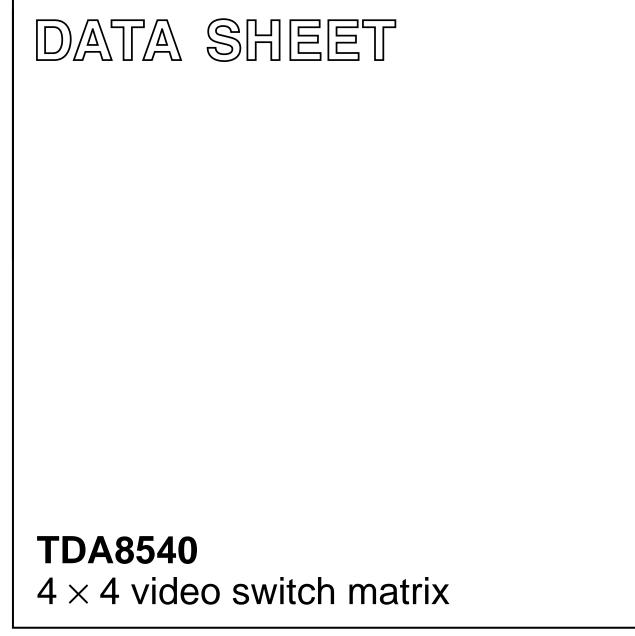
INTEGRATED CIRCUITS



Product specification Supersedes data of April 1993 File under Integrated Circuits, IC02 1995 Feb 06

Philips Semiconductors





$\mathbf{4}\times\mathbf{4}$ video switch matrix

FEATURES

- I²C-bus or non-I²C-bus mode (controlled by DC voltages)
- S-VHS or CVBS processing
- 3-state switches for all channels
- Selectable gain for the video channels
- sub-address facility
- Slave receiver in the I²C mode
- · Auxiliary logic outputs for audio switching
- System expansion possible up to 7 devices (28 sources)
- Static short-circuit proof outputs
- ESD protection.

APPLICATIONS

- Colour Television (CTV) receivers
- Peritelevision sets
- Satellite receivers.

QUICK REFERENCE DATA



GENERAL DESCRIPTION

The TDA8540 has been designed for switching between composite video signals, therefore the minimum of four input lines are provided as requested for switching between two S-VHS sources. Each of the four outputs can be set to a high impedance state, to enable parallel connection of several devices.

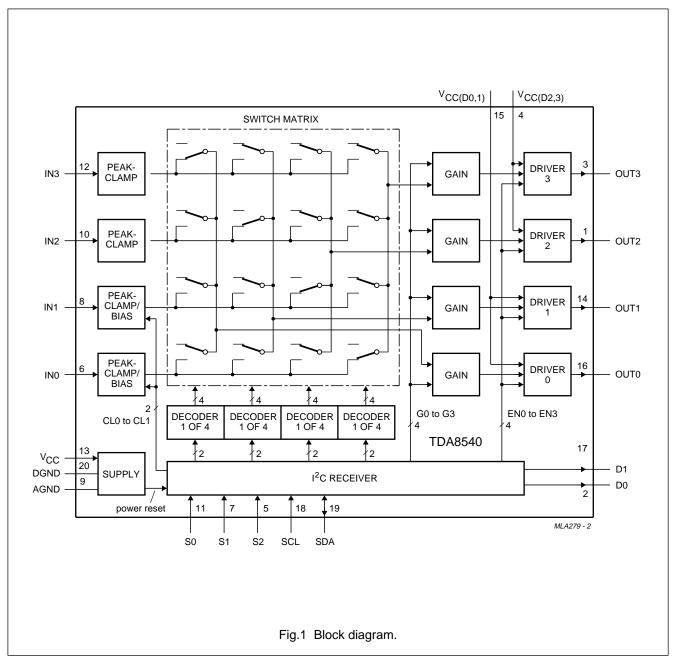
SYMBOL PARAMETER		CONDITIONS	MIN.	TYP.	MAX.	UNIT
V _{CC}	supply voltage		7.2	-	8.8	V
I _{CC}	supply current		-	20	30	mA
I _{SO}	isolation 'OFF' state	at f = 5 MHz	60	80	-	dB
В	3 dB bandwidth		12	_	_	MHz
α _{ct}	crosstalk attenuation between channels		60	70	-	dB

ORDERING INFORMATION

TYPE		PACKAGE			
NUMBER	NAME DESCRIPTION				
TDA8540	DIP20	plastic dual in-line package; 20 leads (300 mil)	SOT146-1		
TDA8540T	SO20	plastic small outline package; 20 leads; body width 7.5 mm	SOT163-1		

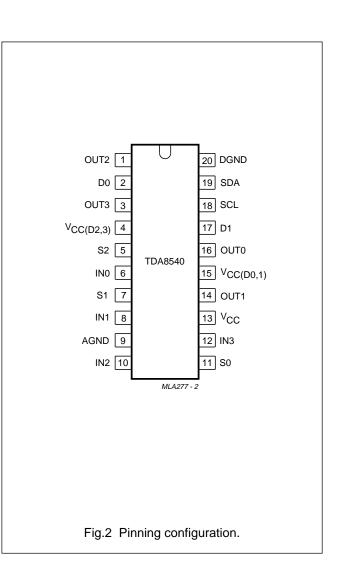
TDA8540

BLOCK DIAGRAM



PINNING

SYMBOL	PIN	DESCRIPTION
OUT2	1	video output 2
D0	2	control output 0
OUT3	3	video output 3
V _{CC(D2,3)}	4	driver supply voltage; for drivers 2 and 3
S2	5	sub-address input 2
INO	6	video input 0 (CVBS or chrominance signal)
S1	7	sub-address input 1
IN1	8	video input 1 (CVBS or chrominance signal)
AGND	9	analog ground
IN2	10	video input 2 (CVBS or luminance signal)
S0	11	sub-address input 0
IN3	12	video input 3 (CVBS or luminance signal)
V _{CC}	13	general supply voltage
OUT1	14	video output 1
V _{CC(D0,1)}	15	driver supply voltage; for drivers 0 and 1
OUT0	16	video output 0
D1	17	control output 1
SCL	18	serial clock input
SDA	19	serial data input/output
DGND	20	digital ground



TDA8540

A0

0

1

0

1

0

1

0

FUNCTIONAL DESCRIPTION

The TDA8540 is controlled via a bidirectional I²C-bus. 3 bits of the I²C address can be selected via the address pin, thus providing a facility for parallel connection of 7 devices.

Control options via the I²C-bus:

- The input signals can be clamped at their negative peak (top sync).
- The gain factor of the outputs can be selected between $1 \times$ or $2 \times$.
- Each of the four outputs can individually be connected to one of the four inputs.
- Each output can individually be set in a high impedance state.
- Two binary output data lines can be controlled for switching accompanying sound signals.

The SDA and SCL pins (pins 19 and 18) can be connected to the l^2 C-bus or to DC switching voltage sources. Address inputs S0 to S2 (pins 11, 7 and 5) are used to select sub-addresses or switching to the non- l^2 C mode. Inputs S0 to S2 can be connected to the supply voltage (HIGH) or the ground (LOW). In this way no peripheral components are required for selection.

S2	61	S0	SU	B-ADDRE	SS
	S1	50	A2	A1	4
L	L	L	0	0	

Н

L

Н

L

Н

L

0

0

0

1

1

1

0

1

1

0

0

1

non I²C addressable

Table 1 I²C-bus sub-addressing

L

Н

Н

L

L

н

н н н

I²C-bus control

L

L

L

Н

Н

Н

After power-up the outputs are initialized in the high impedance state, and D0 and D1 are at a LOW level.

Detailed description of the l^2C -bus specification, with applications, is given in brochure "*The* l^2C -bus and how to use it". This brochure may be ordered using the code 9398 393 40011.

The TDA8540 is a **slave receiver** and the protocol is given in Table 2.

Table 2The TDA8540 protocol

				SE	QUENCE				
S ⁽¹⁾	SLV ⁽²⁾	A ⁽³⁾	SUB	A ⁽³⁾	DATA	A ⁽³⁾	DATA	A ⁽³⁾	P ⁽⁴⁾

Notes

1. S = START condition.

- 2. Data transmission to the TDA8540 starts with the slave address (SLV).
- 3. A = acknowledge bit, generated by TDA8540.
- 4. P = STOP condition.

Table 3 Data transmission to the TDA8540 begins with SLV

A6 MSB	A5	A4	A3	A2	A1	A0	R/W LSB
1	0	0	1	A2 ⁽¹⁾	A1 ⁽¹⁾	A0 ⁽¹⁾	0 ⁽²⁾

Notes

1. A2 to A0: pin programmable slave address bits.

2. $R/\overline{W} = 0$; write only.

After the SLV, a second byte, SUB, is required for selecting the functions, as shown in Table 4.

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7 MSB	6	5	4	3	2	1	0 LSB
0	0	0	0	0	0	RS1	RS0

Options for SUB:

If SUB = 00H: access to switch control (SW1)

If SUB = 01H: access to gain/clamp/data control (GCO)

If SUB = 02H: access to output enable control (OEN).

Remarks:

If more than one data byte is sent, the SUB byte will be automatically incremented.

If more than 3 data bytes are sent, the internal counter will roll over and the device will then rewrite the first register.

Data Bytes

SWI (SUB = 00H): selects which input is connected to the different outputs, as shown in Table 5.

Table 5	SWI (SUB = 00	H) selection	of inputs	connected t	to outputs
---------	---------------	--------------	-----------	-------------	------------

7 MSB	6	5	4	3	2	1	0 LSB
S31	S30	S21	S20	S11	S10	S01	S00

Table 6Selection of inputs

OUTPUT	Sj1 AND Sj0 ⁽¹⁾					
	00	01	10	11		
OUTj	IN0	IN1	IN2	IN3		

Note

Example: if S21 = 0 and S20 = 1, then OUT2 is connected to IN1.

GCO (SUB = 01H):

- Selects the gain of each output.
- Selects the clamp action or mean value on inputs 0 and 1.
- Determines the value of the auxiliary outputs D1 and D0.

Table 7GCO byte

7 MSB	6	5	4	3	2	1	0 LSB
G3 ⁽¹⁾	G2 ⁽¹⁾	G1 ⁽¹⁾	G0 ⁽¹⁾	CL1 ⁽²⁾	CL0 ⁽²⁾	D1 ⁽³⁾	D0 ⁽³⁾

Notes

- 1. For j = 0 to 3: if Gj = 0 (1), then output j has a gain of 2 (1).
- 2. If CL0 (CL1) = 0, then input signal on IN0 (IN1) is clamped.
- 3. For j = 0 or 1: if Dj = 0 (1), then logical output j is LOW (HIGH).

^{1.} For j = 0 to 3.

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OEN (SUB = 02H): selects, for each output, if the output is active or high impedance, see Table 8.

 Table 8
 OEN (SUB = 02H) determines which output is active or high impedance

7 MSB	6	5	4	3	2	1	0 LSB
X ⁽¹⁾	X ⁽¹⁾	X ⁽¹⁾	X ⁽¹⁾	EN3 ⁽²⁾	EN2 ⁽²⁾	EN1 ⁽²⁾	EN0 ⁽²⁾

Notes

1. X = don't care.

2. For j = 0 to 3: if ENj = 0 (1), then OUT j is high impedance (active).

After a power-on reset:

- The outputs are set to a high impedance state; the outputs are connected to INO; the gains are set at two and inputs INO and IN1 are clamped.
- Programming of the device is necessary because the outputs are in high impedance state.

Non-I²C-bus control

If the S0, S1 and S2 pins are all connected to V_{CC} the device will enter the non-I²C-bus mode.

- After a power-on reset:
- Gain is set at two for all outputs.
- All inputs are clamped.
- All outputs are active.
- The matrix position is given by the SDA and SCL voltage level.

Table 9 Non-I²C-bus control

OUTPUT	SCL AND SDA					
OUIFUI	00	01	10	11		
OUT3	IN3	IN2	IN1	IN0		
OUT2	IN2	IN3	IN0	IN1		
OUT1	IN1	INO	IN3	IN2		
OUT0	IN0	IN1	IN2	IN3		

SCL and SDA act as normal input pins:

SCL interchanges (OUT3 and OUT2) with (OUT1 and OUT0).

SDA interchanges OUT3 with OUT2 and OUT1 with OUT0.

Remark: For use with chrominance signals, the clamp action must be overruled by external bias.

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LIMITING VALUES

In accordance with the Absolute Maximum System (IEC 134).

SYMBOL	PARAMETER	CONDITIONS	MIN.	MAX.	UNIT
V _{CC}	supply voltage (pin 13)		-0.3	+9.1	V
P _{tot}	total power dissipation		-	750	mW
V _{CC(D0,1)} , V _{CC(D2,3)}	driver supply voltage		-0.3	+13.8	V
IN0 to IN3	video input voltage		-0.3	+7.2	V
OUT0 to OUT3	video output voltage		-0.3	+7.2	V
D0, D1	control output voltage		-0.3	+7.2	V
SDA, SDL	I ² C input/output voltage		-0.3	+8.8	V
S0 to S2	sub-address input voltage		-0.3	+8.8	V
T _{stg}	IC storage temperature		-55	+125	°C
Tj	junction temperature		-	+150	°C
V _{es}	electrostatic handling	HBM; note 1	-1500	+1500	V
		MM; note 2	-200	+200	V

Notes

- 1. Human Body Model (HBM): in accordance with UZW-BO/FQ-A302.
- Machine Model (MM): in accordance with UZW-BO/FQ-B302 (stress reference pins: AGND and DGND short-circuited and V_{CC}).

THERMAL CHARACTERISTICS

SYMBOL	PARAMETER	VALUE	UNIT
R _{th j-a}	thermal resistance from junction to ambient in free air		
	SOT146-1	60 (typ.)	K/W
	SOT163-1	85 (typ.)	K/W

OPERATING CHARACTERISTICS

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
General						
V _{CC}	supply voltage (pin 13)		7.2	-	8.8	V
T _{amb}	operating ambient temperature		0	_	70	°C
Video inputs (pins	6, 8, 10 and 12)					
CI	external capacitor		-	100	-	nF
V _{I(p-p)}	C signal amplitude (peak-to-peak value)	note 1	_	_	1	V
V _{I(p-p)}	CVBS or Y-signal amplitude (peak-to-peak value)	note 2	-	-	1.5	V
Video drivers (pins	s 4 and 15)					
R _D	external collector resistor	note 3	-	25	_	Ω
C _D	external decoupling capacitor	note 4	_	22	_	μF

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SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
Sub-address S0, S1 and S2 (pins 5, 7 and 11)						
V _{IH}	HIGH level input voltage		4	_	V _{CC}	V
V _{IL}	LOW level input voltage		0	_	1	V

Notes

- 1. Only for pins 6 and 8 when clamp action is not selected for these pins.
- On all the video input pins, when non-l²C-bus control mode is selected or when clamp action is selected on pins 6 and 8 (by l²C-bus control).
- 3. Connected between V_{CC} and pin 4 or pin 15.
- 4. Connected between AGND and pin 4 or pin 15.

CHARACTERISTICS

 V_{CC} = 8 V; T_{amb} = 25 °C; gain condition, clamp condition and OFF state are controlled by the I²C-bus; unless otherwise specified.

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
Supply						
I _{CC}	supply current	without load	-	20	30	mA
		OFF state	-	12	-	mA
Video inputs: IN	0 to IN3 when the clamp is active (see Figs	s 3 and 4)				
ILI	input leakage current	V _I = 3 V	-	0.4	1	μA
V _{clamp}	input clamping voltage	I _I = 5 μA	_	2.2	_	V
I _{clamp}	input clamping current	V _I = 0 V	1.2	-	_	mA
Video inputs: IN	0 and IN2 when the clamp is not active (se	e Fig.3)		·		
V _{bias}	DC input bias level	$I_{I} = 0$	-	2.9	-	V
RI	input resistance		-	10	_	kΩ
Video outputs: C	DUT0 to OUT3 (see Fig.5)					
Z _O	output impedance	OFF state	100	-	-	kΩ
R _O	output resistance		-	5	_	Ω
ISO	isolation	OFF state; f = 5 MHz	60	_	_	dB
Vo	output top sync level; (Y or CVBS)		0.4	0.7	1	V
V _{bias}	output mean value for chrominance	G = 2; load = 150 Ω	1.5	1.9	2.2	V
	signals	G = 1; without load	1	1.3	1.6	V
G _v	voltage gain	G = 1; f = 1 MHz	-1	0	+1	dB
		G = 2; f = 1 MHz	5	6	7	dB
G _{diff}	differential gain	note 1	_	0.5	3	%
Φdiff	differential phase	note 1	-	0.6	-	deg
NL	non linearity	note 2	-	0.5	2	%
α _{ct}	crosstalk attenuation between channels	note 3	60	70	-	dB
SVRR	supply voltage rejection	note 4	36	55	_	dB

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SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
ΔG	maximum gain variation	100 kHz < f < 5 MHz	-	0.5	-	dB
		100 kHz < f < 8.5 MHz	-	1	-	dB
		100 kHz < f < 12 MHz	-	3	-	dB
α _{ct}	crosstalk attenuation of I ² C-bus signals		60	-	_	dB
Auxiliary output	s D0 and D1 (open collector)					
I _{OH}	HIGH level output current	V _{OH} = 5.5 V	-	-	10	μA
V _{OL}	LOW level output voltage	$I_{OL} = 4 \text{ mA}$	-	-	0.4	V
I ² C-bus inputs S	CL and SDA					
I _{IH}	HIGH level input current	V _{IH} = 3.0 V	_	-	10	μA
IIL	LOW level input current	V _{IL} = 1.5 V	-10	-	-	μA
Ci	input capacitance		-	-	10	pF
I ² C-bus output S	DA					
V _{OL}	LOW level output voltage	I _{OL} = 3 mA	-	-	0.4	V
Sub-address S0	S1 and S2					
I _{IH}	HIGH level input current	$V_{IH} = V_{CC}$	-	-	10	μA
IIL	LOW level input current	$V_{IL} = 0 V$	_	_	10	μA

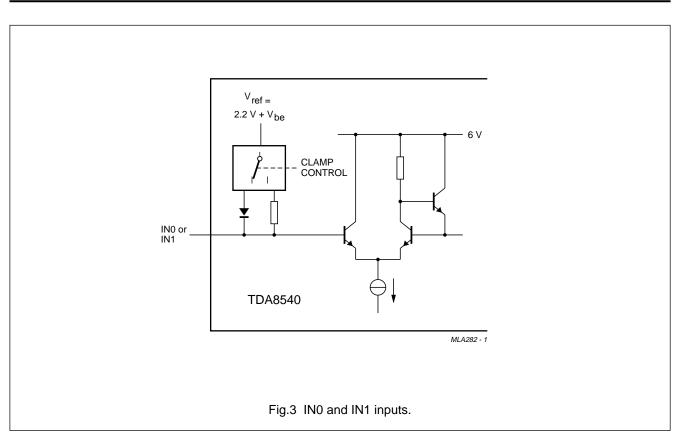
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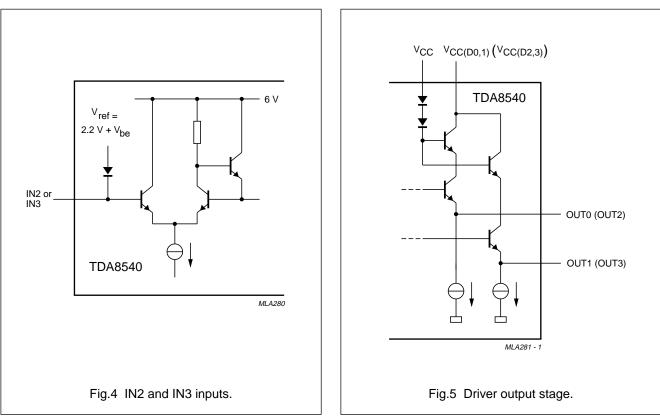
1. Gain set at 2; R_L = 150 Ω ; test signal D2 from CCIR 330.

2. Gain set at 2; R_L = 150 Ω ; test signal D1 from CCIR 17.

- 3. Measured from any selected input to output; f = 5 MHz; R_L = 150 Ω ; gain set at 2; V_I = 1.5 V (peak-to-peak value). This measurement requires an optimized board.
- 4. Supply voltage ripple rejection: 20 log $\frac{V_{ripple (supply)}}{V_{ripple (on output)}}$;

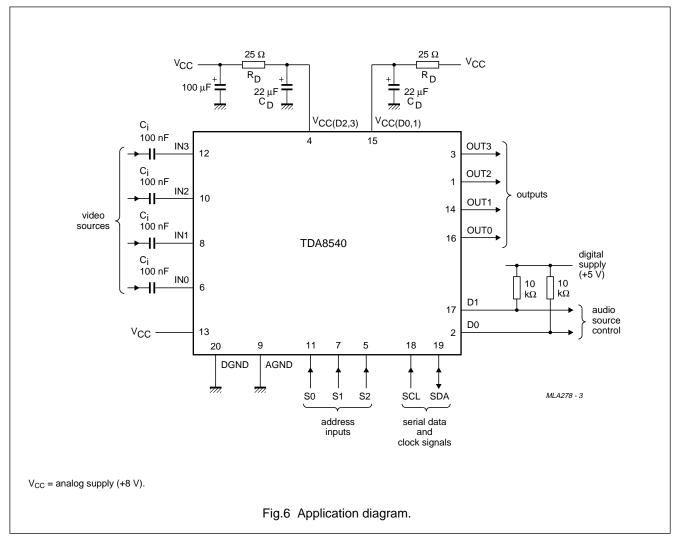
measured at f = 1 kHz with V _{ripple (supply max)} = 100 mV (peak-to-peak value). The supply voltage rejection ratio is >36 dB at f_{max} = 100 kHz.





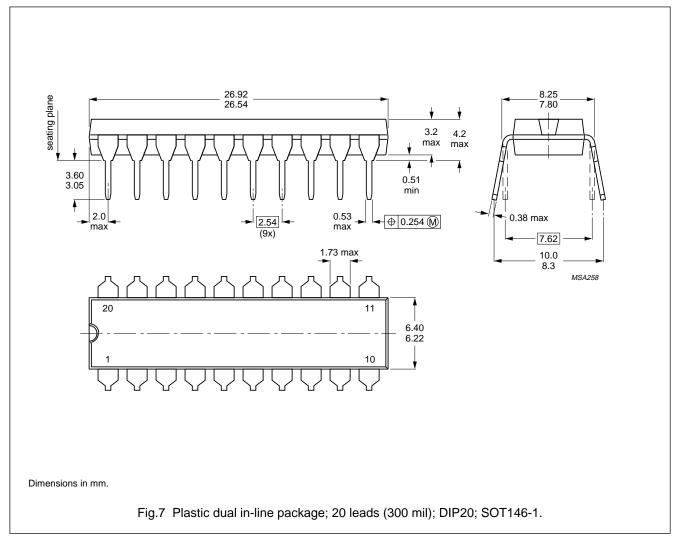
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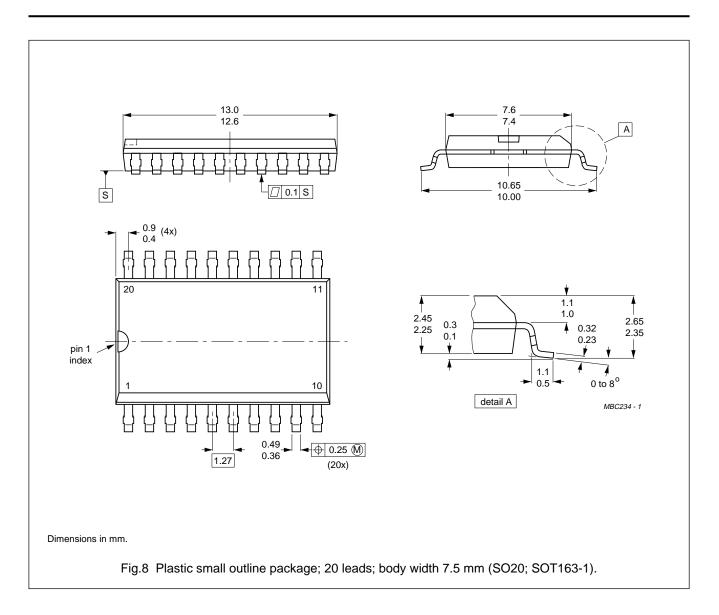
APPLICATION INFORMATION



TDA8540

PACKAGE OUTLINES





SOLDERING

Plastic small outline packages

BY WAVE

During placement and before soldering, the component must be fixed with a droplet of adhesive. After curing the adhesive, the component can be soldered. The adhesive can be applied by screen printing, pin transfer or syringe dispensing.

Maximum permissible solder temperature is 260 °C, and maximum duration of package immersion in solder bath is 10 s, if allowed to cool to less than 150 °C within 6 s. Typical dwell time is 4 s at 250 °C.

A modified wave soldering technique is recommended using two solder waves (dual-wave), in which a turbulent wave with high upward pressure is followed by a smooth laminar wave. Using a mildly-activated flux eliminates the need for removal of corrosive residues in most applications.

BY SOLDER PASTE REFLOW

Reflow soldering requires the solder paste (a suspension of fine solder particles, flux and binding agent) to be applied to the substrate by screen printing, stencilling or pressure-syringe dispensing before device placement.

Several techniques exist for reflowing; for example, thermal conduction by heated belt, infrared, and vapour-phase reflow. Dwell times vary between 50 and 300 s according to method. Typical reflow temperatures range from 215 to 250 °C.

Preheating is necessary to dry the paste and evaporate the binding agent. Preheating duration: 45 min at 45 °C.

REPAIRING SOLDERED JOINTS (BY HAND-HELD SOLDERING IRON OR PULSE-HEATED SOLDER TOOL)

Fix the component by first soldering two, diagonally opposite, end pins. Apply the heating tool to the flat part of the pin only. Contact time must be limited to 10 s at up to $300 \,^{\circ}$ C. When using proper tools, all other pins can be soldered in one operation within 2 to 5 s at between 270 and 320 $^{\circ}$ C. (Pulse-heated soldering is not recommended for SO packages.)

For pulse-heated solder tool (resistance) soldering of VSO packages, solder is applied to the substrate by dipping or by an extra thick tin/lead plating before package placement.

Plastic dual in-line packages

BY DIP OR WAVE

The maximum permissible temperature of the solder is 260 °C; this temperature must not be in contact with the joint for more than 5 s. The total contact time of successive solder waves must not exceed 5 s.

The device may be mounted up to the seating plane, but the temperature of the plastic body must not exceed the specified storage maximum. If the printed-circuit board has been pre-heated, forced cooling may be necessary immediately after soldering to keep the temperature within the permissible limit.

REPAIRING SOLDERED JOINTS

Apply a low voltage soldering iron below the seating plane (or not more than 2 mm above it). If its temperature is below 300 $^{\circ}$ C, it must not be in contact for more than 10 s; if between 300 and 400 $^{\circ}$ C, for not more than 5 s.

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DEFINITIONS

Data sheet status					
Objective specification	This data sheet contains target or goal specifications for product development.				
Preliminary specification	This data sheet contains preliminary data; supplementary data may be published later.				
Product specification	This data sheet contains final product specifications.				
Limiting values					
Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.					
Application information					

Where application information is given, it is advisory and does not form part of the specification.

LIFE SUPPORT APPLICATIONS

These products are not designed for use in life support appliances, devices, or systems where malfunction of these products can reasonably be expected to result in personal injury. Philips customers using or selling these products for use in such applications do so at their own risk and agree to fully indemnify Philips for any damages resulting from such improper use or sale.

PURCHASE OF PHILIPS I²C COMPONENTS



Purchase of Philips I²C components conveys a license under the Philips' I²C patent to use the components in the I²C system provided the system conforms to the I²C specification defined by Philips. This specification can be ordered using the code 9398 393 40011.

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Argentina: IEROD, Av. Juramento 1992 - 14.b, (1428) BUENOS AIRES, Tel. (541)786 7633, Fax. (541)786 9367 Australia: 34 Waterloo Road, NORTH RYDE, NSW 2113, Tel. (02)805 4455, Fax. (02)805 4466 Austria: Triester Str. 64, A-1101 WIEN, P.O. Box 213, Tel. (01)60 101-1236, Fax. (01)60 101-1211 Belgium: Postbus 90050, 5600 PB EINDHOVEN, The Netherlands, Tel. (31)40 783 749, Fax. (31)40 788 399 Brazil: Rua do Rocio 220 - 5th floor, Suite 51, CEP: 04552-903-SÃO PAULO-SP, Brazil. P.O. Box 7383 (01064-970). Tel. (011)821-2333, Fax. (011)829-1849 Canada: PHILIPS SEMICONDUCTORS/COMPONENTS: Tel. (800) 234-7381, Fax. (708) 296-8556 Chile: Av. Santa Maria 0760, SANTIAGO, Tel. (02)773 816, Fax. (02)777 6730 Colombia: IPRELENSO LTDA, Carrera 21 No. 56-17, 77621 BOGOTA, Tel. (571)249 7624/(571)217 4609, Fax. (571)217 4549 Denmark: Prags Boulevard 80, PB 1919, DK-2300 COPENHAGEN S, Tel. (032)88 2636, Fax. (031)57 1949 Finland: Sinikalliontie 3, FIN-02630 ESPOO, Tel. (9)0-50261, Fax. (9)0-520971 France: 4 Rue du Port-aux-Vins, BP317, 92156 SURESNES Cedex, Tel. (01)4099 6161, Fax. (01)4099 6427 Germany: P.O. Box 10 63 23, 20043 HAMBURG, Tel. (040)3296-0, Fax. (040)3296 213. Greece: No. 15, 25th March Street, GR 17778 TAVROS, Tel. (01)4894 339/4894 911, Fax. (01)4814 240 Hong Kong: PHILIPS HONG KONG Ltd., 15/F Philips Ind. Bldg., 24-28 Kung Yip St., KWAI CHUNG, N.T., Tel. (852)424 5121, Fax. (852)480 6960/480 6009 India: Philips INDIA Ltd, Shivsagar Estate, A Block , Dr. Annie Besant Rd. Worli, Bombay 400 018 Tel. (022)4938 541, Fax. (022)4938 722 Indonesia: Philips House, Jalan H.R. Rasuna Said Kav. 3-4, P.O. Box 4252, JAKARTA 12950, Tel. (021)5201 122, Fax. (021)5205 189 Ireland: Newstead, Clonskeagh, DUBLIN 14, Tel. (01)640 000, Fax. (01)640 200 Italy: PHILIPS SEMICONDUCTORS S.r.I. Piazza IV Novembre 3, 20124 MILANO Tel. (0039)2 6752 2531, Fax. (0039)2 6752 2557 Japan: Philips Bldg 13-37, Kohnan 2-chome, Minato-ku, TOKYO 108, Tel. (03)3740 5028, Fax. (03)3740 0580 Korea: (Republic of) Philips House, 260-199 Itaewon-dong, Yongsan-ku, SEOUL, Tel. (02)794-5011, Fax. (02)798-8022 Malaysia: No. 76 Jalan Universiti, 46200 PETALING JAYA, SELANGOR, Tel. (03)750 5214, Fax. (03)757 4880 Mexico: 5900 Gateway East, Suite 200, EL PASO, TX 79905, Tel. 9-5(800)234-7381, Fax. (708)296-8556 Netherlands: Postbus 90050, 5600 PB EINDHOVEN, Bldg. VB Tel. (040)783749, Fax. (040)788399 New Zealand: 2 Wagener Place, C.P.O. Box 1041, AUCKLAND, Tel. (09)849-4160, Fax. (09)849-7811 Norway: Box 1, Manglerud 0612, OSLO, Tel. (022)74 8000, Fax. (022)74 8341

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