



Differential Driver and Receiver Pair

FEATURES

- Low Power: I_{CC} = 300µA Typical
- Designed for RS485 or RS422 Applications
- Single 5V Supply
- -7V to 12V Bus Common Mode Range
 Permits ±7V Ground Difference Between Devices on the Bus
- Thermal Shutdown Protection
- Power-Up/-Down Glitch-Free Driver Outputs Permit Live Insertion or Removal of Package
- Driver Maintains High Impedance in Three-State or with the Power Off
- Combined Impedance of a Driver Output and Receiver Allows up to 32 Transceivers on the Bus
- 70mV Typical Input Hysteresis
- 28ns Typical Driver Propagation Delays with 5ns Skew for 2.5MB Operation
- Pin Compatible with the SN75180
- Available in 14-Lead PDIP and SO Packages

APPLICATIONS

- Low Power RS485/RS422 Transceiver
- Level Translator

DESCRIPTION

The LTC[®]491 is a low power differential bus/line transceiver designed for multipoint data transmission standard RS485 applications with extended common mode range (12V to -7V). It also meets the requirements of RS422.

The CMOS design offers significant power savings over its bipolar counterpart without sacrificing ruggedness against overload or ESD damage.

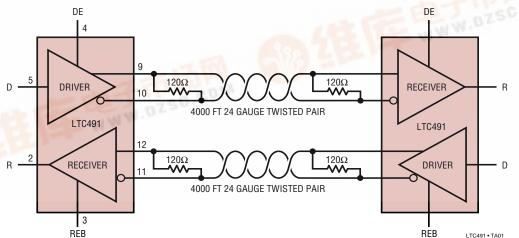
The driver and receiver feature three-state outputs, with the driver outputs maintaining high impedance over the entire common mode range. Excessive power dissipation caused by bus contention or faults is prevented by a thermal shutdown circuit which forces the driver outputs into a high impedance state.

The receiver has a fail safe feature which guarantees a high output state when the inputs are left open.

Both AC and DC specifications are guaranteed from 0°C to 70°C and 4.75V to 5.25V supply voltage range.

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TYPICAL APPLICATION

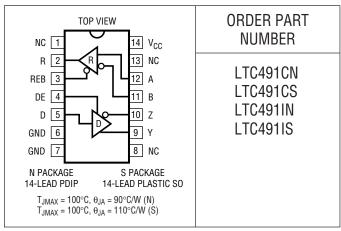




ABSOLUTE MAXIMUM RATINGS (Note 1)

| Supply Voltage (V _{CC}) | 12V |
|-----------------------------------|----------------------------|
| Control Input Voltages | |
| Control Input Currents | 50mA to 50mA |
| Driver Input Voltages | $-0.5V$ to $V_{CC} + 0.5V$ |
| Driver Input Currents | 25mA to 25mA |
| Driver Output Voltages | ±14V |
| Receiver Input Voltages | ±14V |
| Receiver Output Voltages | $-0.5V$ to $V_{CC} + 0.5V$ |
| Operating Temperature Range | |
| LTC491C | 0°C to 70°C |
| LTC491I | 40°C to 85°C |
| Storage Temperature Range | 65°C to 150°C |
| Lead Temperature (Soldering, 1 | 0 sec)300°C |
| | |

PACKAGE/ORDER INFORMATION



Consult LTC Marketing for parts specified with wider operating temperature ranges.

DC ELECTRICAL CHARACTERISTICS The \bullet denotes the specifications which apply over the full operating temperature range, otherwise specifications are at $T_A = 25^{\circ}C$. $V_{CC} = 5V \pm 5\%$

| SYMBOL | PARAMETER | CONDITIONS | | | MIN | TYP | MAX | UNITS |
|----------------------|--|---|------------------|---|------|-----|------|-------|
| $\overline{V_{0D1}}$ | Differential Driver Output Voltage (Unloaded) | I ₀ = 0 | | • | | | 5 | V |
| $\overline{V_{0D2}}$ | Differential Driver Output Voltage (With load) | R = 50Ω; (RS422) | | • | 2 | | | V |
| | | $R = 27\Omega$; (RS485) (Figure 1) | | • | 1.5 | | 5 | V |
| ΔV_{0D} | Change in Magnitude of Driver Differential Output Voltage for Complementary Output States | $R = 27\Omega$ or $R = 50\Omega$ (Figure 1) | | • | | | 0.2 | V |
| $\overline{V_{0C}}$ | Driver Common Mode Output Voltage | | | | | | 3 | V |
| Δ V _{OC} | Change in Magnitude of Driver Common Mode Output Voltage for Complementary Output States | | | • | | | 0.2 | V |
| V_{IH} | Input High Voltage | D, DE, REB | | • | 2.0 | | | V |
| V_{IL} | Input Low Voltage | | | | | | 0.8 | V |
| I _{IN1} | Input Current | | | • | | | ±2 | μА |
| I _{IN2} | Input Current (A, B) | V _{CC} = 0V or 5.25V | | • | | | 1.0 | mA |
| | | | | • | | | -0.8 | mA |
| V_{TH} | Differential Input Threshold Voltage for Receiver | -7V ≤V _{CM} ≤12V | | • | -0.2 | | 0.2 | V |
| ΔV_{TH} | Receiver Input Hysteresis | V _{CM} = 0V | | • | | 70 | | mV |
| V _{OH} | Receiver Output High Voltage | $I_0 = -4\text{mA}, V_{ID} = 0.2\text{V}$ | | • | 3.5 | | | V |
| V_{0L} | Receiver Output Low Voltage | $I_0 = 4mA, V_{ID} = -0.2V$ | | • | | | 0.4 | V |
| I _{OZR} | Three-State Output Current at Receiver | $V_{CC} = \text{Max } 0.4 \text{V} \le \text{V}_0 \le 2.4 \text{V}$ | | • | | | ±1 | μА |
| I _{CC} | Supply Current | No Load; D = GND, | Outputs Enabled | • | | 300 | 500 | μΑ |
| | | or V _{CC} | Outputs Disabled | • | | 300 | 500 | μА |
| R _{IN} | Receiver Input Resistance | -7V ≤V _{CM} ≤12V | | • | 12 | | | kΩ |
| I _{OSD1} | Driver Short Circuit Current, V _{OUT} = High | $V_0 = -7V$ | | • | | 100 | 250 | mA |
| I _{OSD2} | Driver Short Circuit Current, V _{OUT} = Low | V ₀ = 12V | | • | | 100 | 250 | mA |
| I _{OSR} | Receiver Short Circuit Current | $0V \le V_0 \le V_{CC}$ | | • | 7 | | 85 | mA |
| I _{OZ} | Driver Three-State Output Current | $V_0 = -7V \text{ to } 12V$ | | • | | ±2 | ±200 | μА |

SWITCHING CHARACTERISTICS The \bullet denotes the specifications which apply over the full operating temperature range, otherwise specifications are at $T_A = 25^{\circ}C$. $V_{CC} = 5V \pm 5\%$

| SYMBOL | PARAMETER | CONDITIONS | | MIN | TYP | MAX | UNITS |
|-------------------|--|---|---|-----|---------|-----|----------|
| t _{PLH} | Driver Input to Output | $R_{DIFF} = 54\Omega, C_{L1} = C_{L2} = 100pF$ | • | 10 | 30 | 50 | ns |
| t _{PHL} | Driver Input to Output | (Figures 2, 5) | | 10 | 30 | 50 | ns |
| t _{SKEW} | Driver Output to Output Driver Rise or Fall Time | | • | 5 | 5 15 | 25 | ns ns |
| t _{ZH} | Driver Enable to Output High | C _L = 100pF (Figures 4, 6) S2 Closed | • | | 40 | 70 | ns |
| t _{ZL} | Driver Enable to Output Low | C _L = 100pF (Figures 4, 6) S1 Closed | • | | 40 | 70 | ns |
| t_{LZ} | Driver Disable Time From Low | C _L = 15pF (Figures 4, 6) S1 Closed | • | | 40 | 70 | ns |
| t _{HZ} | Driver Disable Time From High | C _L = 15pF (Figures 4, 6) S2 Closed | • | | 40 | 70 | ns |
| t _{PLH} | Receiver Input to Output | R_{DIFF} = 54 Ω , C_{L1} = C_{L2} = 100pF (Figures 2, 7) | • | 40 | 70 | 150 | ns |
| t _{PHL} | Receiver Input to Output | | • | 40 | 70 | 150 | ns |
| t _{SKD} | t _{PLH} – t _{PHL} Differential Receiver Skew | | • | | 13 | | ns |
| t_{ZL} | Receiver Enable to Output Low | C _L = 15pF (Figures 3, 8) S1 Closed | • | | 20 | 50 | ns |
| t _{ZH} | Receiver Enable to Output High | C _L = 15pF (Figures 3, 8) S2 Closed | • | | 20 | 50 | ns |
| t_{LZ} | Receiver Disable From Low | C _L = 15pF (Figures 3, 8) S1 Closed | • | | 20 | 50 | ns |
| t _{HZ} | Receiver Disable From High | C _L = 15pF (Figures 3, 8) S2 Closed | • | | 20 | 50 | ns |

Note 1: Absolute Maximum Ratings are those values beyond which the life of the device may be impaired.

Note 2: All currents into device pins are positive; all currents out of device pins are negative. All voltages are referenced to device ground unless otherwise specified.

Note 3: All typicals are given for $V_{CC} = 5V$ and temperature = $25^{\circ}C$.

PIN FUNCTIONS

NC (Pin 1): Not Connected.

R (Pin 2): Receiver Output. If the receiver output is enabled (REB low), then if A > B by 200mV, R will be high. If A < B by 200mV, then R will be low.

REB (Pin 3): Receiver Output Enable. A low enables the receiver output, R. A high input forces the receiver output into a high impedance state.

DE (Pin 4): Driver Output Enable. A high on DE enables the driver outputs, Y and Z. A low input forces the driver outputs into a high impedance state.

D (**Pin 5**): Driver Input. If the driver outputs are enabled (DE high), then a low on D forces the driver outputs Y low and Z high. A high on D will force Y high and Z low.

GND (Pin 6): Ground Connection.

GND (Pin 7): Ground Connection.

NC (Pin 8): Not Connected.

Y (Pin 9): Driver Output.

Z (Pin 10): Driver Output.

B (Pin 11): Receiver Input.

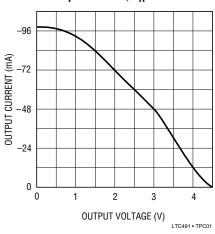
A (Pin 12): Receiver Input.

NC (Pin 13): Not Connected.

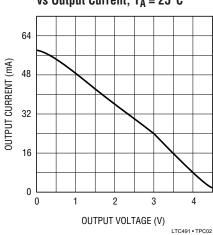
V_{CC} (**Pin 14**): Positive Supply; $4.75V \le V_{CC} \le 5.25V$.

TYPICAL PERFORMANCE CHARACTERISTICS

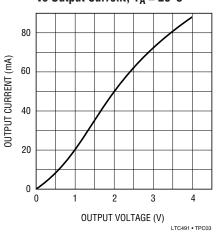
Driver Output High Voltage vs Output Current, $T_A = 25$ °C



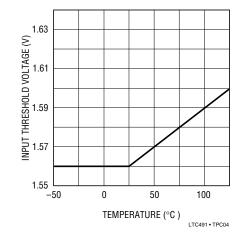
Driver Differential Output Voltage vs Output Current, T_A = 25°C



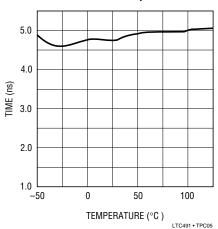
Driver Output Low Voltage vs Output Current, T_A = 25°C



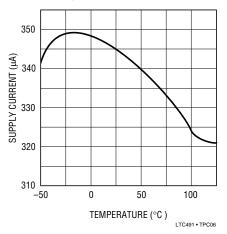
TTL Input Threshold vs Temperature



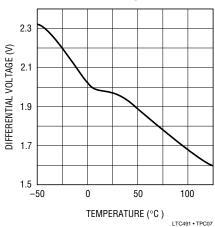
Driver Skew vs Temperature



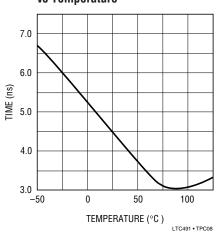
Supply Current vs Temperature



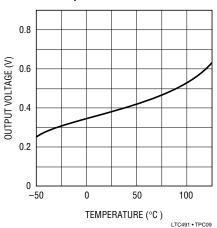
Driver Differential Output Voltage vs Temperature, $R_0 = 54\Omega$



Receiver |t_{PLH} t_{PHL} | vs Temperature



Receiver Output Low Voltage vs Temperature at I = 8mA



TEST CIRCUITS

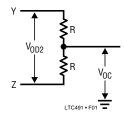


Figure 1. Driver DC Test Load

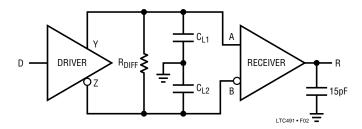


Figure 2. Driver/Receiver Timing Test Circuit

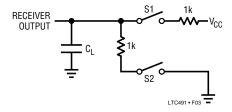


Figure 3. Receiver Timing Test Load

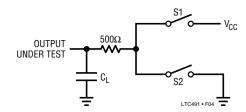


Figure 4. Driver Timing Test Load

SWITCHING TIME WAVEFORMS

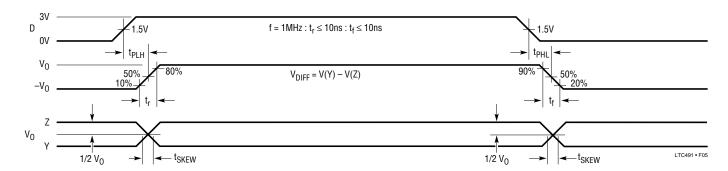


Figure 5. Driver Propagation Delays

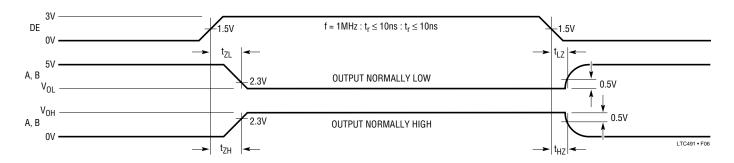


Figure 6. Driver Enable and Disable Times

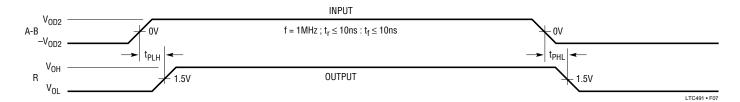


Figure 7. Receiver Propagation Delays

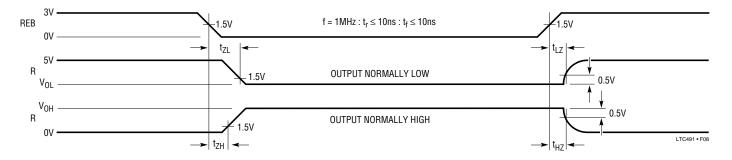


Figure 8. Receiver Enable and Disable Times

Typical Application

A typical connection of the LTC491 is shown in Figure 9. Two twisted-pair wires connect up to 32 driver/receiver pairs for full duplex data transmission. There are no restrictions on where the chips are connected to the wires, and it isn't necessary to have the chips connected at the ends. However, the wires must be terminated only at the ends with a resistor equal to their characteristic impedance, typically 120Ω . The input impedance of a receiver is typically $20k\Omega$ to GND, or 0.6 unit RS-485 load, so in practice 50 to 60 transceivers can be connected to the same wires. The optional shields around the twisted pair help reduce unwanted noise, and are connected to GND at one end.

The LTC491 can also be used as a line repeater as shown in Figure 10. If the cable length is longer than 4000 feet, the LTC491 is inserted in the middle of the cable with the receiver output connected back to the driver input.

Thermal Shutdown

The LTC491 has a thermal shutdown feature which protects the part from excessive power dissipation. If the

outputs of the driver are accidently shorted to a power supply or low impedance source, up to 250mA can flow through the part. The thermal shutdown circuit disables the driver outputs when the internal temperature reaches 150°C and turns them back on when the temperature cools to 130°C. If the outputs of two or more LTC491 drivers are shorted directly, the driver outputs can not supply enough current to activate the thermal shutdown. Thus, the thermal shutdown circuit will not prevent contention faults when two drivers are active on the bus at the same time.

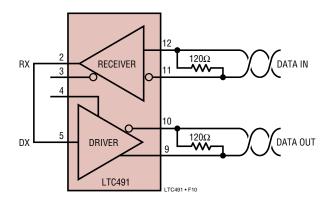


Figure 10. Line Repeater

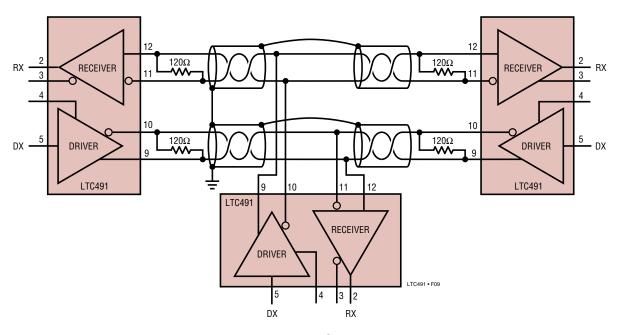


Figure 9. Typical Connection

Cables and Data Rate

The transmission line of choice for RS485 applications is a twisted pair. There are coaxial cables (twinaxial) made for this purpose that contain straight pairs, but these are less flexible, more bulky, and more costly than twisted pairs. Many cable manufacturers offer a broad range of 120Ω cables designed for RS485 applications.

Losses in a transmission line are a complex combination of DC conductor loss, AC losses (skin effect), leakage and AC losses in the dielectric. In good polyethylene cables such as the Belden 9841, the conductor losses and dielectric losses are of the same order of magnitude, leading to relatively low over all loss (Figure 11).

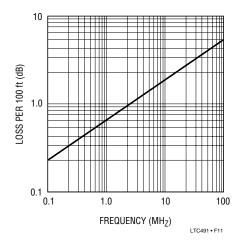


Figure 11. Attenuation vs Frequency for Belden 9481

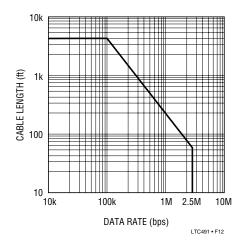


Figure 12. Cable Length vs Data Rate

When using low loss cables, Figure 12 can be used as a guideline for choosing the maximum line length for a given data rate. With lower quality PVC cables, the dielectric loss factor can be 1000 times worse. PVC twisted pairs have terrible losses at high data rates (>100kBs), and greatly reduce the maximum cable length. At low data rates however, they are acceptable and much more economical.

Cable Termination

The proper termination of the cable is very important. If the cable is not terminated with it's characteristic impedance, distorted waveforms will result. In severe cases, distorted (false) data and nulls will occur. A quick look at the output of the driver will tell how well the cable is terminated. It is best to look at a driver connected to the end of the cable, since this eliminates the possibility of getting reflections from two directions. Simply look at the driver output while transmitting square wave data. If the cable is terminated properly, the waveform will look like a square wave (Figure 13).

If the cable is loaded excessively (47Ω) , the signal initially sees the surge impedance of the cable and jumps to an initial amplitude. The signal travels down the cable and is reflected back out of phase because of the mistermination.

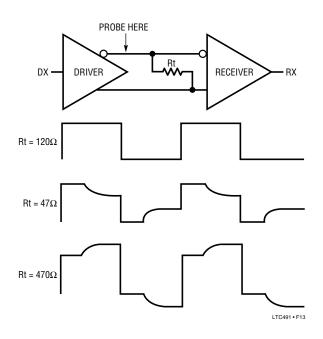


Figure 13. Termination Effects

When the reflected signal returns to the driver, the amplitude will be lowered. The width of the pedestal is equal to twice the electrical length of the cable (about 1.5ns/foot). If the cable is lightly loaded (470 Ω), the signal reflects in phase and increases the amplitude at the driver output. An input frequency of 30kHz is adequate for tests out to 4000 feet of cable.

AC Cable Termination

Cable termination resistors are necessary to prevent unwanted reflections, but they consume power. The typical differential output voltage of the driver is 2V when the cable is terminated with two 120Ω resistors, causing 33mA of DC current to flow in the cable when no data is being sent. This DC current is about 60 times greater than the supply current of the LTC491. One way to eliminate the unwanted current is by AC coupling the termination resistors as shown in Figure 14.

The coupling capacitor must allow high-frequency energy to flow to the termination, but block DC and low frequencies. The dividing line between high and low frequency depends on the length of the cable. The coupling capacitor must pass frequencies above the point where the line represents an electrical one-tenth wavelength. The value of the coupling capacitor should therefore be set at 16.3pF per foot of cable length for 120Ω cables. With the coupling capacitors in place, power is consumed only on the signal edges, and not when the driver output is idling at a 1 or 0 state. A 100nF capacitor is adequate for lines up to 4000 feet in length. Be aware that the power savings start to decrease once the data rate surpasses $1/(120\Omega \times C)$.

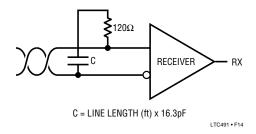


Figure 14. AC Coupled Termination

Receiver Open-Circuit Fail-Safe

Some data encoding schemes require that the output of the receiver maintains a known state (usually a logic 1) when the data is finished transmitting and all drivers on the line are forced into three-state. The receiver of the LTC491 has a fail-safe feature which guarantees the output to be in a logic 1 state when the receiver inputs are left floating (open-circuit). However, when the cable is terminated with 120Ω , the differential inputs to the receiver are shorted together, not left floating. Because the receiver has about 70mV of hysteresis, the receiver output will tend to maintain the last data bit received, but this is not guaranteed.

The termination resistors are used to generate a DC bias which forces the receiver output to a known state; in the case of Figure 15, a logic 0. The first method consumes about 208mW and the second about 8mW. The lowest power solution is to use an AC termination with a pull-up resistor. Simply swap the receiver inputs for data protocols ending in logic 1.

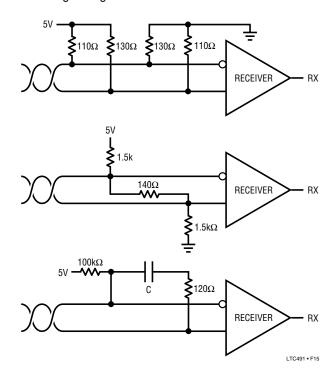


Figure 15. Forcing "O" When All Drivers are Off

Fault Protection

All of LTC's RS485 products are protected against ESD transients up to 2kV using the human body model (100pF, $1.5k\Omega$). However, some applications need more protection. The best protection method is to connect a bidirectional TransZorb® from each line side pin to ground (Figure 16).

A TransZorb is a silicon transient voltage suppressor that has exceptional surge handling capabilities, fast response time, and low series resistance. They are available from General Semiconductor Industries and come in a variety of breakdown voltages and prices. Be sure to pick a breakdown voltage higher than the common mode voltage

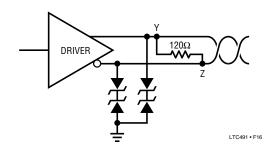


Figure 16. ESD Protection with TransZorbs

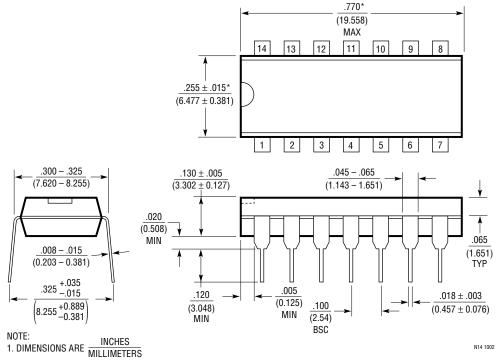
required for your application (typically 12V). Also, don't forget to check how much the added parasitic capacitance will load down the bus.

TransZorb is a registered trademark of General Instruments, GSI

PACKAGE DESCRIPTION

N Package 14-Lead PDIP (Narrow .300 Inch)

(Reference LTC DWG # 05-08-1510)

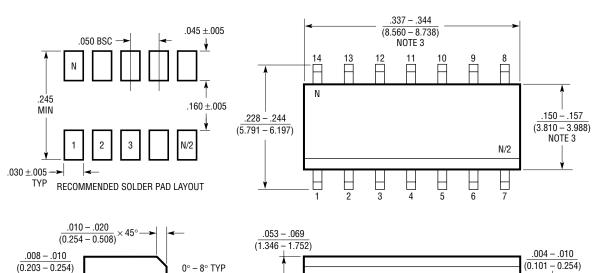


*THESE DIMENSIONS DO NOT INCLUDE MOLD FLASH OR PROTRUSIONS. MOLD FLASH OR PROTRUSIONS SHALL NOT EXCEED .010 INCH (0.254mm)

PACKAGE DESCRIPTION

S Package 14-Lead Plastic Small Outline (Narrow .150 Inch)

(Reference LTC DWG # 05-08-1610)



.014 - .019

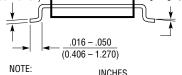
(0.355 - 0.483)

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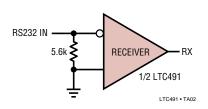
NOTE:
1. DIMENSIONS IN (MILLIMETERS)

2. DRAWING NOT TO SCALE

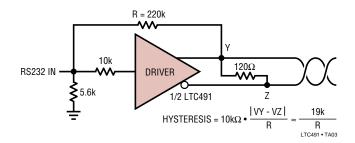
^{3.} THESE DIMENSIONS DO NOT INCLUDE MOLD FLASH OR PROTRUSIONS. MOLD FLASH OR PROTRUSIONS SHALL NOT EXCEED .006" (0.15mm)

TYPICAL APPLICATIONS

RS232 Receiver



RS232 to RS485 Level Transistor with Hysteresis



RELATED PARTS

| PART NUMBER | DESCRIPTION | COMMENTS | |
|-----------------|---|--|--|
| LTC486/LTC487 | Low Power Quad RS485 Drivers | 110µA Supply Current | |
| LTC488/LTC489 | Low Power Quad RS485 Receivers | 7mA Supply Current | |
| LTC1480 | 3.3V Supply RS485 Transceiver | Lower Supply Voltage | |
| LTC1481 | Low Power RS485 Transceiver with Shutdown | Lowest Power | |
| LTC1482 | RS485 Transceiver with Carrier Detect | ±15kV ESD, Fail-Safe | |
| LTC1483 | Low Power, Low EMI RS485 Transceiver | Slew Rate Limited Driver Outputs, Lowest Power | |
| LTC1484 | RS485 Transceiver with Fail-Safe | ±15kV ESD, MSOP Package | |
| LTC1485 | 10Mbps RS485 Transceiver | High Speed | |
| LTC1518/LTC1519 | 52Mbps Quad RS485 Receivers | Higher Speed, LTC488/LTC489 Pin-Compatible | |
| LTC1520 | LVDS-Compatible Quad Receiver | 100mV Threshold, Low Channel-to-Channel Skew | |
| LTC1535 | 2500V Isolated RS485 Transceiver | Full-Duplex, Self-Powered Using External Transformer | |
| LTC1685 | 52Mbps RS485 Transceiver | Industry-Standard Pinout, 500ps Propagation Delay Skew | |
| LTC1686/LTC1687 | 52Mbps Full-Duplex RS485 Transceiver | LTC490/LTC491 Pin Compatible | |
| LTC1688/LTC1689 | 100Mbps Quad RS485 Drivers | Highest Speed, LTC486/LTC487 Pin Compatible | |
| LTC1690 | Full-Duplex RS485 Transceiver with Fail-Safe | ±15kV ESD, LTC490 Pin Compatible | |
| LT1785/LTC1785A | ±60V Protected RS485 Transceivers | ±15kV ESD, Fail-Safe (LT1785A) | |
| LT1791/LTC1791A | ±60V Protected Full-Duplex RS485 Transceivers | ±15kV ESD, Fail-Safe (LT1791A), LTC491 Pin Compatible | |