# **INT201**

# **High-side Driver IC**

# Floating Inputs Floating High-side Drive

### **Product Highlights**

#### **Floating Control Inputs**

- Connects directly to INT200 or INT202 HSD outputs
- No external level translators or transformers required

#### Gate Drive Output for an External MOSFET

- Provides 300 mA sink/150 mA source current
- Can drive MOSFET gate at up to 15 V
- Floating source for driving high-side N-channel MOSFET
- External MOSFET allows flexibility in design for various motor sizes

#### **Built-in Protection Circuits**

- Logic inputs include noise rejection circuitry
- Undervoltage lockout

### **Description**

The INT201 high-side driver IC provides gate drive for an external high-side MOSFET switch. When used in conjunction with the INT200 or INT202 low-side drivers, the INT201 provides a simple, cost-effective interface between low-voltage control logic and high-voltage loads.

Built-in noise rejection circuitry shared between the INT201 and the INT200 or INT202 provides reliable operation in the harshest industrial environments. The INT201 is powered from a ground-referenced low-voltage supply. A floating supply is derived from this rail by using a simple bootstrap technique to provide adequate gate drive for the external N-channel MOSFET.

Applications include motor drives, electronic ballasts, and uninterruptible power supplies. The INT201 can also be used to implement full-bridge and multi-phase configurations.

The INT201 is available in 8-pin plastic DIP and SOIC packages.



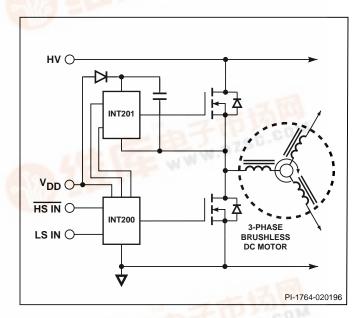


Figure 1. Typical Application.

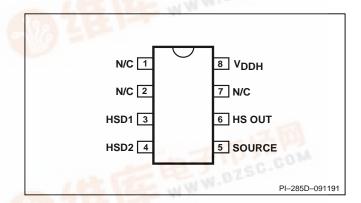


Figure 2. Pin Configuration.

ORDERING INFORMATION			
PART NUMBER	PACKAGE OUTLINE	TEMP RANGE	
INT201PFI	P08A	-40 to 85°C	
INT201TFI	T08A	-40 to 85°C	



### **Pin Functional Description**

#### **Pin 1:**

No connection.

#### **Pin 2:**

No connection.

#### **Pin 3:**

Level shift input HSD 1 works in conjunction with HSD 2 to provide interface from the low side control logic and to give noise immunity.

#### **Pin 4:**

Level shift input HSD 2 works in conjunction with HSD 1 to provide interface from the low side control logic and to give noise immunity.

#### **Pin 5:**

**SOURCE** connection. Analog reference point for the circuit, normally connected to the source of the high side MOSFET.

#### Pin 6:

**HS OUT** is the output of the MOSFET driver for the high side.

#### Pin 7:

No connection.

#### **Pin 8:**

 $\mathbf{V}_{\mathbf{DDH}}$  supplies power to the control logic and output driver.

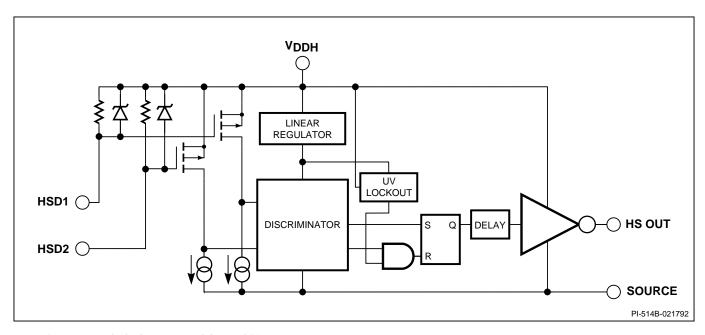


Figure 3. Functional Block Diagram of the INT201.

### **INT201 Functional Description**

#### 5 V Regulator

The 5 V linear regulator circuit provides the supply voltage for the noise rejection circuitry and control logic. This allows the logic section and the driver circuitry to be directly compatible with 5 V CMOS logic without the need of an external 5 V supply.

#### **Undervoltage Lockout**

The undervoltage lockout circuit disables the HS OUT pin whenever the  $V_{\tiny DDH}$ power supply falls below 9.0 V, and maintains this condition until the  $V_{\scriptscriptstyle DDH}$ power supply rises above 9.35 V. This guarantees that the high side MOSFET will be off during power-up or fault conditions.

#### **Noise Immunization Circuit**

This circuit provides noise immunity by combining a sampling circuit with a flip-flop to turn on and off the driver only when required to and not when there is noise on the HSD inputs.

#### **Driver**

The CMOS driver circuit provides drive power to the gate of the MOSFET used on the high side of the half bridge circuit. The driver consists of a CMOS buffer capable of driving external transistors at up to 15 V. The SOURCE pin is connected to the source of the external MOSFET to establish a reference for the gate voltage.

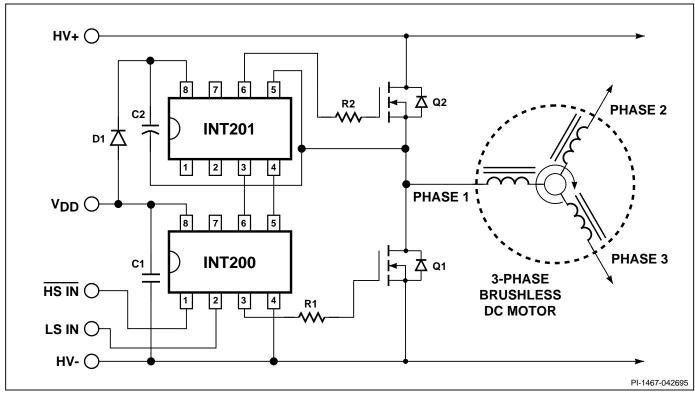


Figure 4. Using the INT200 and INT201 in a 3-phase Configuration.

### **General Circuit Operation**

One phase of a three-phase brushless DC motor drive circuit is shown in Figure 4 to illustrate an application of the INT200/201. The LS IN signal directly controls MOSFET Q1. The HS IN signal causes the INT200 to command the INT201 to turn MOSFET Q2 on or off as required. The INT200 will ignore input signals that would command both Q1 and Q2 to conduct simultaneously, protecting against shorting the HV+ bus to HV-.

Local bypassing for the low-side driver is provided by C1. Bootstrap bias for the high-side driver is provided by D1 and C2. Slew rate and effects of parasitic oscillations in the load waveforms are controlled by resistors R1 and R2.

The inputs are designed to be compatible with 5 V CMOS logic levels and should not be connected to  $V_{\rm DD}$ . Normal CMOS power supply sequencing should be observed. The order of signal application should be  $V_{\rm DD}$ , logic signals, and then HV+.

The INT201 is latched on and off by the edges of the appropriate low-side logic signal (HS IN for the INT200 and HS IN for the INT202). The high-side driver will latch off and stay off if the bootstrap capacitor discharges below the

undervoltage lockout threshold. Undervoltage lockout-induced turn off can occur during conditions such as power ramp up, motor start, or low speed operation.

### C<sub>BOOTSTRAP</sub> vs. ON TIME

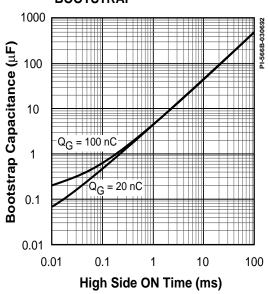


Figure 5. High-side On Time versus Bootstrap Capacitor.

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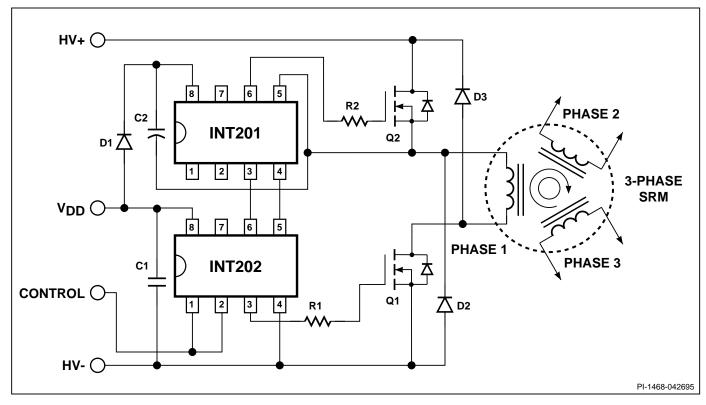


Figure 6. Using the INT202 and INT201 to Drive a Switched Reluctance Motor.

### **General Circuit Operation (cont.)**

The bootstrap capacitor must be large enough to provide bias current over the entire on time interval of the high-side driver without significant voltage sag or decay. The MOSFET gate charge must also be supplied at the desired switching frequency. Figure 5 shows the maximum high-side on time versus gate charge of

the external MOSFET. Applications with extremely long high-side on times require special techniques discussed in AN-10.

A three-phase switched reluctance motor example using the INT202/201 is given in Figure 6. The LS IN signal directly

controls MOSFET Q1. Unlike the INT200, the INT202 allows both the low and high-side drivers to be on at the same time, as this is required in applications where the load is placed between the low and high-side output MOSFETs.

ABSOLUTE MAXIMUM RATINGS <sup>1</sup>				
$\begin{array}{cccccccccccccccccccccccccccccccccccc$	Power Dissipation PF Suffix ( $T_A = 25^{\circ}C$ )			
	<ol> <li>Unless noted, all voltages referenced to SOURCE, T<sub>A</sub> = 25°C</li> <li>1/16" from case for 5 seconds.</li> </ol>			

Parameter	Symbol	Conditions (Unless Otherwise Specified) $V_{DDH} = 15 \text{ V, SOURCE} = 0 \text{ V}$ $T_A = -40 \text{ to } 85^{\circ}\text{C}$		Min	Тур	Max	Units
HSD INPUTS							
Input Current Threshold	I <sub>HSD1</sub> , I <sub>HSD2</sub>				-5	-2.5	mA
HS OUT	HS OUT						
Output Voltage, High	V <sub>OH</sub>	I <sub>o</sub> = -20 mA		V <sub>DDH</sub> -1.0	V <sub>DDH</sub> -0.5		V
Output Voltage, Low	V <sub>OL</sub>	I <sub>o</sub> = 40 mA			0.3	1.0	V
Output Short Circuit Current	I <sub>os</sub>	See Note 1	$V_{O} = 0 V$ $V_{O} = V_{DDH}$	300		-150	mA
Turn-on Delay Time	t <sub>d(on)</sub>	See Figure 7			1.0	1.5	μs
Rise Time	t <sub>r</sub>	See Figure 7			80	120	ns
Turn-off Delay Time	t <sub>d(off)</sub>	See Figure 7			420	600	ns
Fall Time	t,	See Figure 7			50	100	ns



Parameter	Symbol	Conditions (Unless Otherwise Specified) $V_{DDH} = 15 \text{ V, SOURCE} = 0 \text{ V}$ $T_A = -40 \text{ to } 85^{\circ}\text{C}$	Min	Тур	Max	Units
SYSTEM RESPO	NSE					
Deadtime (Low Off to High On)	Dt <sub>P+</sub>	See Figure 8	0	450		ns
Deadtime (Low On to High Off)	Dt <sub>P-</sub>	See Figure 8	0	300		ns
Matching (Low On to High On)	Mt <sub>P+</sub>	See Figure 9		0.3	1.0	μs
Matching (Low Off to High Off)	Mt <sub>P-</sub>	See Figure 9		0.3	1.0	μs
UNDERVOLTAGE LOCKOUT						
Input UV Threshold Voltage	V <sub>DDH(UV)</sub>		8.5	9.0	10	V
Input UV Hysteresis			175	350		mV
SUPPLY						
Supply Current	I <sub>DDH</sub>			1.5	3.0	mA
Supply Voltage	V <sub>DDH</sub>		10		16	V

#### NOTES:

<sup>1.</sup> Applying a short circuit to the HS OUT pin for more than  $500~\mu s$  will exceed the thermal rating of the package, resulting in destruction of the part.

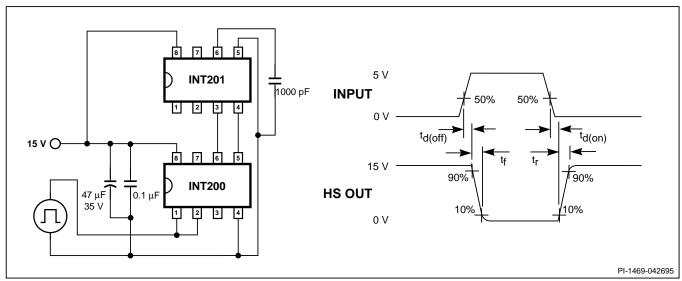


Figure 7. Switching Time Test Circuit.

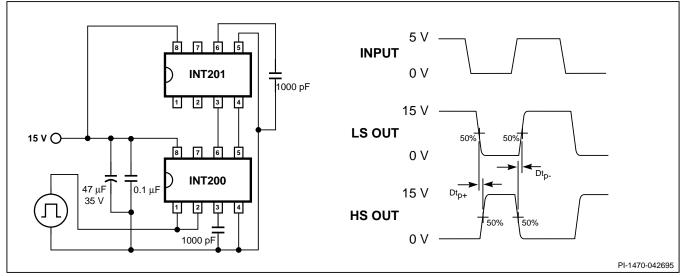


Figure 8. Dead Time Test Circuit.

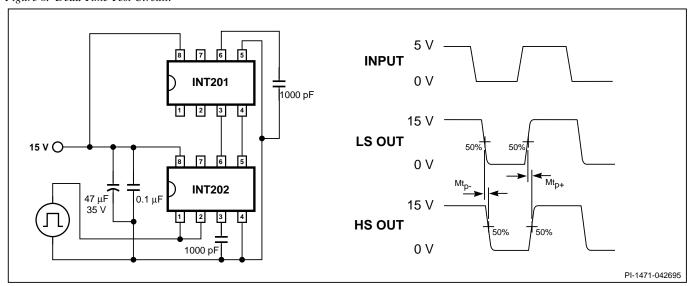
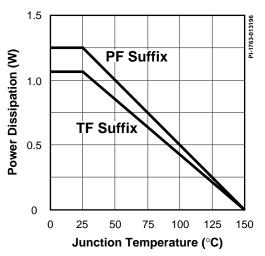


Figure 9. Matching Test Circuit.



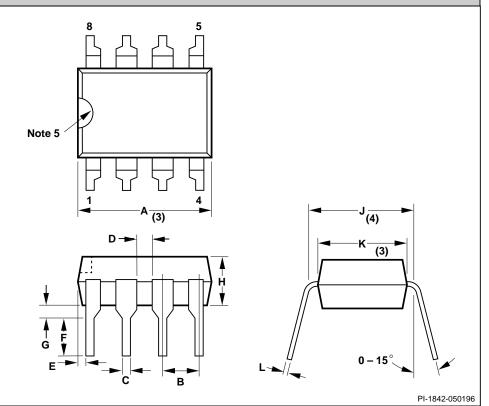
### **PACKAGE POWER DERATING**



#### **Plastic DIP-8 P08A**

Dim.	inches	mm
Α	.395 MAX	10.03 MAX
В	.090110	2.29-2.79
С	.015021	0.38-0.53
D	.040 TYP	1.02 TYP
E	.015030	0.38-0.76
F	.125 MIN	3.18 MIN
G	.015 MIN	0.38 MIN
н	.125135	3.18-3.43
J	.300320	7.62-8.13
K	.245255	6.22-6.48
L	.009015	0.23-0.38

- Package dimensions conform to JEDEC specification MS-001-AB for standard dual in-
- specimication MS-001-AB for standard dual inline (DIP) package .300 inch row spacing
  (PLASTIC) 8 leads (issue B, 7/85).
  2. Controlling dimensions: inches.
  3. Dimensions are for the molded body and do
  not include mold flash or other protrusions.
  Mold flash or protrusions shall not exceed .010 inch (.25 mm) on any side.
- These dimensions measured with the leads constrained to be perpendicular to package
- bottom.
  5. Pin 1 orientation identified by end notch or dot adjacent to Pin 1.

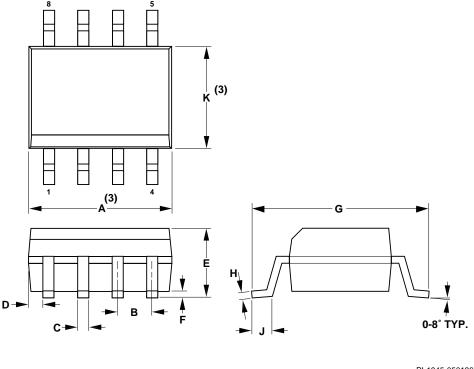


#### **Plastic SO-8 T08A**

DIM	inches	mm
Α	0.189-0.197	4.80-5.00
В	0.050 TYP	1.27 TYP
С	0.014-0.019	0.35-0.49
D	0.012 TYP	0.31 TYP
Е	0.053-0.069	1.35-1.75
F	0.004-0.010	0.10-0.25
G	0.228-0.244	5.80-6.20
Н	0.007-0.010	0.19-0.25
J	0.021-0.045	0.51-1.14
K	0.150-0.157	3.80-4.00

#### Notes:

- Package dimensions conform to JEDEC specification MS-012-AA for standard small outline (SO) package, 8 leads, 3.75 mm (.150 inch) body width (issue A, June 1985). 2. Controlling dimensions are in mm.
- Dimensions are for the molded body and do not include mold flash or protrusions. Mold flash or protrusions shall not exceed .15 mm (.006 inch) on any
- 4. Pin 1 side identified edge by chamfer on top of the package body or indent on Pin 1 end.



PI-1845-050196



# Notes

# Notes

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