## DSP Evaluation Platform

The HSP－EVAL is the mother board for a set of daughter boards based on the HSPxxxxx family of Digital Signal Processing products．Each product specific daughter board is mated with the HSP－EVAL to provide a mechanism for rapid evaluation and prototyping．As shown in Figure 1，the HSP－EVAL consists of a series of busses which provide input，output，and control to the target daughter board． These busses are brought out through dual 96 Pin connectors to support daisy chaining HSP－EVALs for multichip prototyping and evaluation．

For added flexibility，the input and control busses can be driven by registers on－board the HSP－EVAL which have been down loaded with data via the parallel port of an IBM PC ${ }^{\top M}$ or compatible．In addition，a Shift Register is provided to serialize data on the daughter board output busses for reading into the PC via the status lines of the parallel port． Together，the I／O and Control Registers can be used to drive the target daughter board with a PC based vector set while collecting daughter board outputs to the PC＇s disk．

Jumper selectable clock sources provide three different methods of clocking the part under evaluation．In mode one， the clock signal is generated under PC based software control．In mode two，the HSP－EVAL＇s on－board oscillator may be selected as the clock source．In mode three，the user may provide an external clock through the 96 Pin Input Connector．

The HSP－EVAL was built into a 3U Euro－Card form factor with dual 96 Pin Input／Output connectors．The I／O connectors conform to the VME J2／P2 connector standard．

## Features

－Single HSP－EVAL May be Used to Evaluate a Variety of Parts Within the HSPXXXXX Family of DSP Products
－May be Daisy Chained to Support Evaluation of Multi－Chip Solutions
－Parallel Port Interface to Support IBM PC™ Based Evaluation and Control
－Three Clocking Modes for Flexibility in Performance Analysis and Prototyping
－Dual 96－Pin Input／Output Connectors Conforming to the VME J2／P2 Connector Standard

## Applications

－PC Based Performance Analysis of HSPXXXXX Family of DSP Products
－Rapid Prototyping

## DSP Evaluation Platform



## Getting Started

The HSP-EVAL was designed to operate in conjunction with daughter boards designed for the HSPXXXXX family of DSP products. A simple procedure for assembly and operation of the target daughter board with the HSP-EVAL is described in the respective daughter board's User's Manual. What follows in this document is a detailed description of the HSP-EVAL and its operation.

## Bus Structure

The HSP-EVAL utilizes a series of 16-bit busses for daughter board input, output and control as shown in Figure 1. The input and output busses interface the daughter board to the outside world through 96 Pin DIN connectors conforming to the VME J2/P2 connector standard. Daughter board control is provided by register driven control busses down loaded with data via the parallel port of a PC. For added flexibility, the input busses may also be register driven with down loaded data.

Two input busses, IN1_0-15 and IN2_0-15, bring data from the 96 Pin DIN connector (P1) to the daughter board through the 50 position Input Connector (J1). Each input bus is 16 bits wide and the signal mapping for the above connectors is given in Tables 1 and 3. As an alternative, the input busses may be driven by registers which have been down loaded with data through the Parallel Port Bus.

Two output busses, OUT1_0-15 and OUT2_0-15, carry daughter board output from the 50 Pin Output Connector
(J2) to the 96 Pin DIN connector (P2). Each output bus is 16 bits wide and the signal mapping for the above connectors is given in Tables 2 and 4. A shift register is provided to serialize data on the output busses for transmission via the Parallel Port Bus.

A status bus, STAT0-3, maps four status outputs from the daughter board Output Connector J2 to the Configuration Jumper Field (J4). The Configuration Jumper Field is used to select one of the four status lines for transmission via the Parallel Port Bus (see Configuration Jumper Field Section).

The two control busses, IN3_0-15 and CTLO-15, connect a set of registers to the 50 Pin Control Connector (J3). Each control bus is 16 bits wide and the signal mapping for the J3 Control Connector is shown in Table 5. The four least significant bits of the CTLO-15 bus are also used to control the operation of the HSP-EVAL (see Register Structure Section). As with the registers driving the input busses, the registers driving the control busses are down loaded with data via the Parallel Port Bus.

## Parallel Port Bus

The Parallel Port Bus carries the data and signals required to support bidirectional data transfers between the HSPEVAL and the parallel port of an IBM PC or compatible. The port bus contains eight data lines, PCD0-7, two control lines, PCWR0-1, and three serial output lines, PCRD0-2. The control and data lines are used to down load data into the HSPEVAL's on board registers via the Parallel Port Interface. The serial output lines carry daughter board status and output serialized by the On Board Shift Register.


FIGURE 1. BLOCK DIAGRAM OF HSP-EVAL

TABLE 1. PIN ASSIGNMENTS FOR 96 PIN INPUT CONNECTOR P1

| PIN NUMBER | ROW A SIGNAL MNEMONI | ROW B SIGNAL MNEMONIC | ROW C SIGNAL MNEMONIC |
| :---: | :---: | :---: | :---: |
| 1 | AUXINO | $\mathrm{V}_{\mathrm{CC}}$ | GND |
| 2 | IN2_0 | GND | IN2_1 |
| 3 | IN2_2 | N.C. | IN2_3 |
| 4 | IN2_4 | N.C. | IN2_5 |
| 5 | IN2_6 | N.C. | IN2_7 |
| 6 | GND | N.C. | IN2_8 |
| 7 | IN2_9 | N.C. | IN2_10 |
| 8 | IN2_11 | N.C. | IN2_12 |
| 9 | IN2_13 | N.C. | IN2_14 |
| 10 | IN2_15 | N.C. | GND |
| 11 | AUXIN1 | N.C. | IN1_0 |
| 12 | IN1_1 | GND | IN1_2 |
| 13 | IN1_3 | $\mathrm{V}_{\mathrm{CC}}$ | IN1_4 |
| 14 | IN1_5S | N.C. | IN1_6 |
| 15 | IN1_7 | N.C. | GND |
| 16 | IN1_8 | N.C. | IN1_9 |
| 17 | IN1_10 | N.C. | IN1_11 |
| 18 | IN1_12 | N.C. | IN1_13 |
| 19 | IN1_14 | N.C. | IN1_15 |
| 20 | GND | N.C. | CLKIN |
| 21 | GND | N.C. | N.C. |
| 22 | GND | GND | N.C. |
| 23 | GND | N.C. | N.C. |
| 24 | GND | N.C. | N.C. |
| 25 | GND | N.C. | N.C. |
| 26 | PCD0 | N.C. | PCD1 |
| 27 | PCD2 | N.C. | PCD3 |
| 28 | PCD4 | N.C. | PCD5 |
| 29 | PCD6 | N.C. | PCD7 |
| 30 | PCWR0 | N.C. | GND |
| 31 | PCWR1 | GND | PCRD0 |
| 32 | PCRD1 | $\mathrm{V}_{\mathrm{CC}}$ | PCRD2 |

TABLE 2. PIN ASSIGNMENTS FOR 96 PIN OUTPUT CONNECTOR P2

| PIN NUMBER | ROW A SIGNAL MNEMONIC | ROW B SIGNAL MNEMONIC | ROW C SIGNAL MNEMONIC |
| :---: | :---: | :---: | :---: |
| 1 | AUXOUTO | $\mathrm{V}_{\mathrm{CC}}$ | GND |
| 2 | OUT2_0 | GND | OUT2_1 |
| 3 | OUT2_2 | N.C. | OUT2_3 |
| 4 | OUT2_4 | N.C. | OUT2_5 |
| 5 | OUT2_6 | N.C. | OUT2_7 |
| 6 | GND | N.C. | OUT2_8 |
| 7 | OUT2_9 | N.C. | OUT2_10 |
| 8 | OUT2_11 | N.C. | OUT2_12 |
| 9 | OUT2_13 | N.C. | OUT2_14 |
| 10 | OUT2_15 | N.C. | GND |
| 11 | AUXOUT1 | N.C. | OUT1_0 |
| 12 | OUT1_1 | GND | OUT1_2 |
| 13 | OUT1_3 | $\mathrm{V}_{\mathrm{CC}}$ | OUT1_4 |
| 14 | OUT1_5 | N.C. | OUT1_6 |
| 15 | OUT1_7 | SN.C. | GND |
| 16 | OUT1_8 | N.C. | OUT1_9 |
| 17 | OUT1_10 | N.C. | OUT1_11 |
| 18 | OUT1_12 | N.C. | OUT1_13 |
| 19 | OUT1_14 | N.C. | OUT1_15 |
| 20 | GND | N.C. | CLKOUT |
| 21 | GND | N.C. | STAT0 |
| 22 | GND | GND | STAT1 |
| 23 | GND | N.C. | STAT2 |
| 24 | GND | N.C. | STAT3 |
| 25 | GND | N.C. | N.C. |
| 26 | PCDO | N.C. | PCD1 |
| 27 | PCD2 | N.C. | PCD3 |
| 28 | PCD4 | N.C. | PCD5 |
| 29 | PCD6 | N.C. | PCD7 |
| 30 | PCWRO | N.C. | GND |
| 31 | PCWR1 | GND | PCRD0 |
| 32 | PCRD1 | $\mathrm{V}_{\mathrm{CC}}$ | PCRD2 |

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The Parallel Port Bus is interfaced to the PC by connecting the provided ribbon cable between the 26 position shrouded header (J5) and the PC's parallel port. The ribbon cable maps the Parallel Port Bus signals to the PC's parallel port as shown in Table 6.

The Parallel Port Bus is brought out through each of the 96 Pin DIN connectors (P1, P2) so that Multiple HSP-EVALs can be daisy chained. This allows different HSP-EVALs in the chain to be controlled through a single HSP-EVAL which has been connected to a host PC.

## Register Structure

The HSP-EVAL provides a series of registers which may be used as a source for daughter board input and control. In addition, a Shift Register is supplied to serialize data on the daughter board output bus for transmission via the Parallel Port Bus. Data transfers involving these registers are described in the following sections.

The HSP-EVAL has a set of eight 8-bit data registers which are organized as a set of four "logical" input and control registers, Input Registers 1 thru 3 and the CTL Control Register. The outputs of these registers drive four 16 bit busses which are mapped to the daughter board through the Input Connector (J1) and the Control Connector (J3) (see Bus Structure Section). The mapping of the 8 -bit data registers to bus signals and "logical" registers is given in Table 7.

TABLE 4. SIGNAL ASSIGNMENTS FOR 50 POSITION OUTPUT CONNECTOR J2

| PIN NUMBER | J2A SIGNAL MNEMONIC | J2B SIGNAL MNEMONIC |
| :---: | :---: | :---: |
| 1 | AUXOUT0 | GND |
| 2 | OUT2_0 | OUT2_1 |
| 3 | OUT2_2 | OUT2_3 |
| 4 | OUT2_4 | OUT2_5 |
| 5 | OUT2_6 | OUT2_7 |
| 6 | GND | OUT2_8 |
| 7 | OUT2_9 | OUT2_10 |
| 8 | OUT2_11 | OUT2_12 |
| 9 | OUT2_13 | OUT2_14 |
| 10 | OUT2_15 | GND |
| 11 | AUXOUT1 | OUT1_0 |
| 12 | OUT1_1 | OUT1_2 |
| 13 | OUT1_3 | OUT1_4 |
| 14 | OUT1_5 | OUT1_6 |
| 15 | OUT1_7 | GND |
| 16 | OUT1_8 | OUT1_9 |
| 17 | OUT1_10 | OUT1_11 |
| 18 | OUT1_12 | OUT1_13 |
| 19 | OUT1_14 | OUT1_15 |
| 20 | GND | CLKOUT |
| 21 | GND | STATO |
| 22 | GND | STAT1 |
| 23 | GND | STAT2 |
| 24 | GND | STAT3 |
| 25 | GND | N.C. |

The registers driving the control and input busses may be three-stated when it is desired to drive those busses through the 96 Pin Input Connector or headers on the target daughter board. The registers driving a particular bus are three-stated by removing the respective Output Enable jumper in the J4 Configuration Jumper Field (see Configuration Jumper Field).

The HSP-EVAL's two 16-bit output busses can be serialized by a 32-bit shift register for reading via the Parallel Port Bus. The CTL Control Register governs the loading and clocking of data out of the shift register. The mapping of this register to the output busses is shown in Table 8.

TABLE 5. SIGNAL ASSIGNMENTS FOR 50 POSITION CONTROL CONNECTOR J3

| PIN NUMBER | J3A SIGNAL MNEMONIC | J3B SIGNAL MNEMONIC |
| :---: | :---: | :---: |
| 1 | N.C. | GND |
| 2 | IN3_0 | IN3_1 |
| 3 | IN3_2 | IN3_3 |
| 4 | IN3_4 | IN3_5 |
| 5 | IN3_6 | IN3_7 |
| 6 | GND | IN3_8 |
| 7 | IN3_9 | IN3_10 |
| 8 | IN3_11 | IN3_12 |
| 9 | IN3_13 | IN3_14 |
| 10 | IN3_15 | GND |
| 11 | N.C. | CTLO |
| 12 | CTL1 | CTL2 |
| 13 | CTL3 | CTL4 |
| 14 | CTL5 | CTL6 |
| 15 | CTL7 | GND |
| 16 | CTL8 | CTL9 |
| 17 | CTL10 | CTL11 |
| 18 | CTL12 | CTL13 |
| 19 | CTL14 | CTL15 |
| 20 | GND | N.C. |
| 21 | GND | N.C. |
| 22 | GND | N.C. |
| 23 | GND | N.C. |
| 24 | GND | N.C. |
| 25 | GND | N.C. |

## Down Loading Data via Parallel Port Interface

The four "logical" control and input registers are down loaded by a series of single byte writes to the to the Parallel Port Interface. The Parallel Port Interface consists of two decoders, an 8-bit address register, and an 8-bit holding register. The on-board registers are down loaded by first writing data to the Parallel Port Interface's holding register followed by two writes to the Interface's Address Register. By writing the address register, data in the holding register is loaded into one of the eight registers on-board the HSPEVAL. The address register specifies the particular register for loading, as well as the board address of the HSP-EVAL targeted for the data download. The HSP-EVAL board address is selected in the J4 Jumper Field (see Configuration Jumper Field Section), and the memory map for the 8 data registers is shown in Table 7. The bit map for the Parallel Port Interface's Address Register is given in Table 9.

The Parallel Port Interface's address and holding registers are loaded with data from the PCD0-7 data lines of the Parallel Port Bus by a "low" to "high" transition on the appropriate bus control line. Specifically, the Interface's Address Register is loaded with data when a "low" to "high" transition occurs on the PCWR0 line of the Parallel Port Bus, and the holding register is loaded by a like transition on the PCWR1 line. The mapping of the Parallel Port Bus signals mentioned above to the PC's parallel port is given in Table 6.

TABLE 6. SIGNAL MAPPING SFOR 27 PIN SHROUDED HEADER J5

|  | J6A SIGNAL MNEMONIC | J6B SIGNAL MNEMONIC |
| :---: | :---: | :---: |
| 1 | N.C. | N.C. |
| 2 | PCD0 (D0) | N.C. |
| 3 | PCD1 (D1) | PCWRO (INIT PRINTER) |
| 4 | PCD2 (D2) | PCWR1 (SELECT IN) |
| 5 | PCD3 (D3) | GND |
| 6 | PCD4 (D4) | GND |
| 7 | PCD5 (D5) | GND |
| 8 | PCD6 (D6) | GND |
| 9 | PCD7 (D7) | GND |
| 10 | N.C. | GND |
| 11 | PCRD0 (BUSY) | GND |
| 12 | PCRD2 (PAPER END) | GND |
| 13 | PCRD1 (SELECT) | GND |

NOTE: BM PC compatible parallel port signals are shown in parenthesis.

As an example, consider the loading of the least significant byte of the "Logical" Input Register, Input Register 1, as shown by the Timing Diagram in Figure 2. First, data is down loaded to the Parallel Port Interface's Holding Register. Next, the address register is written with a value which contains the address of the LSB Register for Input Register 1 (see Table 7 for memory map), the HSP-EVAL board address (assumed to be zero in this example), and a "high" in the LD bit position (see Table 9 for Address Register Bit Map). Finally, data is latched into the targeted register by rewriting the address register with the same board and register address but with a "low" in the LD bit position. The "high/low" transition of the LD bit loads the data in the holding register into the target data register on the specified HSP-EVAL.

TABLE 7. SHIFT REGISTER TO OUTPUT BUS MAPPINGS

| SHIFT REGISTER <br> BITS <br> (MSBIT-LSBIT) | REGISTER TO BUS <br> SIGNAL MAPPING <br> (MSBIT-LSBIT) | DESCRIPTION |
| :---: | :---: | :--- |$|$| $15-0$ | OUT2_15-0 | DATA ON OUTPUT <br> BUS 2 |
| :---: | :---: | :---: |
| $31-16$ | OUT1_31-16 | DATA ON OUTPUT <br> BUS 1 |

TABLE 8. ADDRESS REGISTER BIT MAP

| NOT USED | LD BIT | BOARD <br> ADDRESS | REGISTER <br> ADDRESS |
| :---: | :---: | :---: | :---: |
| D7 | D6 | D5-3 | D2-0 |

## Up Loading Data via PC's Parallel Port

Data is up loaded to the host PC through the "Busy", "Paper End", and "Select" status lines of the PC's parallel port. The PC up loads data by monitoring the state of the PCRD0-2 serial output lines on the HSP-EVAL's Parallel Port Bus. The mapping of the parallel port status lines to the Parallel Port Busses serial output lines is given in Table 6. The serial output lines are driven by daughter board output and status as specified by jumper placement in the J4 Configuration Jumper Field.

By monitoring the Parallel Port Bus's PCRD2 line, a PC up loads data on the HSP_EVAL's output busses which has been serialized by the Output Shift Register. The Shift Register is loaded by a "low" to "high" transition on the CTL3 bit of the CTL Control Register. Once the Shift Register has been loaded, data is clocked out by "low" to "high" transitions on the CTL2 bit of the CTL Register. The timing relationship between CTL2-3 for loading and clocking data out of the Shift Register is shown in Figure 3. The data in the Shift Register is output to the PCRD2 line of the HSP-EVAL's Parallel Port Bus by inserting a jumper in the SR_RD position of the J4 Configuration Jumper Field. The PCRD2 line is monitored by the "Paper End" status line of the PC's parallel port.
The HSP-EVAL can be configured such that one of the four Status Bus Lines STAT0-3 is selected for monitoring via the PCRD0-1 lines of the Parallel Port Bus. To select one of the Status Bus lines for output, a jumper is inserted in one of the STAT0-3 positions of the J4 Jumper Configuration Field.
The selected status line drives a flip-flop which is configured to function as an R/S latch (see U17, page 2, of the schematics). A "low" state on the selected status line sets the output of the flip-flop "high" when the CTL1 bit of the CTL Control Register is "high". The output of the latch remains "high" until it is reset by forcing the CTL1 bit "low" while the status input is "high". This structure is used to capture the occurrence of a "low" state on a status line which is normally "high". The output of the flip-flop drives either the PCRD0 or PCRD1 lines of the Parallel Port Bus by placing a jumper at either the PCRD0 or PCRD1 positions in the J4 Configuration Jumper Field.

TABLE 9. REGISTER TO INPUT/CONTROL BUS MAPPINGS

| REGISTER ADDRESS | REGISTER BITS <br> (MSB-LSB) | REGISTER TO BUS <br> SIGNAL MAPPING <br> (MSB-LSB) | REGISTER TO <br> CONNECTOR <br> MAPPING | LOGICAL REGISTER <br> MAPPING |
| :---: | :---: | :--- | :--- | :--- |
| 0 | $7-0$ | IN3_7-0 | $\mathrm{J3}$ | INPUT REGISTER 3 (LSBYTE) |
| 1 | $7-0$ | IN3_15-8 | J 3 | INPUT REGISTER 3 (MSBYTE) |
| 2 | $7-0$ | IN2_7-0 | J | INPUT REGISTER 2 (LSBYTE) |
| 3 | $7-0$ | IN2_15-8 | J | INPUT REGISTER 2 (MSBYTE) |
| 4 | $7-0$ | CTL7-0 | $\mathrm{J3}$ | CTL CONTROL REGISTER <br> (LSBYTE) |
| 5 | $7-0$ | CTL15-8 | $\mathrm{J3}$ | CTL CONTROL REGISTER <br> (MSBYTE) |
| 6 | $7-0$ | IN1_7-0 | J | INPUT REGISTER 1 (LSBYTE) |
| 7 | $7-0$ | IN1_15-8 | J | INPUT REGISTER 1 (MSBYTE) |



FIGURE 2. TIMING DIAGRAM FOR A LOADING DATA INTO LSBYTE OF INPUT REGISTER 1

## Daughter Board Clocking Modes

The HSP-EVAL provides the daughter board with one of three jumper selectable clock sources. The three clock choices consist of an on-board oscillator, a user provided external clock, and a clock generated by toggling the LSB of the CTL Control Register. The clock source is select by placing a jumper in the Clock Select Portion of the J4 Configuration Jumper Field. The selected clock source is provided to the daughter board through the J1 Input Connector. To support applications in which multiple HSPEVALs are daisy chained together, a clock output line is routed from the Daughter Board Output Connector J2 to the HSP-EVAL's 96 Pin Output Connector P2.

The on-board oscillator is selected as a clock source by inserting a jumper at the OSC_CLK position in the J4 jumper field. In this mode, the oscillator on-board the HSP-EVAL is supplied as a clock to the daughter board. Since data
transfers to the daughter board via the HSP-EVAL's I/O registers are much slower than the daughter board's data rate using the oscillator clock, the HSP-EVAL is used to provide the daughter board with asynchronous control in this mode.

An external clock may be selected by inserting a jumper at the EXT_CLK position in the J4 Jumper Field. In this mode, an external clock supplied to the CLKIN Pin of the 96 Pin Input Connector is provided to the daughter board. This configuration supports the use of a common clock between daisy-chained HSP-EVALs by wiring CLKOUT from the P2 Output Connector of one board to the CLKIN pin of another board's P1 Input Connector. Since there is no synchronization between the externally provided clock and data transfers to the HSP-EVAL's I/O Registers, the HSPEVAL typically provides the daughter board with asynchronous control in this mode.

The LSB of the CTL Control Register is selected as the clock source if a jumper is inserted in the CTL0 position of the J4 Configuration Jumper field. In this mode, the clock signal is generated by using register writes to toggle the CTLO bit. Since the clock may be controlled by software, input and Control Register writes and the Output Shift Register reads can be performed synchronously with the clock. Consequently, the HSP-EVAL, in combination with a daughter board can be used as a hardware modeler where input and output data vectors are transferred via a PC's parallel port.

## Configuration Jumper Field

The HSP-EVAL is configured for operation by placing jumpers in the Configuration Jumper Field (J4). As shown in Figure 4, the jumper field has areas dedicated for clock selection, register output enables, board address selection, and daughter board output selection. The default jumper placement is shown as an overlay on the jumper field schematic in Figure 4. Each HSP-EVAL leaves the factory jumpered with the default configuration.


FIGURE 3. TIMING DIAGRAMS FOR SHIFT REGISTER I/O

The Clock Select jumpers are used to specify one of the three available daughter board clocking modes. These include EXT_CLK for selection of an external clock source, OSC_CLK for selection of the on board oscillator clock, and CTLO for selection of a register driven clock using the LSB of the CTL Control Register. The clocking modes are described in the Daughter Board Clocking Modes Section of this manual. Note: Only one clock source may be jumpered at a time.

The Output Enable jumpers control the outputs of the registers driving the four input and control busses (see Bus and Register Structure Sections). The outputs of the "logical" Input and Control Registers, Input Registers 1 thru 3 and the CTL Control Register, are enabled by placing jumpers at the OE_BUS1, OE_BUS2, OE_BUS3, OECTLLO, and OECTLHI positions respectively. The two eight bit registers which make up the CTL Control Register are enabled separately by using OECTLHI to enable CTL8-15 and OECTLLO to enable CTLO-7. If a jumper is removed, the output of the respective register is three-stated.


The Board Address Jumpers are used to specify the HSPEVAL board address used for data transfers via the Parallel Port Bus. An address from 0 to 7 may be selected by inserting a jumper in positions ADDR0 thru ADDR7 respectively. Only one jumper may be inserted in this field.

The Output Select jumpers are used to configure the mapping from the daughter board output and status busses to the serial output lines of the Parallel Port Bus. The mapping of the Status Bus to the Parallel Port Bus is achieved by first selecting the desired Status Bus signal and then selecting the desired Parallel Port Bus serial output line. This mapping is achieved by inserting a jumper to select one of the four status lines, STAT0 thru STAT3, and then specifying the serial output line by inserting a jumper at either the PCRD0 or PCRD1 position. Only one of the four status lines may be selected for output to the Parallel Port Bus. The output of the 32-bit Shift Register is selected for output via the PCRD2 line of the Parallel Port Bus by inserting a jumper in the SR_RD position.

## HSP-EVAL Limited Warranty

Intersil warrants the HSP-EVAL to be free of defects in material and workmanship under normal use for a period of ninety (90) days. Intersil also warrants that the HSP-EVAL User's Manual is substantially complete and contains all the information which Intersil considers necessary to use the HSP-EVAL, and that the HSP-EVAL functions substantially as described in the HSP-EVAL User's Manual. Intersil will replace the HSP-EVAL as Intersil' sole duty under this warranty only if you ship it, postage prepaid, to Intersil within 90 days of such acquisition and provide proof of date of acquisition.

This limited warranty does not extend to any products which have been damaged as a result of accident, misuse, abuse, or as a result of service or modification by anyone other than Intersil or Intersil's' authorized representatives.

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Intersil reserves the right to revise and make changes to this manual and the HSP-EVAL from time to time without obligation to notify any person of, or to provide any person with, such revisions or changes.

HSP-EVAL


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