

TOSHIBA CMOS DIGITAL INTEGRATED CIRCUIT SILICON MONOLITHIC

# TC4W66F, TC4W66FU

## DUAL BILATERAL SWITCH

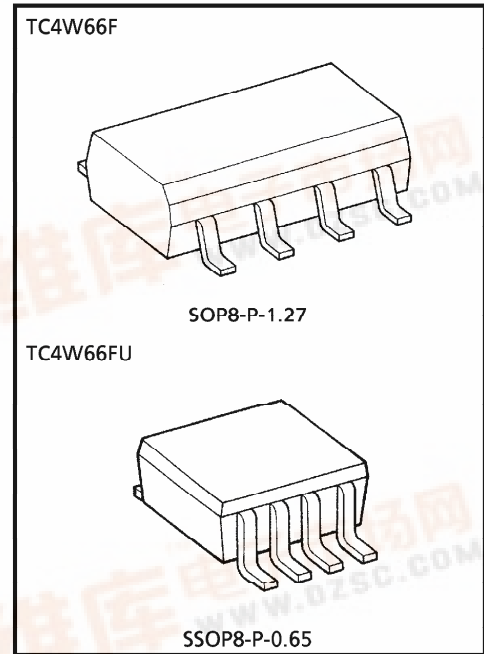
The TC4W66 contains two independence circuits of bidirectional switches. When control input CONT is set to "H" level, the impedance between input and output of the switch becomes low and when it is set to "L" level, the switch becomes high. This can be applied for switching of analog signals and digital signals.

### FEATURES

- ON-resistance,  $R_{ON}$   
 $250\Omega$  (Typ.) ....  $V_{DD}-V_{SS} = 5V$   
 $110\Omega$  (Typ.) ....  $V_{DD}-V_{SS} = 10V$   
 $70\Omega$  (Typ.) .....  $V_{DD}-V_{SS} = 15V$
- OFF-resistance,  $R_{OFF}$   
 $R_{OFF}$  (Typ.)  $> 10^9\Omega$

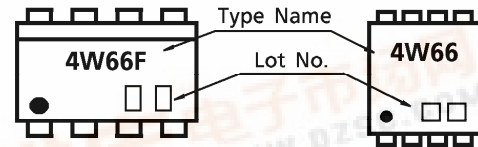
### MAXIMUM RATINGS

CHARACTERISTIC	SYMBOL	RATING	UNIT
DC Supply Voltage	$V_{DD}$	$V_{SS} - 0.5 \sim V_{SS} + 20$	V
Control Input Voltage	$V_{C IN}$	$V_{SS} - 0.5 \sim V_{DD} + 0.5$	V
Switch I/O Voltage	$V_{I/O}$	$V_{SS} - 0.5 \sim V_{DD} + 0.5$	V
Power Dissipation	$P_D$	300	mW
Potential difference across I/O during ON	$V_I - V_O$	$\pm 0.5$	V
Control Input Current	$I_{C IN}$	$\pm 10$	mA
Operating Temperature Range	$T_{opr}$	$-40 \sim 85$	$^{\circ}C$
Storage Temperature	$T_{stg}$	$-65 \sim 150$	$^{\circ}C$
Lead Temp./Time	$T_L$	$260^{\circ}C / 10s$	

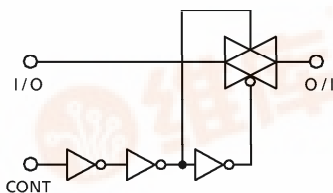


Weight SOP8-P-1.27 : 0.05g (Typ.)  
 SSOP8-P-0.65 : 0.02g (Typ.)

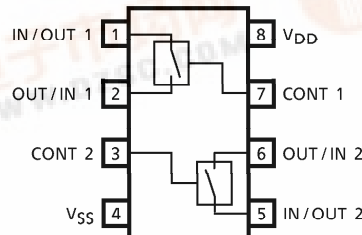
### MARKING



### LOGIC DIAGRAM (1/2 TC4W66F)



### PIN ASSIGNMENT (TOP VIEW)



### TRUTH TABLE

CONTROL	IMPEDANCE BETWEEN IN / OUT-OUT / IN *
H	$0.5 \sim 5 \times 10^2\Omega$
L	$> 10^9\Omega$

\* See static electrical characteristics.

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**RECOMMENDED OPERATING CONDITIONS (V<sub>SS</sub> = 0V)**

CHARACTERISTICS	SYMBOL		MIN.	TYP.	MAX.	UNIT
DC Supply Voltage	V <sub>DD</sub>	—	3	—	18	V
Input/Output Voltage	V <sub>DD</sub> /V <sub>OUT</sub>	—	0	—	V <sub>DD</sub>	

**STATIC ELECTRICAL CHARACTERISTICS (In case not specifically appointed, V<sub>SS</sub> = 0V)**

CHARACTERISTICS	SYM-BOL	TEST CONDITION	V <sub>DD</sub> (V)	Ta = -40°C		Ta = 25°C			Ta = 85°C		UNIT	
				MIN.	MAX.	MIN.	TYP.	MAX.	MIN.	MAX.		
Control Input High Voltage	V <sub>IH</sub>	I <sub>S</sub>   = 10μA	5	3.5	—	3.5	2.75	—	3.5	—	V	
			10	7.0	—	7.0	5.50	—	7.0	—		
			15	11.0	—	11.0	8.25	—	11.0	—		
Control Input Low Voltage	V <sub>IL</sub>	I <sub>S</sub>   = 10μA	5	—	1.5	—	2.25	1.5	—	1.5	V	
			10	—	3.0	—	4.5	3.0	—	3.0		
			15	—	4.0	—	6.75	4.0	—	4.0		
On-State Resistance	R <sub>ON</sub>	0 ≤ V <sub>I</sub> ≤ V <sub>DD</sub> R <sub>L</sub> = 10kΩ	5	—	800	—	290	950	—	1200	Ω	
			10	—	210	—	120	250	—	300		
			15	—	140	—	85	160	—	200		
Δ On-State Resistance (Between Any2 Switches)	R <sub>ON Δ</sub>	—	5	—	—	—	10	—	—	—	Ω	
			10	—	—	—	6	—	—	—		
			15	—	—	—	4	—	—	—		
Input/Output Leakage Current	I <sub>OFF</sub>	V <sub>IN</sub> = 18V, V <sub>OUT</sub> = 0V V <sub>IN</sub> = 0V, V <sub>OUT</sub> = 18V	18	—	± 100	—	± 0.1	± 100	—	± 1000	nA	
			18	—	± 100	—	± 0.1	± 100	—	± 1000		
Quiescent Device Current	I <sub>DD</sub>	V <sub>IN</sub> = V <sub>DD</sub> , V <sub>SS</sub> *	5	—	0.25	—	0.001	0.25	—	7.5	μA	
			10	—	0.5	—	0.001	0.5	—	15		
			15	—	1.0	—	0.002	1.0	—	30		
Input Current	H Level	I <sub>IH</sub>	V <sub>IH</sub> = 18V	18	—	0.1	—	10 <sup>-5</sup>	0.1	—	1.0	μA
	L Level	I <sub>IL</sub>	V <sub>IL</sub> = 0V	18	—	-0.1	—	-10 <sup>-5</sup>	-0.1	—	-1.0	

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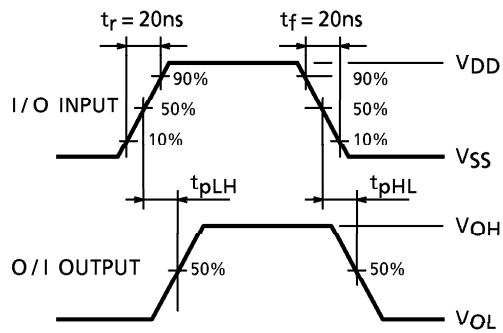
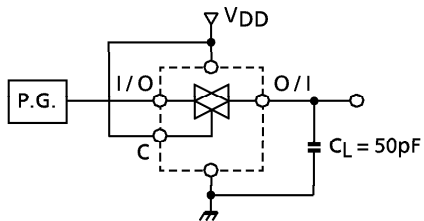
**DYNAMIC ELECTRICAL CHARACTERISTICS (Ta = 25°C, VSS = 0V, CL = 50pF)**

CHARACTERISTICS	SYMBOL	TEST CONDITION	VDD (V)		MIN.	TYP.	MAX.	UNIT
			VSS (V)	VDD (V)				
Phase Difference between Input to Output	$\phi$ I-O	CL = 50pF	0	5	—	15	40	ns
			0	10	—	8	20	
			0	15	—	5	15	
Propagation Delay Time (CONTROL-OUT)	tpZL tpZH	RL = 1kΩ CL = 50pF	0	5	—	55	120	
			0	10	—	25	40	
			0	15	—	20	30	
Propagation Delay Time (CONTROL-OUT)	tpLZ tpHZ	RL = 1kΩ CL = 50pF	0	5	—	45	80	
			0	10	—	30	70	
			0	15	—	25	60	
MAX. Control Input Repetition Rate	fMAX (C)	RL = 1kΩ CL = 50pF	0	5	—	10	—	MHz
			0	10	—	12	—	
			0	15	—	12	—	
- 3dB Cutoff Frequency	fMAX (I-O)	RL = 1kΩ CL = 50pF (*1)	- 5	5	—	30	—	
Total Harmonic Distortion	—	RL = 10kΩ f = 1kHz (*2)	- 5	5	—	0.03	—	%
- 50dB Feed through Frequency	—	RL = 1kΩ (*3)	- 5	5	—	600	—	kHz
- 50dB Crosstalk Frequency	—	RL = 1kΩ (*4)	- 5	5	—	1	—	MHz
Crosstalk (CONTROL-OUT)	—	RIN = 1kΩ ROUT = 10kΩ CL = 15pF	0	5	—	200	—	mV
			0	10	—	400	—	
			0	15	—	600	—	
Input Capacitance	CIN	Control Input	—	—	—	5	7.5	pF
		Switch I/O	—	—	—	10	—	
Feed through Capacitance	CIN-OUT	—	—	—	—	0.5	—	

- \*1 Since wave of  $\pm 2.5V_{p-p}$  shall be used for  $V_{IS}$  and the frequency of  $20\log_{10} \frac{V_{OS}}{V_{IS}}$  = - 3dB shall be fMAX.
- \*2  $V_{IS}$  shall be sine wave of  $\pm 2.5V_{p-p}$ .
- \*3 Sine wave of  $\pm 2.5V_{p-p}$  shall be used for  $V_{IS}$  and the frequency of  $20\log_{10} \frac{V_{OUT}}{V_{IS}}$  = - 50dB shall be feed-through.
- \*4 Sine wave of  $\pm 2.5V_{p-p}$  shall be used for  $V_{IS}$  and the frequency of  $20\log_{10} \frac{V_{OUT}}{V_{IS}}$  = - 50dB shall be crosstalk.

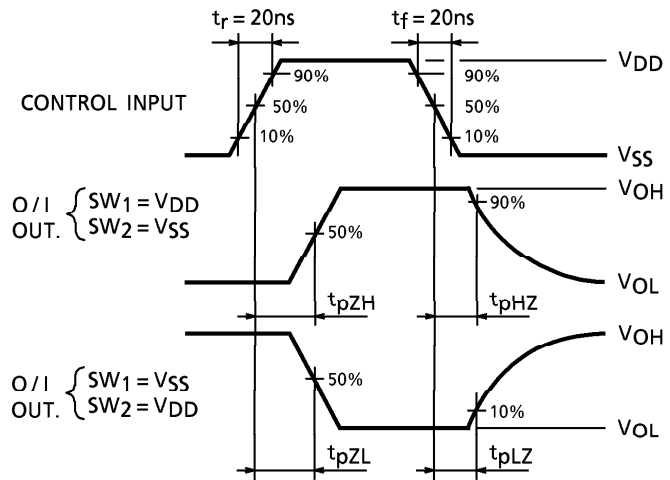
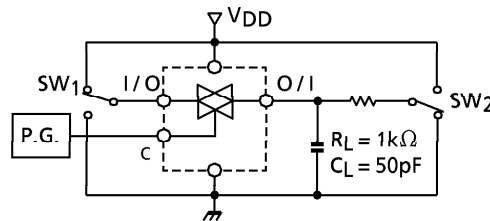
1.  $t_{pLH}$ ,  $t_{pHL}$

I/O-O/I

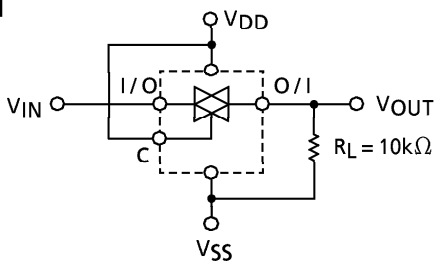


2.  $t_{pZL}$ ,  $t_{pZH}$ ,  $t_{pLZ}$ ,  $t_{pHZ}$

CONTROL-O/I

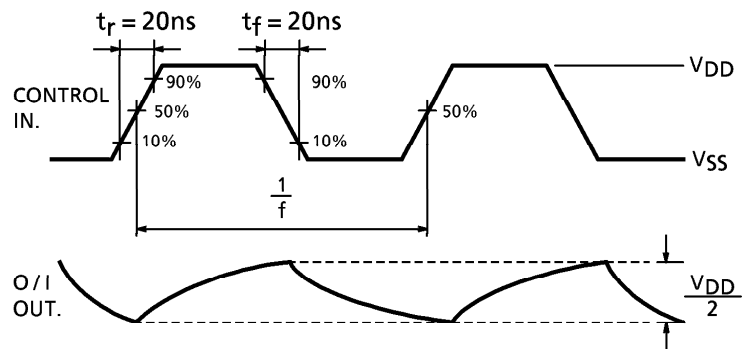
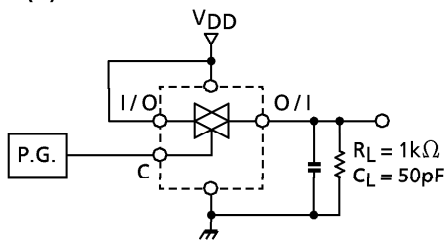


3. RON

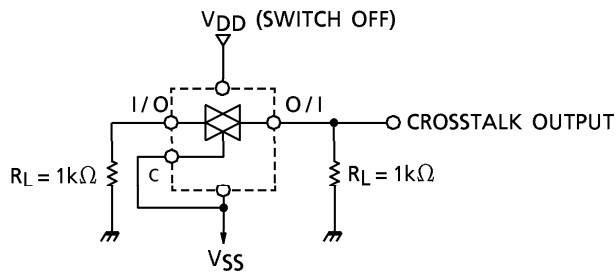
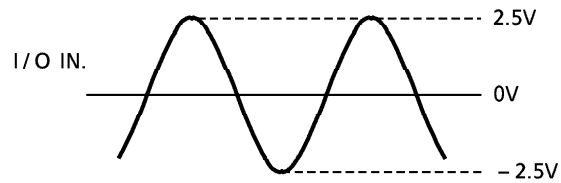
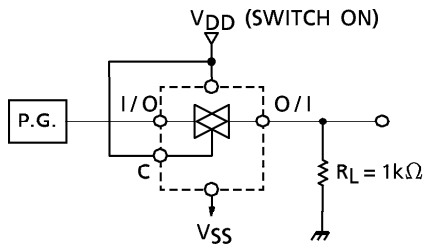


$$RON = 10 \times \frac{(V_{IN} - V_{OUT})}{V_{OUT}} \text{ (k}\Omega\text{)}$$

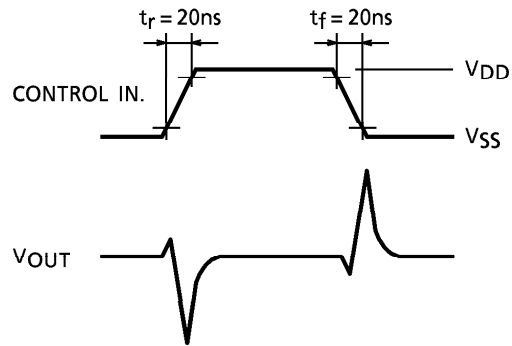
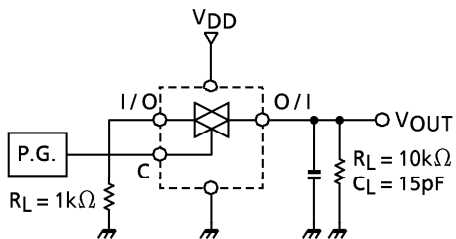
4.  $f_{MAX}(C)$



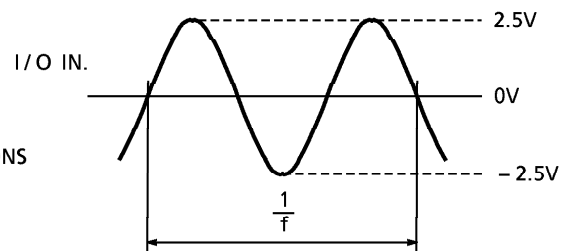
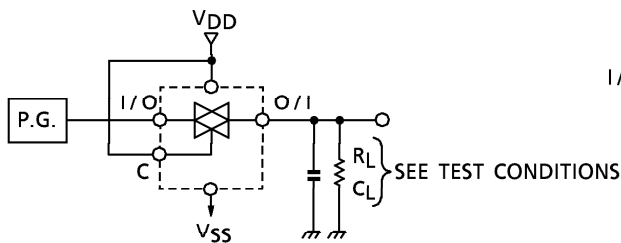
5. CROSSTALK (SWITCH I/O)



6. CROSSTALK (CONTROL INPUT)

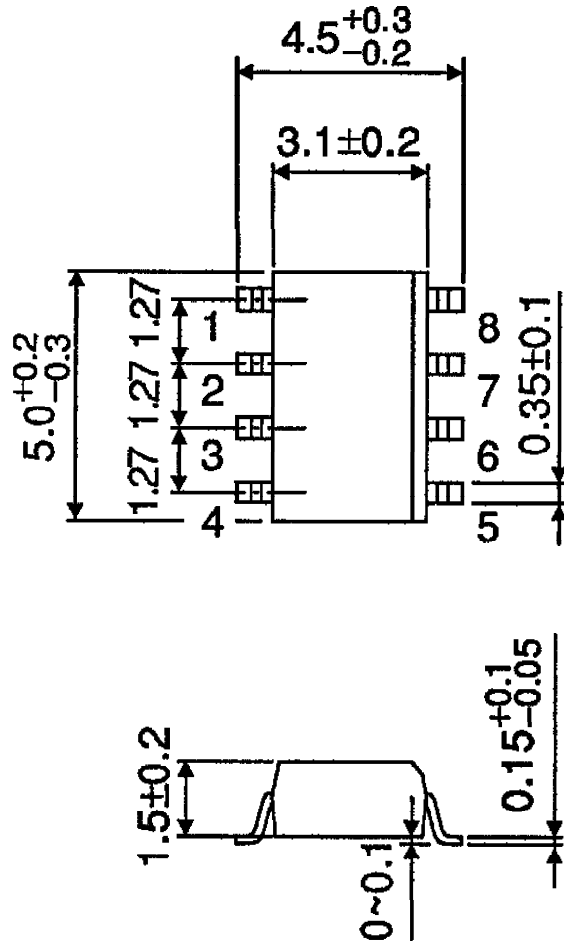


7. TOTAL HARMONIC DISTORTION,  $f_{MAX}$  (I/O-O/I), FEEDTHROUGH (SWITCH OFF)



OUTLINE DRAWING  
SOP8-P-1.27

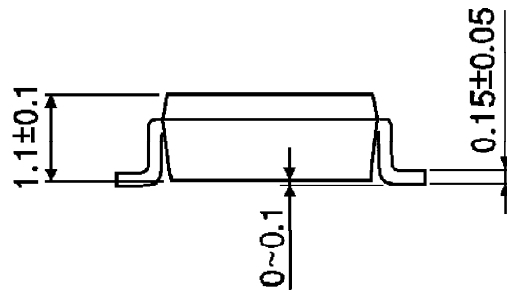
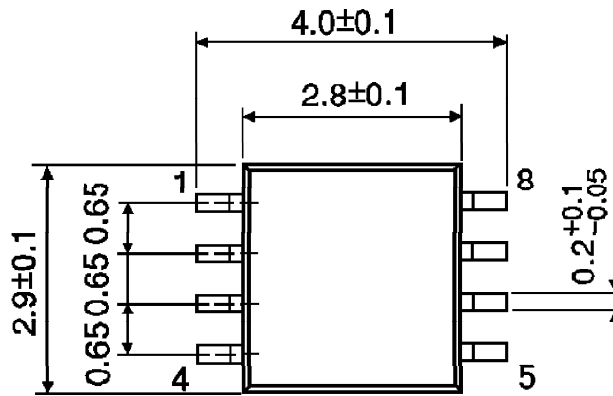
Unit : mm



Weight : 0.05g (Typ.)

OUTLINE DRAWING  
SSOP8-P-0.65

Unit : mm



Weight : 0.02g (Typ.)