

## INTEGRATED CIRCUITS

# DATA SHEET

## TEA1098A Speech and handsfree IC

Preliminary specification  
File under Integrated Circuits, IC03

2000 Mar 21

**Speech and handsfree IC****TEA1098A****FEATURES****Line interface**

- Low DC line voltage
- Voltage regulator with adjustable DC voltage
- Symmetrical high impedance inputs ( $70\text{ k}\Omega$ ) for dynamic, magnetic or electret microphones
- DTMF input with confidence tone on earphone and/or loudspeaker
- Earphone amplifier for dynamic, magnetic or piezo-electric earpieces (with externally adjustable gain)
- Digital volume control on earphone amplifier (4 steps)
- Automatic Gain Control (AGC) for true line loss compensation
- Microphone mute
- Key tone mode.

**Supplies**

- Provides a strong 3.35 V regulated supply for microcontroller or dialler
- Provides filtered power supply, optimized according to line current
- Filtered 2.0 V power supply output for electret microphone
- $\overline{\text{PD}}$  logic input for power-down.

**Handsfree**

- Asymmetrical high input impedance for electret microphone
- Loudspeaker amplifier with single-ended rail-to-rail output and externally adjustable gain
- Dynamic limiter on loudspeaker amplifier to prevent distortion
- Digital volume control on loudspeaker amplifier (8 steps)

**ORDERING INFORMATION**

TYPE NUMBER	PACKAGE		
	NAME	DESCRIPTION	VERSION
TEA1098ATV	VSO40	plastic very small outline package; 40 leads	SOT158-1
TEA1098AH	QFP44	plastic quad flat package; 44 leads (lead length 1.3 mm); body $10 \times 10 \times 1.75$ mm	SOT307-2

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## QUICK REFERENCE DATA

$I_{line} = 15 \text{ mA}$ ;  $R_{SLPE} = 20 \Omega$ ;  $Z_{line} = 600 \Omega$ ;  $f = 1 \text{ kHz}$ ;  $T_{amb} = 25^\circ \text{C}$ ; AGC pin connected to LN;  $\overline{PD} = \text{HIGH}$ ; HFC = LOW; MUTE = HIGH;  $\overline{BPC} = \text{HIGH}$ ; measured according to test circuits; unless otherwise specified.

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
$I_{line}$	line current operating range	normal operation	11	—	130	mA
		with reduced performance	1	—	11	mA
$V_{SLPE}$	stabilized voltage between SLPE and GND	$I_{line} = 15 \text{ mA}$	3.4	3.7	4.0	V
		$I_{line} = 70 \text{ mA}$	5.7	6.1	6.5	V
$V_{BB}$	regulated supply voltage for internal circuitry	$I_{line} = 15 \text{ mA}$	2.75	3.0	3.25	V
		$I_{line} = 70 \text{ mA}$	4.9	5.3	5.7	V
$V_{DD}$	regulated supply voltage on pin $V_{DD}$	$V_{BB} > 3.35 \text{ V} + 0.25 \text{ V} (\text{typ.})$	3.1	3.35	3.6	V
		otherwise	—	$V_{BB} - 0.25$	—	V
$I_{BB}$	current available on pin $V_{BB}$ in speech mode in handsfree mode	—	11	—	—	mA
		—	9	—	—	mA
$I_{BB(PD)}$	current consumption on $V_{BB}$ during power-down phase	$\overline{PD} = \text{LOW}$	—	460	—	$\mu\text{A}$
$G_v(\text{MIC-LN})$	voltage gain from pin MIC+/MIC- to LN	$V_{MIC} = 5 \text{ mV} (\text{RMS})$	43.3	44.3	45.3	dB
$G_v(\text{IR-RECO})$	voltage gain from pin IR (referenced to LN) to RECO	$V_{IR} = 15 \text{ mV} (\text{RMS})$ ; HFC = HIGH	28.7	29.7	30.7	dB
$\Delta G_v(\text{RECO-EARO})$	gain voltage range between pins RECO and EARO	—	—3	—	+15	dB
$G_v(\text{TXI-TXO})$	voltage gain from pin TXI to TXO	$V_{TXI} = 3 \text{ mV} (\text{RMS})$ ; $R_{GATX} = 30.1 \text{ k}\Omega$	12.7	15.2	17.7	dB
$G_v(\text{HFTX-LN})$	voltage gain from pin HFTX to LN	$V_{HFTX} = 15 \text{ mV} (\text{RMS})$	33.5	34.7	35.9	dB
$G_v(\text{HFRX-LSAO})$	voltage gain from pin HFRX to LSAO	$V_{HFRX} = 30 \text{ mV} (\text{RMS})$ ; $R_{GALS} = 255 \text{ k}\Omega$ ; $I_{line} = 70 \text{ mA}$	25.5	28	30.5	dB
SWR	switching range	—	—	40	—	dB
$\Delta \text{SWR}$	switching range adjustment	with $R_{SWR}$ referenced to 365 k $\Omega$	—40	—	+12	dB
$\Delta G_v(\text{tr})$	gain control range for transmit and receive amplifiers affected by the AGC; with respect to $I_{line} = 15 \text{ mA}$	$I_{line} = 70 \text{ mA}$	5.45	6.45	7.45	dB

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## BLOCK DIAGRAM

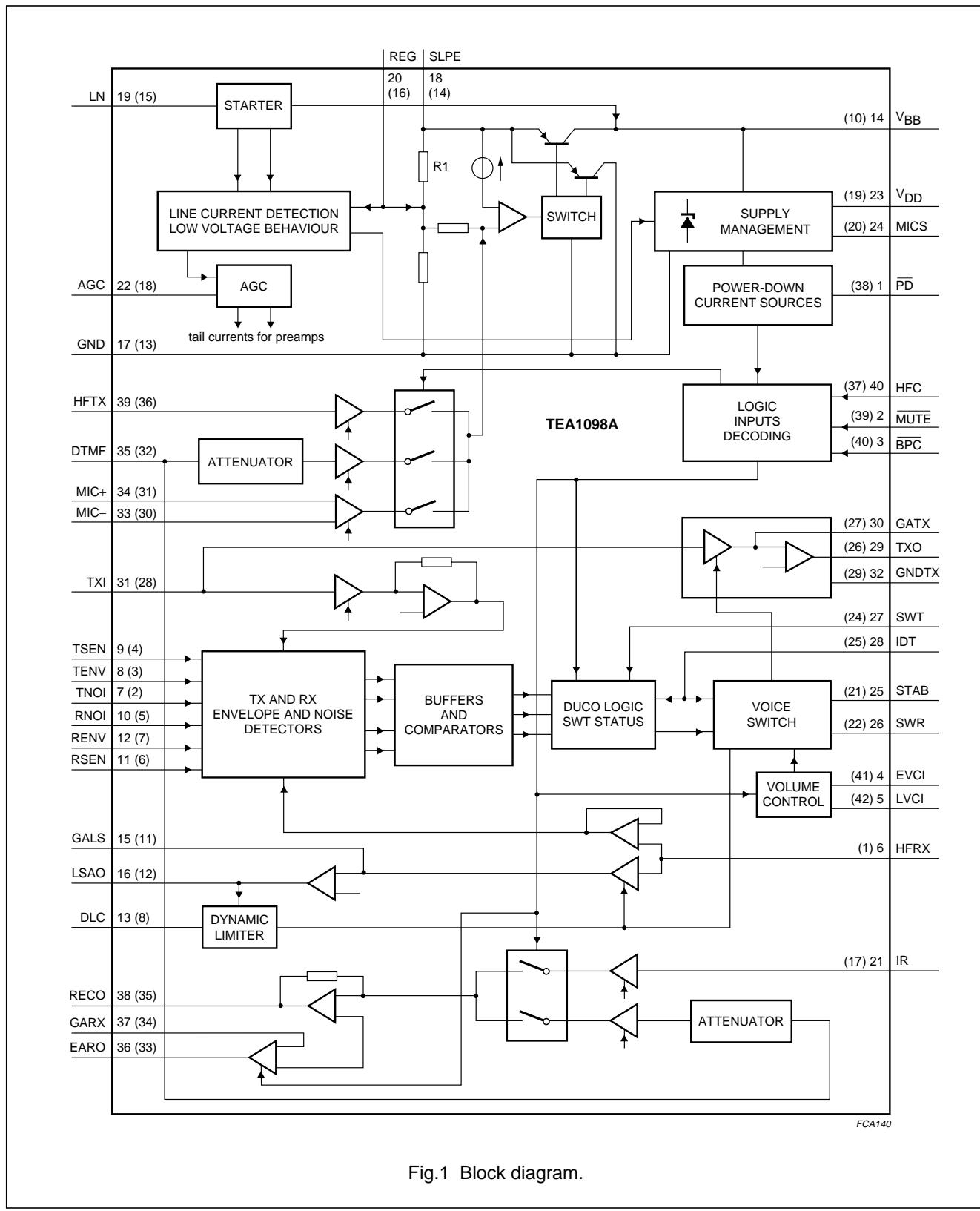


Fig.1 Block diagram.

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## PINNING

SYMBOL	PIN		DESCRIPTION
	TEA1098ATV	TEA1098AH	
PD	1	38	power-down input (active LOW)
MUTE	2	39	logic input (active LOW)
BPC	3	40	logic input (active LOW)
EVCI	4	41	logic input for digital volume control (earpiece and loudspeaker LSB)
LVCI	5	42	logic input for digital volume control (loudspeaker MSB)
n.c.	–	43	not connected
n.c.	–	44	not connected
HFRX	6	1	receive input for loudspeaker amplifier
TNOI	7	2	transmit noise envelope timing adjustment
TENV	8	3	transmit signal envelope timing adjustment
TSEN	9	4	transmit signal envelope sensitivity adjustment
RNOI	10	5	receive noise envelope timing adjustment
RSEN	11	6	receive signal envelope sensitivity adjustment
RENV	12	7	receive signal envelope timing adjustment
DLC	13	8	dynamic limiter capacitor for the loudspeaker amplifier
n.c.	–	9	not connected
V <sub>BB</sub>	14	10	stabilized supply for internal circuitry
GALS	15	11	loudspeaker amplifier gain adjustment
LSAO	16	12	loudspeaker amplifier output
GND	17	13	ground reference
SLPE	18	14	line current sense
LN	19	15	positive line terminal
REG	20	16	line voltage regulator decoupling
IR	21	17	receive amplifier input
AGC	22	18	automatic gain control/line loss compensation
V <sub>DD</sub>	23	19	3.35 V regulated voltage supply for microcontrollers
MICS	24	20	microphone supply
STAB	25	21	reference current adjustment
SWR	26	22	switching range adjustment
n.c.	–	23	not connected
SWT	27	24	switch-over timing adjustment
IDT	28	25	Idle mode timing adjustment
TXO	29	26	handsfree microphone amplifier output
GATX	30	27	handsfree microphone amplifier gain adjustment
TXI	31	28	handsfree microphone amplifier input
GNDTX	32	29	ground reference for microphone amplifiers
MIC–	33	30	negative handset microphone amplifier input
MIC+	34	31	positive handset microphone amplifier input

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SYMBOL	PIN		DESCRIPTION
	TEA1098ATV	TEA1098AH	
DTMF	35	32	dual tone multi-frequency input
EARO	36	33	earpiece amplifier output
GARX	37	34	earpiece amplifier gain adjustment
RECO	38	35	receive amplifier output
HFTX	39	36	transmit input for line amplifier
HFC	40	37	logic input

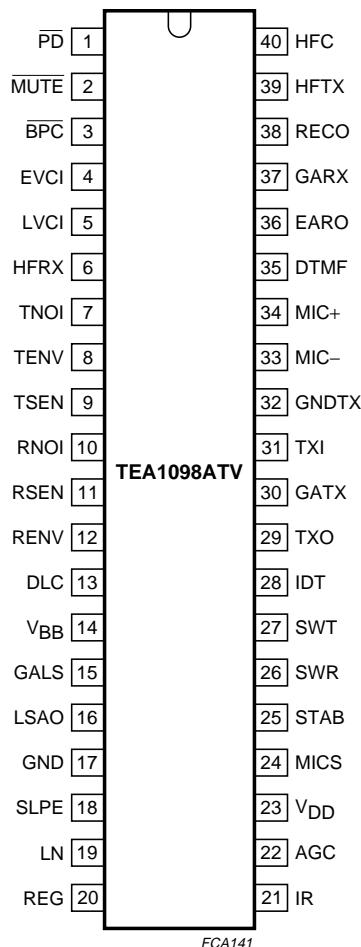


Fig.2 Pin configuration (TEA1098ATV).

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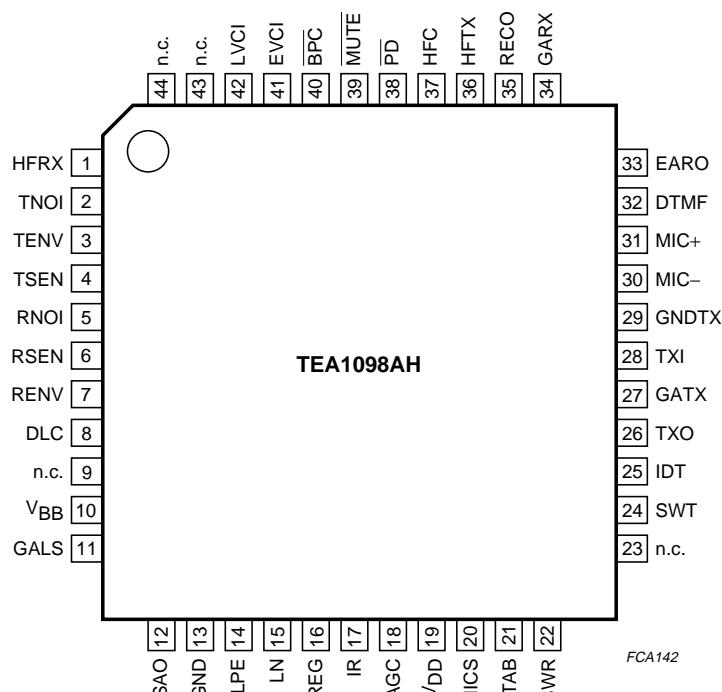


Fig.3 Pin configuration (TEA1098AH).

## FUNCTIONAL DESCRIPTION

All data given in this chapter are typical values, except when otherwise specified.

## Supplies

LINE INTERFACE AND INTERNAL SUPPLY (PINS LN, SLPE, REG AND  $V_{BB}$ )

The supply for the TEA1098A and its peripherals is obtained from the line. The IC generates a stabilized reference voltage ( $V_{ref}$ ) between pins SLPE and GND.

This reference voltage is equal to 3.7 V for line currents lower than 18 mA. It then increases linearly with the line current and reaches the value of 6.1 V for line currents higher than 45 mA. For line currents below 9 mA, the internal reference voltage generating  $V_{ref}$  is automatically adjusted to a lower value. This is the so-called low voltage area and the TEA1098A has limited performances in this area (see Section "Low voltage behaviour"). This reference voltage is temperature compensated.

The voltage between pins SLPE and REG is used by the internal regulator to generate the stabilized reference voltage and is decoupled by means of a capacitor between pins LN and REG.

This capacitor converted into an equivalent inductance realizes the set impedance conversion from its DC value ( $R_{SLPE}$ ) to its AC value (done by an external impedance).

The IC regulates the line voltage at pin LN and can be calculated as follows:

$$V_{LN} = V_{ref} + R_{SLPE} \times I_{SLPE}$$

$$I_{SLPE} = I_{line} - I^x$$

where:

$I_{line}$  = line current

$I^x$  = current consumed on pin LN (approximately a few  $\mu$ A)

$I_{SLPE}$  = current flowing through the  $R_{SLPE}$  resistor

The preferred value for  $R_{SLPE}$  is 20  $\Omega$ . Changing this value will affect more than the DC characteristics; it also influences the transmit gains to the line, the gain control characteristic, the sidetone level and the maximum output swing on the line.

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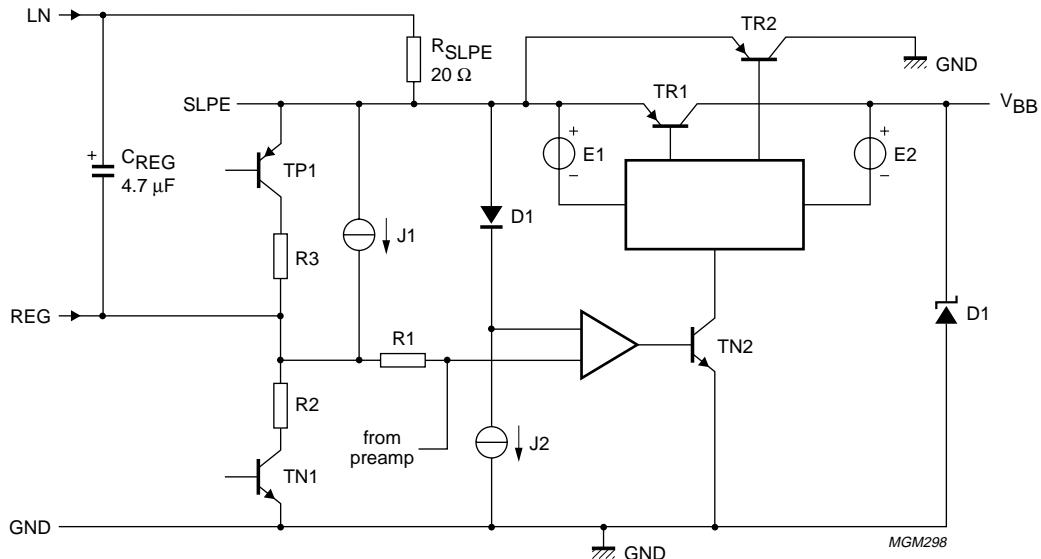


Fig.4 Line interface principle.

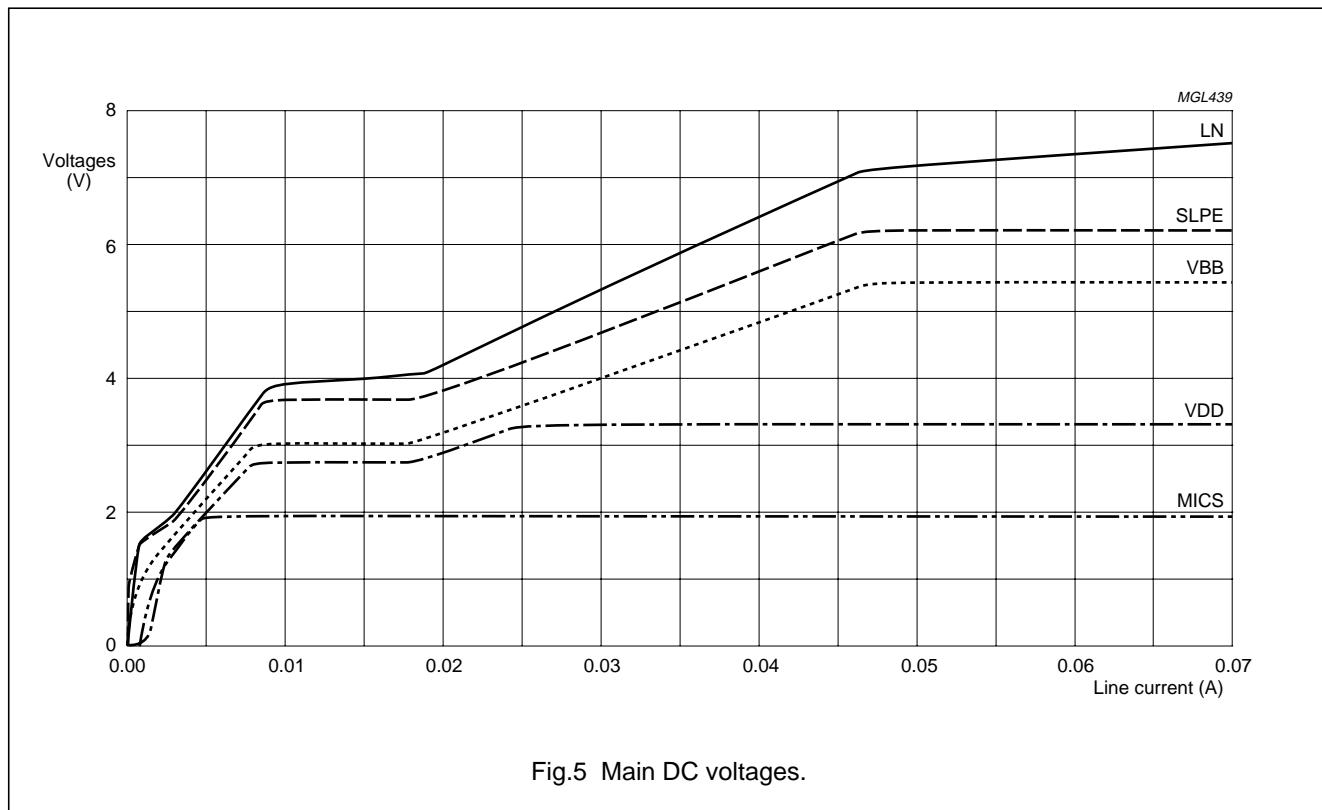
As can be seen from Fig.4, the internal circuitry is supplied by pin  $V_{BB}$ , which is a strong supply point combined with the line interface. The line current is flowing through the  $R_{SLPE}$  resistor and is sunk by the  $V_{BB}$  voltage stabilizer, thus becoming available for a loudspeaker amplifier or any peripheral IC. Its voltage is equal to 3.0 V for line currents lower than 18 mA. It then increases linearly with the line current and reaches the value of 5.3 V for line currents greater than 45 mA. It is temperature compensated.

The aim of the current switch TR1 and TR2 is to reduce distortion of large AC line signals. Current  $I_{SLPE}$  is supplied to  $V_{BB}$  via TR1 when the voltage on SLPE is greater than  $V_{BB} + 0.25$  V. When the voltage on SLPE is lower than this value, the current  $I_{SLPE}$  is shunted to GND via TR2.

The reference voltage  $V_{ref}$  can be increased by connecting an external resistor between pins REG and SLPE. For large line currents, this increase can slightly affect some dynamic performances such as maximum signal level on the line for 2% THD. The voltage on pin  $V_{BB}$  is not affected by this external resistor; see Fig.5 for the main DC voltages.

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 **$V_{DD}$  SUPPLY FOR MICROCONTROLLER (PIN  $V_{DD}$ )**

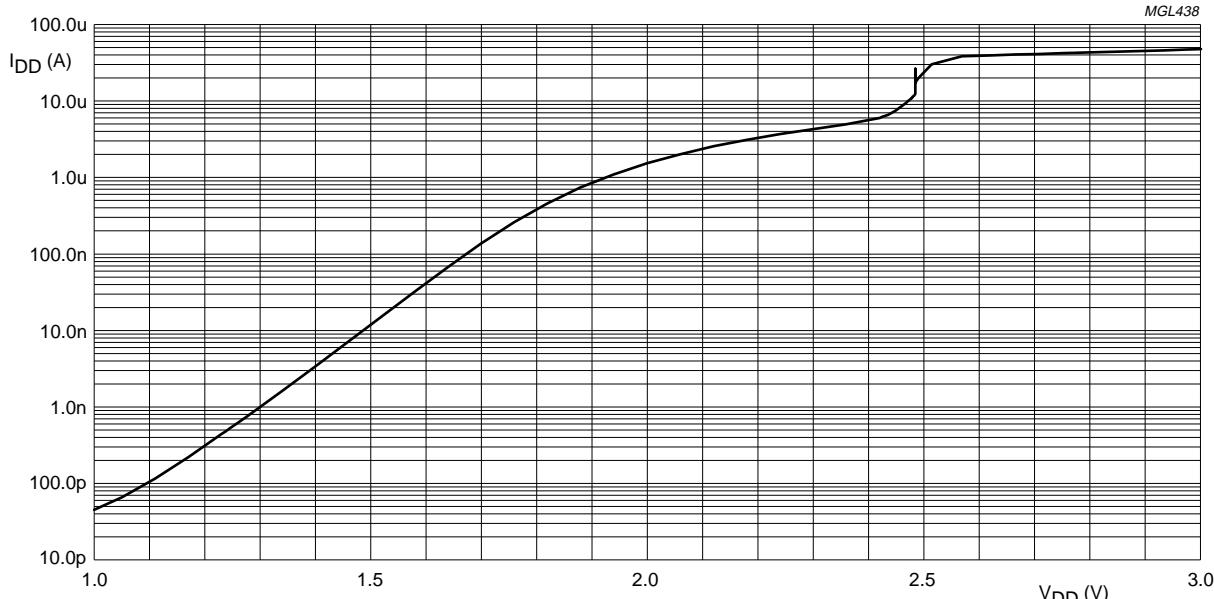
The voltage on the  $V_{DD}$  supply point follows the voltage on  $V_{BB}$  with a difference typically equal to 250 mV and is internally limited to 3.35 V. This voltage is temperature compensated. This supply point can provide a current up to 3 mA typically. Its internal consumption stays low (a few 10 nA) as long as  $V_{DD}$  does not exceed 1.5 V.

$V_{DD}$  can also be used as an input; in this case the voltage will be stabilised to 3.35 V up to 75 mA input current.

$V_{BB}$  and  $V_{DD}$  can supply external circuits in the limit of currents provided from the line, taking into account the internal current consumption.

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Fig.6 Current consumption on  $V_{DD}$ .

## SUPPLY FOR MICROPHONE (PINS MICS AND GNDTX)

The MICS output can be used as a supply for an electret microphone. Its voltage is equal to 2.0 V; it can source a current up to 1 mA and has an output impedance equal to 200  $\Omega$ .

## LOW VOLTAGE BEHAVIOUR

For line currents below 9 mA, the reference voltage is automatically adjusted to a lower value; the  $V_{BB}$  voltage follows the SLPE voltage with 250 mV difference. The excess current available for other purposes than DC biasing of the IC becomes small. In this low voltage area, the IC has limited performances.

When the  $V_{BB}$  voltage becomes lower than 2.7 V, the  $V_{BB}$  detector of the receive dynamic limiter on pin LSAO acts continuously, discharging the capacitor connected to pin DLC. In the DC condition, the loudspeaker is then automatically disabled below this voltage.

When  $V_{BB}$  goes below 2.5 V, the TEA1098A is forced into a low voltage mode whatever the levels on the logic inputs are. It is a speech mode with reduced performances only enabling the microphone channel (between the MIC inputs and LN) and the earpiece amplifier. These two channels are able to deliver signals for line currents as small as 3 mA. The HFC input is tied to GND sinking a current typically equal to 300  $\mu$ A.

POWER-DOWN MODE (PIN  $\overline{PD}$ )

To reduce consumption during dialling or register recall (flash), the TEA1098A is provided with a power-down input ( $\overline{PD}$ ). When the voltage on pin  $\overline{PD}$  is LOW, the current consumption from  $V_{BB}$  and  $V_{DD}$  is reduced to 460  $\mu$ A typically. Therefore a capacitor of 470  $\mu$ F on  $V_{BB}$  is sufficient to power the TEA1098A during pulse dialling or flash. The  $\overline{PD}$  input has a pull-up structure. In this mode, the capacitor  $C_{REG}$  is internally disconnected.

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### Transmit channels (pins MIC+, MIC-, DTMF, HFTX and LN)

#### HANDSET MICROPHONE AMPLIFIER (PINS MIC+, MIC- AND LN)

The TEA1098A has symmetrical microphone inputs. The input impedance between pins MIC+ and MIC- is typically  $70\text{ k}\Omega$ . The voltage gain between pins MIC+/MIC- and LN is set to 44.3 dB. Without limitation from the output, the microphone input stage can accommodate signals up to 18 mV (RMS) at room temperature for 2% of Total Harmonic Distortion (THD). The microphone inputs are biased at one diode voltage.

Automatic gain control is provided for line loss compensation.

#### DTMF AMPLIFIER (PINS DTMF, LN AND RECO)

The TEA1098A has an asymmetrical DTMF input. The input impedance between pins DTMF and GND is typically  $20\text{ k}\Omega$ . The voltage gain between pins DTMF and LN is set to 25.35 dB. Without limitation from the output, the input stage can accommodate signals up to 180 mV (RMS) at room temperature for 2% of THD.

When the DTMF amplifier is enabled, dialling tones may be sent on the line. These tones can be heard in the earpiece or in the loudspeaker at a low level. This is called the confidence tone. The voltage attenuation between pins DTMF and RECO is typically  $-16.5\text{ dB}$  in handsfree mode (HFC HIGH), and  $-28.2\text{ dB}$  in handset mode (HFC LOW).

The DC biasing of this input is 0 V.

The automatic gain control has no effect on these channels.

#### HANDSFREE TRANSMIT AMPLIFIER (PINS HFTX AND LN)

The TEA1098A has an asymmetrical HFTX input, which is mainly intended for use in combination with the TXO output. The input impedance between pins HFTX and GND is typically  $20\text{ k}\Omega$ . The voltage gain between pins HFTX and LN is set to 34.7 dB. Without limitation from the output, the input stage can accommodate signals up to 95 mV (RMS) at room temperature for 2% of THD. The HFTX input is biased at two diodes voltage.

Automatic gain control is provided for line loss compensation.

### Receive channels (pins IR, RECO, GARX, EARO and EVCI)

#### RX AMPLIFIER (PINS IR, RECO AND EVCI)

The receive amplifier has one input IR which is referred to the line. The input impedance between pins IR and LN is typically  $20\text{ k}\Omega$  and the DC biasing between these pins is equal to one diode voltage.

When  $\text{HFC} = 0$ , the gain between pins IR (referred to LN) and RECO is typically 17.0 dB which compensates typically 15 dB lower than attenuation of the anti-sidetone network. The receive amplifier gain can be digitally increased with the 4-level logic input EVCI, providing 4 steps of 4.85 dB which apply in all handset receive modes. Without limitation from the output, the input stage can accommodate signals up to 50 mV (RMS) at room temperature for 2% of THD.

When  $\text{HFC} = 1$ , the gain is set automatically to 29.7 dB which compensates the anti-sidetone network attenuation minus 2.3 dB.

This receive amplifier has a rail-to-rail output RECO, which is designed for use with high ohmic (real) loads (larger than  $5\text{ k}\Omega$ ). This output is biased at two diodes voltage.

Automatic gain control is provided for line loss compensation.

#### EARPIECE AMPLIFIER (PINS GARX AND EARO)

The earpiece amplifier is an operational amplifier having its output (EARO) and its inverting input (GARX) available. Its input signal comes, via a decoupling capacitor, from the receive output RECO. It is used in combination with two resistors to get the required gain or attenuation compared to the receive gain. The typical resistor ratio is 4, which gives a 12 dB gain. The gain range can be chosen between 0 dB and 20 dB.

Two external capacitors  $C_{\text{GAR}}$  (connected between pins GAR and EARO) and  $C_{\text{GARS}}$  (connected between pins GAR and GND) ensure stability. The  $C_{\text{GAR}}$  capacitor provides a first-order low-pass filter. The cut-off frequency corresponds to the time constant  $C_{\text{GAR}} \times R_{\text{E2}}$ . The relationship  $C_{\text{GARS}} \geq 10 \times C_{\text{GAR}}$  must be fulfilled.

The earpiece amplifier has a rail-to-rail output EARO, biased at two diodes voltage. It is designed for use with low ohmic (real) loads ( $150\text{ }\Omega$ ) or capacitive loads ( $100\text{ nF}$  in series with  $100\text{ }\Omega$ ).

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## AGC (pin AGC)

The TEA1098A performs automatic line loss compensation, which fits well with the true line attenuation. The automatic gain control varies the gain of some transmit and receive amplifiers in accordance with the DC line current. The control range is 6.45 dB for  $G_{V(MIC-LN)}$  and  $G_{V(IR-RECO)}$  and 6.8 dB for  $G_{V(HFTX-LN)}$ , which corresponds approximately to a line length of 5.5 km for a 0.5 mm twisted-pair copper cable.

To enable this gain control, pin AGC must be shorted to pin LN. The start current for compensation corresponds to a line current of typically 23 mA and the stop current to 57 mA. The start current can be increased by connecting an external resistor between pins AGC and LN. It can be increased up to 40 mA (using a resistor typically 80 k $\Omega$ ). The start and stop current will be maintained in a ratio equal to 2.5. By leaving the AGC pin open-circuit, the gain control is disabled and no line loss compensation is performed.

## Handsfree application

As can be seen from Fig.4, a loop is formed via the sidetone network in the line interface part and the acoustic coupling between loudspeaker and microphone of the handsfree part. When this loop gain is greater than 1, howling occurs. In a full duplex application this would be the case. The loop-gain has to be much lower than 1 and therefore has to be decreased to avoid howling.

This is achieved by the duplex controller. The duplex controller of the TEA1098A detects which channel has the 'largest' signal and then controls the gains of the microphone and loudspeaker amplifiers so that the sum of the gains remains constant.

As a result, in handsfree application, the circuit can be in three stable modes:

## 1. Transmit mode (TX mode).

The gain of the microphone amplifier is at its maximum and the gain of the loudspeaker amplifier is at its minimum.

## 2. Receive mode (RX mode).

The gain of the loudspeaker amplifier is at its maximum and the gain of the microphone amplifier is at its minimum.

## 3. Idle mode.

The gain of the amplifiers is halfway between their maximum and minimum value.

The difference between the maximum gain and minimum gain is called the switching range.

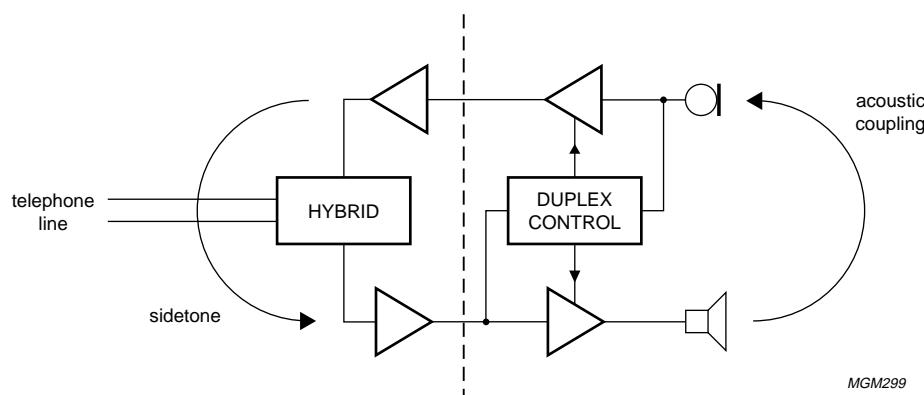


Fig.7 Handsfree telephone set principles.

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HANDSFREE MICROPHONE CHANNEL (PINS TXI, GATX, TXO AND GNDTX; SEE Fig.8)

The TEA1098A has an asymmetrical handsfree microphone input (pin TXI) with an input resistance of  $20\text{ k}\Omega$ . The DC biasing of the input is 0 V. The gain of the input stage varies according to the mode of the TEA1098A. In the transmit mode, the gain is at its maximum; in the receive mode, it is at its minimum and in the Idle mode, it is halfway between maximum and minimum.

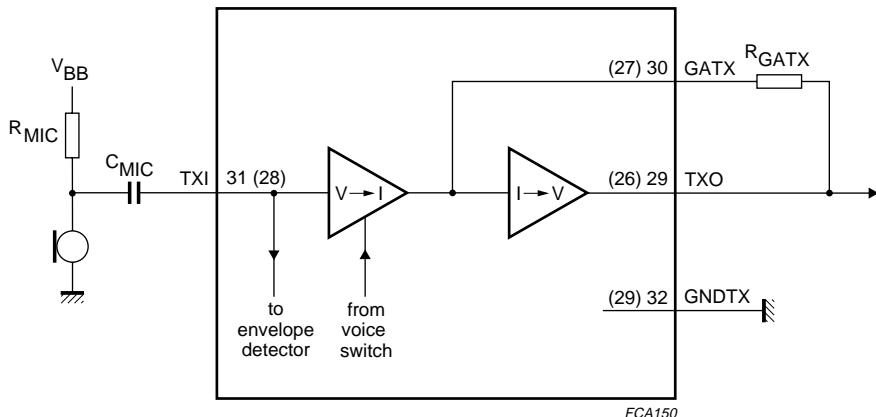


Fig.8 Handsfree microphone channel

Switch-over from one mode to the other is smooth and click-free. The output TXO is biased at two diodes voltage and has a current capability equal to 20  $\mu$ A (RMS). In the transmit mode, the overall gain of the microphone amplifier (from pins TXI to TXO) can be adjusted from 0 dB up to 31 dB to suit specific application requirements. The gain is proportional to the value of  $R_{GATX}$  and equals 15.2 dB with  $R_{GATX} = 30.1$  k $\Omega$ . Without limitation from the output, the microphone input stage can accommodate signals up to 18 mV (RMS) at room temperature for 2% of THD.

## LOUDSPEAKER CHANNEL

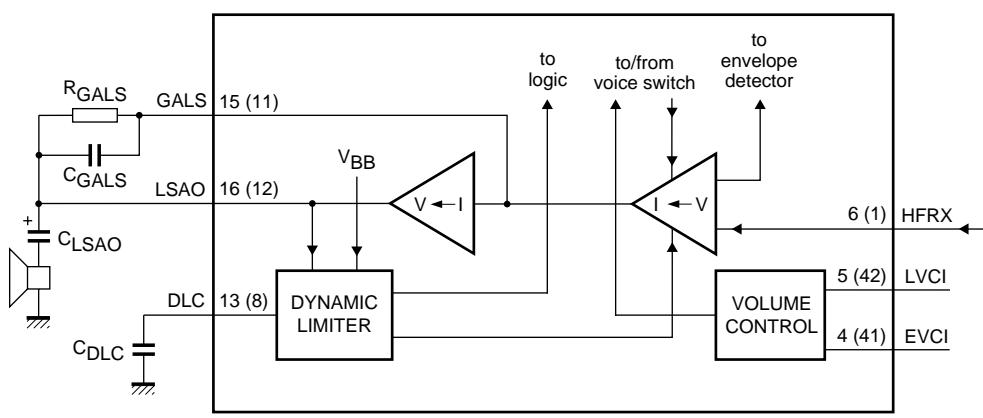


Fig. 9. Loudspeaker channel

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### *Loudspeaker amplifier (pins HFRX, GALS and LSAO)*

The TEA1098A has an asymmetrical input for the loudspeaker amplifier with an input resistance of  $20\text{ k}\Omega$  between pins HFRX and GND. It is biased at two diodes voltage. Without limitation from the output, the input stage can accommodate signals up to 580 mV (RMS) at room temperature for 2% of THD.

The gain of the input stage varies according to the mode of the TEA1098A. In the receive mode, the gain is at its maximum; in the transmit mode, it is at its minimum and in the Idle mode, it is halfway between maximum and minimum. Switch-over from one mode to the other is smooth and click-free. The rail-to-rail output stage is designed to power a loudspeaker connected as a single-ended load (between pins LSAO and GND).

In the receive mode, the overall gain of the loudspeaker amplifier can be adjusted from 0 dB up to 35 dB to suit specific application requirements. The gain from HFRX to LSAO is proportional to the value of  $R_{GALS}$  and equals 28 dB with  $R_{GALS} = 255\text{ k}\Omega$ . A capacitor connected in parallel with  $R_{GALS}$  is recommended and provides a first-order low-pass filter.

### *Digital volume control (pins LVCI and EVCI)*

The loudspeaker amplifier gain can be adjusted (attenuated) with the LVCI logic input (as MSB) and the 4-level input EVCI (as LSBs). This combination provides 8 steps of  $-4\text{ dB}$  which applies in all handsfree receive modes.

### *Dynamic limiter (pin DLC)*

The dynamic limiter of the TEA1098A prevents clipping of the loudspeaker output stage and protects the operation of the circuit when the supply voltage at  $V_{BB}$  falls below 2.7 V.

Hard clipping of the loudspeaker output stage is prevented by rapidly reducing the gain when the output stage starts to saturate. The time in which gain reduction is effected (clipping attack time) is approximately a few milliseconds. The circuit stays in the reduced gain mode until the peaks of the loudspeaker signals no longer cause saturation. The gain of the loudspeaker amplifier then returns to its normal value within the clipping release time (typically 250 ms). Both attack and release times are proportional to the value of the capacitor  $C_{DLC}$ . The total harmonic distortion of the loudspeaker output stage, in reduced gain mode, stays below 2% up to 10 dB (minimum) of input voltage overdrive [providing  $V_{HFRX}$  is below 580 mV (RMS)].

When the supply voltage drops below an internal threshold voltage of 2.7 V, the gain of the loudspeaker amplifier is rapidly reduced (approximately 1 ms). When the supply voltage exceeds 2.7 V, the gain of the loudspeaker amplifier is increased again.

By forcing a level lower than 0.2 V on pin DLC, the loudspeaker amplifier is muted and the TEA1098A is automatically forced into the transmit mode.

### DUPLEX CONTROLLER

### *Signal and noise envelope detectors (pins TSEN, TENV, TNOI, RSEN, RENV and RNOI)*

The signal envelopes are used to monitor the signal level strength in both channels. The noise envelopes are used to monitor background noise in both channels. The signal and noise envelopes provide inputs for the decision logic. The signal and noise envelope detectors are illustrated in Fig.10.

For the transmit channel, the input signal at pin TXI is 40 dB amplified to TSEN. For the receive channel, the input signal at pin HFRX is 0 dB amplified to RSEN. The signals from TSEN and RSEN are logarithmically compressed and buffered to TENV and RENV respectively.

The sensitivity of the envelope detectors is set with  $R_{TSEN}$  and  $R_{RSEN}$ . The capacitors connected in series with the two resistors block any DC component and form a first-order high-pass filter. In the basic application (see Fig.18) it is assumed that  $V_{TXI} = 1\text{ mV}$  (RMS) and  $V_{HFRX} = 100\text{ mV}$  (RMS) nominal and both  $R_{TSEN}$  and  $R_{RSEN}$  have a value of  $10\text{ k}\Omega$ . With the value of  $C_{TSEN}$  and  $C_{RSEN}$  at 100 nF, the cut-off frequency is at 160 Hz.

The buffer amplifiers feeding the compressed signals to pins TENV and RENV have a maximum source current of  $120\text{ }\mu\text{A}$  and a maximum sink current of  $1\text{ }\mu\text{A}$ . Capacitors  $C_{TENV}$  and  $C_{RENV}$  set the timing of the signal envelope monitors. In the basic application, the value of both capacitors is 470 nF. Because of the logarithmic compression, each 6 dB signal increase means 18 mV increase of the voltage on the envelopes TENV or RENV at room temperature. Thus, timings can be expressed in dB/ms. At room temperature, the  $120\text{ }\mu\text{A}$  sourced current corresponds to a maximum rise-slope of the signal envelope of 85 dB/ms. This is sufficient to track normal speech signals. The  $1\text{ }\mu\text{A}$  current sunk by TENV or RENV corresponds to a maximum fall-slope of 0.7 dB/ms. This is sufficient for a smooth envelope and also eliminates the effect of echoes on switching behaviour.

## Speech and handsfree IC

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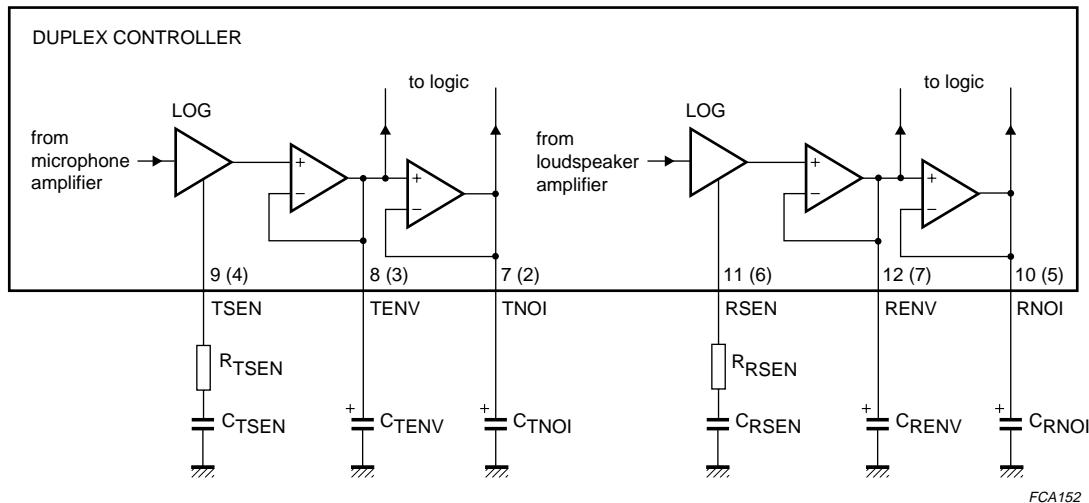


Fig.10 Signal and noise envelope detectors.

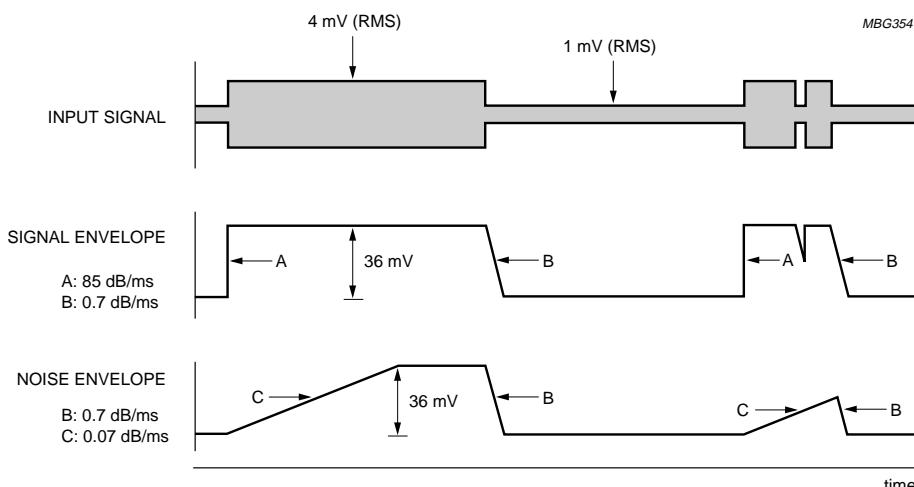


Fig.11 Signal and noise envelope waveforms.

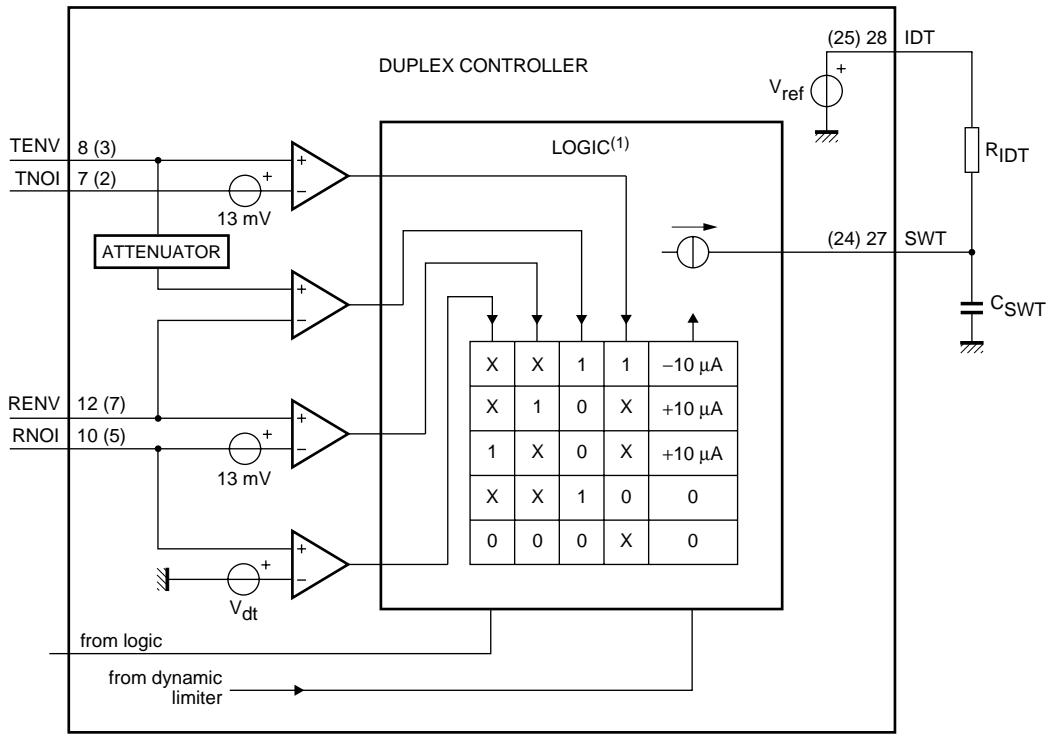
To determine the noise level, the signals on pins TENV and RENV are buffered to pins TNOI and RNOI. These buffers have a maximum source current of 1  $\mu$ A and a maximum sink current of 120  $\mu$ A. Capacitors  $C_{TNOI}$  and  $C_{RNOI}$  set the timing. In the basic application, see Fig.18, the value of both capacitors is 4.7  $\mu$ F. At room temperature, the 1  $\mu$ A sourced current corresponds to a maximum rise-slope of the noise envelope of approximately 0.07 dB/ms.

This is small enough to track background noise and not to be influenced by speech bursts. The 120  $\mu$ A current that is sunk corresponds to a maximum fall-slope of approximately 8.5 dB/ms. However, during the decrease of the signal envelope, the noise envelope tracks the signal envelope so it will never fall faster than approximately 0.7 dB/ms. The behaviour of the signal envelope and noise envelope monitors is illustrated in Fig.11.

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Decision logic (pins IDT and SWT)



(1) When DLC &lt; 0.2 V, -10 μA is forced.

Fig.12 Decision logic.

The TEA1098A selects its mode of operation (transmit, receive or Idle mode) by comparing the signal and the noise envelopes of both channels. This is executed by the decision logic. The resulting voltage on pin SWT is the input for the voice-switch.

To facilitate the distinction between signal and noise, the signal is considered as speech when its envelope is more than 4.3 dB above the noise envelope. At room temperature, this is equal to a voltage difference  $V_{ENV} - V_{NOI} = 13 \text{ mV}$ . This so-called speech/noise threshold is implemented in both channels.

The signal on pin TXI contains both speech and the signal from the loudspeaker (acoustic coupling). When receiving, the contribution from the loudspeaker overrules the speech.

As a result, the signal envelope on pin TENV is formed mainly by the loudspeaker signal. To correct this, an attenuator is connected between pin TENV and the TENV/RENV comparator. Its attenuation equals that applied to the microphone amplifier.

When a dial tone is present on the line, without monitoring, the tone would be recognized as noise because it is a signal with a constant amplitude. This would cause the TEA1098A to go into the Idle mode and the user of the set would hear the dial tone fade away. To prevent this, a dial tone detector is incorporated which, in standard applications, does not consider input signals between HFRX and GND as noise when they have a level greater than 25 mV (RMS). This level is proportional to  $R_{RSEN}$ .

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In the same way, a transmit detector is integrated which, in standard applications, does not consider input signals between pins TXI and GNDTX as noise when they have a level greater than 0.75 mV (RMS). This level is proportional to  $R_{TSEN}$ .

As can be seen from Fig.12, the output of the decision logic is a current source. The logic table gives the relationship between the inputs and the value of the current source. It can charge or discharge the capacitor  $C_{SWT}$  with a current of 10  $\mu$ A (switch-over). If the current is zero, the voltage on pin SWT becomes equal to the voltage on pin IDT via the high-ohmic resistor  $R_{IDT}$  (idling). The resulting voltage difference between pins SWT and IDT determines the mode of the TEA1098A and can vary between -400 and +400 mV (see Table 1).

**Table 1** Modes of TEA1098A

$V_{SWT} - V_{IDT}$ (mV)	MODE
<-180	transmit mode
0	Idle mode
>180	receive mode

The switch-over timing can be set with  $C_{SWT}$ , the Idle mode timing with  $C_{SWT}$  and  $R_{IDT}$ . In the basic application given in Fig.18,  $C_{SWT}$  is 220 nF and  $R_{IDT}$  is 2.2 M $\Omega$ . This enables a switch-over time from transmit to receive mode or vice-versa of approximately 13 ms (580 mV swing on pin SWT). The switch-over time from Idle mode to transmit mode or receive mode is approximately 4 ms (180 mV swing on pin SWT).

The switch-over time, from receive mode or transmit mode to Idle mode is equal to  $4 \times R_{IDT}C_{SWT}$  and is approximately 2 seconds (Idle mode time).

The input at pin DLC overrules the decision logic. When the voltage on pin DLC goes lower than 0.2 V, the capacitor  $C_{SWT}$  is discharged with 10  $\mu$ A thus resulting in the transmit mode.

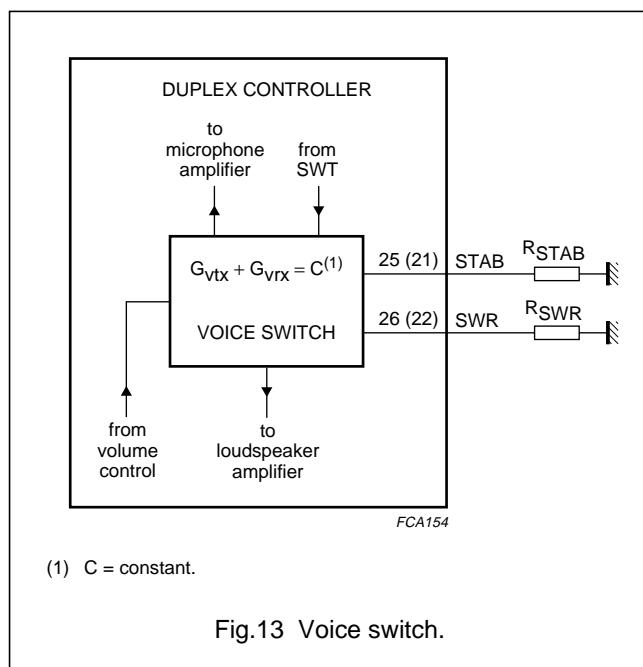
*Voice-switch (pins STAB and SWR)*

A diagram of the voice-switch is illustrated in Fig.13. With the voltage on pin SWT, the TEA1098A voice-switch regulates the gains of the transmit and the receive channels so that the sum of both is kept constant.

In the transmit mode, the gain of the microphone amplifier is at its maximum and the gain of the loudspeaker amplifier is at its minimum. In the receive mode, the opposite applies. In the Idle mode, both microphone and loudspeaker amplifier gains are halfway.

The difference between maximum and minimum is the so called switching range. This range is determined by the ratio of  $R_{SWR}$  and  $R_{STAB}$  and is adjustable between 0 and 52 dB.  $R_{STAB}$  should be 3.65 k $\Omega$  and sets an internally used reference current. In the basic application diagram given in Fig.18,  $R_{SWR}$  is 365 k $\Omega$  which results in a switching range of 40 dB. The switch-over behaviour is illustrated in Fig.14.

In the receive mode, the gain of the loudspeaker amplifier can be reduced using the volume control. Since the voice-switch keeps the sum of the gains constant, the gain of the microphone amplifier is increased at the same time (see dashed curves in Fig.14). In the transmit mode, however, the volume control has no influence on the gain of the microphone amplifier or the gain of the loudspeaker amplifier. Consequently, the switching range is reduced when the volume is reduced. At maximum reduction of volume, the switching range becomes 0 dB.



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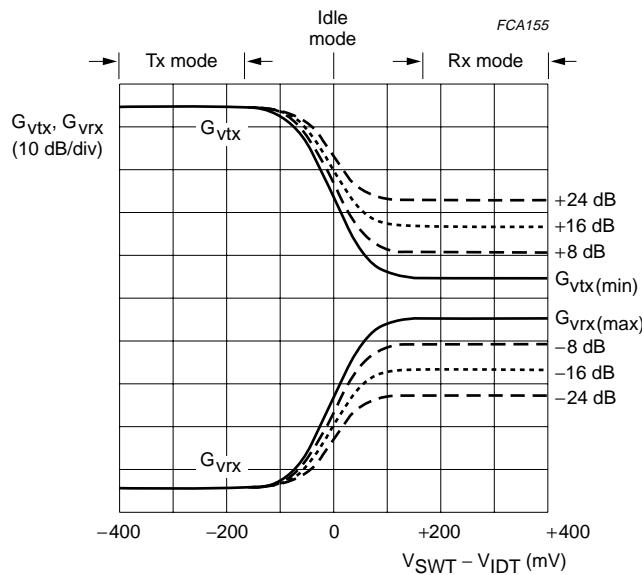


Fig.14 Switch-over behaviour.

**Logic inputs**

The actions of the logic inputs  $\overline{BPC}$  and  $\overline{MUTE}$ , combined with the HFC input are detailed in the Table 2.

**Table 2** Table of switch management

LOGIC INPUTS			FEATURES	APPLICATION
HFC	MUTE	BPC		
0	0	0	DTMF to RECO; RECO to EARO; MICS is active	handset beep mode
0	0	1	DTMF to LN; DTMF to RECO; RECO to EARO; MICS is active	handset dialling mode
0	1	0	IR to RECO; RECO to EARO; MICS is active	handset secret mode
0	1	1	MIC to LN; IR to RECO; RECO to EARO; MICS is active	handset conversation mode
1	0	0	DTMF to RECO; HFRX to LSAO; MICS is active	handsfree beep mode
1	0	1	DTMF to LN; DTMF to RECO; HFRX to LSAO; MICS is active	handsfree dialling mode
1	1	0	IR to RECO; HFRX to LSAO; MICS is active	handsfree secret mode
1	1	1	TXI to TXO; HFTX to LN; IR to RECO; HFRX to LSAO; MICS is active	handsfree conversation mode

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## LIMITING VALUES

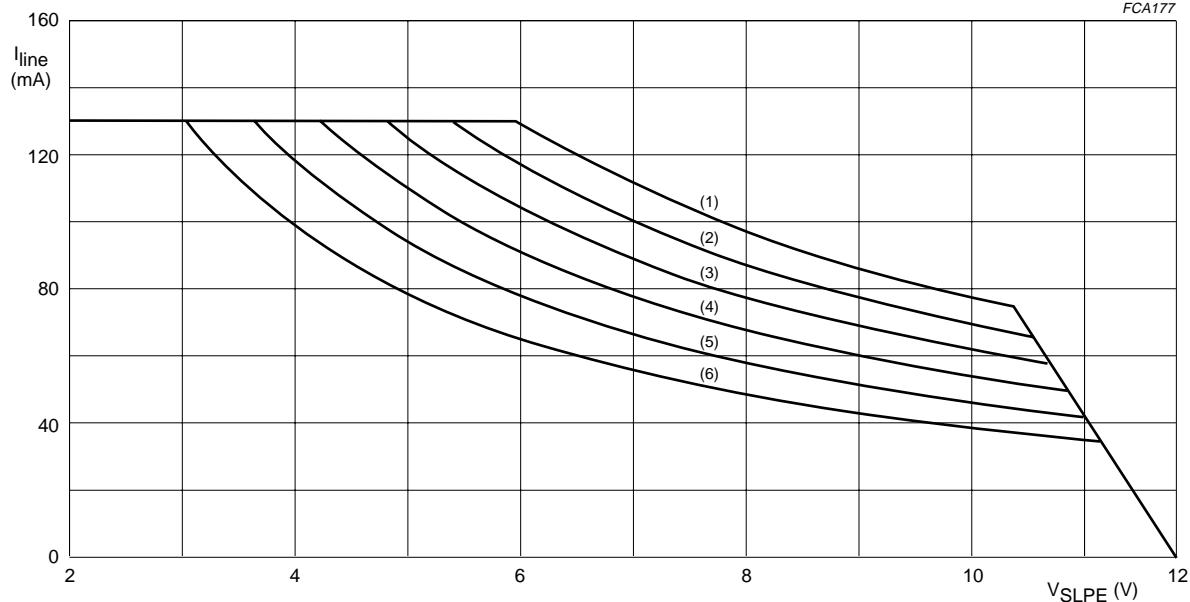
SYMBOL	PARAMETER	CONDITIONS	MIN.	MAX.	UNIT
$V_{LN}$	positive continuous line voltage		-0.4	12	V
	repetitive line voltage during switch-on or line interruption		-0.4	13.2	V
$V_{n(max)}$	maximum voltage on pins REG, SLPE, IR and AGC		-0.4	$V_{LN} + 0.4$	V
	maximum voltage on all other pins except $V_{DD}$		-0.4	$V_{BB} + 0.4$	V
$I_{line}$	maximum line current		-	130	mA
$P_{tot}$	total power dissipation	$T_{amb} = 75 \text{ }^{\circ}\text{C}$	-	400	mW
	TEA1098ATV (see Fig.15)		-	720	mW
$T_{stg}$	IC storage temperature		-40	+125	$^{\circ}\text{C}$
$T_{amb}$	ambient temperature		-25	+75	$^{\circ}\text{C}$

## THERMAL CHARACTERISTICS

SYMBOL	PARAMETER	CONDITIONS	VALUE	UNIT
$R_{th(j-a)}$	thermal resistance from junction to ambient TEA1098ATV TEA1098AH	in free air	117 66	K/W K/W

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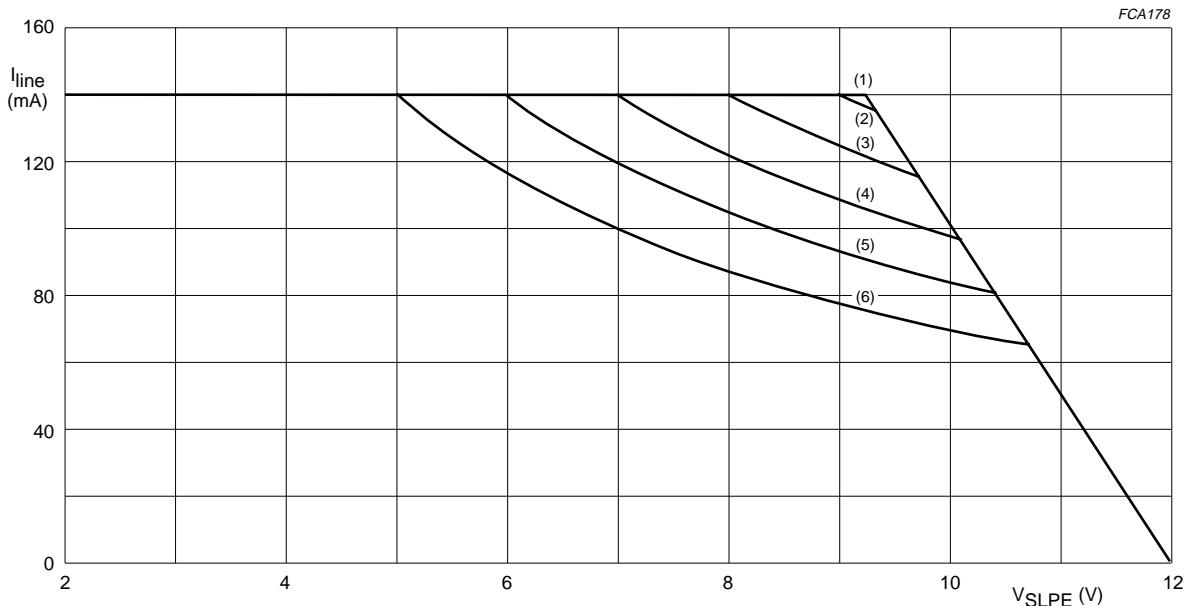


LINE	$T_{amb}$ (°C)	$P_{tot}$ (mW)
(1)	25	790
(2)	35	710
(3)	45	630
(4)	55	550
(5)	65	470
(6)	75	390

Fig.15 Safe operating area (TEA1098ATV)

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LINE	$T_{amb}$ ( $^{\circ}\text{C}$ )	$P_{tot}$ (mW)
(1)	25	1290
(2)	35	1250
(3)	45	1110
(4)	55	975
(5)	65	835
(6)	75	695

Fig.16 Safe operating area (TEA1098AH).

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## CHARACTERISTICS

$I_{line} = 15 \text{ mA}$ ;  $R_{SLPE} = 20 \Omega$ ;  $Z_{line} = 600 \Omega$ ;  $f = 1 \text{ kHz}$ ;  $T_{amb} = 25^\circ\text{C}$ ; AGC pin connected to LN;  $\overline{PD} = \text{HIGH}$ ; HFC = LOW; MUTE = HIGH;  $\overline{BPC} = \text{HIGH}$ ; all DC levels are referenced to GND; unless otherwise specified.

SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
<b>Supplies</b>						
LINE INTERFACE AND INTERNAL SUPPLY (PINS LN, SLPE, REG AND $V_{BB}$ )						
$V_{SLPE}$	stabilized voltage between SLPE and GND	$I_{line} = 15 \text{ mA}$	3.4	3.7	4	V
		$I_{line} = 70 \text{ mA}$	5.7	6.1	6.5	V
$V_{REF}$	stabilized voltage with an external resistor $R_{VA}$ between REG and SLPE	$R_{VA} = 40 \text{ k}\Omega$	—	4.5	—	V
$\Delta V_{REF}(T)$	stabilized voltage variation with temperature referenced to $25^\circ\text{C}$	$T_{amb} = -25 \text{ to } +75^\circ\text{C}$	—	$\pm 60$	—	mV
$V_{LN}$	line voltage	$I_{line} = 1 \text{ mA}$	—	1.55	—	V
		$I_{line} = 4 \text{ mA}$	—	2.35	—	V
		$I_{line} = 15 \text{ mA}$	3.7	4.0	4.3	V
		$I_{line} = 130 \text{ mA}$	—	8.7	9.3	V
$V_{BB}$	regulated supply voltage for internal circuitry	$I_{line} = 15 \text{ mA}; I_{VBB} = 0$	2.75	3.0	3.25	V
		$I_{line} = 70 \text{ mA}; I_{VBB} = 0$	4.9	5.3	5.7	V
$I_{line}$	line current for voltage increase	start current	—	18	—	mA
		stop current	—	45	—	mA
$\Delta V_{BB}(T)$	regulated voltage variation with temperature referenced to $25^\circ\text{C}$	$T_{amb} = -25 \text{ to } +75^\circ\text{C}$	—	$\pm 30$	—	mV
$I_{BB}$	current available on pin $V_{BB}$	in speech mode	—	11	—	mA
		in handsfree mode	—	9	—	mA
SUPPLY FOR PERIPHERALS (PIN $V_{DD}$ )						
$V_{DD}$	supply output voltage	$V_{BB} > 3.35 \text{ V} + 0.25 \text{ V} (\text{typ.})$	3.1	3.35	3.6	V
		otherwise	—	$V_{BB} - 0.25$	—	V
$\Delta V_{DD}(T)$	regulated voltage variation with temperature referenced to $25^\circ\text{C}$	$T_{amb} = -25 \text{ to } +75^\circ\text{C}$ ; $V_{BB} > 3.35 \text{ V} + 0.25 \text{ V} (\text{typ.})$	—	$\pm 30$	—	mV
$I_{DD}$	current consumption on $V_{DD}$	in trickle mode; $I_{line} = 0 \text{ mA}$ ; $V_{DD} = 1.5 \text{ V}$ ; $V_{BB}$ discharging	—	15	150	nA
$I_{VDD}$	current sunk from external source	in ringer mode; $I_{line} = 0$ ; $V_{DD} = 3.35 \text{ V}$	—	—	75	mA

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SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
$I_{DD(O)}$	current available for peripherals	$V_{DD} = 3.3$ V	–	–3	–	mA
<b>SUPPLY FOR MICROPHONE (PIN MICS)</b>						
$V_{MICS}$	supply voltage for a microphone		–	2.0	–	V
<b>POWER-DOWN INPUT (PIN <math>\bar{PD}</math>)</b>						
$V_{IL}$	LOW-level input voltage		–0.4	–	0.3	V
$I_{i(PD)(l)}$	input current at low voltage		–	–3	–6	$\mu$ A
$V_{IH}$	HIGH-level input voltage		1.4	–	$V_{BB} + 0.3$	V
$I_{BB(PD)}$	current consumption on $V_{BB}$ during power-down phase	$\bar{PD} = \text{LOW}$	–	460	–	$\mu$ A
<b>Preamplifier inputs (pins MIC+, MIC–, IR, DTMF, TXI, HFTX and HFRX)</b>						
$ Z_{i(MIC)} $	input impedance differential between pins MIC+ and MIC– single-ended between pins MIC+/MIC– and GND <sub>TX</sub>		–	70	–	k $\Omega$
			–	35	–	k $\Omega$
$ Z_{i(IR)} $	input impedance between pins IR and LN		–	20	–	k $\Omega$
$ Z_{i(DTMF)} $	input impedance between pins DTMF and GND		–	20	–	k $\Omega$
$ Z_{i(TXI)} $	input impedance between pins TXI and GND <sub>TX</sub>		–	20	–	k $\Omega$
$ Z_{i(HFTX)} $	input impedance between pins HFTX and GND		–	20	–	k $\Omega$
$ Z_{i(HFRX)} $	input impedance between pins HFRX and GND		–	20	–	k $\Omega$
<b>TX amplifiers</b>						
TX HANDSET MICROPHONE AMPLIFIER (PINS MIC+, MIC– AND LN)						
$G_{V(MIC-LN)}$	voltage gain from pin MIC+/MIC– to LN	$V_{MIC} = 5$ mV (RMS)	43.3	44.3	45.3	dB
$\Delta G_{V(f)}$	gain variation with frequency referenced to 1 kHz	$f = 300$ to $3400$ Hz	–	$\pm 0.25$	–	dB

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SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
$\Delta G_{v(T)}$	gain variation with temperature referenced to 25 °C	$T_{amb} = -25$ to $+75$ °C	–	$\pm 0.25$	–	dB
CMRR	common mode rejection ratio		–	80	–	dB
THD	total harmonic distortion at LN	$V_{LN} = 1.4$ V (RMS)	–	–	2	%
		$I_{line} = 4$ mA; $V_{LN} = 0.12$ V (RMS)	–	–	10	%
$V_{no(LN)}$	noise output voltage at pin LN; pins MIC+/MIC– shorted through 200 $\Omega$	psophometrically weighted (p53 curve)	–	–77	–	dB <sup>mp</sup>
$\Delta G_{v(mute)}$	gain reduction when muted	$\overline{MUTE} = 0$ ; see Table 2	60	80	–	dB
$\Delta G_{v(MIC)(mute)}$	gain reduction in microphone mute mode	$V_{MIC} = 10$ mV (RMS); $\overline{MUTE} = 1$ ; $\overline{BPC} = 0$ ; see Table 2	60	–	–	dB
DTMF AMPLIFIER (PINS DTMF, LN AND RECO)						
$G_{v(DTMF-LN)}$	voltage gain from pin DTMF to LN	$V_{DTMF} = 50$ mV (RMS)	24.35	25.35	26.35	dB
$\Delta G_{v(f)}$	gain variation with frequency referenced to 1 kHz	$f = 300$ to $3400$ Hz	–	$\pm 0.25$	–	dB
$\Delta G_{v(T)}$	gain variation with temperature referenced to 25 °C	$T_{amb} = -25$ to $+75$ °C	–	$\pm 0.25$	–	dB
$\Delta G_{v(mute)}$	gain reduction if not active	$\overline{MUTE} = 1$ ; see Table 2	60	80	–	dB
$G_{v(DTMF-RECO)}$	voltage gain from pin DTMF to RECO in handsfree mode	$V_{DTMF} = 50$ mV (RMS); $\overline{MUTE} = 0$ ; HFC = 1	–	–17	–	dB
$G_{v(DTMF-RECO)}$	voltage gain from pin DTMF to RECO in handset mode	$V_{DTMF} = 50$ mV (RMS); $\overline{MUTE} = 0$ ; HFC = 0; EVCI = 0	–	–28.2	–	dB
$\Delta G_{v(DTMF-RECO)}$	digital volume control adjustment range in handset mode	$V_{DTMF} = 50$ mV (RMS); $\overline{MUTE} = 0$ ; HFC = 0	–	–12.75	–	dB
$\Delta G_{v(DTMF-RECO)}$	digital volume control adjustment step in handset mode	$\overline{MUTE} = 0$ ; HFC = 0; per step	–	+4.25	–	dB

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SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
TX AMPLIFIER USING HFTX (PINS HFTX AND LN)						
$G_v(HFTX-LN)$	voltage gain from pin HFTX to LN	$V_{HFTX} = 15 \text{ mV (RMS)}$	33.5	34.7	35.9	dB
$\Delta G_{v(f)}$	gain variation with frequency referenced to 1 kHz	$f = 300 \text{ to } 3400 \text{ Hz}$	–	$\pm 0.25$	–	dB
$\Delta G_{v(T)}$	gain variation with temperature referenced to 25 °C	$T_{amb} = -25 \text{ to } +75^\circ\text{C}$	–	$\pm 0.35$	–	dB
THD	total harmonic distortion at LN	$V_{LN} = 1.4 \text{ V (RMS)}$	–	–	2	%
$V_{HFTX(rms)}$	maximum input voltage at HFTX (RMS value)	$I_{line} = 70 \text{ mA}; \text{THD} = 2\%$	–	85	–	mV
$V_{no(LN)}$	noise output voltage at pin LN; pin HFTX shorted to GND through 200 Ω in series with 10 μF	psophometrically weighted (p53 curve)	–	–77	–	dB <sub>mp</sub>
$\Delta G_{v(m)}$	gain reduction when muted	$\overline{\text{MUTE}} = 0$ ; see Table 2	60	80	–	dB
$\Delta G_{v(MIC)(mute)}$	gain reduction in microphone mute mode	$\overline{\text{MUTE}} = 1; \overline{\text{BPC}} = 0$ ; see Table 2	60	–	–	dB
RX amplifiers						
RX AMPLIFIERS USING IR (PINS IR AND RECO)						
$G_v(IR-RECO)(HF)$	voltage gain from IR to RECO (handsfree mode)	$V_{IR} = 4 \text{ mV (RMS)}; \text{HFC} = 1$	28.4	29.4	30.4	dB
$G_v(IR-RECO)(HS)$	voltage gain from IR to RECO (handset mode)	$V_{IR} = 4 \text{ mV (RMS)}; \text{HFC} = 0; \text{EVCI} = 0$	16.2	17.2	18.2	dB
$\Delta G_{v(IR-RECO)}$	digital volume control adjustment range in handset mode	$V_{IR} = 4 \text{ mV (RMS)}; \text{HFC} = 0; \text{EVCI} = V_{DD}$	13	14.5	16	dB
$\Delta G_{v(IR-RECO)}$	digital volume control adjustment step in handset mode	$\text{HFC} = 0$ ; per step	–	+4.85	–	dB
$\Delta G_{v(f)}$	gain variation with frequency referred to 1 kHz	$f = 300 \text{ to } 3400 \text{ Hz}$	–	$\pm 0.25$	–	dB
$\Delta G_{v(T)}$	gain variation with temperature referenced to 25 °C	$T_{amb} = -25 \text{ to } +75^\circ\text{C}$	–	$\pm 0.3$	–	dB
$V_{IR(rms)(max)}$	maximum input voltage on IR (referenced to LN) (RMS value)	$I_{line} = 70 \text{ mA}; \text{THD} = 2\%$	–	50	–	mV

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SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
$V_{RECO(rms)(max)}$	maximum output voltage on RECO (RMS value)	THD = 2%; $G_v(RECO-EARO) = 12 \text{ dB}$	0.75	0.9	—	V
$V_{no(RECO)(rms)}$	noise output voltage at pin RECO; pin IR is an open-circuit (RMS value)	psophometrically weighted (p53 curve)	—	-84	—	dBVp
$\Delta G_v(mute)$	gain reduction if not active	$\overline{MUTE} = 0$ ; see Table 2	60	80	—	dB
<b>RX EARPiece AMPLIFIER (PINS GARX AND EARO)</b>						
$\Delta G_v(RECO-EARO)$	gain voltage range between pins RECO and EARO		0	—	+20	dB
$V_{EARO(rms)(max)}$	maximum output voltage on EARO (RMS value)	sine wave drive; $R_L = 150 \Omega$ ; THD < 2%	0.75	0.9	—	V
$V_{no(EARO)(rms)}$	noise output voltage at pin EARO; pin IR is an open-circuit (RMS value)	$G_v(EARO) = 12 \text{ dB}$ ; EVCI = 0; psophometrically weighted (p53 curve)	—	-84	—	dBVp
<b>Automatic Gain Control (pin AGC)</b>						
$\Delta G_v(trx)$	gain control range for transmit and receive signals affected by the AGC; with respect to $I_{line} = 15 \text{ mA}$	$I_{line} = 70 \text{ mA}$ ; $G_v(MIC-LN)$ ; $G_v(IR-RECO)$ ; $R_{AGC} = 0$ ;	5.45	6.45	7.45	dB
		$I_{line} = 70 \text{ mA}$ for $G_v(HFTX-LN)$ ; $R_{AGC} = 0$	5.8	6.8	7.8	dB
$I_{start}$	highest line current for maximum gain		—	23	—	mA
$I_{stop}$	lowest line current for maximum gain		—	57	—	mA
$\Delta I_{start}$	$I_{start}$ adjustment range with $R_{AGC}$		—	—	40	mA
<b>Logic inputs (pins HFC, <math>\overline{MUTE}</math>, and <math>\overline{BPC}</math>)</b>						
$V_{IL}$	LOW-level input voltage		-0.4	—	0.3	V
$V_{IH}$	HIGH-level input voltage		1.4	—	$V_{BB} + 0.3$	V
$I_{i(l)}$	input current at low voltage for pin HFC for pin $\overline{MUTE}$ for pin $\overline{BPC}$	$V_{BB} = 3.0 \text{ V}$	—	0	—	$\mu\text{A}$
			—	-5	—	$\mu\text{A}$
			—	-2.5	—	$\mu\text{A}$

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SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
$I_{i(h)}$	input current at high voltage for pin HFC for pin <u>MUTE</u> for pin BPC	$V_{BB} = 3.0$ V	—	2.5	—	$\mu A$
<b>Handsfree mode (HFC = HIGH)</b>						
HF MICROPHONE AMPLIFIER (PINS TXI, TXO AND GATX)						
$G_{v(TXI-TXO)}$	voltage gain from pin TXI to TXO	$V_{TXI} = 3$ mV (RMS); $R_{GATX} = 30.1$ k $\Omega$	12.7	15.2	17.7	dB
$\Delta G_v$	voltage gain adjustment with $R_{GATX}$		-15	—	+16	dB
$\Delta G_{v(f)}$	gain variation with frequency referenced to 1 kHz	$f = 300$ to 3400 Hz	—	$\pm 0.1$	—	dB
$\Delta G_{v(T)}$	gain variation with temperature referenced to 25 °C	$T_{amb} = -25$ to +75 °C	—	$\pm 0.15$	—	dB
$V_{no(TXO)(rms)}$	noise output voltage at pin TXO; pin TXI is shorted through 200 $\Omega$ and 10 $\mu F$ to GNDTX	psophometrically weighted (p53 curve); $G_{v(TXI)} = 15$ dB; RMS value	—	-101	—	dBVp
$\Delta G_{v(mute)}$	gain reduction when muted	<u>MUTE</u> = 0; see Table 2	60	80	—	dB
$\Delta G_{v(SEC)}$	gain reduction in SECRET mode	$V_{txi} = 10$ mV (RMS); <u>MUTE</u> = 1; BPC = 0; see Table 2	60	—	—	dB
HF LOUDSPEAKER AMPLIFIER (PINS HFRX, LSAO, GALS AND DLC)						
$G_{v(HFRX-LSAO)}$	nominal voltage gain from pin HFRX to LSAO	$V_{HFRX} = 30$ mV (RMS); $R_{GALS} = 255$ k $\Omega$ ; LVCI = $V_{DD}$ ; EVCI = $V_{DD}$	24.5	27	29.5	dB
$\Delta G_{v(HFRX-LSAO)}$	digital volume control adjustment range	$V_{HFRX} = 30$ mV (RMS); $R_{GALS} = 255$ k $\Omega$	25.5	27	28.5	dB
$\Delta G_{v(step)}$	digital volume adjustment step	per step	—	3.85	—	dB
$\Delta G_v$	voltage gain adjustment with $R_{GALS}$		-28	—	+7	dB
$\Delta G_{v(f)}$	gain variation with frequency referenced to 1 kHz	$f = 300$ to 3400 Hz	—	$\pm 0.3$	—	dB
$\Delta G_{v(T)}$	gain variation with temperature referenced to 25 °C	$T_{amb} = -25$ to +75 °C	—	$\pm 0.3$	—	dB
$V_{HFRX(rms)(max)}$	maximum input voltage at pin HFRX (RMS value)	$I_{line} = 70$ mA; $R_{GALS} = 33$ k $\Omega$ ; for 2% THD in the input stage	—	580	—	mV

## Speech and handsfree IC

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SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
$V_{no( LSAO)(rms)}$	noise output voltage at pin LSAO; pin HFRX is open-circuit (RMS value)	psophometrically weighted (p53 curve); LVCI = $V_{DD}$ ; EVCI = $V_{DD}$	–	–79	–	dBVp
$\Delta G_{v(mute)}$	gain reduction if not active	see Table 2	60	–	–	dB
$V_{LSAO(rms)}$	output voltage capability at pin LSAO with sine wave signal and loaded with $50 \Omega + 220 \mu F$ ; $G_{vLSAO} = 28 \text{ dB}$	$I_{BB} = 1 \text{ mA}; I_{DD} = 1 \text{ mA}$ $I_{line} = 18 \text{ mA}$ $I_{line} = 30 \text{ mA}$ $I_{line} > 50 \text{ mA}$	– – – –	– 0.9 1.3 1.6	– – – –	V V V V
$I_{LSAO(max)}$	maximum output current at pin LSAO (peak value)		150	300	–	mA
DYNAMIC LIMITER (PINS LSAO AND DLC)						
$t_{att}$	attack time	when $V_{HFRX}$ jumps up from 20 mV to 20 mV +10 dB	–	–	5	ms
		when $V_{BB}$ drops below $V_{BB(th)}$	–	1	–	ms
$t_{rel}$	release time	when $V_{HFRX}$ jumps down from 20 mV +10 dB to 20 mV	–	100	–	ms
THD	total harmonic distortion	$V_{HFRX} = 20 \text{ mV} + 10 \text{ dB}$ ; $G_{v( LSAO)} = 28 \text{ dB}$ ; $t > t_{att}$	–	1	2	%
$V_{BB(th)}$	$V_{BB}$ limiter threshold		–	2.7	–	V
MUTE RECEIVE (PIN DLC)						
$V_{DLC(th)}$	threshold voltage required on pin DLC to obtain mute receive condition		–	–	0.2	V
$I_{DLC(th)}$	Start-up current sourced by pin DLC	$V_{DLC} = 0.2 \text{ V}$	–	100	–	$\mu A$
$\Delta G_{vrx(m)}$	voltage gain reduction in mute receive condition	$V_{DLC} = 0.2 \text{ V}$	60	80	–	dB
TX AND RX ENVELOPE AND NOISE DETECTORS (PINS TSEN, TENV, TNOI, RSEN, RENV AND RNOI)						
Preamplifiers						
$G_{v(TSEN)}$	voltage gain from pin TXI to TSEN		–	40	–	dB
$G_{v(RSEN)}$	voltage gain from pin HFRX to RSEN		–	0	–	dB

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SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
<i>Logarithmic compressor and sensitivity adjustment</i>						
$\Delta V_{\text{det}(\text{TSEN})}$	sensitivity detection on pin TSEN; voltage change on pin TENV when doubling the current from TSEN	$I_{\text{TSEN}} = 0.8 \text{ to } 160 \mu\text{A}$	—	18	—	mV
$\Delta V_{\text{det}(\text{RSEN})}$	sensitivity detection on pin RSEN; voltage change on pin RENV when doubling the current from RSEN	$I_{\text{RSEN}} = 0.8 \text{ to } 160 \mu\text{A}$	—	18	—	mV
<i>Signal envelope detectors</i>						
$I_{\text{source}(\text{ENV})}$	maximum current sourced from pin TENV or RENV		—	120	—	$\mu\text{A}$
$I_{\text{sink}(\text{ENV})}$	maximum current sunk by pin TENV or RENV		-1.25	-1	-0.75	$\mu\text{A}$
$\Delta V_{\text{ENV}}$	voltage difference between RENV and TENV	10 $\mu\text{A}$ sourced from both RSEN and TSEN; signal detectors tracking; note 1	—	$\pm 3$	—	mV
<i>Noise envelope detectors</i>						
$I_{\text{source}(\text{NOI})}$	maximum current sourced from pin TNOI or RNOI		0.75	1	1.25	$\mu\text{A}$
$I_{\text{sink}(\text{NOI})}$	maximum current sunk by pin TNOI or RNOI		—	-120	—	$\mu\text{A}$
$\Delta V_{\text{NOI}}$	voltage difference between pins RNOI and TNOI	when 5 $\mu\text{A}$ is sourced from both RSEN and TSEN; noise detectors tracking; note 1	—	$\pm 3$	—	mV
DIAL TONE DETECTOR						
$V_{\text{HFRX}(\text{th})(\text{rms})}$	threshold level at pin HFRX (RMS value)	$R_{\text{RSEN}} = 10 \text{ k}\Omega$ ; $C_{\text{RSEN}} = 100 \text{ nF}$	—	25	—	mV
TX LEVEL LIMITER						
$V_{\text{TXI}(\text{th})(\text{rms})}$	threshold level at pin TXI (RMS value)	$R_{\text{TSEN}} = 10 \text{ k}\Omega$	—	0.75	—	mV
DECISION LOGIC (PINS IDT AND SWT)						
<i>Signal recognition</i>						
$\Delta V_{\text{Strx}(\text{th})}$	threshold voltage between RENV/RNOI or between TENV/TNOI to switch-over from Idle mode to RX/TX mode	$V_{\text{HFRX}} < V_{\text{HFRX}(\text{th})}$ ; $V_{\text{TXI}} < V_{\text{TXI}(\text{th})}$ ; note 2	—	13	—	mV

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SYMBOL	PARAMETER	CONDITIONS	MIN.	TYP.	MAX.	UNIT
<i>Switch-over</i>						
$I_{\text{source(SWT)}}$	current sourced from pin SWT when switching to receive mode		7.5	10	12.5	$\mu\text{A}$
$I_{\text{sink(SWT)}}$	current sunk by pin SWT when switching to transmit mode		-12.5	-10	-7.5	$\mu\text{A}$
$I_{\text{idle(SWT)}}$	current sourced from pin SWT in Idle mode		-	0	-	$\mu\text{A}$
VOICE SWITCH (PINS STAB AND SWR)						
SWR	switching range		-	40	-	dB
$\Delta\text{SWR}$	switching range adjustment	with $R_{\text{SWR}}$ referenced to 365 k $\Omega$	-40	-	+12	dB
$ \Delta G_v $	voltage gain variation from active modes to Idle mode	SWRA = 40 dB	-	$\pm 20$	-	dB
$G_{\text{tr}}$	gain tracking ( $G_{\text{vtx}} + G_{\text{vrx}}$ ) during switching, referred to Idle mode		-	$\pm 0.5$	-	dB

## Notes

1. Corresponds to  $\pm 1$  dB tracking.
2. Corresponds to 4.3 dB noise/speech recognition level.

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## TEST AND APPLICATION INFORMATION

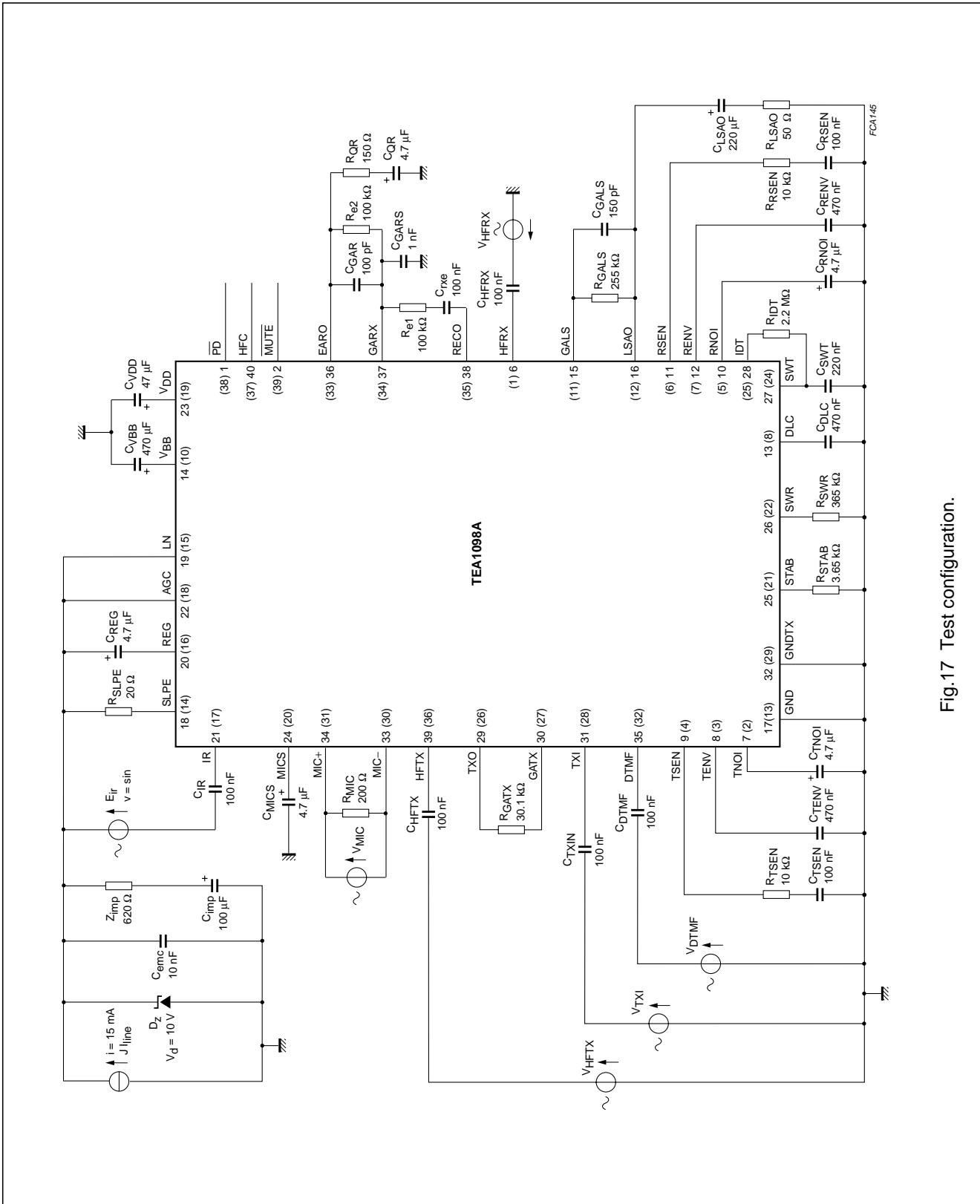


Fig.17 Test configuration.

## Speech and handsfree IC

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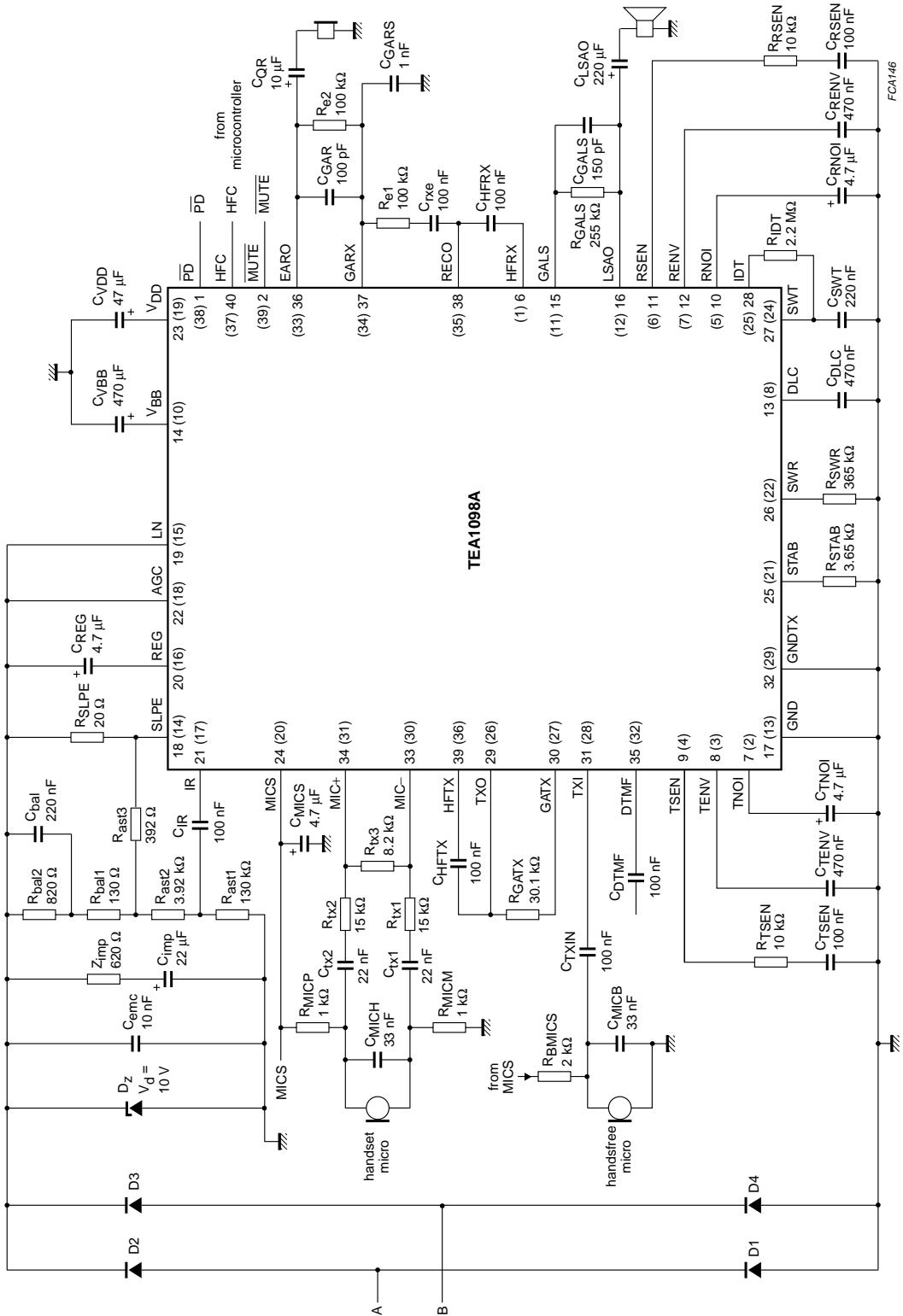


Fig.18 Basic application diagram.

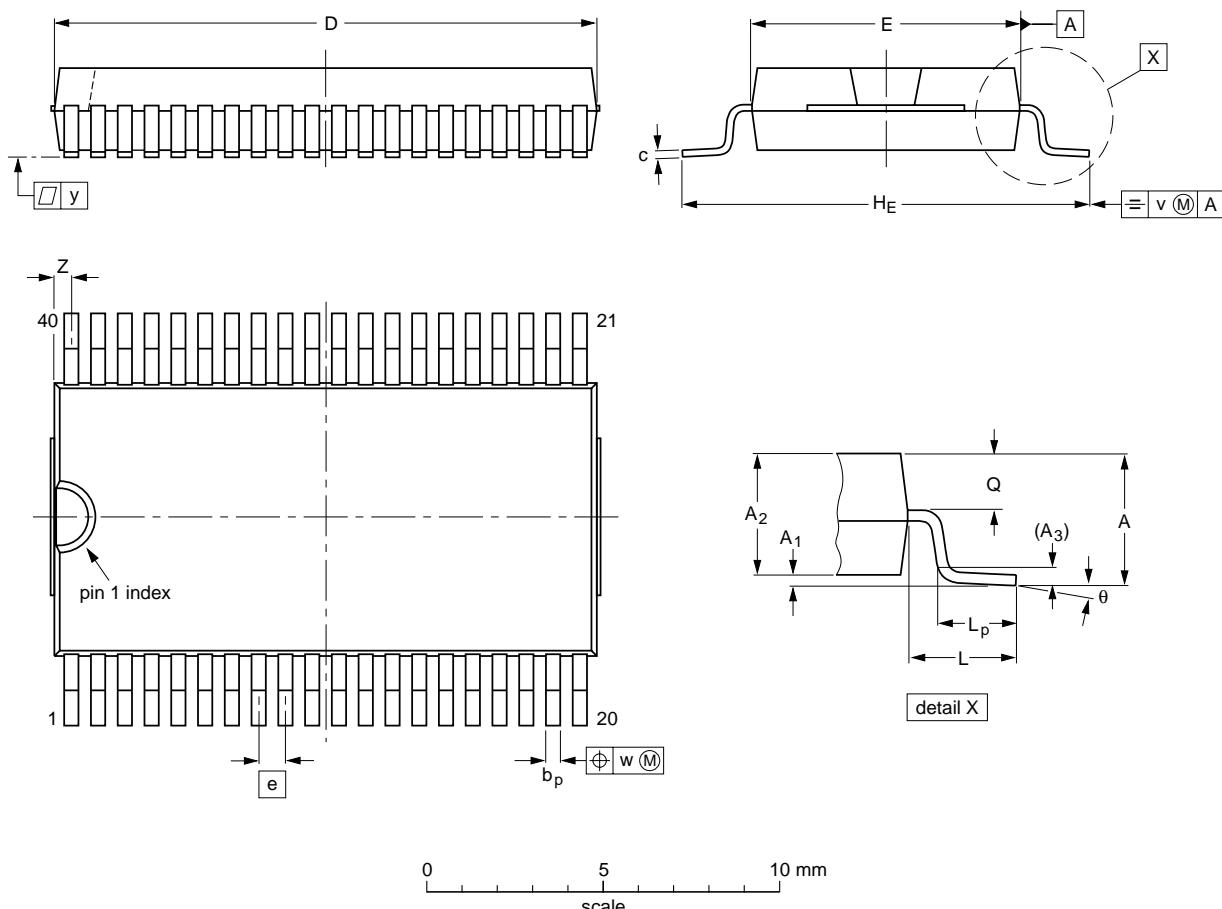
## Speech and handsfree IC

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## PACKAGE OUTLINES

VSO40: plastic very small outline package; 40 leads

SOT158-1



## DIMENSIONS (inch dimensions are derived from the original mm dimensions)

UNIT	A max.	A <sub>1</sub>	A <sub>2</sub>	A <sub>3</sub>	b <sub>p</sub>	c	D <sup>(1)</sup>	E <sup>(2)</sup>	e	H <sub>E</sub>	L	L <sub>p</sub>	Q	v	w	y	z <sup>(1)</sup>	θ
mm	2.70 0.1	0.3 0.1	2.45 2.25	0.25	0.42 0.30	0.22 0.14	15.6 15.2	7.6 7.5	0.762	12.3 11.8	2.25	1.7 1.5	1.15 1.05	0.2	0.1	0.1	0.6 0.3	7° 0°
inches	0.11 0.004	0.012 0.089	0.096 0.089	0.010	0.017 0.012	0.0087 0.0055	0.61 0.60	0.30 0.29	0.03	0.48 0.46	0.089	0.067 0.059	0.045 0.041	0.008	0.004	0.004	0.024 0.012	

## Notes

1. Plastic or metal protrusions of 0.4 mm maximum per side are not included.
2. Plastic interlead protrusions of 0.25 mm maximum per side are not included.

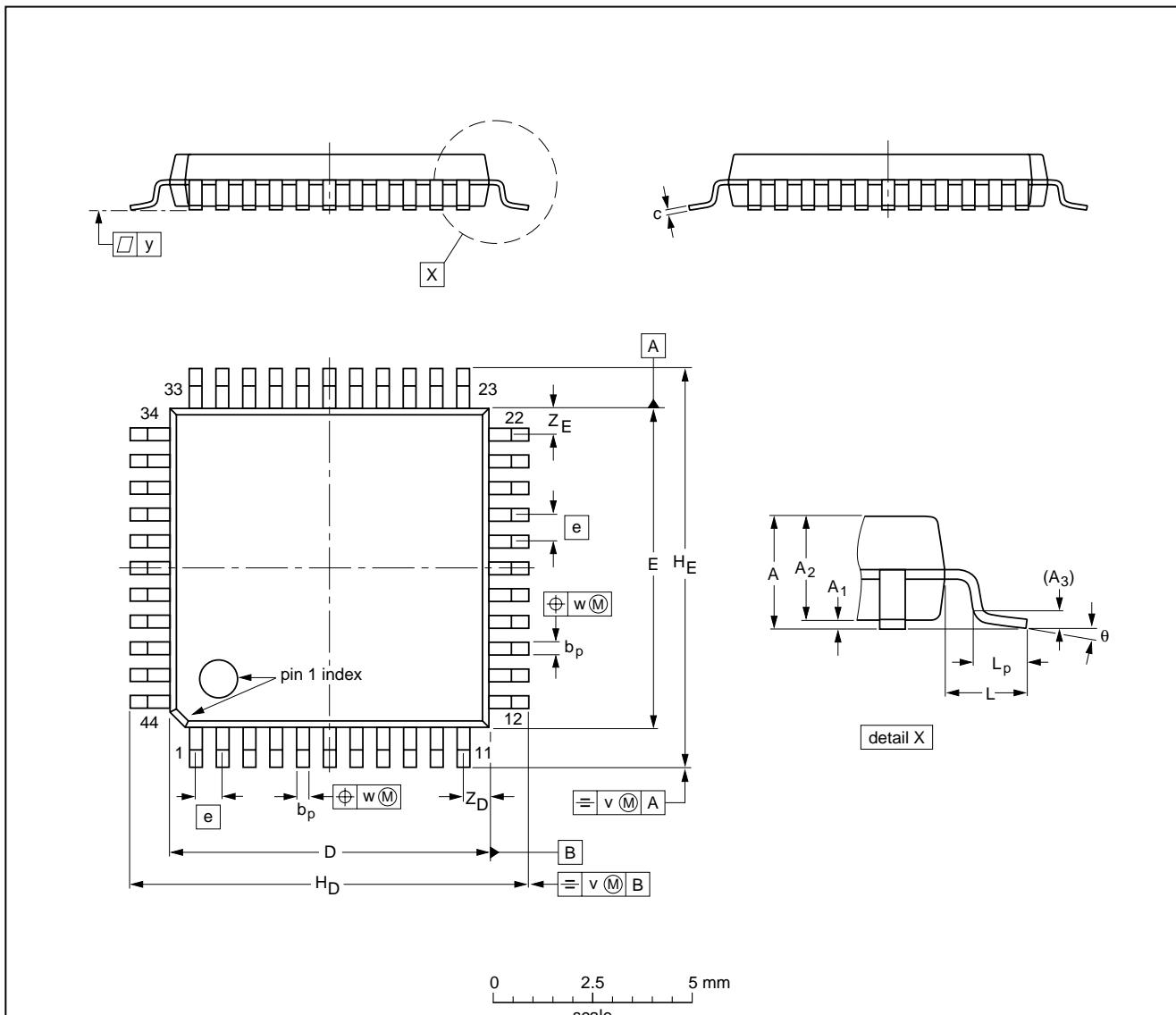
OUTLINE VERSION	REFERENCES				EUROPEAN PROJECTION	ISSUE DATE
	IEC	JEDEC	EIAJ			
SOT158-1						92-11-17 95-01-24

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QFP44: plastic quad flat package; 44 leads (lead length 1.3 mm); body 10 x 10 x 1.75 mm

SOT307-2



## DIMENSIONS (mm are the original dimensions)

UNIT	A max.	A <sub>1</sub>	A <sub>2</sub>	A <sub>3</sub>	b <sub>p</sub>	c	D <sup>(1)</sup>	E <sup>(1)</sup>	e	H <sub>D</sub>	H <sub>E</sub>	L	L <sub>p</sub>	v	w	y	Z <sub>D</sub> <sup>(1)</sup>	Z <sub>E</sub> <sup>(1)</sup>	θ
mm	2.10 0.05	0.25 1.65	1.85 0.25	0.25	0.40 0.20	0.25 0.14	10.1 9.9	10.1 9.9	0.8	12.9 12.3	12.9 12.3	1.3	0.95 0.55	0.15	0.15	0.1	1.2 0.8	1.2 0.8	10° 0°

## Note

1. Plastic or metal protrusions of 0.25 mm maximum per side are not included.

OUTLINE VERSION	REFERENCES				EUROPEAN PROJECTION	ISSUE DATE
	IEC	JEDEC	EIAJ			
SOT307-2						95-02-04 97-08-01

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### SOLDERING

#### Introduction

There is no soldering method that is ideal for all IC packages. Wave soldering is often preferred when through-hole and surface mounted components are mixed on one printed-circuit board. However, wave soldering is not always suitable for surface mounted ICs, or for printed-circuits with high population densities. In these situations reflow soldering is often used.

This text gives a very brief insight to a complex technology. A more in-depth account of soldering ICs can be found in our *"Data Handbook IC26; Integrated Circuit Packages"* (order code 9398 652 90011).

#### Reflow soldering

Reflow soldering techniques are suitable for all VSO packages.

Reflow soldering requires solder paste (a suspension of fine solder particles, flux and binding agent) to be applied to the printed-circuit board by screen printing, stencilling or pressure-syringe dispensing before package placement.

Several techniques exist for reflowing; for example, thermal conduction by heated belt. Dwell times vary between 50 and 300 seconds depending on heating method. Typical reflow temperatures range from 215 to 250 °C.

Preheating is necessary to dry the paste and evaporate the binding agent. Preheating duration: 45 minutes at 45 °C.

#### Wave soldering

Wave soldering techniques can be used for all VSO packages if the following conditions are observed:

- A double-wave (a turbulent wave with high upward pressure followed by a smooth laminar wave) soldering technique should be used.
- The longitudinal axis of the package footprint must be parallel to the solder flow.
- The package footprint must incorporate solder thieves at the downstream end.

During placement and before soldering, the package must be fixed with a droplet of adhesive. The adhesive can be applied by screen printing, pin transfer or syringe dispensing. The package can be soldered after the adhesive is cured.

Maximum permissible solder temperature is 260 °C, and maximum duration of package immersion in solder is 10 seconds, if cooled to less than 150 °C within 6 seconds. Typical dwell time is 4 seconds at 250 °C.

A mildly-activated flux will eliminate the need for removal of corrosive residues in most applications.

#### Repairing soldered joints

Fix the component by first soldering two diagonally-opposite end leads. Use only a low voltage soldering iron (less than 24 V) applied to the flat part of the lead. Contact time must be limited to 10 seconds at up to 300 °C. When using a dedicated tool, all other leads can be soldered in one operation within 2 to 5 seconds between 270 and 320 °C.

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### DEFINITIONS

<b>Data sheet status</b>	
Objective specification	This data sheet contains target or goal specifications for product development.
Preliminary specification	This data sheet contains preliminary data; supplementary data may be published later.
Product specification	This data sheet contains final product specifications.
<b>Limiting values</b>	
Limiting values given are in accordance with the Absolute Maximum Rating System (IEC 134). Stress above one or more of the limiting values may cause permanent damage to the device. These are stress ratings only and operation of the device at these or at any other conditions above those given in the Characteristics sections of the specification is not implied. Exposure to limiting values for extended periods may affect device reliability.	
<b>Application information</b>	
Where application information is given, it is advisory and does not form part of the specification.	

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