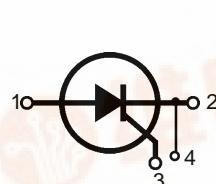


Phase Control Thyristors

V_{RSM}	V_{RRM}	Type
V_{DSM}	V_{DRM}	
V	V	
1300	1200	CS 142-12io8
1700	1600	CS 142-16io8

Not for new application

 $V_{RRM} = 1200-1600 \text{ V}$ $I_{T(RMS)} = 260 \text{ A}$ $I_{T(AV)M} = 164 \text{ A}$ TO-209AC
(TO-94)1 = Anode, 2 = Cathode,
3 = Gate, 4 = Auxiliary Cathode

Symbol	Test Conditions	Maximum Ratings		
$I_{T(RMS)}$	$T_{VJ} = T_{VJM}$	260	A	
$I_{T(AV)M}$	$T_{case} = 85^\circ\text{C}; 180^\circ \text{ sine}$	140	A	
	$T_{case} = 75^\circ\text{C}; 180^\circ \text{ sine}$	164	A	
I_{TSM}	$T_{VJ} = 45^\circ\text{C}; V_R = 0$ $t = 10 \text{ ms (50 Hz), sine}$ $t = 8.3 \text{ ms (60 Hz), sine}$	3100	A	
	$T_{VJ} = T_{VJM}$ $V_R = 0$ $t = 10 \text{ ms (50 Hz), sine}$ $t = 8.3 \text{ ms (60 Hz), sine}$	2600	A	
	$T_{VJ} = T_{VJM}$ $V_R = 0$ $t = 10 \text{ ms (50 Hz), sine}$ $t = 8.3 \text{ ms (60 Hz), sine}$	2800	A	
I^2t	$T_{VJ} = 45^\circ\text{C}$ $V_R = 0$ $t = 10 \text{ ms (50 Hz), sine}$ $t = 8.3 \text{ ms (60 Hz), sine}$	48 000	A^2s	
	$T_{VJ} = T_{VJM}$ $V_R = 0$ $t = 10 \text{ ms (50 Hz), sine}$ $t = 8.3 \text{ ms (60 Hz), sine}$	45 000	A^2s	
$(di/dt)_{cr}$	$T_{VJ} = T_{VJM}$ $f = 50 \text{ Hz}, t_p = 200 \mu\text{s}$ $V_D = 1/2 V_{DRM}$ $I_G = 0.5 \text{ A}$ $di_G/dt = 0.5 \text{ A}/\mu\text{s}$	repetitive, $I_T = 500 \text{ A}$	150	$\text{A}/\mu\text{s}$
		non repetitive, $I_T = I_{T(AV)M}$	500	$\text{A}/\mu\text{s}$
$(dv/dt)_{cr}$	$T_{VJ} = T_{VJM}$ $R_{GK} = \infty$; method 1 (linear voltage rise)	$V_{DR} = 2/3 V_{DRM}$	1000	$\text{V}/\mu\text{s}$
P_{GM}	$T_{VJ} = T_{VJM}$ $I_T = I_{T(AV)M}$	$t_p = 30 \mu\text{s}$ $t_p = 500 \mu\text{s}$ $t_p = 10 \text{ ms}$	120 60 16	W
V_{RGM}			10	V
T_{VJ}			-40...+125	$^\circ\text{C}$
T_{VJM}			125	$^\circ\text{C}$
T_{stg}			-40...+125	$^\circ\text{C}$
M_d	Mounting torque	16-20 142-177	Nm lb.in.	
Weight		110	g	

Features

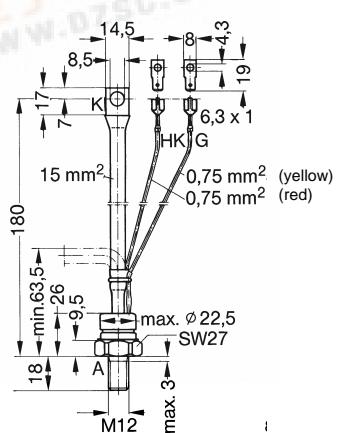
- Thyristor for line frequencies
- International standard package JEDEC TO-209AC
- Planar glassivated chip
- Long-term stability of blocking currents and voltages
- Gate and auxiliary cathode pin connection

Applications

- Motor control
- Power converter
- AC power controller

Advantages

- Space and weight savings
- Simple mounting
- Improved temperature and power cycling

Dimensions in mm (1 mm = 0.0394")

Symbol	Test Conditions	Characteristic Values		
I_R, I_D	$T_{VJ} = T_{VJM}$; $V_R = V_{RRM}$; $V_D = V_{DRM}$	≤	15	mA
V_T	$I_T = 300 \text{ A}$; $T_{VJ} = 25^\circ\text{C}$	≤	1.35	V
V_{TO}	For power-loss calculations only ($T_{VJ} = 125^\circ\text{C}$)	1.0	1.7	V
r_T				$\text{m}\Omega$
V_{GT}	$V_D = 6 \text{ V}$; $T_{VJ} = 25^\circ\text{C}$	≤	2.5	V
	$T_{VJ} = -40^\circ\text{C}$	≤	3.5	V
I_{GT}	$V_D = 6 \text{ V}$; $T_{VJ} = 25^\circ\text{C}$	≤	150	mA
	$T_{VJ} = -40^\circ\text{C}$	≤	200	mA
V_{GD}	$T_{VJ} = T_{VJM}$; $V_D = 2/3 V_{DRM}$	≤	0.2	V
I_{GD}		≤	10	mA
I_L	$T_{VJ} = 25^\circ\text{C}$; $t_p = 10 \mu\text{s}$ $I_G = 0.5 \text{ A}$; $di_G/dt = 0.5 \text{ A}/\mu\text{s}$	≤	300	mA
I_H	$T_{VJ} = 25^\circ\text{C}$; $V_D = 6 \text{ V}$; $R_{GK} = \infty$	≤	200	mA
t_{gd}	$T_{VJ} = 25^\circ\text{C}$; $V_D = 1/2 V_{DRM}$ $I_G = 0.5 \text{ A}$; $di_G/dt = 0.5 \text{ A}/\mu\text{s}$	≤	2	μs
t_q	$T_{VJ} = T_{VJM}$; $I_T = 50 \text{ A}$, $t_p = 200 \mu\text{s}$; $di/dt = -10 \text{ A}/\mu\text{s}$ $V_R = 100 \text{ V}$; $dv/dt = 20 \text{ V}/\mu\text{s}$; $V_D = 2/3 V_{DRM}$	typ.	150	μs
R_{thJC}	DC current		0.18	K/W
R_{thJH}	DC current		0.22	K/W
d_s	Creepage distance on surface	10.5	mm	
d_A	Strike distance through air	10.5	mm	
a	Max. acceleration, 50 Hz	50	m/s^2	

Accessories:

Nut M12 DIN 439/SW27

Lock washer A12 DIN 128