

# CDCF5801A

SCAS816-MARCH 2006

# CLOCK MULTIPLIER WITH DELAY CONTROL AND PHASE ALIGNMENT

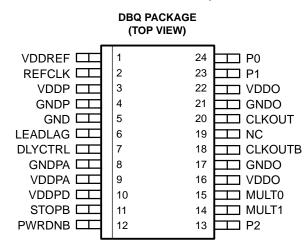
## **FEATURES**

- Low-Jitter Clock Multiplier: x1, x2, x4, x8
- Fail-Safe Power Up Initialization
- Programmable Bidirectional Delay Steps of 1.3 mUI
- Output Frequency Range of 25 MHz to 280 MHz
- Input Frequency Range of 12.5 MHz to 240 MHz
- Low Jitter Generation
- Single-Ended REFCLK Input With Adjustable Trigger Level (Works With LVTTL, HSTL, and LVPECL)
- Differential/Single-Ended Output
- Output Can Drive LVPECL, LVDS, and LVTTL
- Three Power Operating Modes to Minimize Power
- Low Power Consumption (< 190 mW at 280 MHz/3.3 V)</li>
- Packaged in a Shrink Small-Outline Package (DBQ)
- No External Components Required for PLL

### Spread Spectrum Clock Tracking Ability to Reduce EMI (SSC)

## APPLICATIONS

- Video Graphics
- Gaming Products
- Datacom
- Telecom
- Noise Cancellation Created by FPGAs



## DESCRIPTION

The CDCF5801A provides clock multiplication from a reference clock (REFCLK) signal with the unique capability to delay or advance the CLKOUT/CLKOUTB with steps of only 1.3 mUI through a phase aligner. For every rising edge on the DLYCTRL pin the CLKOUT is delayed by a 1.3-mUI step size as long as the LEADLAG input detects a low signal at the time of the DLYCTRL rising edge. Similarly for every rising edge on the DLYCTRL pin the CLKOUT is advanced by a 1.3-mUI step size as long as the LEADLAG pin is high during the transition. This unique capability allows the device to phase align (zero delay) between CLKOUT/CLKOUTB and any one other CLK in the system by feeding the clocks that need to be aligned to the DLYCTRL and the LEADLAG pins. Also it provides the capability to program a fixed delay by providing the proper number of edges on the DLYCTRL pin, while strapping the LEADLAG pin to dc high or low. Further possible applications are:

- Aligning the rising edge of the output clock signal to the input clock rising edge
- Avoiding PLL instability in applications that require very long PLL feedback lines
- Isolation of jitter and digital switching noise
- · Limitation of jitter in systems with good ppm frequency stability

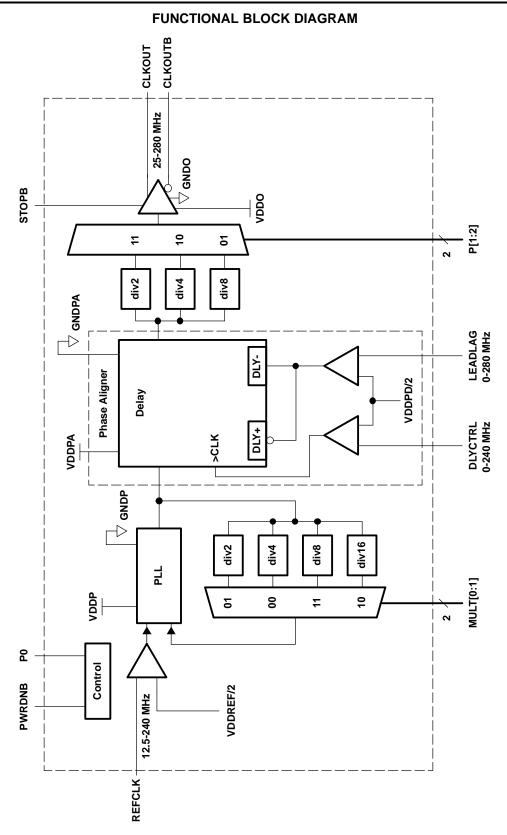
The CDCF5801A has a fail-safe power up initialization state-machine which supports proper operation under all power up conditions.



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The CDCF5801A provides clock multiplication and division from a reference clock (REFCLK) signal. The device is optimized to have extremely low jitter impact from input to output. The predivider pins MULT[0:1] and post-divider pins P[0:2] provide selection for frequency multiplication and division ratios, generating CLKOUT/CLOUTKB frequencies ranging from 25 MHz to 280 MHz with clock input references (REFCLK) ranging from 12.5 MHz to 240 MHz. See Table 1 for detailed frequency support. The selection of pins MULT[0:1] and P[1:2] determines the multiplication value of 1, 2, 4, or 8. The CDCF5801A offers several power-down/ high-impedance modes, selectable by pins P0, STOPB and PWRDN. Another unique capability of the CDCF5801A is the high sensitivity and wide common-mode range of the clock-input pin REFCLK by varying the voltage on the VDDREF pin. The clock signal outputs CLKOUT and CLKOUTB can be used independently to generate single-ended clock signals. The CLKOUT/CLKOUTB outputs can also be combined to generate a differential output signal suitable for LVDS, LVPECL, or HSTL/SSTL signaling. The CDCF5801A is characterized for operation over free-air temperatures of -40°C to 85°C.





#### **TERMINAL FUNCTIONS**

TERMINAL			DECODIDEION
NAME	NO.	I/O	DESCRIPTION
CLKOUT CLKOUTB	2018	0	Output CLK signal (low-noise CMOS) Complementary output CLK signal (low-noise CMOS)
DLYCTRL	7	I	Every rising edge on this pin delays/advances the CLKOUT/CLKOUTB signal by 1/768 <sup>th</sup> of the CLKOUT/CLKOUTB period (1.3 mUI). (E.g., for a 90-degree delay or advancement one needs to provide 192 rising edges). See Table 3.
GND	5		GND for VDDREF and VDDPD
GNDO	17, 21		GND for the output pins (CLKOUT, CLKOUTB)
GNDP	4		GND for the PLL
GNDPA	8		GND for phase aligner, digital logic, and inputs P[0:2], MULT[0:1], STOPB, PWRDNB
LEADLAG	6	I	Controls whether the output CLK is delayed or advanced relative to REFCLK. See Table 3.
MULT0	15	I	PLL multiplication factor select. See Table 1.
MULT1	14		MULT[0:1] = 10: x16
			MULT[0:1] = 11: x8
			MULT[0:1] = 00: ×4
			MULT[0:1] = 01: ×2
NC	19		Not connected; leave pin floating or tied to GND.
P0	24	I	Mode control pins (see Table 1)
			0 - Normal operation
			1 - High-Z outputs and other special settings
P1	23	I	Post divider control (see Table 1)
			P[1:2] = 11: div2
			P[1:2] = 10: div4
P2	13		P[1:2] = 01: div8
PWRDNB	12	I	Active-low power-down state. CLKOUT/CLKOUTB goes low, See Table 2).
			0 - IC in power down
			1 - Normal operation
REFCLK	2	I	Reference input clock
STOPB	11	I	Active low output disabler, PLL and PA still running, CLKOUT and CLKOUTB goes to a dc value as listed in Table 2.
			0 - Outputs disabled
			1 - Normal operation
VDDO	16, 22		VDD for the output pin (CLKOUT, CLKOUTB) and power down circuit
VDDP	3		VDD for PLL and input buffer
VDDPA	9		VDD for phase aligner, digital logic, and inputs P[0:2], MULT[0:1], and STOPB
VDDPD	10		Reference voltage for inputs LEADLAG and DLYCTRL
VDDREF	1		Reference voltage for REFCLK

INPUT-TO-OUTPUT MULTIPLICATION-RATIO	INPUT OUTPUT FREQUENCY (MHz) FREQUENCY (MHz)			PREDIVIDER		POST DIVIDER			NOTE	
WULTIFLICATION-RATIO	FROM	то	FROM	то	MULT0	MULT1	P0	P1	P2	
8	12.5	35	100	280	1	0		1	1	
4	12.5	39	50	156	1	0		1	0	
4	25	70	100	280	1	1		1	1	
	12.5	39	25	78	1	0		0	1	
2	25	78	50	156	1	1	0	1	0	Normal operation <sup>(1)</sup>
	50	140	100	280	0	0		1	1	
	25	78	25	78	1	1		0	1	
1	50	156	50	156	0	0		1	0	
	100	240	100	240	0	1		1	1	
		CI	KOUT high-	impedance	х	x		0	0	
		CLC	OUOTB high-	impedance	^	^		0	0	
CLKOUT = h				OUT = high	х	x	1		1	Special mode of operation
CLKOUTB = high					~	^	1	0	1	Special mode of operation
	CLKOUT = P2						]	1	х	
			CLK	$OUTB = \overline{P2}$	х	X			^	

#### Table 1. Input-to-Output Settings

(1) There is some overlapping of the input frequency ranges for multiplication ratios of 1, 2, and 4. For example, an input frequency of 30 MHz for a multiplication ratio of four falls within both the 12.5 to 39-MHz range and the 25 to 70-MHz range. For best device operation in a case such as this, always select the input frequency range nearer to the top of the table.

#### PLL DIVIDER/MULITPLIER SELECTION

#### Table 2. Power Down Modes

STATE	PWRDNB	STOPB	CLKOUT and CLKOUTB
Power down	0	Х	GNDO
Clock stop	1	0	V <sub>O</sub> , STOP
Normal	1	1	See Table 1

#### Table 3. Programmable Delay and Phase Alignment

DLYCTR	NOTE	LEADLAG	CLKOUT and CLKOUTB
Each rising edge+	For every 32 edges, there are one or two edges for which the phase aligner does not update the phase. Therefore, CLKOUT phase is not updated for every 32 <sup>nd</sup> edge.	Н	Advanced by one step: step size: $1/768$ of the CLKOUT period (1.3 mUI) at P[1:2] = 11 1/1536 of the CLKOUT period (0.65 mUI) at P[1:2] = 10 1/3072 of the CLKOUT period (0.325 mUI) at P[1:2] = 01
Each rising edge+	The frequency of the DI YCTRL pin should	LO	Delayed by one step: step size: $1/768$ of the CLKOUT period (1.3 mUI) at P[1:2] = 11 1/1536 of the CLKOUT period (0.65 mUI) at P[1:2] = 10 1/3072 of the CLKOUT period (0.325 mUI) at P[1:2] = 01

# ABSOLUTE MAXIMUM RATINGS

over operating free-air temperature (unless otherwise noted)<sup>(1)</sup>

V <sub>DDx</sub> <sup>(2)</sup>	Supply voltage range	-0.5 V to 4 V
	Voltage range at any output terminal	-0.5 V to V <sub>DD</sub> + 0.5 V
	Voltage range at any input terminal	-0.5 V to V <sub>DD</sub> + 0.5 V
T <sub>stg</sub>	Storage temperature range	-65°C to 150°C
	Lead temperature 1,6 mm (1/16 inch) from case for 10 seconds	260°C

(1) Stresses beyond those listed under, absolute maximum ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated under, recommended operating conditions" is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.

(2) All voltage values are with respect to the GND terminals.

#### POWER DISSIPATION RATING TABLE

PACKA GE	T <sub>A</sub> ≤ 25°C POWER RATING	DERATING FACTOR <sup>(1)</sup> ABOVE $T_A = 25^{\circ}C$	T <sub>A</sub> = 85°C POWER RATING
DBQ	830 mW	8.3 mW/°C	332 mW

(1) This is the inverse of the junction-to-ambient thermal resistance when board-mounted and with no air flow.

### **RECOMMENDED OPERATING CONDITIONS**

		MIN	NOM	MAX	UNIT
VDDP, VDDPA, VDDO	Supply voltage	3	3.3	3.6	V
V <sub>IH (CMOS)</sub>	High-level input voltage	0.7 VDD			V
VIL (CMOS)	Low-level input voltage			0.3 VDD	V
V <sub>IL</sub> (DLYCTRL, LEADLAG)	Input signal low voltage		V	<u>DDPD</u> – 0.2	V
V <sub>IH</sub> (DLYCTRL, LEADLAG)	Input signal high voltage	$\frac{\text{VDDPD}}{2} + 0.2$			V
(VDDPD)	Input reference voltage for DLYCNTRL and LEADLAG	1.2		VDD	V
I <sub>OH</sub>	High-level output current			-16	mA
I <sub>OL</sub>	Low-level output current			16	mA
(VDDREF) (see Application section)	Input reference voltage for REFCLK	1.2		VDD	V
V <sub>IL</sub> (see Application section)	REFCLK input low voltage		<u>V</u> [	<u>DDREF</u> – 0.2	V
V <sub>IH</sub> (see Application section)	REFCLK input high voltage	$\frac{\text{VDDREF}}{2} + 0.2$			V
T <sub>A</sub>	Operating free-air temperature	-40		85	°C

### TIMING REQUIREMENTS

	PARAMETER	MIN	MAX	UNIT
F <sub>mod</sub>	Input frequency of modulation, (if driven by SSC CLKIN)		33	kHz
	Modulation index, nonlinear maximum 0.5%		0.6%	
SR	Input slew rate	1	4	V/ns
	Input duty cycle on REFCLK	40%	60%	
	Input frequency on REFCLK	12.5	240	MHz
	Output frequency on CLKOUT and CLKOUTB	25	280	MHz
	Allowable frequency on DLYCTRL		240	MHz

## TIMING REQUIREMENTS (continued)

PARAMETER	MIN	MAX	UNIT
Allowable frequency on LEADLAG		280	MHz
Allowable duty cycle on DLYCTRL and LEADLAG pins	25%	75%	

### **ELECTRICAL CHARACTERISTICS**

over recommended operating conditions (unless otherwise noted)

	PARAMET	ER	TEST CON	NDITIONS <sup>(1)</sup>	MIN	TYP <sup>(2)</sup>	MAX	UNIT
V <sub>O(STOP)</sub>	Output voltage	e during Clkstop mode	See Figure 1		1.1		2	V
V <sub>O(X)</sub>	Output crossin	ig-point voltage	See Figure 1 and	Figure 4	$\frac{\text{VDDO}}{2} - 0.2$		$\frac{\text{VDDO}}{2} + 0.2$	V
Vo	Output voltage	e swing (V <sub>OH</sub> - V <sub>OL</sub> )	See Figure 1		1.7		2.9	V
V <sub>IK</sub>	Input clamp vo	oltage	V <sub>DD</sub> = 3 V,	l <sub>l</sub> = -18 mA			-1.2	V
M			V <sub>DD</sub> = 3 to 3.6 V,	See Figure 1	2	2.5		V
V <sub>OH</sub>	High-level input current       PWRDNB; P[0:2 MULT[0:1]; DLYCTRL; LEA         Output impedance (single ended)       High state         Reference current       Low state         Input capacitance       V <sub>DD</sub> REF; VDDP         Input capacitance       Output capacitance         Supply current in power-down s       Supply current in CLK stop state	out voltage	V <sub>DD</sub> = 3 V,	I <sub>OH</sub> = -16 mA	2.2			v
<u> </u>		ut volto go	$V_{DD} = 3 \text{ to } 3.6 \text{ V},$	See Figure 1		0.4	$\begin{array}{c} 2 \\ \hline \frac{VDDO}{2} + 0.2 \\ \hline 2.9 \\ \hline -1.2 \\ \hline .5 \\ \hline 0.4 \\ 0.5 \\ \hline 52 \\ \hline 51 \\ .5 \\ \hline .5 \\ -21 \\ .5 \\ \hline .5 \\ -21 \\ \hline .5 \\ \hline .5 \\ \hline .5 \\ -21 \\ \hline .5 \\ \hline .5$	V
V <sub>OL</sub>	Low-level outp	out voltage	V <sub>DD</sub> = 3 V,	I <sub>OH</sub> = 16 mA			0.5	v
			V <sub>DD</sub> = 3.135 V,	$V_0 = 1 V$	-32	-52		
I <sub>OH</sub>	High-level out	out current	V <sub>DD</sub> = 3.3 V,	V <sub>O</sub> = 1.65 V		-51		mA
			V <sub>DD</sub> = 3.465 V,	V <sub>O</sub> = 3.135 V		-14.5	-21	
			V <sub>DD</sub> = 3.135 V,	V <sub>O</sub> = 1.95 V	43	61.5		
I <sub>OL</sub>	Low-level outp	out current	V <sub>DD</sub> = 3.3 V,	V <sub>O</sub> = 1.65 V		65		mA
			V <sub>DD</sub> = 3.465 V,	$V_{0} = 0.4 V$		25.5	40	
I <sub>OZ</sub>	High-impedan	ce-state output current	P0 = 1,	P1 = P2 = 0			±10	μA
I <sub>OZ(STOP)</sub>			Stop = 0,	$V_{O} = GND \text{ or } V_{DD}$			±100	μA
I <sub>OZ(PD)</sub>			PWRDNB = 0,	$V_{O} = GND \text{ or } V_{DD}$	-10		100	μA
I <sub>IH</sub>		REFCLK; STOPB;	V <sub>DD</sub> = 3.6 V,	$V_I = V_{DD}$			10	μA
IIL	0	PWRDNB; P[0:2]; MULT[0:1]; DLYCTRL; LEADLAG		V <sub>1</sub> =0			-10	μA
		High state	R <sub>I</sub> at I <sub>O</sub> -14.5 mA to	o -16.5 mA	15	35	50	
Z <sub>O</sub>	(single	Low state	R <sub>I</sub> at I <sub>O</sub> 14.5 mA to	o 16.5 mA	10	17	35	Ω
	Reference			PWRDNB = 0			50	μA
I <sub>REF</sub>		V <sub>DD</sub> REF; VDDPD	V <sub>DD</sub> = 3.6 V	PWRDNB = 1			0.5	mA
Cl	Input capacita	nce	$V_I = V_{DD}$ or GND	1		2		pF
C <sub>O</sub>	Output capacit	tance	$V_0 = GND \text{ or } V_{DD}$			3		pF
I <sub>DD</sub> (PD)	Supply current	t in power-down state	REFCLK = 0 MHz PWRDNB = 0; ST	to 280 MHz;			4	mA
I <sub>DD</sub> (CLKSTOP)	Supply current	t in CLK stop state	BUSCLK configure	ed for 280 MHz			44	mA
I <sub>DD</sub> (NORMAL)	Supply current mode)	t (normal operation	BUSCLK 280 MHz P[0:2] = 011; Load	z, MULT[0:1] = 10; d , See Figure 1			75	mA

(1) V<sub>DD</sub> refers to any of the following; VDDP, VDDREF, VDDO, VDDPD, and VDDPA (2) All typical values are at V<sub>DD</sub> = 3.3 V, T<sub>A</sub> =  $25^{\circ}$ C.

## JITTER SPECIFICATION

over recommended free-air temperature range and  $V_{\text{CC}}$  range (unless otherwise noted)

			TEST	CONDITIONS				
	PARAMETER	REFCLK (MHz)	CLKOUT (MHz)	MULT[0:1]	P[0:2]	NOTES	TYP (ps)	MAX (ps)
	Period rms (1-sigma jitter, full frequency band) Period p-p Cycle to cycle +	25	25	11	001		20	48
	Period p-p						120	225
	Cycle to cycle +						70	165
	Cycle to cycle -						70	165
	RMS phase jitter (accumulated, 100 kHz-12.5 MHz)						20 120 70	160
	Period rms (1-sigma jitter, full frequency band)	50	z)         (MHz)         MOL [[0:1]         P[0:2]         NOTES           25         11         001 $\end{tabular}$ $tab$		7	15		
	Period p-p						37	75
	Cycle to cycle +						27	55
	Cycle to cycle -					5	27	55
	RMS phase jitter (accumulated, 100 kHz-25 MHz)					aligner	27	65
	Period rms (1-sigma jitter, full frequency band)	100	100	00	010	(CLKOUT tight to LEADLAG;	5	14
	Period p-p						30	65
(jitter)	Cycle to cycle +					tight to	24	55
	Cycle to cycle -					All typical values are at VDD = 3.3 V,	24	55
	RMS phase jitter (accumulated, 100 kHz-40 MHz)						35	65
	Period rms (1-sigma jitter, full frequency band)	156	156	00	010		4	8
	Period p-p					$I_{A} = 25 \text{ C}.$	20	40
	Cycle to cycle +						17	40
	Cycle to cycle -						17	40
	RMS phase jitter (accumulated, 100 kHz-40 MHz)						15	35
	Period rms (1-sigma jitter, full frequency band)	200	200	01	011		8	15
	Period p-p						38	60
	Cycle to cycle +						20 120 70 70 80 7 37 27 27 27 27 27 27 27 27 27 2	55
	Cycle to cycle -						35	55
	RMS phase jitter (accumulated, 100 kHz-40 MHz)						20 120 70 70 80 7 37 27 27 27 27 27 27 27 27 27 30 24 24 35 4 24 35 4 20 17 17 15 8 38 5 35	60

## **JITTER SPECIFICATION (continued)**

over recommended free-air temperature range and  $V_{\text{CC}}$  range (unless otherwise noted)

			TEST (	CONDITIONS			TYP (ps)	
	PARAMETER	REFCLK (MHz)	CLKOUT (MHz)	MULT[0:1]	P[0:2]	NOTES		MAX (ps)
	Period rms (1-sigma jitter, full frequency band)	25	200	10	011		4	11
	Period p-p					-	20	48
	Cycle to cycle +						16	45
	Cycle to cycle -						16	45
	Period rms (1-sigma jitter, full frequency band)	25	100	10	010		4	11
	Period p-p					-	22	55
	Cycle to cycle +					-	15	45
	Cycle to cycle -						15	45
	Period rms (1-sigma jitter, full frequency band)	70	280	11	011	Phase aligner	4	11
	Period p-p	-				not running	18	48
	Cycle to cycle +					(LEADLAG = 0,	15	45
	Cycle to cycle -					DLYCTRL = 0). All	15	45
(jitter)	Period rms (1-sigma jitter, full frequency band)	25	50	10	001	typical values are	4 20 16 16 4 22 15 15 4 18 15	16
	Period p-p					at	34	75
	Cycle to cycle +					VDD = 3.3 V, T <sub>A</sub> = 25°C.	4 20 16 16 4 22 15 15 4 15 4 15 6 34 20 20 3 15 13 13 6 35 25	65
	Cycle to cycle -						20	65
	Period rms (1-sigma jitter, full frequency band)	78	156	11	010		3	11
	Period p-p					-	15	44
	Cycle to cycle +						13	40
	Cycle to cycle -						13	40
	Period rms (1-sigma jitter, full frequency band)	62.5	125	00	011		6	20
	Period p-p						35	80
	Cycle to cycle +						4 20 16 16 4 22 15 15 4 15 4 15 6 34 20 20 3 15 13 13 6 35 25	75
	Cycle to cycle -						25	75

## SWITCHING CHARACTERISTICS

over recommended operating free-air temperature range (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
t <sub>(DC)</sub>	Output duty cycle over 1000 cycles	See Figure 3	42%		58%	
t <sub>r</sub> , t <sub>f</sub>	Output rise and fall times (measured at 20%-80% of output voltage	See Figure 5	150	250	350	ps

## STATE TRANSITION LATENCY SPECIFICATIONS

	PARAMETER	FROM	то	TEST CONDITION	MIN	TYP	MAX	UNIT
	Delay time, PWRDNB↑ to CLKOUT / CLKOUTB settled	Dower down	Normal				3	
t <sub>(powerup)</sub>	Delay time, PWRDNB <sup>↑</sup> to internal PLL and clock are on and settled	Power down	Normal	See Figure 6			3	ms

### STATE TRANSITION LATENCY SPECIFICATIONS (continued)

	PARAMETER	FROM	то	TEST CONDITION	MIN	ΤΥΡ	МАХ	UNIT
•	Delay time, power up to CLKOUT output settled	N/	Normal	See Figure 6			3	ms
t <sub>(VDDpowerup)</sub>	Delay time, power up to internal PLL and clock are on and settled	V <sub>DD</sub>	Normai	See Figure 6			3	1115
t <sub>(MULT)</sub>	MULT0 and MULT1 change to CLKOUT output resettled	Normal	Normal	See Figure 7			1	ms
t <sub>(CLKON)</sub>	STOPB <sup>↑</sup> to CLKOUT glitch-free clock edges	CLK stop	Normal	See Figure 8			10	ns
t <sub>(CLKSETL)</sub>	STOPB <sup>↑</sup> to CLKOUT output settled to within 50 ps of the phase before STOPB was disabled	CLK stop	Normal	See Figure 8			20	cycles
t <sub>(CLKOFF)</sub>	STOPB $\downarrow$ to CLKOUT output disabled	Normal	CLK stop	See Figure 8			5	ns
t <sub>(powerdown)</sub>	Delay time, PWRDNB↓ to the device in the power-down mode	Normal	Power down	See Figure 6			1	ms
t <sub>(STOP)</sub>	Maximum time in CLKSTOP (STOPB = 0) before reentering normal mode (STOPB = 1)	STOPB	Normal	See Figure 8	100			μs
t <sub>(ON)</sub>	Minimum time in normal mode (STOPB = 1) before reentering CLKSTOP (STOPB = 0)	Normal	CLK stop	See Figure 8	100			ms

### PARAMETER MEASUREMENT INFORMATION

### **TESTING CONDITIONS**

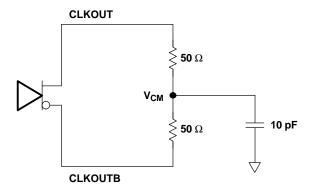
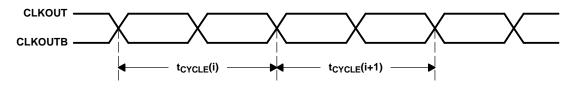


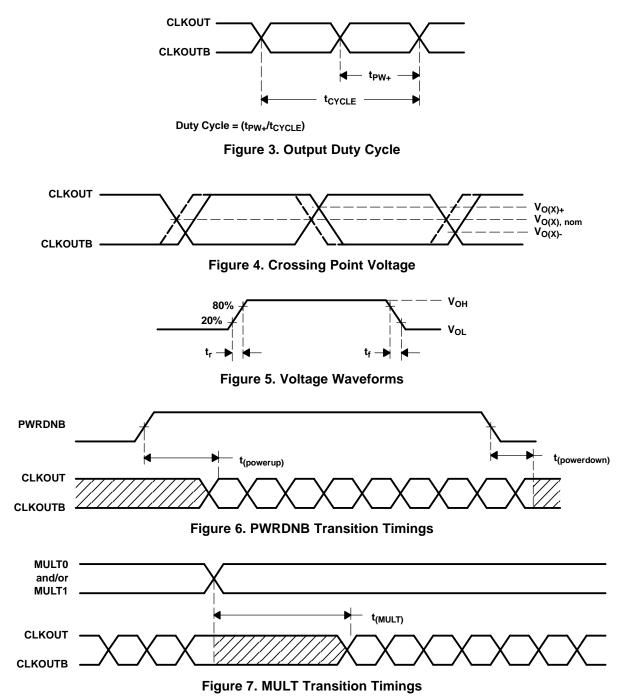
Figure 1. Test Load and Voltage Definitions V<sub>OH</sub>, V<sub>OL</sub>, V<sub>O(STOP)</sub>

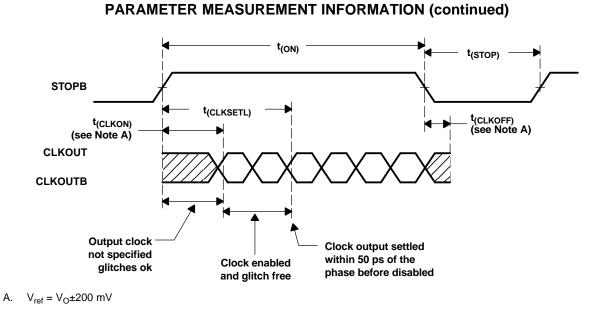


 $\label{eq:cycle-to-Cycle Jitter (t_{(jitter)}) = \ |\ t_{CYCLE}(i) - t_{CYCLE}(i+1) \ | \ over \ 1000 \ consecutive \ cycles$ 

Figure 2. Cycle-to-Cycle Jitter









## APPLICATION INFORMATION

#### **APPLICATION EXAMPLE**

The following figure shows an example of using the CDCF5801A as a phase aligner de-skewing the unknown buffer delay of the two CDCV304s in the circuit. This circuitry would not be possible with a simple PLL because the feedback of the PLL would have the second CDCV304 in the loop, causing instability of the PLL due to a long delay.

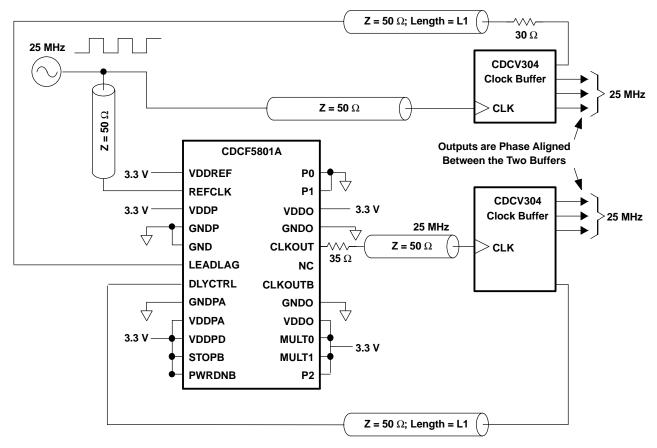


Figure 9. Application Example

#### NOTE:

If an active element (microcontroller, ASIC, DSP< FPYA, DSP, etc.) is used in the CDCF5801A CLKOUT to DLYCTRL feedback loop, see application report SCAA075.

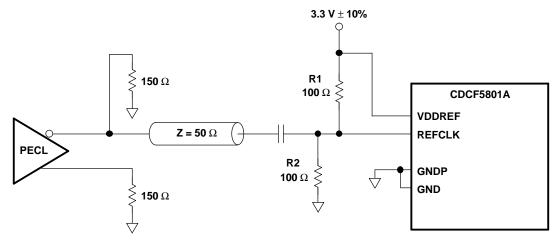
### SELECTING VDDREF

Generally, VDDREF can be set to any value between 1.2 V and VDD. The setting of VDDREF directly influences the trigger voltage of the input. Special care must be taken when using small signal swings to drive the CVDCF5801 input (e.g., PECL). It is recommended to connect VDDREF directly to VDD, ac-couple the REFCLK input, and rebias the signal.

The following circuit is recommended to drive the CDCF5801A from a differential clock signal like PECL.



### **APPLICATION INFORMATION (continued)**



A. NOTE: If more signal swing is required and an unterminated transmission is on option, then R1 and R2 can both be replaced with 10-k $\Omega$  resistors.

Figure 10. Driving the CDCF5801A From a Differential Clock Signal

## **Revision History**

DATE	REV	PAGE	SECTION	DESCRIPTION
15 MAR 05	*	-	_	Original version

### **PACKAGING INFORMATION**

Orderable Device	Status <sup>(1)</sup>	Package Type	Package Drawing	Pins	Package Qty	e Eco Plan <sup>(2)</sup>	Lead/Ball Finish	MSL Peak Temp <sup>(3)</sup>
CDCF5801ADBQ	ACTIVE	SSOP/ QSOP	DBQ	24	50	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
CDCF5801ADBQG4	ACTIVE	SSOP/ QSOP	DBQ	24	50	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
CDCF5801ADBQR	ACTIVE	SSOP/ QSOP	DBQ	24	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR
CDCF5801ADBQRG4	ACTIVE	SSOP/ QSOP	DBQ	24	2500	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-2-260C-1 YEAR

<sup>(1)</sup> The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

**PREVIEW:** Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

<sup>(2)</sup> Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

TBD: The Pb-Free/Green conversion plan has not been defined.

**Pb-Free (RoHS):** TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes.

**Pb-Free (RoHS Exempt):** This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

<sup>(3)</sup> MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

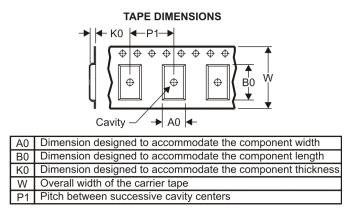
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### TAPE AND REEL INFORMATION





## QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



*All dimensions are nomina	*All	dimensions	are	nomina	l
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Device	Package Type	Package Drawing			Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
CDCF5801ADBQR	SSOP/ QSOP	DBQ	24	2500	330.0	16.4	6.5	9.0	2.1	8.0	16.0	Q1



# PACKAGE MATERIALS INFORMATION

11-Mar-2008

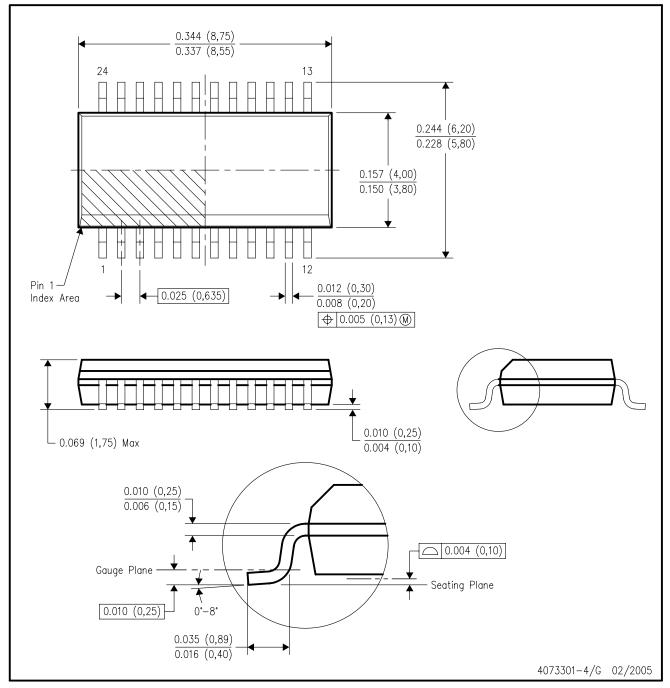


\*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
CDCF5801ADBQR	SSOP/QSOP	DBQ	24	2500	346.0	346.0	33.0

DBQ (R-PDSO-G24)

PLASTIC SMALL-OUTLINE PACKAGE



NOTES: A. All linear dimensions are in inches (millimeters).

B. This drawing is subject to change without notice.

C. Body dimensions do not include mold flash or protrusion not to exceed 0.006 (0,15) per side.

D. Falls within JEDEC MO-137 variation AE.



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