



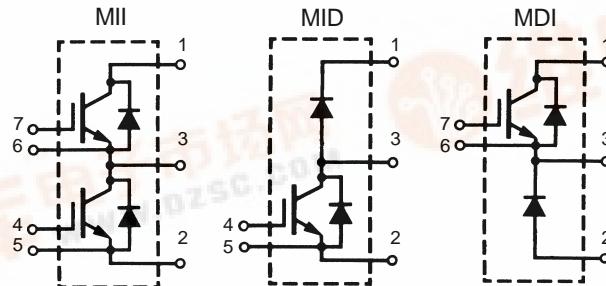
MII 75-12 A3

MID 75-12 A3  
MDI 75-12 A3

## IGBT Modules

Short Circuit SOA Capability  
Square RBSOA

$I_{C25}$  = 90 A  
 $V_{CES}$  = 1200 V  
 $V_{CE(sat)}$  typ. = 2.2 V



E 72873

Symbol	Conditions	Maximum Ratings		
$V_{CES}$	$T_J = 25^\circ\text{C}$ to $150^\circ\text{C}$	1200	V	
$V_{GCR}$	$T_J = 25^\circ\text{C}$ to $150^\circ\text{C}$ ; $R_{GE} = 20 \text{ k}\Omega$	1200	V	
$V_{GES}$	Continuous	$\pm 20$	V	
$V_{GEM}$	Transient	$\pm 30$	V	
$I_{C25}$	$T_C = 25^\circ\text{C}$	90	A	
$I_{C80}$	$T_C = 80^\circ\text{C}$	60	A	
$I_{CM}$	$T_C = 80^\circ\text{C}$ , $t_p = 1 \text{ ms}$	120	A	
$t_{SC}$	$V_{GE} = \pm 15 \text{ V}$ , $V_{CE} = V_{CES}$ , $T_J = 125^\circ\text{C}$	10	$\mu\text{s}$	
(SCSOA)	$R_G = 22 \Omega$ , non repetitive			
RBSOA	$V_{GE} = \pm 15 \text{ V}$ , $T_J = 125^\circ\text{C}$ , $R_G = 22 \Omega$ Clamped inductive load, $L = 100 \mu\text{H}$	$I_{CM} = 100$ $V_{CEK} \leq V_{CES}$	A	
$P_{tot}$	$T_C = 25^\circ\text{C}$	370	W	
$T_J$		150	$^\circ\text{C}$	
$T_{stg}$		-40 ... +150	$^\circ\text{C}$	
$V_{ISOL}$	50/60 Hz, RMS $I_{ISOL} \leq 1 \text{ mA}$	4000 4800	V~	
	$t = 1 \text{ min}$ $t = 1 \text{ s}$			
	Insulating material: $\text{Al}_2\text{O}_3$			
$M_d$	Mounting torque (module) (terminals)	2.25-2.75 20-25 2.5-3.7 22-33	Nm lb.in. Nm lb.in.	
$d_s$	Creepage distance on surface	12.7	mm	
$d_A$	Strike distance through air	9.6	mm	
$a$	Max. allowable acceleration	50	$\text{m/s}^2$	
Weight	Typical	130 4.6	g oz.	

Data according to a single IGBT/FRED unless otherwise stated.

### Features

- NPT IGBT technology
- low saturation voltage
- low switching losses
- switching frequency up to 30 kHz
- square RBSOA, no latch up
- high short circuit capability
- positive temperature coefficient for easy paralleling
- MOS input, voltage controlled
- ultra fast free wheeling diodes
- package with DCB ceramic base plate
- isolation voltage 4800 V
- UL registered E72873

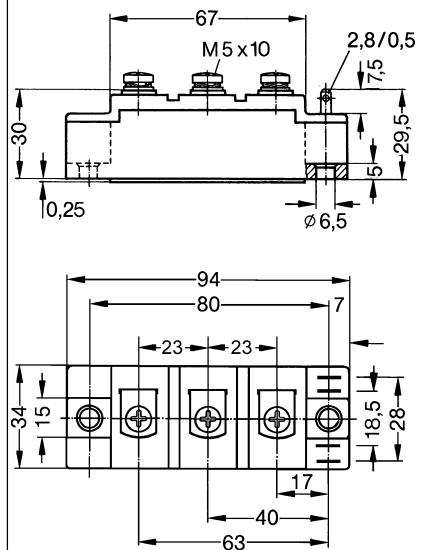
### Advantages

- space and weight savings
- reduced protection circuits

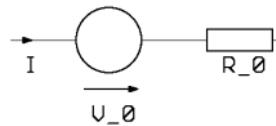
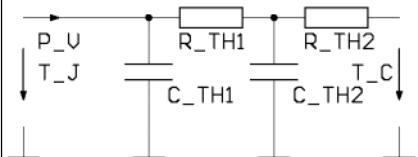
### Typical Applications

- AC and DC motor control
- AC servo and robot drives
- power supplies
- welding inverters

Symbol	Conditions	Characteristic Values ( $T_J = 25^\circ\text{C}$ , unless otherwise specified)		
		min.	typ.	max.
$V_{(\text{BR})\text{CES}}$	$V_{\text{GE}} = 0 \text{ V}$	1200		V
$V_{\text{GE}(\text{th})}$	$I_C = 2 \text{ mA}, V_{\text{CE}} = V_{\text{GE}}$	4.5		6.5 V
$I_{\text{CES}}$	$V_{\text{CE}} = V_{\text{CES}}$ $T_J = 25^\circ\text{C}$ $T_J = 125^\circ\text{C}$		6	4 mA mA
$I_{\text{GES}}$	$V_{\text{CE}} = 0 \text{ V}, V_{\text{GE}} = \pm 20 \text{ V}$			$\pm 200 \text{ nA}$
$V_{\text{CE}(\text{sat})}$	$I_C = 50 \text{ A}, V_{\text{GE}} = 15 \text{ V}$	2.2	2.7	V
$C_{\text{ies}}$ $C_{\text{oes}}$ $C_{\text{res}}$	$V_{\text{CE}} = 25 \text{ V}, V_{\text{GE}} = 0 \text{ V}, f = 1 \text{ MHz}$	3.3 0.5 0.22		nF nF nF
$t_{\text{d}(\text{on})}$ $t_r$ $t_{\text{d}(\text{off})}$ $t_f$ $E_{\text{on}}$ $E_{\text{off}}$	$\text{Inductive load, } T_J = 125^\circ\text{C}$ $I_C = 50 \text{ A}, V_{\text{GE}} = \pm 15 \text{ V}$ $V_{\text{CE}} = 600 \text{ V}, R_G = 22 \Omega$	100 70 500 70 7.6 5.6		ns ns ns ns mJ mJ
$R_{\text{thJC}}$				0.33 K/W
$R_{\text{thJS}}$	with heatsink compound	0.66		K/W

**Dimensions in mm (1 mm = 0.0394")**

**Reverse Diode (FRED)**

		Characteristic Values ( $T_J = 25^\circ\text{C}$ , unless otherwise specified)		
		min.	typ.	max.
$V_F$	$I_F = 50 \text{ A}, V_{\text{GE}} = 0 \text{ V},$ $I_F = 50 \text{ A}, V_{\text{GE}} = 0 \text{ V}, T_J = 125^\circ\text{C}$		2.2 1.8	2.5 V 1.9 V
$I_F$	$T_C = 25^\circ\text{C}$ $T_C = 80^\circ\text{C}$			100 A 60 A
$I_{RM}$	$I_F = 50 \text{ A}, V_{\text{GE}} = 0 \text{ V}, -di_F/dt = 400 \text{ A}/\mu\text{s}$	40		A
$t_{rr}$	$T_J = 125^\circ\text{C}, V_R = 600 \text{ V}$	200		ns
$R_{\text{thJC}}$			0.66	K/W
$R_{\text{thJS}}$	with heatsink compound	1.32		K/W

**Equivalent Circuits for Simulation**
**Conduction**

**IGBT (typ. at  $V_{\text{GE}} = 15 \text{ V}; T_J = 125^\circ\text{C}$ )**  
 $V_0 = 1.5 \text{ V}; R_0 = 20.1 \text{ m}\Omega$ 
**Free Wheeling Diode (typ. at  $T_J = 125^\circ\text{C}$ )**  
 $V_0 = 1.3 \text{ V}; R_0 = 10.8 \text{ m}\Omega$ 
**Thermal Response**

**IGBT (typ.)**

$$C_{th1} = 0.13 \text{ J/K}; R_{th1} = 0.323 \text{ K/W}$$

$$C_{th2} = 0.32 \text{ J/K}; R_{th2} = 0.008 \text{ K/W}$$

**Free Wheeling Diode (typ.)**

$$C_{th1} = 0.10 \text{ J/K}; R_{th1} = 0.645 \text{ K/W}$$

$$C_{th2} = 0.18 \text{ J/K}; R_{th2} = 0.013 \text{ K/W}$$

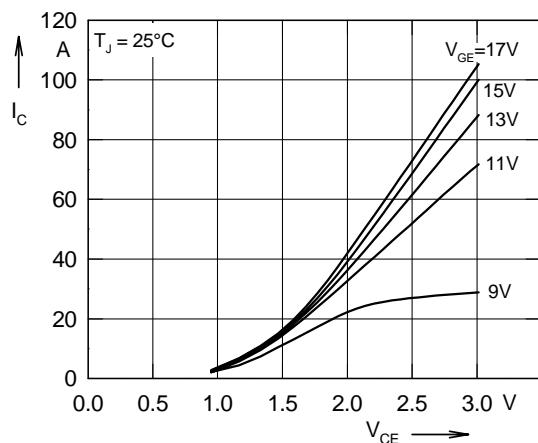


Fig. 1 Typ. output characteristics

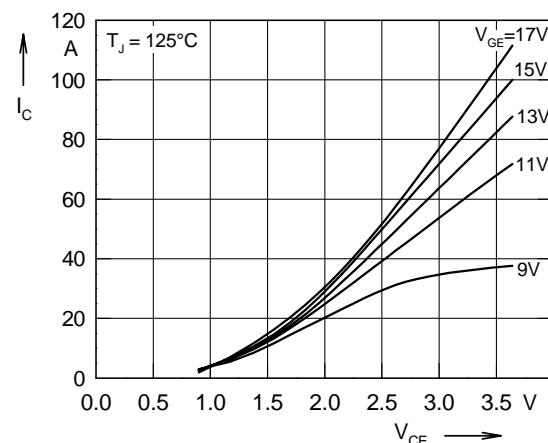


Fig. 2 Typ. output characteristics

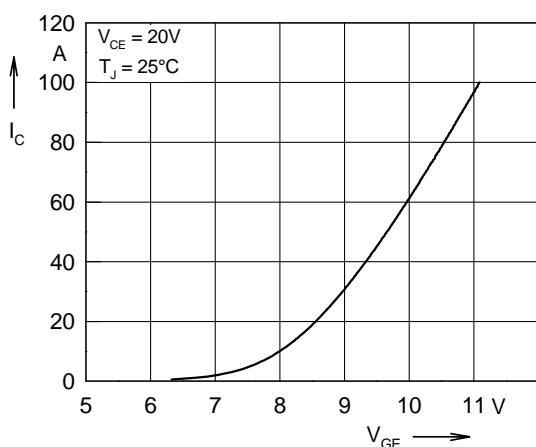


Fig. 3 Typ. transfer characteristics

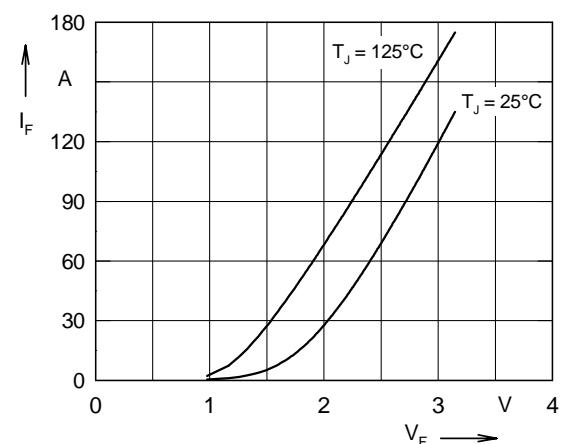


Fig. 4 Typ. forward characteristics of free wheeling diode

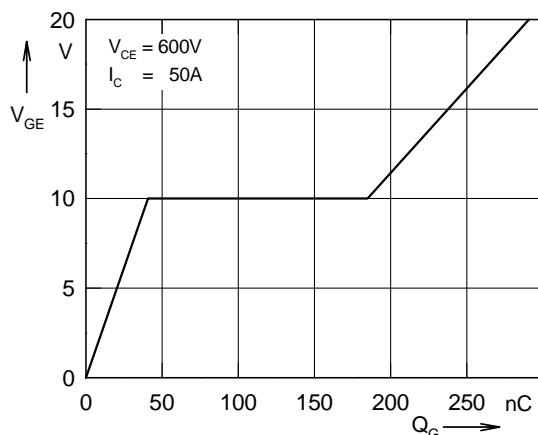


Fig. 5 Typ. turn on gate charge

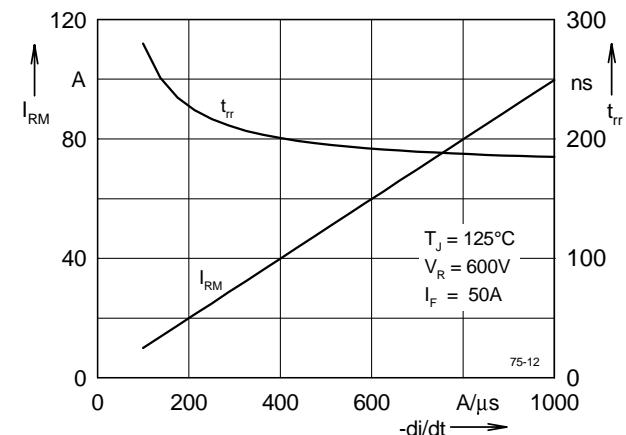


Fig. 6 Typ. turn off characteristics of free wheeling diode

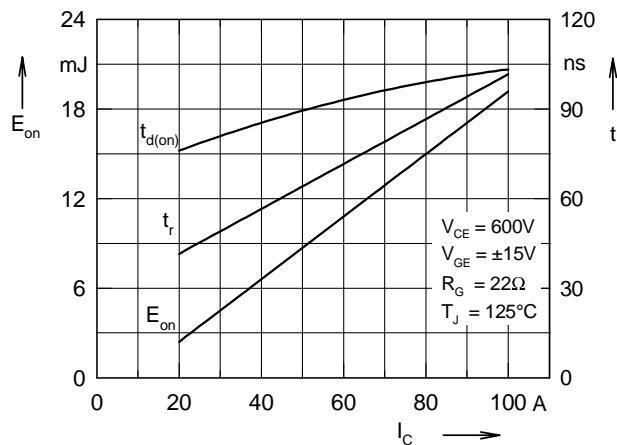


Fig. 7 Typ. turn on energy and switching times versus collector current

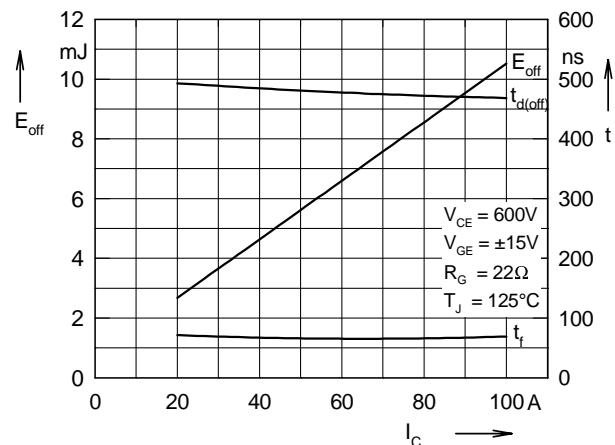


Fig. 8 Typ. turn off energy and switching times versus collector current

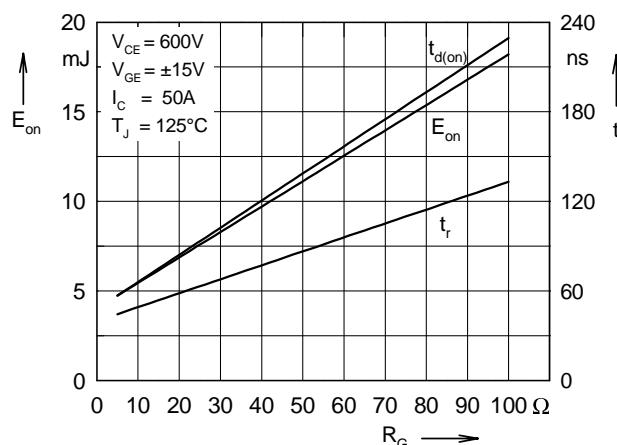


Fig. 9 Typ. turn on energy and switching times versus gate resistor

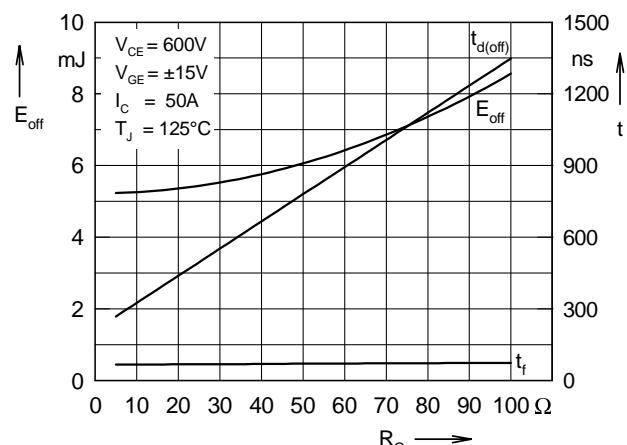


Fig. 10 Typ. turn off energy and switching times versus gate resistor

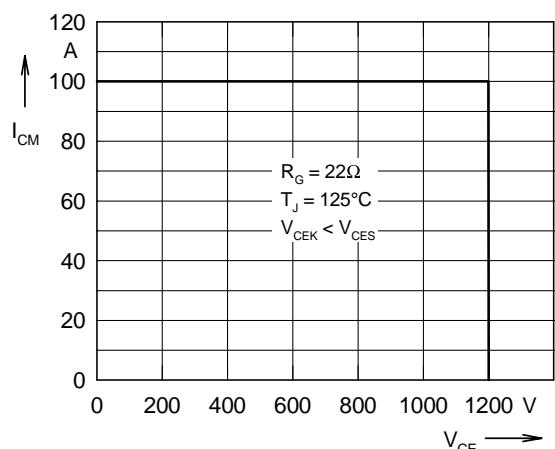


Fig. 11 Reverse biased safe operating area RBSOA

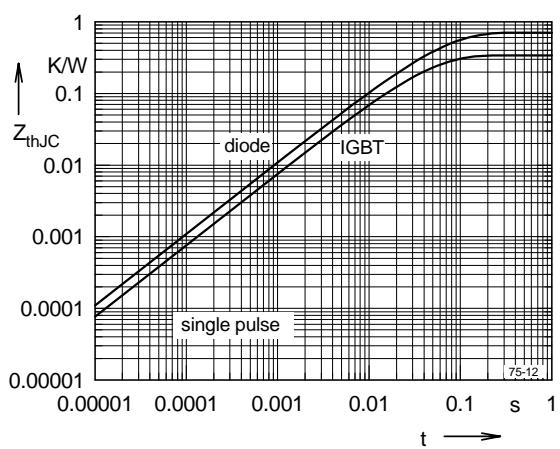


Fig. 12 Typ. transient thermal impedance