

# SN75LBC968 9-CHANNEL BUS TRANSCEIVER WITH ACTIVE TERMINATION

SLLS179C – APRIL 1994 – REVISED JANUARY 1999

- **Nine Single-Ended SCSI Transceiver Channels With Active Termination**
- **Programmable Drivers Provide Active Negation (Totem Pole) or Wired-OR (Open Drain) Outputs**
- **24-mA Current-Mode Active Termination With Common Nine-Channel Bus Enable**
- **Low Output Capacitance Presented to SCSI Bus, 13.5 pF Typ**
- **3.3 V Compatible Logic Inputs Provide Bridge from 3 V Controllers to 5 V SCSI Bus**
- **Designed to Operate at 10-Million Data Transfers Per Second (Fast-SCSI)**
- **Controlled Driver Rise and Fall Times 5 ns Min**
- **High-Receiver Input-Voltage Hysteresis 500 mV Typ**
- **Receiver Input-Noise Pulse Filter 5 ns Typ**
- **Each Driver and Receiver Meets ANSI X3.131-1994 (SCSI-2) and the Proposed SCSI-3 Standards**
- **Power-Up/Power-Down Glitch Protection**
- **High Impedance Driver With  $V_{CC}$  at 0 V**

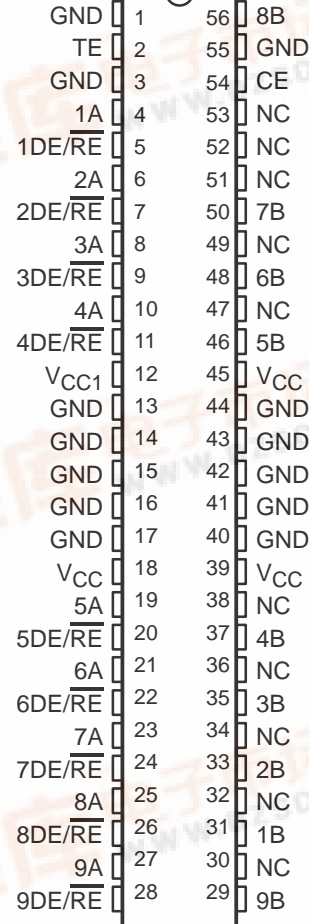
## description

The SN75LBC968 is a nine-channel transceiver with active termination that drives and receives the signals from the single-ended, parallel data buses such as the Small Computer-Systems Interface (SCSI) bus. The features of the line drivers, receivers, and active-termination circuits provide the optimum signal-to-noise ratios for reliable data transmission. Integration of the termination and transceivers in the LinBiCMOS™ process provides the necessary analog-circuit performance, has low quiescent power, and reduces the capacitance presented to the bus over separate termination and I/O circuits.

The transceivers of the SN75LBC968 can be enabled to function as totem-pole or open-drain outputs. The open-drain mode drives the wired-OR lines of SCSI (BSY, SEL, and RST) by inputting the data to the direction control input DE/RE instead of the A input. When driving the data through the A input, the outputs become totem poles and provide active signal negation for a higher voltage level on low-to-high signal transitions on heavily loaded buses. In either mode, the turn-on and turn-off output transition times are limited to minimize crosstalk through capacitive coupling to adjacent lines and RF emissions from the cable. The receivers are also designed for optimum analog performance by precisely controlling the input-voltage thresholds, providing wide input-voltage hysteresis and including an input-noise filter. These features significantly increase the likelihood of detecting only the desired data signal and rejecting noise.

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DL PACKAGE  
(TOP VIEW)



NC – No internal connection



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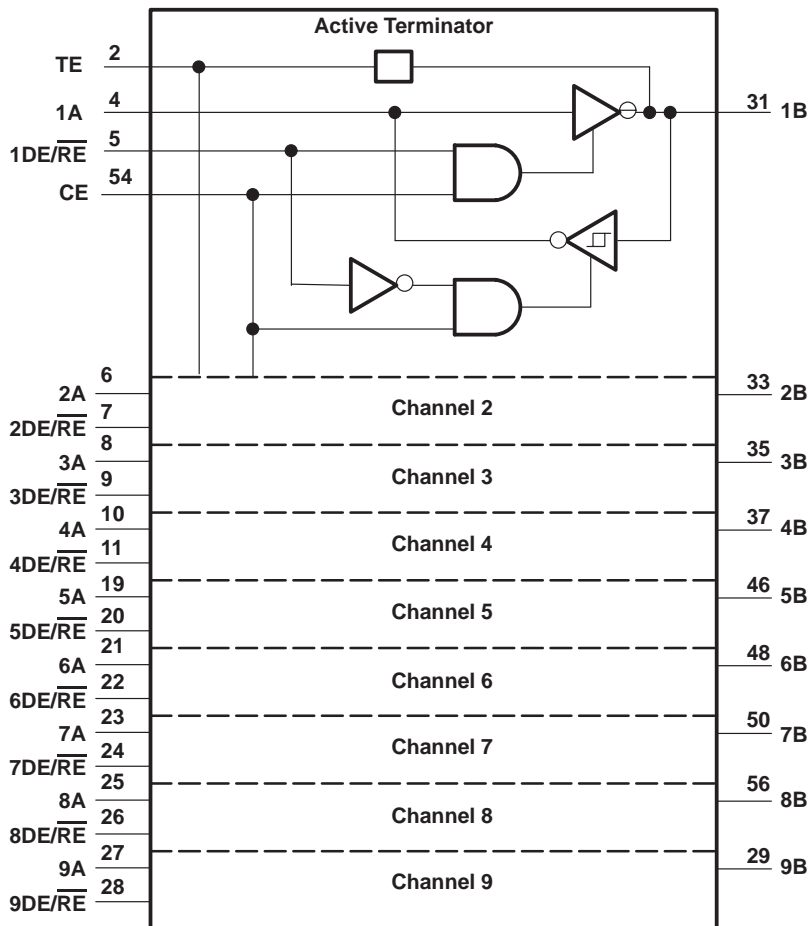
## description (continued)

The communication between the SN75LBC968 and the controller can be accomplished at 3.3-V logic levels provided that the  $V_{CC1}$  input connects to the same supply rail as the controller. This provides a bridge from the lower-voltage circuit and the 5-V SCSI bus. The SN75LBC968 also removes the need for special I/O buffers (and associated power dissipation) on the controller itself. The SN75LBC968 must be used with a SCSI controller with support for Differential SCSI.

The integrated, current-mode, active termination supplies a constant 24 mA of current (TERMPWR) to the bus when the bus voltage falls below 2.5 V. This makes the next low-to-high (negation) signal transition independent of the low-level (asserted) bus voltage, unlike voltage-mode terminators. The termination current is provided through the TE input and from TERMPWR and can be disabled by letting the TE input float or by connecting it to ground. The termination circuitry is independent from the line drivers and receivers and  $V_{CC}$  or  $V_{CC1}$ . Operational termination is present as long as TERMPWR is applied.

The switching speeds of the SN75LBC968 are sufficient to transfer data over the data bus at ten million transfers per second (Fast-SCSI). The specification,  $t_{sk(lim)}$ , is for system skew budgeting and maintenance of bus set-up and hold times. The device is available in the space-efficient shrink-small-outline package (SSOP) with 25-mil lead pitch. The SN75LBC968 meets or exceeds the requirements of ANSI X3.131–1994 (SCSI-2) and the proposed SPI (SCSI-3) standards, and is characterized for operation from 0°C to 70°C.

## logic diagram (positive logic)



## Function Tables

### TRANSCEIVER FUNCTIONS

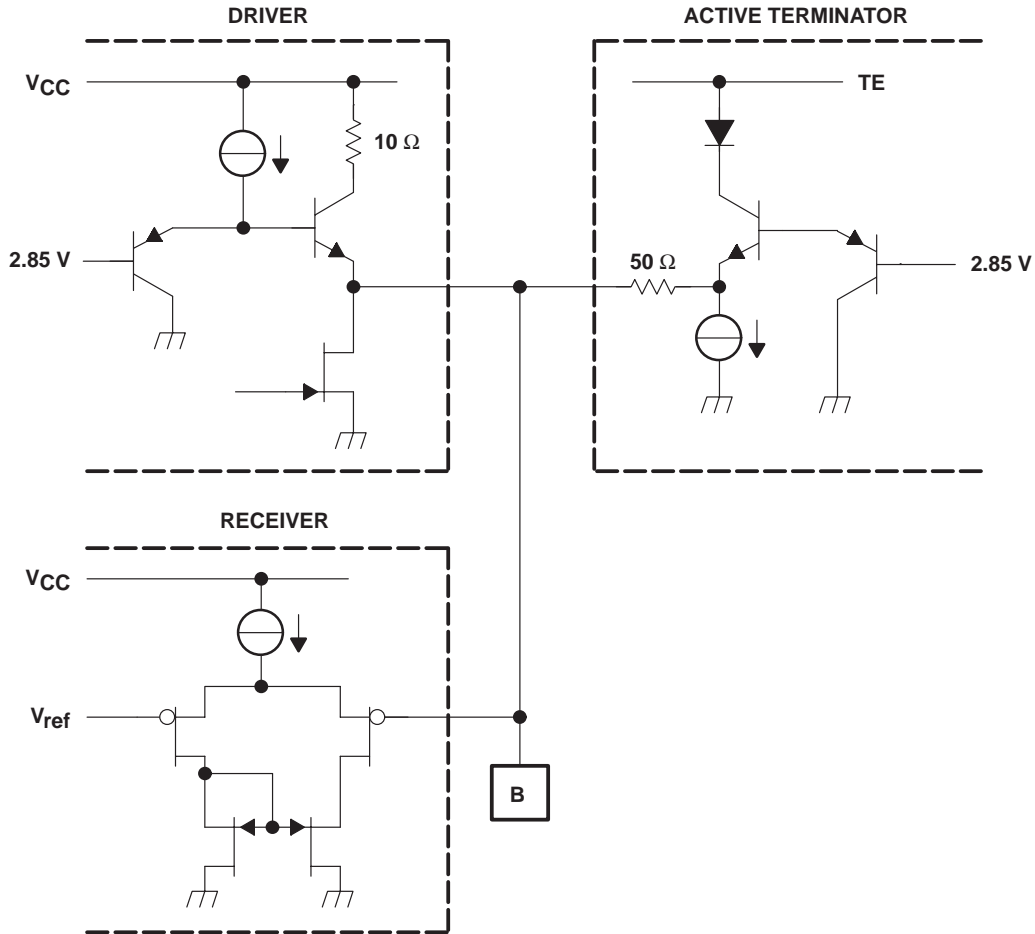
CE	DE/ $\overline{RE}$	INPUTS		OUTPUTS	
		A	B	A	B
L	X	X	X	Z	Z
H	L	X	L	H	Z
H	L	X	H	L	Z
H	H	L	X	Z	H
H	H	H	X	Z	L
H	L	X	Open	H	Z
H	H	Open	X	Z	L

H = high level L = low level  
X = irrelevant Z = high impedance

### TERMINATION FUNCTION

INPUT TE	OUTPUT B
GND	Z
$V_{TE}$	24-mA source
Open	Z

**schematics**



**absolute maximum ratings over operating free-air temperature range (unless otherwise noted)†**

Supply voltage range, $V_{CC}$ , $V_{CC1}$ , $V_{TE}$ (see Note 1)	–0.5 V to 7 V
Input voltage range, $V_I$ (A-side)	$V_{CC1} + 0.3$ V
Bus voltage range (B-side)	–0.5 V to 7 V
Data I/O and control (A-side) voltage range	–0.5 V to 7 V
Continuous power dissipation (see Note 2)	Internally Limited
Operating free-air temperature range, $T_A$	0°C to 70°C
Storage temperature range, $T_{stg}$	65°C to 150°C
Lead temperature 1,6 mm (1/16 inch) from case for 10 seconds	260°C

† Stresses beyond those listed under “absolute maximum ratings” may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under “recommended operating conditions” is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

- NOTES: 1. All voltage values are with respect to GND.  
 2. The maximum operating-junction temperature is internally limited. Use the dissipation rating table to operate below this temperature.

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DISSIPATION RATING TABLE

PACKAGE	$T_A \leq 25^\circ\text{C}$ POWER RATING	DERATING FACTOR† ABOVE $T_A = 25^\circ\text{C}$	$T_A = 70^\circ\text{C}$ POWER RATING
DL	2500 mW	20 mW/°C	1600 mW

† Derating factors are the inverse of the junction-to-ambient thermal resistance when board-mounted with no air flow.

### recommended operating conditions

	MIN	NOM	MAX	UNIT
Supply voltage, $V_{CC}$	4.75	5	5.25	V
Supply voltage, $V_{CC1}$ (see Note 3)	3		5.25	V
Termination voltage, $V_{TE}$	4.25		5.25	V
High-level input voltage, $V_{IH}$	DE/ $\overline{RE}$ , CE, A, B		2	V
Low-level input voltage, $V_{IL}$	DE/ $\overline{RE}$ , CE, A, B		0.8	V
High-level output current, $I_{OH}$	A		-8	mA
Low-level output current, $I_{OL}$	B		48	mA
	A		8	
Operating free-air temperature, $T_A$	0		70	°C

NOTE 3: All electrical characteristics are measured with  $V_{CC1} = V_{CC}$  unless otherwise noted.

### driver electrical characteristics over recommended operating conditions (unless otherwise noted) (see Figure 1)

PARAMETER	TEST CONDITIONS	MIN	MAX	UNIT
$V_{OH}$ High-level output voltage	$I_{OH} = -20$ mA	2		V
$V_{OL}$ Low-level output voltage	$I_{OL} = 48$ mA		0.5	V
$I_{IH}$ High-level input current	$V_{IH} = 2$ V, $V_{CC} = V_{CC1} = 5.25$ V		-100	$\mu$ A
$I_{IL}$ Low-level input current, A	$V_{IL} = 0.5$ V, $V_{CC} = V_{CC1} = 5.25$ V		-100	$\mu$ A
$I_{OZ}$ High-impedance-state output current	$V_O = 5.25$ V, $V_{CC} = V_{CC1} = 5.25$ V		-100	$\mu$ A
	$V_O = 0$ V, $V_{CC} = V_{CC1} = 5.25$ V		-100	

### termination electrical characteristics over recommended operating conditions (unless otherwise noted) (see Figure 2)

PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
$V_{O(OC)}$ Open-circuit output voltage	$I_O = 0$ mA, $V_{CC} = V_{CC1} = 0$ V	2.5	2.85	3.24	V
$I_O$ Output current	$V_O = 0$ V, $V_{CC} = V_{CC1} = 0$ V			-24	mA
	$V_O = 0.5$ V, $V_{CC} = V_{CC1} = 0$ V			-20	mA
	$V_O = 3$ V, $V_{CC} = V_{CC1} = 0$ V			100	$\mu$ A
	$V_O = 4$ V, $V_{CC} = V_{CC1} = 0$ V			2	12

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receiver electrical characteristics over recommended operating conditions (unless otherwise noted) (see Figure 3)

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
V <sub>OH</sub>	High-level output voltage	I <sub>OH</sub> = -8 mA	2	2.5		V
V <sub>OL</sub>	Low-level output voltage	I <sub>OL</sub> = 8 mA			0.8	V
V <sub>IT+</sub>	Positive-going input threshold voltage	V <sub>CC</sub> = V <sub>CC1</sub>	1.2	1.6	2	V
V <sub>IT-</sub>	Negative-going input threshold voltage		0.8	1.1	1.4	V
V <sub>hys</sub>	Input hysteresis voltage (V <sub>IT+</sub> - V <sub>IT-</sub> )		0.2	0.5		V
I <sub>IH</sub>	High-level input current	V <sub>IH</sub> = 2 V			100	μA
I <sub>IL</sub>	Low-level input current	V <sub>IL</sub> = 0.5 V			100	μA
I <sub>OZ</sub>	High-impedance-state output current	V <sub>O</sub> = 0 V			-100	μA
		V <sub>O</sub> = 5.25 V			-100	

device electrical characteristics over recommended operating conditions (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP†	MAX	UNIT
I <sub>CC</sub>	Supply current to V <sub>CC</sub> and V <sub>CC1</sub>	All drivers, receivers, and terminator disabled	All inputs at 0 V	1.3	3	mA
		All receivers enabled, termination and drivers disabled, No load	CE at V <sub>CC</sub> , DE/ $\overline{RE}$ at 0 V, TE at 0 V	14	21	
		All drivers enabled, termination and receivers disabled, No load	DE/ $\overline{RE}$ and CE at V <sub>CC</sub> , A and TE at 0 V	33	45	
			DE/ $\overline{RE}$ and CE at V <sub>CC</sub> , V <sub>TE</sub> = 0 V, A at V <sub>CC1</sub>	15	21	
I <sub>CC</sub>	Supply current to TE	Termination and receivers enabled, No load	TE at V <sub>TE</sub> , DE/ $\overline{RE}$ at 0 V	33	45	
C <sub>O</sub>	Bus port capacitance (see Note 4)			13.5	16.5	pF
I <sub>IH</sub>	High-level input current	DE/ $\overline{RE}$ , CE	V <sub>IH</sub> = V <sub>CC</sub> or 2 V		100	μA
I <sub>IL</sub>	Low-level input current	DE/ $\overline{RE}$ , CE	V <sub>IL</sub> = 0.5 V		100	μA

† All typical values are at V<sub>CC</sub> = V<sub>CC1</sub> = 5 V, T<sub>A</sub> = 25°C.

NOTE 4: Tested in accordance with Annex G X3T9.2/855D, revision 14

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#### driver switching characteristics over recommended operating conditions (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP†	MAX	UNIT
t <sub>PHL</sub>	Propagation delay time, high- to low-level output (see Figure 4)	C <sub>L</sub> = 15 pF	10		35	ns
t <sub>PLH</sub>	Propagation delay time, low- to high-level output (see Figure 4)		15		45	ns
t <sub>sk(lim)</sub>	Skew limit‡, the maximum delay time – minimum delay time	V <sub>CC</sub> = V <sub>CC1</sub> = 5 V, T <sub>A</sub> = 25°C, C <sub>L</sub> = 15 pF			14	ns
		V <sub>CC</sub> = V <sub>CC1</sub> = 5 V, T <sub>A</sub> = 70°C, C <sub>L</sub> = 15 pF			14	ns
t <sub>sk(p)</sub>	Pulse skew,  t <sub>PHL</sub> – t <sub>PLH</sub>	V <sub>CC</sub> = V <sub>CC1</sub> = 5 V, T <sub>A</sub> = 25°C		8		ns
t <sub>t</sub>	Output transition time, 10% to 90% or 90% to 10% of the steady-state output	15 pF < C <sub>L</sub> < 100 pF	5		20	ns
t <sub>PLZ</sub>	Propagation delay time, low-level to high-impedance output (see Figure 5)	From CE, C <sub>L</sub> = 15 pF	5		150	ns
		From DE/ $\overline{RE}$ , C <sub>L</sub> = 15 pF			45	
t <sub>PZL</sub>	Propagation delay time, high-impedance to low-level output (see Figure 5)	From CE, C <sub>L</sub> = 15 pF	5		150	ns
		From DE/ $\overline{RE}$ , C <sub>L</sub> = 15 pF			45	

† All typical values are at V<sub>CC</sub> = V<sub>CC1</sub> = 5 V, T<sub>A</sub> = 25°C.

‡ The value for this parameter was derived from the difference between the slowest and the fastest driver delay times measured on devices from four sample wafer lots.

#### receiver switching characteristics over recommended of operating conditions (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN	TYP†	MAX	UNIT
t <sub>PHL</sub>	Propagation delay time, high- to low-level output	See Figure 6	5		20	ns
t <sub>PLH</sub>	Propagation delay time, low- to high-level output		5		25	ns
t <sub>sk(lim)</sub>	Skew limit‡, the maximum delay time – minimum delay time	V <sub>CC</sub> = V <sub>CC1</sub> = 5 V, T <sub>A</sub> = 25°C, See Figure 6			8.5	ns
		V <sub>CC</sub> = V <sub>CC1</sub> = 5 V, T <sub>A</sub> = 70°C, See Figure 6			8.5	ns
t <sub>sk(p)</sub>	Pulse skew,  t <sub>PHL</sub> – t <sub>PLH</sub>	V <sub>CC</sub> = V <sub>CC1</sub> = 5 V, T <sub>A</sub> = 25°C, See Figure 6		6		ns
t <sub>PLZ</sub>	Propagation delay time, low-level to high-impedance output	From CE, See Figure 7	5		150	ns
		From DE/ $\overline{RE}$ , See Figure 7			45	
t <sub>PZL</sub>	Propagation delay time, high-impedance to low-level output	From CE, See Figure 7	5		150	ns
		From DE/ $\overline{RE}$ , See Figure 7			80	
t <sub>PHZ</sub>	Propagation delay time, high-level to high-impedance output	From CE, See Figure 8	5		150	ns
		From DE/ $\overline{RE}$ , See Figure 8			45	
t <sub>PZH</sub>	Propagation delay time, high-impedance to high-level output	From CE, See Figure 8	5		150	ns
		From DE/ $\overline{RE}$ , See Figure 8			80	

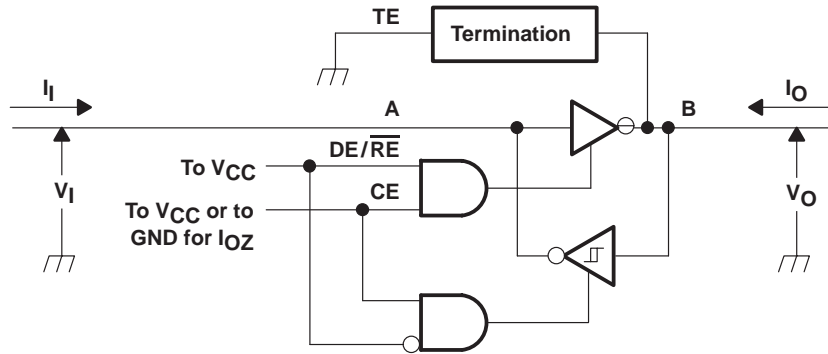
† All typical values are at V<sub>CC</sub> = V<sub>CC1</sub> = 5 V, T<sub>A</sub> = 25°C.

‡ The value for this parameter was derived from the difference between the slowest and the fastest driver delay times measured on devices from four sample wafer lots.

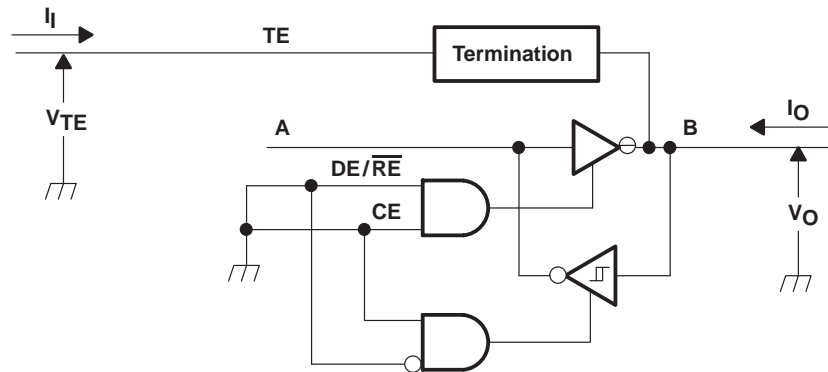
#### thermal characteristics

PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
R <sub>θJA</sub>	Junction-to-free-air thermal resistance	Board-mounted, no air flow		50		°C/W
R <sub>θJC</sub>	Junction-to-case thermal resistance			12		°C/W
T <sub>JS</sub>	Junction-shutdown temperature			180		°C

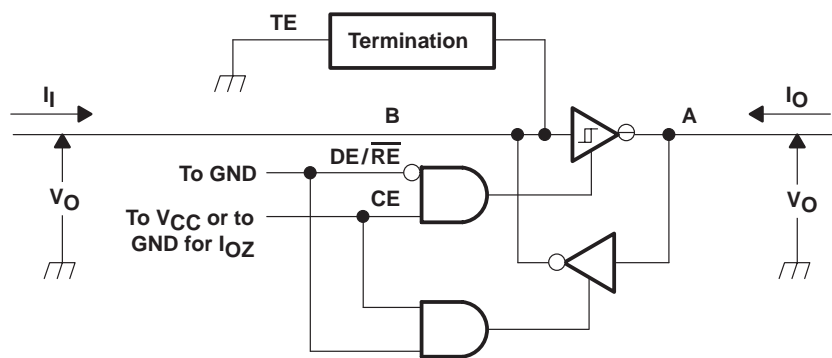
**PARAMETER MEASUREMENT INFORMATION**



**Figure 1. Driver Test Circuit Currents and Voltages.**



**Figure 2. Active Termination Voltages, Currents, and Test Circuit.**



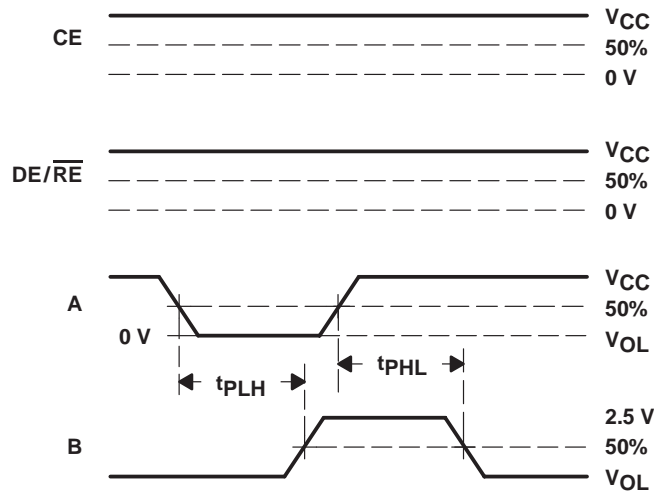
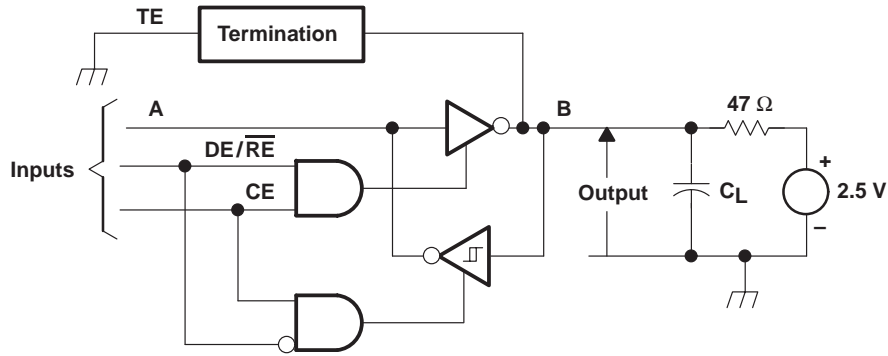
**Figure 3. Receiver Voltages, Currents, and Test Circuit**

- NOTES: A. All input pulses are supplied by a generator having the following characteristics:  $t_r \leq 6 \text{ ns}$ ,  $t_f \leq 6 \text{ ns}$ ,  $\text{PRR} \leq 1 \text{ MHz}$ , duty cycle = 50%,  $Z_O = 50 \Omega$ .
- B. All resistances are in ohms and  $\pm 5\%$ , unless otherwise indicated.
- C. All capacitances are in picofarads and  $\pm 10\%$ , unless otherwise indicated.
- D. All indicated voltages are  $\pm 10 \text{ mV}$ .

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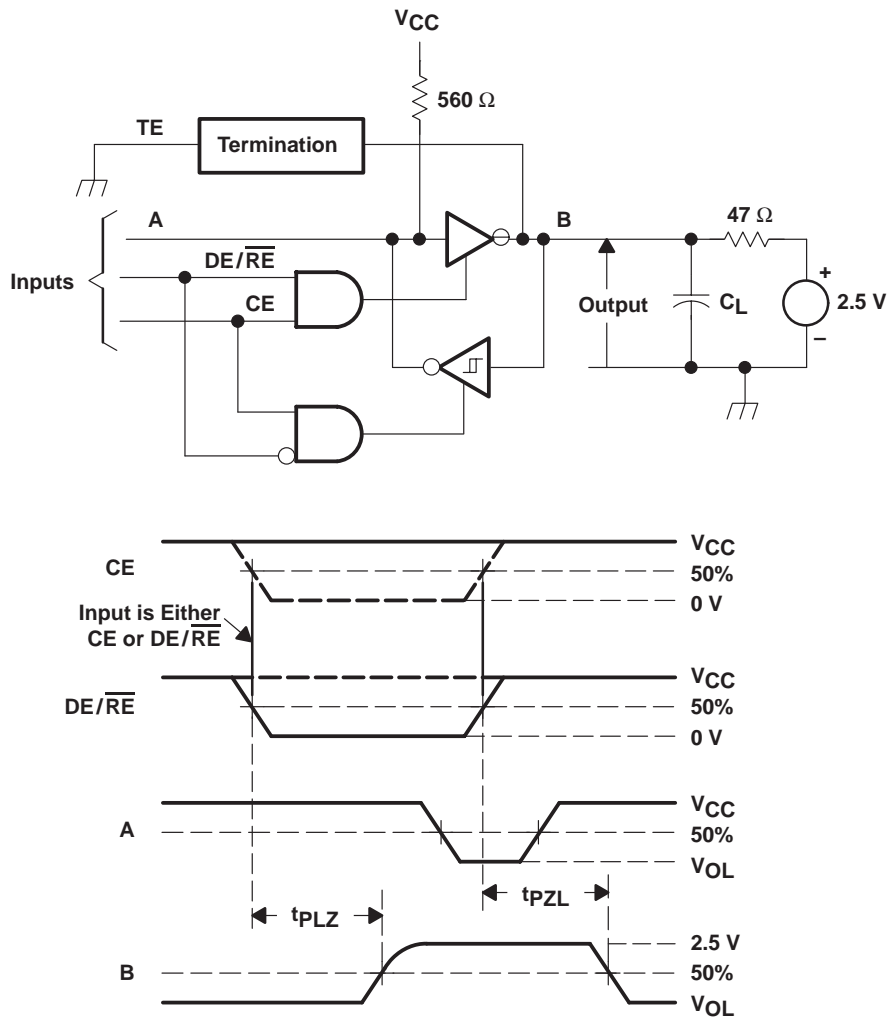
**PARAMETER MEASUREMENT INFORMATION**



- NOTES: A. All input pulses are supplied by a generator having the following characteristics:  $t_r \leq 6$  ns,  $t_f \leq 6$  ns, PRR  $\leq 1$  MHz, duty cycle = 50%,  $Z_O = 50 \Omega$ .  
 B. All resistances are in ohms and  $\pm 5\%$ , unless otherwise indicated.  
 C. All capacitances are in picofarads and  $\pm 10\%$ , unless otherwise indicated.  
 D. All indicated voltages are  $\pm 10$  mV.

**Figure 4. Driver Delay Time Test Circuit and Waveforms**





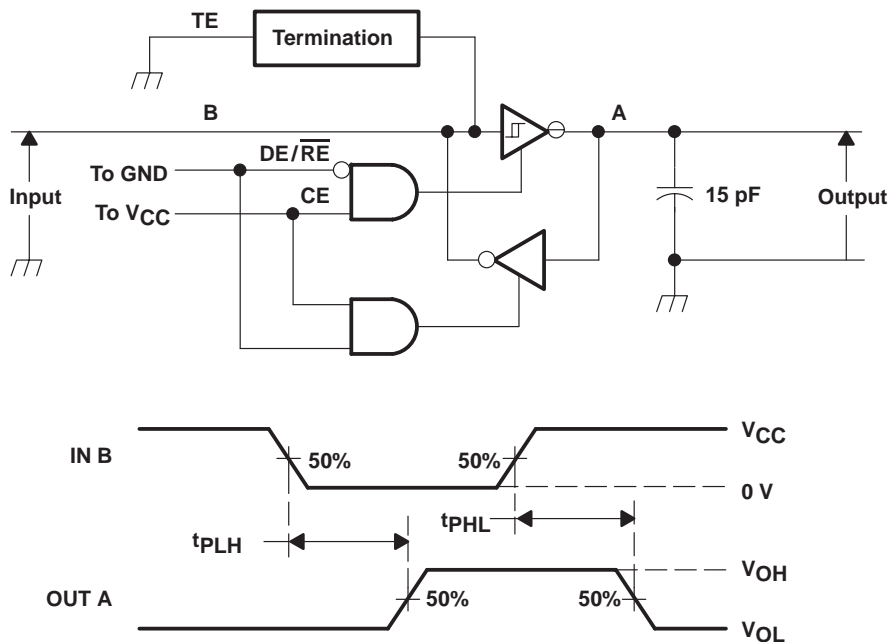
- NOTES: A. All input pulses are supplied by a generator having the following characteristics:  $t_r \leq 6$  ns,  $t_f \leq 6$  ns,  $PRR \leq 1$  MHz, duty cycle = 50%,  $Z_O = 50$  Ω.
- B. All resistances are in ohms and  $\pm 5\%$ , unless otherwise indicated.
- C. All capacitances are in picofarads and  $\pm 10\%$ , unless otherwise indicated.
- D. All indicated voltages are  $\pm 10$  mV.

**Figure 5. Driver Delay Time Test Circuit and Waveforms**

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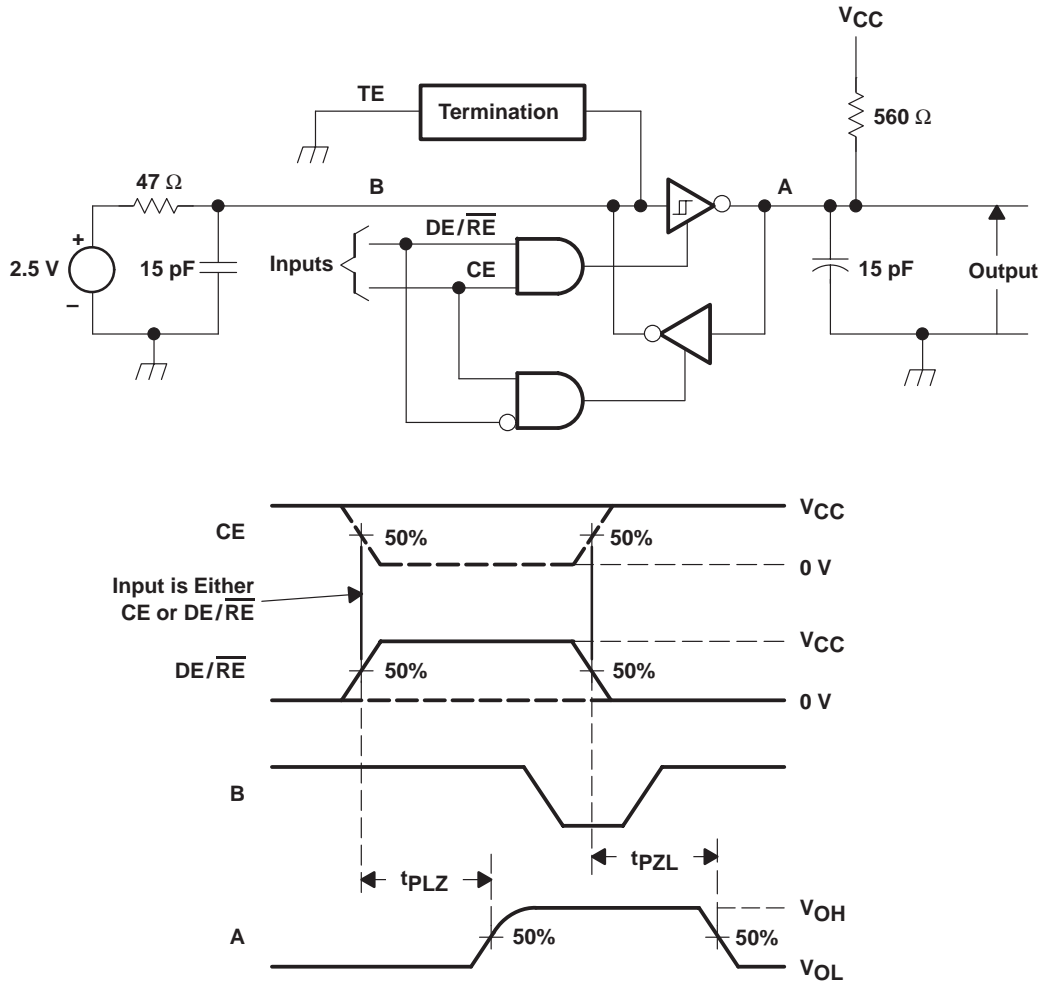
**PARAMETER MEASUREMENT INFORMATION**



- NOTES: A. All input pulses are supplied by a generator having the following characteristics:  $t_r \leq 6$  ns,  $t_f \leq 6$  ns, PRR  $\leq 1$  MHz, duty cycle = 50%,  $Z_O = 50 \Omega$ .  
 B. All resistances are in ohms and  $\pm 5\%$ , unless otherwise indicated.  
 C. All capacitances are in picofarads and  $\pm 10\%$ , unless otherwise indicated.  
 D. All indicated voltages are  $\pm 10$  mV.

**Figure 6. Receiver Propagation Delay Time Test Circuit and Waveforms**

**PARAMETER MEASUREMENT INFORMATION**

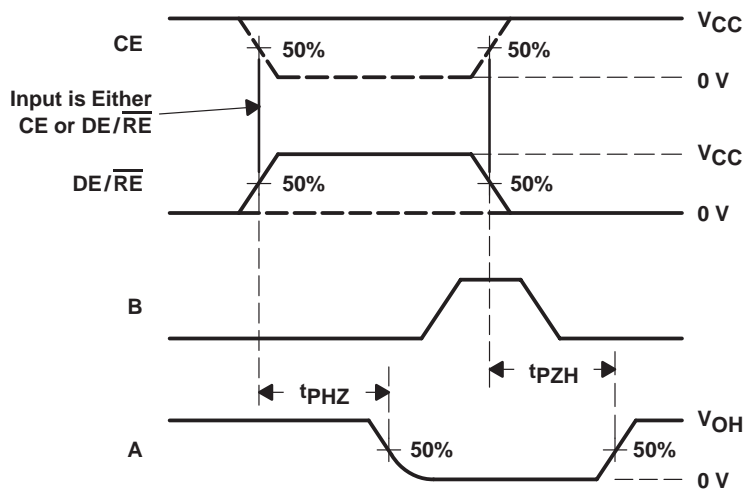
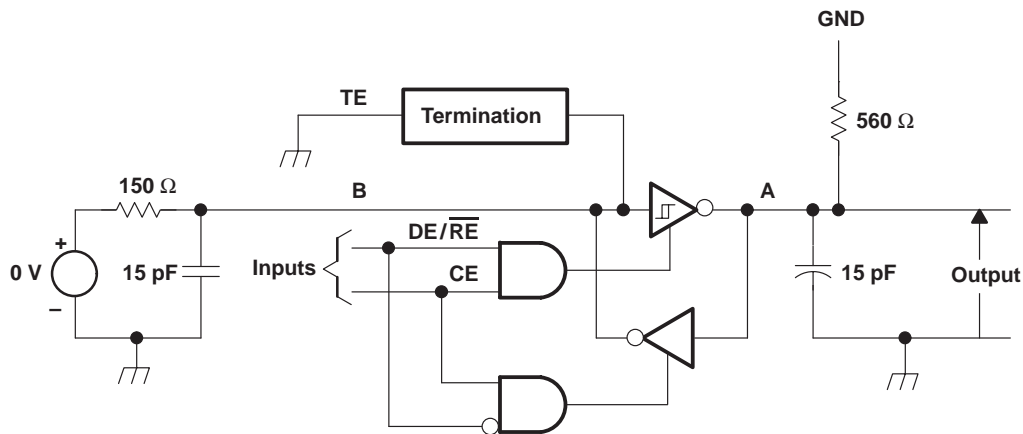


- NOTES: A. All input pulses are supplied by a generator having the following characteristics:  $t_r \leq 6$  ns,  $t_f \leq 6$  ns,  $PRR \leq 1$  MHz, duty cycle = 50%,  $Z_O = 50$  Ω.  
 B. All resistances are in ohms and  $\pm 5\%$ , unless otherwise indicated.  
 C. All capacitances are in picofarads and  $\pm 10\%$ , unless otherwise indicated.  
 D. All indicated voltages are  $\pm 10$  mV.

**Figure 7. Receiver Enable and Disable Times to and From Low-Level Output Test Circuit and Waveforms**

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**PARAMETER MEASUREMENT INFORMATION**



- NOTES: A. All input pulses are supplied by a generator having the following characteristics:  $t_r \leq 6$  ns,  $t_f \leq 6$  ns, PRR  $\leq 1$  MHz, duty cycle = 50%,  $Z_O = 50 \Omega$ .  
 B. All resistances are in ohms and  $\pm 5\%$ , unless otherwise indicated.  
 C. All capacitances are in picofarads and  $\pm 10\%$ , unless otherwise indicated.  
 D. All indicated voltages are  $\pm 10$  mV.

**Figure 8. Receiver Enable and Disable Times to and From High-Level Output Test Circuit and Waveforms**

**TYPICAL CHARACTERISTICS**

DRIVER AND TERMINATION  
 LOW-LEVEL OUTPUT VOLTAGE  
 vs  
 LOW-LEVEL OUTPUT CURRENT

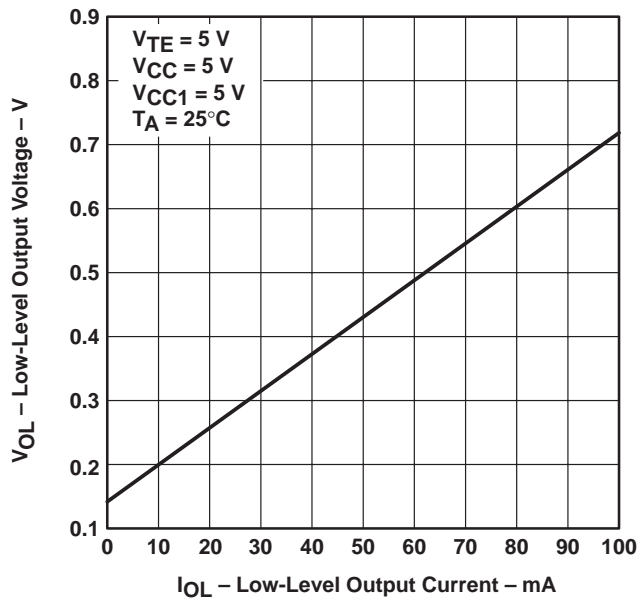


Figure 9

TERMINATION  
 OUTPUT VOLTAGE  
 vs  
 OUTPUT CURRENT

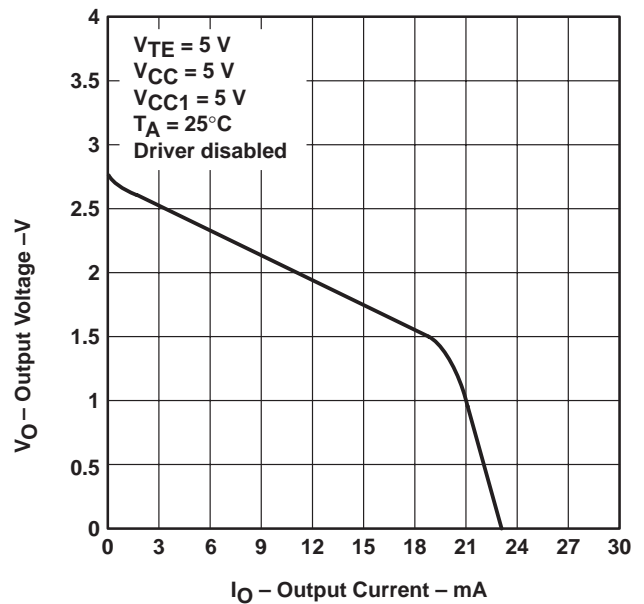


Figure 10

DRIVER  
 LOW-LEVEL OUTPUT VOLTAGE  
 vs  
 LOW-LEVEL OUTPUT CURRENT

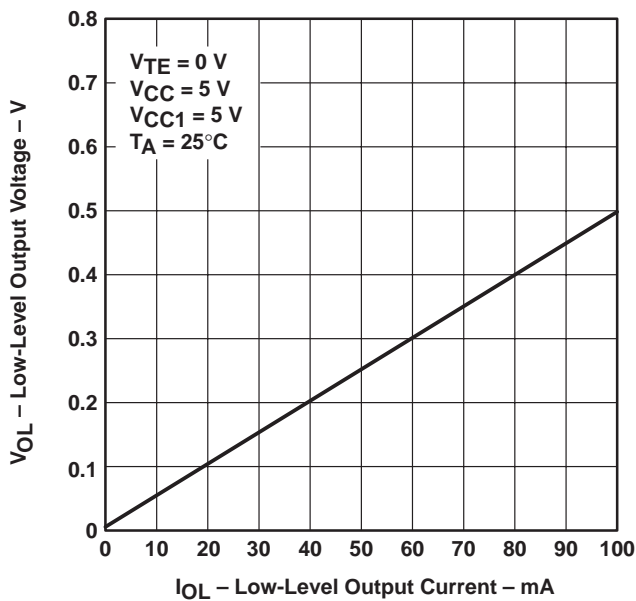


Figure 11

DRIVER  
 HIGH-LEVEL OUTPUT VOLTAGE  
 vs  
 HIGH-LEVEL OUTPUT CURRENT

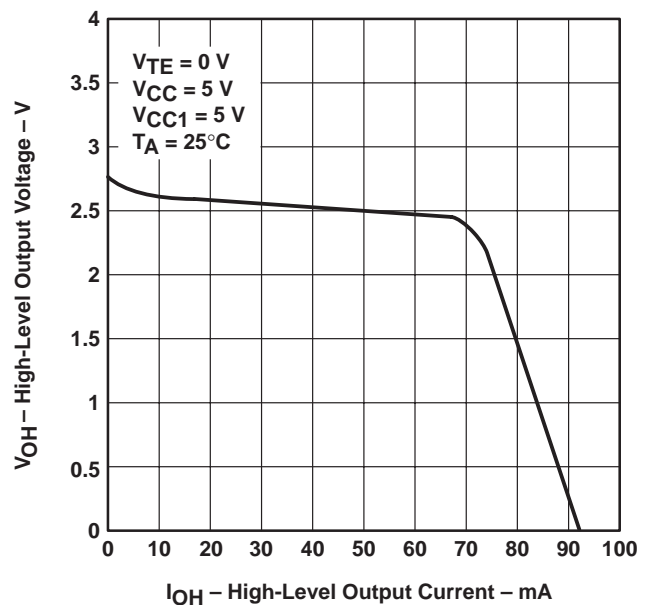
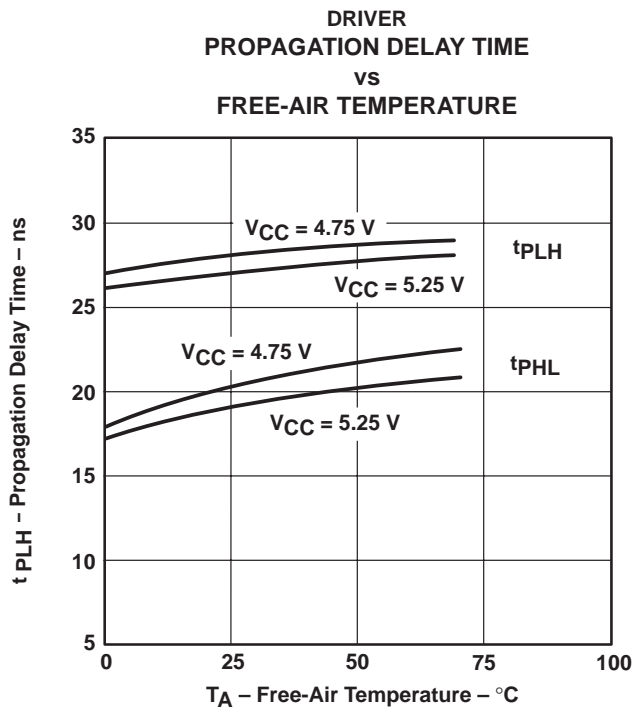


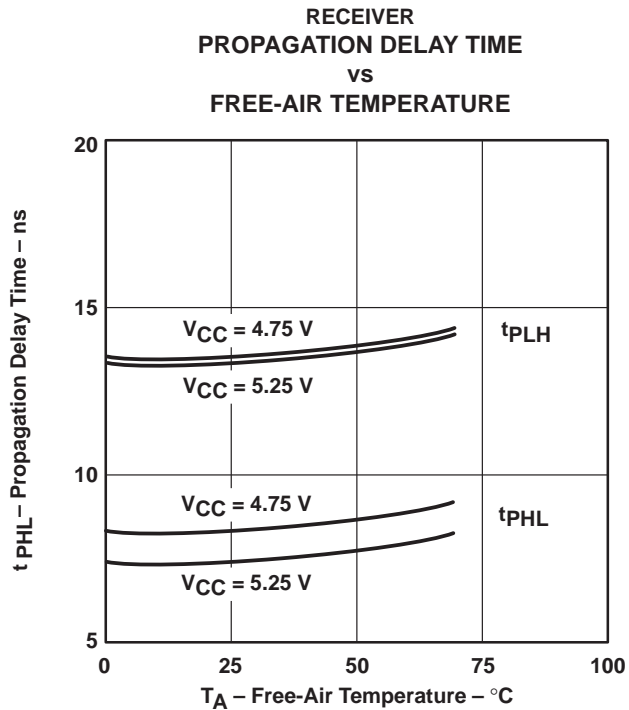
Figure 12

**SN75LBC968**  
**9-CHANNEL BUS TRANSCEIVER**  
**WITH ACTIVE TERMINATION**  
 SLLS179C – APRIL 1994 – REVISED JANUARY 1999

**TYPICAL CHARACTERISTICS**



**Figure 13**



**Figure 14**

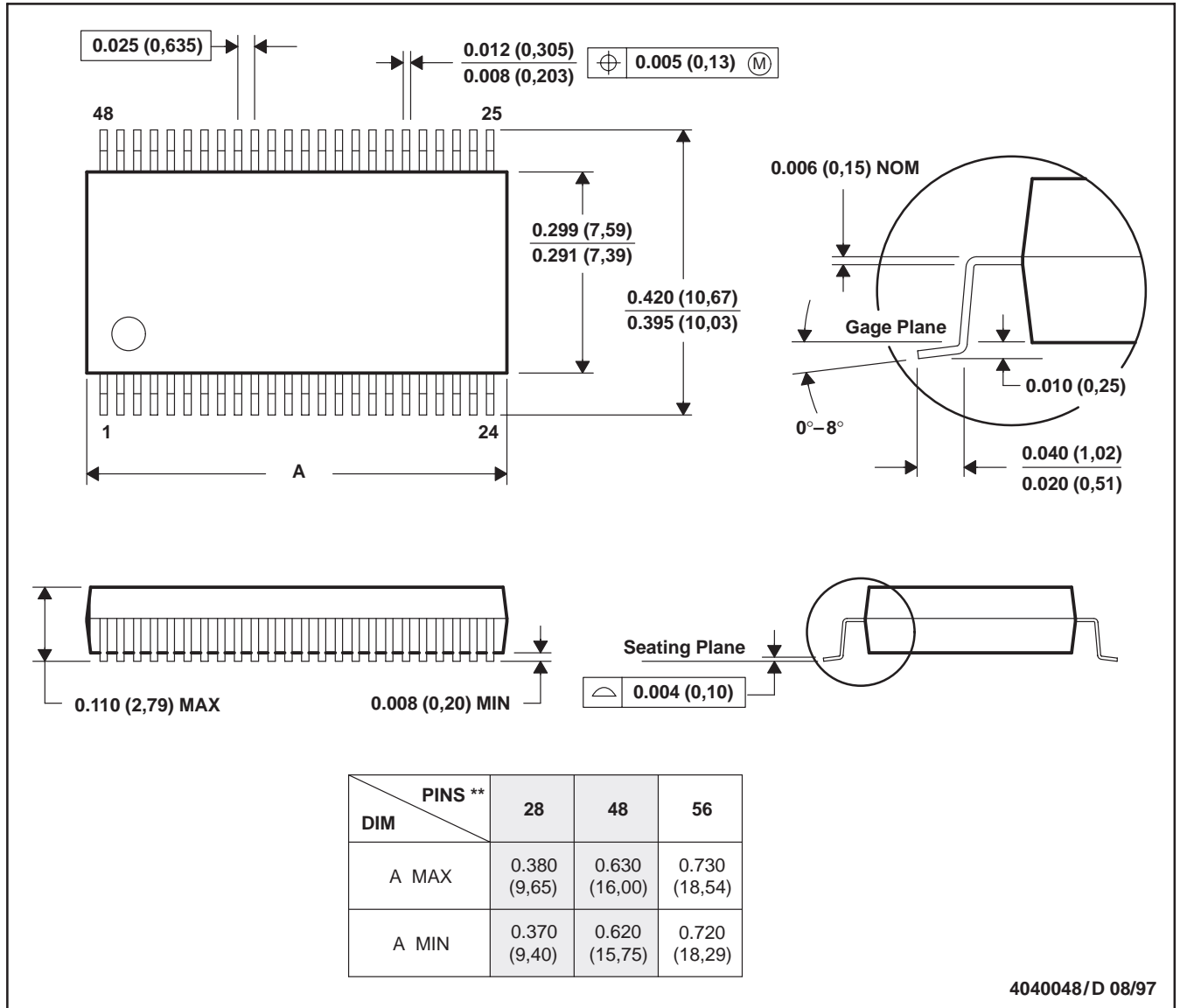
**SN75LBC968**  
**9-CHANNEL BUS TRANSCEIVER**  
**WITH ACTIVE TERMINATION**  
 SLLS179C – APRIL 1994 – REVISED JANUARY 1999

**MECHANICAL DATA**

**DL (R-PDSO-G\*\*)**

**PLASTIC SMALL-OUTLINE PACKAGE**

48-PIN SHOWN



- NOTES: A. All linear dimensions are in inches (millimeters).  
 B. This drawing is subject to change without notice.  
 C. Body dimensions do not include mold flash or protrusion not to exceed 0.006 (0,15).  
 D. Falls within JEDEC MO-118

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