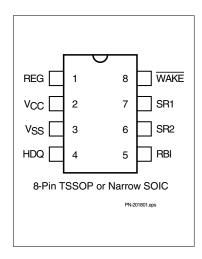
Features

- Multifunction charge/discharge counter
- ► Resolves signals less than 12.5μ V
- Internal offset calibration improves accuracy
- ➤ 1024 bits of NVRAM configured as 128 x 8
- Internal temperature sensor for self-discharge estimation
- ► Single-wire serial interface
- ► Dual operating modes:
 - Operating: <80µA
 - Sleep: <10µA
- REG output for low-cost microregulation
- Internal timebase eliminates external components
- 8-pin TSSOP or SOIC allows battery pack integration

Pin Connections



General Description

The bq2018 is a low-cost charge/discharge counter peripheral packaged in an 8-pin TSSOP or SOIC. It works with an intelligent host controller, providing state-of-charge information for rechargeable batteries.

The bq2018 measures the voltage drop across a low-value series sense resistor between the negative terminal of the battery and the battery pack ground contact. By using the accumulated counts in the charge, discharge, and self-discharge registers, an intelligent host controller can determine battery state-of-charge information. To improve accuracy, an offset count register is available. The system host controller is responsible for the register maintenance by resetting the charge in/out and selfdischarge registers as needed. The bq2018 also features 128 bytes of NVRAM registers. The upper 13 bytes of NVRAM contain the capacity monitoring and status information. The RBI input operates from an external power storage source such as a capacitor or a series cell in the battery pack, providing register nonvolatility for periods when the battery is shorted to ground or when the battery charge state is not sufficient to operate the bq2018. During this mode, the register backup current is less than 100nA.

Power Minder[™] IC

Packaged in an 8-pin TSSOP or SOIC, the bq2018 is small enough to fit in the crevice between two Asize cells or within the width of a prismatic cell.

Pin Names

REG	Regulator output	WAKE	Wake-up output
V_{CC}	Supply voltage input	SR1	Current sense input 1
V _{SS}	Ground	SR2	Current sense input 2
HDQ	Data input/output	RBI	Register backup input

SLUS003–JUNE 1999 C

Pin Descriptions

REG Regulator output

REG is the output of the operational transconductance amplifier (OTA) that drives an external pass n-channel JFET to provide an optional regulated supply. The supply is regulated at 3.7V nominal.

V_{CC} Supply voltage input

When regulated by the REG output, V_{CC} is 3.7V $\pm 200mV.$ When the REG output is not used, the valid operating range is 2.8V to 5.5V.

V_{SS} Ground

SR1- Current sense inputs

SR2

The bq2018 interprets charge and discharge activity by monitoring and integrating the voltage drop (V_{SR}) across pins SR1 and SR2. The SR1 input connects to the sense resistor and the negative terminal of the battery. The SR2 input connects to the sense resistor and the negative terminal of the pack. V_{SR1} indicates discharge, and $V_{SR1} > V_{SR2}$ indicates discharge, and $V_{SR1} > V_{SR2}$ indicates charge. The effective voltage drop, V_{SR0} , as seen by the bq2018, is $V_{SR} + V_{OS}$. Valid input range is \pm 200mV.

HDQ Data input/output

This bi-directional input/output communicates the register information to the host system. HDQ is open drain and requires a pullup/down resistor in the battery pack to disable/enable sleep mode if the pack is removed from the system.

RBI Register backup input

This input maintains the internal register states during periods when $V_{\rm CC}$ is below the minimum operating voltage.

WAKE Wake-up output

When asserted, this output is used to indicate that the charge or discharge activity is above a programmed minimal level.

Functional Description General Operation

A host can use the bq2018 internal counters and timers to measure battery state-of-charge, estimate self-discharge, and calculate the average charge and discharge current into and out of a rechargeable battery. The bq2018 needs an external host system to perform all register maintenance. Using information from the bq2018, the system host can determine the battery state-of-charge, estimate self-discharge, and calculate the average charge and discharge currents. During pack storage periods, the use of an internal temperature sensor doubles the self-discharge count rate every 10° above 25° C.

To reduce cost, power to the bq2018 may be derived using a low-cost external FET in conjunction with the REG pin. The bq2018 operating current is less than 80µA. When the HDQ line remains low for greater than ten seconds and $V_{\rm SRO}$ ($V_{\rm SR}$ + $V_{\rm OS}$ where $V_{\rm SR}$ is the voltage drop between SR1 and SR2 and $V_{\rm OS}$ is the offset voltage) is below the programmed minimal level (WAKE is in High Z), the bq2018 enters a sleep mode of <10µA where all operations are suspended. HDQ transitioning high reinitiates the bq2018.

A register is available to store the calculated offset, allowing current calibration. The offset cancellation register is written by the bq2018 during pack assembly and is available to the host system to adjust the current measurements. By adding or subtracting the offset value stored in the OFR, the true charge and discharge counts can be calculated to a high degree of certainty.

Figure 1 shows a block diagram of the bq2018, and Table 1 outlines the bq2018 operational states.

REG Output

The bq2018 can operate directly from three or four nickel-chemistry cells or a single Li-Ion cell as long as $V_{\rm CC}$ is limited to 2.8 to 5.5V. To facilitate the power supply requirements of the bq2018, a REG output is present to regulate an external low-threshold n-JFET. A micropower $V_{\rm CC}$ source for the bq2018 can inexpensively be built using this FET.

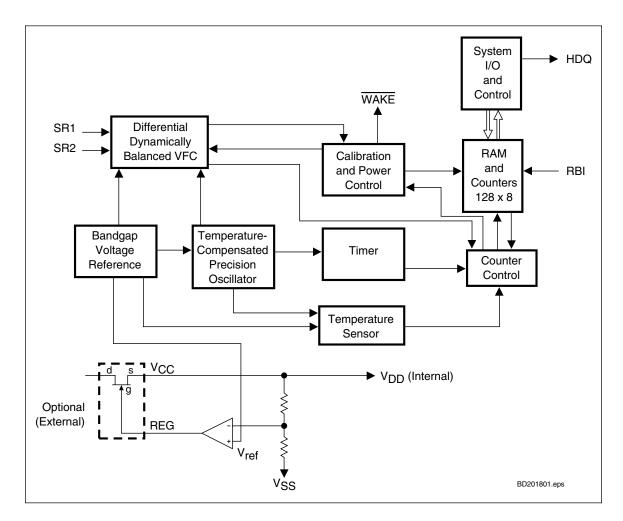


Figure 1. bq2018 Block Diagram

Table	1.	Operational	States
Table		operational	Oluco

HDQ Pin	DCR/CCR/SCR	WOE	WAKE	Operating State
HDQ High	yes	$ V_{SRO} > V_{WOE}$	Low	Normal
HDQ High	yes	$ V_{SRO} < V_{WOE}$	High Z	Normal
HDQ Low	no	$ V_{SRO} < V_{WOE}$	High Z	Sleep

Note: V_{SRO} is the voltage difference between SR1 and SR2 plus the offset voltage V_{OS} .

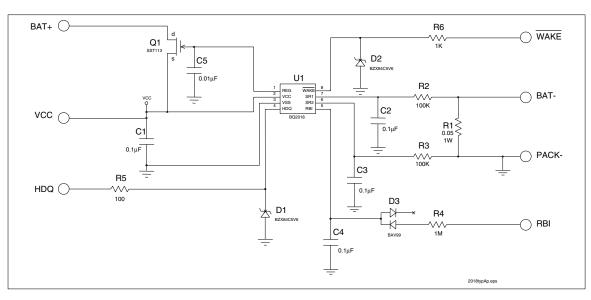


Figure 2. Typical Application

RBI Input

The RBI input pin is used with a storage capacitor or external supply to provide back-up potential to the internal RAM when V_{CC} drops below 2.4V. The maximum discharge current is 100nA in this mode. The bq2018 outputs V_{CC} on RBI when the supply is above 2.4V, so a diode is required to isolate an external supply.

Charge/Discharge Count Operation

Table 2 shows the main counters and registers of the bq2018. The bq2018 accumulates charge and discharge counts into two main count registers, the Discharge Count Register (DCR) and the Charge Count Register (CCR). The bq2018 produces charge and discharge

counts by sensing the voltage difference across a lowvalue resistor between the negative terminal of the battery pack and the negative terminal of the battery. The DCR or CCR counts depending on the signal between SR1 and SR2.

During discharge, the DCR and the Discharge Time Counter (DTC) are active. If $V_{\rm SR1}$ is less than $V_{\rm SR2}$, indicating a discharge, the DCR counts at a rate equivalent to 12.5µV every hour, and the DTC counts at a rate of 1 count/0.8789 seconds (4096 counts per 1 hour). For example, a -100mV signal produces 8000 DCR counts and 4096 DTC counts each hour. The amount of charge removed from the battery can easily be calculated.

Name	Description	Description Range			
DCR	Discharge count register	V _{SR1} < V _{SR2} (Max. =-200mV) 12.5µVh increments	16-bit		
CCR	Charge count register	$V_{SR1} > V_{SR2}$ (Max. = +200mV) 12.5µVh increments	16-bit		
SCR	Self-discharge count register	1 count/hour @ 25°C	16-bit		
DTC	Discharge time counter	1 count/0.8789s default 1 count/225s if STD is set	16-bit		
CTC	Charge time counter	1 count/0.8789s default 1 count/225s if STC is set	16-bit		
MODE/ WOE	MODE/ Wake output enable	—	8-bit		

Table 2. bq2018 Counters

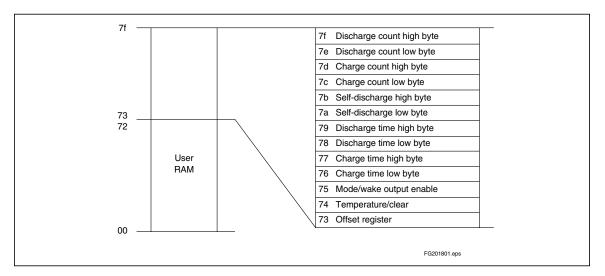


Figure 3. Address Map

During charge, the CCR and the Charge Time Counter (CTC) are active. If $V_{\rm SR1}$ is greater than $V_{\rm SR2}$, indicating a charge, the CCR counts at a rate equivalent to $12.5\mu V$ every hour, and the CTC counts at a rate of 1 count/0.8789 seconds. For example, a +100mV signal produces 8000 CCR counts and 4096 CTC counts each hour. The amount of charge added to the battery can easily be calculated.

The DTC and the CTC are 16-bit registers, and roll over beyond ffffh. If a rollover occurs, the corresponding bit in the MODE/WOE register is set, and the counter will subsequently increment at 1/256 of the normal rate (16 counts/hr.).

Whenever the signal between SR1 and SR2 is above the Wakeup Output Enable (WOE) threshold and the HDQ pin is high, the bq2018 is in its full operating state. In this state, the DCR, <u>CCR</u>, <u>DTC</u>, <u>CTC</u>, and SCR are fully operational, and the WAKE output is low. During this mode, the internal RAM registers of the bq2018 may be accessed over the HDQ pin, as described in the section "Communicating With the 2018."

If the signal between SR1 and SR2 is below the WOE threshold (refer to the \overline{WAKE} section for details) and HDQ remains low for greater than 10 seconds, the bq2018 enters a sleep mode where all register counting is suspended. The bq2018 remains in this mode until HDQ returns high.

For self-discharge calculation, the self-discharge count register (SCR) counts at a rate equivalent to 1 count every hour at a nominal 25° C and doubles approximately every 10°C up to 60°C. The SCR count rate is halved every 10 °C below 25° C down to 0°C. The value in SCR is

useful in determining an estimation of the battery selfdischarge based on capacity and storage temperature conditions.

The bq2018 may be programmed to measure the voltage offset between SR1 and SR2 during pack assembly or at any time by invoking the Calibration mode. The Offset Register (OFR) is used to store the bq2018 offset. The 8-bit 2's complement value stored in the OFR is scaled to the same units as the DCR and CCR, representing the amount of positive or negative offset in the bq2018. The maximum offset for the bq2018 is specified as \pm 500µV. Care should be taken to ensure proper PCB layout. Using OFR, the system host can cancel most of the effects of bq2018 offset for greater resolution and accuracy.

Figure 3 shows the bq2018 register address map. The bq2018 uses the upper 13 locations. The remaining memory can store user-specific information such as chemistry, serial number, and manufacturing date.

WAKE Output

This output is used to inform the system that the voltage difference between SR1 and SR2 is above or below the Wake Output Enable (WOE) threshold programmed in the MODE/WOE register. When the voltage difference between SR1 and SR2 is below $V_{\rm WOE}$, the WAKE output goes into High Z and remains in this state until the discharge or charge current increases above the specified value. The MODE/WOE resets to 0eh after a power-on reset. $V_{\rm WOE}$ is set by dividing 3.84mV by a value between 1 and 7 (1–7h) according to Table 3.

WOE ₃₋₁ (hex)	V _{WOE} (mV)				
0h	n/a				
1h	3.840				
2h	1.920				
3h	1.280				
4h	0.960				
5h	0.768				
6h	0.640				
7h*	0.549				

Table 3. WOE Thresholds

* Default value after POR.

Temperature

The bq2018 has an internal temperature sensor which is used to set the value in the temperature register (TMP/CLR) and set the self-discharge count rate value. The register reports the temperature in 8 steps of 10°C from <0°C to >60°C as Table 4 specifies. The bq2018 temperature sensor has typical accuracy of $\pm 2^{\circ}$ C at 25°C. See the TMP/CLR register description for more details.

Clear Register

The host system is responsible for register maintenance. To facilitate this maintenance, the bq2018 has a Clear Register (TMP/CLR) designed to reset the specific counter or register pair to zero. The host system clears a register by writing the corresponding register bit to 1. When the bq2018 completes the reset, the corresponding bit in the TMP/CLR register is automatically reset to 0, which saves the host an extra write/read cycle. Clearing the DTC register clears the STD bit and sets the DTC count rate to the default value of 1 count per 0.8789s. Clearing

Temp	Value (hex)	SDR Count Rate
<0°	0h	imes 1/8
0–10°	1h	imes 1/4
10-20°	2h	imes 1/2
20–30°	3h	1 count/hr.
30–40°	4h	imes 2
40–50°	5h	imes 4
50–60°	6h	× 8
>60°	7h	× 16

Table 4. Temperature Steps

the CTC register clears the STC bit and sets the CTC count rate to the default value of 1 count per 0.8789s.

Calibration Mode

The system can enable bq2018 $V_{\rm OS}$ calibration by setting the calibration bit in the MODE/WOE register (Bit 6) to 1. The bq2018 then enters calibration mode when the HDQ line is low for greater than 10 seconds and when the signal between SR1 and SR2 is below $V_{\rm WOE}$. Caution: Take care to ensure that no low-level external signal is present between SR1 and SR2 because this affects the calibration value that the bq2018 calculates.

If HDQ remains low for one hour and $|V_{\rm SR}| < V_{\rm WOE}$ for the entire time, the measured $V_{\rm OS}$ is latched into the OFR register, and the calibration bit is reset to zero, indicating to the system that the calibration cycle is complete. Once calibration is complete, the bq2018 enters a

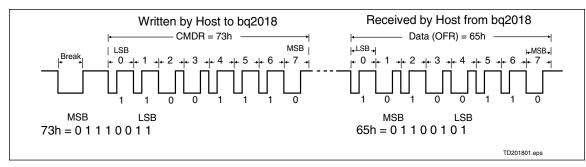


Figure 4. Typical Communication with the bq2018

	Register	Loc.	Read/									
Symbol	Name	(hex)	Write	7(MSB)	6	5	4	3	2	1	0(LSB)	
CMDR	Command register	-	Write	W/R	AD6	AD5	AD4	AD3	AD2	AD1	AD0	
DCRH	Discharge count register high byte	7f	Read	DCRH7	DCRH6	DCRH5	DCRH4	DCRH3	DCRH2	DCRH1	DCRH0	
DCRL	Discharge count register low byte	7e	Read	DCRL7	DCRL6	DCRL5	DCRL4	DCRL3	DCRL2	DCRL1	DCRL0	
CCRH	Charge count register high byte	7d	Read	CCRH7	CCRH6	CCRH5	CCRH4	CCRH3	CCRH2	CCRH1	CCRH0	
CCRL	Charge count register low byte	7c	Read	CCRL7	CCRL6	CCRL5	CCRL4	CCRL3	CCRL2	CCRL1	CCRL0	
SCRH	Self-discharge count register high byte	7b	Read	SCRH7	SCRH6	SCRH5	SCRH4	SCRH3	SCRH2	SCRH1	SCRH0	
SCRL	Self-discharge count register low byte	7a	Read	SCRL7	SCRL6	SCRL5	SCRL4	SCRL3	SCRL2	SCRL1	SCRL0	
DTCH	Discharge time count high byte	79	Read	DTCH7	DTCH6	DTCH5	DTCH4	DTCH3	DTCH2	DTCH1	DTCH0	
DTCL	Discharge time count low byte	78	Read	DTCL7	DTCL6	DTCL5	DTCL4	DTCL3	DTCL2	DTCL1	DTCL0	
СТСН	Charge time count high byte	77	Read	CTCH7	CTCH6	CTCH5	CTCH4	СТСНЗ	CTCH2	CTCH1	CTCH0	
CTCL	Charge time count low byte	76	Read	CTCL7	CTCL6	CTCL5	CTCL4	CTCL3	CTCL2	CTCL1	CTCL0	
MODE/ WOE	MODE/ wake- up output enable	75	Read/ write	OVRDQ	CAL	STC	STD	WOE3	WOE2	WOE1	0	
TMP/CLR	Tempera- ture/Clear register	74	Read/ write	TMP2	TMP1	TMP0	CTC	DTC	SCR	CCR	DCR	
OFR	Offset register	73	Read/ write	OFR7	OFR6	OFR5	OFR4	OFR3	OFR2	OFR1	OFR0	
RAM	User memory	72-00	Read/ write	-	-	-	-	-	-	-	-	

Table 5. bq2018 Command and Status Registers

Notes: 1. MODE/WOE register bit 0 is set to zero at startup and should not be written to 1 for proper bq2018 operation.

2. OFR value is in two's complement.

low-power mode until HDQ goes high, indicating an external system is ready to access the bq2018. If HDQ transitions high prior to completion of the $V_{\rm OS}$ calculation or if $|V_{\rm SR}| > V_{\rm WOE}$, then the calibration cycle is reset. The bq2018 then postpones the calibration cycle until the conditions are met. The calibration bit does not reset to zero until a valid calibration cycle is completed. The requirement for HDQ to remain low for the calibration cycle can be disabled by setting the OVRDQ bit to 1. In this case, calibration continues as long as $|V_{\rm SR}| < V_{\rm WOE}$. The OVRDQ bit is reset to zero at the end of a valid calibration cycle.

Communicating with the bq2018

The bq2018 includes a simple single-pin (referenced to $V_{SS})$ serial data interface. A host processor uses the interface to access various bq2018 registers. Battery activity may be easily monitored by adding a single contact to the battery pack. Note: The HDQ pin requires an external pull-up or pull-down resistor.

The interface uses a command-based protocol, where the host processor sends a command byte to the bq2018. The command directs the bq2018 either to store the next eight bits of data received to a register specified by the command byte or to output the eight bits of data from a register specified by the command byte.

The communication protocol is asynchronous return-toone. Command and data bytes consist of a stream of eight bits that have a maximum transmission rate of 5K bits/sec. The least-significant bit of a command or data byte is transmitted first. The protocol is simple enough that it can be implemented by most host processors using either polled or interrupt processing. Data input from the bq2018 may be sampled using the pulse-width capture timers available on some microcontrollers. A UART may also be used to communicate through the HDQ pin.

If a communication time-out occurs, e.g., the host waits longer than $t_{\rm CYCB}$ for the bq2018 to respond or if this is the first access command, then a BREAK should be sent by the host. The host may then resend the command. The bq2018 detects a BREAK when the HDQ pin is driven to a logic-low state for a time, $t_{\rm B}$ or greater. The HDQ pin then returns to its normal ready-high logic state for a time, $t_{\rm BR}$. The bq2018 is then ready to receive a command from the host processor.

The return-to-one data bit frame consists of three distinct sections. The first section is used to start the transmission by either the host or the bq2018 taking the HDQ pin to a logic-low state for a period, $t_{\rm STRH,B}$. The next section is the actual data transmission, where the data should be valid by a period, $t_{\rm DSUB}$, after the negative edge used to start communication. The data should be held for a period, $t_{\rm DV}/t_{\rm DH}$, to allow the host or bq2018 to sample the data bit.

The final section is used to stop the transmission by returning the HDQ pin to a logic-high state by at least a period, $t_{\rm SSU,B}$, after the negative edge used to start communication. The final logic-high state should be held until a period, $t_{\rm CYCH,B}$, to allow time to ensure that the bit transmission ceased properly. The serial communication timing specification and illustration sections give the timings for data and break communication.

Communication with the bq2018 always occurs with the least-significant bit being transmitted first. Figure 4 shows an example of a communication sequence to read the bq2018 OFR register.

bq2018 Registers

The bq2018 command and status registers are listed in Table 5 and described below.

Command (CMDR)

The write-only command register is accessed when the bq2018 has received eight contiguous valid command bits. The command register contains two fields:

- W/R
- Command address

The W/\overline{R} bit of the command register is used to select whether the received command is for a read or a write function. The W/\overline{R} values are

	CMDR Bits												
7 6 5 4 3 2 1 0													
W/R	-	-	-	-	-	-	-						

Where W/R is

- 0 The bq2018 outputs the requested register contents specified by the address portion of the CMDR
- 1 The following eight bits should be written to the register specified by the address portion of the CMDR

The lower seven-bit field of CMDR contains the address portion of the register to be accessed.

CMDR Bits											
7 6 5 4 3 2 1 0											
-	AD6	AD5	AD4	AD3	AD2	AD1	AD0				

Discharge Count Registers (DCRH/DCRL)

The DCRH high-byte register (address = 7fh) and the DCRL low-byte register (address = 7eh) contain the count

of the discharge, and are incremented whenever $V_{\rm SR1}$ < $V_{\rm SR2}.$ These registers continue to count beyond ffffh, so proper register maintenance should be done by the host system. The TMP/CLR register is used to force the reset of both the DCRH and DCRL to zero.

Charge Count Registers (CCRH/CCRL)

The CCRH high-byte register (address = 7dh) and the CCRL low-byte register (address = 7ch) contain the count of the charge, and are incremented whenever $V_{\rm SR1}$ > $V_{\rm SR2}$. These registers continue to count beyond ffffh, so proper register maintenance should be done by the host system. The TMP/CLR register is used to force the reset of both the CCRH and CCRL to zero.

Self-discharge Count Registers (SCRH/SCRL)

The SCRH high-byte register (address = 7bh) and the SCRL low-byte register (address = 7ah) contain the selfdischarge count. This register is continually updated whenever the bq2018 is in its normal operating mode. The counts in these registers are incremented based on time and temperature. The SCR counts at a rate of 1 count per hour at 20–30°C and doubles every 10°C to greater than 60°C (16 counts/hour). The count will half every 10°C below 20–30°C to less than 0°C (1 count/8 hours). These registers continue to count beyond ffffh, so proper register maintenance should be done by the host system. The TMP/CLR register is used to force the reset of both the SCRH and SCRL to zero.

Discharge Time Count Registers (DTCH/DTCL)

The DTCH high-byte register (address = 79h) and the DTCL low-byte register (address = 78h) are used to determine the length of time the $V_{\rm SR1} < V_{\rm SR2}$ indicating a discharge. The counts in these registers are incremented at a rate of 4096 counts per hour. If the DTCH/DTCL register continues to count beyond ffffh, the STD bit is set in the MODE/WOE register indicating a rollover. Once set, DTCH and DTCL increment at a rate of 16 counts per hour. Note: If a second rollover occurs, STD is cleared. Access to the bq2018 should be timed to clear DTCH/DTCL more often than every 170 days. The TMP/CLR register is used to force the reset of both the DTCH and DTCL to zero.

Charge Time Count Registers (CTCH/CTCL)

The CTCH high-byte register (address = 77h) and the CTCL low-byte register (address = 76h) are used to determine the length of time the $V_{SR1} > V_{SR2}$ indicating a charge. The counts in these registers are incremented at a rate of 4096 counts per hour. If the CTCH/CTCL registers continue to count beyond fffth, the STC bit is set in the MODE/WOE register indicating a rollover. Once set,

DTCH and DTCL increment at a rate of 16 counts per hour. Note: If a second rollover occurs, STC is cleared. Access to the bq2018 should be timed to clear CTCH/CTCL more often than every 170 days. The TMP/CLR register is used to force the reset of both the CTCH and CTCL to zero.

Mode/Wake-up Enable Register

The Mode/WOE register (address = 75h) contains the calibration, wakeup enable information, and the STC and STD bits as described below.

The Override DQ(OVRDQ) bit (bit 7) is used to override the requirement for HDQ to be low prior to initiating $V_{\rm OS}$ calibration. This bit is normally set to zero. If OVRDQ is written to one, the bq2018 begins offset calibration when $|V_{\rm SR}| <\! V_{\rm WOE}$ where HDQ = Don't care.

The OVRDQ location is

MODE/WOE Bits												
7 6 5 4 3 2 1 0												
OVRDQ	-	-	-	-	-	-	-					

Where OVRDQ is

- 0 HDQ = 0 and $|V_{SR}| < V_{WOE}$ for V_{OS} calibration to begin
- $1 \qquad HDQ = Don't \ care \ and \ |V_{SR}| {<} V_{WOE} \ for \ V_{OS} \\ calibration \ to \ begin$

Note: The OVRDQ bit should only be used in conjunction with a calibration cycle. Normal operation of the bq2018 cannot be guaranteed when this bit is set. After a valid calibration cycle, bit 7 is reset to zero.

The calibration (CAL) bit 6 is used to enable the bq2018 offset calibration test. Setting this bit to 1 enables a $V_{\rm OS}$ calibration whenever HDQ is low (default), and $|V_{\rm SRO}| < V_{\rm WOE}$. This bit is cleared to 0 by the bq2018 whenever a valid $V_{\rm OS}$ calibration is completed, and the OFR register is updated with the new calculated offset. The bit remains 1 if the offset calibration was not completed.

The CAL location is

	MODE/WOE Bits											
7 6 5 4 3 2 1 0												
-	CAL	-	-	-	-	-	-					

Where CAL is

- 0 Valid offset calibration
- 1 Offset calibration pending

The slow time charge (STC) and slow time discharge (STD) flags indicate if the CTC or DTC registers have rolled over beyond ffffh. STC set to 1 indicates a CTC rollover; STD set to 1 indicates a DTC rollover.

The STC and STD locations are

	MODE/WOE Bits												
7	6	5	4	3	2	1	0						
-	-	STC	STD	-	-	-	-						

Where STC/STD is

- 0 No rollover
- 1 Rollover occurred in the corresponding CTC/DTC register.

The WOE 3-1 locations are

	MODE/WOE Bits									
7	7 6 5 4 3 2 1 0									
-	WOE3 WOE2 WOE1 -									

Where WOE3–1 is determined by dividing 3.84mV by the value in WOE.

Bit 0 is reserved and must remain 0.

Temperature and Clear Register

The TMP/CLR register (address = 74h) is used to give the present temperature step between < 0°C to > 60°C and clear the various count registers. The values of the TMP0–TMP2 (bits 5–7) denote the current temperature step sense by the bq2018 as outlined in Table 4. The bq2018 temperature sense is trimmed to \pm 2°C typical (\pm 4°C maximum).

The TMP2-0 locations are

TMP/CLR Bits									
7	7 6 5 4 3 2 1 0								
TMP2 TMP1 TMP0									

Where TMP2–0 is the temperature step sensed by this bq2018.

The Clear bits (Bits 0–4) are used to reset the various bq2018 counters and STC and STD bits to zero. Writing the bits to 1 resets the corresponding register to 0. The clear bit resets to 0 indicating a successful register reset. Each clear bit is independent, so it is possible to clear the DCRH/DCRL registers without affecting the values in any other bq2018 register. The high-byte and low-byte registers are both cleared when the corresponding bit is written to 1 per the figure below.

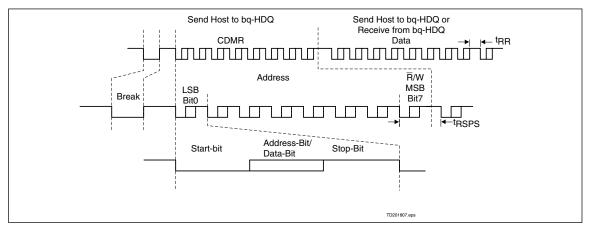


Figure 5. Communications Frame Example

The Clear bit locations are

TMP/CLR Bits										
7	7 6 5 4 3 2 1 0									
-	CTC DTC SCR CCR DCR									

Where:

CTC bit (bit 4) resets both the CTCH and CTCL registers and the STC bit to 0.

The DTC bit (bit 3) resets both the DTCH $\,$ and DTCL registers and the STD bit to 0.

The SCR bit (bit 2) resets both the SCRH $\,$ and SCRL registers to 0.

The CCR bit (bit 1) resets both the CCRH $\,$ and CCRL registers to 0.

The DCR bit (bit 0) resets both the DCRH $\,$ and DCRL registers to 0.

Offset Register (OFR)

The OFR register (address = 73h) is used to store the calculated V_{OS} of the bq2018. The OFR value can be used to cancel the voltage offset between V_{SR1} and V_{SR2} . The up/down offset counter is centered at zero. The actual offset is an 8-bit two's complement value located in OFR.

The OFR locations are

OFR Bits									
7 6 5 4 3 2 1 0									
OFR7 OFR6 OFR5 OFR4 OFR3 OFR2 OFR1 OFR0									

Where OFR7 is

- 1 Discharge
- 0 Charge

Symbol	Parameter	Parameter Minimum Maximum		Uni t	Notes
V _{CC}	Relative to V_{SS}	-0.3	+6.0	V	
HDQ	Relative to V_{SS}	-0.3	+6.0	v	
All other pins		$V_{\rm SS}$ -0.3V	V_{CC} +3.0V	v	
I _{REG}	REG to V_SS		1.0	mA	
V_{SR1}/V_{SR2}	Relative to V_{SS}	-0.3	+6.0	v	A 100kΩ series resistor is recommended to protect SR1 / SR2 in case of a shorted battery.
T _{OPR}	Operating temperature	- 20	+70	°C	

Absolute Maximum Ratings

Note: Permanent device damage may occur if **Absolute Maximum Ratings** are exceeded. Functional operation should be limited to the Recommended DC Operating Conditions detailed in this data sheet. Exposure to conditions beyond the operational limits for extended periods of time may affect device reliability.

Symbol	Parameter	Minimum	Typical	Maximum	Unit	Notes
v	Secondary and the sec	2.8	4.25	5.5	V	REG = No connect
V _{CC}	Supply voltage	3.5	3.7	3.9	V	$V_{\rm CC}$ derived from REG, Note 3
т		-	60	70	μA	$V_{CC,HDQ} = 3.7V$
I _{CC}	Operating current	-	70	80	μA	$V_{CC,HDQ} = 5.5V$
I _{CC2}	Sleep	-	-	10	μA	$V_{\rm CC} = 5.5 V$
I _{RBI}	RBI current	-	-	100	nA	$V_{\rm CC} < 2.4 V$
V _{SR}	Sense resistor input	-200	-	200	mV	$V_{SR1} < V_{SR2}$ = discharge; $V_{SR1} > V_{SR2}$ = charge Note 2
R _{SR}	SR1 / SR2 input impedance	10	-	-	MΩ	$-200 \text{mV} < \text{V}_{\text{SR}} < 200 \text{mV}$
I _{OL}	Open-drain sink current	-	-	2.0	mA	$\frac{V_{OL} = V_{SS} + 0.3V}{WAKE, HDQ}$
V _{IHDQ}	HDQ input high	2.5	-	-	V	
V _{ILDQ}	HDQ input low	-	-	0.8	V	

DC Electrical Characteristics (T_A = T_{OPR})

Notes: 1. All voltages relative to V_{SS} .

2. $V_{SR1/SR2}$ + V_{OS} . V_{OS} is affected by PC board layout. Follow proper layout guidelines for optimal performance.

3. Can be guaranteed by design when using an SST108 or equivalent JFET.

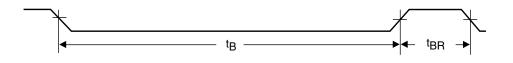
Symbol	Parameter	Typical	Maximum	Unit	Notes
V _{OS}	Offset voltage		±500	μV	Voltage offset between SR1 and SR2
OSC	Timer accuracy	1.5	±3.0	%	$V_{CC} = 3.5 - 3.9 V (T_A = 0-70^{\circ}C)$
INR	Integrated non- repeatability error	0.5	1.0	%	Measured repeatability given similar operating conditions
INL	Integrated non-linearity	1.0	2.0	%	Add 0.05% per °C above or below 25° C and 0.5% per volt above or below 3.7V.

Performance Characteristics ($T_A = T_{OPR}$)

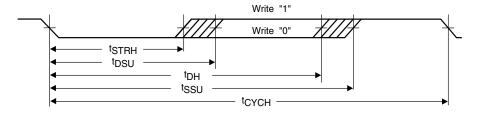
Standard Serial Communication Timing Specification (T_A = T_{OPR})

Symbol	Parameter	Minimum	Typical	Maximum	Unit	Notes
t_{CYCH}	Cycle time, host to bq2018 (write)	190	-	-	μs	
t_{CYCB}	Cycle time, bq2018 to host (read)	190	205	250	μs	
$t_{\rm STRH}$	Start hold, host to bq2018 (write)	5	-	-	ns	
t _{STRB}	Start hold, bq2018 to host (read)	32	-	-	μs	
t _{DSU,B}	Data setup	-	-	50	μs	
t _{DH}	Data hold	90	-	-	μs	
t _{DV}	Data valid	-	-	80	μs	
t _{SSUB}	Stop setup (bq2018 to host)	-	-	95	μs	
t_{SSU}	Stop setup (host to bq2018)	-	-	145	μs	
t _B	Break	190	-	-	μs	
t _{BR}	Break recovery	40	-	-	μs	
t _{RSPS}	Response time, bq2018 to host	190	-	320	μs	
t _{RR}	Read recovery	40	-	-	μs	Host read to next cycle

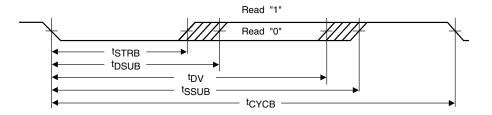
Break Timing



Host to bq2018

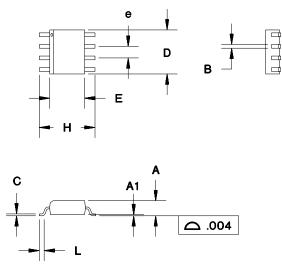


bq2018 to Host



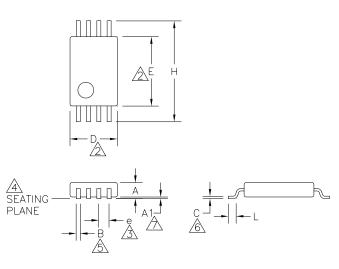
	Millim	neters	Inc	hes	
Dimension	Min.	Max.	Min.	Max.	
Α	1.52	1.78	0.060	0.070	
A1	0.10	0.25	0.004	0.010	
В		0.51	0.013	0.020	
С	0.18	0.25	0.007	0.010	
D	4.70	5.08	0.185	0.200	
Е	3.81	4.06	0.150	0.160	
е	1.14	1.40	0.045	0.055	
Н	5.72	6.22	0.225	0.245	
L	0.38	0.89	0.015	0.035	

8-Pin SOIC Narrow ~ SN Package Suffix



	Millim	eters	Inches			
Dimension	Min. Max.		Min.	Max.		
A	-	1.10	-	0.043		
A1	0.05	0.15	0.002	0.006		
В	0.18	0.30	0.007	0.012		
C	0.09	0.18	0.004	0.007		
D	2.90	3.10	0.115	0.122		
Е	4.30	4.48	0.169	0.176		
е	0.65	BSC	0.025	6BSC		
Н	6.25	6.50	0.246	0.256		
L	0.50	0.70	0.020	0.028		

8-Pin TSSOP ~ TS Package Suffix



Notes:

1. Controlling dimension: millimeters. Inches shown for reference only.

2 'D' and 'E' do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.15mm per side a Each lead centerline shall be located within ±0.10mm of its exact true position.

A Leads shall be coplanar within 0.08mm at the seating plane.

Dimension 'B' does not include dambar protrusion. The dambar protrusion(s) shall not cause the lead width to exceed 'B' maximum by more than 0.08mm.

6 Dimension applies to the flat section of the lead between 0.10mm and 0.25mm from the lead tip.

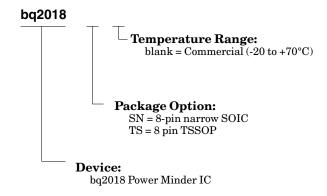
A 'A1' is defined as the distance from the seating plane to the lowest point of the package body (base plane).

Data Sheet Revision History

Change No.	Page No.	Description	Nature of Change
1	All		
2	12		Clarification of absolute maximum pin ratings

Note: Change 1 = Jan. 1999 B changes to Final from Dec. 1998 Preliminary data sheet. Change 2 = June 1999 C changes from Jan. 1999 B.

Ordering Information



Notes

PACKAGING INFORMATION

Orderable Device	Status ⁽¹⁾	Package Type	Package Drawing	Pins	Package Qty	Eco Plan ⁽²⁾	Lead/Ball Finish	MSL Peak Temp ⁽³⁾
BQ2018SN-E1	ACTIVE	SOIC	D	8	75	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
BQ2018SN-E1TR	ACTIVE	SOIC	D	8	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
BQ2018SN-E1TRG4	ACTIVE	SOIC	D	8	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-1-260C-UNLIM
BQ2018TS-E1	ACTIVE	TSSOP	PW	8	150	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
BQ2018TS-E1TR	ACTIVE	TSSOP	PW	8	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
BQ2018TS-E1TRG4	ACTIVE	TSSOP	PW	8	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR

⁽¹⁾ The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

OBSOLETE: TI has discontinued the production of the device.

⁽²⁾ Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

Pb-Free (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

Pb-Free (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

⁽³⁾ MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

Important Information and Disclaimer:The information provided on this page represents TI's knowledge and belief as of the date that it is provided. TI bases its knowledge and belief on information provided by third parties, and makes no representation or warranty as to the accuracy of such information. Efforts are underway to better integrate information from third parties. TI has taken and continues to take reasonable steps to provide representative and accurate information but may not have conducted destructive testing or chemical analysis on incoming materials and chemicals. TI and TI suppliers consider certain information to be proprietary, and thus CAS numbers and other limited information may not be available for release.

In no event shall TI's liability arising out of such information exceed the total purchase price of the TI part(s) at issue in this document sold by TI to Customer on an annual basis.

TAPE AND REEL INFORMATION





QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*A	Il dimensions are nominal												
	Device		Package Drawing		SPQ	Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
	BQ2018SN-E1TR	SOIC	D	8	2500	330.0	12.4	6.4	5.2	2.1	8.0	12.0	Q1
	BQ2018TS-E1TR	TSSOP	PW	8	2000	330.0	12.4	7.0	3.6	1.6	8.0	12.0	Q1



PACKAGE MATERIALS INFORMATION

11-Mar-2008



*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
BQ2018SN-E1TR	SOIC	D	8	2500	346.0	346.0	29.0
BQ2018TS-E1TR	TSSOP	PW	8	2000	346.0	346.0	29.0

IMPORTANT NOTICE

Texas Instruments Incorporated and its subsidiaries (TI) reserve the right to make corrections, modifications, enhancements, improvements, and other changes to its products and services at any time and to discontinue any product or service without notice. Customers should obtain the latest relevant information before placing orders and should verify that such information is current and complete. All products are sold subject to TI's terms and conditions of sale supplied at the time of order acknowledgment.

TI warrants performance of its hardware products to the specifications applicable at the time of sale in accordance with TI's standard warranty. Testing and other quality control techniques are used to the extent TI deems necessary to support this warranty. Except where mandated by government requirements, testing of all parameters of each product is not necessarily performed.

TI assumes no liability for applications assistance or customer product design. Customers are responsible for their products and applications using TI components. To minimize the risks associated with customer products and applications, customers should provide adequate design and operating safeguards.

TI does not warrant or represent that any license, either express or implied, is granted under any TI patent right, copyright, mask work right, or other TI intellectual property right relating to any combination, machine, or process in which TI products or services are used. Information published by TI regarding third-party products or services does not constitute a license from TI to use such products or services or a warranty or endorsement thereof. Use of such information may require a license from a third party under the patents or other intellectual property of the third party, or a license from TI under the patents or other intellectual property of TI.

Reproduction of TI information in TI data books or data sheets is permissible only if reproduction is without alteration and is accompanied by all associated warranties, conditions, limitations, and notices. Reproduction of this information with alteration is an unfair and deceptive business practice. TI is not responsible or liable for such altered documentation. Information of third parties may be subject to additional restrictions.

Resale of TI products or services with statements different from or beyond the parameters stated by TI for that product or service voids all express and any implied warranties for the associated TI product or service and is an unfair and deceptive business practice. TI is not responsible or liable for any such statements.

TI products are not authorized for use in safety-critical applications (such as life support) where a failure of the TI product would reasonably be expected to cause severe personal injury or death, unless officers of the parties have executed an agreement specifically governing such use. Buyers represent that they have all necessary expertise in the safety and regulatory ramifications of their applications, and acknowledge and agree that they are solely responsible for all legal, regulatory and safety-related requirements concerning their products and any use of TI products in such safety-critical applications, notwithstanding any applications-related information or support that may be provided by TI. Further, Buyers must fully indemnify TI and its representatives against any damages arising out of the use of TI products in such safety-critical applications.

TI products are neither designed nor intended for use in military/aerospace applications or environments unless the TI products are specifically designated by TI as military-grade or "enhanced plastic." Only products designated by TI as military-grade meet military specifications. Buyers acknowledge and agree that any such use of TI products which TI has not designated as military-grade is solely at the Buyer's risk, and that they are solely responsible for compliance with all legal and regulatory requirements in connection with such use.

TI products are neither designed nor intended for use in automotive applications or environments unless the specific TI products are designated by TI as compliant with ISO/TS 16949 requirements. Buyers acknowledge and agree that, if they use any non-designated products in automotive applications, TI will not be responsible for any failure to meet such requirements.

Following are URLs where you can obtain information on other Texas Instruments products and application solutions:

Products		Applications	
Amplifiers	amplifier.ti.com	Audio	www.ti.com/audio
Data Converters	dataconverter.ti.com	Automotive	www.ti.com/automotive
DSP	dsp.ti.com	Broadband	www.ti.com/broadband
Clocks and Timers	www.ti.com/clocks	Digital Control	www.ti.com/digitalcontrol
Interface	interface.ti.com	Medical	www.ti.com/medical
Logic	logic.ti.com	Military	www.ti.com/military
Power Mgmt	power.ti.com	Optical Networking	www.ti.com/opticalnetwork
Microcontrollers	microcontroller.ti.com	Security	www.ti.com/security
RFID	www.ti-rfid.com	Telephony	www.ti.com/telephony
RF/IF and ZigBee® Solutions	www.ti.com/lprf	Video & Imaging	www.ti.com/video
		Wireless	www.ti.com/wireless

Mailing Address: Texas Instruments, Post Office Box 655303, Dallas, Texas 75265 Copyright © 2008, Texas Instruments Incorporated