Recommended Device Values:**

 $R_{\text{REF}}$  22 k $\Omega$ , Current limiting is set to 50 mA

 $C_{\text{TP}}$  220 nF, 'APFI' delay time is set to 20 msec

 $C_{HP}$  4.7 µF,AC longitudinal disturbances in a frequency range

higher than 16.666 Hz do not effect a current limiting.

 $R_{\rm IA}$ ,  $R_{\rm IB}$  23  $\Omega$ , Minimum value, so that peek currents don't exceed 16 A

(using voltage peek = 1 kV from 40  $\Omega$  source resistance) in

case of lightning.

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# **7** Electrical Characteristics

Table 7-1 Absolute Maximum Ratings

Parameter	Symbol Limit Values		Unit	Test Condition		
		min.	max.			
Battery voltage	$V_{\scriptscriptstyle \sf BAT}$	- 150	0.5	V	Referred to GNDB	
$\overline{V_{\scriptscriptstyle  m DD}}$ supply voltage	$V_{\scriptscriptstyle DD}$	- 0.5	6	V	Referred to GNDD	
Ground voltage difference	$V_{ ext{gndb}} - V_{ ext{gndd}}$	- 0.5	0.5	V		
Ground pulse voltage difference	$V_{ ext{GNDB}} - V_{ ext{GNDD}}$	<b>– 1</b>	1	V	$t_{\rm max} = 1 \; {\rm msec}$	
Junction temperature	$T_{\rm j}$		150	°C		
Voltages on logic inputs PFEN, PFENQ	$V_{\scriptscriptstyle{PFENQ}},\ V_{\scriptscriptstyle{PFENQ}}$	- 0.3	$V_{\rm DD}$ + 0.3	V	Referred to GNDD	
Voltages on REF	$V_{\scriptscriptstyle{REF}}$	- 0.3	$V_{\rm DD}$ + 0.3	V	Referred to GNDD	
Voltages on CP	$V_{ extsf{CP}}$	- 0.3	$V_{\rm DD}$ + 0.3	V	Referred to GNDD	
Voltages on CN	$V_{\scriptscriptstyleCN}$	- 0.3	$V_{\rm DD}$ + 0.3	V	Referred to GNDD	
Voltages on CTP	$V_{\mathtt{CTP}}$	- 0.3	$V_{\text{DD}}$ + 0.3	V	Referred to GNDD	
Voltages on logic output APFI	$V_{\scriptscriptstyleAPFI}$	- 0.3	$V_{\text{DD}}$ + 0.3	V	Referred to GNDD	
RB voltage	$V_{\scriptscriptstyle{RB}}$	- 0.5	+ 0.5	V	Referred to GNDB	
RB pulse current	$I_{\rm RB}$ (into pin RB)	- 8	8	А	$t_{\rm max} = 1 \; {\rm msec}$	
RB peak current	$I_{ extsf{RB\_peak}}$	<b>– 16</b>	16	Α	See figure 7-7	
RA voltages	$V_{\scriptscriptstyle{RA}}$	- 0.3	150	V	Referred to $V_{\scriptscriptstyle BAT}$	
RA pulse current	$I_{\rm RA}$ (into pin RA)	<b>– 1</b>	1	А	$t_{\rm max} = 1 \; {\rm msec}$	
RA pulse voltage	$V_{ extsf{RA\_pulse}}$	<b>– 1</b>	170	V	$t_{\rm max}$ = 1 msec, Referred to $V_{\rm BAT}$	
ESD-voltage, all pins			1	kV	Human body model	

Note: Maximum ratings are absolute ratings; exceeding only one of these values may cause irreversible damage to the integrated circuit.



Table 7-2 Operating Range

Parameter	Symbol	Limit Va	Limit Values		<b>Test Condition</b>
		min.	max.		
Battery voltage	$V_{\scriptscriptstyle BAT}$	- 130	- 30	V	Referred to GNDB
$\overline{V_{\scriptscriptstyle  m DD}}$ supply voltage	$V_{ exttt{DD}}$	4.75	5.25	V	Referred to GNDD
Ground voltage difference	$V_{ ext{GNDB}} - V_{ ext{GNDD}}$	- 0.3	0.3	V	
Ambient temperature PEB 2026 PEF 2026	$T_{\scriptscriptstyle{A}}$ $T_{\scriptscriptstyle{A}}$	0 -40	+70 +85	°C °C	

#### Static Thermal Resistance

Junction to ambient	$R_{th, jA}$	55	K/W	P-DSO-20-10
Junction to case	$R_{th, jC}$	4	K/W	P-DSO-20-10
Junction to ambient	$R_{th, jA}$	65	K/W	P-DSO-20-6
Junction to pins	$R_{th, jPins}$	15	K/W	P-DSO-20-6

Note: In the operating range the functions given in the circuit description are fulfilled.

The power package P-DSO-20-10 has an exposed copper-heatspreader with a high thermal capacitance. For power feeding to ISDN-lines which are in a fault condition (e.g. short circuit) the maximum power dissipation on chip will become  $V_{\rm BAT}$  supply voltage times limiting current (e.g.:  $100{\rm V}_{\star}~50{\rm mA}=5{\rm W}$ ). It is necessary to try to feed the line for about 2 seconds under this condition (5W), then the feeding can be switched off but must be switched on again about 30 seconds later. In this application the thermal capacitance of the cooper-heatspreader helps to keep the maximum chip temperature below the thermal protection temperature level (165°C). No extra heatsink is necessary.

The small P-DSO-20-6 package is applicable if the device is mounted on a pcb having at least 900 mm<sup>2</sup> copper area close to the device. The pcb serves as heat sink, heat flowing off through the pins, particularly the Vbat pins. With a mounting like this, the IHPC performs as follows: a current of 50 mA is supplied for 5 sec, while the device is shorted to Vbat=100V. At an ambient temperature of 70°C the current pulse may be periodically repeated with a period of 32 sec.

all

all

all



### **Electrical Characteristics**

### **Electrical Parameters**

Typical values are defined at the following test conditions:

 $V_{\rm DD}$ =5V± 1 % $C_{\rm HP}$ =4.7 $\mu$ F± 10 %(6.3 V)

 $V_{\text{BAT}}$ =- 100V± 1 % $C_{\text{TP}}$ =220nF± 10 %(6.3 V)

 $R_{\text{\tiny LA}}$ =23 $\Omega$ ± 1 % $T_{\text{\tiny A}}$ =25± 5 °C

 $R_{LB} = 23\Omega \pm 1 \% R_{Line} = \pm 0.1 \%$ 

 $R_{\text{REF}}$ =22k $\Omega$ ± 1 %no heatsink

Min. and max. values are in force within the whole operating range.

Table 7-3 Power-Supply

No.	Parameter	Symbol	Limit Values			Unit	Test	Test	Mode	
			min.	typ.	max.		Condition	Fig.		
Sup	oly Currents ( $I_{\scriptscriptstyle  extsf{F}}$	$_{\text{RB}} = I_{\text{RA}} = 0$								
1	$V_{\scriptscriptstyle  extsf{DD}}$ current	$I_{ extsf{DD}}$		0.57	0.9	mA		7-1	all	

Table 7-4 DC-Characteristics

H-input voltage

L-input voltage

Input current

5

6

7

 $V_{\mathsf{IH}}$ 

 $V_{\scriptscriptstyle \mathsf{IL}}$ 

 $I_{\mathsf{inp}}$ 

2

2

No.	Parameter	Symbol	Limit \	Limit Values			Test	Test	Mode
			min.	typ.	max.		Condition	Fig.	
Max	imal Line Curre	ents							
3	Line current	$I_{limit,ON}$	45	50	55	mA		7-2	ON, Sta- tus:
4	Line current	$I_{\sf max,OFF}$		0	10	μΑ		7-2	OFF

11

٧

μΑ

= > V 8.0

 $V_{\mbox{\scriptsize inp}}$  < =  $V_{\mbox{\scriptsize DD}}$ 

8.0

20



Table 7-4 DC-Characteristics (cont'd)

No.	Parameter	Symbol	Limit V	alues		Unit	Test	Test	Mode
			min.	typ.	max.		Condition	Fig.	
Logi	c Output Levels	on APFI							
8	H-output voltage	$V_{OH}$	$V_{\scriptscriptstyle  extsf{DD}}-0.4$			V	$I_{\text{Source}} = 100 \mu\text{A}$		ON
9	L-output voltage	$V_{OL}$			0.4	V	I <sub>Sink</sub> = 100 μA		ON, OFF
Resi	stance from GND	B to R <sub>B</sub>							
10	R: GNDB to RB	$R_{\scriptscriptstyle{RB}}$	3	5	7	Ω	$I_{\rm RB}$ = 30 mA $\pm$ 5 %	7-3	ON, OFF
ON-r	esistance from <i>R</i>	$C_{ extsf{A}}$ to $V_{ extsf{BAT}}$							
11	ON-R: RA to $V_{\rm BAT}$ ( $T_{\rm L}$ - $R_{\rm on}$ included)	$R_{RA}$	2.65	5	7.35	Ω	$I_{RA}$ = 30 mA $\pm$ 5 %	7-3	ON, Sta- tus: LIMOFF
Diffe	erence-resistance	between	$R_{\scriptscriptstyle RA}$ and	$R_{RB}$					
12	R <sub>RA</sub> - R <sub>RB</sub> PEB 2026 PEF 2026	$R_{ exttt{DIFF}}$	- 0.35 - 0.40	0	0.35 0.40	ΩΩ			ON, Sta- tus: LIMOFF

**Table 7-5** Indication of Current Limit

No.	Parameter	Symbol	Mode	Test Condition	Status	Test Fig.
Indi	cation of Currer	nt Limit				
13	Line Status	$S_{\sf LIMON}$	ON	$R_{\rm Line} = 1762 \ \Omega$	$\begin{array}{c} {\sf LIMON}, \\ {\sf APFI} = V_{\sf OL} \end{array}$	7-4
14	Line Status	$S_{LIMOFF}$	ON	$R_{\rm Line}$ = 2166 $\Omega$	$\begin{array}{c} LIMOFF, \\ APFI = V_{OH} \end{array}$	7-4



Table 7-5 Indication of Current Limit (cont'd)

No.	Parameter	Symbol	Mode	Test Condition	Status	Test Fig.
India	eation of Curron	at Limit undo	r Supori	mnosod Longitudi	nal Current	

### Indication of Current Limit under Superimposed Longitudinal Current

15	Line Status	$S_{LLIMON}$	ON	$R_{\rm Line} = 1482 \ \Omega$	LIMON, APFI = $V_{\rm OL}$	7-5
16	Line Status	$S_{ t LLIMOFF}$	ON	$R_{\rm Line} = 2801 \ \Omega$		7-5

# Calculation and Values of $R_{\scriptscriptstyle \rm Line}$

$$R_{\rm Line} = \frac{V_{\rm BAT}}{I_{\rm Line}} - R_{\rm RA} - R_{\rm RB} - R_{\rm LA} - R_{\rm LB} = \frac{100 \, \rm V}{I_{\rm Line}} - 5 \, \Omega - 5 \, \Omega - 23 \, \Omega - 23 \, \Omega$$

where:

 $R_{\rm LA},\,R_{\rm LB}$  ... referred to page 7-3, electrical parameters

 $R_{\rm RA},\,R_{\rm RB}$  ... referred to Spec.-No.: 10 and 11

$I_{Line}$	$R_{Line}$
35 mA	2801 Ω
45 mA	2166 Ω
55 mA	1762 Ω
65 mA	1482 Ω

Note: In some of these cases the IHPC will limit the line current to lower values.



 Table 7-6
 Timing-Characteristics

No	Paramete	Symbol	Limit	Value	es	Unit	Test Condition	Tes	Mod
•	r		min	typ.	max			t Fig.	е
								Fig.	

### Delay from Begin/End of Current Limiting to Status LIMON/LIMOFF

17	Time to LIMON	t <sub>LIMON</sub>	10	20	30	msec	$R_{\text{Line}}$ : 2166 $\Omega$	7-6	ON
18	Time to LIMOFF	t <sub>LIMOFF</sub>	10	20	30	msec	$R_{\text{Line}}$ : 1762 $\Omega$ $\triangle$ $\Diamond$ 2166 $\Omega$ ==> APFI: LIMON $\triangle$ $\Diamond$ LIMOFF	7-6	ON

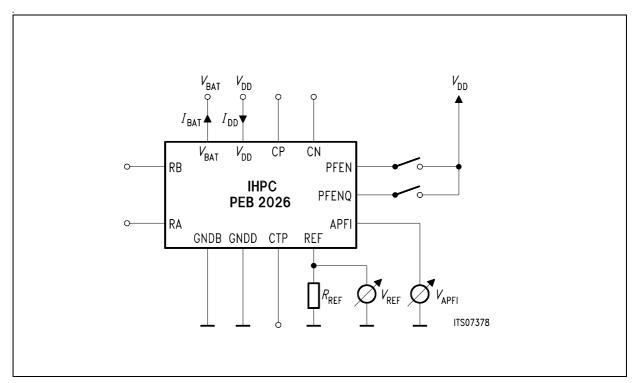


Figure 7-1 Power Dissipation and Reference Voltage Output



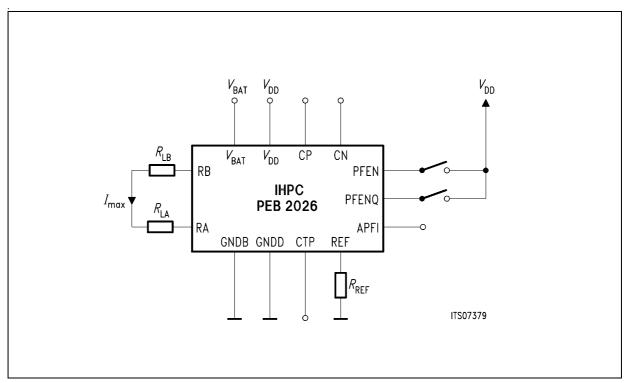


Figure 7-2 Maximal Line Currents

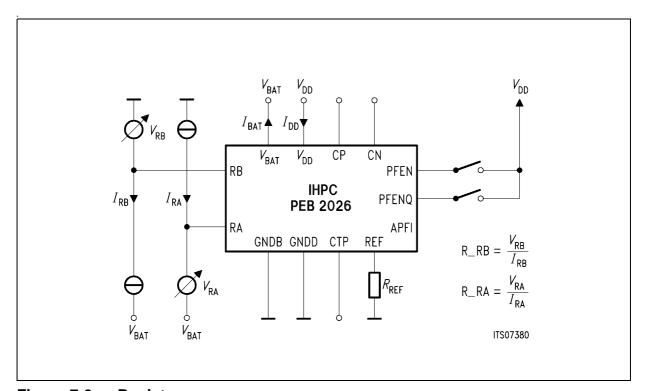


Figure 7-3 Resistances



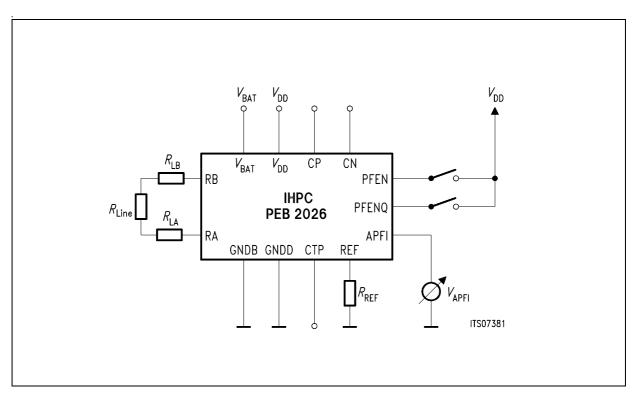


Figure 7-4 Line Status

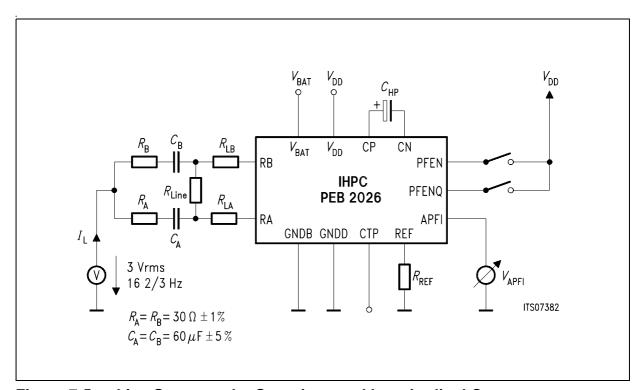


Figure 7-5 Line Status under Superimposed Longitudinal Current



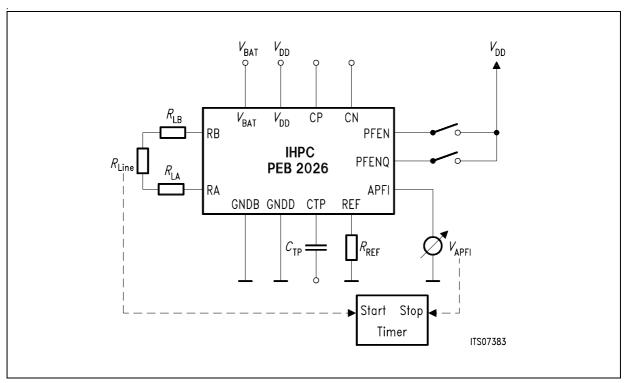


Figure 7-6 Timing-Characteristics



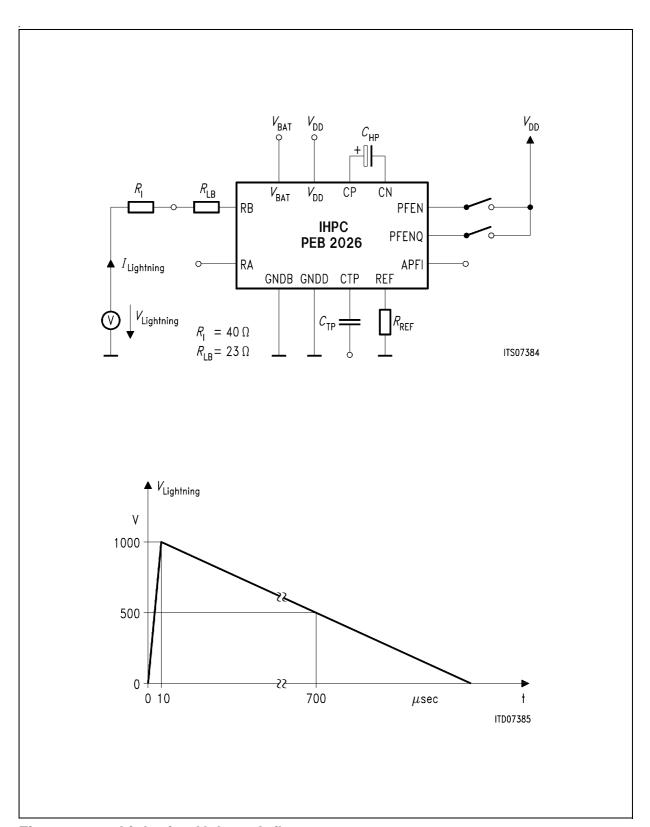
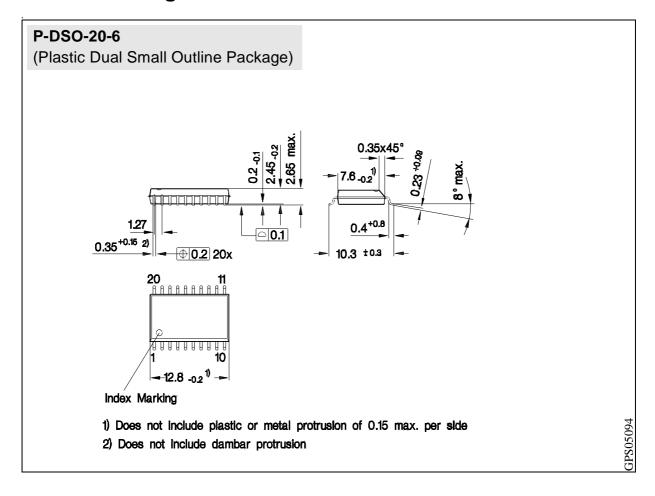


Figure 7-7 Lightning Voltage Influence



### **Package Outlines**

# 8 Package Outlines



Sorts of Packing

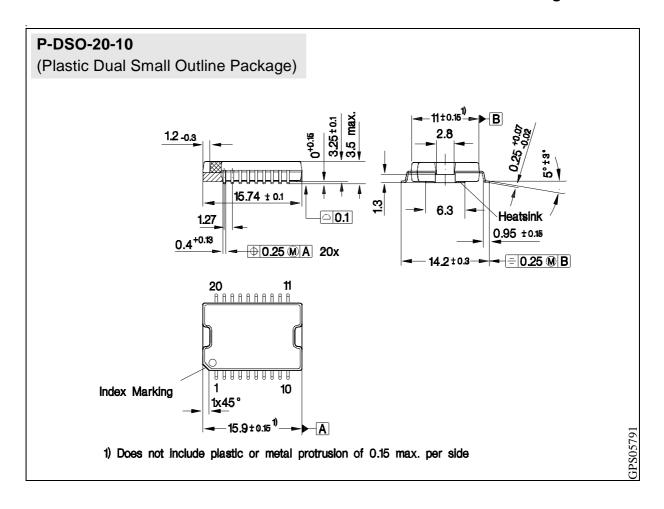
Package outlines for tubes, trays etc. are contained in our

SMD = Surface Mounted Device

Dimensions in mm



### **Package Outlines**



Sorts of Packing

Package outlines for tubes, trays etc. are contained in our

SMD = Surface Mounted Device

Dimensions in mm