

INTEGRATED CIRCUITS

DATA SHEET



TDA9887TS

I²C-bus controlled multistandard alignment-free IF-PLL demodulator with FM radio

Product specification

2002 Mar 05

I²C-bus controlled multistandard alignment-free IF-PLL demodulator with FM radio

TDA9887TS

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1 FEATURES

- 5 V supply voltage
- Gain controlled wide-band Vision Intermediate Frequency (VIF) amplifier, AC-coupled
- Multistandard true synchronous demodulation with active carrier regeneration: very linear demodulation, good intermodulation figures, reduced harmonics, and excellent pulse response
- Gated phase detector for L and L-accent standard
- Fully integrated VIF Voltage Controlled Oscillator (VCO), alignment-free, frequencies switchable for all negative and positive modulated standards via I²C-bus
- Digital acquisition help, VIF frequencies of 33.4, 33.9, 38.0, 38.9, 45.75, and 58.75 MHz
- 4 MHz reference frequency input: signal from Phase-Locked Loop (PLL) tuning system or operating as crystal oscillator
- VIF Automatic Gain Control (AGC) detector for gain control, operating as peak sync detector for negative modulated signals and as a peak white detector for positive modulated signals on pin OTP2
- External AGC setting via pin OP1
- Precise fully digital Automatic Frequency Control (AFC) detector with 4-bit digital-to-analog converter, AFC bits readable via I²C-bus
- TakeOver Point (TOP) adjustable via I²C-bus or alternatively with potentiometer
- Fully integrated sound carrier trap for 4.5, 5.5, 6.0, and 6.5 MHz, controlled by FM-PLL oscillator
- Sound IF (SIF) input for single reference Quasi Split Sound (QSS) mode, PLL controlled
- SIF-AGC for gain controlled SIF amplifier, single reference QSS mixer able to operate in high performance single reference QSS mode and in intercarrier mode, switchable via I²C-bus
- AM demodulator without extra reference circuit
- Alignment-free selective FM-PLL demodulator with high linearity and low noise
- I²C-bus control for all functions
- I²C-bus transceiver with pin programmable Module Address (MAD)
- Four I²C-bus addresses via MAD
- SIF and FM-AGC for radio (optional)
- Radio IF (RIF) input using the sound IF SAW input for converting to 10.7 MHz, input frequencies are 41.3 MHz for NTSC (M/N standard) applications and 33.3 MHz for other applications
- Alignment-free FM radio demodulation at 10.7 MHz
- Radio AFC
- External FM input and demodulation.



2 GENERAL DESCRIPTION

The TDA9887TS is an alignment-free multistandard (PAL, SECAM and NTSC) vision and sound IF signal PLL demodulator for positive and negative modulation, including sound AM and FM processing. A special function is implemented for the demodulation of FM radio signals ($f_{RIF} = 10.7$ MHz).

3 APPLICATIONS

- TV, VTR, PC, and STB applications.

4 ORDERING INFORMATION

| TYPE NUMBER | PACKAGE | | |
|--------------|---------|---|----------|
| | NAME | DESCRIPTION | VERSION |
| TDA9887TS/V3 | SSOP24 | plastic shrink small outline package; 24 leads; body width 5.3 mm | SOT340-1 |

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5 QUICK REFERENCE DATA

| SYMBOL | PARAMETER | CONDITIONS | MIN. | TYP. | MAX. | UNIT |
|--------------------------------|--|--|------|-------|------|--------|
| V _P | supply voltage | notes 1 and 2 | 4.5 | 5.0 | 5.5 | V |
| I _P | supply current | | 52 | 63 | 70 | mA |
| Video part | | | | | | |
| V _{i(VIF)(rms)} | VIF input voltage sensitivity (RMS value) | -1 dB video at output | - | 60 | 100 | μV |
| G _{VIF(cr)} | VIF gain control range | | 60 | 66 | - | dB |
| f _{VIF} | vision carrier operating frequencies | see Table 17 | - | 33.4 | - | MHz |
| | | | - | 33.9 | - | MHz |
| | | | - | 38.0 | - | MHz |
| | | | - | 38.9 | - | MHz |
| | | | - | 45.75 | - | MHz |
| | | | - | 58.75 | - | MHz |
| Δf _{VIF} | VIF frequency window of digital acquisition help | related to f _{VIF} ; see Fig.9 | - | ±2.3 | - | MHz |
| V _{o(video)(p-p)} | video signal output voltage (peak-to-peak value) | see Fig.3 | | | | |
| | | normal mode | 1.7 | 2.0 | 2.3 | V |
| | | trap bypass mode | 0.95 | 1.10 | 1.25 | V |
| G _{dif} | differential gain | "CCIR 330"; note 3 | | | | |
| | | B/G standard | - | - | 5 | % |
| | | L standard | - | - | 7 | % |
| φ _{dif} | differential phase | "CCIR 330" | - | 2 | 4 | deg |
| B _{video(-1dB)} | -1 dB video bandwidth | trap bypass mode; AC load; C _L < 20 pF; R _L > 1 kΩ | 5 | 6 | - | MHz |
| B _{video(-3dB)(trap)} | -3 dB video bandwidth including sound carrier trap | note 4 | | | | |
| | | f _{trap} = 4.5 MHz | 3.95 | 4.05 | - | MHz |
| | | f _{trap} = 5.5 MHz | 4.90 | 5.00 | - | MHz |
| | | f _{trap} = 6.0 MHz | 5.40 | 5.50 | - | MHz |
| | | f _{trap} = 6.5 MHz | 5.50 | 5.95 | - | MHz |
| α _{SC1} | trap attenuation at first sound carrier | M/N standard | 30 | 36 | - | dB |
| | | B/G standard | 30 | 36 | - | dB |
| S/N _{W(video)} | weighted signal-to-noise ratio of video signal | see Fig.11; note 5 | 56 | 59 | - | dB |
| PSRR _{CVBS} | power supply ripple rejection at pin CVBS | f _{ripple} = 70 Hz; video signal; grey level; positive and negative modulation; see Fig.4 | 20 | 25 | - | dB |
| AFC _{stps} | AFC control steepness | definition: ΔI _{AFC} /Δf _{VIF} | 0.85 | 1.05 | 1.25 | μA/kHz |

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| SYMBOL | PARAMETER | CONDITIONS | MIN. | TYP. | MAX. | UNIT |
|----------------------------|---|--|------|------|------|-------------|
| Audio part | | | | | | |
| $V_{o(AF)(rms)}$ | AF output voltage (RMS value) | 27 kHz FM deviation; 50 μ s de-emphasis | 430 | 540 | 650 | mV |
| THD | total harmonic distortion of audio signal | FM: 27 kHz FM deviation; 50 μ s de-emphasis | – | 0.15 | 0.50 | % |
| | | AM: m = 54% | – | 0.5 | 1.0 | % |
| $B_{AF(-3dB)}$ | –3 dB AF bandwidth | without de-emphasis; dependent on FM-PLL filter | 80 | 100 | – | kHz |
| $S/N_{W(AF)}$ | weighted signal-to-noise ratio of audio signal | FM: 27 kHz FM deviation; 50 μ s de-emphasis; vision carrier unmodulated | 52 | 56 | – | dB |
| | | AM: m = 54% | 45 | 50 | – | dB |
| $\alpha_{AM(sup)}$ | AM suppression of FM demodulator | 50 μ s de-emphasis; AM: f = 1 kHz and m = 54%; referenced to 27 kHz FM deviation | 40 | 46 | – | dB |
| PSRR _{AUD} | power supply ripple rejection on pin AUD | f _{ripple} = 70 Hz; see Fig.4 for AM | 20 | 26 | – | dB |
| | | for FM | 14 | 20 | – | dB |
| $V_{o(intc)(rms)}$ | IF intercarrier output level (RMS value) | QSS mode; SC ₁ ; SC ₂ off | 90 | 140 | 180 | mV |
| | | L standard; without modulation | 90 | 140 | 180 | mV |
| | | intercarrier mode; SC ₁ ; SC ₂ off; note 6 | – | – | – | mV |
| Radio part | | | | | | |
| AFC _{stps} | AFC control steepness | definition: $\Delta I_{AFC}/\Delta f_{RIF}$ | 0.85 | 1.05 | 1.25 | μ A/kHz |
| $V_{i(FM)(rms)}$ | IF intercarrier input level on pin FMIN for gain controlled operation of FM-PLL (RMS value) | radio mode and FM external mode; see Table 16 | 1 | – | 100 | mV |
| Reference frequency | | | | | | |
| f _{ref} | reference signal frequency | note 7 | – | 4 | – | MHz |
| $V_{ref(rms)}$ | reference signal voltage (RMS value) | operation as input terminal | 80 | – | 400 | mV |

Notes

- Values of video and sound parameters can be decreased at $V_P = 4.5$ V.
- For applications without I²C-bus, the time constant (R × C) at the supply must be >1.2 μ s (e.g. 1 Ω and 2.2 μ F).
- Condition: luminance range (5 steps) from 0% to 100%.
- AC load: C_L < 20 pF and R_L > 1 k Ω . The sound carrier frequencies (depending on the TV standard) are attenuated by the integrated sound carrier traps (see Figs 13 to 18; |H(s)| is the absolute value of transfer function).
- $S/N_{W(video)}$ is the ratio of the black-to-white amplitude to the black level noise voltage (RMS value measured on pin CVBS). B = 5 MHz weighted in accordance with "CCIR 567".

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6. The intercarrier output signal at pin SIOMAD can be calculated by the following formula taking into account the internal video signal with 1.1 V (p-p) as a reference:

$$V_{o(intc)} = 1.1 \text{ V (p-p)} \times \frac{1}{2\sqrt{2}} \times 10^{\frac{\frac{V_{i(SC)}(dB) + 6 \text{ dB} \pm 3 \text{ dB}}{V_{i(PC)}}}{20}} \quad (\text{RMS})$$

where:

$\frac{1}{2\sqrt{2}}$ is the correction term for RMS value, $\frac{V_{i(SC)}}{V_{i(PC)}}(dB)$ is the sound-to-picture carrier ratio at pins VIF1 and VIF2 in dB, 6 dB is the correction term of internal circuitry and $\pm 3 \text{ dB}$ is the tolerance of video output and intercarrier output $V_{o(intc)(rms)}$.

7. Pin REF is able to operate as a 1-pin crystal oscillator input as well as an external reference signal input, e.g. from the tuning system.

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6 BLOCK DIAGRAM

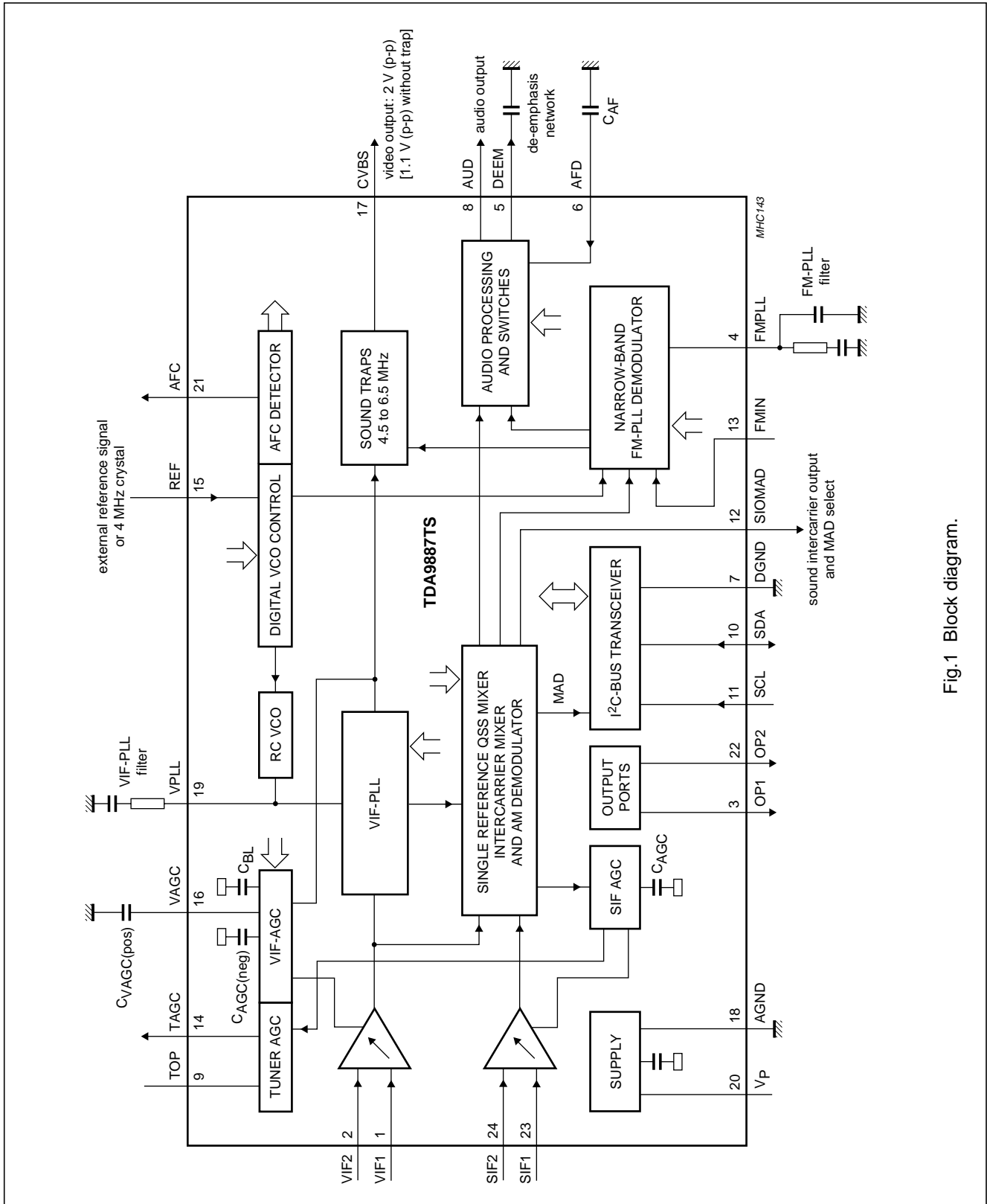


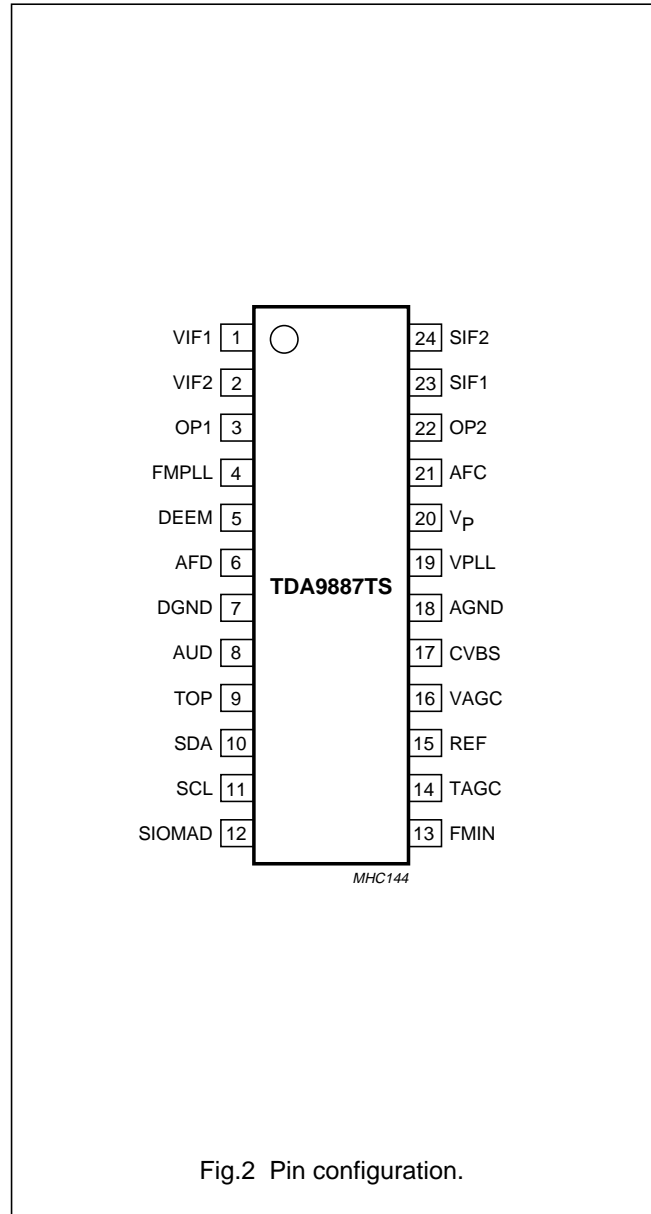
Fig.1 Block diagram.

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7 PINNING

| SYMBOL | PIN | DESCRIPTION |
|----------------|-----|--|
| VIF1 | 1 | VIF differential input 1 |
| VIF2 | 2 | VIF differential input 2 |
| OP1 | 3 | output port 1; open-collector |
| FMPLL | 4 | FM-PLL for loop filter |
| DEEM | 5 | de-emphasis output for capacitor |
| AFD | 6 | AF decoupling input for capacitor |
| DGND | 7 | digital ground |
| AUD | 8 | audio output |
| TOP | 9 | tuner AGC TakeOver Point (TOP) for resistor adjustment |
| SDA | 10 | I ² C-bus data input and output |
| SCL | 11 | I ² C-bus clock input |
| SIOMAD | 12 | sound intercarrier output and MAD select with resistor |
| FMIN | 13 | radio IF and external second SIF input |
| TAGC | 14 | tuner AGC output |
| REF | 15 | 4 MHz crystal or reference signal input |
| VAGC | 16 | VIF-AGC for capacitor |
| CVBS | 17 | composite video output |
| AGND | 18 | analog ground |
| VPLL | 19 | VIF-PLL for loop filter |
| V _P | 20 | supply voltage |
| AFC | 21 | AFC output |
| OP2 | 22 | output port 2; open-collector |
| SIF1 | 23 | SIF differential input 1 and MAD select with resistor |
| SIF2 | 24 | SIF differential input 2 and MAD select with resistor |



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8 FUNCTIONAL DESCRIPTION

Figure 1 shows the simplified block diagram of the device which comprises the following functional blocks:

1. VIF amplifier
2. Tuner AGC and VIF-AGC
3. VIF-AGC detector
4. Frequency Phase-Locked Loop (FPLL) detector
5. VCO and divider
6. AFC and digital acquisition help
7. Video demodulator and amplifier
8. Sound carrier trap
9. SIF amplifier
10. SIF-AGC detector
11. Single reference QSS mixer
12. AM demodulator
13. FM demodulator and acquisition help
14. Audio amplifier and mute time constant
15. Radio mode
16. Internal voltage stabilizer
17. I²C-bus transceiver and MAD (module address).

8.1 VIF amplifier

The VIF amplifier consists of three AC-coupled differential stages. Gain control is performed by emitter degeneration. The total gain control range is typical 66 dB. The differential input impedance is typical 2 k Ω in parallel with 3 pF.

8.2 Tuner AGC and VIF-AGC

This block adapts the voltages, generated at the VIF-AGC and SIF-AGC detectors, to the internal signal processing at the VIF and SIF amplifiers and performs the tuner AGC control current generation. The onset of the tuner AGC control current generation can be set either via the I²C-bus (see Table 13) or optional by a potentiometer at pin TOP (in case that the I²C-bus information cannot be stored, related to the device). The presence of a potentiometer will automatically be detected and disables the I²C-bus setting.

Furthermore, derived from the AGC detector voltage, a comparator is used to test the corresponding VIF input voltage to be higher than 200 μ V. This information can be read out via the I²C-bus (bit VIFLEV = 1).

8.3 VIF-AGC detector

Gain control is performed by sync level detection (negative modulation) or peak white detection (positive modulation).

For negative modulation, the sync level voltage is stored at an integrated capacitor by means of a fast peak detector. This voltage is compared with a reference voltage (nominal sync level) by a comparator which charges or discharges the integrated AGC capacitor for the generation of the required VIF gain. The time constants for decreasing or increasing the gain are nearly equal and the total AGC reaction time is fast to cope with 'aeroplane fluttering'.

For positive modulation, the white peak level voltage is compared with a reference voltage (nominal white level) by a comparator which charges (fast) or discharges (slow) the external AGC capacitor directly for the generation of the required VIF gain. The need of a very large time constant for VIF gain increase is caused by the fact that the peak white level may appear only once in a field. In order to reduce this time constant, an additional level detector increases the discharging current of the AGC capacitor (fast mode) in the event of a decreasing VIF amplitude step controlled by the detected actual black level voltage. The threshold level for fast mode AGC is typical -6 dB video amplitude. The fast mode state is also transferred to the SIF-AGC detector for speed-up. In case of missing peak white pulses, the VIF gain increase is limited to typical +3 dB by comparing the detected actual black level voltage with a corresponding reference voltage.

8.4 FPLL detector

The VIF amplifier output signal is fed into a frequency detector and into a phase detector via a limiting amplifier for removing the video AM.

During acquisition the frequency detector produces a current proportional to the frequency difference between the VIF and the VCO signal. After frequency lock-in the phase detector produces a current proportional to the phase difference between the VIF and the VCO signal. The currents from the frequency and phase detector are charged into the loop filter which controls the VIF VCO and locks it to the frequency and phase of the VIF carrier.

For a positive modulated VIF signal, the charging currents are gated by the composite sync in order to avoid signal distortion in case of overmodulation. The gating depth is switchable via the I²C-bus.

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8.5 VCO and divider

The VCO of the VIF-FPLL operates as an integrated low radiation relaxation oscillator at double the picture carrier frequency. The control voltage, required to tune the VCO to actually double the picture carrier frequency, is generated at the loop filter by the frequency phase detector. The possible frequency range is 50 to 140 MHz (typical value).

The oscillator frequency is divided-by-two for providing two differential square wave signals with exactly 90 degrees phase difference, independent of the frequency, for use in the FPLL detectors, the video demodulator and the intercarrier mixer.

8.6 AFC and digital acquisition help

Each relaxation oscillator of the VIF-PLL and FM-PLL demodulator has a wide frequency range. To prevent false locking of the PLLs and with respect to the catching range, the digital acquisition help provides an individual control, until the frequency of the VCO is within the preselected standard dependent lock-in window of the PLL.

The in-window and out-window control at the FM-PLL is additionally be used to mute the audio stage (if auto mute is selected via the I²C-bus).

The principle working of the digital acquisition help is as following. The PLL VCO output is connected to a down counter which has a predefined start value (standard dependent). The VCO frequency clocks the down counter for a fixed gate time. Thereafter, the down counter stop value is analysed. In case the stop value is higher (lower) than the expected value range, the VCO frequency is lower (higher) than the wanted lock-in window frequency range. A positive (negative) control current is injected into the PLL loop filter and consequently the VCO frequency will be increased (decreased) and a new counting cycle starts.

The gate time as well as the control logic of the acquisition help circuit is dependent on the precision of the reference signal at pin REF. Operation as crystal oscillator is possible as well as connecting this input via a serial capacitor to an external reference frequency e.g. the tuning system oscillator.

The AFC signal is derived from the corresponding down counter stop value after a counting cycle. The last four bits are latched and can be read out via the I²C-bus (see Table 7). Also the digital-to-analog converted value is given as current at pin AFC.

8.7 Video demodulator and amplifier

The video demodulator is realized by a multiplier which is designed for low distortion and large bandwidth. The VIF signal is multiplied with the 'in phase' signal of the VIF-PLL VCO.

The demodulator output signal is fed into the video preamplifier via a level shift stage with integrated low-pass filter to achieve carrier harmonics attenuation.

The output signal of the preamplifier is fed to the VIF-AGC detector (see Section 8.3) and in the sound trap mode also fed internally to the integrated sound carrier trap (see Section 8.8). The differential trap output signal is converted and amplified by the following postamplifier. The video output level at pin CVBS is 2 V (p-p).

In the bypass mode the output signal of the preamplifier is fed directly through the postamplifier to pin CVBS. The output video level is 1.1 V (p-p) for using an external sound trap with 10% loss over all.

Noise clipping is provided in both cases.

8.8 Sound carrier trap

The sound carrier trap consists of a reference filter, a phase detector and the sound trap itself.

A sound carrier reference signal is fed into the reference low-pass filter and is shifted by nominal 90 degrees. The phase detector compares the original reference signal with the signal shifted by the reference filter and produces a DC voltage by charging or discharging an integrated capacitor with a current proportional to the phase difference between both signals, respectively to the frequency error of the integrated filters. The DC voltage controls the frequency position of the reference filter and the sound trap. So the accurate frequency position for the different standards is set by the sound carrier reference signal.

The sound trap itself is constructed of three separate traps to realize sufficient suppression of the first and second sound carrier.

8.9 SIF amplifier

The SIF amplifier consists of three AC-coupled differential stages. Gain control is performed by emitter degeneration. The total gain control range is typical 66 dB. The differential input impedance is typical 2 k Ω in parallel with 3 pF.

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8.10 SIF-AGC detector

SIF gain control is performed by the detection of the DC component of the AM demodulator output signal. This DC signal is directly corresponding to the SIF voltage at the output of the SIF amplifier so that a constant SIF signal is supplied to the AM demodulator and to the single reference QSS mixer.

By switching the gain of the input amplifier of the SIF-AGC detector via the I²C-bus, the internal SIF level for FM sound is 5.5 dB lower than for AM sound. This is done to adapt the SIF-AGC characteristic to the VIF-AGC characteristic. The adaption is ideal for a picture-to-sound FM carrier ratio of 13 dB.

Via a comparator the integrated AGC capacitor is charged or discharged for the generation of the required SIF gain. Due to AM sound, the AGC reaction time is slow ($f_c < 20$ Hz for the closed AGC loop). For reducing this AM sound time constant in the event of a decreasing IF amplitude step, the load current of the AGC capacitor is increased (fast mode) when the VIF-AGC detector (at positive modulation mode) operates in the fast mode too. An additional circuit (threshold approximately 7 dB) ensures a very fast gain reduction for a large increasing IF amplitude step.

8.11 Single reference QSS mixer

With the present system a high performance Hi-Fi stereo sound processing can be achieved. For a simplified application without a SIF SAW filter, the single reference QSS mixer can be switched to the intercarrier mode via the I²C-bus.

The single reference QSS mixer generates the 2nd FM TV sound intercarrier signal. It is realized by a linear multiplier which multiplies the SIF amplifier output signal and the VIF-PLL VCO signal (90 degrees output) which is locked to the picture carrier. By this way the QSS mixer operates as a quadrature mixer in the intercarrier mode and provides suppression of the low frequency video signals.

The QSS mixer output signal is fed internally via a high-pass and low-pass combination to the FM demodulator as well as via an operational amplifier to the intercarrier output pin SIOMAD.

8.12 AM demodulator

The amplitude modulated SIF amplifier output signal is fed both to a two-stage limiting amplifier for removing the AM and to a linear multiplier. The result of the multiplication of the SIF signal with the limiter output signal is AM demodulation (passive synchronous demodulator). The demodulator output signal is fed via a low-pass filter for the attenuation of carrier harmonics and via the input amplifier of the SIF-AGC detector to the audio amplifier.

8.13 FM demodulator and acquisition help

The narrow-band FM-PLL detector consists of:

- Gain controlled FM amplifier and AGC detector
- Narrow-band PLL.

The intercarrier signal from the intercarrier mixer or from pin FMIN is fed to the input of an AC-coupled gain controlled amplifier with two stages. The gain controlled output signal is fed to the phase detector of the narrow-band FM-PLL (FM demodulator). For good selectivity and robustness against disturbance caused by the video signal, a high linearity of the gain controlled FM amplifier and of the phase detector as well as a constant signal level are required. The gain control is done by means of an 'in phase' demodulator for the FM carrier (from the output of the FM amplifier). The demodulation output is fed into a comparator for charging or discharging the integrated AGC capacitor. This leads to a mean value AGC loop to control the gain of the FM amplifier

The FM demodulator is realized as a narrow-band PLL with an external loop filter, which provides the necessary selectivity (bandwidth approximately 100 kHz). To achieve good selectivity, a linear phase detector and a constant input level are required. The gain controlled intercarrier signal from the FM amplifier is fed to the phase detector. The phase detector controls via the loop filter the integrated low radiation relaxation oscillator. The designed frequency range is from 4 to 7 MHz.

The VCO within the FM-PLL is phase-locked to the incoming 2nd SIF signal, which is frequency modulated. On to this fact, the VCO control voltage is superimposed by the AF voltage. Therefore, the VCO tracks with the FM of the 2nd SIF signal. So, the AF voltage is present at the loop filter and is typically 5 mV (RMS) for 27 kHz FM deviation. This AF signal is fed via a buffer to the audio amplifier.

The correct locking of the PLL is supported by the digital acquisition help circuit (see Section 8.6).

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8.14 Audio amplifier and mute time constant

The audio amplifier consists of two parts:

- AF preamplifier
- AF output amplifier.

The AF preamplifier used for FM sound is an operational amplifier with internal feedback, high gain and high common mode rejection. The AF voltage from the PLL demodulator is 5 mV (RMS) for frequency deviation of 27 kHz and is amplified by 30 dB. By the use of a DC operating point control circuit (with external capacitor C_{AF}), the AF preamplifier is decoupled from the PLL DC voltage. The low-pass characteristic of the amplifier reduces the harmonics of the sound intercarrier signal at the AF output terminal.

For FM sound a switchable de-emphasis network (with external capacitor) is implemented between the preamplifier and the output amplifier.

The AF output amplifier provides the required AF output level by a rail-to-rail output stage. A preceding stage makes use of an input selector for switching between FM sound, AM sound and mute state. The gain can be switched between 10 dB (normal) and 4 dB (reduced).

Switching to the mute state is controlled automatically, dependent on the digital acquisition help for the case the VCO of the FM-PLL is not in the required frequency window. This is done by a time constant: fast for switching to the mute state and slow (typically 40 ms) for switching to the no-mute state.

All switching functions are controlled via the I²C-bus:

- AM sound, FM sound and forced mute
- Auto mute enable or disable
- De-emphasis off or on with 50 or 75 μ s
- Audio gain normal or reduced.

8.15 Radio mode

The principle is to multiply the first radio IF (e.g. 33.3 MHz at tuner output) with 44 MHz reference signal. The result of the down-conversion is the second radio IF (10.7 MHz) at intercarrier output.

In the radio mode the tuner delivers a first radio IF signal of 33.3 MHz. This signal is fed via the SIF SAW filter (conventional used for QSS TV sound processing) to the SIF input. The sound IF amplifier supplies this radio IF signal by means of gain control with constant level to the QSS mixer. The single reference QSS mixer generates the second radio IF signal of 10.7 MHz. In the radio mode the VIF VCO operates as part of a frequency synthesizer and

delivers a constant 44 MHz signal (derived from the reference signal of 4 MHz) for the down-conversion of the first radio IF to 10.7 MHz. This signal is fed via the external ceramic band-pass filter to the FM demodulator. The demodulated AF signal is amplified by the audio amplifier.

In case of NTSC application (M/N standard) the internal mixing frequency is 52 MHz. So, the first radio IF has to be 41.3 MHz.

For tuning search mode, the device offers certain monitoring functions. Switchable are radio AFC, FM-AGC or SIF-AGC to pin AFC.

8.16 Internal voltage stabilizer

The band gap circuit internally generates a voltage of approximately 2.4 V, independent of supply voltage and temperature. A voltage regulator circuit, connected to this voltage, produces a constant voltage of 3.55 V which is used as an internal reference voltage.

8.17 I²C-bus transceiver and module address

The device can be controlled via the 2-wire I²C-bus by a microcontroller. Two wires carry serial data (SDA) and serial clock (SCL) information between the devices connected to the I²C-bus.

The device has an I²C-bus slave transceiver with auto-increment. The circuit operates up to clock frequencies of 400 kHz.

A slave address is sent from the master to the slave receiver. To avoid conflicts in a real application with other devices providing similar or complementing functions, there are four possible slave addresses available. These Module Addresses (MADs) can be selected by connecting resistors on pin SIOMAD and/or pins SIF1 and SIF2 (see Fig.23). Pin SIOMAD relates with bit A0 and pins SIF1 and SIF2 relate with bit A3. The slave addresses of this device are given in Table 1.

The power-on preset value is dependent on the use of pin SIOMAD and can be chosen for 45.75 MHz NTSC as default (pin SIOMAD left open-circuit) or 58.75 MHz NTSC (resistor on pin SIOMAD). In this way the device can be used without the I²C-bus as an NTSC only device.

Remark: In case of using the device without the I²C-bus, then the rise time of the supply voltage after switching on power must be longer than 1.2 μ s.

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Table 1 Slave address detection

| SLAVE ADDRESS | SELECTABLE ADDRESS BIT | | RESISTOR ON PIN | |
|---------------|------------------------|----|-----------------|--------|
| | A3 | A0 | SIF1 AND SIF2 | SIOMAD |
| MAD1 | 0 | 1 | no | no |
| MAD2 | 0 | 0 | no | yes |
| MAD3 | 1 | 1 | yes | no |
| MAD4 | 1 | 0 | yes | yes |

9 I²C-BUS CONTROL

9.1 Read format

Table 2 I²C-bus read format (slave transmits data)

| S | BYTE 1 | | | | | | | | A | BYTE 2 | | | | | | | | AN | P |
|---|---------------|----|----|----|----|----|----|-----|---|--------|----|----|----|----|----|----|----|----|---|
| | A6 | A5 | A4 | A3 | A2 | A1 | A0 | R/W | | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 | | |
| | slave address | | | | | | | 1 | | data | | | | | | | | | |

Table 3 Explanation of Table 2

| SYMBOL | FUNCTION |
|---------------|---|
| S | START condition, generated by the master |
| Slave address | see Table 4 |
| R/W = 1 | read command, generated by the master |
| A | acknowledge bit, generated by the slave |
| Data | 8-bit data word, transmitted by the slave (see Table 5) |
| AN | acknowledge-not bit, generated by the master |
| P | STOP condition, generated by the master |

The master generates an acknowledge when it has received the dataword READ. The master next generates an acknowledge, then slave begins transmitting the dataword READ, and so on until the master generates an acknowledge-not bit and transmits a STOP condition.

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9.1.1 SLAVE ADDRESS

The first module address MAD1 is the standard address (see Table 1).

Table 4 Slave addresses; notes 1 and 2

| SLAVE ADDRESS | | BIT | | | | | | |
|---------------|-------------|-----|----|----|----|----|----|----|
| NAME | VALUE (HEX) | A6 | A5 | A4 | A3 | A2 | A1 | A0 |
| MAD1 | 43 | 1 | 0 | 0 | 0 | 0 | 1 | 1 |
| MAD2 | 42 | 1 | 0 | 0 | 0 | 0 | 1 | 0 |
| MAD3 | 4B | 1 | 0 | 0 | 1 | 0 | 1 | 1 |
| MAD4 | 4A | 1 | 0 | 0 | 1 | 0 | 1 | 0 |

Notes

1. For MAD activation via external resistor: see Table 1 and Fig.23.
2. For applications without I²C-bus: see Tables 18 and 19.

9.1.2 DATA BYTE

Table 5 Data read register (status register)

| MSB | | BIT | | | | | LSB |
|--------|--------|---------|------|------|------|------|------|
| D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
| AFCWIN | VIFLEV | CARRDET | AFC4 | AFC3 | AFC2 | AFC1 | PONR |

Table 6 Description of status register bits

| BIT | VALUE | DESCRIPTION |
|----------|-------|--|
| AFCWIN | 1 | AFC window VCO in ± 1.6 MHz AFC window; note 1 |
| | 0 | VCO out of ± 1.6 MHz AFC window |
| VIFLEV | 1 | VIF input level high level; VIF input voltage ≥ 200 μ V (typically) |
| | 0 | low level |
| CARRDET | 1 | FM carrier detection detection |
| | 0 | no detection |
| AFC[4:1] | | Automatic frequency control see Table 7 |
| PONR | 1 | Power-on reset after power-on reset or after supply breakdown |
| | 0 | after a successful reading of the status register |

Note

1. If no IF input is applied, then bit AFCWIN = 1 due to the fact that the VCO is forced to the AFC window border for fast load-in behaviour.

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Table 7 Automatic frequency control bits; note 1

| BIT | | | | f_{VIF} |
|------|------|------|------|----------------------------------|
| AFC4 | AFC3 | AFC2 | AFC1 | |
| 0 | 1 | 1 | 1 | $\leq (f_0 - 187.5 \text{ kHz})$ |
| 0 | 1 | 1 | 0 | $f_0 - 162.5 \text{ kHz}$ |
| 0 | 1 | 0 | 1 | $f_0 - 137.5 \text{ kHz}$ |
| 0 | 1 | 0 | 0 | $f_0 - 112.5 \text{ kHz}$ |
| 0 | 0 | 1 | 1 | $f_0 - 87.5 \text{ kHz}$ |
| 0 | 0 | 1 | 0 | $f_0 - 62.5 \text{ kHz}$ |
| 0 | 0 | 0 | 1 | $f_0 - 37.5 \text{ kHz}$ |
| 0 | 0 | 0 | 0 | $f_0 - 12.5 \text{ kHz}$ |
| 1 | 1 | 1 | 1 | $f_0 + 12.5 \text{ kHz}$ |
| 1 | 1 | 1 | 0 | $f_0 + 37.5 \text{ kHz}$ |
| 1 | 1 | 0 | 1 | $f_0 + 62.5 \text{ kHz}$ |
| 1 | 1 | 0 | 0 | $f_0 + 87.5 \text{ kHz}$ |
| 1 | 0 | 1 | 1 | $f_0 + 112.5 \text{ kHz}$ |
| 1 | 0 | 1 | 0 | $f_0 + 137.5 \text{ kHz}$ |
| 1 | 0 | 0 | 1 | $f_0 + 162.5 \text{ kHz}$ |
| 1 | 0 | 0 | 0 | $\geq (f_0 + 187.5 \text{ kHz})$ |

Note

1. f_0 is the nominal frequency of f_{VIF} .

9.2 Write format**Table 8** I²C-bus write format (slave receives data); note 1

| S | BYTE 1 | | A | BYTE 2 | A | BYTE 3 | A | BYTE n | A | P |
|---|---------------|-----|---|------------|---|-------------|---|-------------|---|---|
| | A6 to A0 | R/W | | A7 to A0 | | bits 7 to 0 | | bits 7 to 0 | | |
| | slave address | 0 | | subaddress | | data 1 | | data n | | |

Note

1. The auto-increment of the subaddress stops, if the subaddress is 3.

Table 9 Explanation of Table 8

| SYMBOL | FUNCTION |
|------------------|--|
| S | START condition, generated by the master |
| Slave address | see Table 4 |
| $R/\bar{W} = 0$ | write command, generated by the master |
| A | acknowledge bit, generated by the slave |
| Subaddress (SAD) | see Table 10 |
| Data 1, data n | 8-bit data words, transmitted by the master (see Tables 11, 12 and 14) |
| P | STOP condition |

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9.2.1 SUBADDRESS

If more than 1 data byte is transmitted, then auto-increment is performed: starting from the transmitted subaddress and auto-increment of subaddress in accordance with the order of Table 10.

Table 10 Definition of the subaddress (second byte after slave address); note 1

| REGISTER | MSB | | | | | | | LSB |
|------------------------|-------------------|-------------------|-------------------|-------------------|-------------------|-------------------|----|-----|
| | A7 ⁽²⁾ | A6 ⁽³⁾ | A5 ⁽³⁾ | A4 ⁽³⁾ | A3 ⁽³⁾ | A2 ⁽³⁾ | A1 | A0 |
| SAD for switching mode | 0 | X | X | X | X | X | 0 | 0 |
| SAD for adjust mode | 0 | X | X | X | X | X | 0 | 1 |
| SAD for data mode | 0 | X | X | X | X | X | 1 | 0 |

Notes

1. X = don't care.
2. Bit A7 = 1 is not allowed.
3. Bits A6 to A2 will be ignored by the internal hardware.

9.2.2 DATA BYTE FOR SWITCHING MODE

Table 11 Bit description of SAD register for switching mode (SAD = 00)

| BIT | VALUE | DESCRIPTION |
|---------|-------|--|
| 7 | 1 | Output port 2 for SAW switching or monitoring high-impedance, disabled or HIGH |
| | 0 | low-impedance, active or LOW |
| 6 | 1 | Output port 1 for SAW switching or external input high-impedance, disabled or HIGH |
| | 0 | low-impedance, active or LOW |
| 5 | 1 | Forced audio mute on |
| | 0 | off |
| 4 and 3 | 00 | TV standard modulation and radio mode positive AM TV; note 1 |
| | 01 | FM radio; note 2 |
| | 10 | negative FM TV |
| | 11 | FM radio; note 2 |
| 2 | 1 | Carrier mode QSS mode |
| | 0 | intercarrier mode |

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| BIT | VALUE | DESCRIPTION |
|-----|-------|---|
| 1 | 1 | Mute of FM AF outputs active |
| | 0 | inactive |
| 0 | 1 | Video mode (sound trap) sound trap bypass |
| | 0 | sound trap active |

Notes

- For positive AM TV choose 6.5 MHz for the second SIF.
- For FM radio, select $f_{VIF} = 45.75$ MHz for NTSC applications; otherwise use an arbitrary video IF (see Table 17).

9.2.3 DATA BYTE FOR ADJUST MODE

Table 12 Bit description of SAD register for adjust mode (SAD = 01)

| BIT | VALUE | DESCRIPTION |
|--------|-------|--|
| 7 | 1 | Audio gain −6 dB |
| | 0 | 0 dB |
| 6 | 1 | De-emphasis time constant 50 μ s |
| | 0 | 75 μ s |
| 5 | 1 | De-emphasis on |
| | 0 | off |
| 4 to 0 | | Tuner takeover point adjustment see Table 13 |

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Table 13 Tuner takeover point adjustment bits

| BIT | | | | | TOP ADJUSTMENT (dB) |
|-----|---|---|---|---|------------------------|
| 4 | 3 | 2 | 1 | 0 | |
| 1 | 1 | 1 | 1 | 1 | +15 |
| 1 | 1 | 1 | 1 | 0 | +14 |
| 1 | 1 | 1 | 0 | 1 | +13 |
| 1 | 1 | 1 | 0 | 0 | +12 |
| 1 | 1 | 0 | 1 | 1 | +11 |
| 1 | 1 | 0 | 1 | 0 | +10 |
| 1 | 1 | 0 | 0 | 1 | +9 |
| 1 | 1 | 0 | 0 | 0 | +8 |
| 1 | 0 | 1 | 1 | 1 | +7 |
| 1 | 0 | 1 | 1 | 0 | +6 |
| 1 | 0 | 1 | 0 | 1 | +5 |
| 1 | 0 | 1 | 0 | 0 | +4 |
| 1 | 0 | 0 | 1 | 1 | +3 |
| 1 | 0 | 0 | 1 | 0 | +2 |
| 1 | 0 | 0 | 0 | 1 | +1 |
| 1 | 0 | 0 | 0 | 0 | 0 ⁽¹⁾ |
| 0 | 1 | 1 | 1 | 1 | -1 |
| 0 | 1 | 1 | 1 | 0 | -2 |
| 0 | 1 | 1 | 0 | 1 | -3 |
| 0 | 1 | 1 | 0 | 0 | -4 |
| 0 | 1 | 0 | 1 | 1 | -5 |
| 0 | 1 | 0 | 1 | 0 | -6 |
| 0 | 1 | 0 | 0 | 1 | -7 |
| 0 | 1 | 0 | 0 | 0 | -8 |
| 0 | 0 | 1 | 1 | 1 | -9 |
| 0 | 0 | 1 | 1 | 0 | -10 |
| 0 | 0 | 1 | 0 | 1 | -11 |
| 0 | 0 | 1 | 0 | 0 | -12 |
| 0 | 0 | 0 | 1 | 1 | -13 |
| 0 | 0 | 0 | 1 | 0 | -14 |
| 0 | 0 | 0 | 0 | 1 | -15 |
| 0 | 0 | 0 | 0 | 0 | -16 |

Note

1. 0 dB is equal to 17 mV (RMS).

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9.2.4 DATA BYTE FOR DATA MODE

Table 14 Bit description of SAD register for data mode (SAD = 10)

| BIT | VALUE | DESCRIPTION |
|---------|----------------------|--|
| 7 | | VIF-AGC output at pin OP2 dependent on bits 5 and 1; see Table 15 |
| 6 | 1 0 | L standard PLL gating HIGH gating in case of 36% positive modulation gating in case of 0% positive modulation |
| 5 | | VIF, SIF and tuner minimum gain dependent on bit 7; see Table 15 |
| 4 to 2 | | Frequency selection see Table 17 |
| 1 and 0 | 00 01 10 11 | Standard frequency sound intercarrier (sound 2nd IF) $f_{FM} = 4.5$ MHz $f_{FM} = 5.5$ MHz $f_{FM} = 6.0$ MHz $f_{FM} = 6.5$ MHz (for positive modulation choose 6.5 MHz) |

Table 15 Options in extended TV mode; bit 3 = 0 of SAD = 00 register

| FUNCTION | BIT 7 = 0 | | BIT 7 = 1 | |
|----------|---------------|---------------|----------------|------------------------|
| | BIT 5 = 0 | BIT 5 = 1 | BIT 5 = 0 | BIT 5 = 1 |
| Pin OP1 | port function | port function | port function | VIF-AGC external input |
| Pin OP2 | port function | port function | VIF-AGC output | port function |
| Gain | normal gain | minimum gain | normal gain | external gain |

Table 16 Options in extended radio mode; bit 3 = 1 of SAD = 00 register

| FUNCTION | BIT 7 = 0 | BIT 7 = 1 | |
|----------|------------------------------|----------------------|----------------------|
| | | BIT 4 = 0, BIT 3 = 0 | BIT 4 = 1, BIT 3 = 1 |
| Pin AFC | FM radio carrier related AFC | SIF-AGC radio output | FM-AGC radio output |

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Table 17 Frequency selection bits

| BIT | | | DESCRIPTION | |
|-----|---|---|---|--|
| 4 | 3 | 2 | TV MODE BIT 3 = 0 OF REGISTER SAD = 00 | RADIO MODE BIT 3 = 1 OF REGISTER SAD = 00 |
| 0 | 0 | 0 | $f_{VIF} = 58.75$ MHz; note 1 | $f_{RIF1} = 33.3$ MHz, $f_{VCO} = 44$ MHz; $f_{RIF2} = 10.7$ MHz |
| 0 | 0 | 1 | $f_{VIF} = 45.75$ MHz | $f_{RIF1} = 41.3$ MHz, $f_{VCO} = 52$ MHz; $f_{RIF2} = 10.7$ MHz |
| 0 | 1 | 0 | $f_{VIF} = 38.9$ MHz | $f_{RIF1} = 33.3$ MHz, $f_{VCO} = 44$ MHz; $f_{RIF2} = 10.7$ MHz |
| 0 | 1 | 1 | $f_{VIF} = 38.0$ MHz | $f_{RIF1} = 33.3$ MHz, $f_{VCO} = 44$ MHz; $f_{RIF2} = 10.7$ MHz |
| 1 | 0 | 0 | $f_{VIF} = 33.9$ MHz | $f_{RIF1} = 33.3$ MHz, $f_{VCO} = 44$ MHz; $f_{RIF2} = 10.7$ MHz |
| 1 | 0 | 1 | $f_{VIF} = 33.4$ MHz | $f_{RIF1} = 33.3$ MHz, $f_{VCO} = 44$ MHz; $f_{RIF2} = 10.7$ MHz |
| 1 | 1 | 0 | $f_{VIF} = 45.75$ MHz plus FM external input via pin FMIN; note 2 | $f_{RIF1} = 41.3$ MHz, $f_{VCO} = 52$ MHz; $f_{RIF2} = 10.7$ MHz |
| 1 | 1 | 1 | $f_{VIF} = 38.9$ MHz plus FM external input via pin FMIN; note 2 | $f_{RIF1} = 33.3$ MHz, $f_{VCO} = 44$ MHz; $f_{RIF2} = 10.7$ MHz |

Notes

- Pin SIOMAD can be used for the selection of the different NTSC standards without I²C-bus. With a resistor on pin SIOMAD, the $f_{VIF} = 58.75$ MHz and without a resistor on pin SIOMAD, the $f_{VIF} = 45.75$ MHz (NTSC-M).
- Attention: video sound traps are locked on the FM VCO. The second VIF should be selected in accordance with the selected video standard.

Table 18 Data setting after power-on reset (default setting for MAD = 0)

| REGISTER | MSB | | | | | | | LSB |
|----------------|-----|----|----|----|----|----|----|-----|
| | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
| Switching mode | 1 | 1 | 0 | 1 | 0 | 1 | 1 | 0 |
| Adjust mode | 0 | 0 | 1 | 1 | 0 | 0 | 0 | 0 |
| Data mode | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

Table 19 Data setting after power-on reset (default setting for MAD = 1)

| REGISTER | MSB | | | | | | | LSB |
|----------------|-----|----|----|----|----|----|----|-----|
| | D7 | D6 | D5 | D4 | D3 | D2 | D1 | D0 |
| Switching mode | 1 | 1 | 0 | 1 | 0 | 1 | 1 | 0 |
| Adjust mode | 0 | 0 | 1 | 1 | 0 | 0 | 0 | 0 |
| Data mode | 0 | 0 | 0 | 0 | 0 | 1 | 0 | 0 |

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10 LIMITING VALUES

In accordance with the Absolute Maximum Rating System (IEC 60134).

| SYMBOL | PARAMETER | CONDITIONS | MIN. | MAX. | UNIT |
|-----------|--|------------|--------|--------------|--------|
| V_P | supply voltage | | – | 5.5 | V |
| V_n | voltage on pins VIF1, VIF2, SIF1, SIF2, OP1, OP2, V_P , and FMPLL pin TAGC | | 0 0 | V_P 8.8 | V V |
| t_{sc} | short-circuit time to ground or V_P | | – | 10 | s |
| T_{stg} | storage temperature | | –25 | +150 | °C |
| T_{amb} | ambient temperature | | –20 | +70 | °C |
| V_{es} | electrostatic discharge voltage on all pins | note 1 | –300 | +300 | V |
| | | note 2 | –3000 | +3000 | V |

Notes

- Machine model in accordance with SNW-FQ-302B: class B, discharging a 200 pF capacitor via a 0.75 μ H series inductance.
- Human body model in accordance with SNW-FQ-302A: class 2, discharging a 100 pF capacitor via a 1.5 k Ω series resistor.

11 THERMAL CHARACTERISTICS

| SYMBOL | PARAMETER | CONDITIONS | VALUE | UNIT |
|---------------|---|-------------|-------|------|
| $R_{th(j-a)}$ | thermal resistance from junction to ambient | in free air | 105 | K/W |

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12 CHARACTERISTICS

$V_P = 5\text{ V}$; $T_{\text{amb}} = 25\text{ °C}$; see Table 21 for input frequencies; B/G standard is used for the specification ($f_{\text{PC}} = 38.9\text{ MHz}$; $f_{\text{SC}} = 33.4\text{ MHz}$; $\text{PC/SC} = 13\text{ dB}$; $f_{\text{mod}} = 400\text{ Hz}$); input level $V_{i(\text{VIF})} = 10\text{ mV (RMS)}$ (sync level for B/G; peak white level for L); IF input from $50\ \Omega$ via broadband transformer 1 : 1; video modulation DSB; residual carrier for B/G is 10% and for L is 3%; video signal in accordance with "CCIR line 17 and line 330" or "NTC-7 Composite"; measurements taken in test circuit of Fig.23; unless otherwise specified.

| SYMBOL | PARAMETER | CONDITIONS | MIN. | TYP. | MAX. | UNIT |
|--|--|---|------|-------|------|------|
| Supply (pin V_P) | | | | | | |
| V _P | supply voltage | note 1 | 4.5 | 5.0 | 5.5 | V |
| I _P | supply current | | 52 | 63 | 70 | mA |
| P _{tot} | total power dissipation | | – | 305 | 385 | mW |
| POWER-ON RESET | | | | | | |
| V _{P(start)} | supply voltage for start of reset | decreasing supply voltage | 2.5 | 3.0 | 3.5 | V |
| V _{P(stop)} | supply voltage for end of reset | increasing supply voltage; I ² C-bus transmission enable | – | – | 4.4 | V |
| τ _P | time constant (R × C) for network at pin V _P | for applications without I ² C-bus | 1.2 | – | – | μs |
| VIF amplifier (pins VIF1 and VIF2) | | | | | | |
| V _{i(VIF)(rms)} | VIF input voltage sensitivity (RMS value) | –1 dB video at output | – | 60 | 100 | μV |
| V _{i(max)(rms)} | maximum input voltage (RMS value) | +1 dB video at output | 150 | 190 | – | mV |
| V _{i(ovl)(rms)} | overload input voltage (RMS value) | note 2 | – | – | 440 | mV |
| ΔV _{IF(int)} | internal IF amplitude difference between picture and sound carrier | within AGC range; Δf = 5.5 MHz | – | 0.7 | – | dB |
| G _{VIF(cr)} | VIF gain control range | | 60 | 66 | – | dB |
| B _{VIF(–3dB)(ll)} | lower limit –3 dB VIF bandwidth | | – | 15 | – | MHz |
| B _{VIF(–3dB)(ul)} | upper limit –3 dB VIF bandwidth | | – | 80 | – | MHz |
| R _{i(dif)} | differential input resistance | note 3 | – | 2 | – | kΩ |
| C _{i(dif)} | differential input capacitance | note 3 | – | 3 | – | pF |
| V _I | DC input voltage | | – | 1.93 | – | V |
| FPLL and true synchronous video demodulator; note 4 | | | | | | |
| f _{VCO(max)} | maximum oscillator frequency for carrier regeneration | f = 2f _{PC} | 120 | 140 | – | MHz |
| f _{VIF} | vision carrier operating frequencies | see Table 17 | – | 33.4 | – | MHz |
| | | | – | 33.9 | – | MHz |
| | | | – | 38.0 | – | MHz |
| | | | – | 38.9 | – | MHz |
| | | | – | 45.75 | – | MHz |
| | | | – | 58.75 | – | MHz |

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| SYMBOL | PARAMETER | CONDITIONS | MIN. | TYP. | MAX. | UNIT |
|--|--|--|-------------|-----------|------|-------------|
| Δf_{VIF} | VIF frequency window of digital acquisition help | related to f_{VIF} ; see Fig.9 | – | ± 2.3 | – | MHz |
| t_{acq} | acquisition time | BL = 70 kHz; note 5 | – | – | 30 | ms |
| $V_{i(lock)(rms)}$ | input voltage sensitivity for PLL to be locked (RMS value) | measured on pins VIF1 and VIF2; maximum IF gain | – | 30 | 70 | μV |
| $T_{cy(DAH)}$ | cycle time of digital acquisition help | | – | 64 | – | μs |
| $K_{O(VIF)}$ | VIF VCO steepness | definition: $\Delta f_{VIF}/\Delta V_{VPLL}$ | – | 20 | – | MHz/V |
| $K_{D(VIF)}$ | VIF phase detector steepness | definition: $\Delta I_{VPLL}/\Delta \phi_{VIF}$ | – | 23 | – | $\mu A/rad$ |
| Video output 2 V (pin CVBS) | | | | | | |
| NORMAL MODE (SOUND CARRIER TRAP ACTIVE) AND SOUND CARRIER ON | | | | | | |
| $V_{o(p-p)}$ | video output voltage (peak-to-peak value) | see Fig.3 | 1.7 | 2.0 | 2.3 | V |
| ΔV_o | video output voltage difference | difference between L and B/G standard | –12 | – | +12 | % |
| V/S | ratio between video (black-to-white) and sync level | | 1.90 | 2.33 | 3.00 | |
| V_{sync} | sync voltage level | | 1.0 | 1.2 | 1.4 | V |
| $V_{clip(u)}$ | upper video clipping voltage level | | $V_P - 1.1$ | $V_P - 1$ | – | V |
| $V_{clip(l)}$ | lower video clipping voltage level | | – | 0.7 | 0.9 | V |
| R_o | output resistance | note 3 | – | – | 30 | Ω |
| $I_{bias(int)}$ | internal DC bias current for emitter-follower | | 1.5 | 2.0 | – | mA |
| $I_{o(sink)(max)}$ | maximum AC and DC output sink current | | 1 | – | – | mA |
| $I_{o(source)(max)}$ | maximum AC and DC output source current | | 3.9 | – | – | mA |
| $\Delta V_{o(CVBS)}$ | deviation of CVBS output voltage | 50 dB gain control | – | – | 0.5 | dB |
| | | 30 dB gain control | – | – | 0.1 | dB |
| $\Delta V_{o(bl)}$ | black level tilt | negative modulation | – | – | 1 | % |
| $\Delta V_{o(bl)(v)}$ | vertical black level tilt for worst case in L standard | vision carrier modulated by test line (VITS) only | – | – | 3 | % |
| G_{dif} | differential gain | "CCIR 330"; note 6 B/G standard | – | – | 5 | % |
| | | L standard | – | – | 7 | % |
| ϕ_{dif} | differential phase | "CCIR 330" | – | 2 | 4 | deg |
| $S/N_{W(video)}$ | weighted signal-to-noise ratio | weighted in accordance with "CCIR 567"; see Fig.11; note 7 | 56 | 59 | – | dB |

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| SYMBOL | PARAMETER | CONDITIONS | MIN. | TYP. | MAX. | UNIT |
|--|---|---|----------|----------|--------|----------|
| $S/N_{UW(\text{video})}$ | unweighted signal-to-noise ratio | note 7 | 47 | 51 | – | dB |
| $\alpha_{IM(\text{blue})}$ | intermodulation attenuation at 'blue' | see Fig.12; note 8 f = 1.1 MHz f = 3.3 MHz | 58 58 | 64 64 | – – | dB dB |
| $\alpha_{IM(\text{yellow})}$ | intermodulation attenuation at 'yellow' | see Fig.12; note 8 f = 1.1 MHz f = 3.3 MHz | 60 59 | 66 65 | – – | dB dB |
| $\Delta V_{r(\text{PC})(\text{rms})}$ | residual picture carrier (RMS value) | fundamental wave and harmonics | – | 2 | 5 | mV |
| $\Delta f_{\text{unw}(p-p)}$ | robustness for unwanted frequency deviation of picture carrier (peak-to-peak value) | 3% residual carrier; 50% serration pulses; L standard; note 3 | – | – | 12 | kHz |
| $\Delta\phi$ | robustness for modulator imbalance | 0% residual carrier; 50% serration pulses; L standard; L-gating = 0%; note 3 | – | – | 3 | % |
| α_H | suppression of video signal harmonics | $C_L < 20 \text{ pF}$; $R_L > 1 \text{ k}\Omega$; AC load; note 9a | 35 | 40 | – | dB |
| α_{spur} | suppression of spurious elements | note 9b | 40 | – | – | dB |
| $\text{PSRR}_{\text{CVBS}}$ | power supply ripple rejection at pin CVBS | $f_{\text{ripple}} = 70 \text{ Hz}$; video signal; grey level; positive and negative modulation; see Fig.4 | 20 | 25 | – | dB |
| M/N STANDARD INCLUSIVE KOREA; see Fig.13 | | | | | | |
| $B_{v(-3\text{dB})(\text{trap})}$ | –3 dB video bandwidth including sound carrier trap | $f_{\text{trap}} = 4.5 \text{ MHz}$; note 10 | 3.95 | 4.05 | – | MHz |
| α_{SC1} | attenuation at first sound carrier | f = 4.5 MHz | 30 | 36 | – | dB |
| $\alpha_{\text{SC1}(60\text{kHz})}$ | attenuation at first sound carrier $f_{\text{SC1}} \pm 60 \text{ kHz}$ | f = 4.5 MHz | 21 | 27 | – | dB |
| α_{SC2} | attenuation at second sound carrier | f = 4.724 MHz | 21 | 27 | – | dB |
| $\alpha_{\text{SC2}(60\text{kHz})}$ | attenuation at second sound carrier $f_{\text{SC2}} \pm 60 \text{ kHz}$ | f = 4.724 MHz | 15 | 21 | – | dB |
| $t_{d(g)(\text{cc})}$ | group delay at colour carrier frequency | f = 3.58 MHz; see Fig.14 | 110 | 180 | 250 | ns |
| B/G STANDARD; see Fig.15 | | | | | | |
| $B_{v(-3\text{dB})(\text{trap})}$ | –3 dB video bandwidth including sound carrier trap | $f_{\text{trap}} = 5.5 \text{ MHz}$; note 10 | 4.90 | 5.00 | – | MHz |
| α_{SC1} | attenuation at first sound carrier | f = 5.5 MHz | 30 | 36 | – | dB |
| $\alpha_{\text{SC1}(60\text{kHz})}$ | attenuation at first sound carrier $f_{\text{SC1}} \pm 60 \text{ kHz}$ | f = 5.5 MHz | 24 | 30 | – | dB |
| α_{SC2} | attenuation at second sound carrier | f = 5.742 MHz | 21 | 27 | – | dB |

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| SYMBOL | PARAMETER | CONDITIONS | MIN. | TYP. | MAX. | UNIT |
|---|--|--|------|------|------|------|
| $\alpha_{SC2(60kHz)}$ | attenuation at second sound carrier $f_{SC2} \pm 60$ kHz | $f = 5.742$ MHz | 15 | 21 | – | dB |
| $t_{d(g)(cc)}$ | group delay at colour carrier frequency | $f = 4.43$ MHz; see Fig.16 | 110 | 180 | 250 | ns |
| I STANDARD; see Fig.17 | | | | | | |
| $B_{V(-3dB)(trap)}$ | –3 dB video bandwidth including sound carrier trap | $f_{trap} = 6.0$ MHz; note 10 | 5.40 | 5.50 | – | MHz |
| α_{SC1} | attenuation at first sound carrier | $f = 6.0$ MHz | 26 | 32 | – | dB |
| $\alpha_{SC1(60kHz)}$ | attenuation at first sound carrier $f_{SC1} \pm 60$ kHz | $f = 6.0$ MHz | 20 | 26 | – | dB |
| α_{SC2} | attenuation at second sound carrier | $f = 6.55$ MHz | 12 | 18 | – | dB |
| $\alpha_{SC2(60kHz)}$ | attenuation at second sound carrier $f_{SC2} \pm 60$ kHz | $f = 6.55$ MHz | 10 | 15 | – | dB |
| $t_{d(g)(cc)}$ | group delay at colour carrier frequency | $f = 4.43$ MHz | – | 90 | 160 | ns |
| D/K STANDARD; see Fig.18 | | | | | | |
| $B_{V(-3dB)(trap)}$ | –3 dB video bandwidth including sound carrier trap | $f_{trap} = 6.5$ MHz; note 10 | 5.50 | 5.95 | – | MHz |
| α_{SC1} | attenuation at first sound carrier | $f = 6.5$ MHz | 26 | 32 | – | dB |
| $\alpha_{SC1(60kHz)}$ | attenuation at first sound carrier $f_{SC1} \pm 60$ kHz | $f = 6.5$ MHz | 20 | 26 | – | dB |
| α_{SC2} | attenuation at second sound carrier | $f = 6.742$ MHz | 18 | 24 | – | dB |
| $\alpha_{SC2(60kHz)}$ | attenuation at second sound carrier $f_{SC2} \pm 60$ kHz | $f = 6.742$ MHz | 13 | 18 | – | dB |
| $t_{d(g)(cc)}$ | group delay at colour carrier frequency | $f = 4.28$ MHz | – | 60 | 130 | ns |
| Video output 1.1 V (pin CVBS) | | | | | | |
| TRAP BYPASS MODE AND SOUND CARRIER OFF; note 11 | | | | | | |
| $V_{o(p-p)}$ | video output voltage (peak-to-peak value) | see Fig.3 | 0.95 | 1.10 | 1.25 | V |
| V_{sync} | sync voltage level | | 1.35 | 1.5 | 1.6 | V |
| $V_{clip(u)}$ | upper video clipping voltage level | | 3.5 | 3.6 | – | V |
| $V_{clip(l)}$ | lower video clipping voltage level | | – | 0.9 | 1.0 | V |
| $B_{V(-1dB)}$ | –1 dB video bandwidth | $C_L < 20$ pF; $R_L > 1$ k Ω ; AC load | 5 | 6 | – | MHz |
| $B_{V(-3dB)}$ | –3 dB video bandwidth | $C_L < 20$ pF; $R_L > 1$ k Ω ; AC load | 7 | 8 | – | MHz |

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| SYMBOL | PARAMETER | CONDITIONS | MIN. | TYP. | MAX. | UNIT |
|--|---|---|------|------|------|-------|
| S/N _W | weighted signal-to-noise ratio | weighted in accordance with "CCIR 567"; see Fig.11; note 7 | 56 | 59 | – | dB |
| S/N _{UW} | unweighted signal-to-noise ratio | note 7 | 48 | 52 | – | dB |
| VIF-AGC (pin VAGC); note 12 | | | | | | |
| I _{ch(max)} | maximum charge current | L standard | – | 100 | – | μA |
| I _{ch(add)} | additional charge current | L standard: in the event of missing VITS pulses and no white video content | – | 100 | – | nA |
| I _{dch} | discharge current | L standard; normal mode | – | 35 | – | nA |
| | | L standard; fast mode | – | 1.8 | – | μA |
| t _{resp(inc)} | AGC response time to an increasing VIF step | negative modulation; 20 dB; note 13 | – | 4 | – | ms |
| | | positive modulation; 20 dB; note 13 | – | 2.6 | – | ms |
| t _{resp(dec)} | AGC response time to a decreasing VIF step | negative modulation; 20 dB; note 13 | – | 3 | – | ms |
| | | positive modulation; 20 dB; note 13 | – | 890 | – | ms |
| | | L standard; fast mode | – | 2.6 | – | ms/dB |
| | | L standard; normal mode; note 13 | – | 143 | – | ms/dB |
| ΔV _{i(VIF)} | VIF amplitude step for activating AGC fast mode | L standard | –2 | –6 | –10 | dB |
| V _{VAGV} | gain control voltage range | | 0.8 | – | 3.5 | V |
| CR _{stps} | control steepness | definition: ΔG _{VIF} /ΔV _{VAGC} ; V _{VAGC} = 2 to 3 V | – | –80 | – | dB/V |
| V _{th(VIF)} | threshold voltage for high level VIF input | see Tables 5 and 6 | 120 | 200 | 320 | μV |
| Tuner AGC (pin TAGC); see Figs 5 to 8 | | | | | | |
| V _{i(VIF)(start1)(rms)} | VIF input signal voltage for minimum starting point of tuner takeover at pins VIF1 and VIF2 (RMS value) | I _{TAGC} = 120 μA; R _{TOP} = 22 kΩ or no R _{TOP} and –15 dB via I ² C-bus (see Table 13) | – | 2 | 5 | mV |
| V _{i(VIF)(start2)(rms)} | VIF input signal voltage for maximum starting point of tuner takeover at pins VIF1 and VIF2 (RMS value) | I _{TAGC} = 120 μA; R _{TOP} = 0 Ω or no R _{TOP} and +15 dB via I ² C-bus (see Table 13) | 45 | 90 | – | mV |
| V _{i(SIF)(start1)(rms)} | SIF input signal voltage for minimum starting point of tuner takeover at pins SIF1 and SIF2 (RMS value) | I _{TAGC} = 120 μA; R _{TOP} = 22 kΩ or no R _{TOP} and –15 dB via I ² C-bus (see Table 13) | – | 1 | 2.5 | mV |

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| SYMBOL | PARAMETER | CONDITIONS | MIN. | TYP. | MAX. | UNIT |
|--|---|---|------------------|-------------|------------------|--------------------------|
| $V_{i(\text{SIF})(\text{start2})(\text{rms})}$ | SIF input signal voltage for maximum starting point of tuner takeover at pins SIF1 and SIF2 (RMS value) | $I_{\text{TAGC}} = 120 \mu\text{A}$; $R_{\text{TOP}} = 0 \Omega$ or no R_{TOP} and +15 dB via I ² C-bus (see Table 13) | 22.5 | 45 | – | mV |
| QV_{TOP} | tuner takeover point accuracy | $I_{\text{TAGC}} = 120 \mu\text{A}$; $R_{\text{TOP}} = 10 \text{k}\Omega$ or no R_{TOP} and 0 dB via I ² C-bus (see Table 13) | 7 | 17 | 43 | mV |
| $\Delta QV_{\text{TOP}}/\Delta T$ | takeover point variation with temperature | $I_{\text{TAGC}} = 120 \mu\text{A}$ | – | 0.03 | 0.07 | dB/K |
| V_o | permissible output voltage | from external source | – | – | 8.8 | V |
| V_{sat} | saturation voltage | $I_{\text{TAGC}} = 450 \mu\text{A}$ | – | – | 0.5 | V |
| I_{sink} | sink current | no tuner gain reduction; $V_{\text{TAGC}} = 8.8 \text{V}$ | – | – | 0.75 | μA |
| | | maximum tuner gain reduction; $V_{\text{TAGC}} = 1 \text{V}$ | 450 | 600 | 750 | μA |
| ΔG_{IF} | IF slip by automatic gain control | tuner gain current from 20% to 80% | 3 | 5 | 8 | dB |
| AFC circuit and AGC monitor options (pin AFC); see Figs 9 and 10; notes 14 and 15 | | | | | | |
| $V_{\text{sat(ul)}}$ | upper limit saturation voltage | | $V_P - 0.6$ | $V_P - 0.3$ | – | V |
| $V_{\text{sat(ll)}}$ | lower limit saturation voltage | | – | 0.3 | 0.6 | V |
| $I_{o(\text{source})}$ | output source current | | 160 | 200 | 240 | μA |
| $I_{o(\text{sink})}$ | output sink current | | 160 | 200 | 240 | μA |
| TV MODE | | | | | | |
| AFC_{stps} | AFC control steepness | definition: $\Delta I_{\text{AFC}}/\Delta f_{\text{VIF}}$ | 0.85 | 1.05 | 1.25 | $\mu\text{A}/\text{kHz}$ |
| $Qf_{\text{VIF(a)}}$ | analog accuracy of AFC circuit | $I_{\text{AFC}} = 0$; $f_{\text{REF}} = 4 \text{MHz}$ | –20 | – | +20 | kHz |
| $Qf_{\text{VIF(d)}}$ | digital accuracy of AFC circuit via I ² C-bus | $I_{\text{AFC}} = 0$; $f_{\text{REF}} = 4 \text{MHz}$; 1 digit = 25 kHz | –20 – 1 digit | – | +20 + 1 digit | kHz |
| RADIO MODE | | | | | | |
| AFC_{stps} | AFC control steepness | definition: $\Delta I_{\text{AFC}}/\Delta f_{\text{RIF}}$ | 0.85 | 1.05 | 1.25 | $\mu\text{A}/\text{kHz}$ |
| $Qf_{\text{RIF(a)}}$ | analog accuracy of AFC circuit | $I_{\text{AFC}} = 0$; $f_{\text{REF}} = 4 \text{MHz}$ | –10 | – | +10 | kHz |
| $Qf_{\text{RIF(d)}}$ | digital accuracy of AFC circuit via I ² C-bus | $I_{\text{AFC}} = 0$; $f_{\text{REF}} = 4 \text{MHz}$; 1 digit = 25 kHz | –10 – 1 digit | – | +10 + 1 digit | kHz |
| $I_{o(\text{source})}$ | SIF or FM-AGC monitor source current | see Table 16 | – | – | 600 | mA |
| $I_{o(\text{sink})}$ | SIF or FM-AGC monitor sink current | see Table 16 | – | – | 270 | mA |
| SIF amplifier (pins SIF1 and SIF2) | | | | | | |
| $V_{i(\text{SIF})(\text{rms})}$ | SIF input voltage sensitivity (RMS value) | FM mode; –3 dB at intercarrier output pin SIOMAD | – | 30 | 70 | μV |
| | | AM mode; –3 dB at AF output pin AUD | – | 70 | 100 | μV |

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| SYMBOL | PARAMETER | CONDITIONS | MIN. | TYP. | MAX. | UNIT |
|---|--|---|------|------|------|------------|
| $V_{i(max)(rms)}$ | maximum input voltage (RMS value) | FM mode; 1 dB at intercarrier output pin SIOMAD | 50 | 70 | – | mV |
| | | AM mode; 1 dB at AF output pin AUD | 80 | 140 | – | mV |
| $V_{i(ovl)(rms)}$ | overload input voltage (RMS value) | note 2 | – | – | 320 | mV |
| $G_{SIF(cr)}$ | SIF gain control range | FM and AM mode | 60 | 66 | – | dB |
| $B_{SIF(-3dB)(ll)}$ | lower limit –3 dB SIF bandwidth | | – | 15 | – | MHz |
| $B_{SIF(-3dB)(ul)}$ | upper limit –3 dB SIF bandwidth | | – | 80 | – | MHz |
| $R_{i(dif)}$ | differential input resistance | note 3 | – | 2 | – | k Ω |
| $C_{i(dif)}$ | differential input capacitance | note 3 | – | 3 | – | pF |
| V_I | DC input voltage | | – | 1.93 | – | V |
| SIF-AGC detector | | | | | | |
| t_{resp} | AGC response time to an increasing or decreasing SIF step of 20 dB | FM or AM fast steps | | | | |
| | | increasing | – | 8 | – | ms |
| | | decreasing | – | 25 | – | ms |
| | | AM slow steps | | | | |
| increasing | – | 80 | – | ms | | |
| decreasing | – | 250 | – | ms | | |
| Single reference QSS intercarrier mixer (pin SIOMAD) | | | | | | |
| $V_{o(intc)(rms)}$ | IF intercarrier output level (RMS value) | QSS mode; SC ₁ ; SC ₂ off | 90 | 140 | 180 | mV |
| | | L standard; without modulation | 90 | 140 | 180 | mV |
| | | intercarrier mode; PC/SC ₁ = 20 dB; SC ₂ off; note 16 | – | 75 | – | mV |
| $B_{intc(-3dB)(ul)}$ | upper limit –3 dB intercarrier bandwidth | | 12 | 15 | – | MHz |
| $\Delta V_{r(SC)(rms)}$ | residual sound carrier (RMS value) | fundamental wave and harmonics | | | | |
| | | QSS mode | – | 2 | 5 | mV |
| | | intercarrier mode | – | 2 | 5 | mV |
| $\Delta V_{r(PC)(rms)}$ | residual picture carrier (RMS value) | fundamental wave and harmonics | | | | |
| | | QSS mode | – | 2 | 5 | mV |
| | | intercarrier mode | – | 5 | 20 | mV |
| α_H | suppression of video signal harmonics | intercarrier mode; $f_{video} = 5$ MHz | 35 | 40 | – | dB |
| R_o | output resistance | note 3 | – | – | 30 | Ω |
| V_o | DC output voltage | | – | 2 | – | V |

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| SYMBOL | PARAMETER | CONDITIONS | MIN. | TYP. | MAX. | UNIT |
|---|---|---|------|--------------------|--------------------|------|
| $I_{bias(int)}$ | internal DC bias current for emitter follower | | 0.90 | 1.15 | – | mA |
| $I_{o(sink)(max)}$ | maximum AC output sink current | | 0.6 | 0.8 | – | mA |
| $I_{o(source)(max)}$ | maximum AC output source current | | 0.6 | 0.8 | – | mA |
| $I_{o(source)}$ | DC output source current | MAD2 activated; note 17 | 0.75 | 0.93 | 1.20 | mA |
| FM-PLL demodulator output; notes 15 and 18 to 22 | | | | | | |
| SOUND INTERCARRIER OUTPUT (PIN SIOMAD) | | | | | | |
| $V_{FM(rms)}$ | IF intercarrier level for gain controlled operation of FM-PLL (RMS value) | corresponding PC/SC ratio at input pins VIF1 and VIF2 is 7 to 47 dB | 3.2 | – | 320 | mV |
| $V_{FM(lock)(rms)}$ | IF intercarrier level for lock-in of PLL (RMS value) | | – | – | 2 | mV |
| $V_{FM(det)(rms)}$ | IF intercarrier level for FM carrier detect (RMS value) | see Table 6 | – | – | 2.3 | mV |
| f_{FM} | sound intercarrier operating FM frequencies | see Tables 11 and 14 | – | 4.5 | – | MHz |
| | | | – | 5.5 | – | MHz |
| | | | – | 6.0 | – | MHz |
| | | | – | 6.5 | – | MHz |
| | | | – | 10.7 | – | MHz |
| IF INTERCARRIER INPUT (PIN FMIN) | | | | | | |
| $V_{i(FM)(rms)}$ | IF intercarrier input voltage for gain controlled operation of FM-PLL (RMS value) | radio mode and FM external mode; see Table 16 | 1 | – | 100 | mV |
| $V_{FM(lock)(rms)}$ | IF intercarrier level for lock-in of PLL (RMS value) | | – | – | 0.7 | mV |
| $V_{FM(det)(rms)}$ | IF intercarrier level for FM carrier detect (RMS value) | see Table 6 | – | – | 0.8 | mV |
| AUDIO OUTPUT (PIN AUD) | | | | | | |
| $V_{o(AF)(rms)}$ | AF output voltage (RMS value) | 25 kHz FM deviation; 75 μ s de-emphasis | 400 | 500 | 600 | mV |
| | | 27 kHz FM deviation; 50 μ s de-emphasis | 430 | 540 | 650 | mV |
| | | radio mode; 22.5 kHz modulation | 200 | 250 | 300 | mV |
| $V_{o(AF)(cl)(rms)}$ | AF output clipping level (RMS value) | THD < 1.5% | 1.3 | 1.4 | – | V |
| $\Delta V_{o(AF)}/\Delta T$ | AF output voltage variation with temperature | | – | 3×10^{-3} | 7×10^{-3} | dB/K |

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| SYMBOL | PARAMETER | CONDITIONS | MIN. | TYP. | MAX. | UNIT |
|----------------------------------|--|--|------|------|-----------|-------------|
| THD | total harmonic distortion | 75 μ s de-emphasis; FM deviation: for TV mode 25 kHz and for radio mode 22.5 kHz | – | 0.15 | 0.50 | % |
| Δf_{AF} | frequency deviation | THD < 1.5%; note 19 | – | – | ± 55 | kHz |
| | | –6 dB AF output via I ² C-bus; note 19 | – | – | ± 110 | kHz |
| $B_{AF(-3dB)}$ | –3 dB AF bandwidth | without de-emphasis; measured with FM-PLL filter of Fig.23 | 80 | 100 | – | kHz |
| $S/N_{W(AF)}$ | weighted signal-to-noise ratio of audio signal | FM-PLL only; 27 kHz FM deviation; 50 μ s de-emphasis | 52 | 56 | – | dB |
| | | black picture; see Fig.19 | 50 | 56 | – | dB |
| $S/N_{UW(AF)}$ | unweighted signal-to-noise ratio | radio mode; 22.5 kHz modulation | – | 58 | – | dB |
| $\Delta V_{r(SC)(rms)}$ | residual sound carrier (RMS value) | fundamental wave and harmonics; without de-emphasis | – | – | 2 | mV |
| $\alpha_{AM(sup)}$ | AM suppression of FM demodulator | referenced to 27 kHz FM deviation; 50 μ s de-emphasis; AM: f = 1 kHz; m = 54% | 40 | 46 | – | dB |
| $PSRR_{FM}$ | power supply ripple rejection | $f_{ripple} = 70$ Hz; see Fig.4 | 14 | 20 | – | dB |
| FM-PLL FILTER (PIN FMPLL) | | | | | | |
| V_{loop} | DC loop voltage | | 1.5 | – | 3.3 | V |
| $I_{o(source)(PD)(max)}$ | maximum phase detector output source current | | – | 60 | – | μ A |
| $I_{o(sink)(PD)(max)}$ | maximum phase detector output sink current | | – | 60 | – | μ A |
| $I_{o(source)(DAH)}$ | output source current of digital acquisition help | | – | 55 | – | μ A |
| $I_{o(sink)(DAH)}$ | output sink current of digital acquisition help | | – | 55 | – | μ A |
| $t_{W(DAH)}$ | pulse width of digital acquisition help current | | – | 16 | – | μ s |
| $T_{cy(DAH)}$ | cycle time of digital acquisition help | | – | 64 | – | μ s |
| $K_{O(FM)}$ | VCO steepness | definition: $\Delta f_{FM}/\Delta V_{FMPLL}$ | – | 3.3 | – | MHz/V |
| $K_{D(FM)}$ | phase detector steepness | definition: $\Delta I_{FMPLL}/\Delta \phi_{FM}$ | – | 4 | – | μ A/rad |

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| SYMBOL | PARAMETER | CONDITIONS | MIN. | TYP. | MAX. | UNIT |
|--------------------------------------|---|--|------|------|------|------|
| Audio amplifier | | | | | | |
| DE-EMPHASIS NETWORK (PIN DEEM) | | | | | | |
| R _o | output resistance | 50 μs de-emphasis; see Table 12 | 4.4 | 5.0 | 5.6 | kΩ |
| | | 75 μs de-emphasis; see Table 12 | 6.6 | 7.5 | 8.4 | kΩ |
| V _{AF(rms)} | audio signal (RMS value) | f _{AF} = 400 Hz; V _{AUD} = 500 mV | – | 170 | – | mV |
| V _O | DC output voltage | | – | 2.37 | – | V |
| AF DECOUPLING (PIN AFD) | | | | | | |
| V _{dec} | DC decoupling voltage | dependent on f _{FM} intercarrier frequency | 1.5 | – | 3.3 | V |
| I _L | leakage current | ΔV _{O(AUD)} < ±50 mV | – | – | ±25 | nA |
| I _{ch(max)} | maximum charge current | | 1.15 | 1.50 | 1.85 | μA |
| I _{dch(max)} | maximum discharge current | | 1.15 | 1.50 | 1.85 | μA |
| AUDIO OUTPUT (PIN AUD) | | | | | | |
| R _o | output resistance | note 3 | – | – | 300 | Ω |
| V _{O(AUD)} | DC output voltage | | – | 2.37 | – | V |
| R _L | load resistance | AC-coupled | 10 | – | – | kΩ |
| R _{L(DC)} | DC load resistance | | 100 | – | – | kΩ |
| C _L | load capacitance | | – | – | 1.5 | nF |
| B _{AF(-3dB)(ul)} | upper limit –3 dB AF bandwidth of audio amplifier | | 150 | – | – | kHz |
| B _{AF(-3dB)(ll)} | lower limit –3 dB AF bandwidth of audio amplifier | note 20 | – | – | 20 | Hz |
| α _{mute} | mute attenuation of AF signal | via I ² C-bus | 70 | 75 | – | dB |
| ΔV _{jump} | DC jump voltage for switching AF output to mute state or vice versa | activated by digital acquisition help or via I ² C-bus mute | – | ±50 | ±150 | mV |
| FM operation; notes 21 and 23 | | | | | | |
| INTERCARRIER AF PERFORMANCE; note 24 | | | | | | |
| S/N _w | weighted signal-to-noise ratio | PC/SC ratio is 21 to 27 dB at pins VIF1 and VIF2 | | | | |
| | | black picture | 50 | 56 | – | dB |
| | | white picture | 45 | 51 | – | dB |
| | | 6 kHz sine wave (black-to-white modulation) | 40 | 46 | – | dB |
| | | sound carrier subharmonics; f = 2.75 MHz ±3 kHz | 35 | 40 | – | dB |

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| SYMBOL | PARAMETER | CONDITIONS | MIN. | TYP. | MAX. | UNIT |
|--|--|---|------|------|------|------|
| SINGLE REFERENCE QSS AF PERFORMANCE; notes 25 and 26 | | | | | | |
| S/N _{W(SC1)} | weighted signal-to-noise ratio for SC ₁ | PC/SC ₁ ratio at pins VIF1 and VIF2; 27 kHz (54% FM deviation); "CCIR 468" | 40 | – | – | dB |
| | | black picture | 53 | 58 | – | dB |
| | | white picture | 50 | 53 | – | dB |
| | | 6 kHz sine wave (black-to-white modulation) | 44 | 48 | – | dB |
| | | 250 kHz square wave (black-to-white modulation) | 40 | 45 | – | dB |
| | | sound carrier subharmonics; f = 2.75 MHz ±3 kHz | 45 | 51 | – | dB |
| S/N _{W(SC2)} | weighted signal-to-noise ratio for SC ₂ | PC/SC ₂ ratio at pins VIF1 and VIF2; 27 kHz (54% FM deviation); "CCIR 468" | 40 | – | – | dB |
| | | black picture | 48 | 55 | – | dB |
| | | white picture | 46 | 51 | – | dB |
| | | 6 kHz sine wave (black-to-white modulation) | 42 | 46 | – | dB |
| | | 250 kHz square wave (black-to-white modulation) | 29 | 34 | – | dB |
| | | sound carrier subharmonics; f = 2.75 MHz ±3 kHz | 44 | 50 | – | dB |
| | | sound carrier subharmonics; f = 2.87 MHz ±3 kHz | 46 | 52 | – | dB |
| | | sound carrier subharmonics; f = 2.87 MHz ±3 kHz | 45 | 51 | – | dB |
| AM operation | | | | | | |
| L STANDARD (PIN AUD); see Figs 20 and 21; note 27 | | | | | | |
| V _{o(AF)(rms)} | AF output voltage (RMS value) | 54% modulation | 400 | 500 | 600 | mV |
| THD | total harmonic distortion | 54% modulation | – | 0.5 | 1.0 | % |
| B _{AF(-3dB)} | -3 dB AF bandwidth | | 100 | 125 | – | kHz |
| S/N _{W(AF)} | weighted signal-to-noise ratio of audio signal | in accordance with "CCIR 468" | 45 | 50 | – | dB |

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| SYMBOL | PARAMETER | CONDITIONS | MIN. | TYP. | MAX. | UNIT |
|---|--|---------------------------------------|------|------|-----------------|------|
| V _{O(AUD)} | DC potential voltage | | – | 2.37 | – | V |
| PSRR _{AM} | power supply ripple rejection | see Fig.4 | 20 | 26 | – | dB |
| Reference frequency input (pin REF) | | | | | | |
| V _I | DC input voltage | | 2.3 | 2.6 | 2.9 | V |
| R _i | input resistance | note 3 | – | 5 | – | kΩ |
| R _{x_{tal}} | resonance resistance of crystal | operation as crystal oscillator | – | – | 200 | Ω |
| C _x | pull-up/down capacitance | note 28 | – | – | – | pF |
| f _{ref} | reference signal frequency | note 29 | – | 4 | – | MHz |
| Δf _{ref} | tolerance of reference signal frequency | note 15 | – | – | ±0.1 | % |
| V _{ref(rms)} | reference signal voltage (RMS value) | operation as input terminal | 80 | – | 400 | mV |
| R _{o(ref)} | output resistance of reference signal source | | – | – | 4.7 | kΩ |
| C _K | decoupling capacitance to external reference signal source | operation as input terminal | 22 | 100 | – | pF |
| I²C-bus transceiver (pins SDA and SCL); notes 30 and 31 | | | | | | |
| f _{SCL} | SCL clock frequency | | 0 | – | 400 | kHz |
| V _{IH} | HIGH-level input voltage | | 3 | – | V _{CC} | V |
| V _{IL} | LOW-level input voltage | | –0.3 | – | +1.5 | V |
| I _{IH} | HIGH-level input current | | –10 | – | +10 | μA |
| I _{IL} | LOW-level input current | | –10 | – | +10 | μA |
| V _{OL} | LOW-level output voltage | I _{OL} = 3 mA | – | – | 0.4 | V |
| I _{o(sink)} | output sink current | V _P = 0 V | – | – | 10 | μA |
| I _{o(source)} | output source current | V _P = 0 V | – | – | 10 | μA |
| Output ports (pins OP1 and OP2); note 32 | | | | | | |
| V _{OL} | LOW-level output voltage | I _{OL} = 2 mA (sink current) | – | – | 0.4 | V |
| V _{OH} | HIGH-level output voltage | | – | – | 6 | V |
| I _{o(sink)} | output sink current | | – | – | 2 | mA |
| I _{o(sink/source)(max)} | maximum output sink or source current | pin OP2 functions as VIF-AGC output | – | – | 10 | μA |

Notes

1. Values of video and sound parameters can be decreased at V_P = 4.5 V.
2. Level headroom for input level jumps during gain control setting.
3. This parameter is not tested during the production and is only given as application information for designing the receiver circuit.

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4. Loop bandwidth BL = 70 kHz (damping factor d = 1.9; calculated with sync level within gain control range). Calculation of the VIF-PLL filter can be done by use of the following formula:

$$BL_{-3dB} = \frac{1}{2\pi} K_O K_D R, \text{ valid for } d \geq 1.2$$

$$d = \frac{1}{2} R \sqrt{K_O K_D C},$$

where:

K_O is the VCO steepness $\left(\frac{\text{rad}}{\text{V}}\right)$ or $\left(2\pi \frac{\text{Hz}}{\text{V}}\right)$; K_D is the phase detector steepness $\left(\frac{\mu\text{A}}{\text{rad}}\right)$;

R is the loop resistor; C is the loop capacitor; BL_{-3dB} is the loop bandwidth for -3 dB; d is the damping factor.

5. $V_{i(VIF)} = 10$ mV (RMS); $\Delta f = 1$ MHz (VCO frequency offset related to picture carrier frequency); white picture video modulation.
6. Condition: luminance range (5 steps) from 0% to 100%.
7. S/N is the ratio of black-to-white amplitude to the black level noise voltage (RMS value on pin CVBS). B = 5 MHz (B/G, I and D/K standard). Noise analyzer setting: 200 kHz high-pass and SC-trap switched on.
8. The intermodulation figures are defined for:
- $f = 1.1$ MHz (referenced to black and white signal) as $\alpha_{IM} = 20 \log\left(\frac{V_0 \text{ at } 4.4 \text{ MHz}}{V_0 \text{ at } 1.1 \text{ MHz}}\right) + 3.6$ dB
 - $f = 3.3$ MHz (referenced to colour carrier) as $\alpha_{IM} = 20 \log\left(\frac{V_0 \text{ at } 4.4 \text{ MHz}}{V_0 \text{ at } 3.3 \text{ MHz}}\right)$
9. Measurements taken with SAW filter M1963M (sound shelf: 20 dB); loop bandwidth BL = 70 kHz.
- Modulation Vestigial Side-Band (VSB); sound carrier off; $f_{\text{video}} > 0.5$ MHz.
 - Sound carrier on; $f_{\text{video}} = 10$ kHz to 10 MHz.
10. AC load; $C_L < 20$ pF and $R_L > 1$ k Ω . The sound carrier frequencies (depending on TV standard) are attenuated by the integrated sound carrier traps (see Figs 13 to 18; $|H(s)|$ is the absolute value of transfer function).
11. The sound carrier trap can be bypassed by switching the I²C-bus. In this way the full composite video spectrum appears at pin CVBS. The amplitude is 1.1 V (p-p).
12. If selected by the I²C-bus, the VIF-AGC voltage can be monitored at pin OP2, and pin OP1 can be used as input. In this case, both pins cannot be used for the normal port function.
13. The response time is valid for a VIF input level range from 200 μ V to 70 mV.
14. To match the AFC output signal to different tuning systems a current source output is provided. The test circuit is given in Fig.9. The AFC slope (voltage per frequency) can be changed by resistors R1 and R2.
15. The tolerance of the reference frequency determines the accuracy of the VIF-AFC, FM demodulator centre frequency and maximum FM deviation.

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16. The intercarrier output signal at pin SIOMAD can be calculated by the following formula taking into account the internal video signal with 1.1 V (p-p) as a reference:

$$V_{o(intc)} = 1.1 \text{ V (p-p)} \times \frac{1}{2\sqrt{2}} \times 10^{\frac{\frac{V_{i(SC)}(dB) + 6 \text{ dB} \pm 3 \text{ dB}}{V_{i(PC)}}}{20}} \quad (\text{RMS})$$

where:

$\frac{1}{2\sqrt{2}}$ is the correction term for RMS value, $\frac{V_{i(SC)}(dB)}{V_{i(PC)}}$ is the sound-to-picture carrier ratio at pins VIF1 and VIF2 in dB, 6 dB is the correction term of internal circuitry and ± 3 dB is the tolerance of video output and intercarrier output $V_{o(intc)(rms)}$.

17. For normal operation (with the I²C-bus) no DC load at pin SIOMAD is allowed. The second module address (MAD2) will be activated by the application of a 2.2 k Ω resistor between pin SIOMAD and ground. If this MAD2 is activated, also the power-on set-up state activates a VIF frequency of 58.75 MHz.
18. SIF input level is 10 mV (RMS); VIF input level is 10 mV (RMS) unmodulated.
19. Measured with an FM deviation of 25 kHz and the typical AF output voltage of 500 mV (RMS). The AF output signal can be attenuated by 6 dB to 250 mV (RMS) via the I²C-bus. For handling a frequency deviation of more than 55 kHz, the AF output signal has to be reduced in order to avoid clipping (THD < 1.5%).
20. The lower limit of the audio bandwidth depends on the value of the capacitor at pin AFD. A value of $C_{AF} = 470$ nF leads to $f_{AF(-3dB)} \approx 20$ Hz and $C_{AF} = 220$ nF leads to $f_{AF(-3dB)} \approx 40$ Hz.
21. For all S/N measurements the used VIF modulator has to meet the following specifications:
- Incidental phase modulation for black-to-white jump less than 0.5 degrees.
 - QSS AF performance, measured with the television demodulator AMF2 (audio output, weighted S/N ratio) better than 60 dB (at deviation 27 kHz) for 6 kHz sine wave black-to-white video modulation.
 - Picture-to-sound carrier ratio $PC/SC_1 = 13$ dB (transmitter).
22. Calculation of the loop filter can be done approximately by use of the following formulae:

$$f_o = \frac{1}{2\pi} \sqrt{\frac{K_O K_D}{C_P}}$$

$$\vartheta = \frac{1}{2R \sqrt{K_O K_D C_P}}$$

$$BL_{-3dB} = f_o (1.55 - \vartheta^2)$$

The formulae are only valid under the following conditions:

$$\vartheta \leq 1 \text{ and } C_S > 5C_P$$

where:

K_O is the VCO steepness $\left(\frac{\text{rad}}{\text{V}}\right)$ or $\left(2\pi \frac{\text{Hz}}{\text{V}}\right)$; K_D is the phase detector steepness $\left(\frac{\mu\text{A}}{\text{rad}}\right)$;

R is the loop resistor; C_S is the series capacitor; C_P is the parallel capacitor; f_o is the natural frequency of PLL; BL_{-3dB} is the loop bandwidth for -3 dB; ϑ is the damping factor. For examples, see Table 20.

23. The PC/SC ratio is calculated as the addition of TV transmitter PC/SC₁ ratio and SAW filter PC/SC₁ ratio. This PC/SC ratio is necessary to achieve the S/N_W values as noted. A different PC/SC ratio will change these values.
24. Measurements taken with SAW filter G1984 (Siemens) for vision and sound IF (sound shelf: 14 dB). Picture-to-sound carrier ratio of transmitter PC/SC = 13 dB. Input level on pins VIF1 and VIF2 of $V_{i(SIF)} = 10$ mV (RMS) sync level, 27 kHz FM deviation for sound carrier, $f_{AF} = 400$ Hz. Measurements in accordance with "CCIR 468". De-emphasis is 50 μs .

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25. The QSS signal output on pin SIOMAD is analysed by a test demodulator TDA9820. The S/N ratio of this device is more than 60 dB, related to a deviation of ± 27 kHz, in accordance with "CCIR 468".
26. Measurements taken with SAW filter K3953 for vision IF (suppressed sound carrier) and K9453 for sound IF (suppressed picture carrier). Input level $V_{i(SIF)} = 10$ mV (RMS), 27 kHz (54% FM deviation).
27. Measurements taken with SAW filter K9453 (Siemens) for AM sound IF (suppressed picture carrier).
28. The value of C_x determines the accuracy of the resonance frequency of the crystal. It depends on the used type of crystal.
29. Pin REF is able to operate as a 1-pin crystal oscillator input as well as an external reference signal input, e.g. from the tuning system.
30. The SDA and SCL lines will not be pulled down if V_{CC} is switched off.
31. The AC characteristics are in accordance with the I²C-bus specification for fast mode (maximum clock frequency is 400 kHz). Information about the I²C-bus can be found in the brochure "The I²C-bus and how to use it" (order number 9398 393 40011).
32. Port P1 and port P2 are open-collector outputs.

Table 20 Examples to note 22 (FM-PLL filter)

| BL _{-3dB} (kHz) | C _S (nF) | C _P (pF) | R (k Ω) | ϑ |
|--------------------------|---------------------|---------------------|-----------------|-------------|
| 100 | 10 | 390 | 5.6 | 0.5 |
| 160 | 10 | 150 | 8.2 | 0.5 |

Table 21 Input frequencies and carrier ratios

| DESCRIPTION | SYMBOL | B/G STANDARD | M/N STANDARD | L STANDARD | L ACCENT STANDARD | UNIT |
|--------------------------------|-----------------|--------------|----------------|------------|-------------------|------|
| VIF carrier | f_{PC} | 38.9 | 45.75 or 58.75 | 38.9 | 33.9 | MHz |
| SIF carrier | f_{SC1} | 33.4 | 41.25 or 54.25 | 32.4 | 40.4 | MHz |
| | f_{SC2} | 33.158 | – | – | – | MHz |
| Picture-to-sound carrier ratio | SC ₁ | 13 | 7 | 10 | 10 | dB |
| | SC ₂ | 20 | – | – | – | dB |

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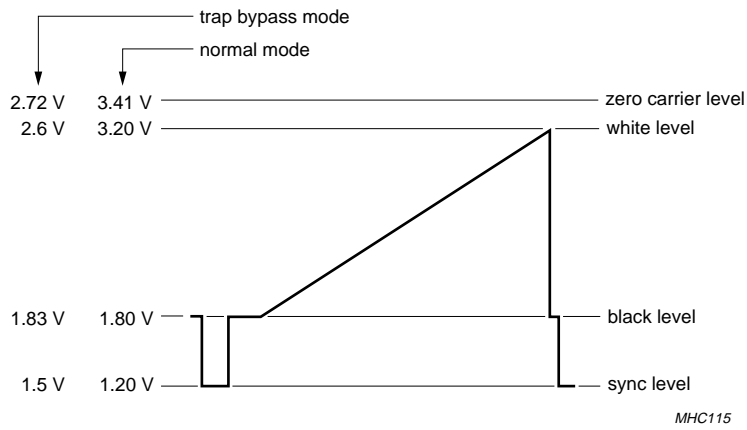


Fig.3 Typical video signal levels on output pin CVBS (sound carrier off).

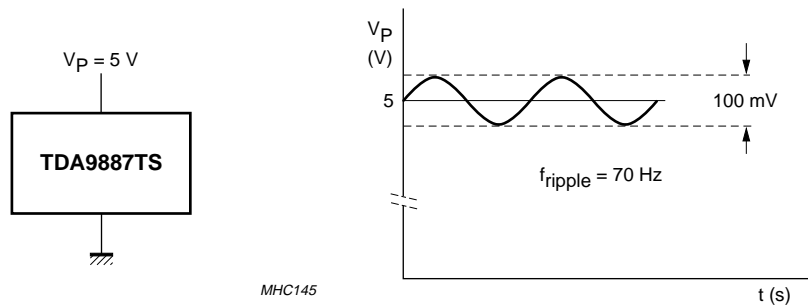
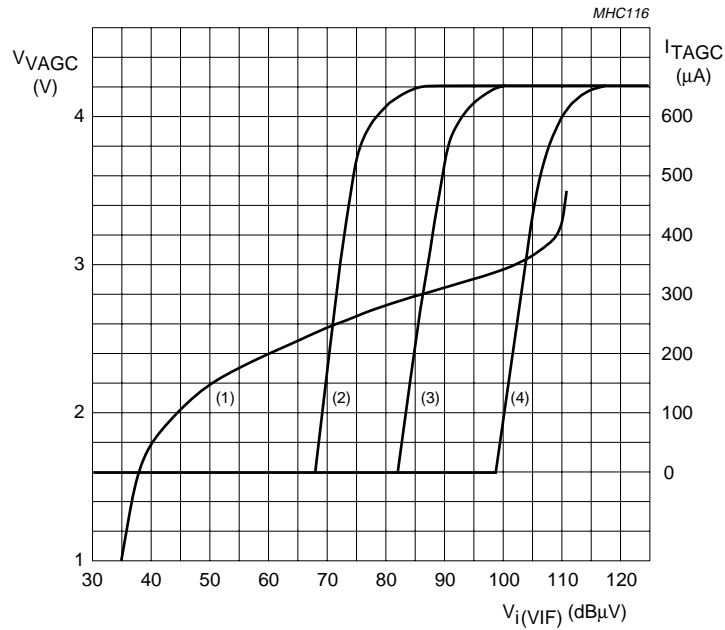


Fig.4 Ripple rejection condition.

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- (1) V_{VAGC} is VIF-AGC voltage and can only be measured at pin OP2 controlled by the I²C-bus (see Table 15).
- (2) I_{TAGC} is tuner current in TV mode with R_{TOP} = 22 kΩ or setting via I²C-bus at -15 dB.
- (3) I_{TAGC} is tuner current in TV mode with R_{TOP} = 10 kΩ or setting via I²C-bus at 0 dB.
- (4) I_{TAGC} is tuner current in TV mode with R_{TOP} = 0 kΩ or setting via I²C-bus at +15 dB.

Fig.5 Typical VIF and tuner AGC characteristic.

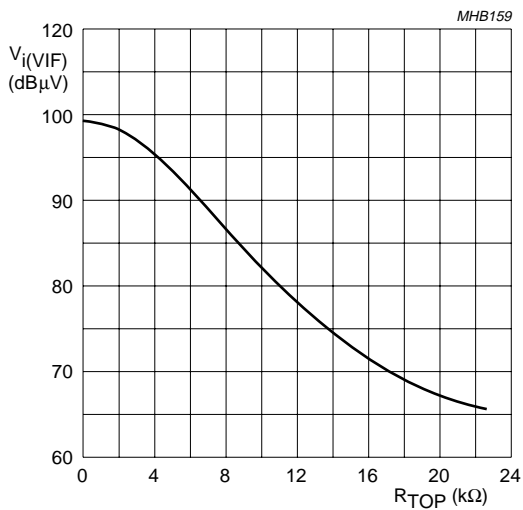


Fig.6 Typical tuner takeover point as a function of resistor R_{TOP}.

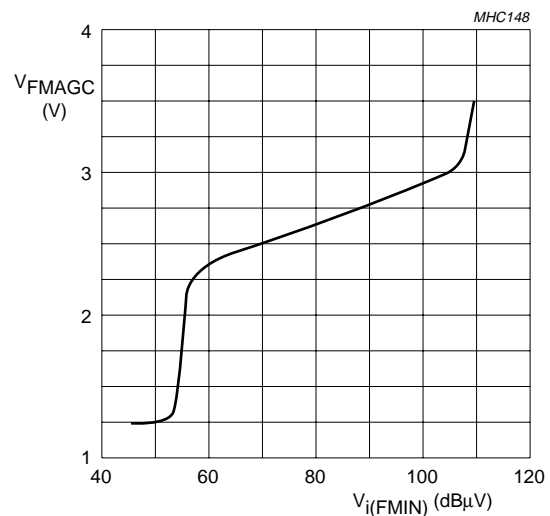
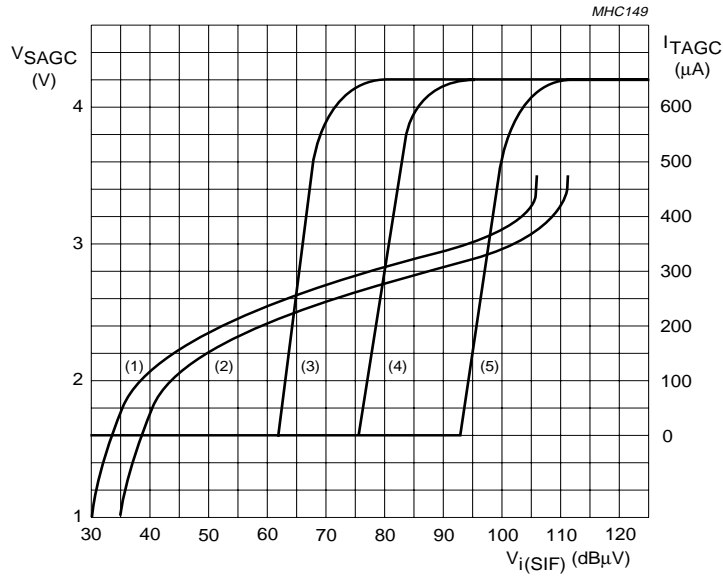


Fig.7 Typical FM-AGC characteristic.

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- (1) V_{SAGC} is SIF-AGC voltage in FM mode.
- (2) V_{SAGC} is SIF-AGC voltage in AM mode.
- (3) I_{TAGC} is tuner current in TV mode with $R_{TOP} = 22\text{ k}\Omega$ or setting via I²C-bus at -15 dB.
- (4) I_{TAGC} is tuner current in TV mode with $R_{TOP} = 10\text{ k}\Omega$ or setting via I²C-bus at 0 dB.
- (5) I_{TAGC} is tuner current in TV mode with $R_{TOP} = 0\text{ k}\Omega$ or setting via I²C-bus at +15 dB.

Fig.8 Typical SIF and tuner AGC characteristic.

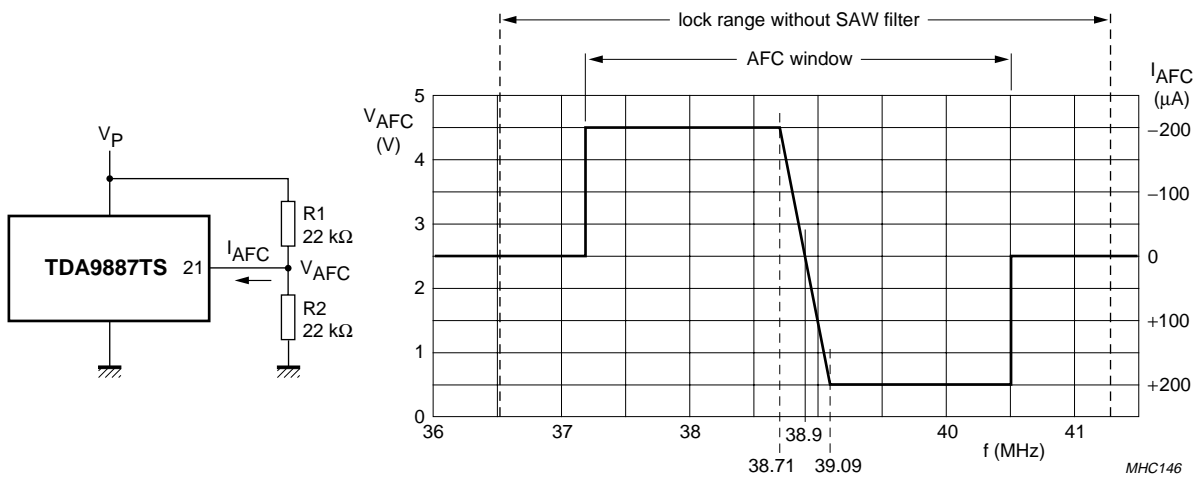


Fig.9 Typical analog AFC characteristic for VIF.

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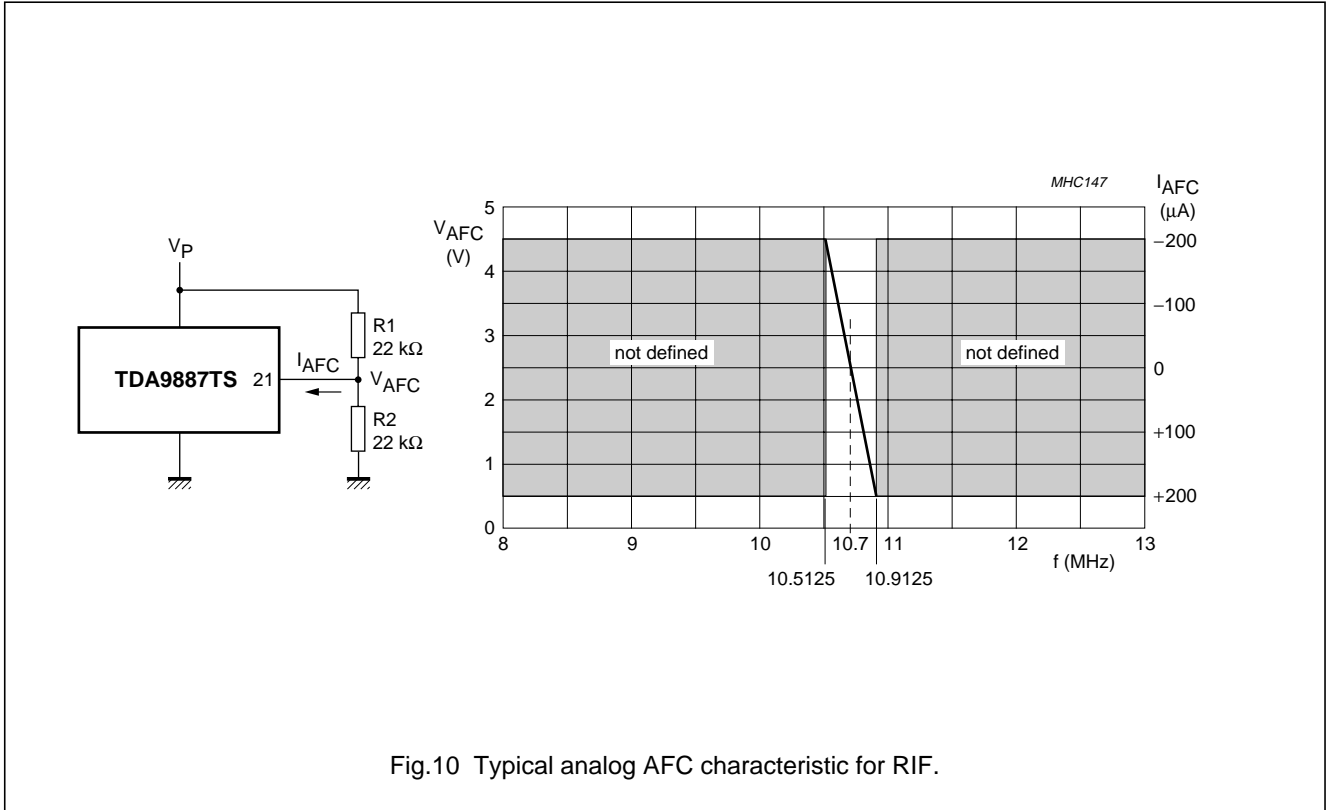


Fig.10 Typical analog AFC characteristic for RIF.

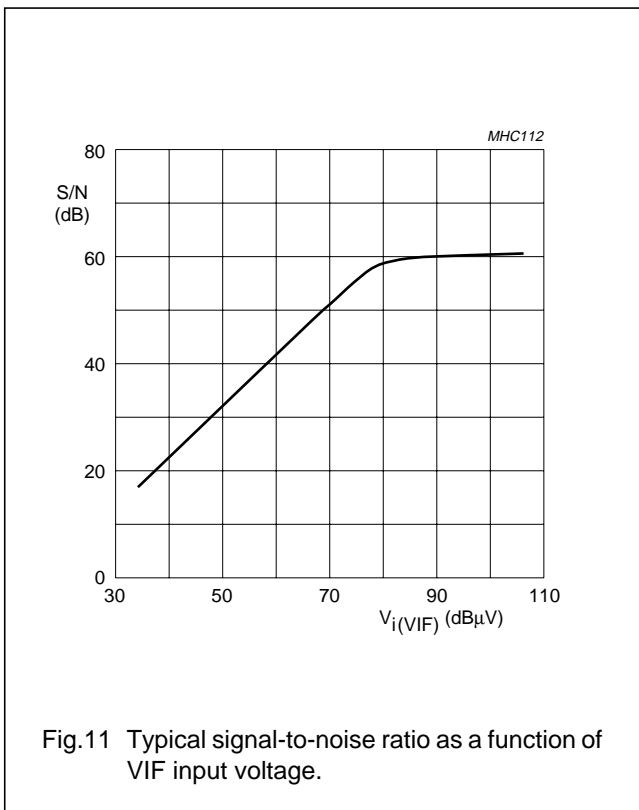
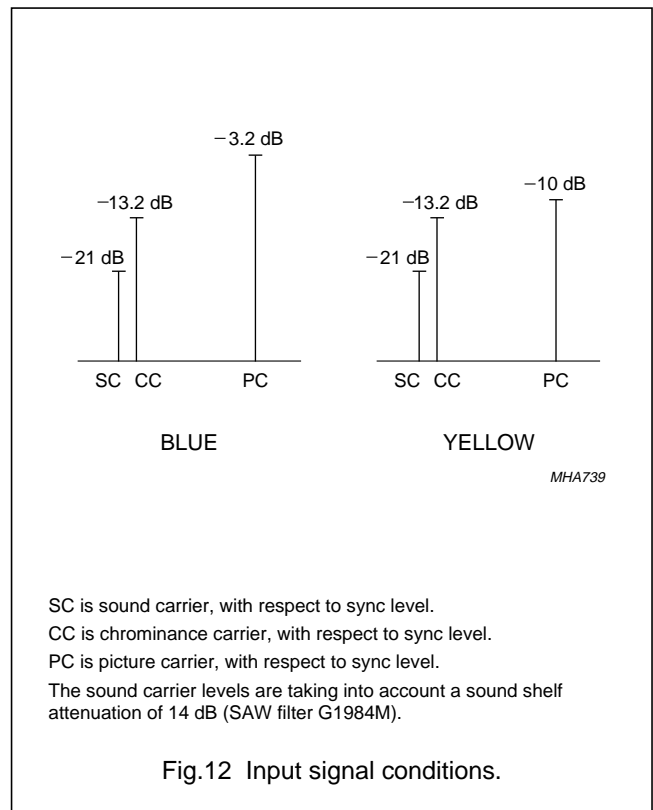


Fig.11 Typical signal-to-noise ratio as a function of VIF input voltage.



SC is sound carrier, with respect to sync level.
CC is chrominance carrier, with respect to sync level.
PC is picture carrier, with respect to sync level.
The sound carrier levels are taking into account a sound shelf attenuation of 14 dB (SAW filter G1984M).

Fig.12 Input signal conditions.

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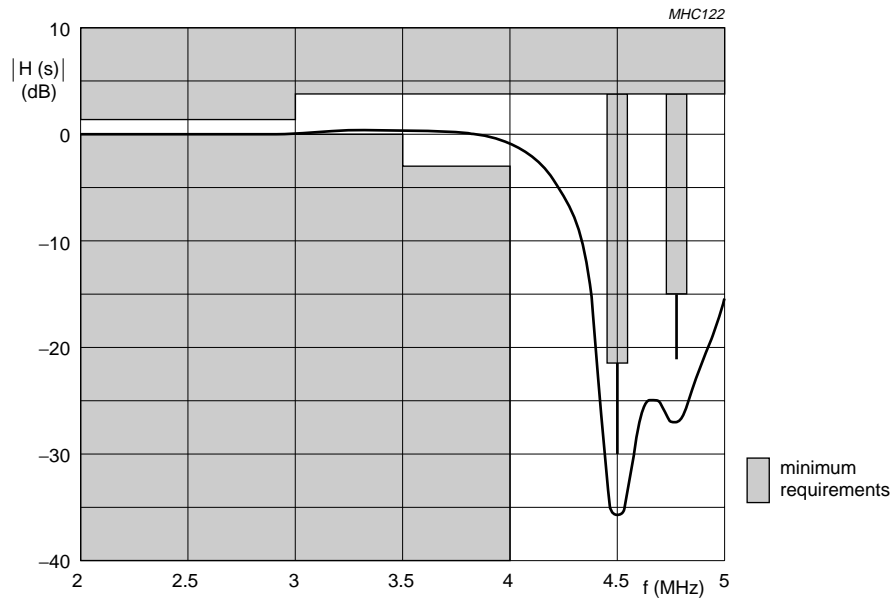
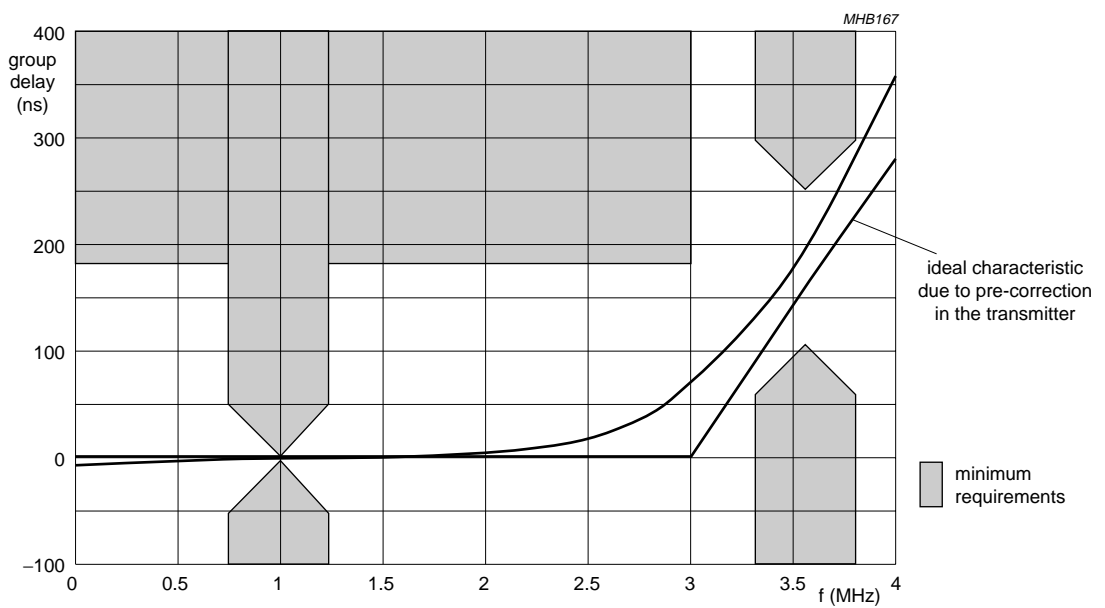


Fig.13 Typical amplitude response for sound trap at M/N standard (inclusive Korea).



Overall delay is not shown, here the maximum ripple is specified.

Fig.14 Typical group delay for sound trap at M/N standard.

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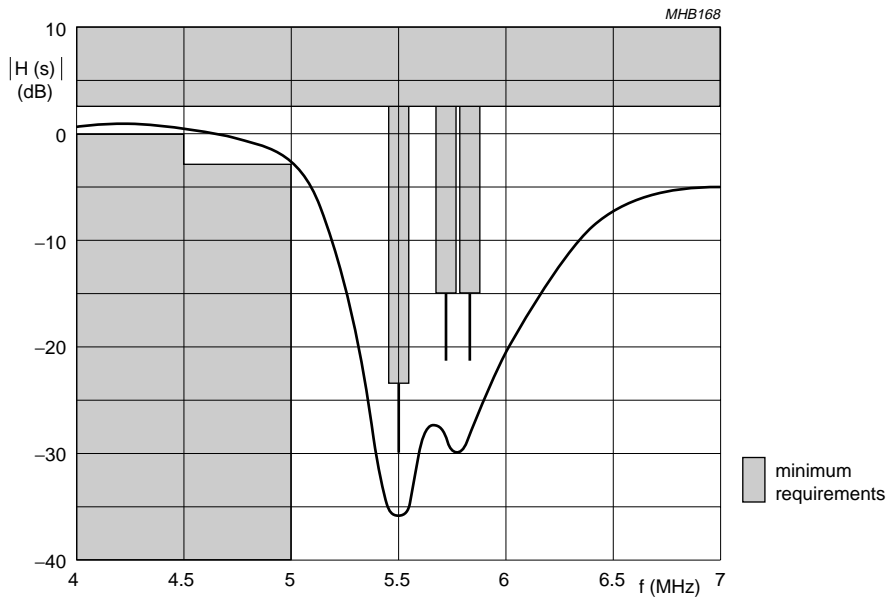
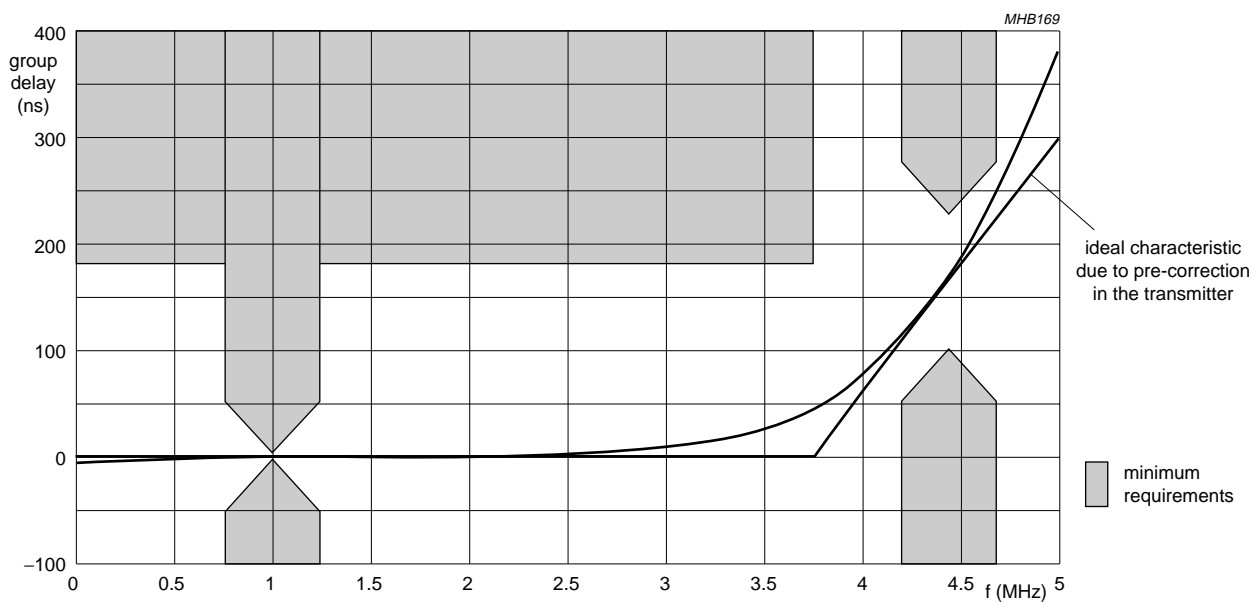


Fig.15 Typical amplitude response for sound trap at B/G standard.



Overall delay is not shown, here the maximum ripple is specified.

Fig.16 Typical group delay for sound trap at B/G standard.

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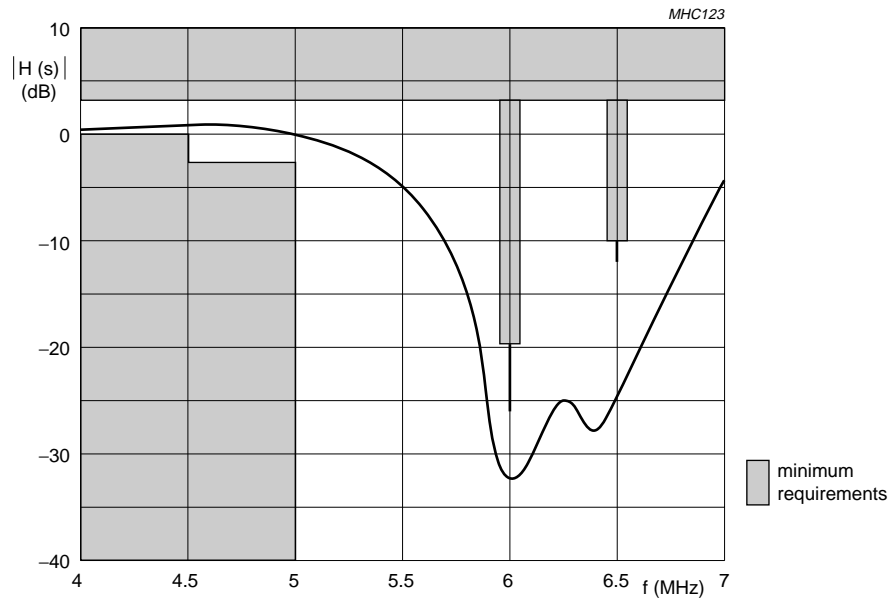


Fig.17 Typical amplitude response for sound trap at I standard.

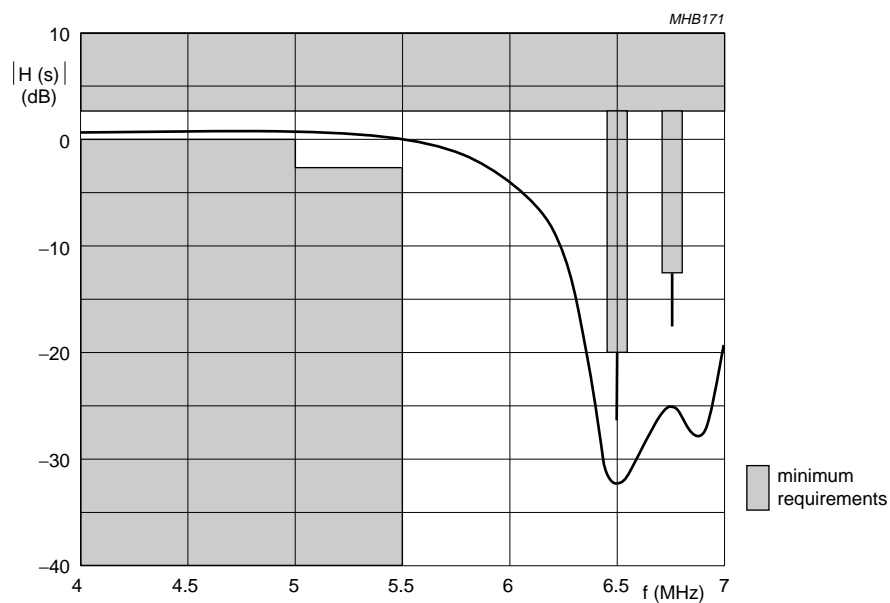
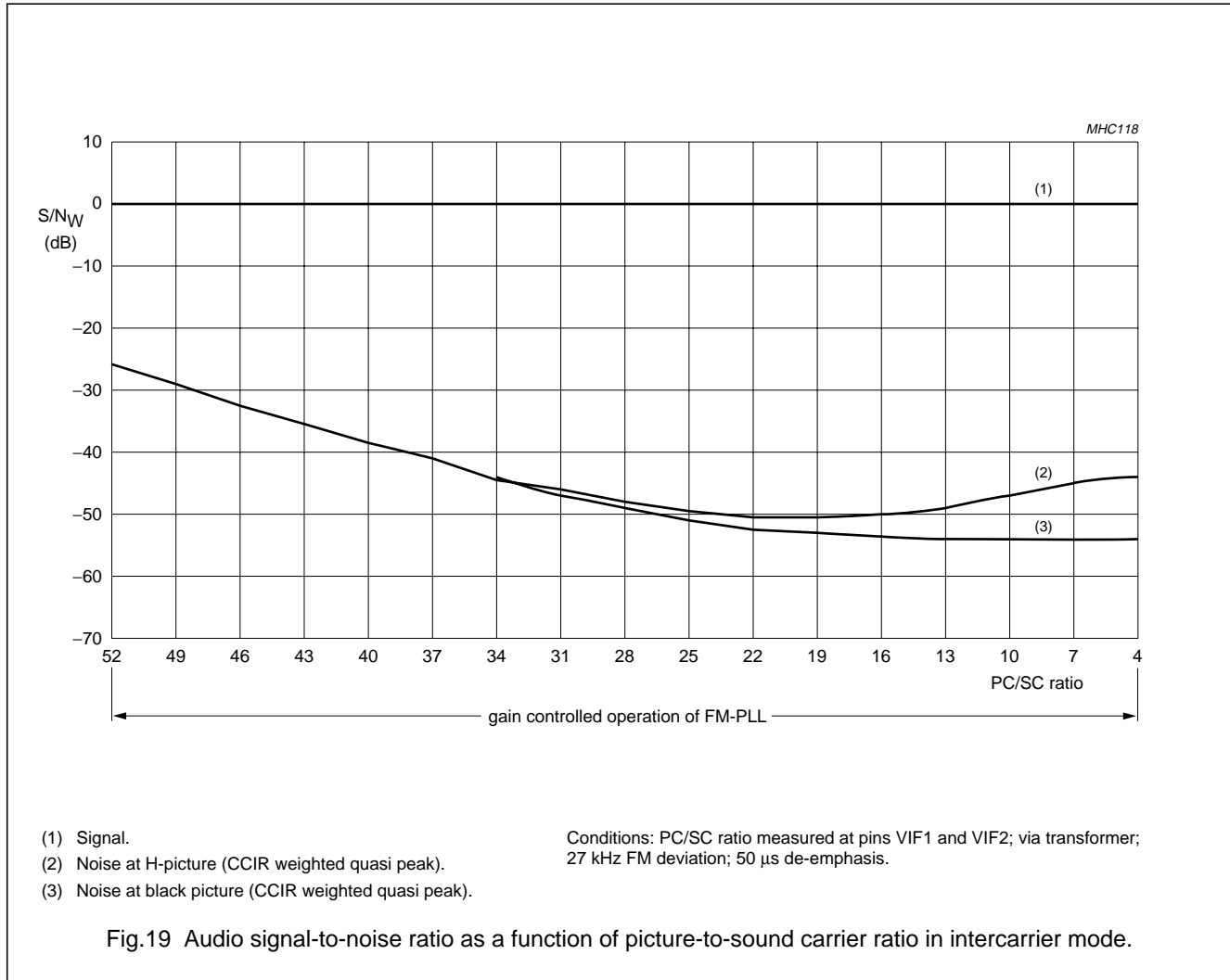


Fig.18 Typical amplitude response for sound trap at D/K standard.

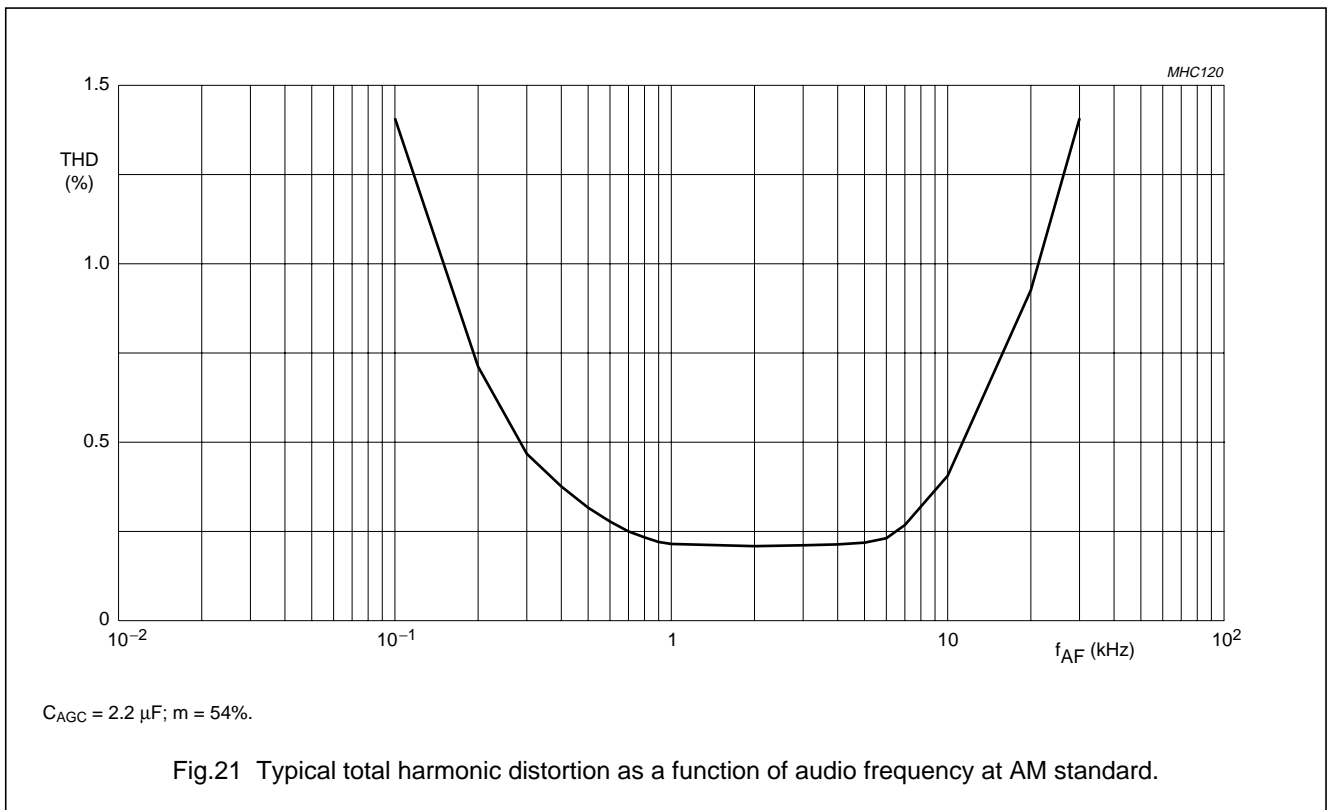
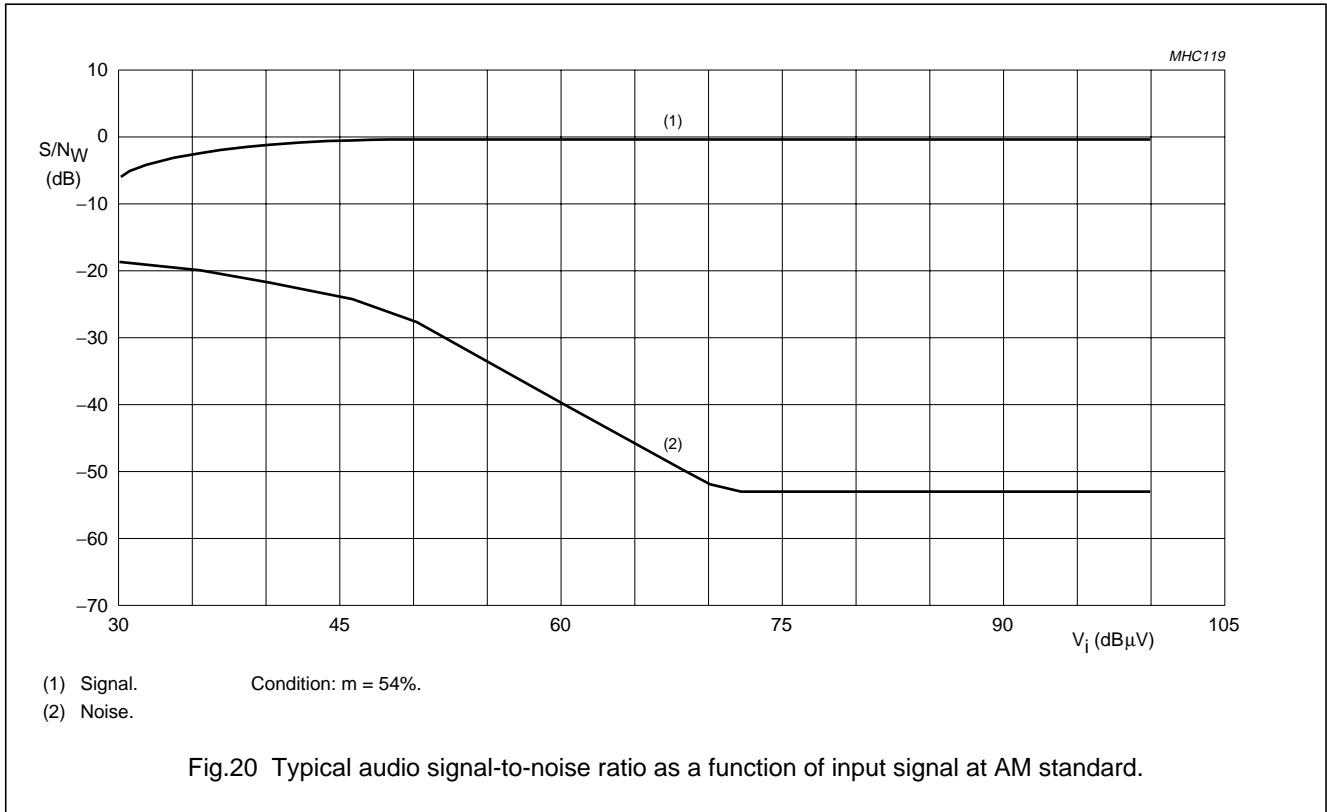
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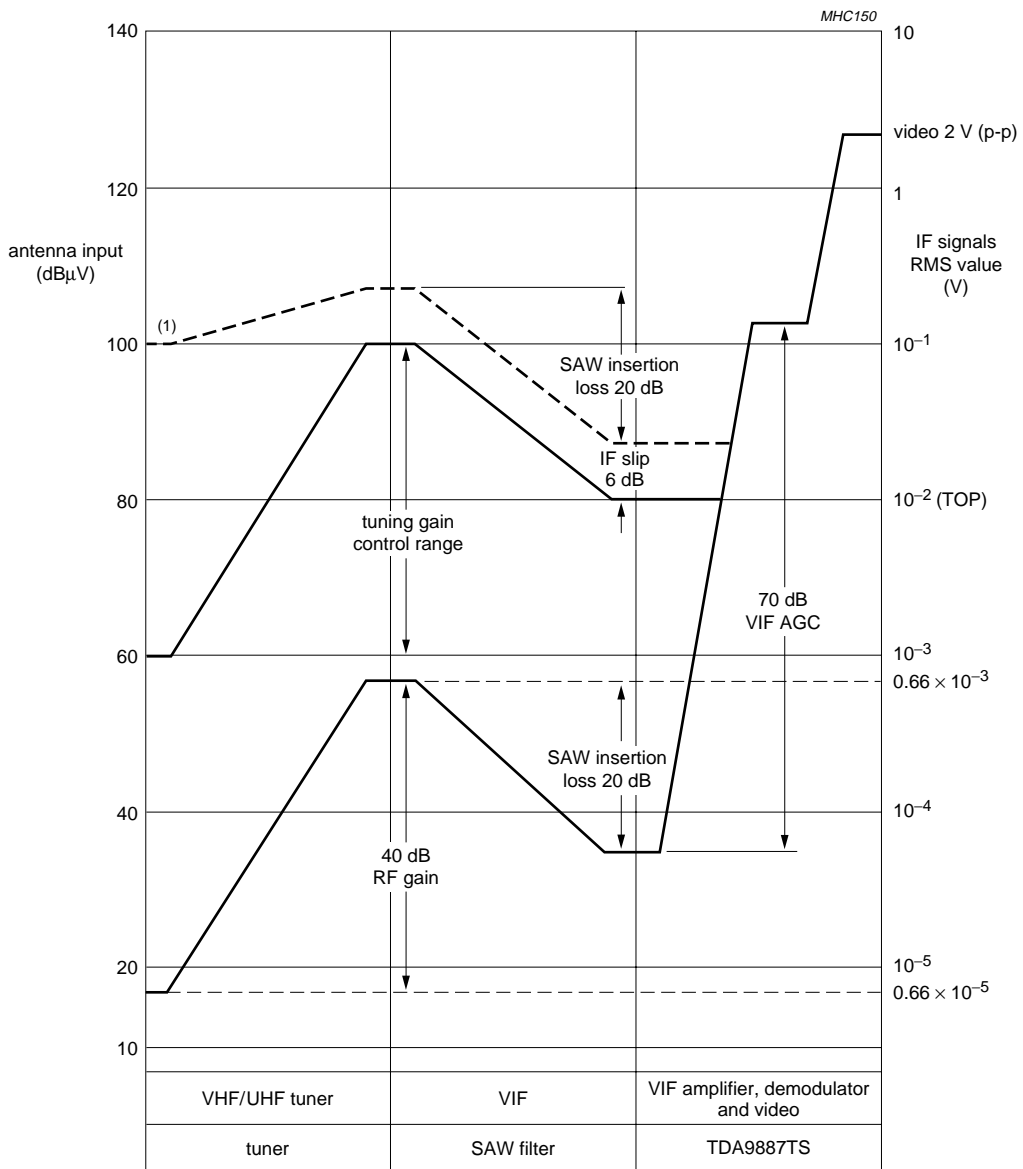
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(1) Depends on TOP.

Fig.22 Front-end level diagram.

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13 TEST AND APPLICATION INFORMATION

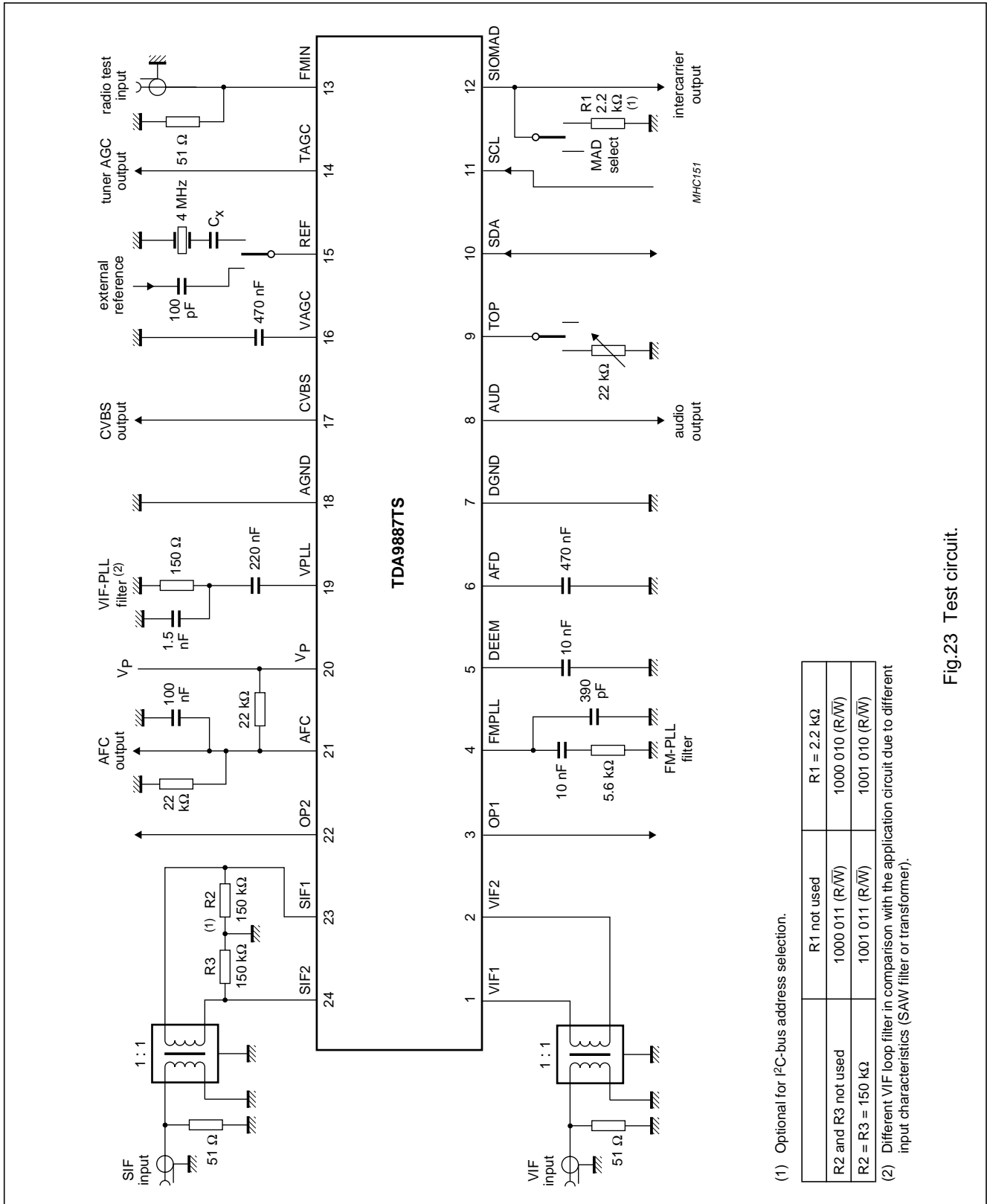
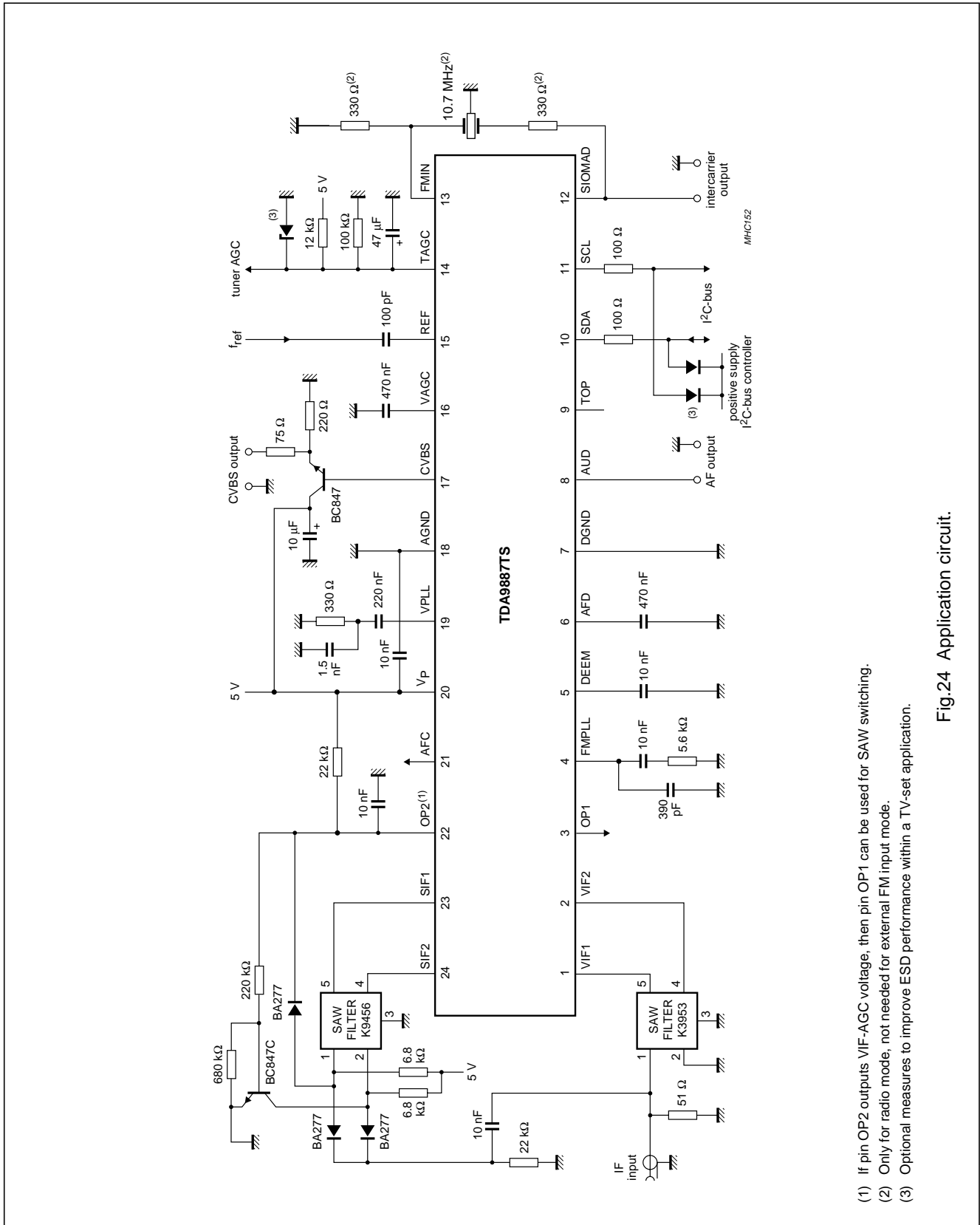


Fig.23 Test circuit.

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- (1) If pin OP2 outputs VIF-AGC voltage, then pin OP1 can be used for SAW switching.
- (2) Only for radio mode, not needed for external FM input mode.
- (3) Optional measures to improve ESD performance within a TV-set application.

Fig.24 Application circuit.

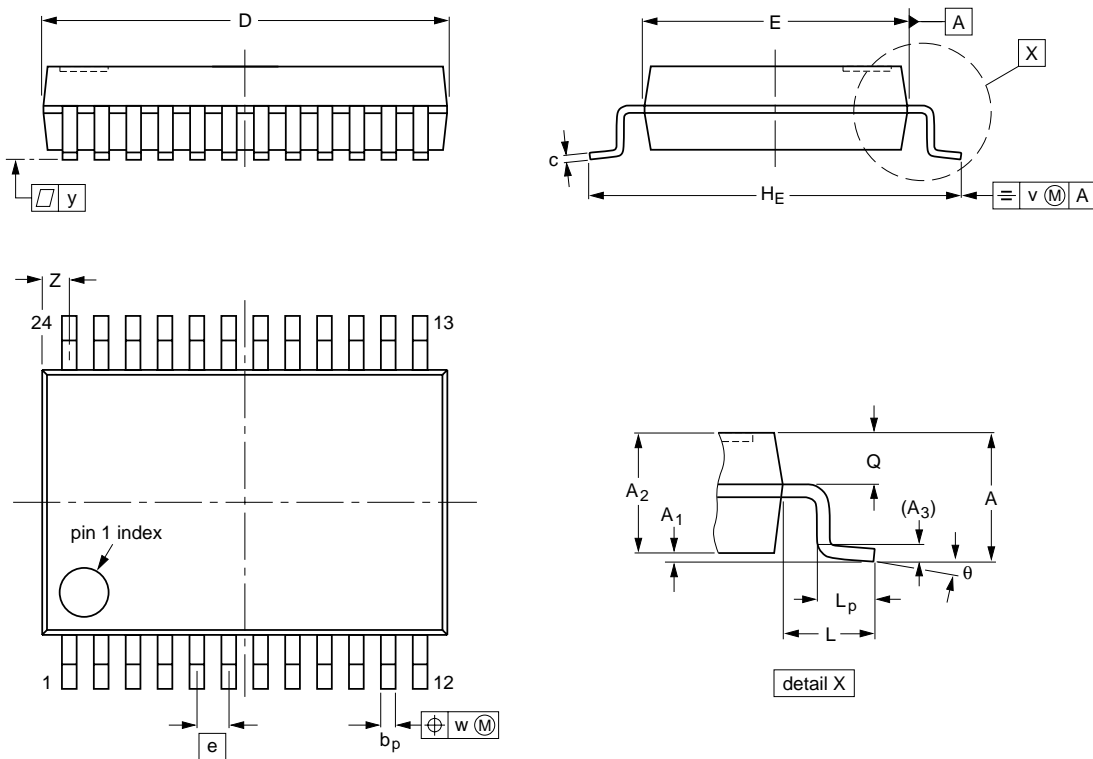
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14 PACKAGE OUTLINE

SSOP24: plastic shrink small outline package; 24 leads; body width 5.3 mm

SOT340-1



DIMENSIONS (mm are the original dimensions)

| UNIT | A max. | A ₁ | A ₂ | A ₃ | b _p | c | D ⁽¹⁾ | E ⁽¹⁾ | e | H _E | L | L _p | Q | v | w | y | Z ⁽¹⁾ | θ |
|------|-----------|----------------|----------------|----------------|----------------|--------------|------------------|------------------|------|----------------|------|----------------|------------|-----|------|-----|------------------|----------|
| mm | 2.0 | 0.21 0.05 | 1.80 1.65 | 0.25 | 0.38 0.25 | 0.20 0.09 | 8.4 8.0 | 5.4 5.2 | 0.65 | 7.9 7.6 | 1.25 | 1.03 0.63 | 0.9 0.7 | 0.2 | 0.13 | 0.1 | 0.8 0.4 | 8° 0° |

Note

1. Plastic or metal protrusions of 0.20 mm maximum per side are not included.

| OUTLINE VERSION | REFERENCES | | | EUROPEAN PROJECTION | ISSUE DATE |
|--------------------|------------|--------|------|------------------------|----------------------|
| | IEC | JEDEC | EIAJ | | |
| SOT340-1 | | MO-150 | | | 95-02-04 99-12-27 |

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15 SOLDERING

15.1 Introduction to soldering surface mount packages

This text gives a very brief insight to a complex technology. A more in-depth account of soldering ICs can be found in our "Data Handbook IC26; Integrated Circuit Packages" (document order number 9398 652 90011).

There is no soldering method that is ideal for all surface mount IC packages. Wave soldering can still be used for certain surface mount ICs, but it is not suitable for fine pitch SMDs. In these situations reflow soldering is recommended.

15.2 Reflow soldering

Reflow soldering requires solder paste (a suspension of fine solder particles, flux and binding agent) to be applied to the printed-circuit board by screen printing, stenciling or pressure-syringe dispensing before package placement.

Several methods exist for reflowing; for example, convection or convection/infrared heating in a conveyor type oven. Throughput times (preheating, soldering and cooling) vary between 100 and 200 seconds depending on heating method.

Typical reflow peak temperatures range from 215 to 250 °C. The top-surface temperature of the packages should preferably be kept below 220 °C for thick/large packages, and below 235 °C for small/thin packages.

15.3 Wave soldering

Conventional single wave soldering is not recommended for surface mount devices (SMDs) or printed-circuit boards with a high component density, as solder bridging and non-wetting can present major problems.

To overcome these problems the double-wave soldering method was specifically developed.

If wave soldering is used the following conditions must be observed for optimal results:

- Use a double-wave soldering method comprising a turbulent wave with high upward pressure followed by a smooth laminar wave.
- For packages with leads on two sides and a pitch (e):
 - larger than or equal to 1.27 mm, the footprint longitudinal axis is **preferred** to be parallel to the transport direction of the printed-circuit board;
 - smaller than 1.27 mm, the footprint longitudinal axis **must** be parallel to the transport direction of the printed-circuit board.

The footprint must incorporate solder thieves at the downstream end.

- For packages with leads on four sides, the footprint must be placed at a 45° angle to the transport direction of the printed-circuit board. The footprint must incorporate solder thieves downstream and at the side corners.

During placement and before soldering, the package must be fixed with a droplet of adhesive. The adhesive can be applied by screen printing, pin transfer or syringe dispensing. The package can be soldered after the adhesive is cured.

Typical dwell time is 4 seconds at 250 °C.

A mildly-activated flux will eliminate the need for removal of corrosive residues in most applications.

15.4 Manual soldering

Fix the component by first soldering two diagonally-opposite end leads. Use a low voltage (24 V or less) soldering iron applied to the flat part of the lead. Contact time must be limited to 10 seconds at up to 300 °C.

When using a dedicated tool, all other leads can be soldered in one operation within 2 to 5 seconds between 270 and 320 °C.

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15.5 Suitability of surface mount IC packages for wave and reflow soldering methods

| PACKAGE | SOLDERING METHOD | |
|---|-----------------------------------|-----------------------|
| | WAVE | REFLOW ⁽¹⁾ |
| BGA, HBGA, LFBGA, SQFP, TFBGA | not suitable | suitable |
| HBCC, HLQFP, HSQFP, HSOP, HTQFP, HTSSOP, HVQFN, SMS | not suitable ⁽²⁾ | suitable |
| PLCC ⁽³⁾ , SO, SOJ | suitable | suitable |
| LQFP, QFP, TQFP | not recommended ⁽³⁾⁽⁴⁾ | suitable |
| SSOP, TSSOP, VSO | not recommended ⁽⁵⁾ | suitable |

Notes

- All surface mount (SMD) packages are moisture sensitive. Depending upon the moisture content, the maximum temperature (with respect to time) and body size of the package, there is a risk that internal or external package cracks may occur due to vaporization of the moisture in them (the so called popcorn effect). For details, refer to the Drypack information in the "Data Handbook IC26; Integrated Circuit Packages; Section: Packing Methods".
- These packages are not suitable for wave soldering as a solder joint between the printed-circuit board and heatsink (at bottom version) can not be achieved, and as solder may stick to the heatsink (on top version).
- If wave soldering is considered, then the package must be placed at a 45° angle to the solder wave direction. The package footprint must incorporate solder thieves downstream and at the side corners.
- Wave soldering is only suitable for LQFP, TQFP and QFP packages with a pitch (e) equal to or larger than 0.8 mm; it is definitely not suitable for packages with a pitch (e) equal to or smaller than 0.65 mm.
- Wave soldering is only suitable for SSOP and TSSOP packages with a pitch (e) equal to or larger than 0.65 mm; it is definitely not suitable for packages with a pitch (e) equal to or smaller than 0.5 mm.

16 DATA SHEET STATUS

| DATA SHEET STATUS ⁽¹⁾ | PRODUCT STATUS ⁽²⁾ | DEFINITIONS |
|----------------------------------|-------------------------------|--|
| Objective data | Development | This data sheet contains data from the objective specification for product development. Philips Semiconductors reserves the right to change the specification in any manner without notice. |
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Notes

- Please consult the most recently issued data sheet before initiating or completing a design.
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17 DEFINITIONS

Short-form specification — The data in a short-form specification is extracted from a full data sheet with the same type number and title. For detailed information see the relevant data sheet or data handbook.

Limiting values definition — Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 60134). Stress above one or more of the limiting values may cause permanent damage to the device.

These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.

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