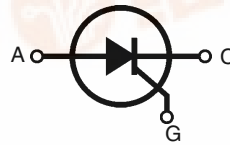


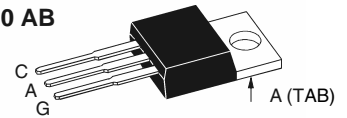
Phase Control Thyristors

$V_{RRM} = 800-1200 \text{ V}$
 $I_{T(RMS)} = 29 \text{ A}$
 $I_{T(AV)M} = 19 \text{ A}$

V_{RSM} V_{DSM}	V_{RRM} V_{DRM}	Type	Type
V	V	TO 220	TO 263
800	800	CS 19-08ho1	CS 19-08ho1S
1200	1200	CS 19-12ho1	CS 19-12ho1S



TO-220 AB



TO-263 AA



A = Anode, C = Cathode, G = Gate

Symbol	Test Conditions	Maximum Ratings	
$I_{T(RMS)}$ $I_{T(AV)M}$	$T_{VJ} = T_{VJM}$ $T_C = 85^\circ\text{C}; 180^\circ \text{ sine}$	29	A
I_{TSM}	$T_{VJ} = 45^\circ\text{C};$ $V_R = 0 \text{ V}$	t = 10 ms (50 Hz), sine	160 A
		t = 8.3 ms (60 Hz), sine	180 A
I^2t	$T_{VJ} = 45^\circ\text{C}$ $V_R = 0 \text{ V}$	t = 10 ms (50 Hz), sine	140 A
		t = 8.3 ms (60 Hz), sine	160 A
$(di/dt)_{cr}$	$T_{VJ} = T_{VJM}$ f = 50 Hz, $t_p = 200\mu\text{s}$ $V_D = 2/3 V_{DRM}$ $I_G = 0.15 \text{ A}$ $di_G/dt = 0.15 \text{ A}/\mu\text{s}$	repetitive, $I_T = 20 \text{ A}$	100 A/ μs
		non repetitive, $I_T = I_{T(AV)M}$	500 A/ μs
$(dv/dt)_{cr}$	$T_{VJ} = T_{VJM}$ $R_{GK} = \infty$; method 1 (linear voltage rise)	$V_{DR} = 2/3 V_{DRM}$	500 V/ μs
P_{GM}	$T_{VJ} = T_{VJM}$ $I_T = I_{T(AV)M}$	$t_p = 30 \mu\text{s}$	5 W
		$t_p = 300 \mu\text{s}$	2.5 W
P_{GAV}			0.5 W
V_{RGM}		10	V
T_{VJ}		-40...+125	$^\circ\text{C}$
T_{VJM}		125	$^\circ\text{C}$
T_{stg}		-40...+125	$^\circ\text{C}$
M_d	Mounting torque with screw M3; TO220	0.45/4	Nm/lb.in.
	Mounting torque with screw M3.5; TO220	0.55/5	Nm/in.
Weight		2	g

Features

- SCR for frequency up to 400Hz
- International standard package
- High performance glass passivated chip
- Long-term stability of leakage current and blocking voltage
- Epoxy meets UL 94V-0

Applications

- Motor control
- Power converter
- AC power controller
- Light and temperature control
- SCR for inrush current limiting in power supplies or AC drive

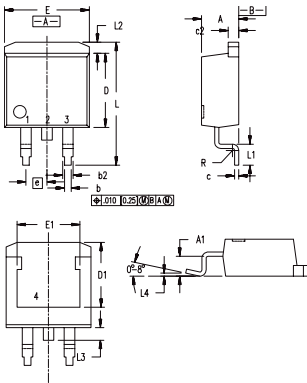
Advantages

- Space and weight savings
- Simple mounting

Symbol	Test Conditions	Characteristic Values
I_R, I_D	$T_{VJ} = T_{VJM}; V_R = V_{RRM}; V_D = V_{DRM}$	≤ 5 mA
V_T	$I_T = 20$ A; $T_{VJ} = 25^\circ\text{C}$	≤ 1.6 V
V_{T0}	For power-loss calculations only ($T_{VJ} = 125^\circ\text{C}$)	0.85 V
r_T		27 m Ω
V_{GT}	$V_D = 6$ V; $T_{VJ} = 25^\circ\text{C}$	≤ 1.5 V
	$T_{VJ} = -40^\circ\text{C}$	≤ 2.5 V
I_{GT}	$V_D = 6$ V; $T_{VJ} = 25^\circ\text{C}$	≤ 28 mA
	$T_{VJ} = -40^\circ\text{C}$	≤ 50 mA
V_{GD}	$T_{VJ} = T_{VJM}; V_D = 2/3 V_{DRM}$	≤ 0.2 V
I_{GD}		≤ 3 mA
I_L	$T_{VJ} = 25^\circ\text{C}; t_p = 10$ μs $I_G = 0.1$ A; $di_G/dt = 0.1$ A/ μs	≤ 75 mA
I_H	$T_{VJ} = 25^\circ\text{C}; V_D = 6$ V; $R_{GK} = \infty$	≤ 50 mA
t_{gd}	$T_{VJ} = 25^\circ\text{C}; V_D = 1/2 V_{DRM}$ $I_G = 0.1$ A; $di_G/dt = 0.1$ A/ μs	≤ 2 μs
R_{thJC}	DC current	1.0 K/W
R_{thCK}	DC current	typ 0.25 K/W
a	Max. acceleration, 50 Hz	50 m/s ²

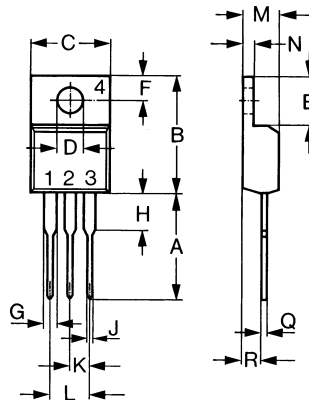
Dimensions in mm (1 mm = 0.0394")

TO 263 AA



Dim.	Millimeter		Inches	
	Min.	Max.	Min.	Max.
A	4.06	4.83	.160	.190
A1	2.03	2.79	.080	.110
b	0.51	0.99	.020	.039
b2	1.14	1.40	.045	.055
c	0.46	0.74	.018	.029
c2	1.14	1.40	.045	.055
D	8.64	9.65	.340	.380
D1	7.11	8.13	.280	.320
E	9.65	10.29	.380	.405
E1	6.86	8.13	.270	.320
e	2.54	BSC	.100	BSC
L	14.61	15.88	.575	.625
L1	2.29	2.79	.090	.110
L2	1.02	1.40	.040	.055
L3	1.27	1.78	.050	.070
L4	0	0.38	0	.015
R	0.46	0.74	.018	.029

TO 220 AB



Dim.	Millimeter		Inches	
	Min.	Max.	Min.	Max.
A	12.70	13.97	0.500	0.550
B	14.73	16.00	0.580	0.630
C	9.91	10.66	0.390	0.420
D	3.54	4.08	0.139	0.161
E	5.85	6.85	0.230	0.270
F	2.54	3.18	0.100	0.125
G	1.15	1.65	0.045	0.065
H	2.79	5.84	0.110	0.230
J	0.64	1.01	0.025	0.040
K	2.54	BSC	0.100	BSC
M	4.32	4.82	0.170	0.190
N	1.14	1.39	0.045	0.055
Q	0.35	0.56	0.014	0.022
R	2.29	2.79	0.090	0.110