# International TOR Rectifier

**ADVANCE INFORMATION** 

Data Sheet No. PD60176-C

IR2172

# LINEAR CURRENT SENSING IC

### **Features**

- Floating channel up to +600V
- Monolithic integration
- Linear current feedback through shunt resistor
- Direct digital PWM output for easy interface
- Low IQBS allows the boot strap power supply
- Independent fast overcurrent trip signal
- · High common mode noise immunity
- Input overvoltage protection for IGBT short circuit condition
- Open Drain outputs

## Description

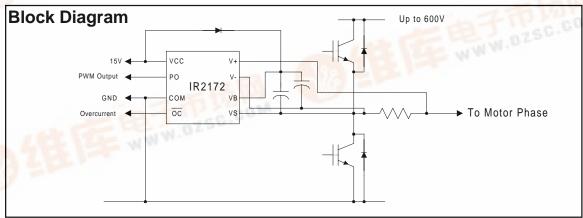
IR2172 is the monolithic current sensing IC designed for motor drive applications. It senses the motor phase current through an external shunt resistor, converts from analog to digital signal, and transfers the signal to the low side. IR's proprietary high voltage isolation technology is implemented to enable the high bandwidth signal processing. The output format is discrete PWM to eliminate need for the A/D input interface. The dedicated overcurrent trip (OC) signal facilitates IGBT short circuit protection. The OC output pulse can be programmed by the external resistor and capacitor. The open-drain outputs make easy for any interface from 3.3V to 15V.

# **Product Summary**

Voffset	600Vmax
I <sub>QBS</sub>	1mA
Vin	+/-260mVmax
Gain temp.drift	20ppm/°C (typ.)
fo	40kHz (typ.)
Overcurrent trip signal delay	1.5usec (typ)
Overcurrent trip level	+/-260mV (typ.)

# **Packages**







# **Absolute Maximum Ratings**

Absolute maximum ratings indicate sustained limits beyond which damage to the device may occur. All voltage parameters are absolute voltages referenced to COM, all currents are defined positive into any lead. The thermal resistance and power dissipation ratings are measured under board mounted and still air conditions.

Symbol	Definition		Min.	Max.	Units
Vs	High side offset voltage		-0.3	600	
V <sub>BS</sub>	High side floating supply voltage		-0.3	25	
V <sub>CC</sub>	Low side and logic fixed supply voltage		-0.3	25	
V <sub>IN</sub>	Maximum input voltage between V <sub>IN+ and</sub> V <sub>II</sub>	N-	-5	5	V
V <sub>PO</sub>	Digital PWM output voltage		COM -0.3	VCC +0.3	
Voc	Overcurrent output voltage		COM -0.3	VCC +0.3	
V <sub>IN-</sub>	V <sub>IN-</sub> input voltage (note 1)		V <sub>S</sub> -5	V <sub>B+</sub> 0.3	
dV/dt	Allowable offset voltage slew rate		_	50	V/ns
PD	Package power dissipation @ T <sub>A</sub> ≤ +25°C	8 lead SOIC	_	.625	
		8 lead PDIP	_	1.0	W
		16 lead SOIC	_	1.25	
Rth <sub>JA</sub>	Thermal resistance, junction to ambient	8 lead SOIC	_	200	
		8 lead PDIP	_	125	°C/W
		16 lead SOIC	_	100	
TJ	Junction temperature		_	150	
T <sub>S</sub>	Storage temperature		-55	150	°C
$T_L$	Lead temperature (soldering, 10 seconds)		_	300	

Note 1: Capacitors are required between VB and Vin-, and between VB and Vs pins when bootstrap power is used. The external power supply, when used, is required between Vs and Vin-, and between VB and Vs pins.

# **Recommended Operating Conditions**

The output logic timing diagram is shown in figure 1. For proper operation the device should be used within the recommended conditions.

Symbol	Definition	Min.	Max.	Units
V <sub>B</sub>	High side floating supply voltage	V <sub>S</sub> +13.0	V <sub>S</sub> +20	
Vs	High side floating supply offset voltage	note 2	600	
V <sub>PO</sub>	Digital PWM output voltage	COM	VCC	V
Voc	Overcurrent output voltage	COM	VCC	
V <sub>CC</sub>	Low side and logic fixed supply voltage	9.5	20	
V <sub>IN</sub>	Input voltage between V <sub>IN+</sub> and V <sub>IN-</sub>	-260	+260	mV
T <sub>A</sub>	Ambient temperature	-40	125	ů

Note 2: Logic operation for Vs of -5 to +600V. Logic state held for Vs of -5V to -VBs.

### **DC Electrical Characteristics**

 $V_{CC} = V_{BS} = 15V$ , unless otherwise specified.

Symbol	Definition	Min.	Тур.	Max.	Units	<b>Test Conditions</b>
V <sub>IN</sub>	Nominal input voltage range before saturation	-260	_	260		
	V <sub>IN+</sub> - V <sub>IN-</sub>					
V <sub>OC+</sub>	Overcurrent trip positive input voltage	_	260	_	mV	
V <sub>OC</sub> -	Overcurrent trip negative input voltage	_	-260	_		
Vos	Input offset voltage	-10	0	10		V <sub>IN</sub> = 0V (Note 1)
$\Delta V_{OS}/\Delta T_{A}$	Input offset voltage temperature drift	_	25	_	μV/°C	
G	Gain (duty cycle % per V <sub>IN</sub> )	157	162	167	%/V	max gain error=5%
						(Note 2)
ΔG/ΔΤΑ	Gain temperature drift	_	20	_	ppm/°C	
I <sub>LK</sub>	Offset supply leakage current	_	_	50	μA	V <sub>B</sub> = V <sub>S</sub> = 600V
I <sub>QBS</sub>	Quiescent V <sub>BS</sub> supply current	_	1	2	· mA	V <sub>S</sub> = 0V
IQCC	Quiescent V <sub>CC</sub> supply current	_	_	1	mA	
LIN	Linearity (duty cycle deviation from ideal linearity	_	0.5	1	%	
	curve)					
ΔV <sub>LIN</sub> /ΔΤΑ	Linearity temperature drift	_	.005	_	%/°C	
lopo	Digital PWM output sink current	20	_	_		V <sub>O</sub> = 1V
		2	_	_	- mA	V <sub>O</sub> = 0.1V
locc	OC output sink current	10	_	_	IIIA	V <sub>O</sub> = 1V
		1	_	_		V <sub>O</sub> = 0.1V

Note 1: ±10mV offset represents ±1.5% duty cycle fluctuation

Note 2: Gain = (full range of duty cycle in %) / (full input voltage range).

# **AC Electrical Characteristics**

 $V_{CC} = V_{BS} = 15V$ , unless otherwise specified.

	*					
Symbol	Definition	Min.	Тур.	Max.	Units	<b>Test Conditions</b>
Propaga	tion delay characteristics			•		
fo	Carrier frequency output	_	40		kHz	figure 1
Δf/ΔΤΑ	Temperature drift of carrier frequency	_	500		ppm/°C	V <sub>IN</sub> = 0 & 5V
Dmin	Minimum duty	_	7		%	V <sub>IN</sub> +=-260mV,V <sub>IN</sub> -=0V
Dmax	Maximum duty	_	93	_	%	V <sub>IN</sub> +=+260mV,V <sub>IN</sub> -=0V
BW	fo bandwidth		15		kHz	V <sub>IN</sub> + = 100mVpk -pk
						sine wave, gain=-3dB
PHS	Phase shift at 1kHz		-10		0	V <sub>IN</sub> + =100mVpk-pk
						sine wave

#### **AC Electrical Characteristics cont.**

 $V_{CC} = V_{BS} = 15V$ , unless otherwise specified.

Symbol	Definition	Min.	Тур.	Max.	Units	Test Conditions
Proagatio	n delay characteristics		_			
tdoc	Propagation delay time of OC	1	1.5	_	usec	
twoc	Low true pulse width of OC	_	1	_	μοσο	

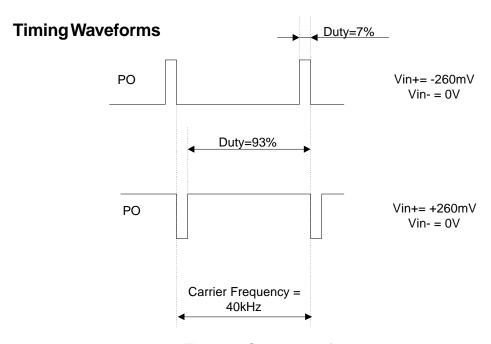


Figure 1 Output waveform

# **Application Hint:**

Temperature drift of the output carrier frequency can be cancelled by measuring both a PWM period and the on-time of PWM (Duty) at the same time. Since both periods vary in the same direction, computing the ratio between these values at each PWM period gives consistent measurement of the current feedback over the temperature drift.

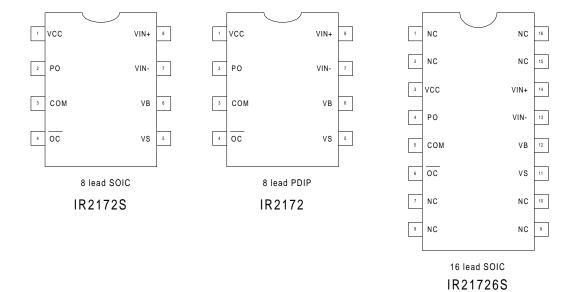
#### **ADVANCE INFORMATION**

**IR2172** 

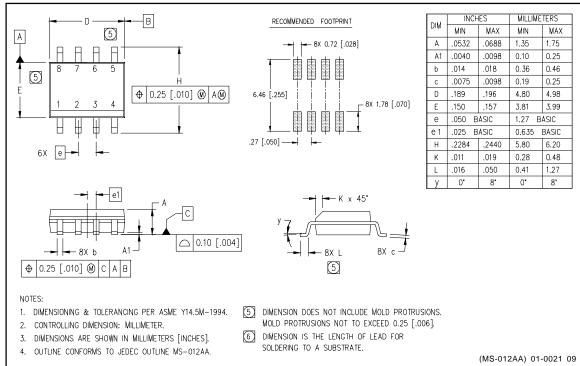
# **Lead Definitions**

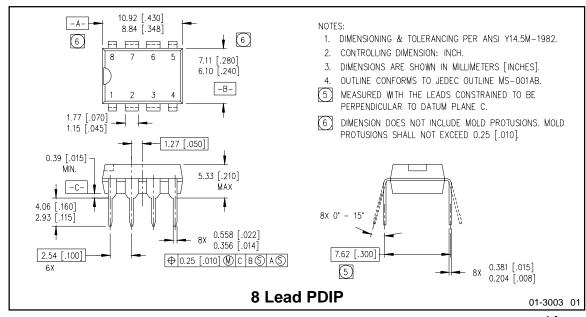
Symbol	Description
Vcc	Low side and logic supply voltage
COM	Low side logic ground
V <sub>IN+</sub>	Positive sense input
V <sub>IN</sub> -	Negative sense input
VB	High side supply
Vs	High side return
PO	Digital PWM output
<u>oc</u>	Overcurrent output (negative logic)
N.C.	No connection

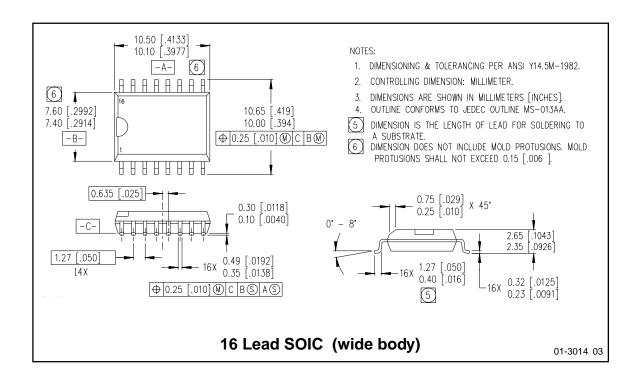
# **Lead Assignment**



#### Case Outline - 8 Lead SOIC







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