

**SONY**

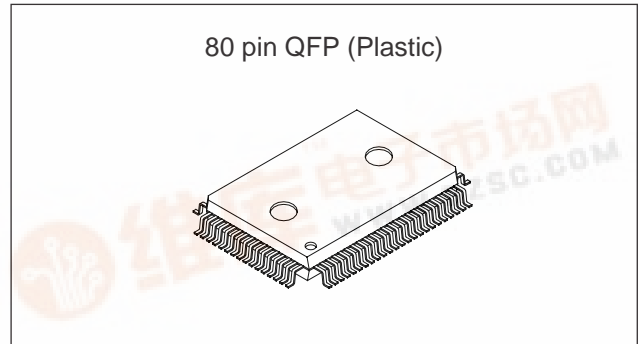
# CXP82612/82616

## CMOS 8-bit Single Chip Microcomputer

### Description

The CXP82612/82616 microcomputer is composed of a CPU, ROM, RAM, and I/O ports. These chips feature many other high-performance circuits in a single-chip CMOS design, including an A/D converter, serial interface, timer/counter, time-base timer, fluorescent display controller/driver, remote control receiver and 32kHz timer/counter.

This device also includes a power-on reset function and sleep/stop functions which can be used to achieve low power consumption.



### Features

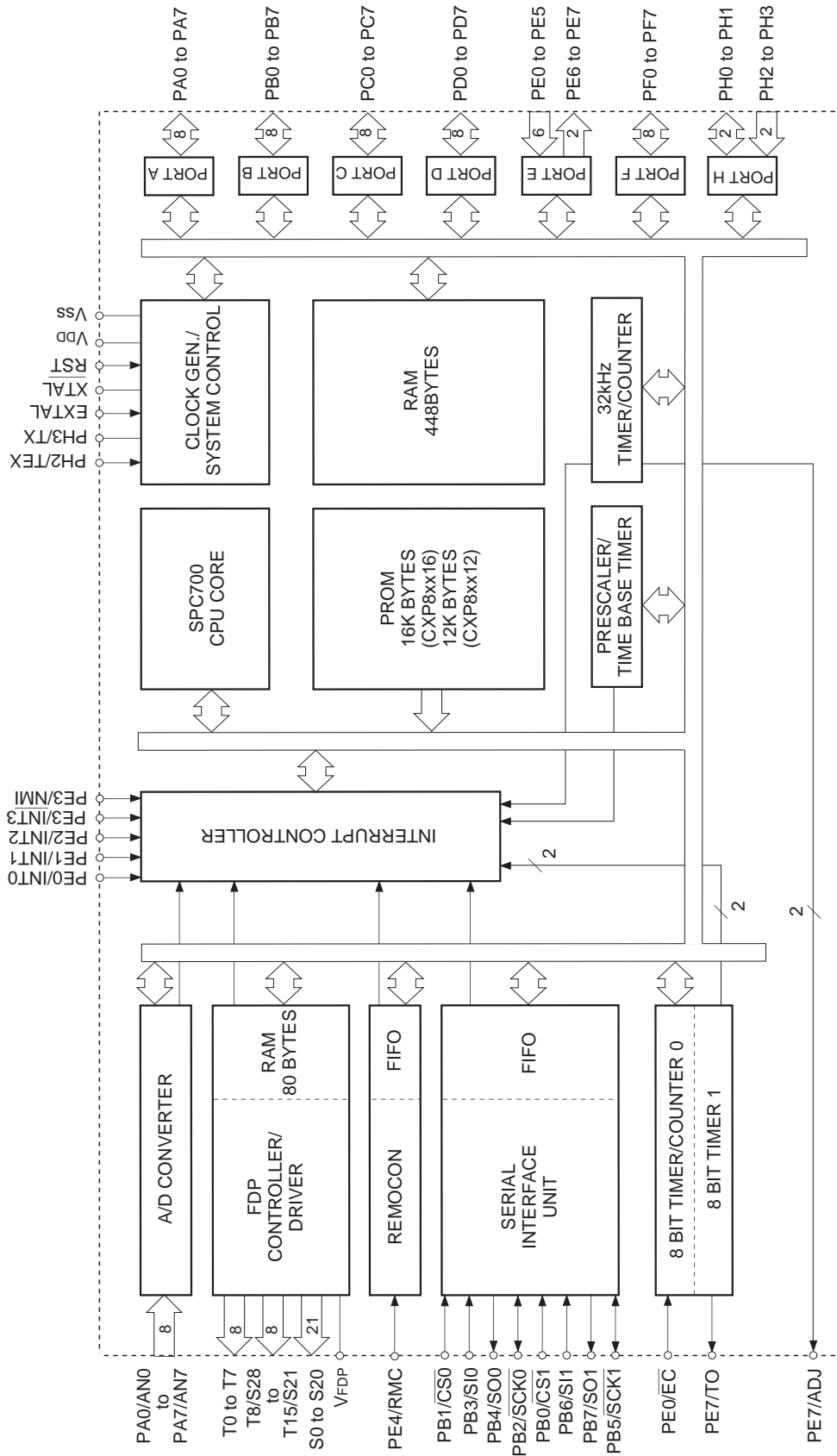
- Instruction set which supports a wide array of data types
  - 213 types of instructions which include 16-bit calculations, multiplication and division arithmetic, and boolean bit operations.
- Minimum instruction cycle 400ns for 10MHz, 122µs/for 32kHz operation
- On-chip ROM 12K bytes (CXP82612)  
16K bytes (CXP82616)
- On-chip RAM 448 bytes (Including fluorescent display data area)
- Peripheral functions
  - A/D converter 8-bit, 8-channel, successive approximation system (conversion rate 32µs/10MHz)
  - Serial interface On-chip 8-bit, 8-stage FIFO (1 to 8 bytes auto transfer),  
1 circuit 2-channel
  - Timers 8-bit timer  
8-bit timer/counter  
19-bit time base timer  
32kHz timer/counter
  - Fluorescent display controller/driver Maximum of 336 segments display available  
1 to 16 digits dynamic display  
Dimmer function  
High voltage tolerance output (40V)  
On-chip pull-down resistor (Mask option)  
Hardware key scan function (Maximum of 8 × 16 key matrix available)
  - Remote control receiver circuit On-chip 6 stage FIFO 8-bit pulse measurement counter
- Interrupts 13 factors, 13 vectors multi-interruption possible
- Standby mode Sleep/stop
- Package 80-pin plastic QFP  
CXP82600 80-pin ceramic QFP
- Piggyback/evaluator

### Structure

Silicon gate CMOS IC

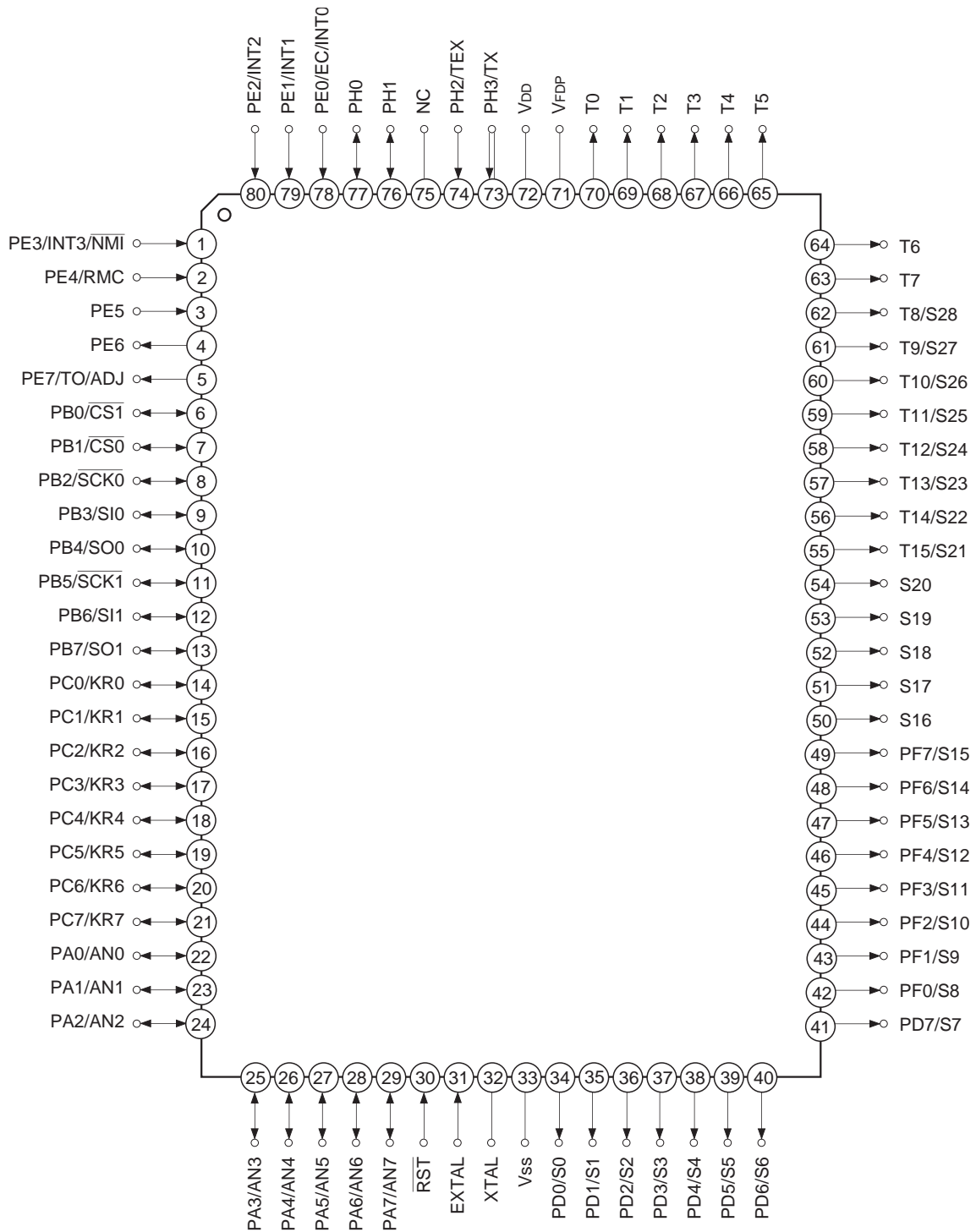
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Block Diagram

Pin Assignment (Top View)



- Note)**
1. NC (Pin 75) is always connected to V<sub>DD</sub>.
  2. PH3/TX (Pin 73) is input port during port selection;  
oscillation output during oscillation selection

Pin Description

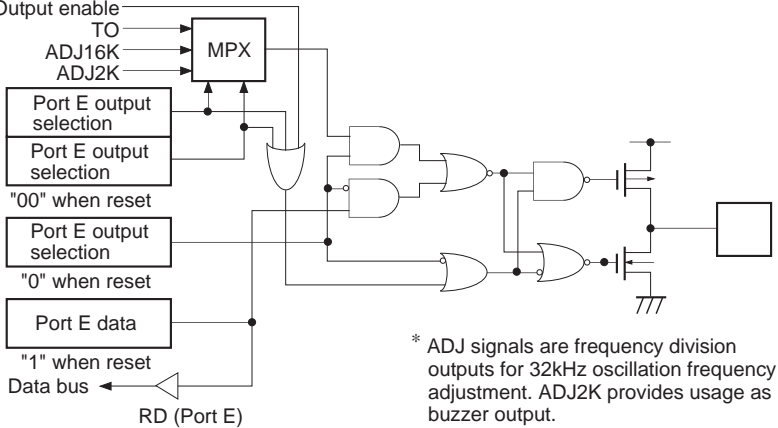
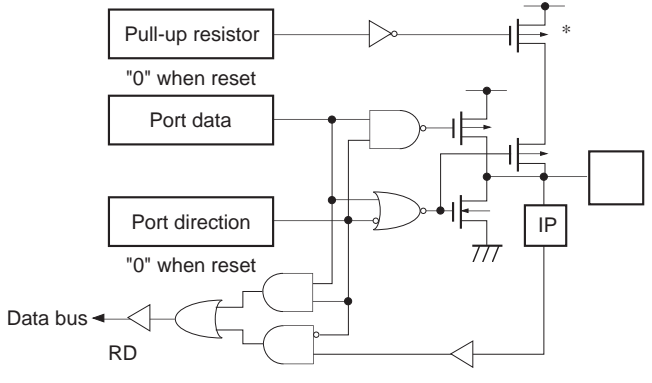
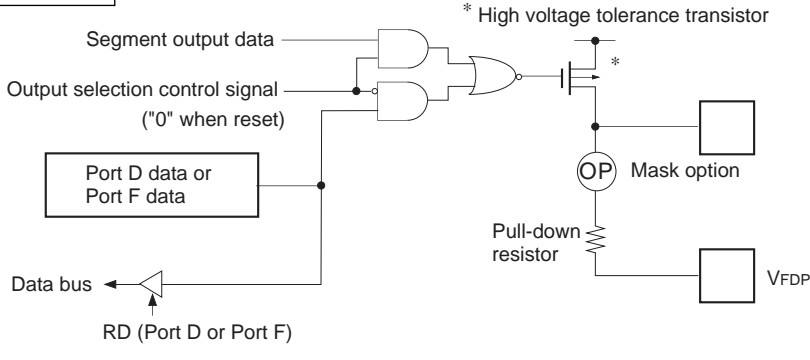
Symbol	I/O	Functions	
PA0/AN0 to PA7/AN7	I/O/Analog Input	(Port A) 8-bit I/O port. I/O can be set in a bit unit. Incorporation of pull-up resistor can be set through the software in a unit of 4 bits. (8 pins)	Analog inputs to A/D converter. (8 pins)
PB0/ $\overline{CS1}$	I/O/Input	(Port B) 8-bit I/O port. I/O can be set in a bit unit. Incorporation of pull-up resistor can be set through the software in a unit of 4 bits. (8 pins)	Chip select input for serial interface (CH1).
PB1/ $\overline{CS0}$	I/O/Input		Chip select input for serial interface (CH0).
PB2/ $\overline{SCK0}$	I/O/I/O		Serial clock I/O (CH0).
PB3/SI0	I/O/Input		Serial data input (CH0).
PB4/SO0	I/O/Output		Serial data output (CH0).
PB5/ $\overline{SCK1}$	I/O/I/O		Serial clock I/O (CH1).
PB6/SI1	I/O/Input		Serial data input (CH1).
PB7/SO1	I/O/Output		Serial data output (CH1).
PC0/KR0 to PC7/KR7	I/O/Input	(Port C) 8-bit I/O port. I/O can be set in a bit unit. Capable of driving 12mA sink current. Incorporation of pull-up resistor can be set through the software in a unit of 4 bits. (8 pins)	Key return input for FDP segment signal which performs key scanning.
PE0/INT0/ $\overline{EC0}$	Input/Input/ Input	(Port E) 8-bit port. Upper 6 bits are for inputs; lower 2 bits are for outputs. (8 pins)	External interrupt requests. (4 pins)
PE1/INT1	Input/Input		
PE2/INT2	Input/Input		External event input to timer/counter. (1 pin)
PE3/INT3/ NMI	Input/Input/ Input		Non-maskable interruption request input.
PE4/RMC	Input/Input		Input for remote control receiver circuit.
PE5	Input		
PE6	Input		
PE7/TO/ ADJ	Output/Output		Output for timer/counter rectangular waveform and 32kHz oscillation frequency division.

Symbol	I/O	Functions	
PH0 to PH1	I/O	(Port H) 2-bit I/O port. I/O can be set in a bit unit. Incorporation of pull-up resistor can be set through the software in a unit of 2 bits. (2 pins)	
PF0/S8 to PF7/S15	Output/Output	(Port F) 8-bit output port. (8 pins)	Segment signal output for FDP.
S16 to S20	Output	Segment signal output for FDP.	
T8/S28 to T15/S21	Output/Output	Dual purpose output for FDP timing and segment signals.	
T0 to T7	Output	Timing signal output for FDP.	
PD0/S0 to PD7/S7	Output/Output	(Port D) 8-bit output port. (8 pins)	Segment signal output for FDP.
V <sub>FDP</sub>		Provides voltage for FDP when on-chip resistor is selected under mask option.	
EXTAL	Input	Crystal connectors for system clock oscillation. When the clock is supplied externally, input to EXTAL; opposite phase clock should be input to XTAL.	
XTAL	Output		
PH2/TEX	Input/Input	(Port H) 2-bit input port. (2 pins)	Crystal connectors for 32kHz timer/counter clock oscillation circuit. Connect a 32kHz crystal oscillator between TEX and TX. For usage as event input, connect clock oscillation source to TEX, and leave TX open.
PH3/TX	Input/Output		
$\overline{\text{RST}}$	Input	Low-level active. System reset. $\overline{\text{RST}}$ is input pin.	
NC		NC. Under normal operating conditions, connect to V <sub>DD</sub> .	
V <sub>DD</sub>		V <sub>CC</sub> supply.	
V <sub>SS</sub>		GND	

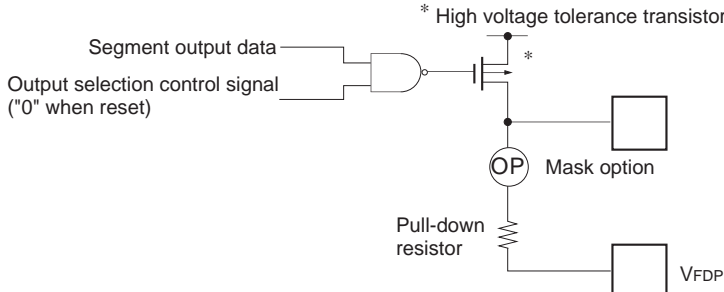
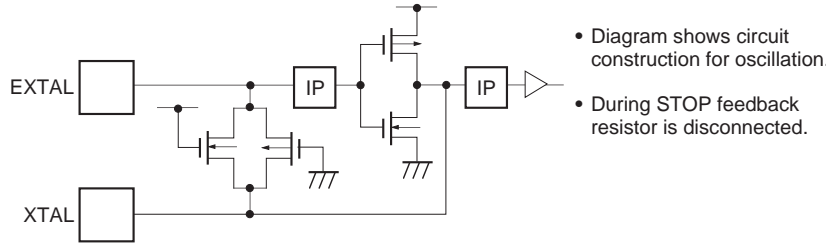
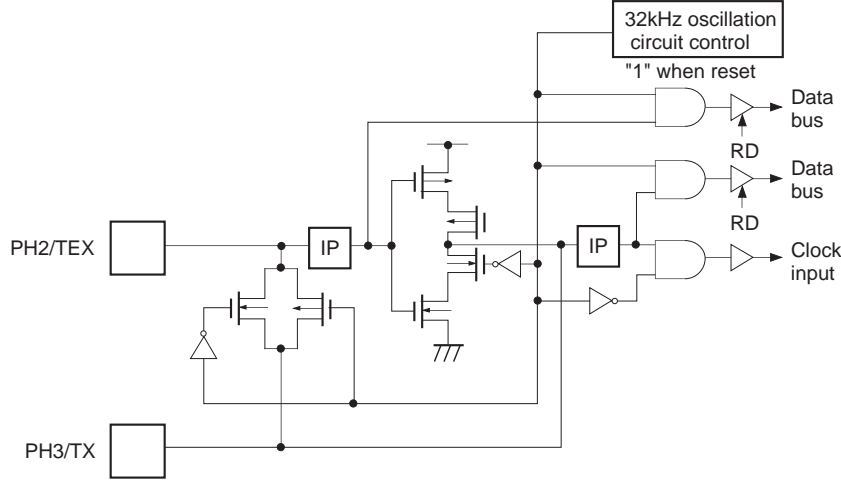
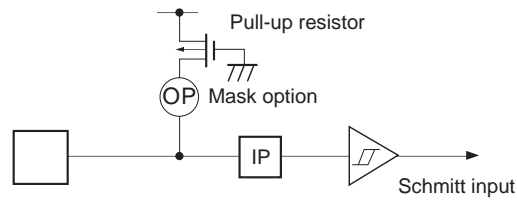
I/O Circuit Format for Pins

Pin	Circuit format	When reset
<p>PA0/AN0 to PA7/AN7</p> <p>8 pins</p>	<p>Port A</p> <p>Pull-up resistor "0" when reset</p> <p>Port A data</p> <p>Port A direction "0" when reset</p> <p>Data bus ←</p> <p>RD (Port A)</p> <p>Port A input selection "0" when reset</p> <p>Input multiplexer</p> <p>A/D converter</p> <p>IP Input protection circuit</p> <p>* Pull-up transistors approx. 100kΩ</p>	<p>Hi-Z</p>
<p>PB0/<math>\overline{\text{CS1}}</math> PB1/<math>\overline{\text{CS0}}</math> PB3/SI0 PB6/SI1</p> <p>4 pins</p>	<p>Port B</p> <p>Pull-up resistor "0" when reset</p> <p>Port B data</p> <p>Port B direction "0" when reset</p> <p>Data bus ←</p> <p>RD (Port B)</p> <p>CS0 CS1 SI0 SI1</p> <p>Schmitt input</p> <p>IP</p> <p>* Pull-up transistors approx. 100kΩ</p> <p>SI0 and SI1 are not schmitt input.</p>	<p>Hi-Z</p>
<p>PB2/<math>\overline{\text{SCK0}}</math> PB5/<math>\overline{\text{SCK1}}</math></p> <p>2 pins</p>	<p>Port B</p> <p>Pull-up resistor "0" when reset</p> <p>SCK OUT</p> <p>Output enable</p> <p>Port B output selection "0" when reset</p> <p>Port B data</p> <p>Port B direction "0" when reset</p> <p>Data bus ←</p> <p>RD (Port B)</p> <p>SCK in</p> <p>Schmitt input</p> <p>IP</p> <p>* Pull-up transistors approx. 100kΩ</p>	<p>Hi-Z</p>

Pin	Circuit format	When reset
<p>PB4/SO0 PB7/SO1</p> <p>2 pins</p>	<p>Port B</p> <p>Pull-up resistor "0" when reset</p> <p>SO</p> <p>Output enable</p> <p>Port B output selection "0" when reset</p> <p>Port B data</p> <p>Port B direction "0" when reset</p> <p>Data bus</p> <p>RD (Port B)</p> <p>* Pull-up transistors approx. 100kΩ</p>	<p>Hi-Z</p>
<p>PC0/KR0 to PC7/KR7</p> <p>8 pins</p>	<p>Port C</p> <p>Pull-up resistor "0" when reset</p> <p>Port C data</p> <p>Port C direction "0" when reset</p> <p>Data bus</p> <p>RD (Port C)</p> <p>Key input signal</p> <p>*1 Large current drive of 12mA possible *2 Pull-up transistors approx. 100kΩ</p>	<p>Hi-Z</p>
<p>PE0/<math>\overline{EC}</math>/INT0 PE1/INT1 PE2/INT2 PE3/INT3/<math>\overline{NMI}</math> PE4/RMC</p> <p>5 pins</p>	<p>Port E</p> <p>Schmitt input</p> <p>IP</p> <p><math>\overline{EC}</math>/INT0 INT1 INT2 INT3/<math>\overline{NMI}</math> RMC</p> <p>Data bus</p> <p>RD (Port E)</p>	<p>Hi-Z</p>
<p>PE5</p> <p>1 pin</p>	<p>Port E</p> <p>IP</p> <p>Data bus</p> <p>RD (Port E)</p>	<p>Hi-Z</p>
<p>PE6</p> <p>1 pin</p>	<p>Port E</p> <p>Port E data "1" when reset</p> <p>Data bus</p> <p>RD (Port E)</p>	<p>High level</p>

Pin	Circuit format	When reset
<p>PE7/TO/ADJ</p> <p>1 pin</p>	<p>Port E</p>  <p>* ADJ signals are frequency division outputs for 32kHz oscillation frequency adjustment. ADJ2K provides usage as buzzer output.</p>	<p>High level (High level with 150kΩ resistor when reset)</p>
<p>PH0 to PH1</p> <p>2 pins</p>	<p>Port H</p>  <p>* Pull-up transistors approx. 100kΩ</p>	<p>Hi-Z</p>
<p>PD0/S0 to PD7/S7</p> <p>PF0/S8 to PF7/S15</p> <p>16 pins</p>	<p>Port D</p> <p>Port F</p>  <p>* High voltage tolerance transistor</p> <p>* Mask option</p>	<p>Hi-Z or Low level (When PD resistor is connected)</p>



Pin	Circuit format	When reset
<p>S16 to S20 T15/S21 to T8/S28 T0 to T7</p> <p>21 pins</p>	 <p>* High voltage tolerance transistor</p> <p>Segment output data</p> <p>Output selection control signal ("0" when reset)</p> <p>Mask option</p> <p>Pull-down resistor</p> <p>V<sub>FDP</sub></p>	<p>Hi-Z or Low level (When PD resistor is connected)</p>
<p>EXTAL XTAL</p> <p>2 pins</p>	 <ul style="list-style-type: none"> <li>• Diagram shows circuit construction for oscillation.</li> <li>• During STOP feedback resistor is disconnected.</li> </ul>	<p>Oscillation</p>
<p>PH2/TEX PH3/TX</p> <p>2 pins</p>	 <p>32kHz oscillation circuit control</p> <p>"1" when reset</p> <p>Data bus</p> <p>RD</p> <p>Data bus</p> <p>RD</p> <p>Clock input</p>	<p>Oscillation halted port input</p>
<p><math>\overline{\text{RST}}</math></p> <p>1 pin</p>	 <p>Pull-up resistor</p> <p>Mask option</p> <p>Schmitt input</p>	<p>High level</p>

## Absolute Maximum Ratings

(V<sub>SS</sub> = 0V)

Item	Symbol	Rating	Unit	Remarks
Supply voltage	V <sub>DD</sub>	-0.3 to +7.0	V	
Input voltage	V <sub>IN</sub>	-0.3 to +7.0* <sup>1</sup>	V	
Output voltage	V <sub>OUT</sub>	-0.3 to +7.0* <sup>1</sup>	V	
Display output voltage	V <sub>OD</sub>	V <sub>DD</sub> - 40 to V <sub>DD</sub> + 0.3	V	As P channel transistor is open drain, V <sub>DD</sub> voltage is determined as standard.
High level output current	I <sub>OH</sub>	-5	mA	Other than display output pins* <sup>2</sup> : per pin
	I <sub>ODH1</sub>	-15	mA	Display output S0 to S20: per pin
	I <sub>ODH2</sub>	-35	mA	Display output T0 to T7 T8/S28 to T15/S21: per pin
High level total output current	∑I <sub>OH</sub>	-40	mA	Total of other than display output pins
	∑I <sub>ODH</sub>	-100	mA	Total of display output pins
Low level output current	I <sub>OL</sub>	15	mA	Port 1 pin
	I <sub>OLC</sub>	20	mA	Large current port pin* <sup>3</sup>
Low level total output current	∑I <sub>OL</sub>	100	mA	Entire pin total
Operating temperature	T <sub>opr</sub>	-20 to +75	°C	
Storage temperature	T <sub>stg</sub>	-55 to +150	°C	
Allowable power dissipation	P <sub>D</sub>	600	mW	

\*<sup>1</sup> V<sub>IN</sub> and V<sub>OUT</sub> must not exceed V<sub>DD</sub> + 0.3V.

\*<sup>2</sup> Specifies output current of general-purpose I/O ports.

\*<sup>3</sup> The large current drive transistor is an N-ch transistor of Port C (PC).

**Note)** If the absolute maximum ratings are exceeded, the LSI could reach permanent breakdown. Also, observing recommended operating conditions is desirable; otherwise, the LSI's reliability could be affected.

## Recommended Operating Conditions

(V<sub>SS</sub> = 0V)

Item	Symbol	Min.	Max.	Unit	Remarks
Supply voltage	V <sub>DD</sub>	4.5	5.5	V	High speed mode (1/2, 1/4 clock) guaranteed operation range
		3.5	5.5	V	Low speed mode (1/16 clock) guaranteed operation range
		2.7	5.5	V	Guaranteed operation range with TEX clock
		2.5	5.5	V	Guaranteed data hold operation range during stop
High level input voltage	V <sub>IH</sub>	0.7V <sub>DD</sub>	V <sub>DD</sub>	V	*1
	V <sub>IHS</sub>	0.8V <sub>DD</sub>	V <sub>DD</sub>	V	Hysteresis input*2
	V <sub>IHEX</sub>	V <sub>DD</sub> - 0.4	V <sub>DD</sub> + 0.3	V	EXTAL pin*3
Low level input voltage	V <sub>IL</sub>	0	0.3V <sub>DD</sub>	V	*1
	V <sub>ILS</sub>	0	0.2V <sub>DD</sub>	V	Hysteresis input*2
	V <sub>ILEX</sub>	-0.3	0.4	V	EXTAL pin*3
Operating temperature	Topr	-20	+75	°C	

\*1 All regular input port (PA, PB3, PB4, PB6, PB7, PC, PE5, PH).

\*2 For pins  $\overline{RST}$ ,  $\overline{CS0}$ ,  $\overline{CS1}$ ,  $\overline{SCK0}$ ,  $\overline{SCK1}$ ,  $\overline{EC}/INT0$ , INT1, INT2, INT3/ $\overline{NMI}$ , RMC.

\*3 Specifies only for external clock input.

**Electrical Characteristics**

**DC Characteristics**

(Ta = -20 to +75°C, Vss = 0V)

Item	Symbol	Pin	Condition	Min.	Typ.	Max.	Unit
High level output voltage	VOH	PA, PB, PC, PE6, PE7, PH0, PH1	VDD = 4.5V, IOH = -0.5mA	4.0			V
			VDD = 4.5V, IOH = -1.2mA	3.5			V
Low level output voltage	VOL		VDD = 4.5V, IOL = 1.8mA			0.4	V
			VDD = 4.5V, IOL = 3.6mA			0.6	V
		PC	VDD = 4.5V, IOL = 12.0mA			1.5	V
Input current	IiHE	EXTAL	VDD = 5.5V, VIH = 5.5V	0.5		40	μA
	IiLE		VDD = 5.5V, VIL = 0.4V	-0.5		-40	μA
	IiHT	TEX	VDD = 5.5V, VIL = 5.5V	0.1		10	μA
			VDD = 5.5V, VIL = 0.4V	-0.1		-10	μA
	IiLR	RST*1	VDD = 5.5V, VIL = 0.4V	-1.5		-400	μA
	IiL	PA to PC*2, PH0*2, PH1*2		VDD = 5.5V, VIL = 0.4V			-50
VDD = 4.5V, VIL = 4.0V			-3.3			μA	
Display output current	IOH	S0 to S20		-8			mA
		S21/T15 to S28/T8 T0 to T7	VDD = 4.5V VOH = VDD - 2.5V	-20			mA
Open drain output leak current (P-CH Tr off state)	ILOL	S0 to S20 S21/T15 to S28/T8 T0 to T7	VDD = 5.5V VOL = VDD - 35V VFDP = VDD - 35V			-20	μA
Pull down resistor*3	RL	S0 to S20 S21/T15 to S28/T8 T0 to T7	VDD = 5V VOD - VFDP = 30V	60	100	270	kΩ
Input/Output leak current	IIZ	PA to PC*2, PH0*2, PH1*2, RST*2	VDD = 5.5V VI = 0, 5.5V			±10	μA

Item	Symbol	Pin	Codition	Min.	Typ.	Max.	Unit
Supply current*4	I <sub>DD1</sub>	V <sub>DD</sub>	High-speed mode operation (1/2 frequency divider clock)		20	40	mA
			V <sub>DD</sub> = 5.5V, 10MHz crystal oscillation (C <sub>1</sub> = C <sub>2</sub> = 15pF)				
	I <sub>DD2</sub>		V <sub>DD</sub> = 3V, 32kHz crystal oscillation (C <sub>1</sub> = C <sub>2</sub> = 47pF)		35	100	μA
	I <sub>DDS1</sub>		Sleep mode		1.2	8	mA
			V <sub>DD</sub> = 5.5V, 10MHz crystal oscillation (C <sub>1</sub> = C <sub>2</sub> = 15pF)				
	I <sub>DDS2</sub>		V <sub>DD</sub> = 3V, 32kHz crystal oscillation (C <sub>1</sub> = C <sub>2</sub> = 47pF)		9	30	μA
I <sub>DDS3</sub>	Stop mode V <sub>DD</sub> = 5.5V, termination of 32kHz and 10MHz crystal oscillation.				30	μA	
Input capacitance	C <sub>IN</sub>	For pins other than S0 to S28, T0 to T7, PE6, PE7, V <sub>DD</sub> , V <sub>SS</sub> , V <sub>FDP</sub>	1MHz clock 0V other than the measured pins		10	20	pF

\*1  $\overline{\text{RST}}$  specifies the input current when pull-up resistor has been selected; leakage current when no resistor has been selected.

\*2 Pins PA to PC, PH0, and PH1 specifies the input current when pull-up resistor has been selected; leakage current when no resistor has been selected.

\*3 Applies when the on-chip pull-down resistor is selected under the mask option.

\*4 All output pins are left open.

AC Characteristics

(1) Clock timing

( $T_a = -20$  to  $+75^\circ\text{C}$ ,  $V_{DD} = 4.5$  to  $5.5\text{V}$ ,  $V_{SS} = 0\text{V}$ )

Item	Symbol	Pins	Conditions	Min.	Typ.	Max.	Unit
System clock frequency	$f_c$	XTAL EXTAL	Fig. 1, Fig. 2	1		10	MHz
System clock input pulse width	$t_{XL}$ , $t_{XH}$	EXTAL	Fig. 1, Fig. 2 External clock drive	37.5			ns
System clock input rise and fall time	$t_{CR}$ , $t_{CF}$	EXTAL	Fig. 1, Fig. 2 External clock drive			200	ns
Event count input clock pulse width	$t_{EH}$ , $t_{EL}$	$\overline{\text{EC}}$	Fig. 3	$t_{\text{sys}} + 50^*$			ns
Event count input clock rise and fall time	$t_{ER}$ , $t_{EF}$	$\overline{\text{EC}}$	Fig. 3			20	ms
System clock frequency	$f_c$	TEX TX	$V_{DD} = 2.7$ to $5.5\text{V}$ Fig. 2 (32kHz clock applied condition)		32.768		kHz
Event count input clock input pulse width	$t_{TL}$ , $t_{TH}$	TEX	Fig. 3	10			$\mu\text{s}$
Event count input clock rise and fall time	$t_{TR}$ , $t_{TF}$	TEX	Fig. 3			20	ms

\*  $t_{\text{sys}}$  indicates the three values below according to the upper two bits (CPU clock selection) of the clock control register (address: 00FEH).

$t_{\text{sys}} [\text{ns}] = 2000/f_c$  (upper two bits = "00"),  $4000/f_c$  (upper two bits = "01"),  $16000/f_c$  (upper two bits = "11")

Fig. 1. Clock timing

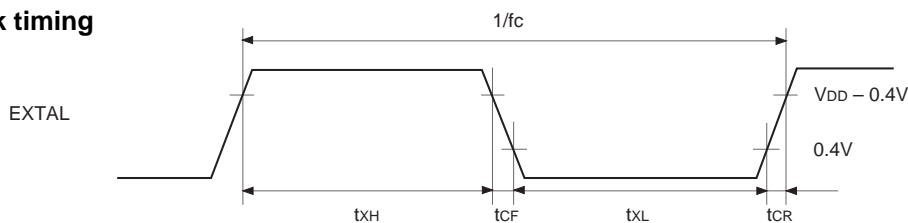


Fig. 2. Clock applied conditions

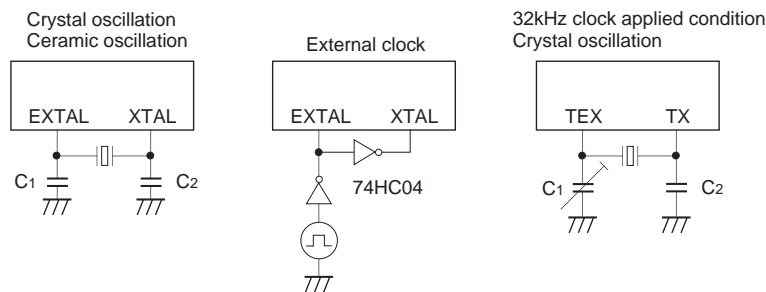
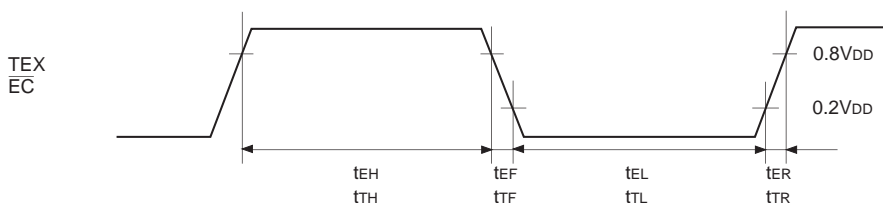


Fig. 3. Event count clock timing



## (2) Serial transfer

(Ta = -20 to +75°C, V<sub>DD</sub> = 4.5 to 5.5V, V<sub>SS</sub> = 0V)

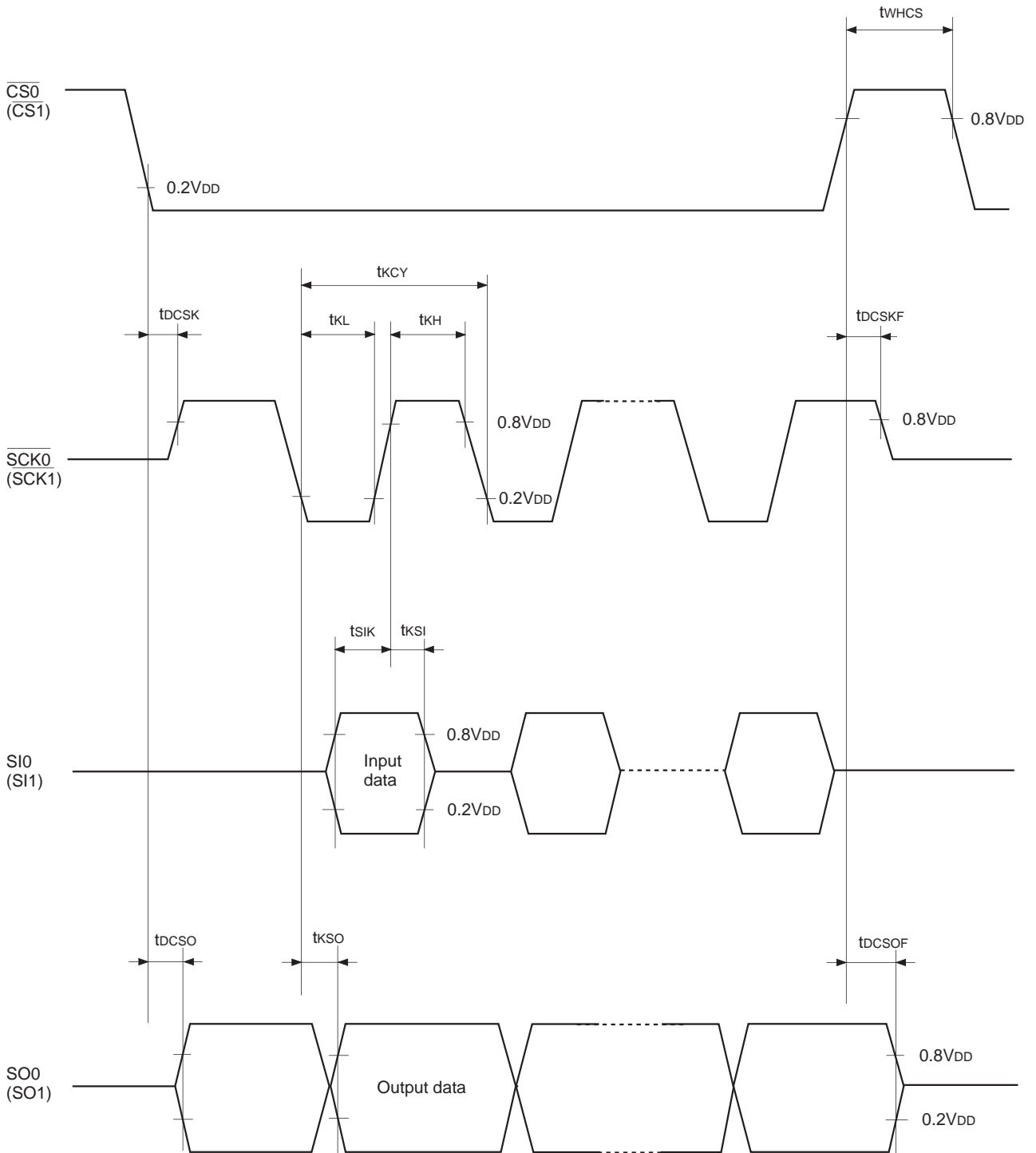
Item	Symbol	Pin	Condition	Min.	Max.	Unit
$\overline{CS0} \downarrow \rightarrow \overline{SCK0}$ ( $\overline{CS1} \downarrow \rightarrow \overline{SCK1}$ ) delay time	t <sub>DCSK</sub>	$\overline{SCK0}$ ( $\overline{SCK1}$ )	Chip select transfer mode ( $\overline{SCK0}$ ( $\overline{SCK1}$ ) = output mode)		t <sub>sys</sub> + 200	ns
$\overline{CS0} \uparrow \rightarrow \overline{SCK0}$ ( $\overline{CS1} \uparrow \rightarrow \overline{SCK1}$ ) float delay time	t <sub>DCSKF</sub>	$\overline{SCK0}$ ( $\overline{SCK1}$ )	Chip select transfer mode ( $\overline{SCK0}$ ( $\overline{SCK1}$ ) = output mode)		t <sub>sys</sub> + 200	ns
$\overline{CS0} \downarrow \rightarrow SO0$ ( $\overline{CS1} \downarrow \rightarrow SO1$ ) delay time	t <sub>DCSO</sub>	SO0 (SO1)	Chip select transfer mode		t <sub>sys</sub> + 200	ns
$\overline{CS0} \uparrow \rightarrow SO0$ ( $\overline{CS1} \uparrow \rightarrow SO1$ ) float delay time	t <sub>DCSOF</sub>	SO0 (SO1)	Chip select transfer mode		t <sub>sys</sub> + 200	ns
$\overline{CS0}$ ( $\overline{CS1}$ ) high level width	t <sub>WHCS</sub>	$\overline{CS0}$ ( $\overline{CS1}$ )	Chip select transfer mode	t <sub>sys</sub> + 200		ns
$\overline{SCK0}$ ( $\overline{SCK1}$ ) cycle time	t <sub>KCY</sub>	$\overline{SCK0}$ ( $\overline{SCK1}$ )	Input mode	2t <sub>sys</sub> + 200		ns
			Output mode	16000/fc		ns
$\overline{SCK0}$ ( $\overline{SCK1}$ ) high and low level widths	t <sub>KH</sub> t <sub>KL</sub>	$\overline{SCK0}$ ( $\overline{SCK1}$ )	Input mode	t <sub>sys</sub> + 100		ns
			Output mode	8000/fc - 50		ns
SI0 (SI1) input setup time (for $\overline{SCK0} \uparrow$ ( $\overline{SCK1} \uparrow$ ))	t <sub>SIK</sub>	SI0 (SI1)	$\overline{SCK0}$ ( $\overline{SCK1}$ ) input mode	100		ns
			$\overline{SCK0}$ ( $\overline{SCK1}$ ) output mode	200		ns
SI0 (SI1) input hold time (for $\overline{SCK0} \uparrow$ ( $\overline{SCK1} \uparrow$ ))	t <sub>KSI</sub>	SI0 (SI1)	$\overline{SCK0}$ ( $\overline{SCK1}$ ) input mode	t <sub>sys</sub> + 200		ns
			$\overline{SCK0}$ ( $\overline{SCK1}$ ) output mode	100		ns
$\overline{SCK0} \downarrow \rightarrow SO0$ ( $\overline{SCK1} \downarrow \rightarrow SO1$ ) delay time	t <sub>KSO</sub>	SO0 (SO1)	$\overline{SCK0}$ ( $\overline{SCK1}$ ) input mode		t <sub>sys</sub> + 200	ns
			$\overline{SCK0}$ ( $\overline{SCK1}$ ) output mode		100	ns

**Note 1)** t<sub>sys</sub> indicates the three values below according to the upper two bits (CPU clock selection) of the control register clock (address: 00FEH).

t<sub>sys</sub> [ns] = 2000/fc (upper two bits = "00"), 4000/fc (upper two bits = "01"), 16000/fc (upper two bits = "11")

**Note 2)** The load condition for the  $\overline{SCK0}$  ( $\overline{SCK1}$ ) output mode, SO0 (SO1) output delay time is 50pF + 1TTL.

Fig. 4. Serial transfer CH0 timing

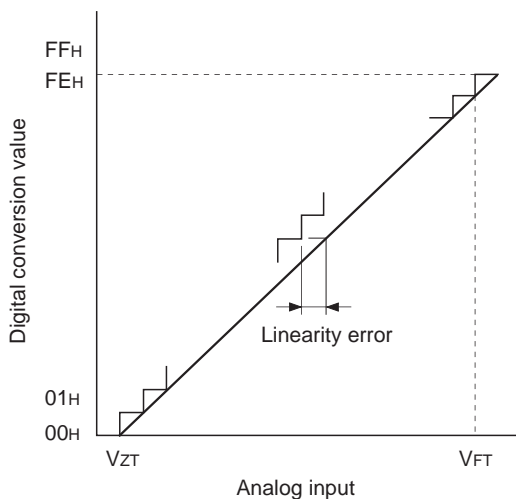




**(3) A/D converter characteristics** (Ta = -20 to +75°C, VDD = 4.5 to 5.5V, AVREF = 4.0 to AVDD, VSS = 0V)

Item	Symbol	Pin	Condition	Min.	Typ.	Max.	Unit
Resolution						8	Bits
Linearity error			Ta = 25°C VDD = 5.0V VSS = 0V			±3	LSB
Zero transition voltage	VZT*1			-10	-70	150	mV
Full-scale transition voltage	VFT*2			4930	5050	5120	mV
Conversion time	tCONV			160/fADC*3			µs
Sampling time	tSAMP			12/fADC*3			µs
Analog input voltage	VIAN	AN0 to AN7		0		AVREF	V

**Fig. 5. Definition of A/D converter terms**



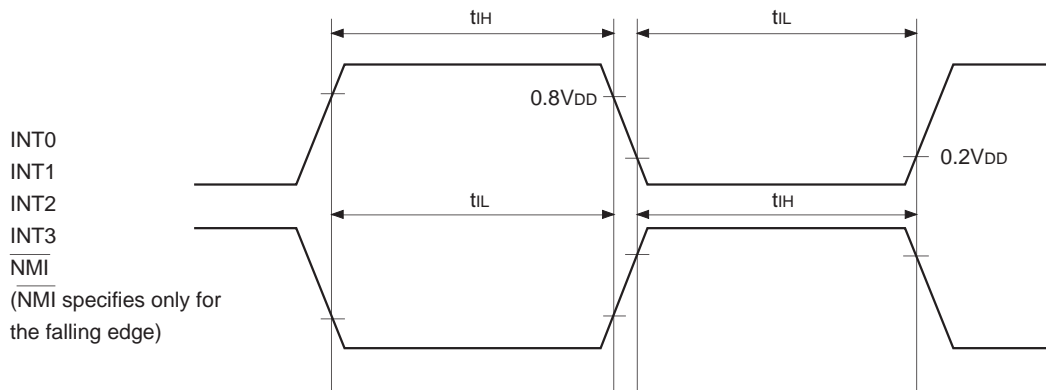
- \*1 VZT: Value at which the digital conversion value changes from 00H to 01H and vice versa.
- \*2 VFT: Value at which the digital conversion value changes from FEH to FFH and vice versa.
- \*3 fADC indicates the below values due to the bit6 (CKS) of A/D control register (address: 00F9H) and the Bit7 (PCK1) and Bit6 (PCK0) of clock control register (address: 00FEH)

PCK1, 0	CKS	
	0 (φ/2 selection)	1 (φ selection)
00 (φ = fEX/2)	fADC = fc/2	fADC = fc
01 (φ = fEX/4)	fADC = fc/4	fADC = fc/2
11 (φ = fEX/16)	fADC = fc/16	fADC = fc/8

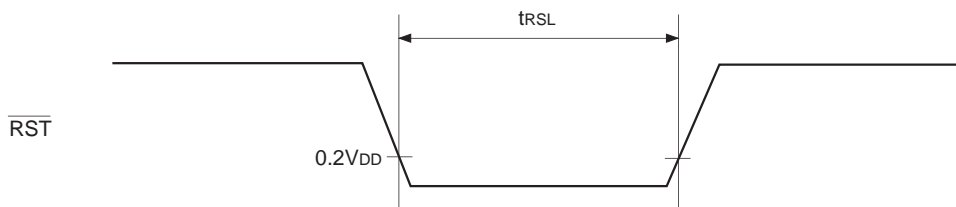
**(4) Interruption, reset input** (Ta = -20 to +75°C, V<sub>DD</sub> = 4.5 to 5.5V, V<sub>SS</sub> = 0V)

Item	Symbol	Pin	Condition	Min.	Max.	Unit
External interruption high and low level widths	t <sub>IH</sub> t <sub>IL</sub>	INT0 INT1 INT2 INT3 NMI		1		μs
Reset input low level width	t <sub>RSL</sub>	$\overline{\text{RST}}$		32/fc		μs

**Fig 6. Interruption input timing**

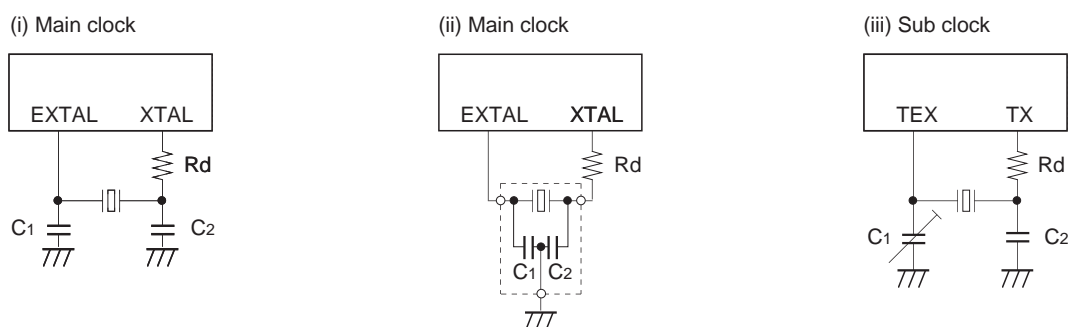


**Fig. 7.  $\overline{\text{RST}}$  input timing**



Appendix

Fig. 8. Recommended oscillation circuit



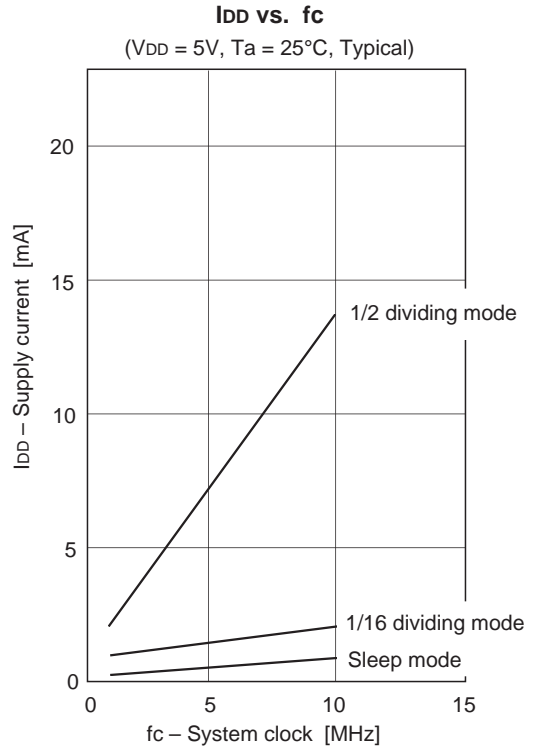
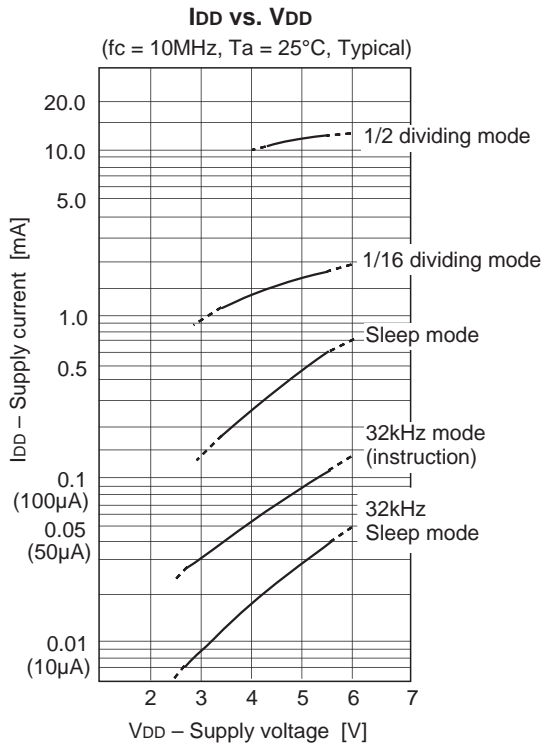
Manufacturer	Model	fc (MHz)	C1 (pF)	C2 (pF)	Rd ( $\Omega$ )	Circuit example
MURATA MFG CO., LTD.	CSA4.19MG	4.19	30	30	0	(i)
	CSA8.00MTZ	8.00				
	CSA10.0MTZ	10.00				
	CST4.19MGW*	4.19				(ii)
	CST8.00MTW*	8.00				
	CST10.0MTW*	10.00				
RIVER ELETEC CORPORATION	HC-49/U03	4.19	12	12	0	(i)
		8.00				
		10.00				
KINSEKI LTD.	HC-49/U (-S)	4.19	27	27	0	
		8.00				
		10.00	20	20		
	P3	32.768kHz	50	22	1M	(iii)

Those marked with an asterisk (\*) signify types with built-in ground capacitance (C1, C2).

Mask Option Table

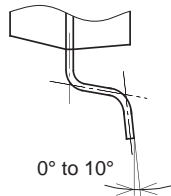
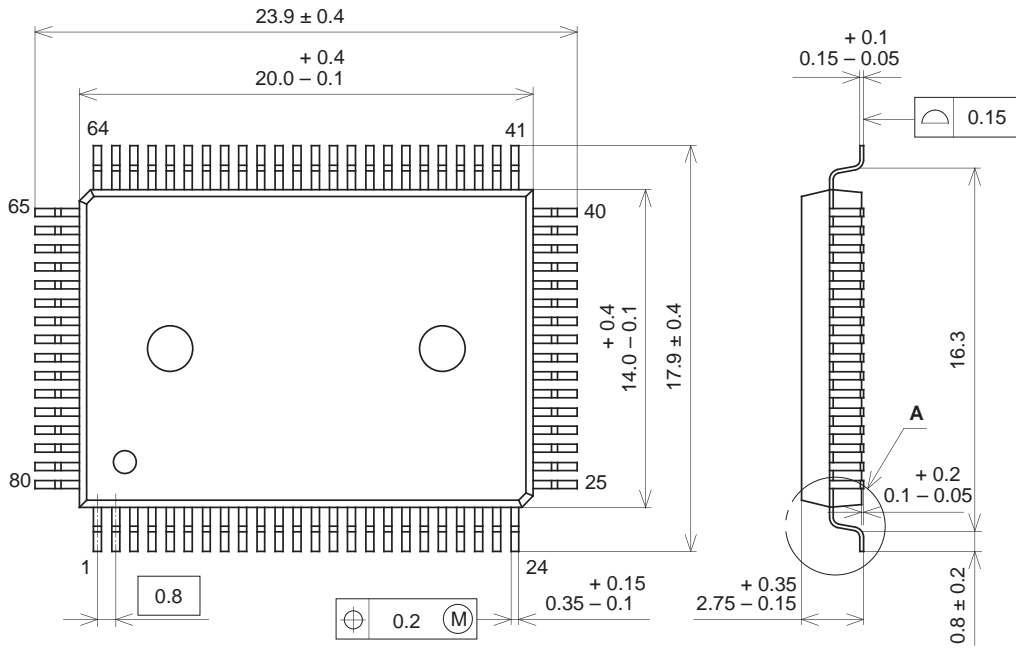
Item	Content	
Reset pin pull-up resistor	Non-existent	Existent
High voltage tolerance pull-down resistor	Non-existent	Existent (selected every pin)

Characteristics Curves



Package Outline Unit : mm

80PIN QFP (PLASTIC)



DETAIL A

PACKAGE STRUCTURE

SONY CODE	QFP-80P-L01
EIAJ CODE	QFP080-P-1420
JEDEC CODE	_____

PACKAGE MATERIAL	EPOXY RESIN
LEAD TREATMENT	SOLDER PLATING
LEAD MATERIAL	42/COPPER ALLOY
PACKAGE MASS	1.6g