

# DS1045 4-Bit Dual Programmable Delay Line

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# FEATURES

- All-silicon time delay
- Two programmable outputs from a single input produce output-to-output delays between 9 and 84 ns depending on device type
- Programmable via four input pins
- Programmable increments of 3 to 5 ns with a minimum of 9 ns and a maximum of 84 ns
- Output pulse is a reproduction of input pulse after
- Delay with both leading and trailing edge accuracy
- Standard 16-pin DIP or surface mount 16-pin SOIC
- Auto-insertable
- Low-power CMOS design is TTL-compatible

# PIN ASSIGNMENT

IN 1 V <sub>cc</sub> 2 EA 3 A0 4 A1 5 A2 6 A3 7 GND 8	16 Vcc 15 EB 14 OUTB 13 B0 12 B1 11 B2 10 B3 9 OUTA	IN [] 1 V <sub>CC</sub> [] 2 EA [] 3 A0 [] 5 A2 [] 6 A3 [] 7 GND [] 8	16 □ V <sub>cc</sub> 15 □ EB 14 □ OUTB 13 □ B0 12 □ B1 11 □ B2 10 □ B3 9 □ OUTA
DS1045 1 See Mech. Sec	Drawings	See Mech	n SOIC (300-mil) . Drawings ttion

#### **PIN DESCRIPTION**

IN OUTA, OUTB

- A0-A3
- B0-B3

GND

 $\overline{EA}, \overline{EB}$ 

for OUT1 - Parallel Program Inputs for OUT2 - Enable A and B Inputs

- Delay Line Input

- Delay Line Outputs

- Parallel Program Inputs

- +5V Input

- Ground

#### DESCRIPTION

The DS1045 is a programmable silicon delay line having one input and two 4-bit programmable delay outputs. Each 4-bit programmable output offers the user 16 possible delay values to select from, starting with a minimum inherent DS1045 delay of 9 ns and a maximum achievable delay in the standard DS1045 family of 84 ns. The standard DS1045 product line provides the user with three devices having uniform delay increments of 3, 4, and 5 ns, depending on the device. Table 1 presents standard device family and delay capability. Additionally, custom delay increments are available for special order through Dallas Semiconductor.

The DS1045 is TTL and CMOS-compatible and capable of driving ten 74LS-type loads. The output produced by the DS1045 is both rising and falling edge precise. The DS1045 programmable silicon delay line has been designed as a reliable, economic alternative to hybrid programmable delay lines. It is offered in a standard 16-pin auto-insertable DIP and a space-saving surface mount 16-pin SOIC package.



# PARALLEL PROGRAMMING

Parallel programming of the DS1045 is accomplished via the set of parallel inputs A0-A3 and B0-B3 as shown in Figure 1. Parallel input A0-A3 and B0-B3 accept TTL levels and are used to set the delay values of outputs OUTA and OUTB, respectively. Sixteen possible delay values between the minimum 9 ns delay and the maxi-mum delay of the DS1045-x device version can be selected using the parallel programming inputs A0-A3 or B0-B3 (see Table 2, "Delay vs. Programmed Input"). For example, the DS1045-3 outputs OUTA or OUTB and can be programmed to produce 16 possible delays between the 9 ns (minimum) and the 54 ns (maximum) in 3 ns increment levels.

For applications that do not require frequent reprogramming, the parallel inputs can be set using fixed logic levels, as would be produced by jumpers, DIP switches, or TTL levels as produced by computer systems. Maximum flexibility in parallel programming can be achieved when inputs are set by computer-generated data. By using the enable input pins for each respective programmed output and observing the input setup ( $t_{DSE}$ ) and hold time ( $t_{DHE}$ ) requirements, data can be latched on an 8-bit bus. If the enable pins,  $\overrightarrow{EA}$  and  $\overrightarrow{EB}$ , are not used to latch data, they should be set to a logic level 1. After each change in the programmed delay value, a settling time ( $t_{EDV}$ ) or ( $t_{PDV}$ ) is required before the delayed output signal is reliably produced. Since the DS1045 is a CMOS design, undefined input pins should be connected to well defined logic levels and not left floating.

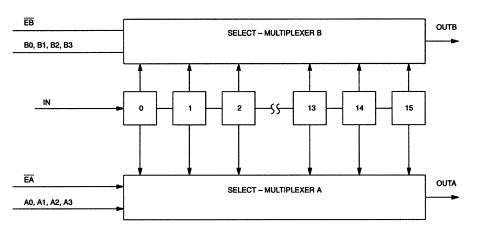
PART NUMBER	STEP ZERO DELAY	MAX DELAY TIME	MAX DELAY TOLERANCE
DS1045-3	9 ± 1 ns	54 ns	±2.5 ns
DS1045-4	9 ± 1 ns	69 ns	±3.3 ns
DS1045-5	9 ± 1 ns	84 ns	±4.1 ns

#### PART NUMBER TABLE Table 1

# NOTE:

Additional delay step times are available from Dallas Semiconductor by special order. Consult factory for availability.

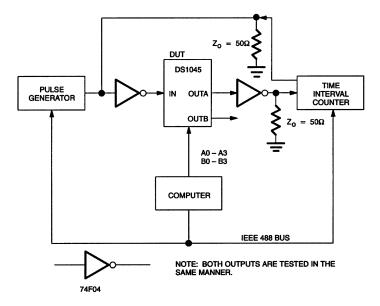
# BLOCK DIAGRAM Figure 1



# DELAY VS. PROGRAMMED VALUE Table 2

PART NUMBER	OUTPUT DELAY VALUE															
DS1045-3	9	12	15	18	21	24	27	30	33	36	39	42	45	48	51	54
DS1045-4	9	13	17	21	25	29	33	37	41	45	49	53	57	61	65	69
DS1045-5	9	14	19	24	29	34	39	44	49	54	59	64	69	74	79	84
Р	PROGRAM VALUES FOR EACH DELAY VALUE															
A0 OR B0	0	1	0	1	0	1	0	1	0	1	0	1	0	1	0	1
A1 OR B1	0	0	1	1	0	0	1	1	0	0	1	1	0	0	1	1
A2 OR B2	0	0	0	0	1	1	1	1	0	0	0	0	1	1	1	1
A3 OR B3	0	0	0	0	0	0	0	0	1	1	1	1	1	1	1	1

# DS1045 TEST CIRCUIT Figure 2



# **TEST SETUP DESCRIPTION**

Figure 2 illustrates the hardware configuration used for measuring the timing parameters of the DS1045. The input waveform is produced by a precision pulse generator under software control. Time delays are measured by a time interval counter (20 ps resolution) connected to the output. The DS1045 parallel inputs are controlled by an interface to a central computer. All measurements are fully automated with each instrument controlled by the computer over an IEEE 488 bus.

# **ABSOLUTE MAXIMUM RATINGS\***

Voltage on Any Pin Relative to Ground Operating Temperature Storage Temperature Soldering Temperature Short Circuit Output Current -1.0V to +7.0V 0°C to 70°C -55°C to +125°C See J-STD-020A specification 50 mA for 1 second

\* This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operation sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods of time may affect reliability.

RECOMMEND	<b>ECOMMENDED DC OPERATING CONDITIONS</b> (0°C to 70°										
PARAMETER	SYMBOL	TEST CONDITION	MIN	ТҮР	MAX	UNITS	NOTES				
Supply Voltage	V <sub>CC</sub>		4.75	5.0	5.25	V	1				
Input Logic 1	V <sub>IH</sub>		2.2		V <sub>CC</sub> +0.5	V	1				
Input Logic 0	V <sub>IL</sub>		-0.5		0.8	μΑ	1				
Input Leakage	$I_{I}$	$0 \leq V_I \leq V_{CC}$	-1.0		+1.0	μΑ					
Active Current	I <sub>CC</sub>	V <sub>CC</sub> =5.25V PERIOD=1 μs			35.0	mA					
Logic 1 Output Current	I <sub>OH</sub>	V <sub>CC</sub> = 4.75V V <sub>OH</sub> = 4.0V			-1.0	mA					
Logic 0 Output Current	I <sub>OL</sub>	$V_{CC} = 4.75 V V_{OL} = 0.5 V$	8			mA					

DC ELECTRICAL CHAR	(0°C to 70°C; V <sub>CC</sub> 5V + 5%)					
PARAMETER	SYMBOL	MIN	ТҮР	MAX	UNITS	NOTES
Period	t <sub>PERIOD</sub>	4 x t <sub>wi</sub>			ns	
Pulse Width	t <sub>WI</sub>	10	0% of outp	out delay size		
Input to Output Delay	t <sub>PLH</sub> , t <sub>PHL</sub>		2			
Parallel Input Change to	t <sub>PDX</sub>				ns	
Delay Invalid						
Parallel Input Valid to Delay	t <sub>PDX</sub>		10		ns	
Valid						
Enable Width	t <sub>EW</sub>	15			ns	
Data Setup to Enable	t <sub>DSE</sub>	10			ns	
Data Hold from Enable	t <sub>DHE</sub>				ns	
Enable to Delay Invalid	t <sub>EDX</sub>		5		ns	
Enable to Delay Valid	t <sub>EDV</sub>		15		ns	

<b>CAPACITANCE</b> $(T_A = 25^{\circ})$								
PARAMETER	SYMBOL	MIN	ТҮР	MAX	UNITS	NOTES		
Input Capacitance	C <sub>IN</sub>			10	pF			

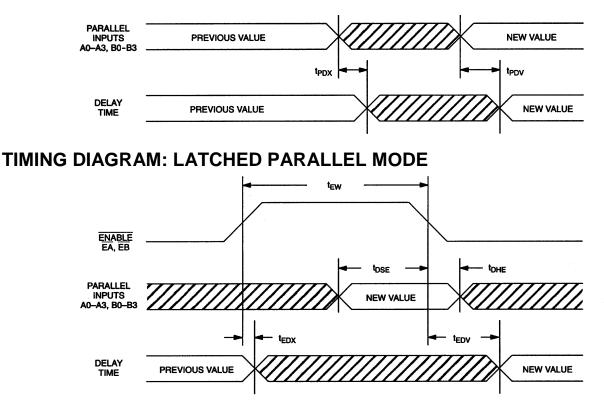
#### **TEST CONDITIONS**

$$\begin{split} T_A &= 25^\circ C \pm 3^\circ C \\ V_{CC} &= 5.0V \pm 0.1V \\ \text{Input Pulse} &= 3.0V \text{ high to } 0.0V \text{ low } \pm 0.1V \\ \text{Input Source Impedance} &= 50\Omega \text{ maximum} \\ \text{Rise and fall times} &= 3.0 \text{ ns max. between } 0.6V \text{ and } 2.4V \\ \text{Pulse Width} &= 250 \text{ ns} \\ \text{Period} &= 500 \text{ ns} \\ \text{Output Load} &= 74F04 \\ \text{Measurement Point} &= 1.5V \text{ on inputs and outputs} \\ \text{Output Load Capacitance} &= 15 \text{ pF} \end{split}$$

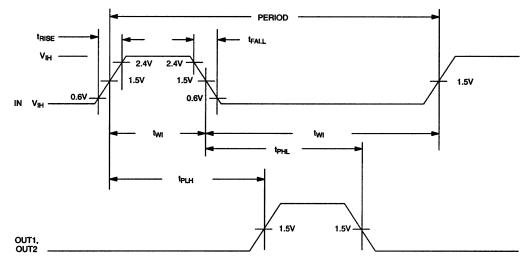
#### NOTE:

Above conditions are for test only and do not restrict the operation of the device under other data sheet conditions.

# TIMING DIAGRAM: NON-LATCHED PARALLEL MODE, $\overline{EA}$ , $\overline{EB} = V_{IH}$



#### TIMING DIAGRAM: DS1045 INPUTS TO OUTPUTS



#### TERMINOLOGY

**PERIOD:** The time elapsed between the leading edge of the first pulse and the leading edge of the following pulse.

 $\mathbf{t}_{WI}$  (Pulse Width): The elapsed time on the pulse between the 1.5V point on the leading edge and the 1.5V point on the trailing edge, or the 1.5V point on the trailing edge and the 1.5V on the leading edge.

 $t_{RISE}$  (Input Rise Time): The elapsed time between the 20% and the 80% point on the leading edge of the input pulse.

 $t_{FALL}$  (Input Fall Time): The elapsed time between the 80% and the 20% point on the trailing edge of the input pulse.

 $t_{PLH}$  (Time Delay, Rising): The elapsed time between the 1.5V point on the leading edge of the input pulse and the 1.5V point on the leading edge of the output pulse.

 $t_{PHL}$  (Time Delay, Falling): The elapsed time between the 1.5V point on the trailing edge of the input pulse and the 1.5V point on the trailing edge of the output pulse.

#### NOTES:

- 1. All voltages are referenced to ground.
- 2. @  $V_{CC} = 5V$  and 25°C. Delay accurate on both rising and falling edges within tolerances given in Table 1.