# **Drivers/Receivers**EIA-232-E and CCITT V.28

These devices are silicon gate CMOS ICs that combine both the transmitter and receiver to fulfill the electrical specifications of EIA Standard 232–E and CCITT V.28. The drivers feature true TTL input compatibility, slew rate limiting outputs, 300  $\Omega$  power–off source impedance, and output typically switching to within 25% of the supply rails. The receivers can handle up to  $\pm$  25 V while presenting 3 to 7 k $\Omega$  impedance. Hysteresis in the receivers aid in the reception of noisy signals. By combining both drivers and receivers in a single CMOS chip, these devices provide efficient, low–power solutions for both EIA–232–E and V.28 applications.

These devices offer the following performance features:

### **Drivers**

- $\pm$  5 to  $\pm$  12 V Supply Range
- 300  $\Omega$  Power–Off Source Impedance
- Output Current Limiting
- TTL and CMOS Compatible Inputs
- Driver Slew Rate Range Limited to 30 V/μs Maximum

### Receivers

- ± 25 V Input Range
- 3 to 7 kΩ Input Impedance
- 0.8 V of Hysteresis for Enhanced Noise Immunity
- TTL and CMOS Compatible Outputs

### **Available Driver/Receiver Combinations**

Device	Drivers	Receivers	Figure	No. of Pins
MC145403	3	5	1	20
MC145404	4	4	2	20
MC145405	5	3	3	20
MC145408	5	5	4	24

Alternative EIA-232 devices to consider are:

**Three Supply**MC145406 (3 x 3)
Single Supply
MC145407 (3 x 3)

MC145705 (2 x 3) with Power Down MC145706 (3 x 2) with Power Down MC145707 (3 x 3) with Power Down MC145403 MC145404 MC145405 MC145408



P SUFFIX PLASTIC DIP CASE 738



P SUFFIX
PLASTIC DIP
CASE 724



DW SUFFIX SOG PACKAGE CASE 751D



DW SUFFIX SOG PACKAGE CASE 751E



SD SUFFIX SSOP CASE 940C

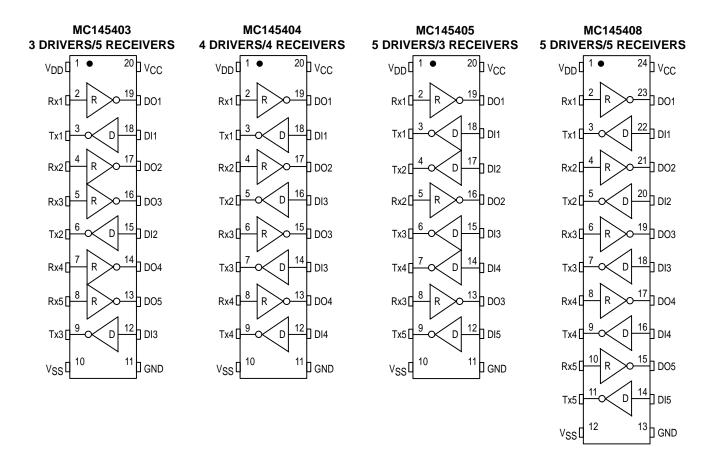
### **ORDERING INFORMATION**

Plastic DIP MC145403P MC145404P Plastic DIP MC145405P Plastic DIP MC145408P Plastic DIP SOG Package MC145403DW MC145404DW SOG Package MC145405DW SOG Package MC145408DW SOG Package SSOP MC145405SD

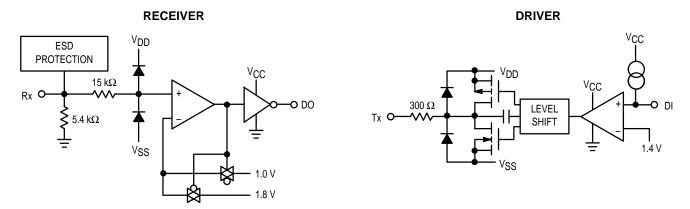




## PIN ASSIGNMENTS (DIP, SOG, AND SSOP)



### **FUNCTIONAL DIAGRAM**



### **ABSOLUTE MAXIMUM RATINGS**

(Voltages referenced to GND, except where noted)

Rating	Symbol	Value	Unit
DC Supply Voltage ( $V_{DD} \ge V_{CC}$ )	V <sub>DD</sub> Vss VCC	- 0.5 to + 13.5 + 0.5 to - 13.5 - 0.5 to + 6.0	V
Input Voltage Range Rx1 – Rxn DI1 – DIn	VIR	V <sub>SS</sub> – 15 to V <sub>DD</sub> + 15 0.5 to V <sub>CC</sub> + 15	V
DC Current Drain per Pin	I	± 00	mA
Power Dissipation	PD	1	W
Operating Temperature Range	TA	- 40 to + 85	°C
Storage Temperature Range	T <sub>stg</sub>	- 85 to + 150	°C

This device contains circuitry to protect the inputs and outputs against damage due to high static voltages or electric fields; however, it is advised that normal precautions be taken to avoid applications of any voltage higher than maximum rated voltages to this high impedance circuit.

For proper operation it is recommended that  $V_{out}$  and  $V_{in}$  be constrained to the ranges described as follows:

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Digital I/O: Driver Inputs (DI):  (\mathsf{GND} \leq \mathsf{V_{DI}} \leq \mathsf{V_{CC}}).  Receiver Outputs (DO):  (\mathsf{GND} \leq \mathsf{V_{DO}} \leq \mathsf{V_{CC}}).  EIA-232 I/O: Driver Outputs (Tx):  (\mathsf{VSS} \leq \mathsf{VT_{X1}} - \mathsf{T_{Xn}} \leq \mathsf{V_{DD}}).  Receiver Inputs (Rx):  \mathsf{VSS} - 15 \; \mathsf{V} \leq \mathsf{V_{RX1}} - \mathsf{R_{Xn}} \leq \mathsf{V_{DD}} + 15 \; \mathsf{V}).
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Reliability of operation is enhanced if unused outputs are tied off to an appropriate logic voltage level (e.g., either GND or V<sub>CC</sub> for DI, and GND for Rx).

### DC ELECTRICAL CHARACTERISTICS (All polarities referenced to GND = 0 V, TA = -40 to + 85°C)

Parameter		Symbol	Min	Тур	Max	Unit
DC Supply Voltage		V <sub>DD</sub> V <sub>SS</sub> V <sub>CC</sub>	4.5 - 4.5 4.5	5 to 12 - 5 to - 12 5	13.2 - 13.2 5.5	V
Quiescent Supply Current (Outputs Unloaded, Inputs Low)	V <sub>DD</sub> = + 12 V V <sub>SS</sub> = - 12 V V <sub>CC</sub> = + 5 V	I <sub>DD</sub> Iss Icc		425 - 400 110	635 - 600 200	μΑ

### **RECEIVER ELECTRICAL SPECIFICATIONS**

(Voltage polarities referenced to GND = 0 V,  $V_{DD}$  = + 12 V,  $V_{SS}$  = - 12 V,  $T_{A}$  = - 40 to + 85°C,  $V_{CC}$  = + 5 V,  $\pm$  10%)

Characteristic		Symbol	Min	Тур	Max	Unit
Input Turn–On Threshold VDO = VOL	Rx1 – Rx <i>n</i>	V <sub>on</sub>	1.35	1.8	2.35	V
Input Turn–Off Threshold VDO = VOH	Rx1 – Rxn	V <sub>off</sub>	0.75	1	1.25	V
Input Threshold Hysteresis $\Delta = V_{ON} - V_{Off}$		V <sub>hys</sub>	0.6	0.8	_	V
Input Resistance $(V_{SS} - 15 \text{ V}) \le V \text{ Rx1} - \text{Rx} n \le (V_{DD} + 15 \text{ V})$		R <sub>in</sub>	3	5.4	7	kΩ
High Level Output Voltage VRx = - 3 to - 25 V* (DO1 - DOn)	I <sub>out</sub> = - 20 μA I <sub>out</sub> = - 1.0 mA	VOH	4.9 3.8	4.9 4.3	_	V
Low Level Output Voltage V <sub>Rx</sub> = + 3 to + 25 V* (DO1 – DO <i>n</i> )	I <sub>out</sub> = + 2 mA I <sub>out</sub> = + 4 mA	VOL	_ _	0.02 0.5	0.5 0.7	V

<sup>\*</sup>This is the range of input voltages as specified by EIA-232-E to cause a receiver to be in the high or low.

### **DRIVER ELECTRICAL SPECIFICATIONS**

(Voltage Polarities Referenced to GND = 0 V,  $V_{DD}$  = + 12 V,  $V_{SS}$  = - 12 V,  $T_A$  = - 40 to + 85°C,  $V_{CC}$  = + 5 V,  $\pm$  10%)

Characteristic	Symbol	Min	Тур	Max	Unit
Digital Input Voltage  Logic 0  Logic 1	V <sub>IL</sub> VIH	_ 2	_ _ _	0.8 —	V
Input Current DI1 – DIn $V_{DI} = GND$ $V_{DI} = V_{CC}$	IIL IIH	_ _	7 —	 ± 1.0	μА
Output High Voltage $ \begin{array}{c} \text{Tx1} - \text{Tx} n \\ \text{V}_{DI} = \text{Logic 0, R}_L = 3 \text{ k}\Omega \\ \text{V}_{DD} = +5.0 \text{ V, V}_{SS} = -5.0 \text{ V} \\ \text{V}_{DD} = +6.0 \text{ V, V}_{SS} = -6.0 \text{ V} \\ \text{V}_{DD} = +12.0 \text{ V, V}_{SS} = -12.0 \text{ V} \\ \end{array} $	Vон	3.5 4.3 9.2	3.9 4.7 9.5	_ _ _	V
Output Low Voltage* $V_{DI} = \text{Logic 1, } R_L = 3 \text{ k}\Omega$ $V_{DD} = +5.0 \text{ V, } V_{SS} = -5.0 \text{ V}$ $V_{DD} = +6.0 \text{ V, } V_{SS} = -6.0 \text{ V}$ $V_{DD} = +12.0 \text{ V, } V_{SS} = -12.0 \text{ V}$	VOL	- 4 - 4.5 - 10	- 4.3 - 5.2 - 10.3	_ _ _ _	V
Input Current Tx1 – Tx <i>n</i> (Figure 5)	Z <sub>off</sub>	300	_	_	Ω
Output Short Circuit Current $V_{DD} = + 12 \text{ V}, \text{ V}_{SS} = - 12 \text{ V}$ $\text{Tx Shorted to GND**}$ $\text{Tx Shorted to } \pm 15 \text{ V****}$	ISC		± 22 ± 60	± 60 ± 100	mA

<sup>\*</sup> Voltage specifications are in terms of absolute values.

### **SWITCHING CHARACTERISTICS** ( $V_{CC}$ = + 5 V, $\pm$ 10%, $V_{DD}$ = + 12 V, $V_{SS}$ = - 12 V, $T_{A}$ = - 40 to + 85°C; See Figures 2 and 3)

Characteristic	Symbol	Min	Тур	Max	Unit
Drivers					
Propagation Delay Time Tx Low-to-High	<sup>t</sup> PLH				ns
$R_L = 3 \text{ k}\Omega$ , $C_L = 50 \text{ pF}$		_	500	1000	
High–to–Low R <sub>L</sub> = 3 kΩ, C <sub>L</sub> = 50 pF	<sup>t</sup> PHL	_	700	1000	
Output Slew Rate Minimum Load	SR				V/μs
$R_L = 7 \text{ k}\Omega$ , $C_L = 0 \text{ pF} (V_{DD} = 6 \text{ to } 12 \text{ V}, V_{SS} = -6 \text{ to } -12 \text{ V})$		_	± 6	± 30	
Maximum Load $R_L = 3 \text{ k}\Omega, C_L = 2500 \text{ pF } (V_{DD} = 12 \text{ V}, V_{SS} = -12 \text{ V}, V_{CC} = 5 \text{ V})$		4	_	_	
Receivers (C <sub>L</sub> = 50 pF)					
Propagation Delay Time Low-to-High	tPLH	_	360	610	ns
High-to-Low	t <sub>PHL</sub>	_	130	610	
Output Rise Time	t <sub>r</sub>		250	400	ns
Output Fall Time	t <sub>f</sub>	_	40	100	ns

<sup>\*\*</sup> Specification is for one Tx output pin to be shorted at a time. Should all three driver outputs be shorted simultaneously, device power dissipation limits will be exceeded.

<sup>\*\*\*</sup> This condition could exceed package limitations.

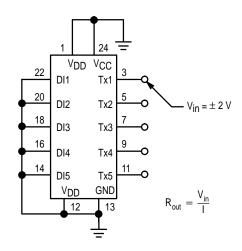
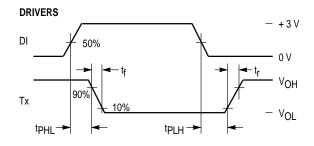


Figure 1. Power–Off Source Resistance Illustrated for MC145408



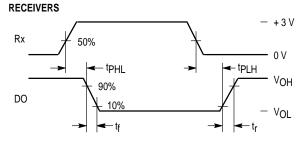


Figure 2. Switching Characteristics

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Figure 3. Slew Rate Characteristics

### PIN DESCRIPTIONS

### V<sub>C</sub>C Digital Power Supply

The digital supply pin, which is connected to the logic power supply (+ 5.5 V maximum).

### GND Ground

Ground return pin is typically connected to the signal ground pin of the EIA-232-E connector (Pin 7) as well as to the logic power supply ground.

### V<sub>DD</sub> Most Positive Device Pin

The most positive power supply pin, which is typically + 5 to + 12 V.

### VSS Most Negative Device Pin

The most negative power supply pin, which is typically -5 to -12 V.

### Rx1 – Rx*n* Receive Data Input Pins

These are the EIA-232–E receive signal inputs. A voltage between + 3 and + 25 V is decoded as a space, and causes the corresponding DO pin to swing to ground (0 V). A voltage between - 3 and - 25 V is decoded as a mark, and causes the corresponding DO pin to swing to VCC.

## DO1 – DO*n*Data Output Pins

These are the receiver digital output pins which swing from V<sub>CC</sub> to GND. Each output pin is capable of driving one LSTTL input load.

## DI1 – DI*n*Data Input Pins

These are the high impedance digital input pins to the drivers. Input voltage levels on these pins are LSTTL compatible and must be between VCC and GND. A weak pull–up on each input sets all unused DI pins to VCC, causing the corresponding unused driver outputs to be at VSS.

### Tx1 – TX*n* Transmit Data Output Pins

These are the EIA–232–E transmit signal output pins, which swing from V<sub>DD</sub> to V<sub>SS</sub>. A logic 1 at the DI input causes the corresponding Tx output to swing to V<sub>SS</sub>. A logic 0 at the DI input causes the corresponding Tx out to swing to V<sub>DD</sub>. The actual levels and slew rate achieved will depend on the output loading (R<sub>I</sub>  $\parallel$  C<sub>I</sub>).

### **APPLICATION INFORMATION**

### **POWER SUPPLY CONSIDERATIONS**

Figure 4 shows a technique to guard against excessive device current.

The diode D1 prevents excessive current from flowing through an internal diode from the  $V_{CC}$  pin to the  $V_{DD}$  pin when  $V_{DD} < V_{CC}$  by approximately 0.6 V or greater. This high current condition can exist for a short period of time during power up/down. Additionally, if the + 12 V supply is switched

off while the + 5 V is on and the off supply is a low impedance to ground, the diode D1 will prevent current flow through the internal diode.

The diode D2 is used as a voltage clamp, to prevent VSS from drifting positive to VCC, in the event that power is removed from VSS (Pin 12). If VSS power is removed, and the impedance from the VSS pin to ground is greater than approximately 3 k $\Omega$ , this pin will be pulled to VCC by internal circuitry causing excessive current in the VCC pin.

If by design, neither of the above conditions are allowed to exist, then the diodes D1 and D2 are not required.

### **ESD PROTECTION**

ESD protection on IC devices that have their pins accessible to the outside world is essential. High static voltages applied to the pins when someone touches them either directly or indirectly can cause damage to gate oxides and transistor junctions by coupling a portion of the energy from the I/O pin to the power supply buses of the IC. This coupling will usually occur through the internal ESD protection diodes. The key to protecting the IC is to shunt as much of the energy to ground as possible before it enters the IC. Figure 4 shows a technique which will clamp the ESD voltage at approximately  $\pm$  15 V using the MMBZ15VDLT1. Any residual voltage which appears on the supply pins is shunted to ground through the capacitors C1 - C3. This scheme has provided protection to the interface part up to  $\pm$  10 kV, using the human body model test.

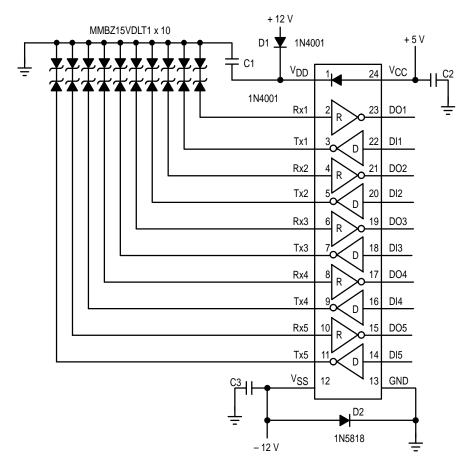
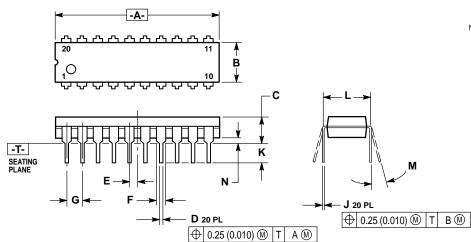


Figure 4.

### **PACKAGE DIMENSIONS**

### P SUFFIX **PLASTIC DIP CASE 738-03**



- NOTES:

  1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.

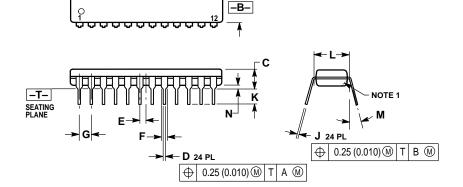
  2. CONTROLLING DIMENSION: INCH.

  3. DIMENSION L TO CENTER OF LEAD WHEN FORMED PARALLEL.

  4. DIMENSION B DOES NOT INCLUDE MOLD

	INC	HES	MILLIN	IETERS	
DIM	MIN	MAX	MIN	MAX	
Α	1.010	1.070	25.66	27.17	
В	0.240	0.260	6.10	6.60	
С	0.150	0.180	3.81	4.57	
D	0.015	0.022	0.39	0.55	
E	0.050	BSC	1.27 BSC		
F	0.050	0.070	1.27	1.77	
G	0.100	BSC	2.54 BSC		
J	0.008	0.015	0.21	0.38	
K	0.110	0.140	2.80	3.55	
L	0.300	BSC	7.62	BSC	
M	0°	15°	0°	15°	
N	0.020	0.040	0.51	1.01	

### P SUFFIX **PLASTIC DIP** CASE 724-03

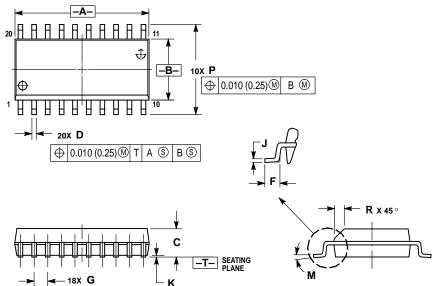


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- NOTES:
  1. CHAMFERED CONTOUR OPTIONAL.
  2. DIMENSION L TO CENTER OF LEADS WHEN FORMED PARALLEL.
  3. DIMENSIONING AND TOLERANCING PER ANSI
- Y14.5M, 1982.
  4. CONTROLLING DIMENSION: INCH.

	INC	HES	MILLIN	IETERS	
DIM	MIN	MAX	MIN	MAX	
Α	1.230	1.265	31.25	32.13	
В	0.250	0.270	6.35	6.85	
С	0.145	0.175	3.69	4.44	
D	0.015	0.020	0.38	0.51	
E	0.050	BSC	1.27	BSC	
F	0.040	0.060	1.02	1.52	
G	0.100	BSC	2.54	BSC	
J	0.007	0.012	0.18	0.30	
K	0.110	0.140	2.80	3.55	
L	0.300	BSC	7.62	BSC	
М	0°	15°	0°	15°	
N	0.020	0.040	0.51	1.01	

### **DW SUFFIX SOG PACKAGE** CASE 751D-04

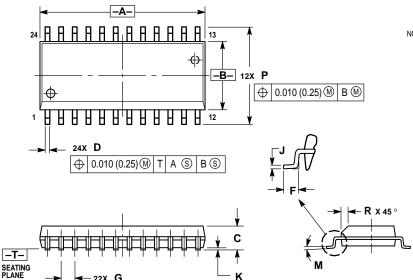


### NOTES:

- DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
- 2. CONTROLLING DIMENSION: MILLIMETER.
  3. DIMENSIONS A AND B DO NOT INCLUDE MOLD PROTRUSION.
- MAXIMUM MOLD PROTRUSION 0.150 (0.006) PER SIDE.
- (0.006) PER SIDE.
  5. DIMENSION D DOES NOT INCLUDE
  DAMBAR PROTRUSION. ALLOWABLE
  DAMBAR PROTRUSION SHALL BE 0.13
  (0.005) TOTAL IN EXCESS OF D DIMENSION
  AT MAXIMUM MATERIAL CONDITION.

	MILLIN	IETERS	INC	HES
DIM	MIN	MAX	MIN	MAX
Α	12.65	12.95	0.499	0.510
В	7.40	7.60	0.292	0.299
С	2.35	2.65	0.093	0.104
D	0.35	0.49	0.014	0.019
F	0.50	0.90	0.020	0.035
G	1.27	BSC	0.050 BSC	
۲	0.25	0.32	0.010	0.012
K	0.10	0.25	0.004	0.009
M	0 °	7°	0 °	7°
Р	10.05	10.55	0.395	0.415
R	0.25	0.75	0.010	0.029





### NOTES:

- (DIES:

  1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.

  2. CONTROLLING DIMENSION: MILLIMETER.

  3. DIMENSIONS A AND B DO NOT INCLUDE MAD DEPOTELISION.

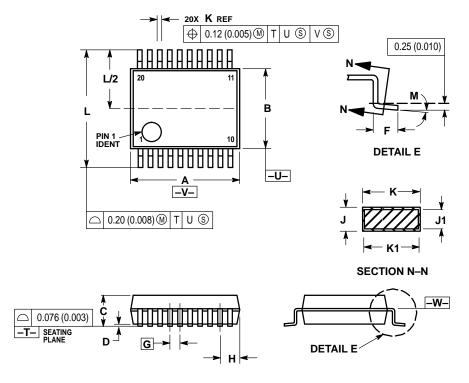
- MOLD PROTRUSION.

  4. MAXIMUM MOLD PROTRUSION 0.15 (0.006) PER SIDE.
- PER SIDE.

  5. DIMENSION D DOES NOT INCLUDE DAMBAR
  PROTRUSION. ALLOWABLE DAMBAR
  PROTRUSION SHALL BE 0.13 (0.005) TOTAL IN
  EXCESS OF D DIMENSION AT MAXIMUM MATERIAL CONDITION.

	MILLIN	IETERS	INC	HES
DIM	MIN	MAX	MIN	MAX
Α	15.25	15.54	0.601	0.612
В	7.40	7.60	0.292	0.299
С	2.35	2.65	0.093	0.104
D	0.35	0.49	0.014	0.019
F	0.41	0.90	0.016	0.035
G	1.27	BSC	0.050	BSC
J	0.23	0.32	0.009	0.013
K	0.13	0.29	0.005	0.011
M	0°	8°	0°	8°
Р	10.05	10.55	0.395	0.415
R	0.25	0.75	0.010	0.029

### **SD SUFFIX SSOP** CASE 940C-03



- 1. DIMENSIONING AND TOLERANCING PER ANSI
- CONTROLLING DIMENSION: MILLIMETER.
- DIMENSION A DOES NOT INCLUDE MOLD FLASH, PROTRUSIONS OR GATE BURRS. MOLD FLASH OR GATE BURRS SHALL NOT EXCEED 0.15 (0.006) PER SIDE
- DIMENSION B DOES NOT INCLUDE INTERLEAD FLASH OR PROTRUSION. INTERLEAD FLASH OR PROTRUSION SHALL NOT EXCEED 0.15 (0.006) PER SIDE.
  DIMENSION K DOES NOT INCLUDE DAMBAR
- PROTRUSION/INTRUSION. ALLOWABLE DAMBAR PROTRUSION SHALL BE 0.13 (0.005) TOTAL IN EXCESS OF K DIMENSION AT MAXIMUM MATERIAL CONDITION DAMBAR INTRUSION SHALL NOT REDUCE DIMENSION K BY MORE THAN 0.07 (0.002) AT LEAST MATERIAL CONDITION.
- TERMINAL NUMBERS ARE SHOWN FOR REFERENCE ONLY.
- DIMENSION A AND B ARE TO BE DETERMINED AT DATUM PLANE –W–.

	MILLIMETERS		INC	HES
DIM	MIN	MAX	MIN	MAX
Α	7.07	7.33	0.278	0.288
В	5.20	5.38	0.205	0.212
С	1.73	1.99	0.068	0.078
D	0.05	0.21	0.002	0.008
F	0.63	0.95	0.024	0.037
G	0.65	BSC	0.026 BSC	
Н	0.59	0.75	0.023	0.030
J	0.09	0.20	0.003	0.008
J1	0.09	0.16	0.003	0.006
K	0.25	0.38	0.010	0.015
K1	0.25	0.33	0.010	0.013
٦	7.65	7.90	0.301	0.311
М	0 °	8 °	0 °	8 °

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