

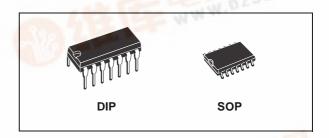
HCF4047B

LOW POWER MONOSTABLE/ASTABLE MULTIVIBRATOR

- LOW POWER CONSUMPTION : SPECIAL CMOS OSCILLATOR CONFIGURATION
- MONOSTABLE (one shot) OR ASTABLE (free-running) OPERATION
- TRUE AND COMPLEMENTED BUFFERED OUTPUTS
- ONLY ONE EXTERNAL R AND C REQUIRED
- BUFFERED INPUTS
- QUIESCENT CURRENT SPECIFIED UP TO 20V
- STANDARDIZED, SYMMETRICAL OUTPUT CHARACTERISTICS
- 5V, 10V AND 15V PARAMETRIC RATINGS
- INPUT LEAKAGE CURRENT I_I = 100nA (MAX) AT V_{DD} = 18V T_A = 25°C
- 100% TESTED FOR QUIESCENT CURRENT
- MEETS ALL REQUIREMENTS OF JEDEC JESD13B " STANDARD SPECIFICATIONS FOR DESCRIPTION OF B SERIES CMOS DEVICES"

DESCRIPTION

The HCF4047B is a monolithic integrated circuit fabricated in Metal Oxide Semiconductor technology available in DIP and SOP packages. The HCF4047B consist of a gatable astable multivibrator with logic techniques incorporated to



ORDER CODES

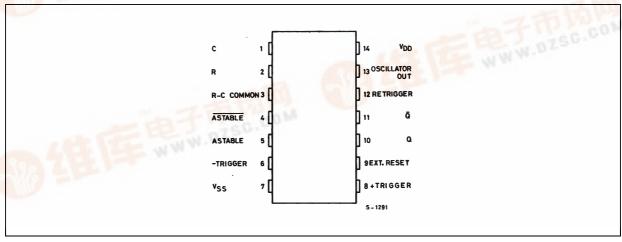
| PACKAGE | TUBE | T & R |
|---------|------------|---------------|
| DIP | HCF4047BEY | M. Add |
| SOP | HCF4047BM1 | HCF4047M013TR |

permit positive or negative edge-triggered monostable multivibrator action with retriggering and external counting options. Inputs include +TRIGGER -TRIGGER, ASTABLE, ASTABLE, RETRIGGER, and EXTERNAL RESET. Buffered outputs are Q, Q and OSCILLATOR. In all modes of operation, an external capacitor must be connected between C-Timing and RC-Common terminals, and an external resistor must be connected between the R-Timing and RC-Common terminals.

For operating modes see functional terminal connections and application notes.

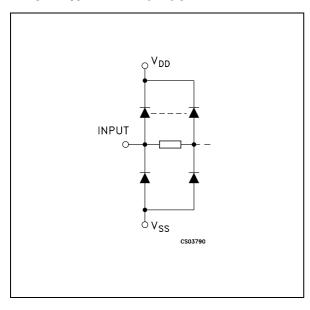
PIN CONNECTION

dzsc.com



September 2001 1/12

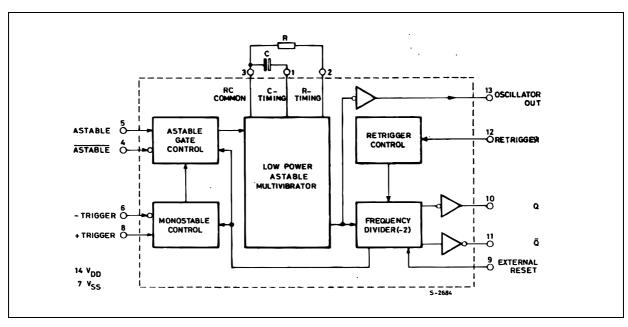
INPUT EQUIVALENT CIRCUIT



PIN DESCRIPTION

| PIN No | SYMBOL | NAME AND FUNCTION |
|--------|-------------------|------------------------------------|
| 1 | С | External Capacitor |
| 2 | R | External Resistor |
| 3 | RC COM- MON | External Connection to (1) and (2) |
| 4 | ASTABLE | Complement Astable Pulse |
| 5 | ASTABLE | True Astable Pulse |
| 6 | -TRIGGER | Negative Trigger Pulse |
| 8 | +TRIGGER | Positive Trigger Pulse |
| 9 | EXT. RESET | External Reset |
| 12 | RETRIG- GER | Retrigger Mode Pulse |
| 13 | OSC. OUT | Oscillator Output |
| 10,11 | Q, \overline{Q} | Q Outputs |
| 7 | V_{SS} | Negative Supply Voltage |
| 14 | V_{DD} | Positive Supply Voltage |

BLOCK DIAGRAM



FUNCTIONAL TERMINAL CONNECTIONS

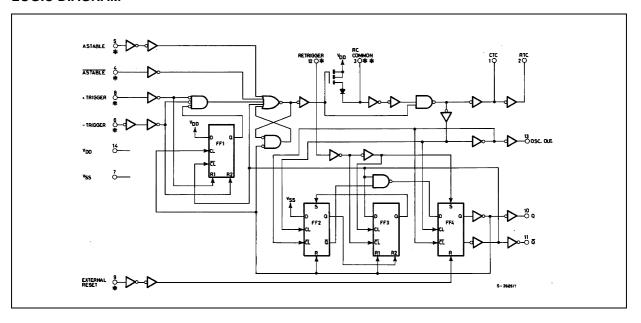
| | TERM | INAL CONNEC | TIONS | OUTPUT | OUTPUT REDIOD OR |
|--------------------------|--------------------|-----------------------------------|-------|---------------|---------------------------------|
| FUNCTION* | to V _{DD} | to V _{SS} Input Pulse to | | PULSE FROM | OUTPUT PERIOD OR PULSE WIDTH |
| Astable Multivibrator | | | | | |
| Free Running | 4, 5, 6, 14 | 7, 8, 9, 12 | - | 10, 11, 13 | t _A (10,11) = 4.40RC |
| True Gating | 4, 6, 14 | 7, 8, 9, 12 | 5 | 10, 11, 13 | |
| Complement Gating | 6, 14 | 5, 7, 8, 9, 12 | 4 | 10, 11, 13 | t _A (13) = 2.20RC |
| Monostable Multivibrator | | • | | | |
| Positive - Edge Trigger | 4, 14 | 5, 6, 7, 9, 12 | 8 | 10, 11 | |
| Negative - Edge Trigger | 4, 8, 14 | 5, 7, 9, 12 | 6 | 10, 11 | |
| Retriggerable | 4, 14 | 5, 6, 7, 9 | 8, 12 | 10, 11 | t _M (10,11) = 2.48RC |
| External Countdown** | 14 | 5, 6, 7, 8, 9, 12 | - | 10, 11 | |

^{*} In all cases external capacitor and resistor between pins, 1, 2 and 3 (see logic diagrams).

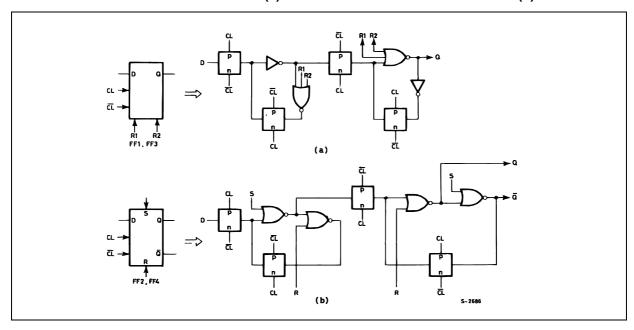
**Input pulse to Reset of External Counting Chip.

External Counting Chip Output to pin 4.

LOGIC DIAGRAM



DETAIL FOR FLIP-FLOPS FF1 AND FF3 (a) AND FOR FLIP-FLOPS FF2 AND FF4 (b)



ABSOLUTE MAXIMUM RATINGS

| Symbol | Parameter | Value | Unit |
|------------------|---|-------------------------------|------|
| V_{DD} | Supply Voltage | -0.5 to +22 | V |
| VI | DC Input Voltage | -0.5 to V _{DD} + 0.5 | V |
| I _I | DC Input Current | ± 10 | mA |
| P_{D} | Power Dissipation per Package | 200 | mW |
| | Power Dissipation per Output Transistor | 100 | mW |
| T _{op} | Operating Temperature | -55 to +125 | °C |
| T _{stg} | Storage Temperature | -65 to +150 | °C |

Absolute Maximum Ratings are those values beyond which damage to the device may occur. Functional operation under these conditions is not implied.
All voltage values are referred to V_{SS} pin voltage.

RECOMMENDED OPERATING CONDITIONS

| Symbol | Parameter | Value | Unit |
|-----------------|-----------------------|----------------------|------|
| V_{DD} | Supply Voltage | 3 to 20 | ٧ |
| V _I | Input Voltage | 0 to V _{DD} | ٧ |
| T _{op} | Operating Temperature | -55 to 125 | °C |

47/ 4/12

DC SPECIFICATIONS

| | | | Test Con | dition | | | | | Value | | | | |
|-----------------|--------------------------|------|----------|----------------|----------|-------|-------------------|------|--------|------|--------|-------|------|
| Symbol | Parameter | Vı | ٧o | l _o | V_{DD} | т | A = 25° | С | -40 to | 85°C | -55 to | 125°C | Unit |
| | | (V) | (V) | (μ A) | (V) | Min. | Тур. | Max. | Min. | Max. | Min. | Max. | |
| ΙL | Quiescent Current | 0/5 | | | 5 | | 0.01 | 1 | | 30 | | 30 | |
| | | 0/10 | | | 10 | | 0.01 | 2 | | 60 | | 60 | |
| | | 0/15 | | | 15 | | 0.01 | 4 | | 120 | | 120 | μΑ |
| | | 0/20 | | | 20 | | 0.02 | 20 | | 600 | | 600 | |
| V _{OH} | High Level Output | 0/5 | | <1 | 5 | 4.95 | | | 4.95 | | 4.95 | | |
| | Voltage | 0/10 | | <1 | 10 | 9.95 | | | 9.95 | | 9.95 | | V |
| | | 0/15 | | <1 | 15 | 14.95 | | | 14.95 | | 14.95 | | |
| V _{OL} | Low Level Output | 5/0 | | <1 | 5 | | 0.05 | | | 0.05 | | 0.05 | |
| | Voltage | 10/0 | | <1 | 10 | | 0.05 | | | 0.05 | | 0.05 | V |
| | | 15/0 | | <1 | 15 | | 0.05 | | | 0.05 | | 0.05 | |
| V_{IH} | High Level Input | | 0.5/4.5 | <1 | 5 | 3.5 | | | 3.5 | | 3.5 | | |
| | Voltage | | 1/9 | <1 | 10 | 7 | | | 7 | | 7 | | V |
| | | | 1.5/13.5 | <1 | 15 | 11 | | | 11 | | 11 | | |
| V_{IL} | Low Level Input | | 4.5/0.5 | <1 | 5 | | | 1.5 | | 1.5 | | 1.5 | |
| | Voltage | | 9/1 | <1 | 10 | | | 3 | | 3 | | 3 | V |
| | | | 13.5/1.5 | <1 | 15 | | | 4 | | 4 | | 4 | |
| I _{OH} | Output Drive | 0/5 | 2.5 | <1 | 5 | -1.36 | -3.2 | | -1.15 | | -1.1 | | |
| | Current | 0/5 | 4.6 | <1 | 5 | -0.44 | -1 | | -0.36 | | -0.36 | | mA |
| | | 0/10 | 9.5 | <1 | 10 | -1.1 | -2.6 | | -0.9 | | -0.9 | | IIIA |
| | | 0/15 | 13.5 | <1 | 15 | -3.0 | -6.8 | | -2.4 | | -2.4 | | |
| I _{OL} | Output Sink | 0/5 | 0.4 | <1 | 5 | 0.44 | 1 | | 0.36 | | 0.36 | | |
| | Current | 0/10 | 0.5 | <1 | 10 | 1.1 | 2.6 | | 0.9 | | 0.9 | | mΑ |
| | | 0/15 | 1.5 | <1 | 15 | 3.0 | 6.8 | | 2.4 | | 2.4 | | |
| I _I | Input Leakage Current | 0/18 | Any In | put | 18 | | ±10 ⁻⁵ | ±0.1 | | ±1 | | ±1 | μΑ |
| Cl | Input Capacitance | | Any In | put | | | 5 | 7.5 | | | | | pF |

The Noise Margin for both "1" and "0" level is: 1V min. with V_{DD} =5V, 2V min. with V_{DD} =10V, 2.5V min. with V_{DD} =15V

DYNAMIC ELECTRICAL CHARACTERISTICS ($T_{amb} = 25$ °C, $C_L = 50$ pF, $R_L = 200$ K Ω , $t_r = t_f = 20$ ns)

| 0 | | | | Test Condition | , | Value (* | ·) | Unit |
|-----------------------------------|-----------------------|---------------------------|---------------------|----------------|------|----------|------|------|
| Symbol | Paran | neter | V _{DD} (V) | | Min. | Тур. | Max. | |
| t _{PLH} t _{PHL} | Propagation Delay | Astable, Astable | 5 | | | 200 | 400 | |
| | Time | to Osc. Out | 10 | | | 100 | 200 | |
| | | | 15 | | | 80 | 160 | |
| | | Astable, Astable | 5 | | | 350 | 700 | |
| | | to Q, Q | 10 | | | 175 | 350 | |
| | | | 15 | | | 125 | 250 | |
| | | + o <u>r</u> - Trigger to | 5 | | | 500 | 1000 | |
| | | Q, \overline{Q} | 10 | | | 225 | 450 | ns |
| | | | 15 | | | 150 | 300 | |
| | | Retrigger to Q, Q | 5 | | | 300 | 600 | |
| | | | 10 | | | 150 | 300 | |
| | | | 15 | | | 100 | 200 | |
| | | External Reset | 5 | | | 250 | 500 | |
| | | to Q, Q | 10 | | | 100 | 200 | |
| | | | 15 | | | 70 | 140 | |
| t _{THL} t _{TLH} | Transition Time Osc | c. Out Q, Q | 5 | | | 100 | 200 | |
| | | | 10 | | | 50 | 100 | ns |
| | | | 15 | | | 40 | 80 | |
| t _W | Input Pulse Width | + Trigger | 5 | | | 200 | 400 | |
| | | - Trigger | 10 | | | 80 | 160 | |
| | | | 15 | | | 50 | 100 | |
| | | Reset | 5 | | | 100 | 200 | |
| | | | 10 | | | 50 | 100 | ns |
| | | | 15 | | | 30 | 60 | |
| | | Retrigger | 5 | | | 300 | 600 | |
| | | | 10 | | | 115 | 230 | |
| | | | 15 | | | 75 | 150 | |
| t _r , t _f | Input Rise and Fall | Time All Inputs | 5 | | | | | |
| | | | 10 | | l | Jnlimite | d | μs |
| | | | 15 | | | | | |
| | Q or Q Deviation from | om 50% Duty | 5 | | | ±0.5 | ±1 | |
| | Factor | | 10 | | | ±0.5 | ±1 | % |
| | | | 15 | | | ±0.1 | ±0.5 | |

^(*) Typical temperature coefficient for all $\rm V_{DD}$ value is 0.3 $\rm \%/^{\circ}C.$

APPLICATION INFORMATION

1 - CIRCUIT DESCRIPTION

Astable operation is enabled by a high level on the ASTABLE input. The period of the square wave at the Q and Q Outputs in this mode of operation is a function of the external components employed. "True" input pulses on the ASTABLE input or "Complement" pulses on the ASTABLE input allow the circuit to be used as a gatable multivibrator. The OSCILLATOR output period will be half of the Q terminal output in the astable mode. However, a 50% duty cycle is not guaranteed at this output. In the monostable

mode, positive-edge triggering is accomplished by application of a leading-edge pulse to the +TRIGGER input and a low level to the -TRIGGER input. For negative-edge triggering, a trailing-edge pulse is applied to the -TRIGGER and a high level is applied to the +TRIGGER. Input pulses may be of any duration relative to the output pulse. The multivibrator can be retriggered (on the leading edge only) by applying a common pulse to both the RETRIGGER and +TRIGGER inputs. In this mode the output pulse remains high as long as the input pulse period is shorter than the period determined by the RC components. An external countdown option can be implemented by

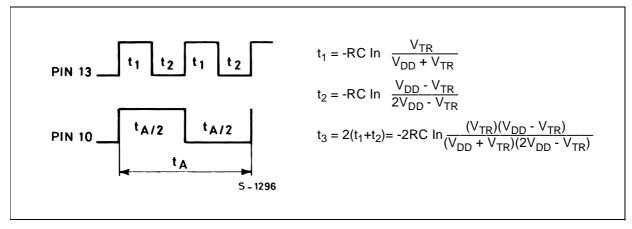
477

coupling "Q" to an external "N" counter and resetting the counter with the trigger pulse. The counter output pulse is fed back to the ASTABLE input and has a duration equal to N times the period of the multivibrator. A high level on the EXTERNAL RESET input assures no output pulse during an "ON" power condition. This input can also be activated to terminate the output pulse at any time. In the monostable mode, a high-level or power-on reset pulse, must be applied to the EXTERNAL RESET whenever V_{DD} is applied.

2 - ASTABLE MODE

The following analysis presents worst-case variations from unit-to-unit as a function of transfer-voltage (VTR) shift (33% - 67% V_{DD}) for free-running (astable) operation.

ASTABLE MODE WAVEFORMS



 $\begin{array}{l} \text{Typ}: V_{TR} = 0.5 \; V_{DD} \; t_A = 4.40 \; RC \\ \text{Min}: V_{TR} = 0.33 \; V_{DD} \; t_A = 4.62 \; RC \\ \text{Max}: V_{TR} = 0.67 \; V_{DD} \; t_A = 4.62 \; RC \\ \text{thus} \; \; \text{if} \; \; t_A = 4.40 \; RC \; \; \text{is used, the maximum} \\ \end{array}$

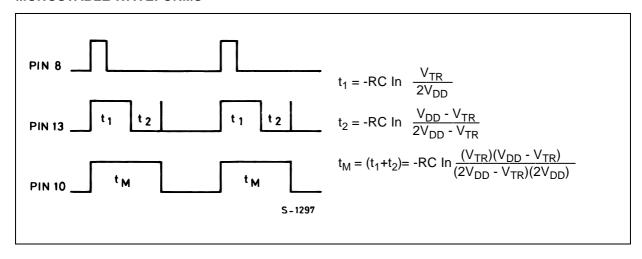
variation will be (+ 5.0%, -0.0%)

In addition to variations from unit-to-unit, the astable period may vary as a function of frequency with respect to V_{DD} and temperature.

3 - MONOSTABLE MODE

The following analysis presents worst-case variations from unit-to-unit as a function of transfer-voltage (V_{TR}) shift (33% - 67% V_{DD}) for one-shot (monostable) operation.

MONOSTABLE WAVEFORMS



Where tM = monostable mode pulse width. Values for tM are as follows :

Typ: $V_{TR} = 0.5 V_{DD} t_{M} = 2.48 RC$ Min: $V_{TR} = 0.33 V_{DD} t_{M} = 2.71 RC$ Max: $V_{TR} = 0.67 V_{DD} t_{M} = 2.48 RC$

Max : $V_{TR} = 0.67 V_{DD} t_{M} = 2.48 RC$ Thus if $t_{M} = 2.48 RC$ is used, the maximum variation will be (+ 9.3%, - 0.0%).

Note : In the astable mode, the first positive half cycle has a duration of T_M ; succeeding durations are $t_\Delta/2$.

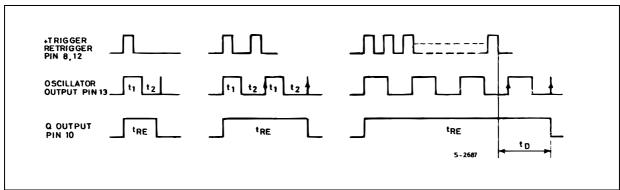
In addition to variations from unit to unit, the monostable pulse width may vary as a function of frequency with respect to V_{DD} and temperature.

4 - RETRIGGER MODE

The HCF4047B can be used in the retrigger mode

to extend the output-pulse duration, or to compare the frequency of an input signal with that of the internal oscillator. In the retrigger mode the input pulse is applied to terminals 8 and 12, and the output is taken from terminal 10 or 11. As shown in fig.A normal monostable action is obtained when one retrigger pulse is applied. Extended pulse duration is obtained when more than one pulse is applied. For two input pulses, $t_{RE} = t_1' + t_1 + 2t_2$. For more than two pulses, t_{RE} (Q OUTPUT) terminates at some variable time t_D after the termination of the last retrigger pulse. t_D is variable because t_{RE} (Q OUTPUT) terminates after the second positive edge of the oscillator output appears at flip-flop 4 (see logic diagram).

FIGURE A: Retrigger-mode waveforms



5 - EXTERNAL COUNTER OPTION

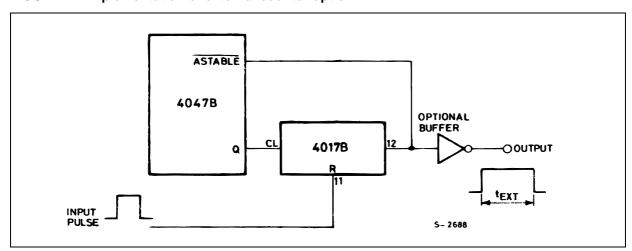
Time t_M can be extended by any amount with the use of external counting circuitry. Advantages include digitally controlled pulse duration, small timing capacitors for long time periods, and extremely fast recovery time.

A typical implementation is shown in fig. B. The pulse duration at the output is

text = $(N - 1) (t_A) + (t_M + t_A/2)$

Where text = pulse duration of the circuitry, and N is the number of counts used.

FIGURE B: Implementation of external counter option



6 - POWER CONSUMPTION

In the standby mode (Monostable or Astable), power dissipation will be a function of leakage current in the circuit, as shown in the static electrical characteristics. For dynamic operation, the power needed to charge the external timing capacitor C is given by the following formula: Astable Mode:

 $P = 2CV^2f$. (Output at Pin 13) $P = 4CV^2f$. (Output at Pin 10 and 11)

Monostable Mode : $P = \frac{(2.9CV^2) \text{ (Duty Cycle)}}{(2.9CV^2) \text{ (Duty Cycle)}}$

(Output at Pin 10 and 11)

The circuit is designed so that most of the total power is consumed in the external components. In practice, the lower the values of frequency and voltage used, the closer the actual power dissipation will be to the calculated value.

Because the power dissipation does not depend on R, a design for minimum power dissipation would be a small value of C. The value of R would depend on the desired period (within the limitations discussed above).

7 - TIMING-COMPONENT LIMITATIONS

The capacitor used in the circuit should be non-polarized and have low leakage (i.e. the parallel resistance of the capacitor should be an order of magnitude greater than the external resistor used). Three is no upper or lower limit for either R or C value to maintain oscillation.

However, in consideration of accuracy, C must be much larger than the inherent stray capacitance in the system (unless this capacitance can be measured and taken into account). R must be much larger than the COS/MOS "ON" resistance in series with it, which typically is hundreds of ohms. In addition, with very large values of R, some short-term instability with respect to time may be noted.

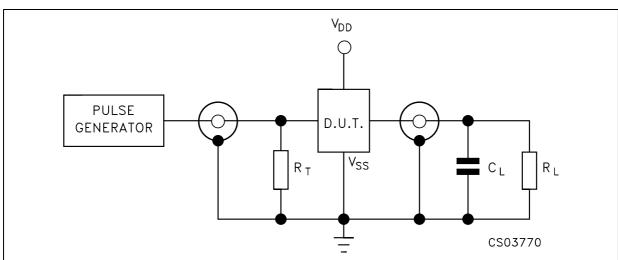
The recommended values for these components to maintain agreement with previously calculated formulas without trimming should be:

 $C \ge 100 pF$, up to any practical value, for a stable modes;

 $C \ge 1000pF$, up to any practical value, for monostable modes.

10K Ω < R < 1M Ω .

TEST CIRCUIT

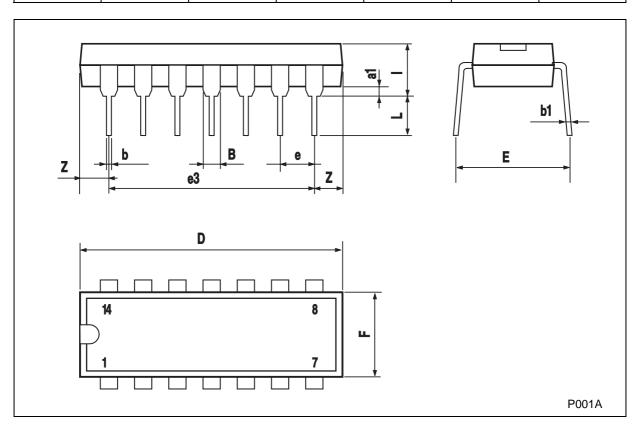


 $C_L = 50$ pF or equivalent (includes jig and probe capacitance)

 $R_T^L = Z_{OUT}$ of pulse generator (typically 50 Ω)

Plastic DIP-14 MECHANICAL DATA

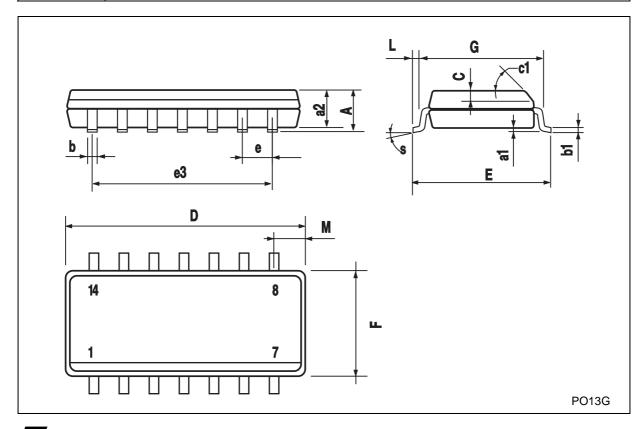
| DIM | | mm. | | inch | | | | | |
|------|------|-------|------|-------|-------|-------|--|--|--|
| DIM. | MIN. | TYP | MAX. | MIN. | TYP. | MAX. | | | |
| a1 | 0.51 | | | 0.020 | | | | | |
| В | 1.39 | | 1.65 | 0.055 | | 0.065 | | | |
| b | | 0.5 | | | 0.020 | | | | |
| b1 | | 0.25 | | | 0.010 | | | | |
| D | | | 20 | | | 0.787 | | | |
| E | | 8.5 | | | 0.335 | | | | |
| е | | 2.54 | | | 0.100 | | | | |
| e3 | | 15.24 | | | 0.600 | | | | |
| F | | | 7.1 | | | 0.280 | | | |
| I | | | 5.1 | | | 0.201 | | | |
| L | | 3.3 | | | 0.130 | | | | |
| Z | 1.27 | | 2.54 | 0.050 | | 0.100 | | | |



10/12

SO-14 MECHANICAL DATA

| DIM | | mm. | | | inch | |
|------|------|------|-------|--------|-------|-------|
| DIM. | MIN. | TYP | MAX. | MIN. | TYP. | MAX. |
| Α | | | 1.75 | | | 0.068 |
| a1 | 0.1 | | 0.2 | 0.003 | | 0.007 |
| a2 | | | 1.65 | | | 0.064 |
| b | 0.35 | | 0.46 | 0.013 | | 0.018 |
| b1 | 0.19 | | 0.25 | 0.007 | | 0.010 |
| С | | 0.5 | | | 0.019 | |
| c1 | | | 45° | (typ.) | • | |
| D | 8.55 | | 8.75 | 0.336 | | 0.344 |
| Е | 5.8 | | 6.2 | 0.228 | | 0.244 |
| е | | 1.27 | | | 0.050 | |
| e3 | | 7.62 | | | 0.300 | |
| F | 3.8 | | 4.0 | 0.149 | | 0.157 |
| G | 4.6 | | 5.3 | 0.181 | | 0.208 |
| L | 0.5 | | 1.27 | 0.019 | | 0.050 |
| М | | | 0.68 | | | 0.026 |
| S | | | 8° (ı | max.) | , | ı |



Information furnished is believed to be accurate and reliable. However, STMicroelectronics assumes no responsibility for the consequences of use of such information nor for any infringement of patents or other rights of third parties which may result from its use. No license is granted by implication or otherwise under any patent or patent rights of STMicroelectronics. Specifications mentioned in this publication are subject to change without notice. This publication supersedes and replaces all information previously supplied. STMicroelectronics products are not authorized for use as critical components in life support devices or systems without express written approval of STMicroelectronics.

© The ST logo is a registered trademark of STMicroelectronics

© 2001 STMicroelectronics - Printed in Italy - All Rights Reserved STMicroelectronics GROUP OF COMPANIES

Australia - Brazil - China - Finland - France - Germany - Hong Kong - India - Italy - Japan - Malaysia - Malta - Morocco Singapore - Spain - Sweden - Switzerland - United Kingdom © http://www.st.com

