PRELIMINARY DATA SHEET



MOS INTEGRATED CIRCUIT $\mu PD4992$

8-Bit Parallel I/O Calendar Clock

The μ PD4992 is a CMOS integrated circuit which outputs 8-bit parallel time and calendar data in a system in which a microprocessor is employed. The μ PD4992 operates at 32.768 kHz and provides year, month, day of month, day of week, hour, minute, and second data to a system. The μ PD4992 internally contains a voltage regulator so that low power consumption operation and high accuracy are realized even if the supply voltage varies. The μ PD4992 uses the 8-bit bus to facilitate interfacing with a microprocessor.

FEATURES:

- Internal counter for time (hour, minute, second), and calendar (leap year, year, month, day of month, day of week)
- Super low power consumption (IDD = 2 μ A MAX. at VDD = 2.4 V)
- Automatic determination of leap year, manual setting possible
- 12 hour/24 hour mode selectable
- · 8-bit parallel input/output in BCD data format
- 12 kinds of interval timer output (can be used as watchdog timer)
- · Internal voltage detection circuit for automatic determination of battery run-down
- High accuracy

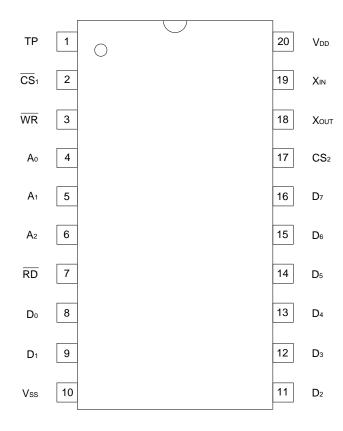
ORDERING INFORMATION:

Order Code	Package
μPD4992CX	20-pin plastic DIP (300 mil)
μPD4992GS	20-pin plastic SOP (300 mil)
μPD4992GS-T1, T2	20-pin plastic SOP (300 mil) Provided on adhesive tape
μPD4992GS-E2	20-pin plastic SOP (300 mil) Provided on embossed carrier tape

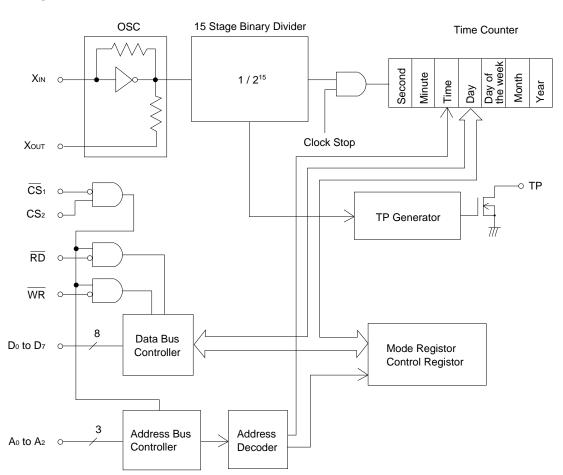
The information in this document is subject to change without notice.



PIN CONFIGURATION



BLOCK DIAGRAM





ABSOLUTE MAXIMUM RATINGS (Vss = 0 V)

Item	Symbol	Ratings	Unit
Supply voltage	V _{DD}	-0.3 to 7.0	V
Input voltage range	Vin	-0.3 to V _{DD} + 0.3	V
Output pin withstand voltage	Vоит	7.0	V
Low level output current (N ch Open Drain)	Іоит	30	mA
Operating temperature range	Topt	-40 to +85	°C
Storage temperature range	T _{stg}	-65 to +125	°C

ELECTRICAL CHARACTERISTICS

(Vss = 0 V, f = 32.768 kHz, Cg = Cp = 20 pF, Ci = 20k ohms, T_a = -40 to +85 °C)

Item	Symbol	Condition	MIN.	TYP.*	MAX.	Unit
Operating voltage range	V _{DD}		2.4		5.5	V
High level input voltage	ViH		0.7 Vdd		V _{DD}	V
Low level input voltage	VIL		Vss		0.3 V _{DD}	V
Supply current	IDD	VDD = 5.5 V, VIN = Vss		2	6	μΑ
Supply current	IDD	VDD = 2.4 V, VIN = Vss		0.6	2	μΑ
Input leakage current	Iμ	VDD = 5.5 V, VIN = VDD or Vss		±1 × 10 ⁻⁵	±1.0	μΑ
High level output voltage	Vон	Iон = −1.0 mA	2.4	4.3		V
Low level output voltage	V _{OL1}	IoL = 2.0 mA		0.1	0.4	V
Low level output voltage	V _{OL2}	IoL = 1.0 mA (N ch Open Drain)			0.4	V
High level leakage current	Ісон	TPout = VDD (N ch Open Drain)		4 × 10 ⁻⁵	1.0	μΑ

*: Ta = +25 °C

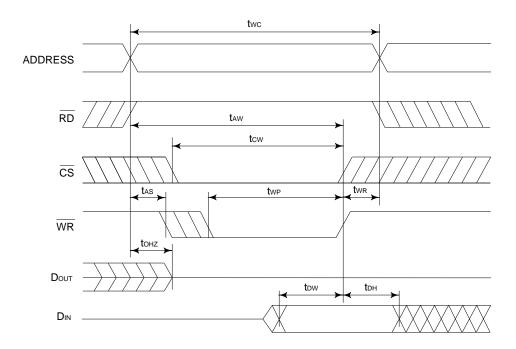
SWITCHING CHARACTERISTICS

WRITE CYCLE (unless otherwise specified V_{DD} = 5 V \pm 10 %, T_a = -40 to +85 °C)

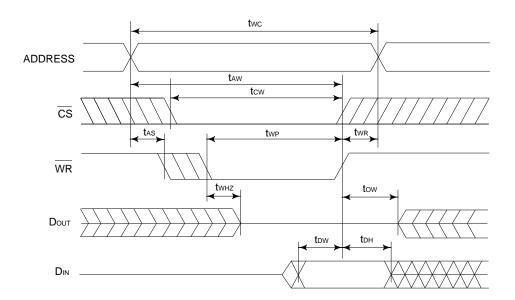
Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Cycle time	twc		150			
CS-WR reset time	tcw		120			
Address - WR reset time	taw		120			
Address - WR set up time	tas		0			
Write pulse width	twp		90			ns
Address hold time	twr		20			
Input data set up time	tow		50			
Input data hold time	tон		0			
WR - output floating time	twнz				50	



WRITE CYCLE TIMING WAVEFORMS 1



WRITE CYCLE TIMING WAVEFORMS 2 (RD = VIL)

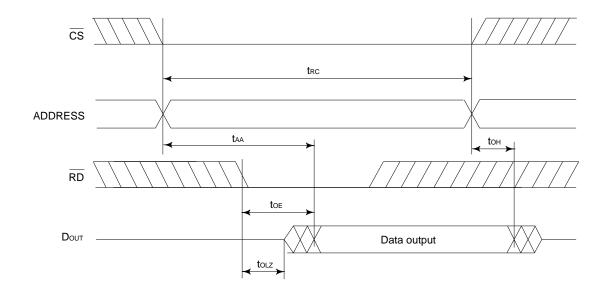




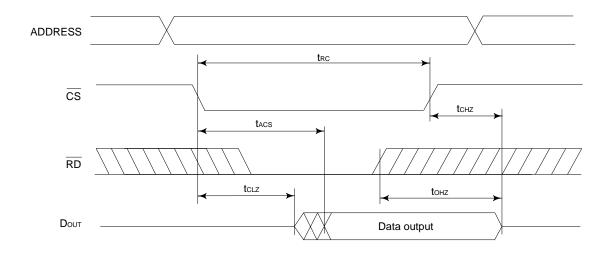
READ CYCLE (unless otherwise specified V_{DD} = 5 V \pm 10 %, T_a = -40 to +85 °C)

Item	Symbol	Condition	MIN.	TYP.	MAX.	Unit
Cycle time	t RC		150			
Address access time	taa				150	
CS - access time	tacs				150	
RD - output delay time	toe				75	
RD - output delay time	tolz		5			ns
RD - output delay time	tонz				50	
Output hold time	tон		15			
CS - output set time	tclz		10			
CS - output floating time	t cHZ		5			

READ CYCLE TIMING WAVEFORMS 1



READ CYCLE TIMING WAVEFORMS 2

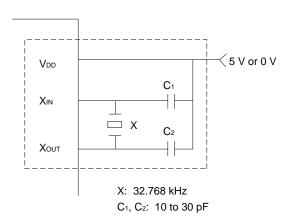




PIN FUNCTION

Pin symbol	Pin name	Pin number	Function
CS ₁	Chip select input	2	Internal register can be accessed when $\overline{CS_1} = L$
CS ₂	Chip select input	17	and CS ₂ = H
WR	Write signal input	3	Writes the contents of data bus to the register selected by address input at the rising edge
RD	Read signal input	7	Outputs the contents of the register selected by address input to the data bus at the rising edge
D ₀ to D ₇	Data input/output	8, 9, 11 to 16	Data input/output bus
A ₀ to A ₂	Address input	4 to 6	Address input to select internal register
TP	Timing pulse output	1	Interval signal and timing pulse output (N ch open drain output)
XIN	Crystal resonator connection pin	19	Crystal resonator and capacitor are connected to
Хоит	Crystal resonator connection pin	18	these pins.
V _{DD}	Power supply pin	20	2.4 V to 5.5 V
Vss	GND	10	Connect to GND

External components (crystal resonator, capacitors) must be located as close as the IC, and separated as far as from high speed clock wiring.





REGISTER – ADDRESS CORRESPONDENCE TABLE

ADI	ADDRESS		Register contents						
HEX	BIN	b7	b6	b5	b4	b3	b2	b1	b0
0H	000B		10s sec	ond digit			1s seco	ond digit	
1H	001B		10s minute digit				1s minu	ute digit	
2H	010B	12/24H	ĀM/PM	10s ho	ur digit	1s hour digit			
3H	011B	Leap yea	ar control	ontrol Leap year counter Day of week digit					
4H	100B		10s da	y digit			1s day of r	month digit	
5H	101B		10s month digit				1s mor	nth digit	
6H	110B	10s year digit				1s yea	ar digit		
7H	111B		Mode register				Control	register	

 \overline{AM}/PM flag (R/W): In 12 hour mode, 0 indicates AM, and 1 indicates PM.

Always 0 in 24 hour mode.

 $12/\overline{24}H$ flag (R/W) : 0 indicates 24 hour mode, and 1 indicates 12 hour mode.

LEAP YEAR CONTROL REGISTER (R/W)

b7	b6	Mode				
0	0	Leap year effective	Writing to leap year counter disabled			
0	1	Leap year effective	Writing to leap year counter enabled			
1	0	Leap year invalid	Writing to leap year counter disabled			
1	1	Leap year invalid	Writing to leap year counter enabled			

When the leap year control register is "0X" and the leap year counter is "00" → Leap year (Feb. has 29 days).

• To disable leap year mode, write "10" to the leap year control register (Feb. 28 is followed by Mar. 1).



MODE REGISTER (R/W)

HEX	BIN	Mode	
0H	0000B	Outputs TP2048 Hz	
1H	0001B	Outputs TP1024 Hz	
2H	0010B	Outputs TP256 Hz	
3Н	0011B	Outputs TP64 Hz	
4H	0100B	Outputs INT1/2048s	
5H	0101B	Outputs INT1/1024s	
6H	0110B	Outputs INT1/256s	
7H	0111B	Outputs INT1/64s	
8H	1000B	Outputs INT1s	
9H	1001B	Outputs INT10s	
АН	1010B	Outputs INT60s	
ВН	1011B	Outputs BUSY signal	
СН	1100B	Test mode 1	
DH	1101B	Test mode 2	
EH	1110B	Test mode 3	
FH	1111B	Test mode 4	

CONTROL REGISTER

Access mode	b3	b2	b1	b0
		CLK adjust	Reset	CLK stop
When writing	0	0: NOP	0: NOP	0: CLK start
		1: CLK adjust	1: Reset	1: CLK stop
	1	TP enable*1	INT reset	INT stop
		0: TP = ENABLE	0: NOP	0: INT start
		1: TP = DISABLE	1: Reset	1: INT stop
	*	TP flag	OSC flag*2	BUSY flag*3
When reading	(Don't care)	0: TP = Z	0: No oscillation	0: OFF
	(Don't care)	1: TP = L	1: Oscillation	1: ON

- *1 : When TP enable is 1 (TP = DISABLE), the TP pin becomes high impedance (actually a high level because a pull up resistor is connected to the TP pin).
 - But TP flag is not DISABLE in this case.
- *2 : If the OSC flag becomes 0 by oscillation stop, the OSC flag remains to be 0 when oscillation is resumed.

 To set OSC flag to 1 again, execute CLK reset (if the OSC flag still remains to be 0, oscillation has not been started again).
 - Upon initial power application of the μ PD4992, 0 is set to the OSC flag.
- *3 : The BUSY flag is "1" when the time counter of the μ PD4992 is operating (when read is disabled).



Table 1 Time Counter Data

TIME COUNTER	DATA	TIME COUNTER	DATA
1s second digit	0-9	1s day of month digit	0-9
10s seocnd digit	0-5	10s day of month digit	0-3
1s minute digit	0-9	1s month digit	0-9
10s minute digit	0-5	10s month digit	0-1
1s hour digit	0-9	1s year digit	0-9
10s hour digit	0-5	10s year digit	0-9
Day of week digit	0-6		

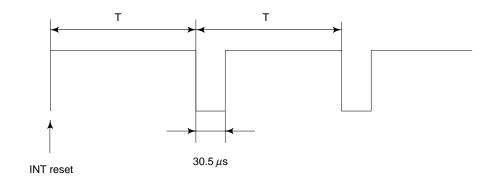
Table 2 Hour Counter Data

Hour	24 hour mode	12 hour mode	Hour	24 hour mode	12 hour mode
AM 1 o'clock	01H	81H	PM 1 o'clock	13H	C1H
AM 2 o'clock	02H	82H	PM 2 o'clock	14H	C2H
AM 3 o'clock	03H	83H	PM 3 o'clock	15H	СЗН
AM 4 o'clock	04H	84H	PM 4 o'clock	16H	C4H
AM 5 o'clock	05H	85H	PM 5 o'clock	17H	C5H
AM 6 o'clock	06H	86H	PM 6 o'clock	18H	C6H
AM 7 o'clock	07H	87H	PM 7 o'clock	19H	C7H
AM 8 o'clock	08H	88H	PM 8 o'clock	20H	C8H
AM 9 o'clock	09H	89H	PM 9 o'clock	21H	C9H
AM 10 o'clock	10H	90H	PM 10 o'clock	22H	D0H
AM 11 o'clock	11H	91H	PM 11 o'clock	23H	D1H
PM 12 o'clock	12H	D2H	AM 12 o'clock	00H	92H

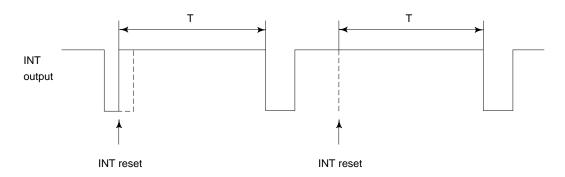


TYPICAL INT CONTROL EXAMPLES (mode register: INT output mode)

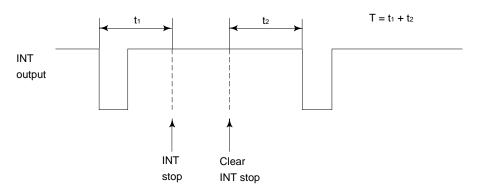
(1) Use of INT reset (example 1)



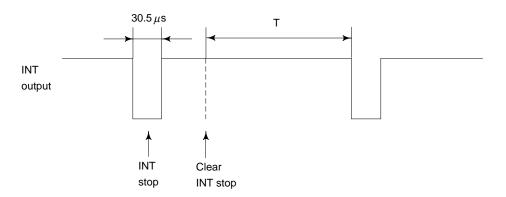
(2) Use of INT reset (example 2)



(3) Use of INT stop (example 1)

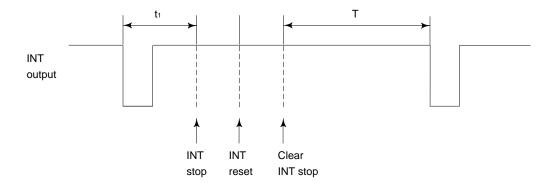


(4) Use of INT stop (example 2)

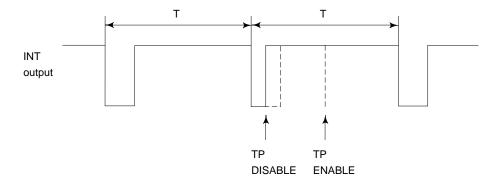




(5) Use of INT reset, INT stop

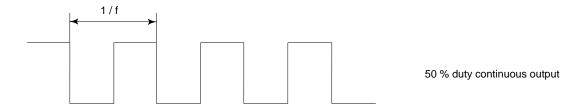


(6) Use of TP enable

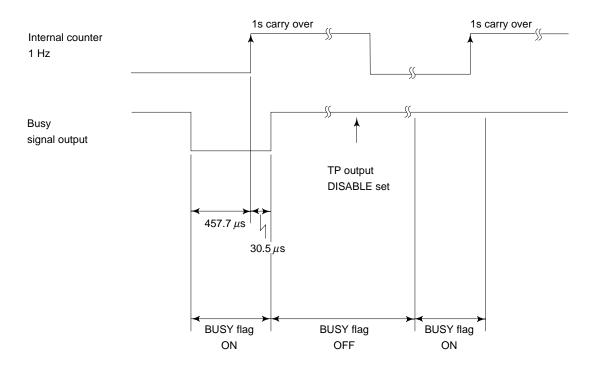




TP OUTPUT (mode register: TP output mode)



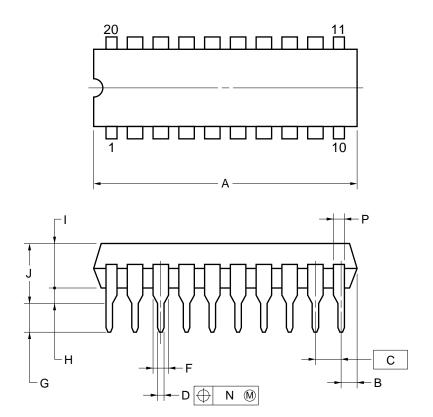
BUSY SIGNAL

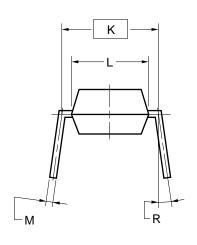


The time and calendar data read out when BUSY signal is being output may not be correct. This is because, the internal time counter is operating. Therefore, accessing must be disabled during this period or the data must be read out twice and checked by the software. (Reading data during BUSY period has not effect on the contents of the internal counter.)

OUTLINE DRAWING

20PIN PLASTIC DIP (300 mil)





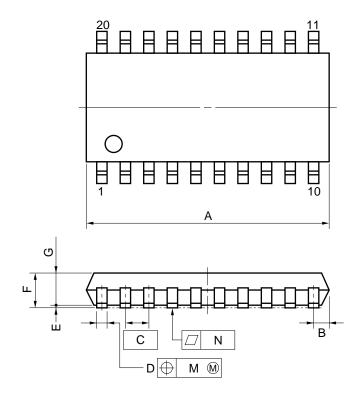
NOTES

- 1) Each lead centerline is located within 0.25 mm (0.01 inch) of its true position (T.P.) at maximum material condition.
- 2) Item "K" to center of leads when formed parallel.

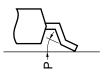
ITEM	MILLIMETERS	INCHES
Α	25.40 MAX.	1.000 MAX.
В	1.27 MAX.	0.050 MAX.
С	2.54 (T.P.)	0.100 (T.P.)
D	0.50±0.10	$0.020^{+0.004}_{-0.005}$
F	1.1 MIN.	0.043 MIN.
G	3.5±0.3	0.138±0.012
Н	0.51 MIN.	0.020 MIN.
I	4.31 MAX.	0.170 MAX.
J	5.08 MAX.	0.200 MAX.
K	7.62 (T.P.)	0.300 (T.P.)
L	6.4	0.252
М	$0.25^{+0.10}_{-0.05}$	$0.010^{+0.004}_{-0.003}$
N	0.25	0.01
Р	0.9 MIN.	0.035 MIN.
R	0~15°	0~15°

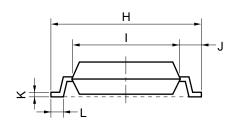
P20C-100-300A,C-1

20 PIN PLASTIC SOP (300 mil)



detail of lead end





NOTE

Each lead centerline is located within 0.12 mm (0.005 inch) of its true position (T.P.) at maximum material condition.

ITEM	MILLIMETERS	INCHES	
Α	13.00 MAX.	0.512 MAX.	
В	0.78 MAX.	0.031 MAX.	
С	1.27 (T.P.)	0.050 (T.P.)	
D	$0.40^{+0.10}_{-0.05}$	0.016+0.004	
Е	0.1±0.1	0.004±0.004	
F	1.8 MAX.	0.071 MAX.	
G	1.55	0.061	
Н	7.7±0.3	0.303±0.012	
- 1	5.6	0.220	
J	1.1	0.043	
K	$0.20^{+0.10}_{-0.05}$	$0.008^{+0.004}_{-0.002}$	
L	0.6±0.2	$0.024^{+0.008}_{-0.009}$	
М	0.12	0.005	
N	0.10	0.004	
Р	3°+7° -3°	3°+7° -3°	

P20GM-50-300B, C-4



RECOMMENDED SOLDERING CONDITIONS

The following conditions (see table below) must be met when soldering this product.

Please consult with our sales offices in case other soldering process is used, or in case soldering is done under different conditions.

TYPES OF SURFACE MOUNT DEVICE

μPD4992GS

Soldering process	Soldering condition	Symbol
Infrared ray reflow	Peak package's surface temperature: 235 °C or below, Reflow time: 30 seconds or below (210 °C or higher), Number of reflow process: 2, Exposure limit*: None	IR35-00-2
VPS	Peak package's surface temperature: 215 °C or below, Reflow time: 40 seconds or below (200 °C or higher), Number of reflow process: 2, Exposure limit*: None	VP15-00-2
Wave soldering	Solder temperature: 260 °C or below, Flow time: 10 seconds or below, Number of flow process: 1, Exposure limit*: None	WS60-00-1
Partial heating method	Terminal temperature: 300 °C or below, Flow time: 10 seconds or below, Exposure limit*: None	

^{*:} Exposure limit before soldering after dry-pack package is opened. Storage conditions: 25 °C and relative humidity at 65 % or less.

Note: Do not apply more than a single process at once, except for "Partial heating method".

TYPE OF THROUGH HOLE MOUNT DEVICE

 μ PD4992CX

Soldering process	Soldering conditions
Wave soldering	Solder temperature: 260 °C or below, Flow time: 10 seconds or below.

NEC μ PD4992

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NEC devices are classified into the following three quality grades:

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Standard: Computers, office equipment, communications equipment, test and measurement equipment, audio and visual equipment, home electronic appliances, machine tools, personal electronic equipment and industrial robots

Special: Transportation equipment (automobiles, trains, ships, etc.), traffic control systems, anti-disaster systems, anti-crime systems, safety equipment and medical equipment (not specifically designed for life support)

Specific: Aircrafts, aerospace equipment, submersible repeaters, nuclear reactor control systems, life support systems or medical equipment for life support, etc.

The quality grade of NEC devices is "Standard" unless otherwise specified in NEC's Data Sheets or Data Books. If customers intend to use NEC devices for applications other than those specified for Standard quality grade, they should contact an NEC sales representative in advance.

Anti-radioactive design is not implemented in this product.

M4 96.5