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National Semiconductor

DS90CR211/DS90CR212 21-Bit Channel Link

General Description

The DS90CR211 transmitter converts 21 bits of CMOS/TTL data into three LVDS (Low Voltage Differential Signaling) data streams. A phase-locked transmit clock is transmitted in parallel with the data streams over a fourth LVDS link. Every cycle of the transmit clock 21 bits of input data are sampled and transmitted. The DS90CR212 receiver converts the LVDS data streams back into 21 bits of CMOS/TTL data. At a transmit clock frequency of 40 MHz, 21 bits of TTL data are transmitted at a rate of 280 Mbps per LVDS data channel. Using a 40 MHz clock, the data throughput is 840 Mbit/s(105 Mbyte/s).

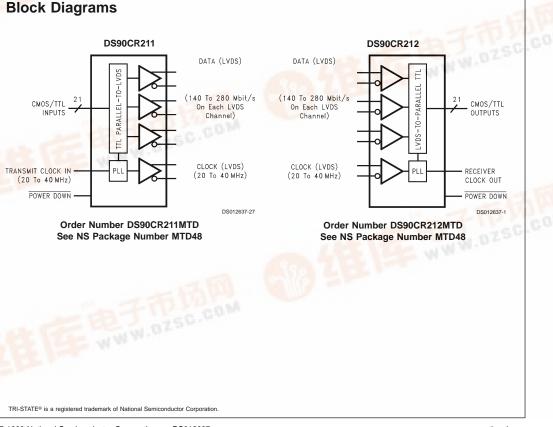
The multiplexing of the data lines provides a substantial cable reduction. Long distance parallel single-ended buses typically require a ground wire per active signal (and have very limited noise rejection capability). Thus, for a 21-bit wide data bus and one clock, up to 44 conductors are required. With the Channel Link chipset as few as 9 conductors (3 data pairs, 1 clock pair and a minimum of one ground) are

needed. This provides a 80% reduction in required cable width, providing a system cost savings, reduces connector physical size, and reduces shielding requirements due to the cables smaller form factor.

The 21 CMOS/TTL inputs can support a variety of signal combinations. For example, 5 4-bit nibbles plus 1 control, or 2 9-bit (byte + parity) and 3 control.

Features

- Narrow bus reduces cable size and cost
- ±1V Common mode range (ground shifting)
- 290 mV swing LVDS data transmission
- 840 Mbit/s data throughput
- Low swing differential current mode drivers reduce EMI
- Rising edge data strobe
- Power down mode
- Offered in low profile 48-lead TSSOP package



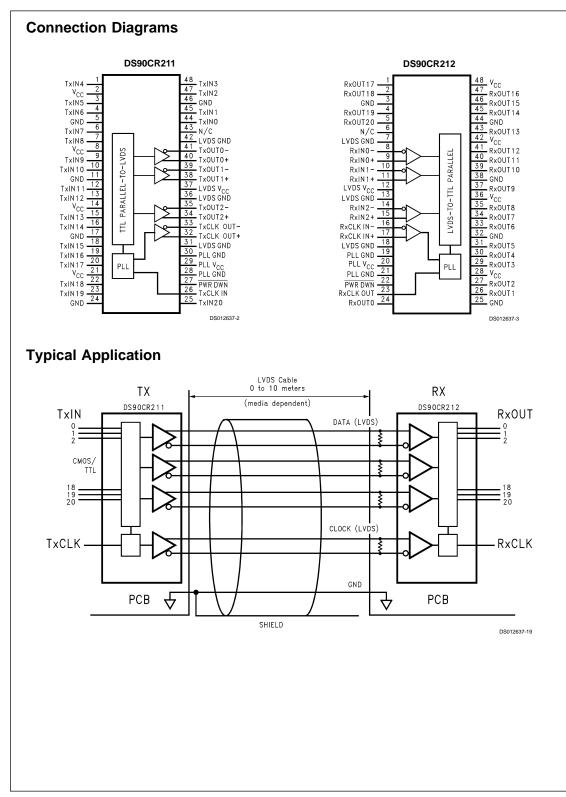
S90CR211/DS90CR212 21-Bit Channel Link

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Absolute Maximum Ratings (Note 1)

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If Military/Aerospace specified devices are required, please contact the National Semiconductor Sales Office/ Distributors for availability and specifications.

Supply Voltage (V _{CC}) CMOS/TTL Input Voltage CMOS/TTL Ouput Voltage LVDS Receiver Input Voltage	$\begin{array}{c} -0.3 \text{V to +6V} \\ -0.3 \text{V to } (\text{V}_{\text{CC}} + 0.3 \text{V}) \\ -0.3 \text{V to } (\text{V}_{\text{CC}} + 0.3 \text{V}) \\ -0.3 \text{V to } (\text{V}_{\text{CC}} + 0.3 \text{V}) \end{array}$
LVDS Driver Output Voltage	–0.3V to (V _{CC} + 0.3V)
LVDS Output	
Short Circuit Duration	continuous
Junction Temperature	+150°C
Storage Temperature Range	-65°C to +150°C
Lead Temperature	
(Soldering, 4 sec.)	+260°C
Maximum Power Dissipation @ +25°0	0

MTD48 (TSSOP) Package:	
DS90CR211	1.98W
DS90CR212	1.89W
Package Derating:	
DS90CR211	16 mW/°C above +25°C
DS90CR212	15 mW/°C above +25°C
This device does not meet 20	00V ESD rating (Note 4) .

Recommended Operating Conditions

	Min	Max	Units
Supply Voltage (V _{CC})	4.5	5.5	V
Operating Free Air Temperature (T _A)	-10	+70	°C
Receiver Input Range	0	2.4	V
Supply Noise Voltage (V _{CC})		100	mV_{PP}

Electrical Characteristics

Symbol	Parameter	Condition	s	Min	Тур	Max	Units
CMOS/TTL	DC SPECIFICATIONS	1				•	
V _{IH}	High Level Input Voltage			2.0		V _{cc}	V
V _{IL}	Low Level Input Voltage			GND		0.8	V
V _{он}	High Level Output Voltage	I _{OH} = -0.4 mA	$I_{OH} = -0.4 \text{ mA}$		4.9		V
V _{OL}	Low Level Output Voltage	I _{OL} = 2 mA			0.1	0.3	V
V _{CL}	Input Clamp Voltage	I _{CL} = -18 mA			-0.79	-1.5	V
I _{IN}	Input Current	$V_{IN} = V_{CC}$, GND, 2.5V or	r 0.4V		±5.1	±10	μA
los	Output Short Circuit Current	V _{OUT} = 0V				-120	mA
LVDS DRI	VER DC SPECIFICATIONS						
V _{OD}	Differential Output Voltage	R _L = 100Ω		250	290	450	mV
ΔV_{OD}	Change in V _{OD} between]				35	mV
	Complementary Output States						
V _{CM}	Common Mode Voltage		1.1	1.25	1.375	V	
ΔV _{CM}	Change in V _{CM} between]			35	mV	
	Complementary Output States						
l _{os}	Output Short Circuit Current	$V_{OUT} = 0V, R_L = 100\Omega$		-2.9	-5	mA	
I _{oz}	Output TRI-STATE [®] Current	Power Down = 0V, V _{OUT}		±1	±10	μA	
LVDS REC	EIVER DC SPECIFICATIONS						
V _{TH}	Differential Input High Threshold	V _{CM} = +1.2V				+100	mV
V _{TL}	Differential Input Low Threshold						mV
I _{IN}	Input Current	V _{IN} = +2.4V	$V_{\rm CC} = 5.5V$		< ±1	±10	μA
		$V_{IN} = 0V$			< ±1	±10	μA
TRANSMI	ITER SUPPLY CURRENT						
I _{CCTW}	Transmitter Supply Current, Worst Case	$R_L = 100\Omega, C_L = 5 \text{ pF},$ Worst Case Pattern	f = 32.5 MHz		34	51	mA
		(Figure 1, Figure 2)	f = 37.5 MHz		36	53	mA
I _{CCTZ}	Transmitter Supply Current, Power Down	Power Down = Low		1	25	μA	
RECEIVER	R SUPPLY CURRENT	1					
CCRW	Receiver Supply Current, Worst Case	$C_L = 8 \text{ pF},$ Worst Case Pattern	f = 32.5 MHz		55	75	mA
		(Figure 1, Figure 3) $f = 37.5 \text{ MHz}$			60	80	mA

Electrical Characteristics (Continued)

Over recommended operating supply and temperature ranges unless otherwise specified

Symbol	Parameter	Conditions	Min	Тур	Max	Units
RECEIVE	R SUPPLY CURRENT					
I _{CCRZ}	Receiver Supply Current, Power Down	Power Down = Low		1	10	μA

Note 1: "Absolute Maximum Ratings" are those values beyond which the safety of the device cannot be guaranteed. They are not meant to imply that the device should be operated at these limits. The tables of "Electrical Characteristics" specify conditions for device operation.

Note 2: Typical values are given for V_{CC} = 5.0V and T_A = +25°C.

Note 3: Current into device pins is defined as positive. Current out of device pins is defined as negative. Voltages are referenced to ground unless otherwise specified (except V_{OD} and ΔV_{OD}).

Note 4: ESD Rating:

HBM (1.5 kΩ, 100 pF) PLL V $_{CC} \ge 1000V$

All other pins $\ge 2000V$

EIAJ (0 Ω , 200 pF) \ge 150V

Transmitter Switching Characteristics

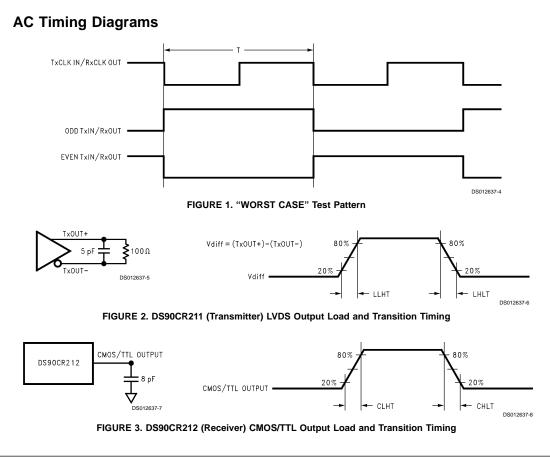
Over recommended operating supply and temperature ranges unless otherwise specified

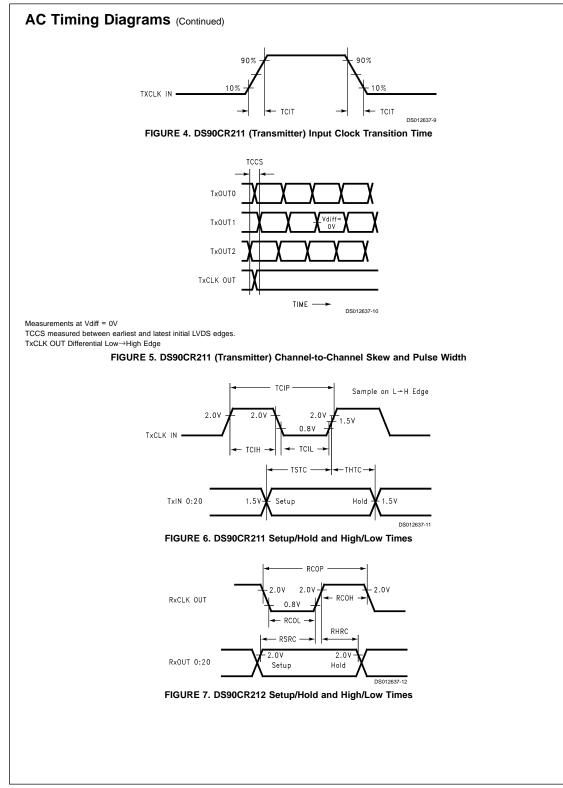
Symbol	Parameter	Min	Тур	Max	Units	
LLHT	LVDS Low-to-High Transition Time (Figure 2)		0.75	1.5	ns	
LHLT	LVDS High-to-Low Transition Time (Figure 2)		0.75	1.5	ns	
TCIT	TxCLK IN Transition Time (Figure 4)				8	ns
TCCS	TxOUT Channel-to-Channel Skew (Note 5) (Figure 5)				350	ps
TPPos0	Transmitter Output Pulse Position for Bit0 (<i>Figure 16</i>) f = 20 MHz				350	ps
TPPos1	Transmitter Output Pulse Position for Bit1		6.3	7.2	7.5	ns
TPPos2	Transmitter Output Pulse Position for Bit2		12.8	13.6	14.6	ns
TPPos3	Transmitter Output Pulse Position for Bit3		20	20.8	21.5	ns
TPPos4	Transmitter Output Pulse Position for Bit4		27.2	28	28.5	ns
TPPos5	Transmitter Output Pulse Position for Bit5		34.5	35.2	35.6	ns
TPPos6	Transmitter Output Pulse Position for Bit6				42.9	ns
TPPos0	Transmitter Output Pulse Position for Bit0 (Figure 16)	tput Pulse Position for Bit0 (<i>Figure 16</i>) f = 40 MHz		100	300	ps
TPPos1	Transmitter Output Pulse Position for Bit1	2.9	3.3	3.9	ns	
TPPos2	Transmitter Output Pulse Position for Bit2		6.1	6.6	7.1	ns
TPPos3	Transmitter Output Pulse Position for Bit3		9.7	10.2	10.7	ns
TPPos4	Transmitter Output Pulse Position for Bit4		13	13.5	14.1	ns
TPPos5	Transmitter Output Pulse Position for Bit5		17	17.4	17.8	ns
TPPos6	Transmitter Output Pulse Position for Bit6				21.4	ns
TCIP	TxCLK IN Period (Figure 6)		25	Т	50	ns
TCIH	TxCLK IN High Time (Figure 6)		0.35T	0.5T	0.65T	ns
TCIL	TxCLK IN Low Time (Figure 6)		0.35T	0.5T	0.65T	ns
TSTC	TxIN Setup to TxCLK IN (Figure 6)	f = 20 MHz	14			ns
		f = 40 MHz	8			ns
THTC	TxIN Hold to TxCLK IN (Figure 6)		2.5	2		ns
TCCD	TxCLK IN to TxCLK OUT Delay @ 25°C, V _{CC} = 5.0V (Figure 8)		5		9.7	ns
TPLLS	Transmitter Phase Lock Loop Set (Figure 10)				10	ms
TPDD	Transmitter Powerdown Delay (Figure 14)				100	ns

Note 5: This limit based on bench characterization.

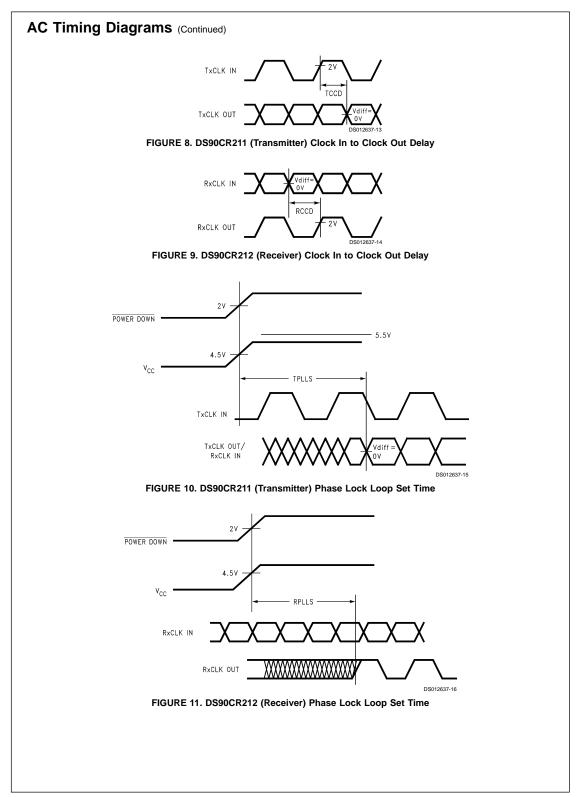
Symbol	Parameter		Min	Тур	Max	Units
CLHT	CMOS/TTL Low-to-High Transition Time (Figure 3	3)		3.5	6.5	ns
CHLT	CMOS/TTL High-to-Low Transition Time (Figure 3	3)		2.7	6.5	ns
RCOP	RxCLK OUT Period (Figure 7)		25	Т	50	ns
RSKM	Receiver Skew Margin (Note 6)	f = 20 MHz	1.1			ns
	$V_{CC} = 5V, T_{A} = 25^{\circ}C$ (<i>Figure 17</i>)	f = 40 MHz	700			ps
RCOH	RxCLK OUT High Time (Figure 7)	f = 20 MHz	19			ns
		f = 40 MHz	6			ns
RCOL	RxCLK OUT Low Time (Figure 7)	f = 20 MHz	21.5			ns
		f = 40 MHz	10.5			ns
RSRC	RxCLK Setup to RxCLK OUT (Figure 7)	f = 20 MHz	14			ns
		f = 40 MHz	4.5			ns
RHRC	RxCLK Hold to RxCLK OUT (Figure 7)	f = 20 MHz	16			ns
		f = 40 MHz	6.5			ns
RCCD	RxCLK IN to RxCLK OUT Delay @ 25°C, V _{CC} = 5.0V (Figure 9)		7.6		11.9	ns
RPLLS	Receiver Phase Lock Loop Set (Figure 11)				10	ms
RPDD	Receiver Powerdown Delay (Figure 15)				1	μs

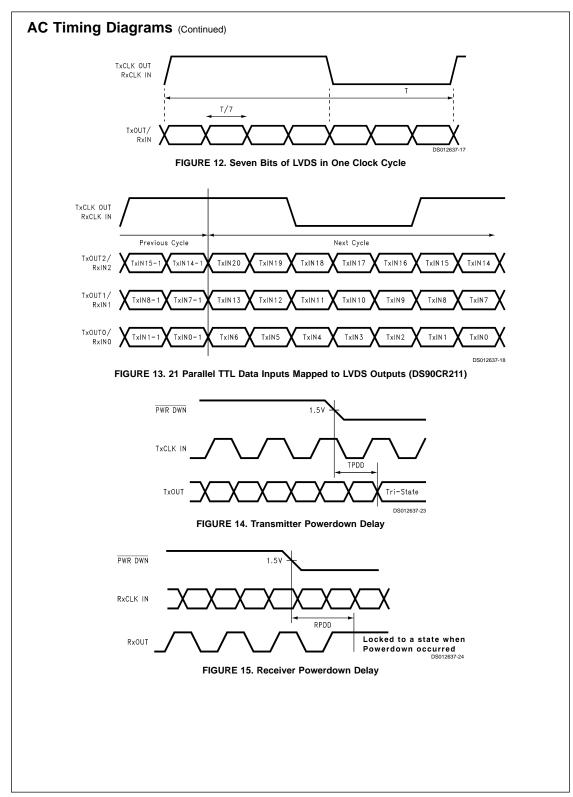
Note 6: Receiver Skew Margin is defined as the valid data sampling region at the receiver inputs. This margin takes into account for transmitter output skew(TCCS) and the setup and hold time (internal data sampling window), allowing LVDS cable skew dependent on type/length and source clock(TxCLK IN) jitter. RSKM ≥ cable skew (type, length) + source clock jitter (cycle to cycle).

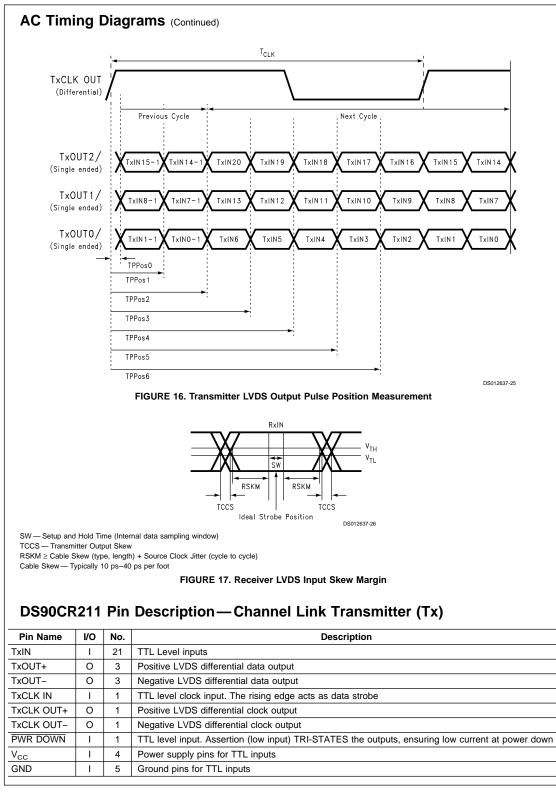




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DS90CR211 Pin Description—Channel Link Transmitter (Tx) (Continued)

Pin Name	I/O	No.	Description
PLL V _{CC}	1	1	Power supply pin for PLL
PLL GND	I	2	Ground pins for PLL
LVDS V _{CC}	I	1	Power supply pin for LVDS outputs
LVDS GND	I	3	Ground pins for LVDS outputs

DS90CR212 Pin Description—Channel Link Receiver (Rx)

Pin Name	I/O	No.	Description
RxIN+	I	3	Positive LVDS differential data inputs
RxIN-	I	3	Negative LVDS differential data inputs
RxOUT	0	21	TTL level outputs
RxCLK IN+	Т	1	Positive LVDS differential clock input
RxCLK IN-	I	1	Negative LVDS differential clock input
RxCLK OUT	0	1	TTL level clock output. The rising edge acts as data strobe
PWR DOWN	Т	1	TTL level input. Assertion (low input) maintains the receiver outputs in the previous state
V _{cc}	Т	4	Power supply pins for TTL outputs
GND	I	5	Ground pins for TTL outputs
PLL V _{CC}	I	1	Power supply for PLL
PLL GND	Т	2	Ground pin for PLL
LVDS V _{CC}	Т	1	Power supply pin for LVDS inputs
LVDS GND	I	3	Ground pins for LVDS inputs

Applications Information

The Channel Link devices are intended to be used in a wide variety of data transmission applications. Depending upon the application the interconnecting media may vary. For example, for lower data rate (clock rate) and shorter cable lengths (< 2m), the media electrical performance is less critical. For higher speed/long distance applications the media's performance becomes more critical. Certain cable constructions provide tighter skew (matched electrical length between the conductors and pairs). Twin-coax for example, has been demonstrated at distances as great as 10 meters and with the maximum data transfer of 1.12 Gbit/s. Additional applications information can be found in the following National Interface Application Notes:

AN = ####	Торіс
AN-1035	PCB Design Guidelines for LVDS and Link Devices
AN-806	Transmission Line Theory
AN-905	Transmission Line Calculations and Differential Impedance
AN-916	Cable Information

CABLES: A cable interface between the transmitter and receiver needs to support the differential LVDS pairs. The 21-bit CHANNEL LINK chipset (DS90CR211/212) requires four pairs of signal wires and the 28-bit CHANNEL LINK chipset (DS90CR281/282) requires five pairs of signal wires. The ideal cable/connector interface would have a constant 100 Ω differential impedance throughout the path. It is also recommended that cable skew remain below 350 ps (@ 40 MHz clock rate) to maintain a sufficient data sampling window at the receiver.

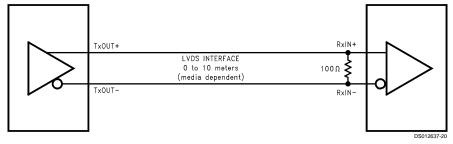
In addition to the four or five cable pairs that carry data and clock, it is recommended to provide at least one additional conductor (or pair) which connects ground between the transmitter and receiver. This low impedance ground provides a common mode return path for the two devices. Some of the more commonly used cable types for point-to-point applications include flat ribbon, flex, twisted pair and Twin-Coax. All are available in a variety of configurations and options. Flat ribbon cable, flex and twisted pair generally perform well in short point-to-point applications while Twin-Coax is good for short and long applications. When using ribbon cable, it is recommended to place a ground line between each differential pair to act as a barrier to noise coupling between adjacent pairs. For Twin-Coax cable applications, it is recommended to utilize a shield on each cable pair. All extended point-to-point applications should also employ an overall shield surrounding all cable pairs regardless of the cable type. This overall shield results in improved transmission parameters such as faster attainable speeds, longer distances between transmitter and receiver and reduced problems associated with EMS or EMI.

The high-speed transport of LVDS signals has been demonstrated on several types of cables with excellent results. However, the best overall performance has been seen when using Twin-Coax cable. Twin-Coax has very low cable skew and EMI due to its construction and double shielding. All of the design considerations discussed here and listed in the supplemental application notes provide the subsystem communications designer with many useful guidelines. It is recommended that the designer assess the tradeoffs of each application thoroughly to arrive at a reliable and economical cable solution.

BOARD LAYOUT: To obtain the maximum benefit from the noise and EMI reductions of LVDS, attention should be paid

Applications Information (Continued)

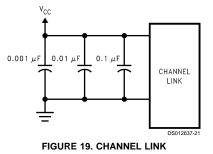
to the layout of differential lines. Lines of a differential pair should always be adjacent to eliminate noise interference from other signals and take full advantage of the noise canceling of the differential signals. The board designer should also try to maintain equal length on signal traces for a given differential pair. As with any high speed design, the impedance discontinuities should be limited (reduce the numbers of vias and no 90 degree angles on traces). Any discontinuities which do occur on one signal line should be mirrored in the other line of the differential pair. Care should be taken to ensure that the differential trace impedance match the differential impedance of the selected physical media (this impedance should also match the value of the termination resistor that is connected across the differential pair at the receiver's input). Finally, the location of the CHANNEL LINK TxOUT/ RxIN pins should be as close as possible to the board edge so as to eliminate excessive pcb runs. All of these considerations will limit reflections and crosstalk which adversely effect high frequency performance and EMI.

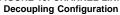




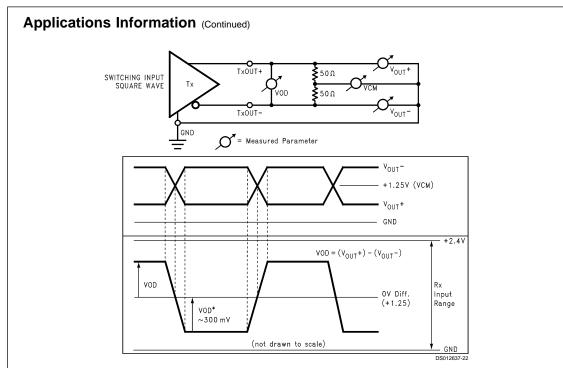
UNUSED INPUTS: All unused inputs at the TxW inputs of the transmitter must be tied to ground. All unused outputs at the RxOUT outputs of the receiver must then be left floating. TERMINATION: Use of current mode drivers requires a terminating resistor across the receiver inputs. The CHANNEL LINK chipset will normally require a single 100 resistor between the true and complement lines on each differential pair of the receiver input. The actual value of the termination resistor should be selected to match the differential mode characteristic impedance (90 Ω to 120 Ω typical) of the cable. Figure 18 shows an example. No additional pull-up or pull-down resistors are necessary as with some other differential technologies such as PECL. Surface mount resistors are recommended to avoid the additional inductance that accompanies leaded resistors. These resistors should be placed as close as possible to the receiver input pins to reduce stubs and effectively terminate the differential lines.

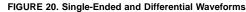
DECOUPLING CAPACITORS: Bypassing capacitors are needed to reduce the impact of switching noise which could limit performance. For a conservative approach three parallel-connected decoupling capacitors (Multi-Layered Ceramic type in surface mount form factor) between each $V_{\rm CC}$ and the ground plane(s) are recommended. The three capacitor values are 0.1 µF, 0.01µF and 0.001 µF. An example is shown in *Figure 19.* The designer should employ wide traces for power and ground and ensure each capacitor has its own via to the ground plane. If board space is limiting the number of bypass capacitors, the PLL $V_{\rm CC}$ should receive the most filtering/bypassing. Next would be the LVDS $V_{\rm CC}$ pins.





CLOCK JITTER: The CHANNEL LINK devices employ a PLL to generate and recover the clock transmitted across the LVDS interface. The width of each bit in the serialized LVDS data stream is one-seventh the clock period. For example, a 40 MHz clock has a period of 25 ns which results in a data bit width of 3.57 ns. Differential skew (Δt within one differential pair), interconnect skew (Δt of one differential pair to another) and clock jitter will all reduce the available window for sampling the LVDS serial data streams. Care must be taken to ensure that the clock input to the transmitter be a clean low noise signal. Individual bypassing of each V_{CC} to ground will minimize the noise passed on to the PLL, thus creating a low jitter LVDS clock. These measures provide more margin for channel-to-channel skew and interconnect skew as a part of the overall jitter/skew budget.





COMMON MODE vs. DIFFERENTIAL MODE NOISE MAR-GIN: The typical signal swing for LVDS is 300 mV centered at +1.2V. The CHANNEL LINK receiver supports a 100 mV threshold therefore providing approximately 200 mV of differential noise margin. Common mode protection is of more importance to the system's operation due to the differential data transmission. LVDS supports an input voltage range of Ground to +2.4V. This allows for a ±1.0V shifting of the center point due to ground potential differences and common mode noise.

POWER SEQUENCING AND POWERDOWN MODE: Outputs of the CHANNEL LINK transmitter remain in TRI-STATE® until the power supply reaches 3V. Clock and data outputs will begin to toggle 10 ms after V_{CC} has reached 4.5V and the Powerdown pin is above 2V. Either device may be placed into a powerdown mode at any time by asserting the Powerdown pin (active low). Total power dissipation for each device will decrease to 5 μ W (typical).

The CHANNEL LINK chipset is designed to protect itself from accidental loss of power to either the transmitter or receiver. If power to the transmit board is lost, the receiver clocks (input and output) stop. The data outputs (RxOUT) retain the states they were in when the clocks stopped. When the receiver board loses power, the receiver inputs are shorted to V $_{\rm CC}$ through an internal diode. Current is limited (5 mA per input) by the fixed current mode drivers, thus avoiding the potential for latchup when powering the device.

