

March 1989 =AIRCHIL Revised August 1999 SEMICONDUCTOR **DM93L28 Dual 8-Bit Shift Register General Description Features** The DM93L28 is a high speed serial storage element providing 16 bits of storage in the form of two 8-bit registers. register The multifunctional capability of this device is provided by Gated clock input circuitry several features: 1) additional gating is provided at the input to both shift registers so that the input is easily multibit of each register plexed between two sources; 2) the clock of each register may be provided separately or together; 3) both the true and complementary outputs are provided from each 8-bit register, and both registers may be master cleared from a common input. **Ordering Code:**

- 2-input multiplexer provided at data input of each
- Both true and complementary outputs provided from last

DM93L28 Dual 8-Bit Shift Register

Asynchronous master reset common to both registers WWW.DZ

	Package Number	
M93L28N	N16E	16-Lead Plastic Dual-In-Line Package (PDIP), JEDEC MS-001, 0.300 Wide
Logic Sym	bol	Connection Diagram
10 9 7		$\frac{1}{07} - 14$ $\frac{1}{07} - 15$ $\frac{1}{07} - 10$
	P NR	
V _{CC} = Pin 16	GND = Pin 8	
	GND = Pin 8	
	GND = Pin 8	
	GND = Pin 8	曲子市村
	GND = Pin 8 ptions Pin	Names Description
	GND = Pin 8 ptions S	Names Description
	GND = Pin 8 ptions S D0, D	Names Description Data Select Input Data Inputs
	GND = Pin 8 ptions S D0, D	Names Description Data Select Input Data Inputs Clock Pulse Input (Active HIGH)
V _{cc} = Pin 16 Pin Descri	GND = Pin 8 ptions 0, C CP MR	Names Description Data Select Input Data Inputs Clock Pulse Input (Active HIGH) Common (Pin 9)
	GND = Pin 8 ptions	Names Description Data Select Input D1 Data Inputs Clock Pulse Input (Active HIGH) Common (Pin 9) Separate (Pins 7 and 10)



Functional Description

The two 8-bit shift registers have a common clock input (pin 9) and separate clock inputs (pins 10 and 7). The clocking of each register is controlled by the OR function of the separate and the common clock input. Each register is composed of eight clocked RS master/slave flip-flops and a number of gates. The clock OR gate drives the eight clock inputs of the flip-flops in parallel. When the two clock inputs (the separate and the common) to the OR gate are LOW, the slave latches are steady, but data can enter the master latches via the R and S input. During the first LOW-to-HIGH transition of either, or both simultaneously, of the two clock inputs, the data inputs (R and S) are inhibited so that a later change in input data will not affect the master; then the now trapped information in the master is transferred to the slave. When the transfer is complete, both the master and the slave are steady as long as either or both clock inputs remain HIGH. During the HIGH-to-LOW transition of the last remaining HIGH clock input, the transfer path from master to slave is inhibited first, leaving the slave steady in its present state. The data inputs (R and S) are enabled so that new data can enter the master. Either of the clock inputs can be used as clock inhibit inputs by applying a logic HIGH signal. Each 8-bit shift register has a 2-input multiplexer in front of the serial data input. The two data inputs D0 and D1 are controlled by the data select input (S) following the Boolean expression:

Serial data in: $S_D = SD0 + SD1$

An asynchronous master reset is provided which, when activated by a LOW logic level, will clear all 16 stages independently of any other input signal.

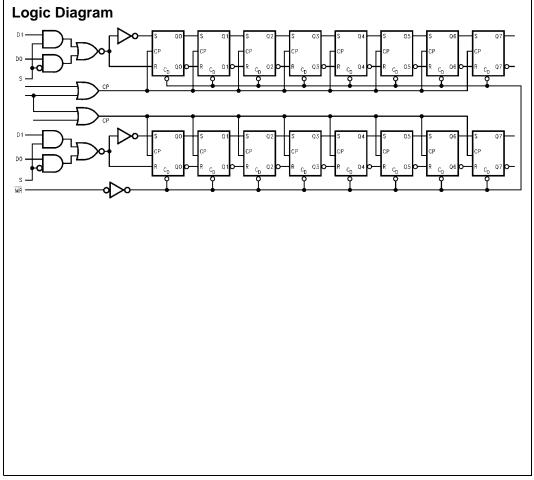
Shift Select Table

	Inputs		Output
S	D0	D1	Q7 (t _{n+8})
L	L	Х	L
L	н	Х	н
н	Х	L	L
н	х	н	н

H = HIGH Voltage Level

L = LOW Voltage Level

n+8 = Indicates state after eight clock pulse



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Absolute Maximum Ratings(Note 1)

Supply Voltage	7V
Input Voltage	5.5V
Operating Free Air Temperature Range	$0^{\circ}C$ to $+70^{\circ}C$
Storage Temperature Range	$-65^{\circ}C$ to $+150^{\circ}C$

Note 1: The "Absolute Maximum Ratings" are those values beyond which the safety of the device cannot be guaranteed. The device should not be operated at these limits. The parametric values defined in the Electrical Characteristics tables are not guaranteed at the absolute maximum ratings. The "Recommended Operating Conditions" table will define the conditions for actual device operation.

Recommended Operating Conditions

Symb	ol Parame	eter	Min	Nom	Max	l	Units
V _{CC}	Supply Voltage		4.5	5	5.5		V
/ _{IH}	HIGH Level Input Voltag	HIGH Level Input Voltage					V
VIL	LOW Level Input Voltage				0.7		V
ОН	HIGH Level Output Curr	rent			-400		μΑ
OL	LOW Level Output Curr	ent			4.8		mA
Γ _Α	Free Air Operating Tem	perature	0		+7°		°C
s(H)	Setup Time HIGH or LC	W	30				ns
t _s (L)	D _n to CP		30				115
_h (H)	Hold Time HIGH or LOV	V	0				ns
t _h (L)	D _n to CP		0				115
t _w (H)	Clock Pulse Width		55				ns
t _w (L)	HIGH or LOW		55				115
t _w (L)	MR Pulse Width with CI	P HIGH	60				ns
t _w (L)	MR Pulse Width with CF	PLOW	70			_	ns
over recor	rical Characteristic mmended operating free air temperat Parameter	ure (unless otherwise	Conditions		Min	Max	
		-	noted)				
over recor	nmended operating free air temperat	-			Min	Max	Un
over recon Symbol	nmended operating free air temperat Parameter Input Clamp Voltage	ure (unless otherwise	Conditions		Min	Max -1.5	
over recon Symbol	nmended operating free air temperat Parameter	ure (unless otherwise $V_{CC} = Min, I_1 =$ $V_{CC} = Min, I_{OH}$	Conditions -10 mA = Max,		Min		V
over recon Symbol V _I V _{OH}	mmended operating free air temperat Parameter Input Clamp Voltage HIGH Level Output Voltage	$\begin{tabular}{ c c c c c } \hline & V_{CC} = Min, I_I = \\ \hline & V_{CC} = Min, I_{OH} \\ \hline & V_{IL} = Max, V_{IH} \end{tabular}$	Conditions -10 mA = Max, = Min				V
over recor Symbol V _I V _{OH}	nmended operating free air temperat Parameter Input Clamp Voltage	$\begin{tabular}{ c c c c c } \hline & V_{CC} = Min, \ I_{I} = \\ \hline & V_{CC} = Min, \ I_{OH} \\ \hline & V_{IL} = Max, \ V_{IH} \\ \hline & V_{CC} = Min, \ I_{OL} \\ \hline \end{tabular}$	Conditions -10 mA = Max, = Min = Max,				Uni V V
over recor Symbol V _I V _{OH} V _{OL}	Input Clamp Voltage HIGH Level Output Voltage LOW Level Output Voltage	$\label{eq:VCC} \begin{array}{ c c c c c } \hline V_{CC} = Min, I_{I} = \\ \hline V_{CC} = Min, I_{OH} \\ \hline V_{IL} = Max, V_{IH} \\ \hline V_{CC} = Min, I_{OL} \\ \hline V_{IH} = Min, V_{IL} = \\ \end{array}$	Conditions -10 mA = Max, = Min = Max, = Max			-1.5	v v
over recor Symbol V _I V _{OH} V _{OL}	mmended operating free air temperat Parameter Input Clamp Voltage HIGH Level Output Voltage	$\begin{tabular}{ c c c c c } \hline & V_{CC} = Min, \ I_{I} = \\ \hline & V_{CC} = Min, \ I_{OH} \\ \hline & V_{IL} = Max, \ V_{IH} \\ \hline & V_{CC} = Min, \ I_{OL} \\ \hline \end{tabular}$	Conditions -10 mA = Max, = Min = Max, = Max			-1.5	V
over recor	Input Current @ Max	$\label{eq:VCC} \begin{array}{ c c c c c } \hline V_{CC} = Min, I_{I} = \\ \hline V_{CC} = Min, I_{OH} \\ \hline V_{IL} = Max, V_{IH} \\ \hline V_{CC} = Min, I_{OL} \\ \hline V_{IH} = Min, V_{IL} = \\ \end{array}$	Conditions -10 mA = Max, = Min = Max, = Max = 5.5V	MR. Dx		-1.5	v v
over recor Symbol V _I V _{OH} V _{OL}	Input Clamp Voltage LOW Level Output Voltage Input Current @ Max Input Voltage	$\label{eq:constraint} \begin{array}{c} V_{CC} = Min, \ I_{I} = \\ V_{CC} = Min, \ I_{OH} \\ V_{IL} = Max, \ V_{IH} \\ V_{CC} = Min, \ I_{OL} \\ V_{IH} = Min, \ V_{IL} \\ V_{CC} = Max, \ V_{I} \end{array}$	Conditions -10 mA = Max, = Min = Max, = Max = 5.5V	MR, Dx CP (7, 10)		-1.5 0.3 1	N N m
over recor Symbol V _I V _{OH} V _{OL}	Input Clamp Voltage Input Current @ Max Input Current @ Max Input Voltage Input Current @ Max Input Voltage IIGH Level	$\label{eq:constraint} \begin{array}{c} V_{CC} = Min, \ I_{I} = \\ V_{CC} = Min, \ I_{OH} \\ V_{IL} = Max, \ V_{IH} \\ V_{CC} = Min, \ I_{OL} \\ V_{IH} = Min, \ V_{IL} \\ V_{CC} = Max, \ V_{I} \end{array}$	Conditions -10 mA = Max, = Min = Max, = Max = 5.5V			-1.5 0.3 1 20	
over recor Symbol V _I V _{OH} V _{OL}	Input Clamp Voltage Input Current @ Max Input Current @ Max Input Voltage Input Current @ Max Input Voltage IIGH Level	$\label{eq:constraint} \begin{array}{c} V_{CC} = Min, \ I_{I} = \\ V_{CC} = Min, \ I_{OH} \\ V_{IL} = Max, \ V_{IH} \\ V_{CC} = Min, \ I_{OL} \\ V_{IH} = Min, \ V_{IL} \\ V_{CC} = Max, \ V_{I} \end{array}$	Conditions -10 mA = Max, = Min = Max, = Max = 5.5V	CP (7, 10)		-1.5 0.3 1 20 30	N N m
over recor Symbol V1 V0H V0L I1 I1 I1H	Input Clamp Voltage Input Current @ Max Input Current @ Max Input Voltage Input Current @ Max Input Voltage IIGH Level	$\label{eq:constraint} \begin{array}{c} V_{CC} = Min, \ I_{I} = \\ V_{CC} = Min, \ I_{OH} \\ V_{IL} = Max, \ V_{IH} \\ V_{CC} = Min, \ I_{OL} \\ V_{IH} = Min, \ V_{IL} \\ V_{CC} = Max, \ V_{I} \end{array}$	Conditions -10 mA = Max, = Max, = 5.5V = 2.4V	CP (7, 10) S		-1.5 0.3 1 20 30 40	\ \ m
over recor Symbol V _I V _{OH} V _{OL}	Input Clamp Voltage Input Clamp Voltage ILOW Level Output Voltage Input Current @ Max Input Voltage HIGH Level Input Voltage HIGH Level Input Current	$V_{CC} = Min, I_{I} = V_{CC} = Min, I_{OH} = V_{CC} = Min, I_{OH} = V_{CC} = Min, I_{OH} = V_{IL} = Max, V_{IH}$ $V_{CC} = Min, I_{OL} = V_{IH} = Min, V_{IL} = V_{CC} = Max, V_{I}$ $V_{CC} = Max, V_{I}$	Conditions -10 mA = Max, = Max, = 5.5V = 2.4V	CP (7, 10) S CP Com		-1.5 0.3 1 20 30 40 60	ν ν π
over recor Symbol V1 V0H V0L I1 I1 I1H	Input Clamp Voltage Input Clamp Voltage ILOW Level Output Voltage Input Current @ Max Input Voltage HIGH Level Input Voltage HIGH Level Input Current LOW Level LOW Level	$V_{CC} = Min, I_{I} = V_{CC} = Min, I_{OH} = V_{CC} = Min, I_{OH} = V_{CC} = Min, I_{OH} = V_{IL} = Max, V_{IH}$ $V_{CC} = Min, I_{OL} = V_{IH} = Min, V_{IL} = V_{CC} = Max, V_{I}$ $V_{CC} = Max, V_{I}$	Conditions -10 mA = Max, = Max, = 5.5V = 2.4V	CP (7, 10) S CP Com MR, Dx		-1.5 0.3 1 20 30 40 60 -400	N N m
over recor Symbol V1 V0H	Input Clamp Voltage Input Clamp Voltage ILOW Level Output Voltage Input Current @ Max Input Voltage HIGH Level Input Voltage HIGH Level Input Current LOW Level LOW Level	$\label{eq:VCC} \begin{array}{ c c c c c c c c c c c c c c c c c c c$	Conditions -10 mA = Max, = Max, = 5.5V = 2.4V	CP (7, 10) S CP Com MR, Dx CP (7, 10)		-1.5 0.3 1 20 30 40 60 -400 -600	
over recor Symbol V1 V0H V0L I1 I1 I1H	Input Clamp Voltage Input Clamp Voltage ILOW Level Output Voltage Input Current @ Max Input Voltage HIGH Level Input Voltage HIGH Level Input Current LOW Level LOW Level	$V_{CC} = Min, I_{I} = V_{CC} = Min, I_{OH} = V_{CC} = Min, I_{OH} = V_{CC} = Min, I_{OH} = V_{IL} = Max, V_{IH} = V_{CC} = Min, I_{OL} = V_{IH} = Min, V_{IL} = V_{CC} = Max, V_{I}$	Conditions -10 mA = Max, = Max, = 5.5V = 2.4V	CP (7, 10) S CP Com MR, Dx CP (7, 10) S	2.4	-1.5 0.3 1 20 30 40 60 -400 -600 -800 -1200	- μι - μι - Γ
over recor Symbol V1 V0H VOL I IH	Input Clamp Voltage Input Clamp Voltage ILOW Level Output Voltage Input Current @ Max Input Voltage HIGH Level Input Current LOW Level Input Current	$\label{eq:VCC} \begin{array}{ c c c c c c c c c c c c c c c c c c c$	Conditions -10 mA = Max, = Max, = 5.5V = 2.4V	CP (7, 10) S CP Com MR, Dx CP (7, 10) S		-1.5 0.3 1 20 30 40 60 -400 -600 -800	

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Switching Characteristics

$V_{CC} = +5.0V$, $T_A = +25^{\circ}C$					
Symbol	Parameter	C _L = 15 pF		Units	
		Min	Мах	Units	
f _{MAX}	Maximum Shift Right Frequency	5.0		MHz	
t _{PLH}	Propagation Delay		45		
t _{PHL}	CP to Q_7 or \overline{Q}_7		80	ns	
t _{PHL}	Propagation Delay $\overline{\text{MR}}$ to Q_7		110	ns	

